

Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	50MHz
Connectivity	I ² C, LINbus, SCI, SPI
Peripherals	LVD, PWM, WDT
Number of I/O	26
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08qe32clc

Table of Contents

1	MCU Block Diagram	3	3.9	Internal Clock Source (ICS) Characteristics	19
2	Pin Assignments	4	3.10	AC Characteristics	20
3	Electrical Characteristics	9	3.10.1	Control Timing	20
3.1	Introduction	9	3.10.2	TPM Module Timing	21
3.2	Parameter Classification	9	3.10.3	SPI Timing	22
3.3	Absolute Maximum Ratings	9	3.11	Analog Comparator (ACMP) Electricals	26
3.4	Thermal Characteristics	10	3.12	ADC Characteristics	26
3.5	ESD Protection and Latch-Up Immunity	12	3.13	Flash Specifications	29
3.6	DC Characteristics	12	4	Ordering Information	30
3.7	Supply Current Characteristics	16	5	Package Information	30
3.8	External Oscillator (XOSC_VLP) Characteristics	18	5.1	Mechanical Drawings	30

Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

<http://freescale.com/>

The following revision history table summarizes changes contained in this document.

Revision	Date	Description of Changes
1	7/2/2008	Initial public released.
2	10/7/2008	Updated the Stop2 and Stop3 mode supply current, and $R_{I_{DD}}$ in FEI mode with all modules on at 25.165 MHz in the Table 8 Supply Current Characteristics. Replaced the stop mode adders section from Table 8 with an individual Table 9 Stop Mode Adders with new specifications.
3	11/4/2008	Updated operating voltage in Table 7 .
4	5/4/2009	Added 10×10 mm information to 44 LQFP in the front page. In Table 7 , added I_{OZTOT} . In Table 11 , updated typicals and Max. for t_{IRST} . In Table 16 , removed the Rev. Voltage High item. Updated Table 17 .
5	8/27/2009	Updated f_{int_t} and f_{int_ut} in the Table 11 .
6	10/13/2009	Corrected the package size descriptions on the cover
7	9/16/2011	Added new package of 32-pin QFN.

Related Documentation

Find the most current versions of all documents at: <http://www.freescale.com>

Reference Manual (MC9S08QE32RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

3 Electrical Characteristics

3.1 Introduction

This section contains electrical and timing specifications for the MC9S08QE32 series of microcontrollers available at the time of publication.

3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 2. Parameter Classifications

P	Those parameters are guaranteed during production testing on each individual device.
C	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
T	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in [Table 3](#) may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pull-up resistor associated with the pin is enabled.

Table 3. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	V_{DD}	-0.3 to +3.8	V
Maximum current into V_{DD}	I_{DD}	120	mA
Digital input voltage	V_{In}	-0.3 to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) ^{1, 2, 3}	I_D	±25	mA
Storage temperature range	T_{stg}	-55 to 150	°C

¹ Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.

² All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD} .

³ Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD} , the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 4. Thermal Characteristics

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T_A	T_L to T_H -40 to 85	$^{\circ}\text{C}$
Maximum junction temperature	T_{JM}	95	$^{\circ}\text{C}$
Thermal resistance Single-layer board			
48-pin QFN	θ_{JA}	81	$^{\circ}\text{C}/\text{W}$
44-pin LQFP		68	
32-pin LQFP		66	
32-pin QFN		92	
28-pin SOIC		57	
Thermal resistance Four-layer board			
48-pin QFN	θ_{JA}	26	$^{\circ}\text{C}/\text{W}$
44-pin LQFP		46	
32-pin LQFP		54	
32-pin QFN		33	
28-pin SOIC		42	

The average chip-junction temperature (T_J) in $^{\circ}\text{C}$ can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA}) \quad \text{Eqn. 1}$$

where:

T_A = Ambient temperature, $^{\circ}\text{C}$

θ_{JA} = Package thermal resistance, junction-to-ambient, $^{\circ}\text{C}/\text{W}$

$P_D = P_{\text{int}} + P_{I/O}$

$P_{\text{int}} = I_{DD} \times V_{DD}$, Watts — chip internal power

$P_{I/O}$ = Power dissipation on input and output pins — user determined

For most applications, $P_{I/O} \ll P_{\text{int}}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_J + 273^{\circ}\text{C}) \quad \text{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273^{\circ}\text{C}) + \theta_{JA} \times (P_D)^2 \quad \text{Eqn. 3}$$

where K is a constant pertaining to the particular part. K can be determined from equation 3 by measuring P_D (at equilibrium) for a known T_A . Using this value of K, the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A .

