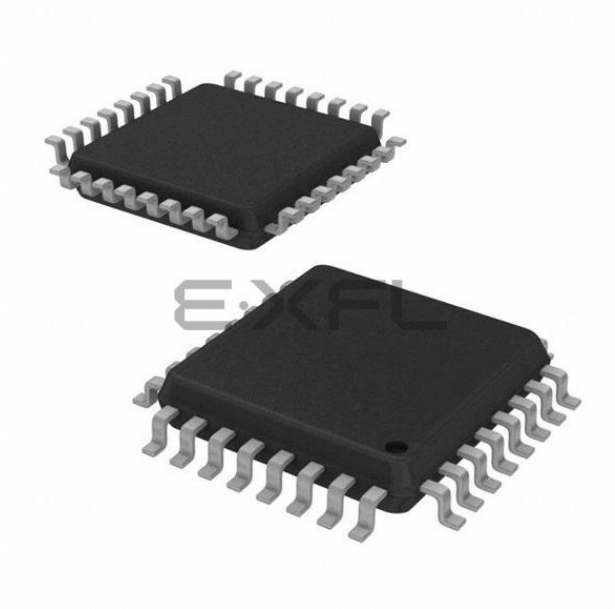

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Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	50MHz
Connectivity	I²C, LINbus, SCI, SPI
Peripherals	LVD, PWM, WDT
Number of I/O	26
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08qe16clc

Table of Contents

Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

http://freescale.com/

The following revision history table summarizes changes contained in this document.

Revision	Date	Description of Changes
1	7/2/2008	Initial public released.
2	10/7/2008	Updated the Stop2 and Stop3 mode supply current, and RI_{DD} in FEI mode with all modules on at 25.165 MHz in the Table 8 Supply Current Characteristics. Replaced the stop mode adders section from Table 8 with an individual Table 9 Stop Mode Adders with new specifications.
3	11/4/2008	Updated operating voltage in Table 7.
4	5/4/2009	Added 10×10 mm information to 44 LQFP in the front page. In Table 7, added $\|I_{OZTOT}\|$. In Table 11, updated typicals and Max. for $t_{IRST.}$ In Table 16, removed the Rev. Voltage High item. Updated Table 17.
5	8/27/2009	Updated f_{int_t} and f_{int_ut} in the Table 11.
6	10/13/2009	Corrected the package size descriptions on the cover
7	9/16/2011	Added new package of 32-pin QFN.

Related Documentation

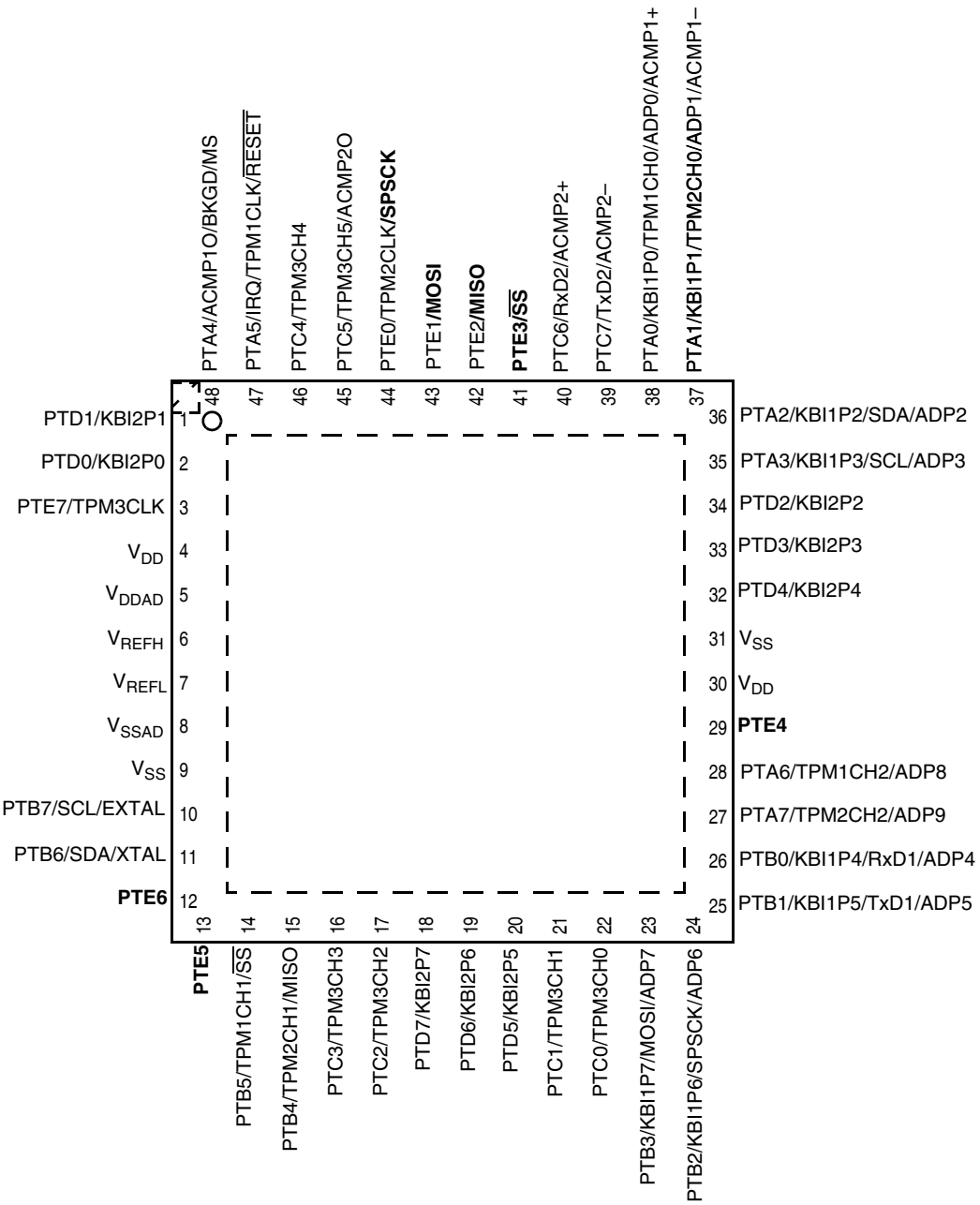
Find the most current versions of all documents at: http://www.freescale.com

Reference Manual (MC9S08QE32RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

