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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	75MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	DMA, WDT
Number of I/O	28
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 16x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mkv10z32vlc7

Ordering Information ¹

Part Number	Memory		Maximum number of I/O's
	Flash (KB)	SRAM (KB)	
MKV10Z32VLC7	32	8	28
MKV10Z32VFM7	32	8	28
MKV10Z32VLF7	32	8	40
MKV10Z16VLC7	16	8	28
MKV10Z16VFM7	16	8	28
MKV10Z16VLF7	16	8	40

1. To confirm current availability of orderable part numbers, go to <http://www.freescale.com> and perform a part number search.

Related Resources

Type	Description	Resource
Selector Guide	The Freescale Solution Advisor is a web-based tool that features interactive application wizards and a dynamic product selector.	Solution Advisor
Product Brief	The Product Brief contains concise overview/summary information to enable quick evaluation of a device for design suitability.	KV10PB ¹
Reference Manual	The Reference Manual contains a comprehensive description of the structure and function (operation) of a device.	KV10P48M75RM ¹
Data Sheet	The Data Sheet includes electrical characteristics and signal connections.	This document
Chip Errata	The chip mask set Errata provides additional or corrective information for a particular device mask set.	KV10Z_1N81H ¹
Package drawing	Package dimensions are provided in package drawings.	QFN 32-pin: 98ASA00473D ¹ LQFP 32-pin: 98ASH70029A ¹ LQFP 48-pin: 98ASH00962A ¹

1. To find the associated resource, go to <http://www.freescale.com> and perform a search using this term.

1 Ratings

1.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T _{STG}	Storage temperature	−55	150	°C	1
T _{SDR}	Solder temperature, lead-free	—	260	°C	2

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

1.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

1.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V _{HBM}	Electrostatic discharge voltage, human-body model	−2000	+2000	V	1
V _{CDM}	Electrostatic discharge voltage, charged-device model	−500	+500	V	2
I _{LAT}	Latch-up current at ambient temperature of 105 °C	−100	+100	mA	

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

1.4 Voltage and current operating ratings

2.2.3 Voltage and current operating behaviors

Table 3. Voltage and current operating behaviors

Symbol	Description	Min.	Max.	Unit	Notes
V_{OH}	Output high voltage — Normal drive pad				
	All port pins, except PTC6 and PTC7	$V_{DD} - 0.5$	—	V	
	<ul style="list-style-type: none"> $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OH} = -5\text{ mA}$ $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OH} = -1.5\text{ mA}$ 	$V_{DD} - 0.5$	—	V	
V_{OH}	Output high voltage — High drive pad				
	PTB0, PTB1, PTC3, PTC4, PTD4, PTD5, PTD6, PTD7 pins	$V_{DD} - 0.5$	—	V	
	<ul style="list-style-type: none"> $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OH} = -18\text{ mA}$ $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OH} = -6\text{ mA}$ 	$V_{DD} - 0.5$	—	V	
I_{OHT}	Output high current total for all ports	—	100	mA	
V_{OL}	Output low voltage — Normal drive pad				
	All port pins	—	0.5	V	
	<ul style="list-style-type: none"> $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OL} = 5\text{ mA}$ $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OL} = 1.5\text{ mA}$ 	—	0.5	V	
V_{OL}	Output low voltage — High drive pad				
	PTB0, PTB1, PTC3, PTC4, PTD4, PTD5, PTD6, PTD7 pins	—	0.5	V	
	<ul style="list-style-type: none"> $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OL} = 18\text{ mA}$ $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OL} = 6\text{ mA}$ 	—	0.5	V	
I_{OLT}	Output low current total for all ports	—	100	mA	
I_{IN}	Input leakage current (per pin) for full temperature range	—	1	μA	
I_{IN}	Input leakage current (per pin) at 25 °C	—	0.025	μA	1
I_{IN}	Input leakage current (total all pins) for full temperature range	—	41	μA	1
I_{OZ}	Hi-Z (off-state) leakage current (per pin)	—	1	μA	
R_{PU}	Internal pullup resistors	20	50	k Ω	2

1. Measured at $V_{DD} = 3.6\text{ V}$

2. Measured at V_{DD} supply voltage = V_{DD} min and $V_{input} = V_{SS}$

2.2.4 Power mode transition operating behaviors

All specifications except t_{POR} and $VLLSx \rightarrow RUN$ recovery times in the following table assume this clock configuration:

- CPU and system clocks = 75 MHz
- Bus and flash clock = 25 MHz
- FEI clock mode

Table 4. Power mode transition operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
t_{POR}	After a POR event, amount of time from the point V_{DD} reaches 1.8 V to execution of the first instruction across the operating temperature range of the chip.	—	—	300	μs	
	• $VLLS0 \rightarrow RUN$	—	106	115	μs	
	• $VLLS1 \rightarrow RUN$	—	106	115	μs	
	• $VLLS3 \rightarrow RUN$	—	47	53	μs	
	• $VLPS \rightarrow RUN$	—	4.5	4.8	μs	
	• $STOP \rightarrow RUN$	—	4.5	4.8	μs	

2.2.5 Power consumption operating behaviors

NOTE

The maximum values stated in the following table represent characterized results equivalent to the mean plus six times the standard deviation (mean + 6 sigma).