Table 7. DC Characteristics

Num	C	Characteristic	Symbol	Condition	Min	Typical ¹	Max	Unit
1		Operating Voltage V _{DD} rising V _{DD} falling			2.0 1.8	—	3.6	V
2	C	Output high voltage ² All I/O pins, low-drive strength	V _{OH}	1.8 V, I _{Load} = -2 mA	V _{DD} - 0.5	—	—	V
	P			2.7 V, I _{Load} = -10 mA	V _{DD} - 0.5	—	—	
	T	All I/O pins, high-drive strength		2.3 V, I _{Load} = -6 mA	V _{DD} - 0.5	—	—	
	C			1.8 V, I _{Load} = -3 mA	V _{DD} - 0.5	—	—	
3	D	Output high current Max total I _{OH} for all ports	I _{OHT}		—	—	100	mA
4	C	Output low voltage All I/O pins, low-drive strength	V _{OL}	1.8 V, I _{Load} = 2 mA	—	—	0.5	V
	P			2.7 V, I _{Load} = 10 mA	—	—	0.5	
	T	All I/O pins, high-drive strength		2.3 V, I _{Load} = 6 mA	—	—	0.5	
	C			1.8 V, I _{Load} = 3 mA	—	—	0.5	
5	D	Output low current Max total I _{OL} for all ports	I _{OLT}		—	—	100	mA
6	P	Input high voltage all digital inputs	V _{IH}	V _{DD} > 2.3 V	0.70 x V _{DD}	—	—	V
	C			V _{DD} ≤ 1.8 V	0.85 x V _{DD}	—	—	
7	P	Input low voltage all digital inputs	V _{IL}	V _{DD} > 2.7 V	—	—	0.35 x V _{DD}	
	C			V _{DD} ≤ 1.8 V	—	—	0.30 x V _{DD}	
8	C	Input hysteresis all digital inputs	V _{hys}		0.06 x V _{DD}	—	—	mV
9	P	Input leakage current all input only pins (Per pin)	I _{In}	V _{In} = V _{DD} or V _{SS}	—	—	1	μA
10	P	Hi-Z (off-state) leakage current all input/output (per pin)	I _{OZ}	V _{In} = V _{DD} or V _{SS}	—	—	1	μA
11	C	Total leakage combined for all inputs and Hi-Z pins All input only and I/O	I _{OZTOT}	V _{In} = V _{DD} or V _{SS}	—	—	2	μA
11	P	Pullup, Pulldown resistors all digital inputs, when enabled	R _{PU} , R _{PD}		17.5	—	52.5	kΩ
12	D	DC injection current ^{3, 4, 5} Single pin limit Total MCU limit, includes sum of all stressed pins	I _{IC}	V _{IN} < V _{SS} , V _{IN} > V _{DD}	-0.2	—	0.2	mA
					-5	—	5	mA
13	C	Input Capacitance, all pins	C _{In}		—	—	8	pF
14	C	RAM retention voltage	V _{RAM}		—	0.6	1.0	V
15	C	POR re-arm voltage ⁶	V _{POR}		0.9	1.4	2.0	V

Table 7. DC Characteristics (continued)

Num	C	Characteristic	Symbol	Condition	Min	Typical ¹	Max	Unit
16	D	POR re-arm time	t_{POR}		10	—	—	μs
17	P	Low-voltage detection threshold — high range	V_{LVDH}	V_{DD} falling V_{DD} rising	2.11 2.16	2.16 2.21	2.22 2.27	V
18	P	Low-voltage detection threshold — low range	V_{LVDL}	V_{DD} falling V_{DD} rising	1.80 1.88	1.82 1.90	1.91 1.99	V
19	P	Low-voltage warning threshold — high range	V_{LVWH}	V_{DD} falling V_{DD} rising	2.36 2.36	2.46 2.46	2.56 2.56	V
20	P	Low-voltage warning threshold — low range	V_{LVWL}	V_{DD} falling V_{DD} rising	2.11 2.16	2.16 2.21	2.22 2.27	V
21	C	Low-voltage inhibit reset/recover hysteresis	V_{hys}		—	80	—	mV
22	P	Bandgap Voltage Reference ⁷	V_{BG}		1.15	1.17	1.18	V

¹ Typical values are measured at 25 °C. Characterized, not tested

² As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above V_{LVDL} .

³ All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD} .

⁴ Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

⁵ Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{in} > V_{DD}$) is greater than I_{DD} , the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

⁶ Maximum is highest voltage that POR is guaranteed.

⁷ Factory trimmed at $V_{DD} = 3.0$ V, Temp = 25 °C

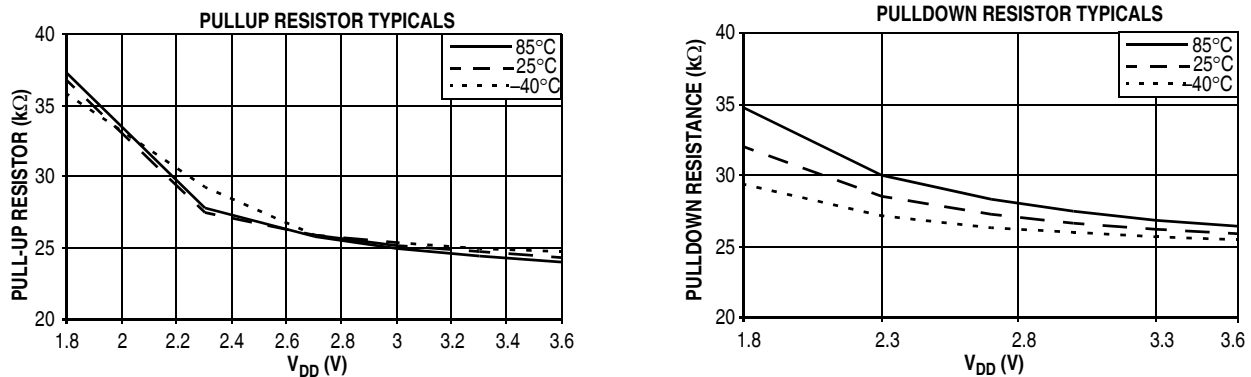


Figure 6. Pullup and Pulldown Typical Resistor Values ($V_{DD} = 3.0$ V)

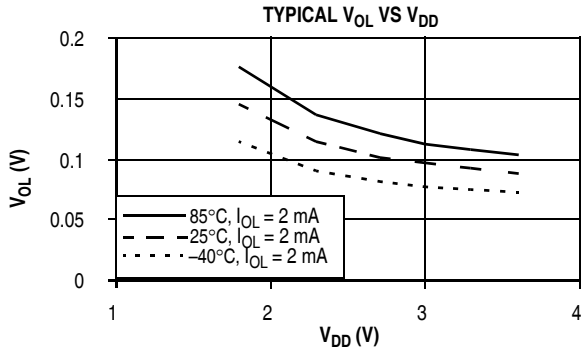
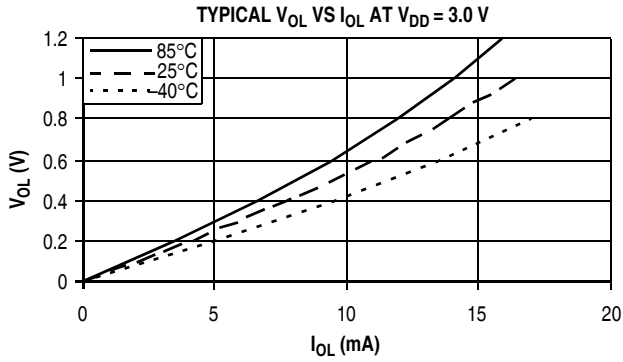