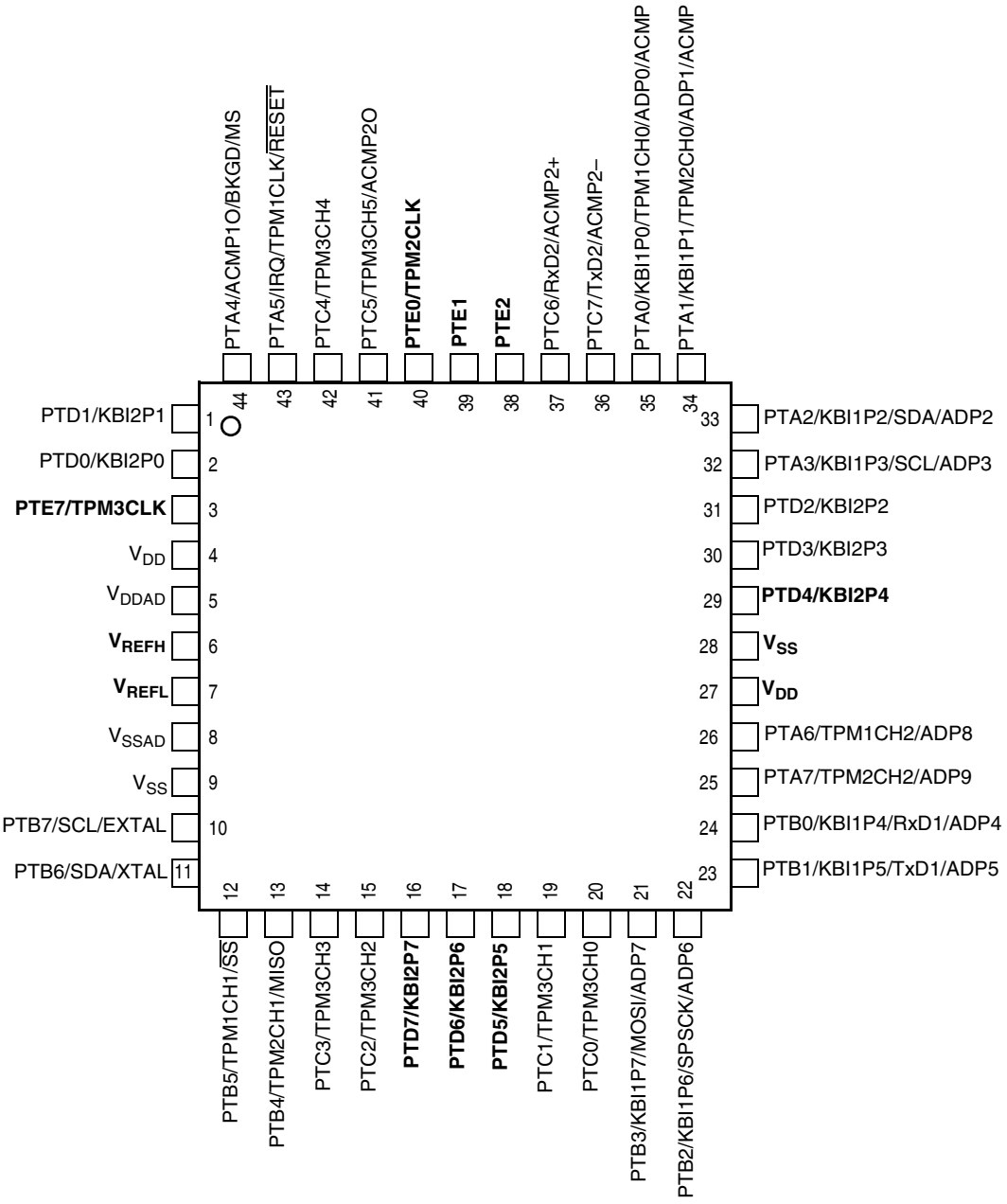
2 Pin Assignments

This section shows the pin assignments for the MC9S08QE32 series devices.



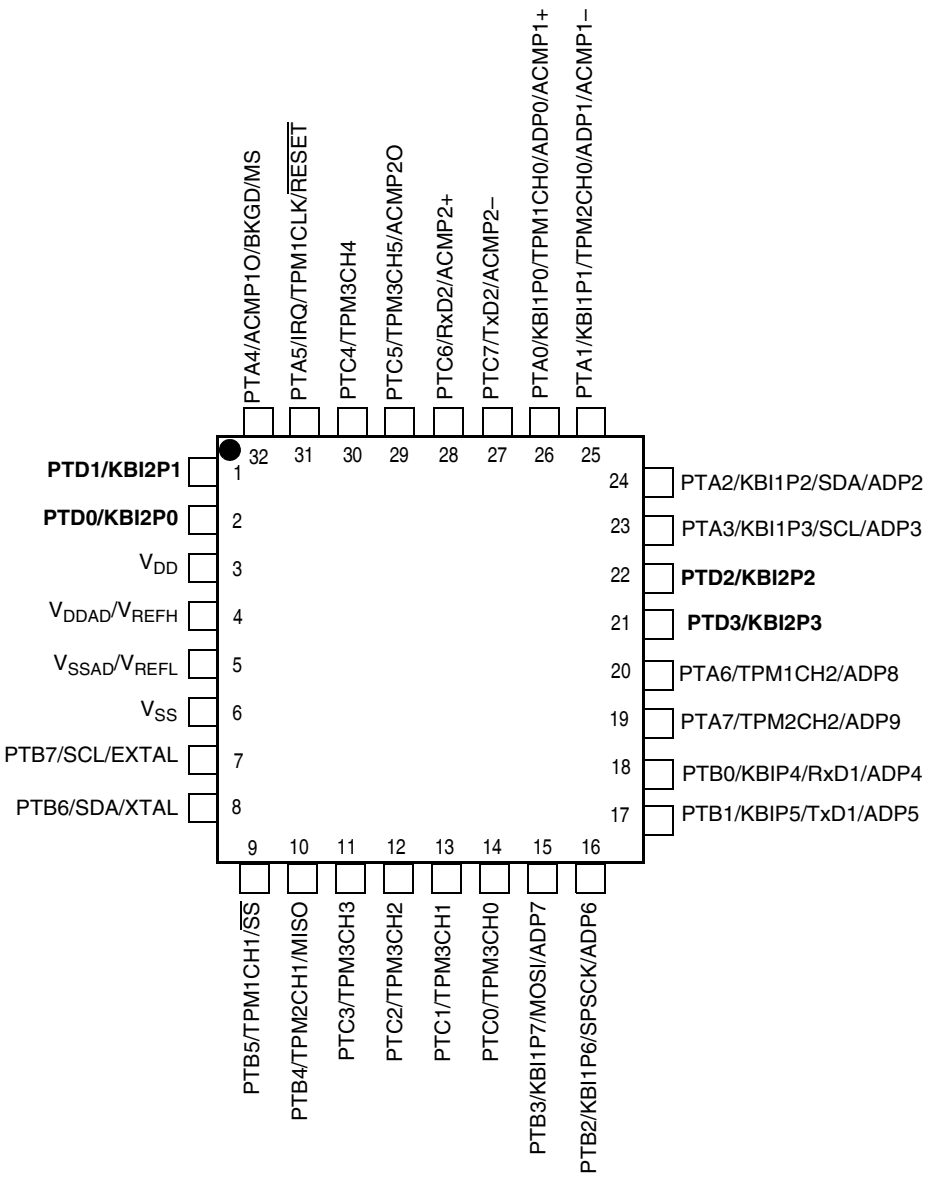
Pins in **bold** are lost in the next lower pin count package.