Table 5. Power consumption operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I_{DDA}	Analog supply current	—	—	5	mA	1
I_{DD_RUN}	Run mode current — all peripheral clocks disabled, code executing from flash <ul style="list-style-type: none"> • at 1.8 V 50 MHz (25 MHz Bus) 	—	5	6.3	mA	Target IDD

Table continues on the next page...

Table 5. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	<ul style="list-style-type: none"> at 3.0 V 50 MHz (25 MHz Bus) at 1.8 V 75 MHz (25 MHz Bus) at 3.0 V 75 MHz (25 MHz Bus) 	—	5	6.3	mA	
		—	6.5	7.8	mA	
		—	6.5	7.5	mA	
I _{DD_RUN}	Run mode current — all peripheral clocks enabled, code executing from flash <ul style="list-style-type: none"> at 1.8 V 50 MHz at 3.0 V 50 MHz at 1.8 V 75 MHz at 3.0 V 75 MHz 	—	7.1	8.2	mA	Target IDD
		—	7.1	8	mA	
		—	9.4	10.9	mA	
		—	9.4	10.6	mA	
I _{DD_WAIT}	Wait mode high frequency 75 MHz current at 3.0 V — all peripheral clocks disabled	—	4	5.2	mA	—
I _{DD_WAIT}	Wait mode reduced frequency 50 MHz current at 3.0 V — all peripheral clocks disabled	—	3.4	4.7	mA	—
I _{DD_VLPR}	Very-Low-Power Run mode current 4 MHz at 3.0 V — all peripheral clocks disabled	—	215	437	μA	4 MHz CPU speed, 1 MHz bus speed.
I _{DD_VLPR}	Very-Low-Power Run mode current 4 MHz at 3.0 V — all peripheral clocks enabled	—	313	570	μA	4 MHz CPU speed, 1 MHz bus speed.
I _{DD_VLPW}	Very-Low-Power Wait mode current at 3.0 V — all peripheral clocks disabled	—	149	303	μA	4 MHz CPU speed, 1 MHz bus speed.
I _{DD_VLPW}	Very-Low-Power Wait mode current at 3.0 V — all peripheral clocks enabled	—	244	347	μA	4 MHz CPU speed, 1 MHz bus speed.
I _{DD_STOP}	Stop mode current at 3.0 V <ul style="list-style-type: none"> -40 °C to 25 °C at 50 °C at 70 °C at 85 °C at 105 °C 	—	248	280	μA	—
		—	261	315		
		—	278	333		
		—	307	435		
		—	381	510		
I _{DD_VLPS}	Very-Low-Power Stop mode current at 3.0 V <ul style="list-style-type: none"> -40 °C to 25 °C at 50 °C 	—	2.2	4.3		—
		—	4.2	9.9		

Table continues on the next page...

Table 5. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	<ul style="list-style-type: none"> at 70 °C at 85 °C at 105 °C 	—	8.8	24	μA	
I _{DD_VLLS3}	Very-Low-Leakage Stop mode 3 current at 3.0 V <ul style="list-style-type: none"> -40 °C to 25 °C at 50 °C at 70 °C at 85 °C at 105 °C 	—	1.3	5.7	μA	—
		—	1.9	6.1		
		—	3.3	7.4		
		—	5.8	11.2		
		—	13	18		
I _{DD_VLLS1}	Very-Low-Leakage Stop mode 1 current at 3.0 V <ul style="list-style-type: none"> -40°C to 25°C at 50°C at 70°C at 85°C at 105°C 	—	0.8	3.0	μA	—
		—	1.2	4.9		
		—	2.2	7.0		
		—	4	12.5		
		—	9.4	29.0		
I _{DD_VLLS0}	Very-Low-Leakage Stop mode 0 current (SMC_STOPCTRL[PORPO] = 0) at 3.0 V <ul style="list-style-type: none"> -40 °C to 25 °C at 50 °C at 70 °C at 85 °C at 105 °C 	—	0.279	0.7	μA	—
		—	0.638	1.2		
		—	1.63	2.5		
		—	3.4	4.5		
		—	8.9	12.0		
I _{DD_VLLS0}	Very-Low-Leakage Stop mode 0 current (SMC_STOPCTRL[PORPO] = 1) at 3.0 V <ul style="list-style-type: none"> -40 °C to 25 °C at 50 °C at 70 °C at 85 °C at 105 °C 	—	0.098	0.485	μA	2
		—	0.448	0.788		
		—	1.4	2.29		
		—	3.19	4.14		
		—	8.47	11.8		