Figure 7. Typical Low-Side Driver (Sink) Characteristics — Low Drive (PTxDSn = 0)

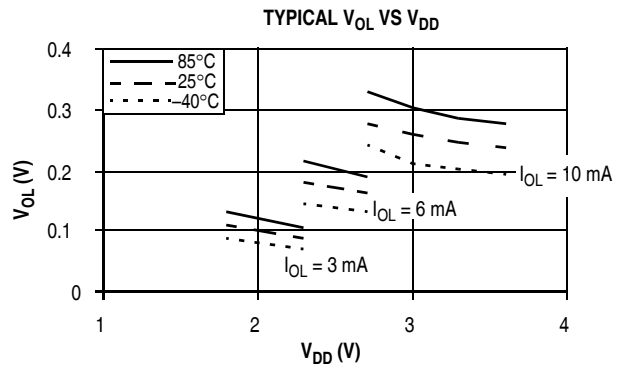
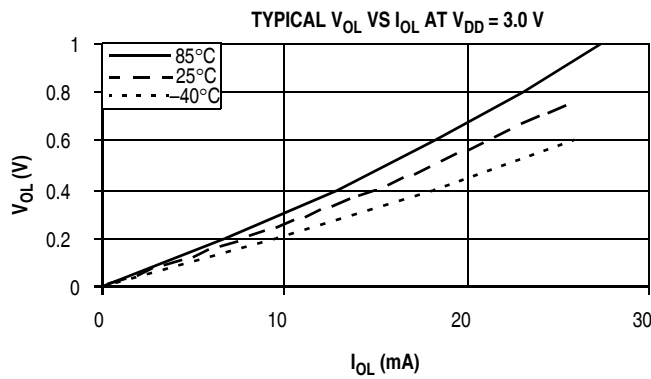


Figure 8. Typical Low-Side Driver (Sink) Characteristics — High Drive (PTxDSn = 1)

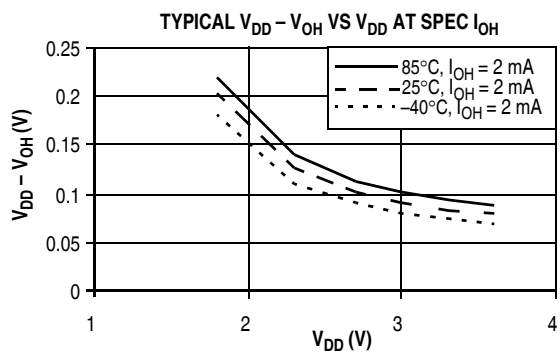
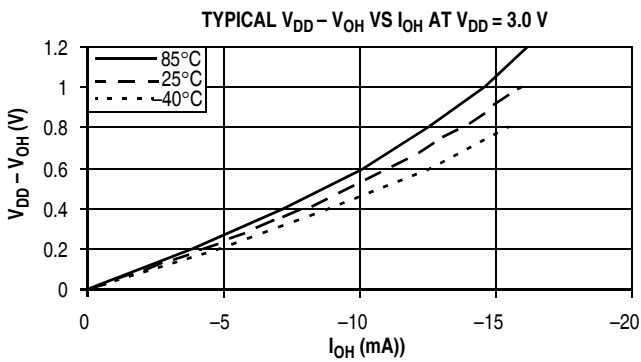


Figure 9. Typical High-Side (Source) Characteristics — Low Drive (PTxDSn = 0)

Table 8. Supply Current Characteristics (continued)

Num	C	Parameter	Symbol	Bus Freq	V _{DD} (V)	Typical ¹	Max	Unit	Temp (°C)	
6	P	Stop2 mode supply current	S2I _{DD}	—	3	0.35	0.65	μA	–40 to 25C	
	C			—		0.8	1.0		70	
	P			—		2.0	4.5		85	
	C			—	2	0.25	0.50		–40 to 25	
	C			—		0.65	0.85		70	
	C			—		1.5	3.5		85	
7	P	Stop3 mode supply current no clocks active	S3I _{DD}	—	3	0.45	1.00	μA	–40 to 25	
	C			—		1.5	2.3		70	
	P			—		4	8		85	
	C			—	2	0.35	0.70		–40 to 25	
	C			—		1	2		70	
	C			—		3.5	6.0		85	
8	T	Low power mode adders:	EREFSTEN=1	32 kHz	3	500	—	nA	–40 to 85	
9	T		IREFSTEN=1	32 kHz		70	—			μA
10	T		TPM PWM	100 Hz		12	—			μA
11	T		SCI, SPI, or IIC	300 bps		15	—			μA
12	T		RTC using LPO	1 kHz		200	—			nA
13	T		RTC using ICSERCLK	32 kHz		1	—			μA
14	T		LVD	n/a		100	—			μA
15	T		ACMP	n/a		20	—			μA

¹ Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

Table 9. Stop Mode Adders

Num	C	Parameter	Condition	Temperature				Units
				–40°C	25°C	70°C	85°C	
1	T	LPO	—	50	75	100	150	nA
2	T	EREFSTEN	RANGE = HGO = 0	1000	1000	1100	1500	nA
3	T	IREFSTEN ¹	—	63	70	77	81	μA
4	T	RTC	Does not include clock source current	50	75	100	150	nA
5	T	LVD ¹	LVDSE = 1	90	100	110	115	μA
6	T	ACMP ¹	Not using the bandgap (BGBE = 0)	18	20	22	23	μA
7	T	ADC ¹	ADLPC = ADLSMP = 1 Not using the bandgap (BGBE = 0)	95	106	114	120	μA

Electrical Characteristics

¹ Not available in stop2 mode.

