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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	25
Program Memory Size	28KB (16K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 17x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f1518-e-ss

1.2 Pin Utilization

Five pins are needed for ICSP $^{\text{TM}}$ programming. The pins are listed in Table 1-1 and Table 1-2.

TABLE 1-1: PIN DESCRIPTIONS DURING PROGRAMMING – PIC16(L)F1526 AND PIC16(L)F1527

Pin Name	During Programming						
Pili Name	Function	Pin Type	Pin Description				
RB6	ICSPCLK	I	Clock Input – Schmitt Trigger Input				
RB7	ICSPDAT	I/O	Data Input/Output – Schmitt Trigger Input				
RG5/MCLR/VPP	Program/Verify mode	P ⁽¹⁾	Program Mode Select/Programming Power Supply				
VDD	Vdd	Р	Power Supply				
Vss	Vss	Р	Ground				

Legend: I = Input, O = Output, P = Power

Note 1: The programming high voltage is internally generated. To activate the Program/Verify mode, high voltage needs to be applied to MCLR input. Since the MCLR is used for a level source, MCLR does not draw any significant current.

TABLE 1-2: PIN DESCRIPTIONS DURING PROGRAMMING – PIC16(L)F1512, PIC16(L)F1513, PIC16(L)F1516, PIC16(L)F1517, PIC16(L)F1518 and PIC16(L)F1519

Din Nome	During Programming							
Pin Name	Function Pin Type		Pin Description					
RB6	ICSPCLK	l	Clock Input – Schmitt Trigger Input					
RB7	ICSPDAT	I/O	Data Input/Output – Schmitt Trigger Input					
RE3/MCLR/VPP	Program/Verify mode	P ⁽¹⁾	Program Mode Select/Programming Power Supply					
VDD	VDD	Р	Power Supply					
Vss	Vss	Р	Ground					

Legend: I = Input, O = Output, P = Power

Note 1: The programming high voltage is internally generated. To activate the Program/Verify mode, high voltage needs to be applied to MCLR input. Since the MCLR is used for a level source, MCLR does not draw any significant current.

2.0 DEVICE PINOUTS

The pin diagrams for the PIC16(L)F151X/152X family are shown in Figure 2-1 through Figure 2-7. The pins that are required for programming are listed in Table 1-1 and shown in bold lettering in the pin diagrams.