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. No brownout

Table 6. Low power mode peripheral adders — typical value

Symbol	Description	Temperature (°C)						Unit
		-40	25	50	70	85	105	
I _{IREFSTEN4MHz}	4 MHz internal reference clock (IRC) adder. Measured by entering STOP or VLPS mode with 4 MHz IRC enabled.	56	56	56	56	56	56	μA
I _{IREFSTEN32KHz}	32 kHz internal reference clock (IRC) adder. Measured by entering STOP mode with the 32 kHz IRC enabled.	52	52	52	52	52	52	μA
I _{EREFSTEN4MHz}	External 4 MHz crystal clock adder. Measured by entering STOP or VLPS mode with the crystal enabled.	206	228	237	245	251	258	uA
I _{EREFSTEN32KHz}	External 32 kHz crystal clock adder by means of the OSC0_CR[EREFSTEN and EREFSTEN] bits. Measured by entering all modes with the crystal enabled.	440	490	540	560	570	580	nA
	VLLS1	440	490	540	560	570	580	
	VLLS3	510	560	560	560	610	680	
	VLPS	510	560	560	560	610	680	
	STOP							
I _{CMP}	CMP peripheral adder measured by placing the device in VLLS1 mode with CMP enabled using the 6-bit DAC and a single external input for compare. Includes 6-bit DAC power consumption.	22	22	22	22	22	22	μA
I _{UART}	UART peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source waiting for RX data at 115200 baud rate. Includes selected clock source power consumption.							μA
	MCGIRCLK (4 MHz internal reference clock)	66	66	66	66	66	66	
	OSCERCLK (4 MHz external crystal)	214	237	246	254	260	268	
I _{SPI}	SPI peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source waiting for RX data at 115200 baud rate. Includes selected clock source power consumption.							μA
	MCGIRCLK (4 MHz internal reference clock)	66	66	66	66	66	66	
	OSCERCLK (4 MHz external crystal)	214	237	246	254	260	268	
I _{I2C}	I2C peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source							

Table continues on the next page...

2.4 Thermal specifications

2.4.1 Thermal operating requirements

Table 11. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit
T _J	Die junction temperature	−40	125	°C
T _A	Ambient temperature	−40	105	°C

NOTE

Maximum T_A can be exceeded only if the user ensures that T_J does not exceed maximum T_J. The simplest method to determine T_J is: $T_J = T_A + \theta_{JA} \times \text{chip power dissipation}$.

2.4.2 Thermal attributes

Table 12. Thermal attributes

Board type	Symbol	Description	48 LQFP	32 LQFP	32 QFN	Unit	Notes
Single-layer (1S)	R _{θJA}	Thermal resistance, junction to ambient (natural convection)	81	85	98	°C/W	1
Four-layer (2s2p)	R _{θJA}	Thermal resistance, junction to ambient (natural convection)	57	57	34	°C/W	
Single-layer (1S)	R _{θJMA}	Thermal resistance, junction to ambient (200 ft./min. air speed)	68	72	82	°C/W	
Four-layer (2s2p)	R _{θJMA}	Thermal resistance, junction to ambient (200 ft./min. air speed)	51	50	28	°C/W	
—	R _{θJB}	Thermal resistance, junction to board	35	33	14	°C/W	2
—	R _{θJC}	Thermal resistance, junction to case	25	25	2.5	°C/W	3
—	Ψ _{JT}	Thermal characterization parameter, junction to package top outside center (natural convection)	7	7	8	°C/W	4

1. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*, or EIA/JEDEC Standard JESD51-6, *Integrated Circuit Thermal Test Method Environmental Conditions—Forced Convection (Moving Air)*.
2. Determined according to JEDEC Standard JESD51-8, *Integrated Circuit Thermal Test Method Environmental Conditions—Junction-to-Board*.

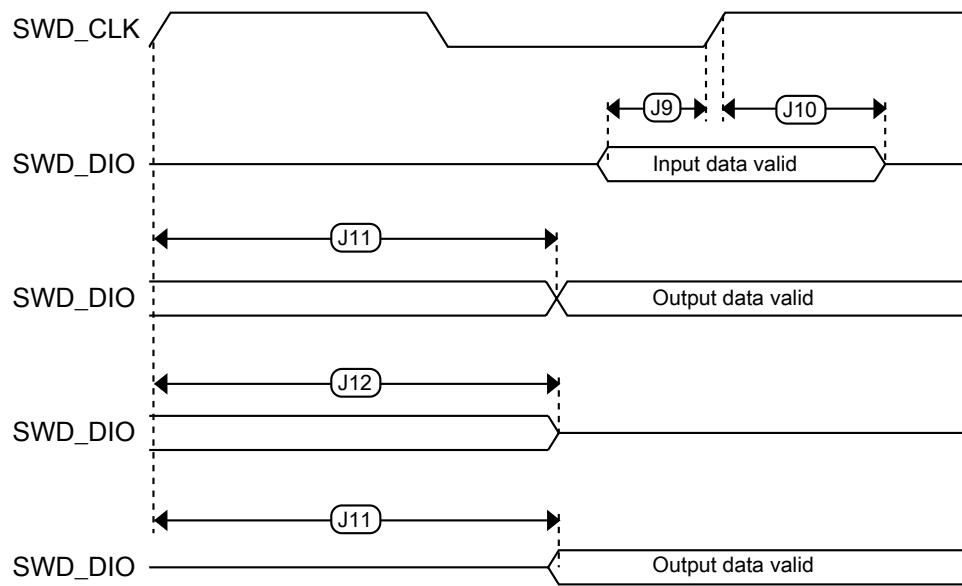


Figure 6. Serial wire data timing

3.2 System modules

There are no specifications necessary for the device's system modules.