3.8 External Oscillator (XOSCVLP) Characteristics

Reference [Figure 11](#) and [Figure 12](#) for crystal or resonator circuits.

Table 10. XOSC and ICS Specifications (Temperature Range = -40 to 85°C Ambient)

Num	C	Characteristic	Symbol	Min	Typical ¹	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1)					
		Low range (RANGE = 0)	f_{lo}	32	—	38.4	kHz
		High range (RANGE = 1), high gain (HGO = 1)	f_{hi}	1	—	16	MHz
		High range (RANGE = 1), low power (HGO = 0)	f_{hi}	1	—	8	MHz
2	D	Load capacitors					
		Low range (RANGE=0), low power (HGO=0) Other oscillator settings	C_1 C_2		See Note ² See Note ³		
3	D	Feedback resistor					
		Low range, low power (RANGE=0, HGO=0) ²	R_F	—	—	—	M Ω
		Low range, High Gain (RANGE=0, HGO=1)		—	10	—	
High range (RANGE=1, HGO=X)	—	1		—			
4	D	Series resistor —					
		Low range, low power (RANGE = 0, HGO = 0) ²	R_S	—	—	—	k Ω
		Low range, high gain (RANGE = 0, HGO = 1)		—	100	—	
		High range, low power (RANGE = 1, HGO = 0)		—	0	—	
		High range, high gain (RANGE = 1, HGO = 1)		—	0	0	
		≥ 8 MHz		—	0	10	
4 MHz	—	0		20			
		1 MHz	—	0	20		
5	C	Crystal start-up time ⁴					
		Low range, low power	t_{CSTL}	—	200	—	ms
		Low range, high power		—	400	—	
		High range, low power	t_{CSTH}	—	5	—	
		High range, high power		—	15	—	
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1)					
		FEE mode	f_{extal}	0.03125	—	40	MHz
		FBE or FBELP mode		0	—	40	MHz

¹ Data in Typical column is characterized at 3.0 V, 25 °C or is typical recommended value.

² Load capacitors (C_1, C_2), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE=HGO=0.

³ See crystal or resonator manufacturer's recommendation.

⁴ Proper PC board layout procedures must be followed to achieve specifications.

Table 11. ICS Frequency Specifications (Temperature Range = –40 to 85°C Ambient) (continued)

Num	C	Characteristic	Symbol	Min	Typical ¹	Max	Unit
8	C	Total deviation of trimmed DCO output frequency over voltage and temperature	Δf_{dco_t}	—	0.5 –1.0	±2	% f_{dco}
9	C	Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0 °C to 70 °C	Δf_{dco_t}	—	±0.5	±1	% f_{dco}
10	C	FLL acquisition time ³	$t_{Acquire}$	—	—	1	ms
11	C	Long term jitter of DCO output clock (averaged over 2-ms interval) ⁴	C_{Jitter}	—	0.02	0.2	% f_{dco}

¹ Data in Typical column is characterized at 3.0 V, 25 °C or is typical recommended value.

² The resulting bus clock frequency must not exceed the maximum specified bus clock frequency of the device.

³ This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

⁴ Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{BUS} . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

3.10 AC Characteristics

This section describes timing characteristics for each peripheral system.

3.10.1 Control Timing

Table 12. Control Timing

Num	C	Rating	Symbol	Min	Typical ¹	Max	Unit
1	D	Bus frequency ($t_{cyc} = 1/f_{Bus}$) $V_{DD} \leq 2.1V$ $2.1 < V_{DD} \leq 2.4V$ $V_{DD} > 2.4Vs$	f_{Bus}	DC	—	10 20 25.165	MHz
2	D	Internal low power oscillator period	t_{LPO}	700	—	1300	µs
3	D	External reset pulse width ²	t_{extrst}	100	—	—	ns
4	D	Reset low drive	t_{rstdrv}	$34 \times t_{cyc}$	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	t_{MSSU}	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes ³	t_{MSH}	100	—	—	µs
7	D	IRQ pulse width Asynchronous path ² Synchronous path ⁴	t_{ILIH}, t_{IHIL}	100 $1.5 \times t_{cyc}$	— —	— —	ns

Table 12. Control Timing (continued)

Num	C	Rating	Symbol	Min	Typical ¹	Max	Unit
8	D	Keyboard interrupt pulse width Asynchronous path ² Synchronous path ⁵	t_{LILH}, t_{IHIL}	100 $1.5 \times t_{cyc}$	— —	— —	ns
9	C	Port rise and fall time — Low output drive (PTxDS = 0) (load = 50 pF) ⁵ Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	— —	8 31	— —	ns
		Port rise and fall time — High output drive (PTxDS = 1) (load = 50 pF) Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	— —	7 24	— —	ns
10	C	Voltage regulator recovery time	t_{VRR}	—	4	—	μ s

¹ Typical values are based on characterization data at $V_{DD} = 3.0$ V, 25 °C unless otherwise stated.

² This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

³ To enter BDM mode following a POR, BKGD/MS must be held low during the power-up and for a hold time of t_{MSH} after V_{DD} rises above V_{LVD} .

⁴ This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

⁵ Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40 °C to 85 °C.