FIGURE 2-1: 28-PIN SPDIP, SOIC, SSOP DIAGRAM FOR PIC16(L)F1512, PIC16(L)F1513, PIC16(L)F1516 AND PIC16(L)F1518

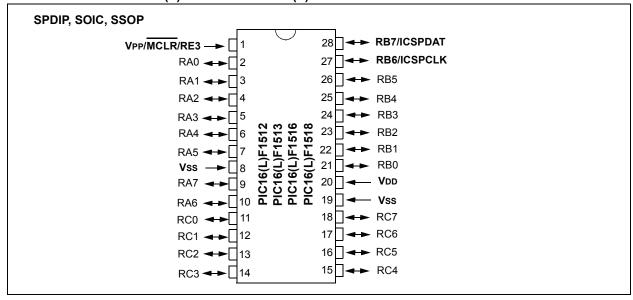
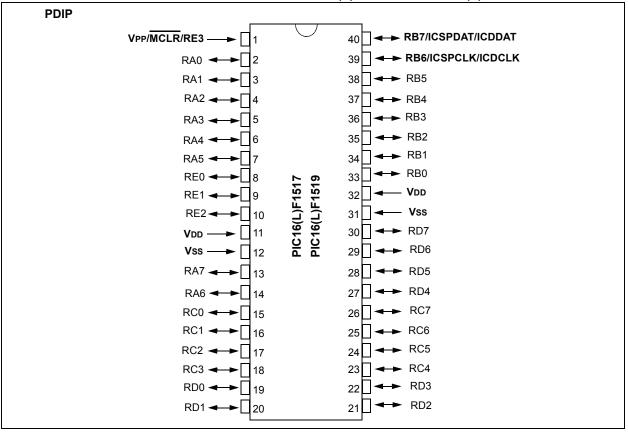
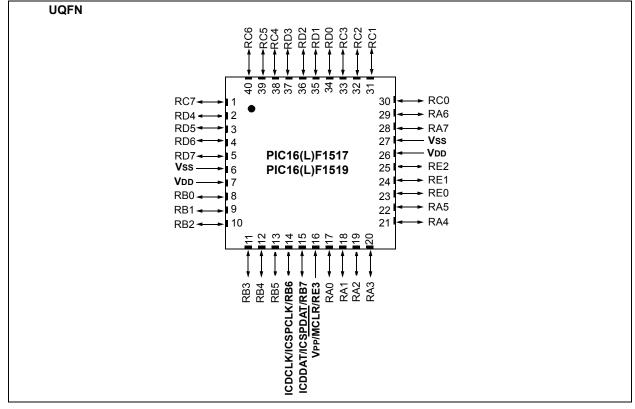
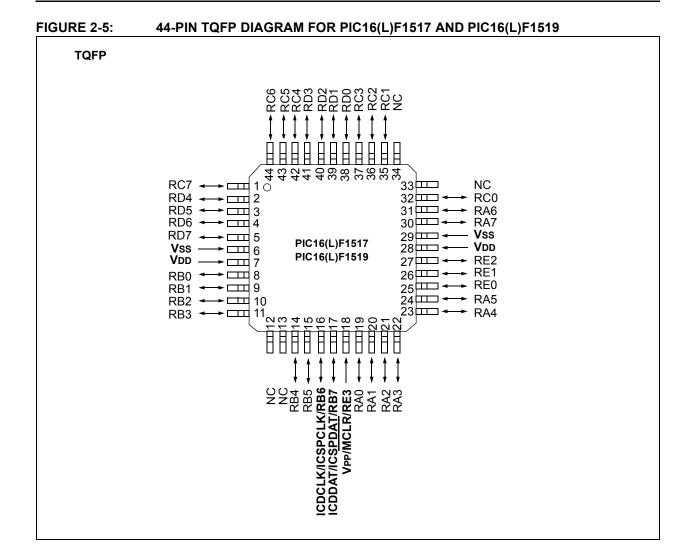


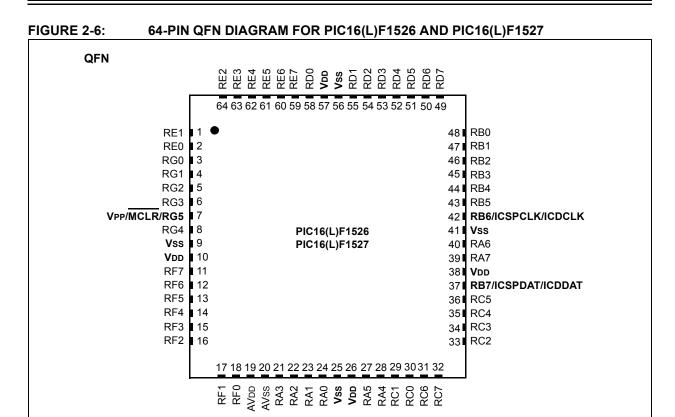
FIGURE 2-3: 40-PIN PDIP DIAGRAM FOR PIC16(L)F1517 AND PIC16(L)F1519 **PDIP**