Figure 2. 48-Pin QFN



Pins in **bold** are lost in the next lower pin count package.

Figure 3. 44-Pin LQFP



Pins in **bold** are lost in the next lower pin count package.

Figure 4. 32-Pin LQFP/QFN

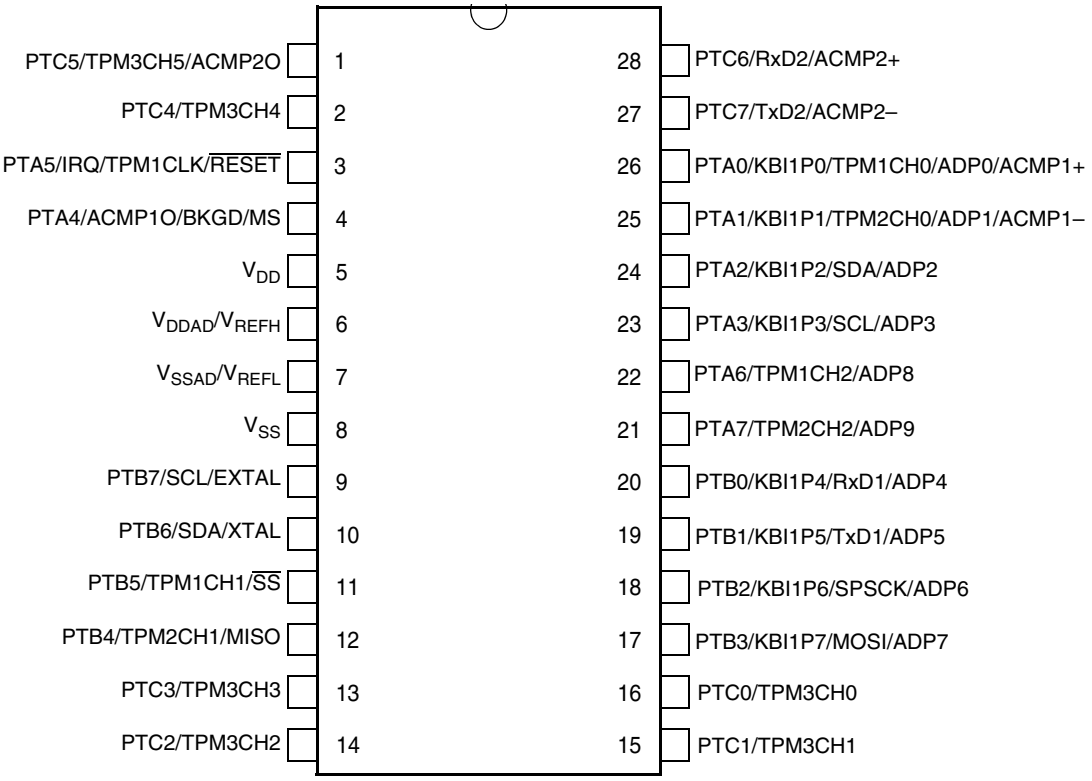


Figure 5. 28-Pin SOIC

Table 1. MC9S08QE32 Series Pin Assignment by Package and Pin Sharing Priority

Pin Number				<-- Lowest **Priority** --> Highest				
48	**44**	**32**	**28**	**Port Pin**	**Alt 1**	**Alt 2**	**Alt 3**	**Alt 4**
1	1	1	—	PTD1	KBI2P1			
2	2	2	—	PTD0	KBI2P0			
3	3	—	—	PTE7	TPM3CLK			
4	4	3	5					V_{DD}
5	5	4	6					V_{DDAD}
6	6							V_{REFH}
7	7	5	7					V_{REFL}
8	8							V_{SSAD}
9	9	6	8					V_{SS}
10	10	7	9	PTB7	SCL[1]			EXTAL
11	11	8	10	PTB6	SDA[1]			XTAL
12	—	—	—	PTE6				
13	—	—	—	PTE5				
14	12	9	11	PTB5	TPM1CH1	$\overline{SS}$[2]		
15	13	10	12	PTB4	TPM2CH1	MISO[2]		
16	14	11	13	PTC3	TPM3CH3			
17	15	12	14	PTC2	TPM3CH2			
18	16	—	—	PTD7	KBI2P7			

Table 4. Thermal Characteristics

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T_A	T_L to T_H –40 to 85	°C
Maximum junction temperature	T_{JM}	95	°C
Thermal resistance Single-layer board			
48-pin QFN	θ_{JA}	81	°C/W
44-pin LQFP		68	
32-pin LQFP		66	
32-pin QFN		92	
28-pin SOIC		57	
Thermal resistance Four-layer board			
48-pin QFN	θ_{JA}	26	°C/W
44-pin LQFP		46	
32-pin LQFP		54	
32-pin QFN		33	
28-pin SOIC		42	

The average chip-junction temperature (T_J) in °C can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA}) \qquad \textit{Eqn. 1}$$

where:

T_A = Ambient temperature, °C
θ_{JA} = Package thermal resistance, junction-to-ambient, °C/W
$P_D = P_{int} + P_{I/O}$
$P_{int} = I_{DD} \times V_{DD}$, Watts — chip internal power
$P_{I/O}$ = Power dissipation on input and output pins — user determined

For most applications, $P_{I/O} << P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_J + 273°C) \qquad \textit{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273°C) + \theta_{JA} \times (P_D)^2 \qquad \textit{Eqn. 3}$$

where K is a constant pertaining to the particular part. K can be determined from equation 3 by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A.