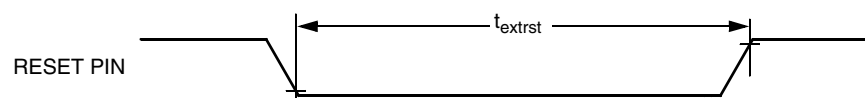
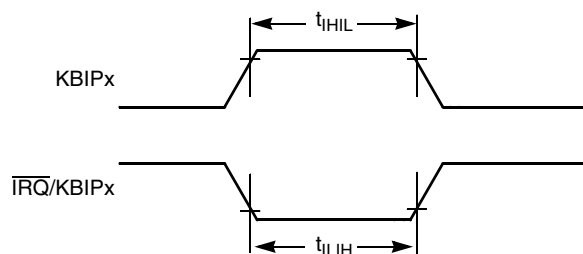


Figure 13. Reset Timing

Figure 14. $\overline{IRQ}/KBIPx$ Timing

3.10.2 TPM Module Timing

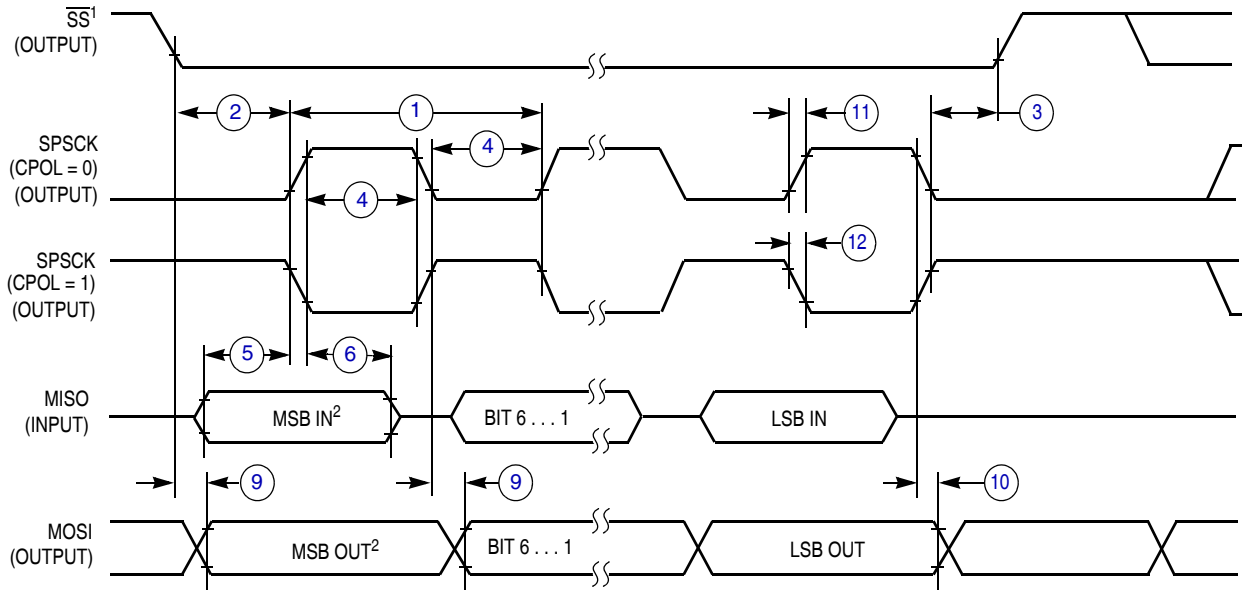
Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 14. SPI Timing (continued)

No.	C	Function	Symbol	Min	Max	Unit
4	D	Clock (SPSCK) high or low time Master Slave	t_{WSPSCK}	$t_{cyc} - 30$ $t_{cyc} - 30$	$1024 t_{cyc}$ —	ns ns
5	D	Data setup time (inputs) Master Slave	t_{SU}	15 15	— —	ns ns
6	D	Data hold time (inputs) Master Slave	t_{HI}	0 25	— —	ns ns
7	D	Slave access time	t_a	—	1	t_{cyc}
8	D	Slave MISO disable time	t_{dis}	—	1	t_{cyc}
9	D	Data valid (after SPSCK edge) Master Slave	t_v	— —	25 25	ns ns
10	D	Data hold time (outputs) Master Slave	t_{HO}	0 0	— —	ns ns
11	D	Rise time Input Output	t_{RI} t_{RO}	— —	$t_{cyc} - 25$ 25	ns ns
12	D	Fall time Input Output	t_{FI} t_{FO}	— —	$t_{cyc} - 25$ 25	ns ns

¹ Max operating frequency limited to 8 MHz when input filter disabled and high output drive strength enabled. Max operating frequency limited to 5 MHz when input filter enabled and high output drive strength disabled.