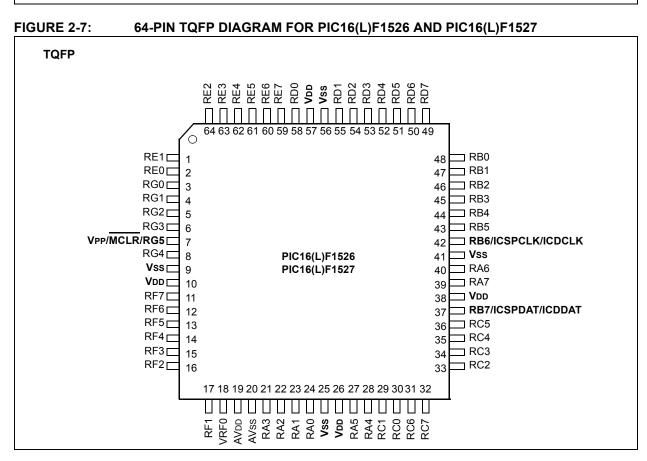








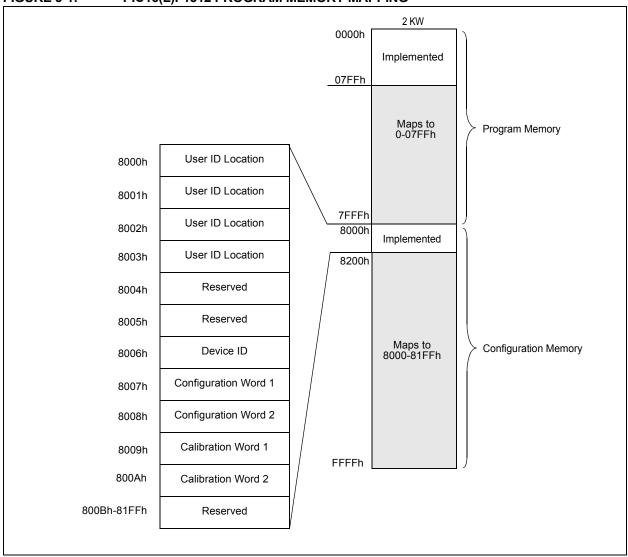


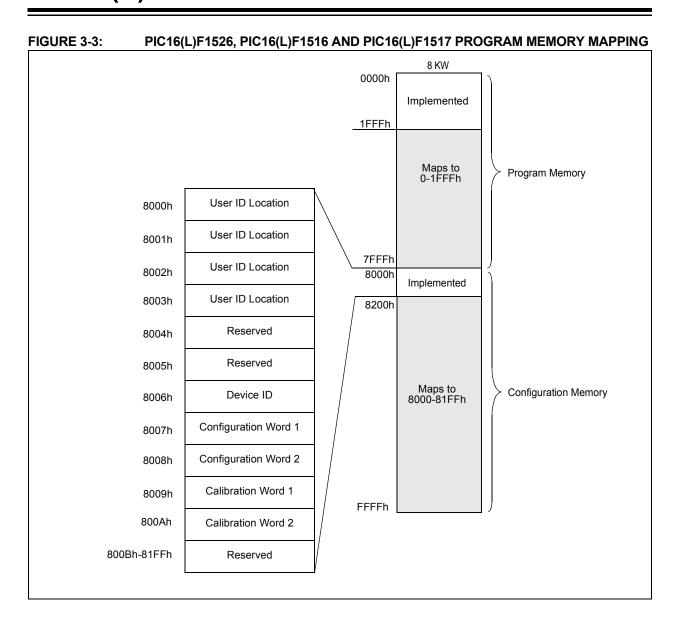


3.0 MEMORY MAP

The memory for the PIC16(L)F151X/152X devices is broken into two sections: program memory and configuration memory. Only the size of the program memory changes between devices, the configuration memory remains the same.

FIGURE 3-1: PIC16(L)F1512 PROGRAM MEMORY MAPPING





3.1 User ID Location

A user may store identification information (user ID) in four designated locations. The user ID locations are mapped to 8000h-8003h. Each location is 14 bits in length. Code protection has no effect on these memory locations. Each location may be read with code protection enabled or disabled.

Note: MPLAB[®] IDE only displays the 7 Least Significant bits (LSb) of each user ID location, the upper bits are not read. It is recommended that only the 7 LSbs be used if MPLAB IDE is the primary tool used to read these addresses.

3.2 Device ID

The device ID word is located at 8006h. This location is read-only and cannot be erased or modified.

REGISTER 3-1: DEVICE ID: DEVICE ID REGISTER⁽¹⁾

R	R	R	R	R	R					
	DEV<8:3>									
bit 13					bit 8					

R	R	R	R	R	R	R	R
	DEV<2:0>				REV<4:0>		
bit 7							bit 0

Legend:	P = Programmable bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	'0' = Bit is cleared
-n = Value at POR	'1' = Bit is set	x = Bit is unknown

bit 13-5 **DEV<8:0>:** Device ID bits

These bits are used to identify the part number.

bit 4-0 **REV<4:0>:** Revision ID bits

These bits are used to identify the revision.

Note 1: This location cannot be written.