3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions must be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits. During the device qualification ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 5. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human Body	Series resistance	R1	1500	Ω
	Storage capacitance	C	100	pF
	Number of pulses per pin	—	3	
Machine	Series resistance	R1	0	Ω
	Storage capacitance	C	200	pF
	Number of pulses per pin	—	3	
Latch-up	Minimum input voltage limit		–2.5	V
	Maximum input voltage limit		7.5	V

Table 6. ESD and Latch-Up Protection Characteristics

No.	Rating[1]	Symbol	Min	Max	Unit
1	Human body model (HBM)	V_{HBM}	±2000	—	V
2	Machine model (MM)	V_{MM}	±200	—	V
3	Charge device model (CDM)	V_{CDM}	±500	—	V
4	Latch-up current at T_A = 85°C	I_{LAT}	±100	—	mA

1 Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 7. DC Characteristics

Num	C	Characteristic	Symbol	Condition	Min	Typical[1]	Max	Unit
1		Operating Voltage V_{DD} rising V_{DD} falling			 2.0 1.8	—	3.6	V
2	C	Output high voltage[2] — All I/O pins, low-drive strength	V_{OH}	1.8 V, I_{Load} = –2 mA	V_{DD} – 0.5	—	—	V
	P	All I/O pins, high-drive strength		2.7 V, I_{Load} = –10 mA	V_{DD} – 0.5	—	—	
	T			2.3 V, I_{Load} = –6 mA	V_{DD} – 0.5	—	—	
	C			1.8V, I_{Load} = –3 mA	V_{DD} – 0.5	—	—	
3	D	Output high current — Max total I_{OH} for all ports	I_{OHT}		—	—	100	mA
4	C	Output low voltage — All I/O pins, low-drive strength	V_{OL}	1.8 V, I_{Load} = 2 mA	—	—	0.5	V
	P	All I/O pins, high-drive strength		2.7 V, I_{Load} = 10 mA	—	—	0.5	
	T			2.3 V, I_{Load} = 6 mA	—	—	0.5	
	C			1.8 V, I_{Load} = 3 mA	—	—	0.5	
5	D	Output low current — Max total I_{OL} for all ports	I_{OLT}		—	—	100	mA
6	P	Input high voltage — all digital inputs	V_{IH}	V_{DD} > 2.3 V	0.70 x V_{DD}	—	—	V
	C			V_{DD} ≤ 1.8 V	0.85 x V_{DD}	—	—	
7	P	Input low voltage — all digital inputs	V_{IL}	V_{DD} > 2.7 V	—	—	0.35 x V_{DD}	
	C			V_{DD} ≤ 1.8 V	—	—	0.30 x V_{DD}	
8	C	Input hysteresis — all digital inputs	V_{hys}		0.06 x V_{DD}	—	—	mV
9	P	Input leakage current — all input only pins (Per pin)	$\lvert I_{In} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	1	μA
10	P	Hi-Z (off-state) leakage current — all input/output (per pin)	$\lvert I_{OZ} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	1	μA
11	C	Total leakage combined for all inputs and Hi-Z pins — All input only and I/O	$\lvert I_{OZTOT} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	2	μA
11	P	Pullup, Pulldown resistors — all digital inputs, when enabled	R_{PU}, R_{PD}		17.5	—	52.5	kΩ
12	D	DC injection current [3, 4, 5] — Single pin limit	I_{IC}	V_{IN} < V_{SS}, V_{IN} > V_{DD}	–0.2	—	0.2	mA
		Total MCU limit, includes sum of all stressed pins			–5	—	5	mA
13	C	Input Capacitance, all pins	C_{In}		—	—	8	pF
14	C	RAM retention voltage	V_{RAM}		—	0.6	1.0	V
15	C	POR re-arm voltage[6]	V_{POR}		0.9	1.4	2.0	V

Table 7. DC Characteristics (continued)

Num	C	Characteristic	Symbol	Condition	Min	Typical[1]	Max	Unit
16	D	POR re-arm time	t_{POR}		10	—	—	µs
17	P	Low-voltage detection threshold — high range	V_{LVDH}	V_{DD} falling V_{DD} rising	2.11 2.16	2.16 2.21	2.22 2.27	V
18	P	Low-voltage detection threshold — low range	V_{LVDL}	V_{DD} falling V_{DD} rising	1.80 1.88	1.82 1.90	1.91 1.99	V
19	P	Low-voltage warning threshold — high range	V_{LVWH}	V_{DD} falling V_{DD} rising	2.36 2.36	2.46 2.46	2.56 2.56	V
20	P	Low-voltage warning threshold — low range	V_{LVWL}	V_{DD} falling V_{DD} rising	2.11 2.16	2.16 2.21	2.22 2.27	V
21	C	Low-voltage inhibit reset/recover hysteresis	V_{hys}		—	80	—	mV
22	P	Bandgap Voltage Reference[7]	V_{BG}		1.15	1.17	1.18	V

1 Typical values are measured at 25 °C. Characterized, not tested

2 As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above V_{LVDL}.

3 All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD}.

4 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

5 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

6 Maximum is highest voltage that POR is guaranteed.

7 Factory trimmed at V_{DD} = 3.0 V, Temp = 25 °C

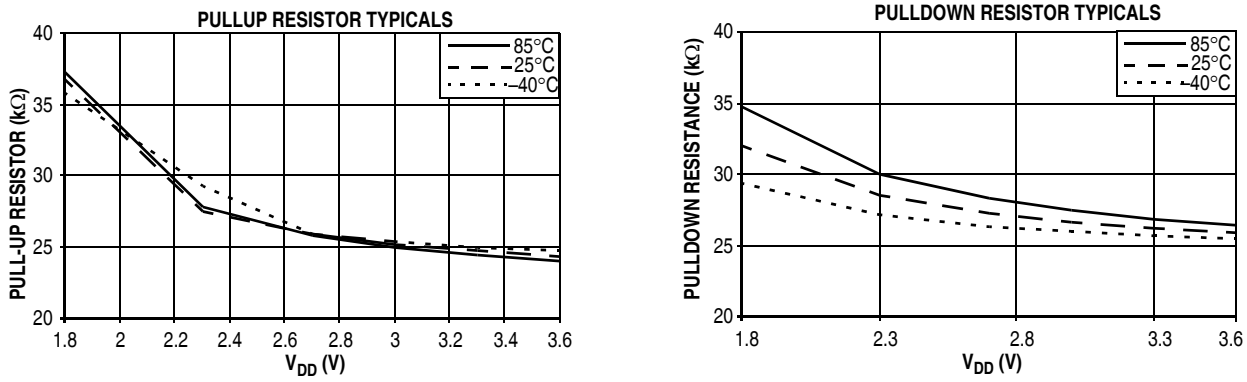


Figure 6. Pullup and Pulldown Typical Resistor Values (V_{DD} = 3.0 V)