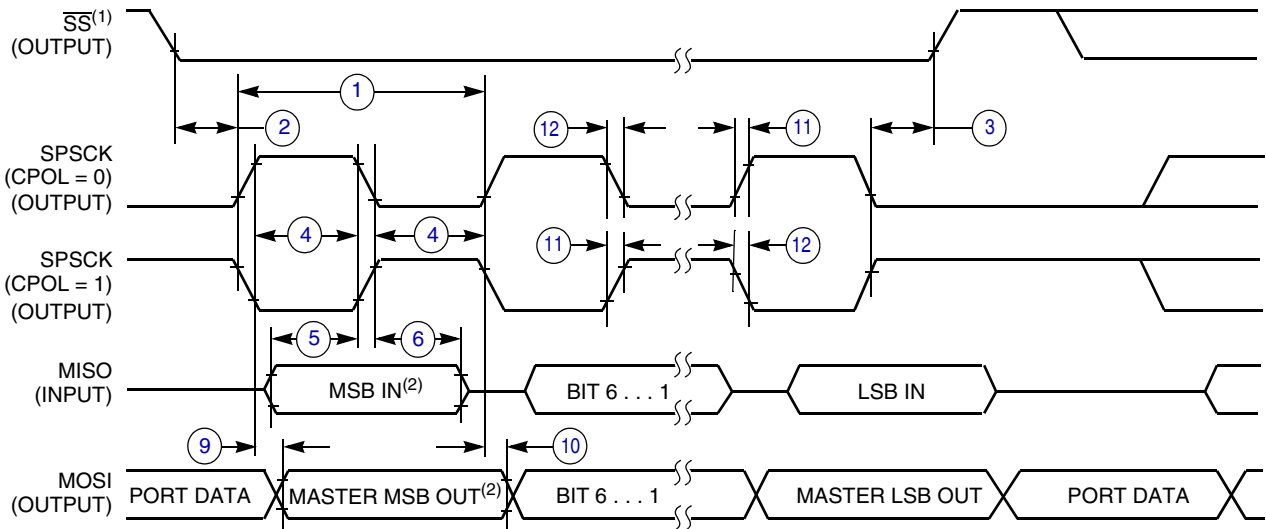
Electrical Characteristics



NOTES:

1. \overline{SS} output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

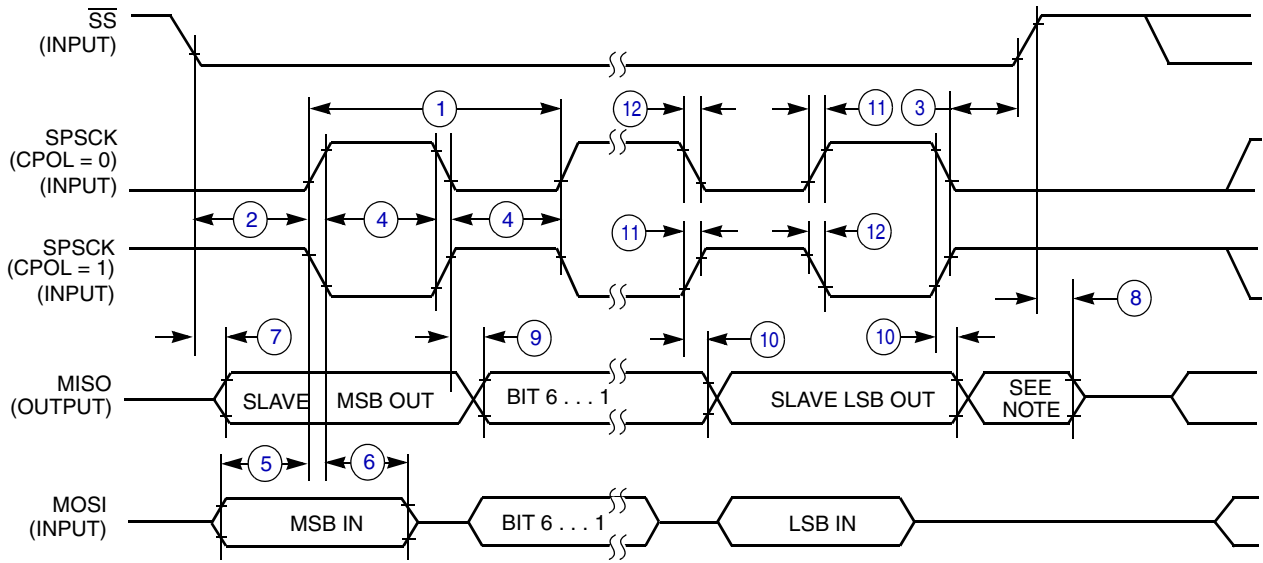
Figure 17. SPI Master Timing (CPHA = 0)



NOTES:

1. \overline{SS} output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

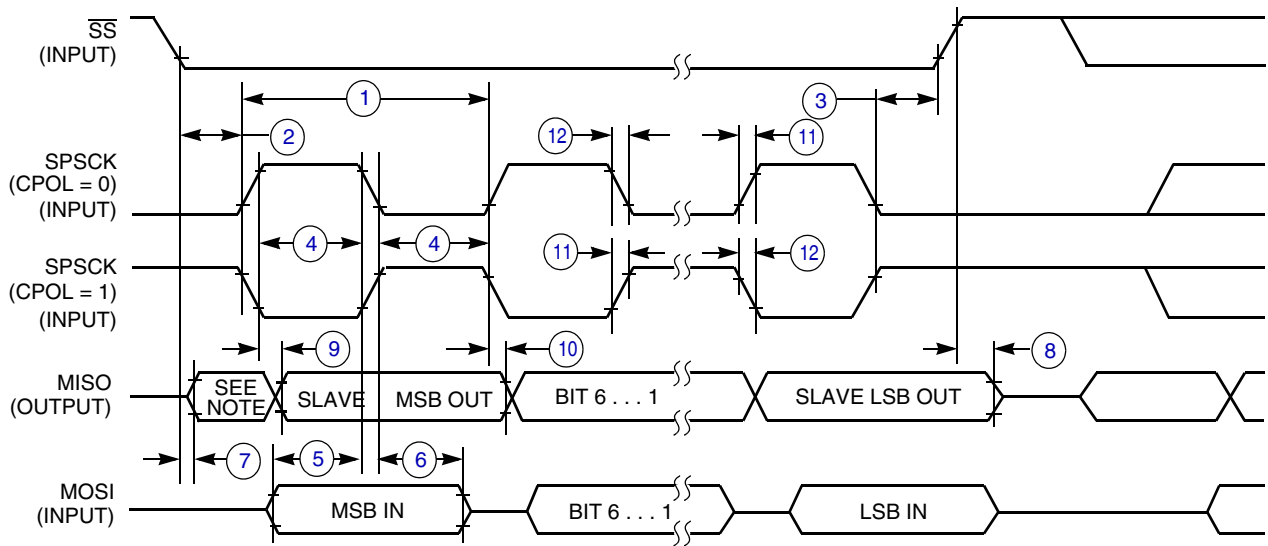
Figure 18. SPI Master Timing (CPHA = 1)