REGISTER 3-2: CONFIGURATION WORD 1

R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	U-1	
FCMEN	IESO	CLKOUTEN	BORE	_		
bit 13					bit	8

R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1
CP	MCLRE	PWRTE	WDTE<1:0>				
bit 7							bit 0

Legend:

R = Readable bit P = Programmable bit U = Unimplemented bit, read as '1

'0' = Bit is cleared '1' = Bit is set -n = Value when blank or after Bulk Erase

bit 13 FCMEN: Fail-Safe Clock Monitor Enable bit

1 = Fail-Safe Clock Monitor is enabled

0 = Fail-Safe Clock Monitor is disabled

bit 12 IESO: Internal External Switchover bit

1 = Internal/External Switchover mode is enabled 0 = Internal/External Switchover mode is disabled

bit 11 CLKOUTEN: Clock Out Enable bit

1 = CLKOUT function is disabled. I/O or oscillator function on CLKOUT pin.

0 = CLKOUT function is enabled on CLKOUT pin

bit 10-9 **BOREN<1:0>:** Brown-out Reset Enable bits⁽¹⁾

11 = BOR enabled

10 = BOR enabled during operation and disabled in Sleep

01 = BOR controlled by SBOREN bit of the PCON register

00 = BOR disabled

bit 8 **Unimplemented:** Read as '1'

bit 7 **CP**: Code Protection bit⁽²⁾

1 = Program memory code protection is disabled

0 = Program memory code protection is enabled

bit 6 MCLRE: MCLR/VPP Pin Function Select bit

If LVP bit = 1:

This bit is ignored.

If LVP bit = 0:

1 = \overline{MCLR}/VPP pin function is \overline{MCLR} ; Weak pull-up enabled.

0 = MCLR/VPP pin function is digital input; MCLR internally disabled; Weak pull-up under control of WPUA register.

bit 5 **PWRTE**: Power-up Timer Enable bit⁽¹⁾

1 = PWRT disabled

0 = PWRT enabled

bit 4-3 WDTE<1:0>: Watchdog Timer Enable bit

11 = WDT enabled

10 = WDT enabled while running and disabled in Sleep

01 = WDT controlled by the SWDTEN bit in the WDTCON register

00 = WDT disabled

bit 2-0 FOSC<2:0>: Oscillator Selection bits

111 = ECH: External Clock, High-Power mode: on CLKIN pin

110 = ECM: External Clock, Medium-Power mode: on CLKIN pin

101 = ECL: External Clock, Low-Power mode: on CLKIN pin

100 = INTOSC oscillator: I/O function on OSC1 pin

011 = EXTRC oscillator: RC function on OSC1 pin

010 = HS oscillator: High-speed crystal/resonator on OSC2 pin and OSC1 pin

001 = XT oscillator: Crystal/resonator on OSC2 pin and OSC1 pin

000 = LP oscillator: Low-power crystal on OSC2 pin and OSC1 pin

Note 1: Enabling Brown-out Reset does not automatically enable Power-up Timer.

2: The entire program memory will be erased when the code protection is turned off.

4.3 Program/Verify Commands

The PIC16(L)F151X/152X implements 10 programming commands; each six bits in length. The commands are summarized in Table 4-1.

Commands that have data associated with them are specified to have a minimum delay of TDLY between the command and the data. After this delay 16 clocks are required to either clock in or clock out the 14-bit data word. The first clock is for the Start bit and the last clock is for the Stop bit.

TABLE 4-1: COMMAND MAPPING

Command				Маррі	Data/Note			
		Binary (MSb LSb)						
Load Configuration	Х	0	0	0	0	0	00h	0, data (14), 0
Load Data For Program Memory	Х	0	0	0	1	0	02h	0, data (14), 0
Read Data From Program Memory	Х	0	0	1	0	0	04h	0, data (14), 0
Increment Address	Х	0	0	1	1	0	06h	_
Reset Address	Х	1	0	1	1	0	16h	_
Begin Internally Timed Programming	Х	0	1	0	0	0	08h	_
Begin Externally Timed Programming	Х	1	1	0	0	0	18h	_
End Externally Timed Programming	Х	0	1	0	1	0	0Ah	_
Bulk Erase Program Memory	Х	0	1	0	0	1	09h	Internally Timed
Row Erase Program Memory	Х	1	0	0	0	1	11h	Internally Timed

4.3.1 LOAD CONFIGURATION

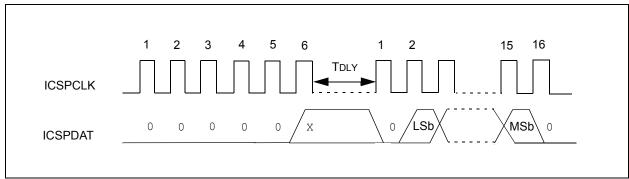
The Load Configuration command is used to access the configuration memory (User ID Locations, Configuration Words, Calibration Words). The Load Configuration command sets the address to 8000h and loads the data latches with one word of data (see Figure 4-1).