3.3 Clock modules

3.3.1 MCG specifications

Table 14. MCG specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{ints_ft}	Internal reference frequency (slow clock) — factory trimmed at nominal V_{DD} and 25 °C	—	32.768	—	kHz	
f_{ints_t}	Internal reference frequency (slow clock) — user trimmed	31.25	—	39.0625	kHz	
$\Delta f_{dco_res_t}$	Resolution of trimmed average DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM	—	± 0.3	± 0.6	$\%f_{dco}$	1

Table continues on the next page...

4. The resulting system clock frequencies must not exceed their maximum specified values. The DCO frequency deviation (Δf_{dco_1}) over voltage and temperature must be considered.
5. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32 = 1.
6. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
7. This specification is based on standard deviation (RMS) of period or frequency.
8. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or there is a change from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

3.3.2 Oscillator electrical specifications

3.3.2.1 Oscillator DC electrical specifications

Table 15. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{DD}	Supply voltage	1.71	—	3.6	V	
I_{DDOSC}	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> 32 kHz 4 MHz 8 MHz 16 MHz 24 MHz 32 MHz 	—	500	—	nA	1
		—	200	—	μA	
		—	300	—	μA	
		—	950	—	μA	
		—	1.2	—	mA	
		—	1.5	—	mA	
I_{DDOSC}	Supply current — high gain mode (HGO=1) <ul style="list-style-type: none"> 4 MHz 8 MHz 16 MHz 24 MHz 32 MHz 	—	500	—	μA	1
		—	600	—	μA	
		—	2.5	—	mA	
		—	3	—	mA	
		—	4	—	mA	
C_x	EXTAL load capacitance	—	—	—		2, 3
C_y	XTAL load capacitance	—	—	—		2, 3
R_F	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	—	—	M Ω	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	—	10	—	M Ω	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	—	—	M Ω	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1	—	M Ω	

Table continues on the next page...

Table 15. Oscillator DC electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
R_S	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	k Ω	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	k Ω	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	k Ω	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	k Ω	
V_{pp} ⁵	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	—	V_{DD}	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	—	V_{DD}	—	V	

1. V_{DD} =3.3 V, Temperature =25 °C
2. See crystal or resonator manufacturer's recommendation
3. C_x, C_y can be provided by using the integrated capacitors when the low frequency oscillator (RANGE = 00) is used. For all other cases external capacitors must be used.
4. When low power mode is selected, R_F is integrated and must not be attached externally.
5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

3.3.2.2 Oscillator frequency specifications

Table 16. Oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{osc_lo}	Oscillator crystal or resonator frequency — low-frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
$f_{osc_hi_1}$	Oscillator crystal or resonator frequency — high-frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	
$f_{osc_hi_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	8	—	32	MHz	
f_{ec_extal}	Input clock frequency (external clock mode)	—	—	50	MHz	1, 2
t_{dc_extal}	Input clock duty cycle (external clock mode)	40	50	60	%	

Table continues on the next page...