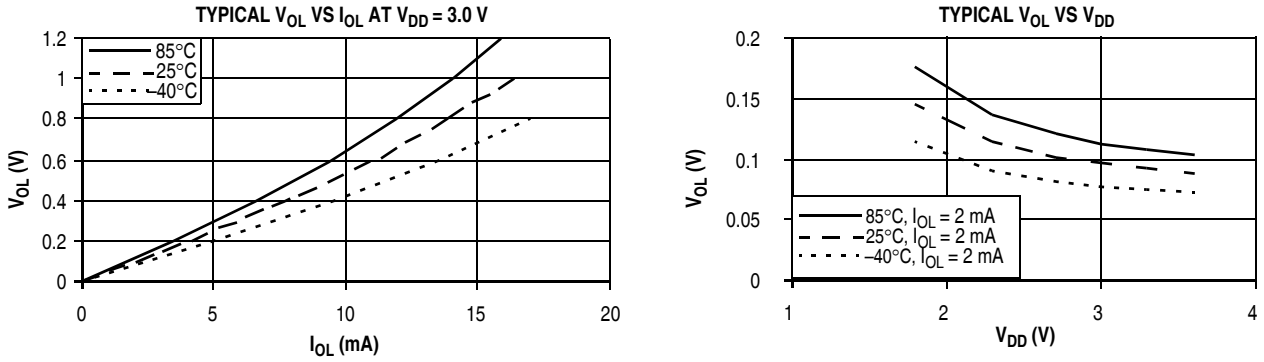


Figure 7. Typical Low-Side Driver (Sink) Characteristics — Low Drive (PTxDSn = 0)

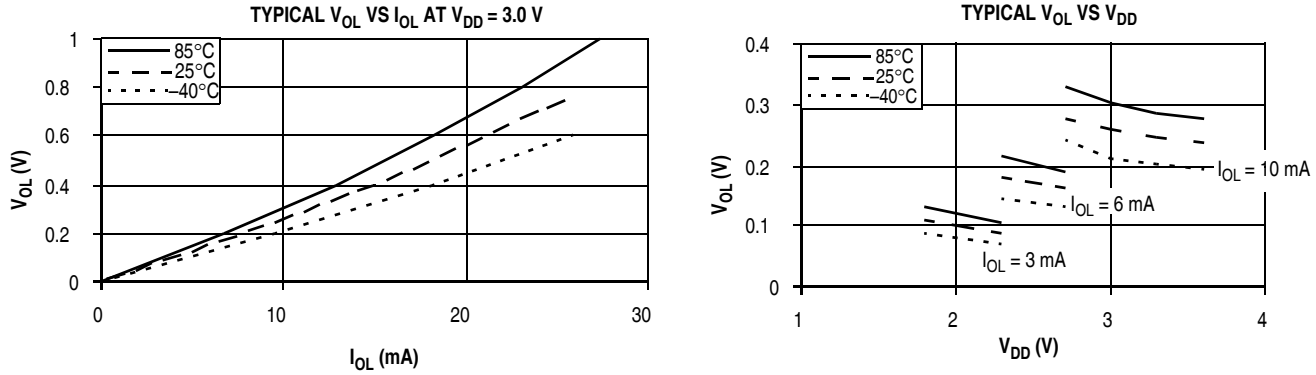


Figure 8. Typical Low-Side Driver (Sink) Characteristics — High Drive (PTxDSn = 1)

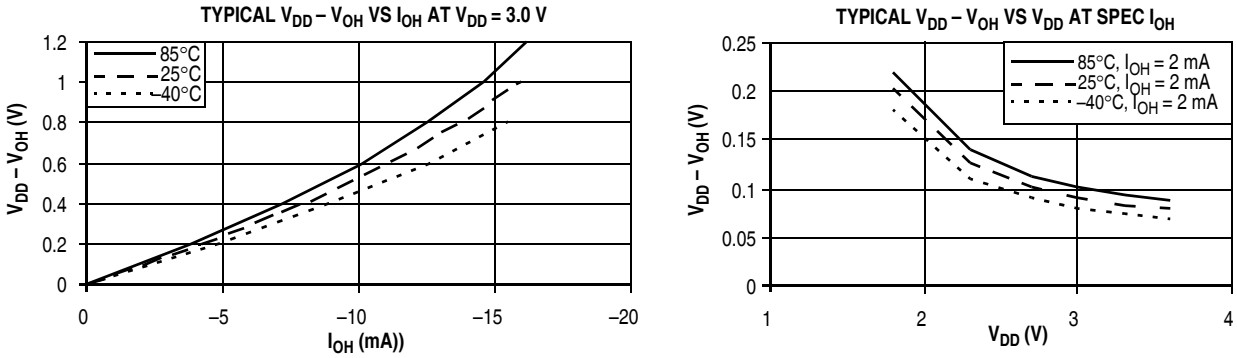


Figure 9. Typical High-Side (Source) Characteristics — Low Drive (PTxDSn = 0)

[1] Not available in stop2 mode.

3.8 External Oscillator (XOSCVLP) Characteristics

Reference Figure 11 and Figure 12 for crystal or resonator circuits.