After issuing the Load Configuration command, use the Increment Address command until the proper address to be programmed is reached. The address is then programmed by issuing either the Begin Internally Timed Programming or Begin Externally Timed Programming command.

Note: Externally timed writes are not supported for Configuration and Calibration bits. Any externally timed write to the Configuration or Calibration Word will have no effect on the targeted word.

The only way to get back to the program memory (address 0) is to exit Program/Verify mode or issue the Reset Address command after the configuration memory has been accessed by the Load Configuration command.

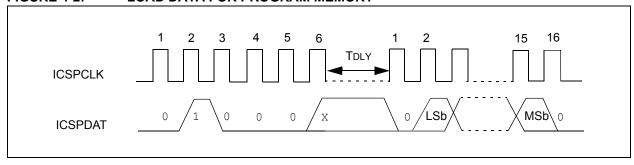
FIGURE 4-1: LOAD CONFIGURATION



4.3.2 LOAD DATA FOR PROGRAM MEMORY

The Load Data for Program Memory command is used to load one 14-bit word into the data latches. The word programs into program memory after the Begin Internally Timed Programming or Begin Externally Timed Programming command is issued (see Figure 4-2).

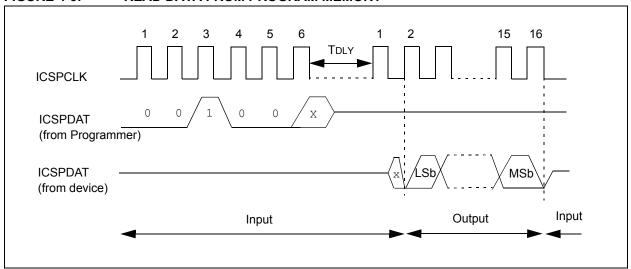
FIGURE 4-2: LOAD DATA FOR PROGRAM MEMORY



4.3.3 READ DATA FROM PROGRAM MEMORY

The Read Data from Program Memory command will transmit data bits out of the program memory map currently accessed, starting with the second rising edge of the clock input. The ICSPDAT pin will go into Output mode on the first falling clock edge, and it will revert to Input mode (high-impedance) after the 16th falling edge of the clock. If the program memory is code-protected (\overline{CP}) , the data will be read as zeros (see Figure 4-3).

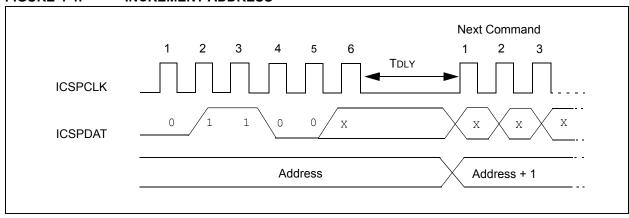
FIGURE 4-3: READ DATA FROM PROGRAM MEMORY



4.3.4 INCREMENT ADDRESS

The address is incremented when this command is received. It is not possible to decrement the address. To reset this counter, the user must use the Reset Address command or exit Program/Verify mode and reenter it. If the address is incremented from address 7FFFh, it will wrap-around to location 0000h. If the address is incremented from FFFFh, it will wrap-around to location 8000h.

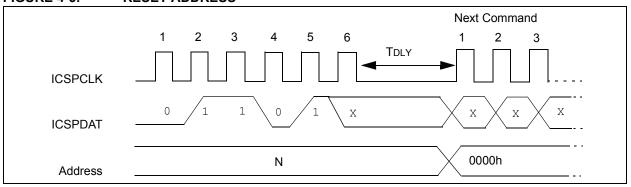
FIGURE 4-4: INCREMENT ADDRESS



4.3.5 RESET ADDRESS

The Reset Address command will reset the address to 0000h, regardless of the current value. The address is used in program memory or the configuration memory.