NOTE:

1. Not defined but normally MSB of character just received

Figure 19. SPI Slave Timing (CPHA = 0)



NOTE:

1. Not defined but normally LSB of character just received

Figure 20. SPI Slave Timing (CPHA = 1)

3.11 Analog Comparator (ACMP) Electricals

Table 15. Analog Comparator Electrical Specifications

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	V_{DD}	1.8	—	3.6	V
P	Supply current (active)	I_{DDAC}	—	20	35	μA
D	Analog input voltage	V_{AIN}	$V_{SS} - 0.3$	—	V_{DD}	V
P	Analog input offset voltage	V_{AIO}	—	20	40	mV
C	Analog comparator hysteresis	V_H	3.0	9.0	15.0	mV
P	Analog input leakage current	I_{ALKG}	—	—	1.0	μA
C	Analog comparator initialization delay	t_{AINIT}	—	—	1.0	μs

3.12 ADC Characteristics

Table 16. 12-Bit ADC Operating Conditions

C	Characteristic	Conditions	Symb	Min	Typical ¹	Max	Unit	Comment
D	Supply voltage	Absolute	V_{DDAD}	1.8	—	3.6	V	—
		Delta to V_{DD} ($V_{DD} - V_{DDAD}$) ²	ΔV_{DDAD}	-100	0	100	mV	—
D	Ground voltage	Delta to V_{SS} ($V_{SS} - V_{SSAD}$) ²	ΔV_{SSAD}	-100	0	100	mV	—
D	Input voltage	—	V_{ADIN}	V_{REFL}	—	V_{REFH}	V	—
C	Input capacitance	—	C_{ADIN}	—	4.5	5.5	pF	—
C	Input resistance	—	R_{ADIN}	—	5	7	k Ω	—
C	Analog source resistance	12-bit mode $f_{ADCK} > 4$ MHz $f_{ADCK} < 4$ MHz	R_{AS}	—	—	2	k Ω	External to MCU
		10-bit mode $f_{ADCK} > 4$ MHz $f_{ADCK} < 4$ MHz		—	—	5		
		8-bit mode (all valid f_{ADCK})		—	—	10		
D	ADC conversion clock freq.	High speed (ADLPC = 0)	f_{ADCK}	0.4	—	8.0	MHz	—
		Low power (ADLPC = 1)		0.4	—	4.0		

¹ Typical values assume $V_{DDAD} = 3.0$ V, Temp = 25 °C, $f_{ADCK} = 1.0$ MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

² DC potential difference.

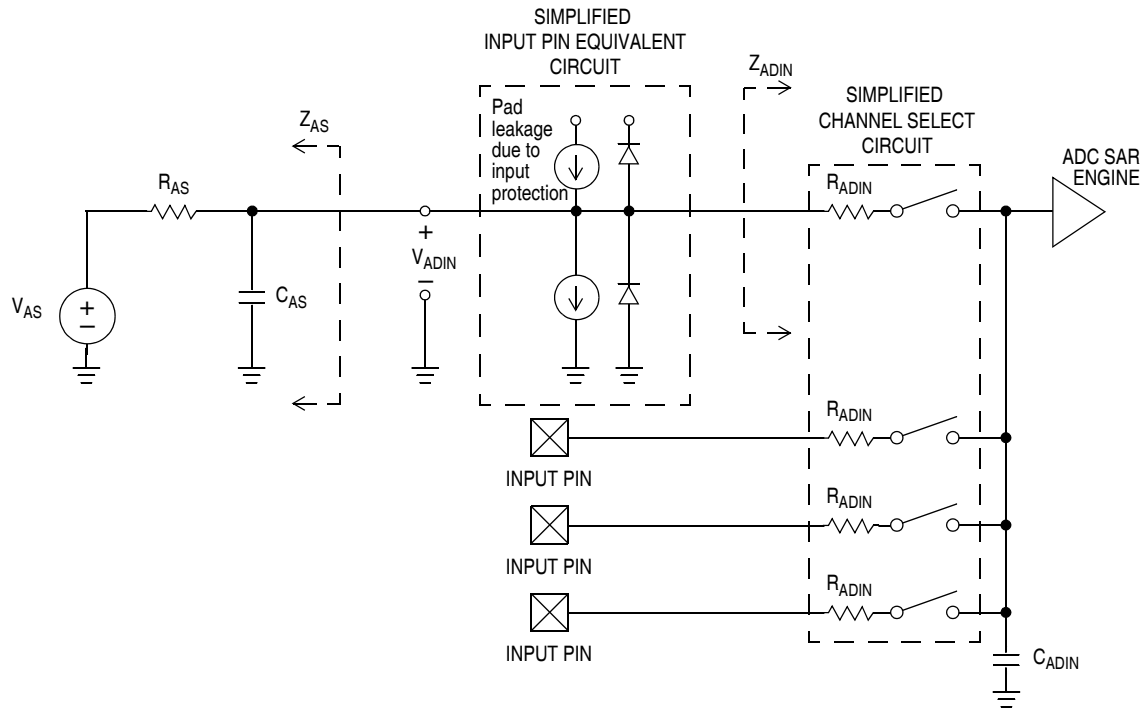


Figure 21. ADC Input Impedance Equivalency Diagram

Table 17. ADC Characteristics ($V_{REFH} = V_{DDAD}$, $V_{REFL} = V_{SSAD}$)

C	Characteristic	Conditions	Symbol	Min	Typ ¹	Max	Unit	Comment
T	Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		I_{DDAD}	—	120	—	μA	
T	Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		I_{DDAD}	—	202	—	μA	
T	Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		I_{DDAD}	—	288	—	μA	
P	Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		I_{DDAD}	—	0.532	1	mA	
P	ADC asynchronous clock source	High speed (ADLPC = 0)	f_{ADACK}	2	3.3	5	MHz	$t_{ADACK} = 1/f_{ADACK}$
		Low power (ADLPC = 1)		1.25	2	3.3		

- ¹ Typical values assume $V_{DDAD} = 3.0\text{ V}$, $\text{Temp} = 25\text{ }^\circ\text{C}$, $f_{ADCK} = 1.0\text{ MHz}$ unless otherwise stated. Typical values are for reference only and are not tested in production.
- ² $1\text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
- ³ Monotonicity and No-missing-codes guaranteed in 10-bit and 8-bit modes
- ⁴ Based on input pad leakage current. Refer to pad electricals.