Table 10. XOSC and ICS Specifications (Temperature Range = –40 to 85°C Ambient)

Num	C	Characteristic	Symbol	Min	Typical[1]	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1) High range (RANGE = 1), low power (HGO = 0)	 f_{lo} f_{hi} f_{hi}	 32 1 1	 — — —	 38.4 16 8	 kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO=0) Other oscillator settings	 C_1 C_2	 See Note [2] See Note [3]			
3	D	Feedback resistor Low range, low power (RANGE=0, HGO=0)[2] Low range, High Gain (RANGE=0, HGO=1) High range (RANGE=1, HGO=X)	R_F	 — — —	 — 10 1	 — — —	MΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0)[2] Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	R_S	 — — — — — —	 — 100 0 0 0 0	 — — — 0 10 20	kΩ
5	C	Crystal start-up time [4] Low range, low power Low range, high power High range, low power High range, high power	 t_{CSTL} t_{CSTH} 	 — — — —	 200 400 5 15	 — — — —	 ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	f_{extal}	0.03125 0	— —	40 40	MHz MHz

[1] Data in Typical column is characterized at 3.0 V, 25 °C or is typical recommended value.

[2] Load capacitors (C_1,C_2), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE=HGO=0.

[3] See crystal or resonator manufacturer's recommendation.

[4] Proper PC board layout procedures must be followed to achieve specifications.

Table 12. Control Timing (continued)

Num	C	Rating	Symbol	Min	Typical[1]	Max	Unit
8	D	Keyboard interrupt pulse width Asynchronous path[2] Synchronous path[5]	t_{ILIH}, t_{IHIL}	 100 1.5 × t_{cyc}	 — —	 — —	ns
9	C	Port rise and fall time — Low output drive (PTxDS = 0) (load = 50 pF)[5] Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	 — —	 8 31	 — —	ns
		Port rise and fall time — High output drive (PTxDS = 1) (load = 50 pF) Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	 — —	 7 24	 — —	ns
10	C	Voltage regulator recovery time	t_{VRR}	—	4	—	µs

1 Typical values are based on characterization data at V_{DD} = 3.0 V, 25 °C unless otherwise stated.

2 This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

3 To enter BDM mode following a POR, BKGD/MS must be held low during the power-up and for a hold time of t_{MSH} after V_{DD} rises above V_{LVD}.

4 This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

5 Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40 °C to 85 °C.

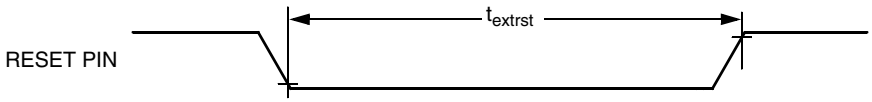


Figure 13. Reset Timing

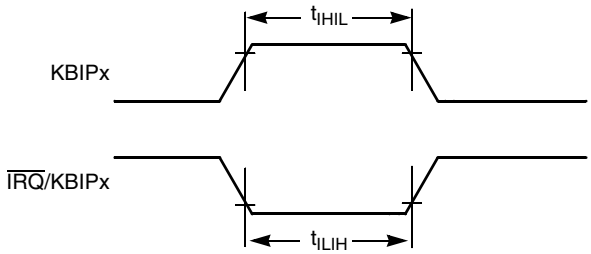


Figure 14. IRQ/KBIPx Timing

3.10.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 13. TPM Input Timing

No.	C	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	f_{TCLK}	0	$f_{Bus}/4$	Hz
2	D	External clock period	t_{TCLK}	4	—	t_{cyc}
3	D	External clock high time	t_{clkh}	1.5	—	t_{cyc}
4	D	External clock low time	t_{clkl}	1.5	—	t_{cyc}
5	D	Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

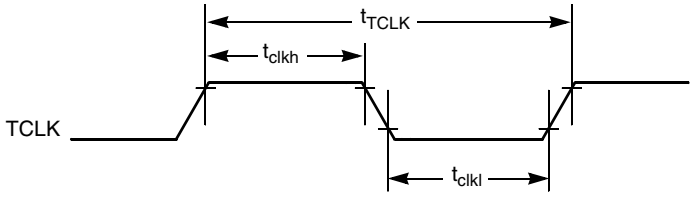


Figure 15. Timer External Clock

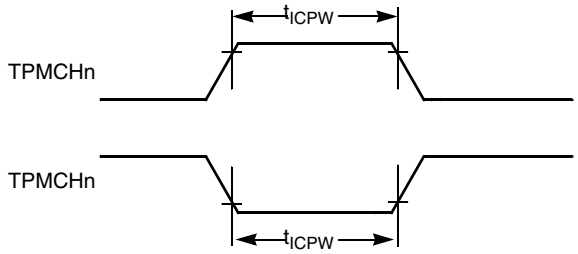


Figure 16. Timer Input Capture Pulse

3.10.3 SPI Timing

Table 14 and Figure 17 through Figure 20 describe the timing requirements for the SPI system.