FIGURE 4-5: RESET ADDRESS



5.0 PROGRAMMING ALGORITHMS

The devices use internal latches to temporarily store the 14-bit words used for programming. Refer to Table 4-2 for specific latch information. The data latches allow the user to write the program words with a single Begin Externally Timed Programming or Begin Internally Timed Programming command. The Load Program Data or the Load Configuration command is used to load a single data latch. The data latch will hold the data until the Begin Externally Timed Programming or Begin Internally Timed Programming command is given.

The data latches are aligned with the LSbs of the address. The PC's address at the time the Begin Externally Timed Programming or Begin Internally Timed Programming command is given will determine which location(s) in memory are written. Writes cannot cross the physical boundary. For example, with the PIC16F1527, attempting to write from address 0002h-0009h will result in data being written to 0008h-000Fh.

If more than the maximum number of data latches are written without a Begin Externally Timed Programming or Begin Internally Timed Programming command, the data in the data latches will be overwritten. The following figures show the recommended flowcharts for programming.

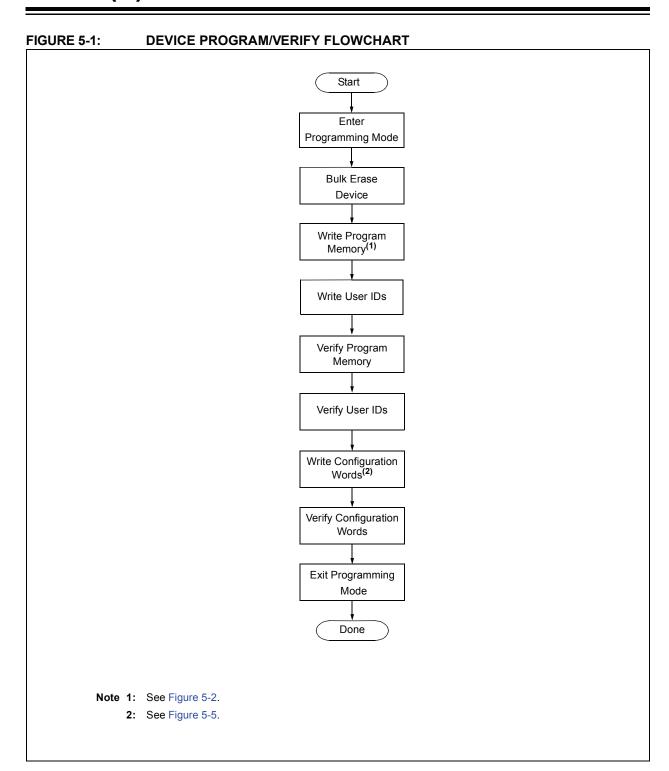
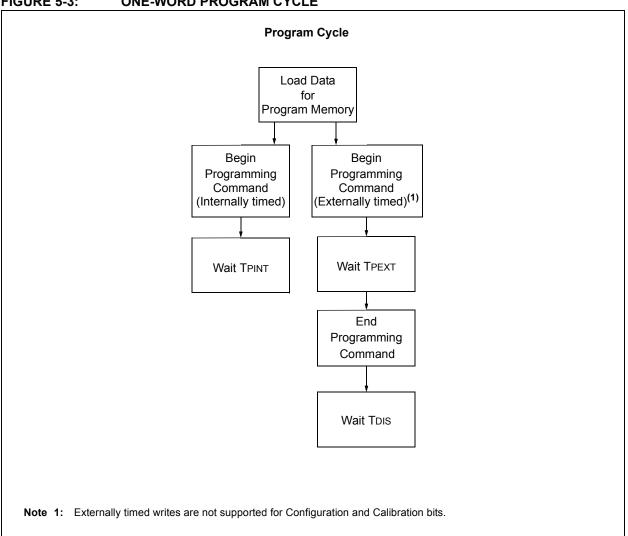


FIGURE 5-3: **ONE-WORD PROGRAM CYCLE**



EXAMPLE 7-1: CHECKSUM COMPUTED WITH PROGRAM CODE PROTECTION DISABLED PIC16F1527, BLANK DEVICE

PIC16F1527 Sum of Memory addresses 0000h-3FFFh⁽¹⁾ C000h
Configuration Word 1⁽²⁾ 3FFFh
Configuration Word 1 mask⁽³⁾ 3EFFh
Configuration Word 2⁽²⁾ 3FFFh
Configuration Word 2 mask⁽³⁾ 3E13h

Checksum = C000h + (3FFFh and 3EFFh) + (3FFFh and 3E13h)

= C000h + 3EFFh + 3E13h

= 3D12h

Note 1: Sum of memory addresses = (Total number of program memory address locations) x (3FFFh) = C000h, truncated to 16 bits.