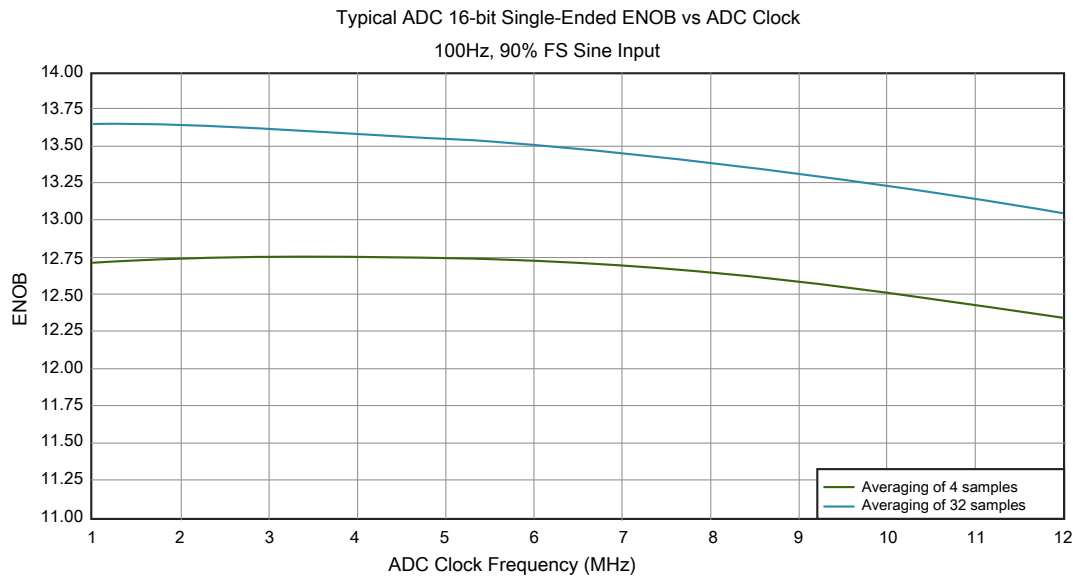


Figure 9. Typical ENOB vs. ADC_CLK for 16-bit single-ended mode

3.6.2 CMP and 6-bit DAC electrical specifications

Table 23. Comparator and 6-bit DAC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V_{DD}	Supply voltage	1.71	—	3.6	V
I_{DDHS}	Supply current, high-speed mode (EN = 1, PMODE = 1)	—	—	200	μ A
$I_{DDL S}$	Supply current, low-speed mode (EN = 1, PMODE = 0)	—	—	20	μ A
V_{AIN}	Analog input voltage	V_{SS}	—	V_{DD}	V
V_{AIO}	Analog input offset voltage	—	—	20	mV
V_H	Analog comparator hysteresis ¹ <ul style="list-style-type: none"> CR0[HYSTCTR] = 00 CR0[HYSTCTR] = 01 CR0[HYSTCTR] = 10 CR0[HYSTCTR] = 11 	—	5 10 20 30	—	mV mV mV mV
V_{CMPOh}	Output high	$V_{DD} - 0.5$	—	—	V
V_{CMPOl}	Output low	—	—	0.5	V
t_{DHS}	Propagation delay, high-speed mode (EN = 1, PMODE = 1)	20	35	200	ns
t_{DLS}	Propagation delay, low-speed mode (EN = 1, PMODE = 0)	80	100	600	ns
	Analog comparator initialization delay ²	—	—	40	μ s

Table continues on the next page...

Table 25. 12-bit DAC operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
t_{DACHP}	Full-scale settling time (0x080 to 0xF7F) — high-power mode	—	15	30	μs	1
t_{CCDACLP}	Code-to-code settling time (0xBF8 to 0xC08)—high-speed mode	—	1	—	μs	1
	—low-power mode	—	—	5	μs	1
V_{dacoutl}	DAC output voltage range low — high-speed mode, no load, DAC set to 0x000	—	—	100	mV	
V_{dacouth}	DAC output voltage range high — high-speed mode, no load, DAC set to 0xFFF	$V_{\text{DACR}} - 100$	—	V_{DACR}	mV	
INL	Integral non-linearity error — high speed mode	—	—	± 8	LSB	2
DNL	Differential non-linearity error — $V_{\text{DACR}} > 2 \text{ V}$	—	—	± 1	LSB	3
DNL	Differential non-linearity error — $V_{\text{DACR}} = V_{\text{REF_OUT}}$	—	—	± 1	LSB	4
V_{OFFSET}	Offset error	—	± 0.4	± 0.8	%FSR	5
E_{G}	Gain error	—	± 0.1	± 0.6	%FSR	5
PSRR	Power supply rejection ratio, $V_{\text{DDA}} \geq 2.4 \text{ V}$	60	—	90	dB	
T_{CO}	Temperature coefficient offset voltage	—	3.7	—	$\mu\text{V/C}$	6
T_{GE}	Temperature coefficient gain error	—	0.000421	—	%FSR/C	
R_{op}	Output resistance (load = 3 k Ω)	—	—	250	Ω	
SR	Slew rate -80h → F7Fh → 80h				V/ μs	
	<ul style="list-style-type: none"> High power (SP_{HP}) Low power (SP_{LP}) 	1.2 0.05	1.7 0.12	— —		
BW	3dB bandwidth				kHz	
	<ul style="list-style-type: none"> High power (SP_{HP}) Low power (SP_{LP}) 	550 40	— —	— —		

- Settling within ± 1 LSB
- The INL is measured for 0 + 100 mV to $V_{\text{DACR}} - 100 \text{ mV}$
- The DNL is measured for 0 + 100 mV to $V_{\text{DACR}} - 100 \text{ mV}$
- The DNL is measured for 0 + 100 mV to $V_{\text{DACR}} - 100 \text{ mV}$ with $V_{\text{DDA}} > 2.4 \text{ V}$
- Calculated by a best fit curve from $V_{\text{SS}} + 100 \text{ mV}$ to $V_{\text{DACR}} - 100 \text{ mV}$
- $V_{\text{DDA}} = 3.0 \text{ V}$, reference select set for V_{DDA} ($\text{DACx_CO:DACRFS} = 1$), high power mode ($\text{DACx_CO:LPEN} = 0$), DAC set to 0x800, temperature range is across the full range of the device