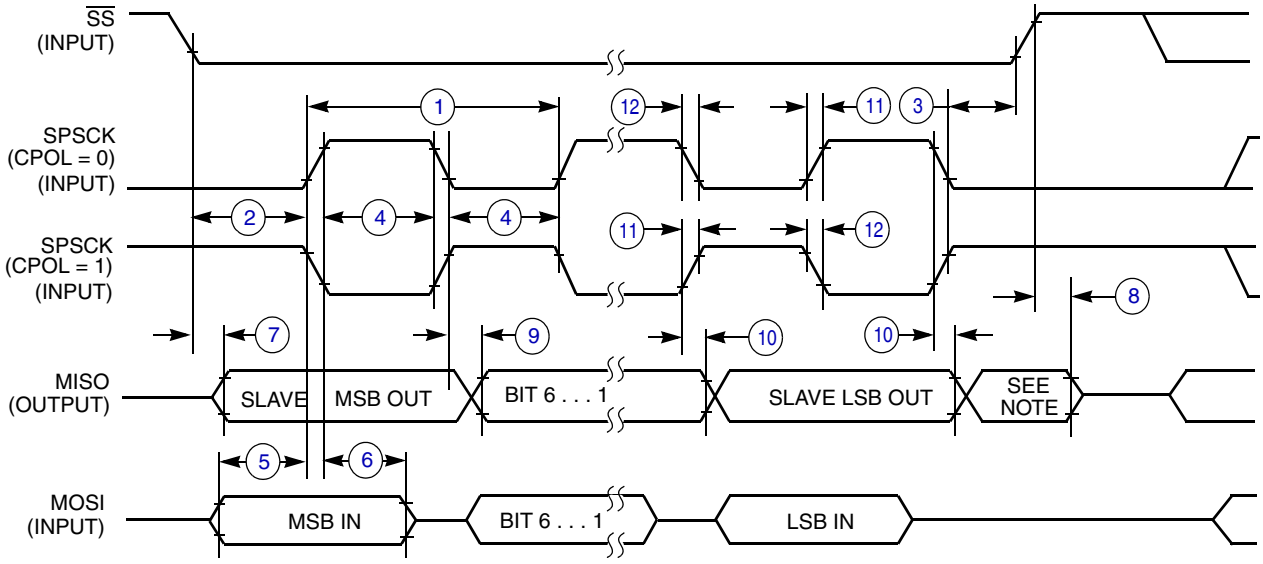
Table 14. SPI Timing

No.	C	Function	Symbol	Min	Max	Unit
—	D	Operating frequency Master Slave	f_{op}	$f_{Bus}/2048$ 0	$f_{Bus}/2^1$ $f_{Bus}/4$	Hz
1	D	SPSCK period Master Slave	t_{SPSCK}	2 4	2048 —	t_{cyc} t_{cyc}
2	D	Enable lead time Master Slave	t_{Lead}	1/2 1	— —	t_{SPSCK} t_{cyc}
3	D	Enable lag time Master Slave	t_{Lag}	1/2 1	— —	t_{SPSCK} t_{cyc}

Table 14. SPI Timing (continued)

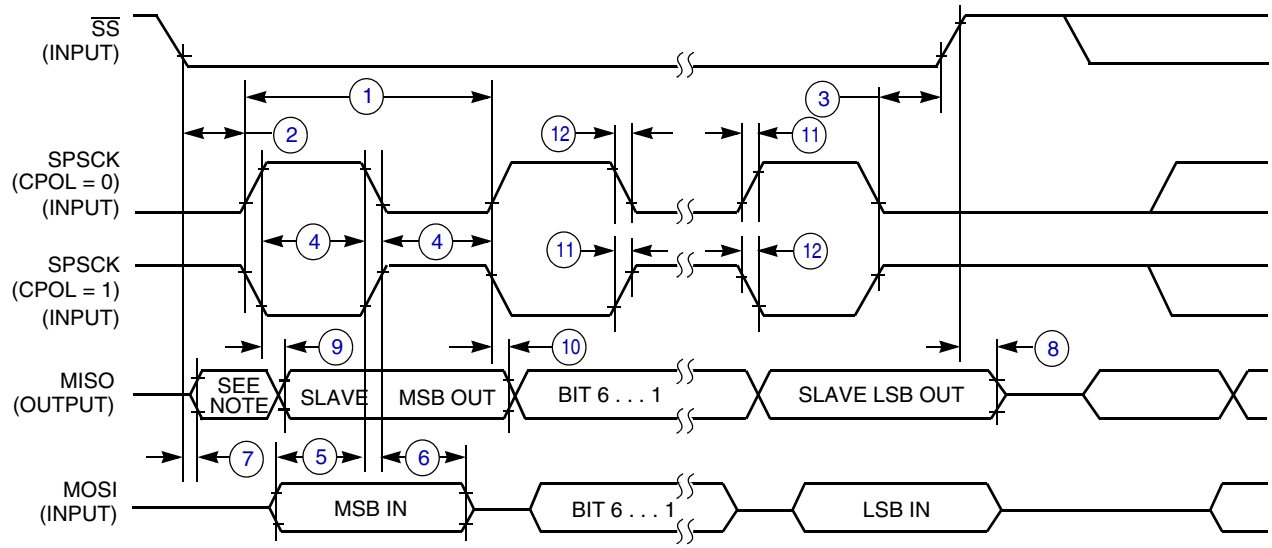
No.	C	Function	Symbol	Min	Max	Unit
4	D	Clock (SPSCK) high or low time Master Slave	t_{WSPSCK}	 $t_{cyc} - 30$ $t_{cyc} - 30$	 1024 t_{cyc} —	 ns ns
5	D	Data setup time (inputs) Master Slave	t_{SU}	 15 15	 — —	 ns ns
6	D	Data hold time (inputs) Master Slave	t_{HI}	 0 25	 — —	 ns ns
7	D	Slave access time	t_a	—	1	t_{cyc}
8	D	Slave MISO disable time	t_{dis}	—	1	t_{cyc}
9	D	Data valid (after SPSCK edge) Master Slave	t_v	 — —	 25 25	 ns ns
10	D	Data hold time (outputs) Master Slave	t_{HO}	 0 0	 — —	 ns ns
11	D	Rise time Input Output	 t_{RI} t_{RO}	 — —	 $t_{cyc} - 25$ 25	 ns ns
12	D	Fall time Input Output	 t_{FI} t_{FO}	 — —	 $t_{cyc} - 25$ 25	 ns ns

1 Max operating frequency limited to 8 MHz when input filter disabled and high output drive strength enabled. Max operating frequency limited to 5 MHz when input filter enabled and high output drive strength disabled.



NOTE:
1. Not defined but normally MSB of character just received

Figure 19. SPI Slave Timing (CPHA = 0)



NOTE:
1. Not defined but normally LSB of character just received

Figure 20. SPI Slave Timing (CPHA = 1)

3.11 Analog Comparator (ACMP) Electricals

Table 15. Analog Comparator Electrical Specifications

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	V_{DD}	1.8	—	3.6	V
P	Supply current (active)	I_{DDAC}	—	20	35	μA
D	Analog input voltage	V_{AIN}	V_{SS} – 0.3	—	V_{DD}	V
P	Analog input offset voltage	V_{AIO}	—	20	40	mV
C	Analog comparator hysteresis	V_H	3.0	9.0	15.0	mV
P	Analog input leakage current	I_{ALKG}	—	—	1.0	μA
C	Analog comparator initialization delay	t_{AINIT}	—	—	1.0	μs