2: Configuration Word 1 and 2 = all bits are '1'; thus, code-protect is disabled.

3: Configuration Word 1 and 2 Mask = all bits are set to '1', except for unimplemented bits that are '0'.

EXAMPLE 7-2: CHECKSUM COMPUTED WITH PROGRAM CODE PROTECTION DISABLED PIC16LF1527, 00AAh AT FIRST AND LAST ADDRESS

PIC16LF1527 Sum of Memory addresses 0000h-3FFFh⁽¹⁾

Configuration Word 1⁽²⁾

Configuration Word 1 mask⁽³⁾

Configuration Word 2⁽²⁾

Configuration Word 2 mask⁽⁴⁾

3E93h

Checksum = 4156h + (3FFFh and 3EFFh) + (3FFFh and 3E03h)

= 4156h + 3EFFh + 3E03h

= BE58h

Note 1: Total number of Program memory address locations: 3FFFh + 1 = 4000h. Then, 4000h - 2 = 3FFEh. Thus, [(3FFEh x 3FFFh) + (2 x 00AAh)] = 4156h, truncated to 16 bits.

- 2: Configuration Word 1 and 2 = all bits are '1'; thus, code-protect is disabled.
- **3:** Configuration Word 1 Mask = all Configuration Word bits are set to '1', except for unimplemented bits that are '0'.
- **4:** On the PIC16LF1527 device, the VCAPEN bit is not implemented in Configuration Word 2; Thus, all unimplemented bits are '0'.

8.0 ELECTRICAL SPECIFICATIONS

Refer to device specific data sheet for absolute maximum ratings.

TABLE 8-1: AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY MODE

AC/DC C	HARACTERISTICS		Standard (Production		Conditions 25°C	3	
Sym.	Characteristics	Min.	Тур.	Max.	Units	Conditions/Comments	
		Supply Volt	ages and C	urrents			
VDD	Supply Voltage	PIC16F151X PIC16F152X	2.3	-	5.5	V	
	(VDDMIN, VDDMAX)	PIC16LF151X PIC16LF152X	1.8	_	3.6	V	
VPEW	Read/Write and Row Erase opera	tions	VDDMIN		VDDMAX	V	
VPBE	Bulk Erase operations		2.7	_	VDDMAX	V	
Iddi	Current on VDD, Idle		_	_	1.0	mA	
IDDP	Current on VDD, Programming		_	_	3.0	mA	
	VPP						
IPP	Current on MCLR/VPP		_	_	600	μА	
VIHH	High voltage on MCLR/VPP for Program/Verify mode entry		8.0	_	9.0	V	
TVHHR	MCLR rise time (VIL to VIHH) for Program/Verify mode entry	_	_	1.0	μS		
	I/O pins						
VIH	(ICSPCLK, ICSPDAT, MCLR/VPP level	0.8 VDD	_	_	V		
VIL	(ICSPCLK, ICSPDAT, MCLR/VPP	_	_	0.2 VDD	V		
Vон	ICSPDAT output high level	VDD-0.7 VDD-0.7 VDD-0.7	_	_	V	IOH = 3.5 mA, VDD = 5V IOH = 3 mA, VDD = 3.3V IOH = 2 mA, VDD = 1.8V	
Vol	ICSPDAT output low level			_	Vss+0.6 Vss+0.6 Vss+0.6	V	IOH = 8 mA, VDD = 5V IOH = 6 mA, VDD = 3.3V IOH = 3 mA, VDD = 1.8V
		Programming	Mode Entry	and Exi	t	I	L
TENTS	Programing mode entry setup tim ICSPDAT setup time before VDD		100	_	_	ns	
TENTH	Programing mode entry hold time ICSPDAT hold time after VDD or N	//CLR↑	250		_	μS	
		Serial F	Program/Vei	rify			
TCKL	Clock Low Pulse Width		100	_	_	ns	
ТСКН	Clock High Pulse Width		100	_		ns	
TDS TDH	Data in setup time before clock↓ Data in hold time after clock↓		100 100			ns	
I DH	Clock↑ to data out valid (during a					ns	
Tco	Read Data command) Clock↓ to data low-impedance (di	uring a	0	_	80	ns	
TLZD	Read Data command)	_	0	_	80	ns	
THZD	Clock↓ to data high-impedance (o Read Data command)	-	0	_	80	ns	
TDLY	Data input not driven to next clock required between command/data command)	1.0	_	_	μS		
TERAB	Bulk Erase cycle time		_		5	ms	
TERAR	Row Erase cycle time		_	_	2.5	ms	