3.8.1 DSPI switching specifications (limited voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

Table 26. Master mode DSPI timing (limited voltage range)

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	25	MHz	
DS1	DSPI_SCK output cycle time	$2 \times t_{\text{BUS}}$	—	ns	
DS2	DSPI_SCK output high/low time	$(t_{\text{SCK}}/2) - 2$	$(t_{\text{SCK}}/2) + 2$	ns	
DS3	DSPI_PCSn valid to DSPI_SCK delay	$(t_{\text{BUS}} \times 2) - 2$	—	ns	1
DS4	DSPI_SCK to DSPI_PCSn invalid delay	$(t_{\text{BUS}} \times 2) - 2$	—	ns	2
DS5	DSPI_SCK to DSPI_SOUT valid	—	8.5	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	-2	—	ns	
DS7	DSPI_SIN to DSPI_SCK input setup	17	—	ns	
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns	

1. The delay is programmable in SPIx_CTARn[PSSCK] and SPIx_CTARn[CSSCK].
2. The delay is programmable in SPIx_CTARn[PASC] and SPIx_CTARn[ASC].

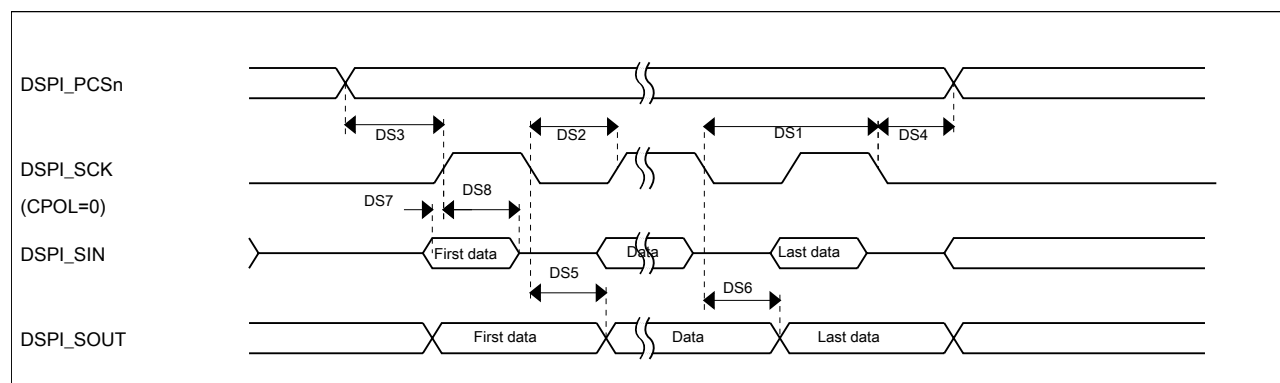


Figure 14. DSPI classic SPI timing — master mode

Table 27. Slave mode DSPI timing (limited voltage range)

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation		12.5	MHz

Table continues on the next page...

5 Pinout

5.1 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

NOTE

- PTB0, PTB1, PTC3, PTC4, PTD4, PTD5, PTD6, PTD7 are high current pins.
- PTC6 and PTC7 have open drain outputs

48 LQFP	32 QFN	32 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
1	1	1	VDD	VDD	VDD							
2	2	2	VSS	VSS	VSS							
3	3	3	PTE16	ADC0_SE1/ ADC0_DP1/ ADC1_SE0	ADC0_SE1/ ADC0_DP1/ ADC1_SE0	PTE16	SPI0_PCS0/ SS_b	UART1_TX	FTM_CLKIN0		FTM0_FLT3	
4	4	4	PTE17	ADC0_SE5/ ADC0_DM1/ ADC1_SE5	ADC0_SE5/ ADC0_DM1/ ADC1_SE5	PTE17	SPI0_SCK	UART1_RX	FTM_CLKIN1		LPTMR0_ ALT3	
5	5	5	PTE18	ADC0_SE6/ ADC1_SE1/ ADC1_DP1	ADC0_SE6/ ADC1_SE1/ ADC1_DP1	PTE18	SPI0_SOUT	UART1_ CTS_b	I2C0_SDA		SPI0_SIN	
6	6	6	PTE19	ADC0_SE7/ ADC1_SE7/ ADC1_DM1	ADC0_SE7/ ADC1_SE7/ ADC1_DM1	PTE19	SPI0_SIN	UART1_ RTS_b	I2C0_SCL		SPI0_SOUT	
7	—	—	PTE20	ADC0_SE0/ ADC0_DP0	ADC0_SE0/ ADC0_DP0	PTE20		FTM1_CH0	UART0_TX			
8	—	—	PTE21	ADC0_SE4/ ADC0_DM0	ADC0_SE4/ ADC0_DM0	PTE21		FTM1_CH1	UART0_RX			
9	7	7	VDDA	VDDA	VDDA							
10	7	7	VREFH	VREFH	VREFH							
11	8	8	VREFL	VREFL	VREFL							
12	8	8	VSSA	VSSA	VSSA							
13	—	—	PTE29	CMP1_IN5/ CMP0_IN5	CMP1_IN5/ CMP0_IN5	PTE29		FTM0_CH2		FTM_CLKIN0		
14	9	9	PTE30	ADC1_SE4/ CMP0_IN4/ CMP1_IN4/ DAC0_OUT	ADC1_SE4/ CMP0_IN4/ CMP1_IN4/ DAC0_OUT	PTE30		FTM0_CH3		FTM_CLKIN1		