3.13 Flash Specifications

This section provides details about program/erase times and program-erase endurance for flash memory. Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see MC9S08QE32 Series Reference Manual Chapter 4 Memory.

Table 18. Flash Characteristics

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage for program/erase -40 °C to 85 °C	$V_{\text{prog/erase}}$	1.8	—	3.6	V
D	Supply voltage for read operation	V_{Read}	1.8	—	3.6	V
D	Internal FCLK frequency ¹	f_{FCLK}	150	—	200	kHz
D	Internal FCLK period (1/FCLK)	t_{FcyC}	5	—	6.67	μs
P	Byte program time (random location) ⁽²⁾	t_{prog}	9			t_{FcyC}
P	Byte program time (burst mode) ⁽²⁾	t_{Burst}	4			t_{FcyC}
P	Page erase time ²	t_{Page}	4000			t_{FcyC}
P	Mass erase time ⁽²⁾	t_{Mass}	20,000			t_{FcyC}
	Byte program current ³	R_{IDDBP}	—	4	—	mA
	Page erase current ³	R_{IDDPPE}	—	6	—	mA
C	Program/erase endurance ⁴ T_L to $T_H = -40\text{ }^\circ\text{C}$ to $85\text{ }^\circ\text{C}$ $T = 25\text{ }^\circ\text{C}$		10,000	— 100,000	—	cycles
C	Data retention ⁵	$t_{\text{D_ret}}$	15	100	—	years

¹ The frequency of this clock is controlled by software setting.

² These values are hardware state machine controlled. User code does not need to count cycles. This information is supplied for calculating approximate time to program and erase.

³ The program and erase currents are additional to the standard run I_{DD} . These values are measured at room temperatures with $V_{DD} = 3.0\text{ V}$, bus frequency = 4.0 MHz.

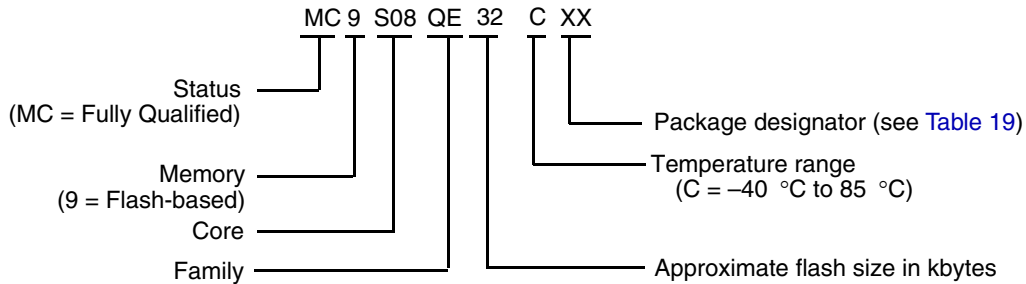
⁴ **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory*.

⁵ **Typical data retention** values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory*.

4 Ordering Information

This section contains ordering information for the MC9S08QE32 series of MCUs.

Example of the device numbering system:



5 Package Information

Table 19. Package Descriptions

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
48	Quad Flat No-Leads	QFN	FT	1314	98ARH99048A
44	Low Quad Flat Package	LQFP	LD	824D	98ASS23225W
32	Low Quad Flat Package	LQFP	LC	873A	98ASH70029A
32	Quad Flat No-Leads	QFN	FM	1582	98ARE10566D
28	Small Outline Integrated Circuit	SOIC	WL	751F	98ASB42345B

5.1 Mechanical Drawings

The following pages are mechanical drawings for the packages described in Table 19. For the latest available drawings please visit our web site (<http://www.freescale.com>) and enter the package's document number into the keyword search box.

How to Reach Us:

Home Page:

www.freescale.com

Web Support:

<http://www.freescale.com/support>

USA/Europe or Locations Not Listed:

Freescale Semiconductor, Inc.
Technical Information Center, EL516
2100 East Elliot Road
Tempe, Arizona 85284
1-800-521-6274 or +1-480-768-2130
www.freescale.com/support

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH
Technical Information Center
Schatzbogen 7
81829 Muenchen, Germany
+44 1296 380 456 (English)
+46 8 52200080 (English)
+49 89 92103 559 (German)
+33 1 69 35 48 48 (French)
www.freescale.com/support

Japan:

Freescale Semiconductor Japan Ltd.
Headquarters
ARCO Tower 15F
1-8-1, Shimo-Meguro, Meguro-ku,
Tokyo 153-0064
Japan
0120 191014 or +81 3 5437 9125
support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor China Ltd.
Exchange Building 23F
No. 118 Jianguo Road
Chaoyang District
Beijing 100022
China
+86 10 5879 8000
support.asia@freescale.com

For Literature Requests Only:

Freescale Semiconductor Literature Distribution Center
P.O. Box 5405
Denver, Colorado 80217
1-800-441-2447 or +1-303-675-2140
Fax: +1-303-675-2150
LDCForFreescaleSemiconductor@hibbertgroup.com

Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductor products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document.

Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals", must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.



Freescale™ and the Freescale logo are trademarks of Freescale Semiconductor, Inc. All other product or service names are the property of their respective owners.

© Freescale Semiconductor, Inc. 2008-2011. All rights reserved.