Note 1: Externally timed writes are not supported for Configuration and Calibration bits.

TABLE 8-1: AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY

VC/UC CHVDVC IEDISTICS		Standard Operating Conditions Production tested at 25°C					
Sym. Characteristics		Min.	Тур.	Max.	Units	Conditions/Comments	
TPINT	Internally timed programming operation time			2.5 5	ms ms	Program memory Configuration Words	
TPEXT	Externally timed programming pulse	1.0	_	2.1	ms	Note 1	
TDIS	Time delay from program to compare (HV discharge time)	300	_	_	μS		
TEXIT	Time delay when exiting Program/Verify mode	1	_	_	μS		

Note 1: Externally timed writes are not supported for Configuration and Calibration bits.

8.1 AC Timing Diagrams

FIGURE 8-1: PROGRAMMING MODE ENTRY – VDD FIRST

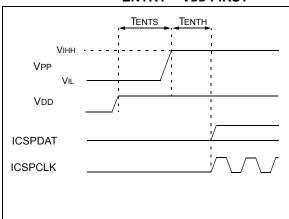


FIGURE 8-2: PROGRAMMING MODE ENTRY – VPP FIRST

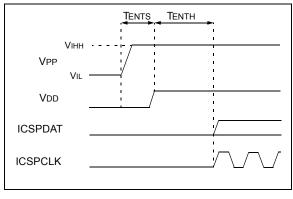


FIGURE 8-3: PROGRAMMING MODE EXIT – VPP LAST

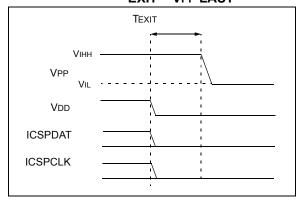


FIGURE 8-4: PROGRAMMING MODE EXIT – VDD LAST

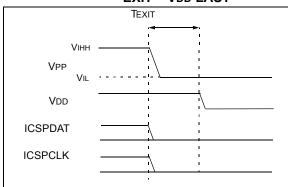


FIGURE 8-8: LVP ENTRY (POWERED)

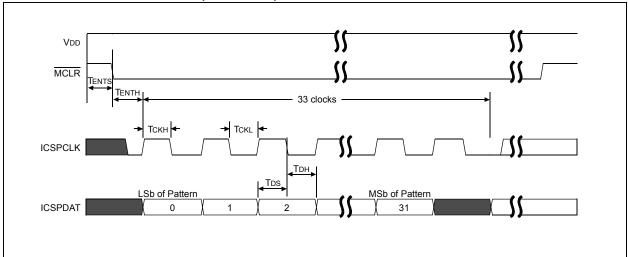
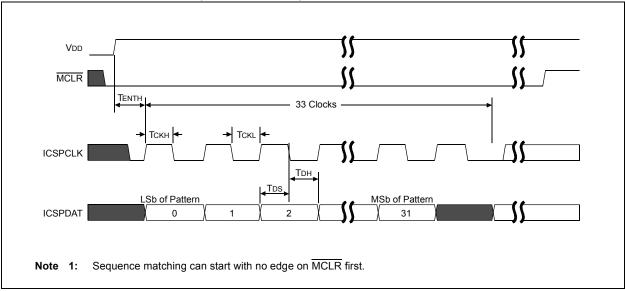


FIGURE 8-9: LVP ENTRY (POWERING UP)



Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
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