3.12 ADC Characteristics

Table 16. 12-Bit ADC Operating Conditions

C	Characteristic	Conditions	Symb	Min	Typical[1]	Max	Unit	Comment
D	Supply voltage	Absolute	V_{DDAD}	1.8	—	3.6	V	—
		Delta to V_{DD} (V_{DD} – V_{DDAD})[2]	ΔV_{DDAD}	–100	0	100	mV	—
D	Ground voltage	Delta to V_{SS} (V_{SS} – V_{SSAD})[2]	ΔV_{SSAD}	–100	0	100	mV	—
D	Input voltage	—	V_{ADIN}	V_{REFL}	—	V_{REFH}	V	—
C	Input capacitance	—	C_{ADIN}	—	4.5	5.5	pF	—
C	Input resistance	—	R_{ADIN}	—	5	7	kΩ	—
C	Analog source resistance	12-bit mode f_{ADCK} > 4 MHz f_{ADCK} < 4 MHz	R_{AS}	 — —	 — —	 2 5	kΩ	External to MCU
		10-bit mode f_{ADCK} > 4 MHz f_{ADCK} < 4 MHz		 — —	 — —	 5 10		
		8-bit mode (all valid f_{ADCK})		—	—	10		
D	ADC conversion clock freq.	High speed (ADLPC = 0)	f_{ADCK}	0.4	—	8.0	MHz	—
		Low power (ADLPC = 1)		0.4	—	4.0		

1 Typical values assume V_{DDAD} = 3.0 V, Temp = 25 °C, f_{ADCK}=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 DC potential difference.

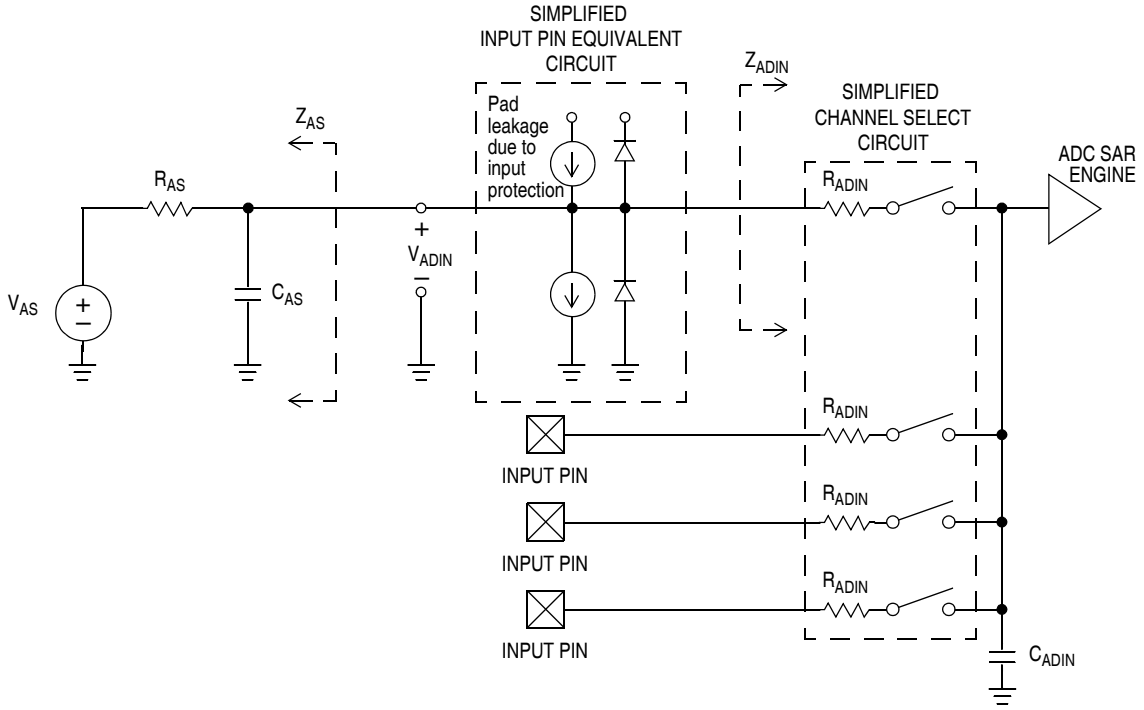


Figure 21. ADC Input Impedance Equivalency Diagram

Table 17. ADC Characteristics (V_{REFH} = V_{DDAD}, V_{REFL} = V_{SSAD})

C	Characteristic	Conditions	Symbol	Min	Typ[1]	Max	Unit	Comment
T	Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		I_{DDAD}	—	120	—	μA	
T	Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		I_{DDAD}	—	202	—	μA	
T	Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		I_{DDAD}	—	288	—	μA	
P	Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		I_{DDAD}	—	0.532	1	mA	
P	ADC asynchronous clock source	High speed (ADLPC = 0)	f_{ADACK}	2	3.3	5	MHz	t_{ADACK} = $1/f_{ADACK}$
		Low power (ADLPC = 1)		1.25	2	3.3		

1 Typical values assume V_{DDAD} = 3.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 1 LSB = $(V_{REFH} - V_{REFL})/2^N$

3 Monotonicity and No-missing-codes guaranteed in 10-bit and 8-bit modes

4 Based on input pad leakage current. Refer to pad electricals.

3.13 Flash Specifications

This section provides details about program/erase times and program-erase endurance for flash memory.

Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see MC9S08QE32 Series Reference Manual Chapter 4 Memory.

Table 18. Flash Characteristics

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage for program/erase –40 °C to 85 °C	$V_{prog/erase}$	1.8	—	3.6	V
D	Supply voltage for read operation	V_{Read}	1.8	—	3.6	V
D	Internal FCLK frequency[1]	f_{FCLK}	150	—	200	kHz
D	Internal FCLK period (1/FCLK)	t_{Fcyc}	5	—	6.67	µs
P	Byte program time (random location)(2)	t_{prog}	9			t_{Fcyc}
P	Byte program time (burst mode)(2)	t_{Burst}	4			t_{Fcyc}
P	Page erase time[2]	t_{Page}	4000			t_{Fcyc}
P	Mass erase time(2)	t_{Mass}	20,000			t_{Fcyc}
	Byte program current[3]	R_{IDDBP}	—	4	—	mA
	Page erase current[3]	R_{IDDPE}	—	6	—	mA
C	Program/erase endurance[4] T_L to T_H = –40 °C to 85 °C T = 25 °C		10,000	— 100,000	— —	cycles
C	Data retention[5]	t_{D_ret}	15	100	—	years

1 The frequency of this clock is controlled by software setting.

2 These values are hardware state machine controlled. User code does not need to count cycles. This information is supplied for calculating approximate time to program and erase.

3 The program and erase currents are additional to the standard run I_{DD}. These values are measured at room temperatures with V_{DD} = 3.0 V, bus frequency = 4.0 MHz.

4 **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory.*

5 **Typical data retention** values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory.*

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