48 LQFP	32 QFN	32 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
41	—	—	PTD0	DISABLED		PTD0/ LLWU_P12	SPI0_PCS0/ SS_b	UART0_ CTS_b	FTM0_CH0	UART1_RX		
42	—	—	PTD1	ADC0_SE2	ADC0_SE2	PTD1	SPI0_SCK	UART0_ RTS_b	FTM0_CH1	UART1_TX		
43	—	—	PTD2	DISABLED		PTD2/ LLWU_P13	SPI0_SOUT	UART0_RX	FTM0_CH2			I2C0_SCL
44	—	—	PTD3	DISABLED		PTD3	SPI0_SIN	UART0_TX	FTM0_CH3			I2C0_SDA
45	29	29	PTD4	DISABLED		PTD4/ LLWU_P14	SPI0_PCS1	UART0_ RTS_b	FTM0_CH4	FTM2_CH0	EWM_IN	
46	30	30	PTD5	ADC0_SE3	ADC0_SE3	PTD5	SPI0_PCS2	UART0_ CTS_b	FTM0_CH5	FTM2_CH1	EWM_OUT_b	
47	31	31	PTD6	ADC1_SE6	ADC1_SE6	PTD6/ LLWU_P15	SPI0_PCS3	UART0_RX	FTM0_CH0	FTM1_CH0	FTM0_FLT0	
48	32	32	PTD7	DISABLED		PTD7		UART0_TX	FTM0_CH1	FTM1_CH1	FTM0_FLT1	

5.2 KV10 Pinouts

The following figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

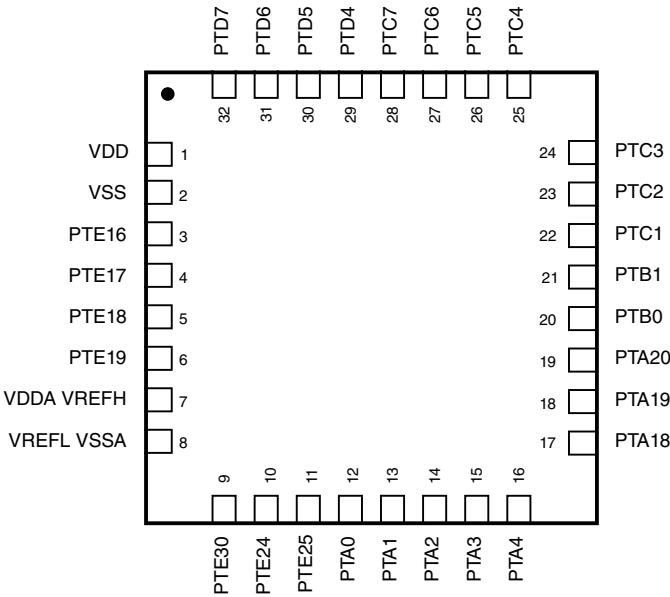


Figure 19. 32 QFN Pinout Diagram

7.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

7.2 Format

Part numbers for this device have the following format:

Q KV## A FFF R T PP CC N

7.3 Fields

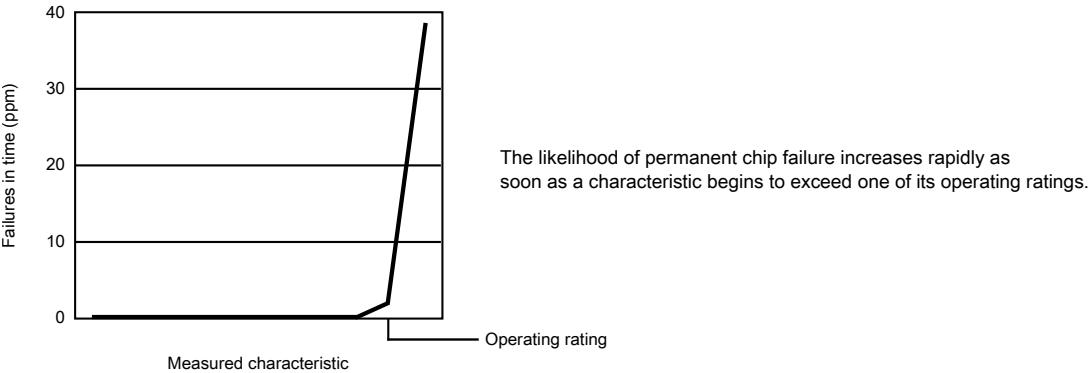
This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"> M = Fully qualified, general market flow P = Prequalification
KV##	Kinetis family	<ul style="list-style-type: none"> KV10
M	Key attribute	<ul style="list-style-type: none"> Z = M0+ core
FFF	Program flash memory size	<ul style="list-style-type: none"> 32 = 32 KB
T	Temperature range (°C)	<ul style="list-style-type: none"> V = -40 to 105
PP	Package identifier	<ul style="list-style-type: none"> FK = 24 QFN (4 mm x 4 mm) LC = 32 LQFP (7 mm x 7 mm) FM = 32 QFN (5 mm x 5 mm) LF = 48 LQFP (7 mm x 7 mm) FT = 48 QFN (10 mm x 10 mm) LH = 64 LQFP (10 mm x 10 mm) LK = 80 LQFP (12 mm x 12 mm) LL = 100 LQFP (14 mm x 14 mm)
CCC	Maximum CPU frequency (MHz)	<ul style="list-style-type: none"> 7 = 75 MHz
N	Packaging type	<ul style="list-style-type: none"> R = Tape and reel (Blank) = Trays

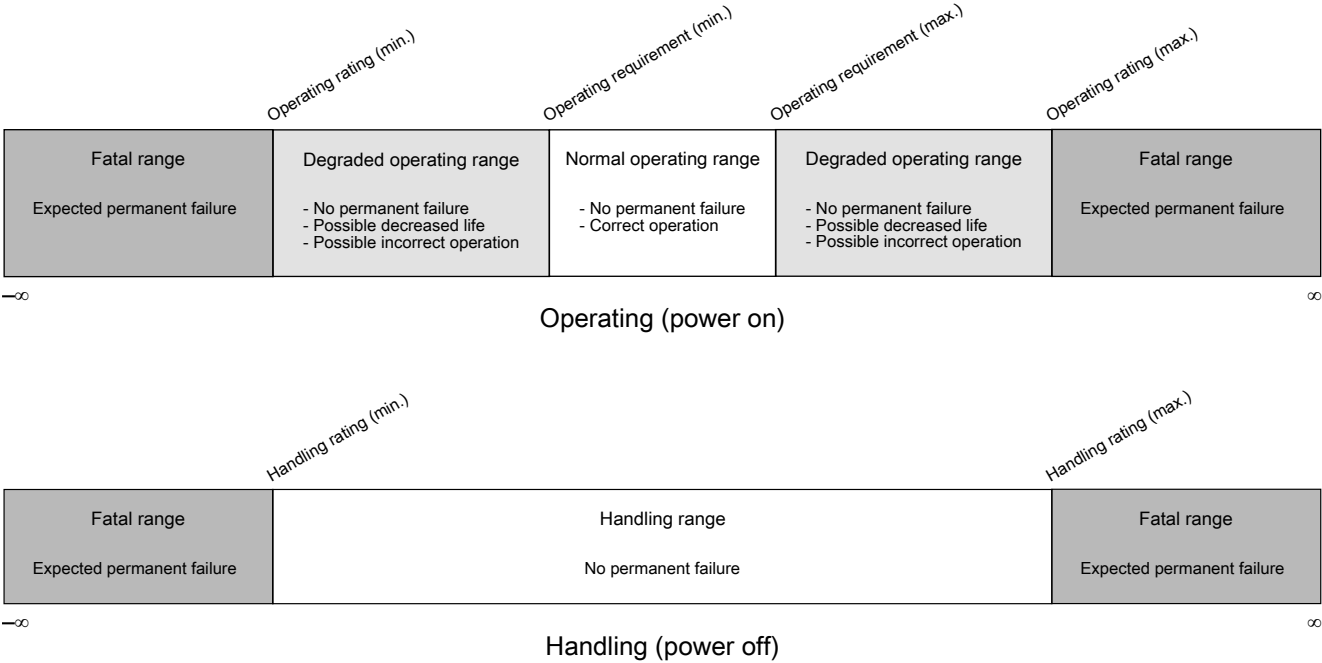
7.4 Example

This is an example part number:

8.5 Result of exceeding a rating



8.6 Relationship between ratings and operating requirements



8.7 Guidelines for ratings and operating requirements

Follow these guidelines for ratings and operating requirements:

- Never exceed any of the chip's ratings.
- During normal operation, don't exceed any of the chip's operating requirements.
- If you must exceed an operating requirement at times other than during normal operation (for example, during power sequencing), limit the duration as much as possible.

8.8 Definition: Typical value

A *typical value* is a specified value for a technical characteristic that:

- Lies within the range of values specified by the operating behavior
- Given the typical manufacturing process, is representative of that characteristic during operation when you meet the typical-value conditions or other specified conditions

Typical values are provided as design guidelines and are neither tested nor guaranteed.

8.8.1 Example 1

This is an example of an operating behavior that includes a typical value:

Symbol	Description	Min.	Typ.	Max.	Unit
I _{WP}	Digital I/O weak pullup/pulldown current	10	70	130	μA

8.8.2 Example 2

This is an example of a chart that shows typical values for various voltage and temperature conditions: