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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	100MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	DMA, LVD, POR, PWM
Number of I/O	26
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 12x16b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount, Wettable Flank
Package / Case	32-VFQFN Exposed Pad
Supplier Device Package	32-HVQFN (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mk02fn64vfm10">https://www.e-xfl.com/product-detail/nxp-semiconductors/mk02fn64vfm10</a>

# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to [www.freescale.com](http://www.freescale.com) and perform a part number search for the following device numbers: PK20 and MK20 .

# 2 Part identification

## 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

## 2.2 Format

Part numbers for this device have the following format:

Q K## A M FFF R T PP CC N

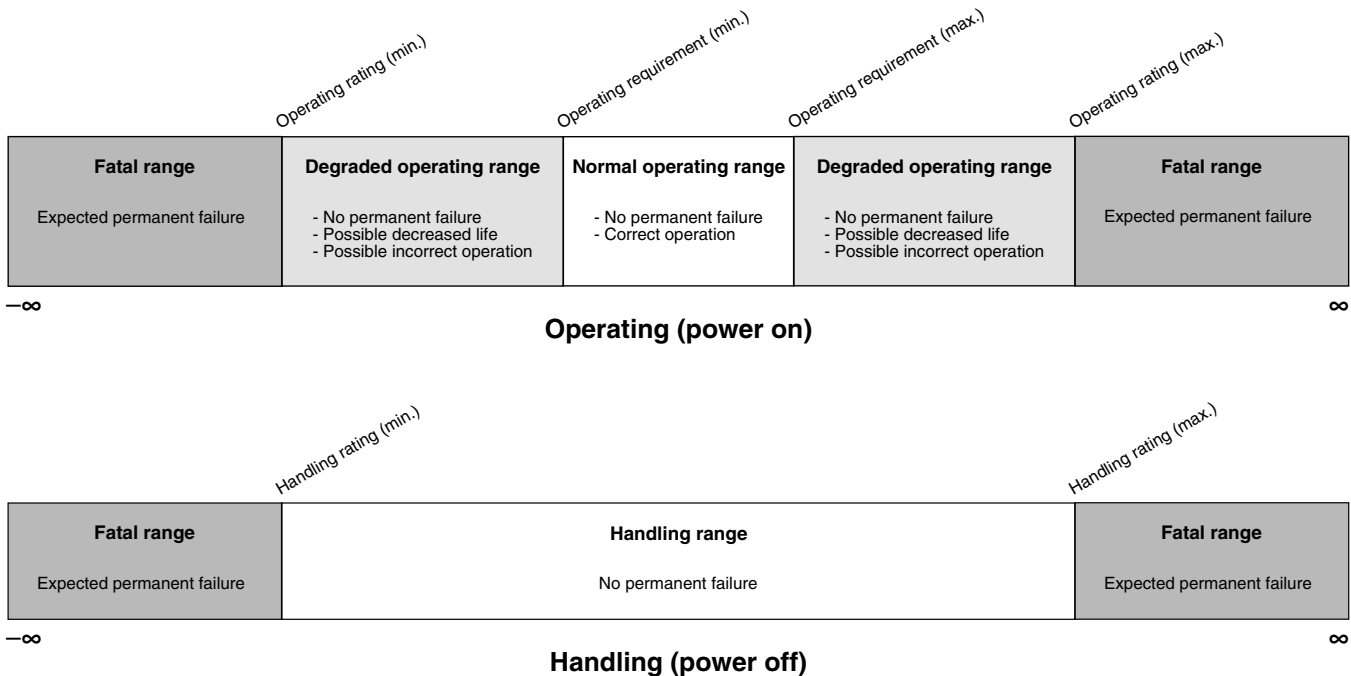
## 2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"> <li>M = Fully qualified, general market flow</li> <li>P = Prequalification</li> </ul>
K##	Kinetis family	<ul style="list-style-type: none"> <li>K20</li> </ul>
A	Key attribute	<ul style="list-style-type: none"> <li>D = Cortex-M4 w/ DSP</li> <li>F = Cortex-M4 w/ DSP and FPU</li> </ul>
M	Flash memory type	<ul style="list-style-type: none"> <li>N = Program flash only</li> <li>X = Program flash and FlexMemory</li> </ul>

Table continues on the next page...

### 3.6 Relationship between ratings and operating requirements



### 3.7 Guidelines for ratings and operating requirements

Follow these guidelines for ratings and operating requirements:

- Never exceed any of the chip's ratings.
- During normal operation, don't exceed any of the chip's operating requirements.
- If you must exceed an operating requirement at times other than during normal operation (for example, during power sequencing), limit the duration as much as possible.

### 3.8 Definition: Typical value

A *typical value* is a specified value for a technical characteristic that:

- Lies within the range of values specified by the operating behavior
- Given the typical manufacturing process, is representative of that characteristic during operation when you meet the typical-value conditions or other specified conditions

Typical values are provided as design guidelines and are neither tested nor guaranteed.

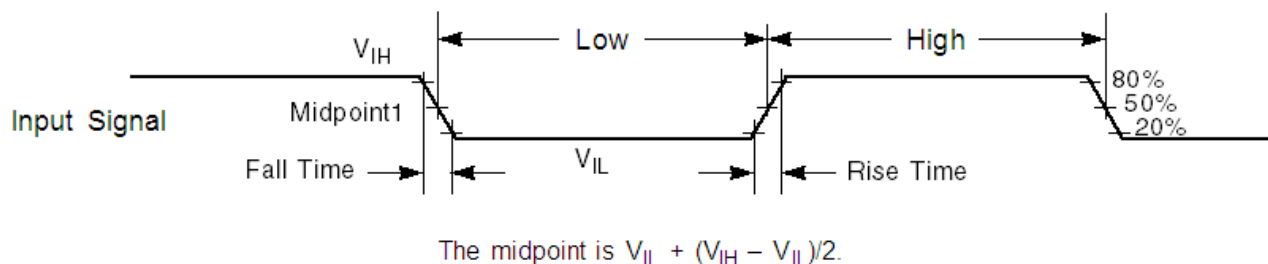
Symbol	Description	Min.	Max.	Unit
$I_{DD}$	Digital supply current	—	185	mA
$V_{DIO}$	Digital input voltage (except RESET, EXTAL, and XTAL)	-0.3	5.5	V
$V_{AIO}$	Analog <sup>1</sup> , RESET, EXTAL, and XTAL input voltage	-0.3	$V_{DD} + 0.3$	V
$I_D$	Maximum current single pin limit (applies to all digital pins)	-25	25	mA
$V_{DDA}$	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V
$V_{USB\_DP}$	USB_DP input voltage	-0.3	3.63	V
$V_{USB\_DM}$	USB_DM input voltage	-0.3	3.63	V
VREGIN	USB regulator input	-0.3	6.0	V
$V_{BAT}$	RTC battery supply voltage	-0.3	3.8	V

1. Analog pins are defined as pins that do not have an associated general purpose I/O port function.

## 5 General

### 5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.



**Figure 1. Input signal measurement reference**

All digital I/O switching characteristics assume:

1. output pins
  - have  $C_L=30\text{pF}$  loads,
  - are configured for fast slew rate (PORTx\_PCRn[SRE]=0), and
  - are configured for high drive strength (PORTx\_PCRn[DSE]=1)
2. input pins
  - have their passive filter disabled (PORTx\_PCRn[PFE]=0)

### 5.2 Nonswitching electrical specifications

## 5.2.2 LVD and POR operating requirements

**Table 2. V<sub>DD</sub> supply LVD and POR operating requirements**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>POR</sub>	Falling VDD POR detect voltage	0.8	1.1	1.5	V	
V <sub>LVDH</sub>	Falling low-voltage detect threshold — high range (LVDV=01)	2.48	2.56	2.64	V	
V <sub>LVW1H</sub>	Low-voltage warning thresholds — high range					1
V <sub>LVW2H</sub>	• Level 1 falling (LVWV=00)	2.62	2.70	2.78	V	
V <sub>LVW3H</sub>	• Level 2 falling (LVWV=01)	2.72	2.80	2.88	V	
V <sub>LVW4H</sub>	• Level 3 falling (LVWV=10)	2.82	2.90	2.98	V	
V <sub>LVW4H</sub>	• Level 4 falling (LVWV=11)	2.92	3.00	3.08	V	
V <sub>HYSH</sub>	Low-voltage inhibit reset/recover hysteresis — high range	—	±80	—	mV	
V <sub>LVDL</sub>	Falling low-voltage detect threshold — low range (LVDV=00)	1.54	1.60	1.66	V	
V <sub>LVW1L</sub>	Low-voltage warning thresholds — low range					1
V <sub>LVW2L</sub>	• Level 1 falling (LVWV=00)	1.74	1.80	1.86	V	
V <sub>LVW3L</sub>	• Level 2 falling (LVWV=01)	1.84	1.90	1.96	V	
V <sub>LVW4L</sub>	• Level 3 falling (LVWV=10)	1.94	2.00	2.06	V	
V <sub>LVW4L</sub>	• Level 4 falling (LVWV=11)	2.04	2.10	2.16	V	
V <sub>HYSL</sub>	Low-voltage inhibit reset/recover hysteresis — low range	—	±60	—	mV	
V <sub>BG</sub>	Bandgap voltage reference	0.97	1.00	1.03	V	
t <sub>LPO</sub>	Internal low power oscillator period — factory trimmed	900	1000	1100	μs	

1. Rising thresholds are falling threshold + hysteresis voltage

**Table 3. VBAT power operating requirements**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>POR_VBAT</sub>	Falling VBAT supply POR detect voltage	0.8	1.1	1.5	V	

**Table 5. Power mode transition operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
$t_{POR}$	After a POR event, amount of time from the point $V_{DD}$ reaches 1.71 V to execution of the first instruction across the operating temperature range of the chip.	—	300	$\mu s$	1
	• VLLS1 → RUN	—	112	$\mu s$	
	• VLLS2 → RUN	—	74	$\mu s$	
	• VLLS3 → RUN	—	73	$\mu s$	
	• LLS → RUN	—	5.9	$\mu s$	
	• VLPS → RUN	—	5.8	$\mu s$	
	• STOP → RUN	—	4.2	$\mu s$	

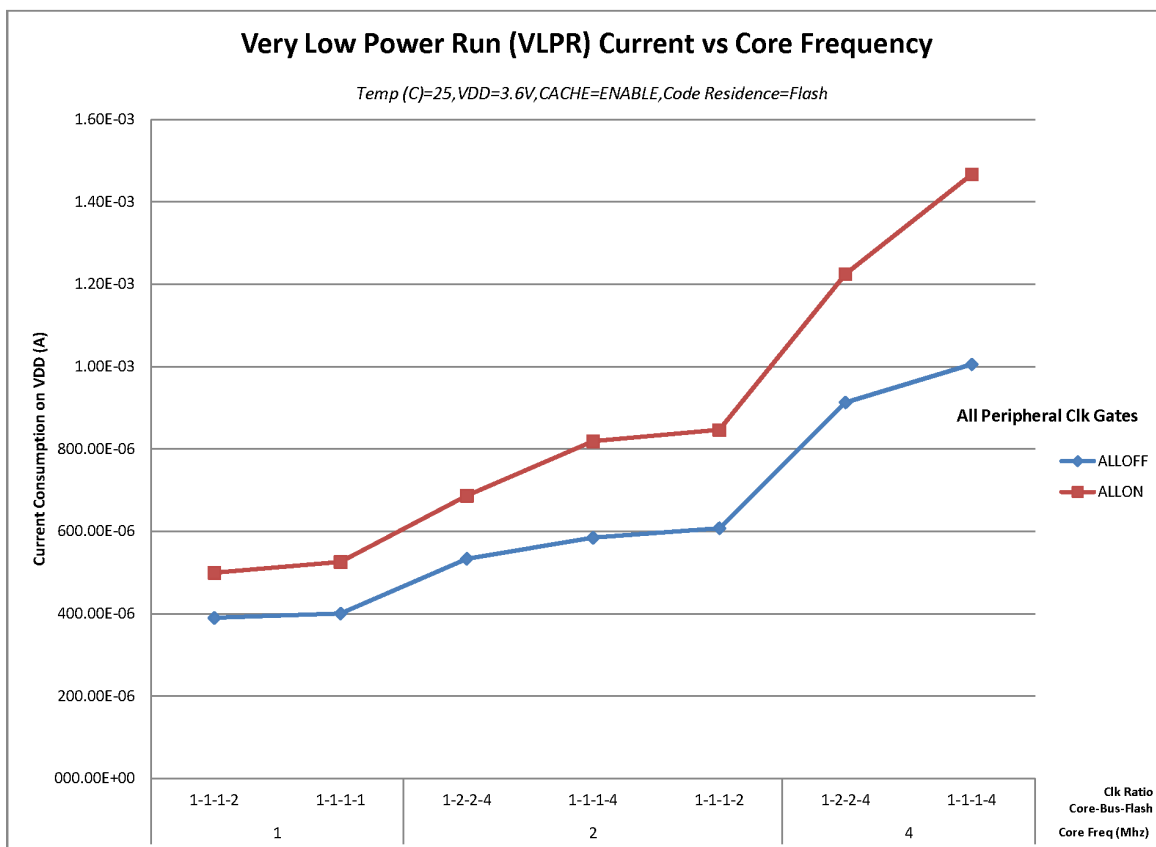
1. Normal boot (FTFL\_OPT[LPBOOT]=1)

## 5.2.5 Power consumption operating behaviors

**Table 6. Power consumption operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$I_{DDA}$	Analog supply current	—	—	See note	mA	1
$I_{DD\_RUN}$	Run mode current — all peripheral clocks disabled, code executing from flash	—	21.5	25	mA	2
		—	21.5	30	mA	
$I_{DD\_RUN}$	Run mode current — all peripheral clocks enabled, code executing from flash	—	31	34	mA	3, 4
		—	31	34	mA	
		—	32	39	mA	
		—	32	39	mA	
$I_{DD\_WAIT}$	Wait mode high frequency current at 3.0 V — all peripheral clocks disabled	—	12.5	—	mA	2
$I_{DD\_WAIT}$	Wait mode reduced frequency current at 3.0 V — all peripheral clocks disabled	—	7.2	—	mA	5
$I_{DD\_VLPR}$	Very-low-power run mode current at 3.0 V — all peripheral clocks disabled	—	0.996	—	mA	6
$I_{DD\_VLPR}$	Very-low-power run mode current at 3.0 V — all peripheral clocks enabled	—	1.46	—	mA	7

Table continues on the next page...



**Figure 3. VLPR mode supply current vs. core frequency**

## 5.2.6 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to [www.freescale.com](http://www.freescale.com).
2. Perform a keyword search for “EMC design.”

## 5.2.7 Capacitance attributes

**Table 7. Capacitance attributes**

Symbol	Description	Min.	Max.	Unit
C <sub>IN_A</sub>	Input capacitance: analog pins	—	7	pF
C <sub>IN_D</sub>	Input capacitance: digital pins	—	7	pF

## 5.3 Switching specifications

### 5.3.1 Device clock specifications

**Table 8. Device clock specifications**

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
$f_{SYS}$	System and core clock	—	72	MHz	
$f_{SYS\_USB}$	System and core clock when Full Speed USB in operation	20	—	MHz	
$f_{BUS}$	Bus clock	—	50	MHz	
$f_{FLASH}$	Flash clock	—	25	MHz	
$f_{LPTMR}$	LPTMR clock	—	25	MHz	
VLPR mode <sup>1</sup>					
$f_{SYS}$	System and core clock	—	4	MHz	
$f_{BUS}$	Bus clock	—	4	MHz	
$f_{FLASH}$	Flash clock	—	0.5	MHz	
$f_{ERCLK}$	External reference clock	—	16	MHz	
$f_{LPTMR\_pin}$	LPTMR clock	—	25	MHz	
$f_{LPTMR\_ERCLK}$	LPTMR external reference clock	—	16	MHz	
$f_{FlexCAN\_ERCLK}$	FlexCAN external reference clock	—	8	MHz	
$f_{I2S\_MCLK}$	I2S master clock	—	12.5	MHz	
$f_{I2S\_BCLK}$	I2S bit clock	—	4	MHz	

1. The frequency limitations in VLPR mode here override any frequency specification listed in the timing specification for any other module.

### 5.3.2 General switching specifications

These general purpose specifications apply to all signals configured for GPIO, UART, CAN, CMT, and I<sup>2</sup>C signals.

**Table 9. General switching specifications**

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1, 2
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter enabled) — Asynchronous path	100	—	ns	3

Table continues on the next page...



**Table 12. JTAG limited voltage range electricals (continued)**

Symbol	Description	Min.	Max.	Unit
J1	TCLK frequency of operation <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	0 0 0	10 25 50	MHz
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	50 20 10	— — —	ns ns ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1	—	ns
J11	TCLK low to TDO data valid	—	17	ns
J12	TCLK low to TDO high-Z	—	17	ns
J13	TRST assert time	100	—	ns
J14	TRST setup time (negation) to TCLK high	8	—	ns

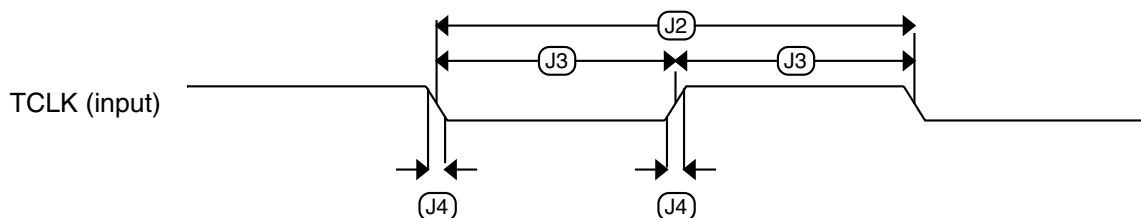
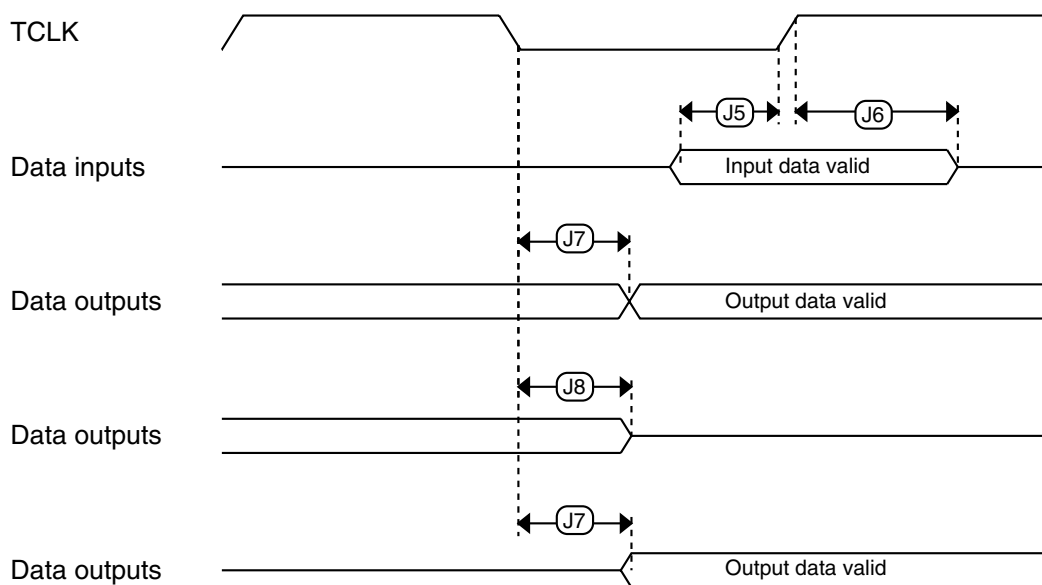
**Table 13. JTAG full voltage range electricals**

Symbol	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
J1	TCLK frequency of operation <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	0 0 0	10 20 40	MHz
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	50 25 12.5	— — —	ns ns ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns

Table continues on the next page...

**Table 13. JTAG full voltage range electricals (continued)**

Symbol	Description	Min.	Max.	Unit
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1.4	—	ns
J11	TCLK low to TDO data valid	—	22.1	ns
J12	TCLK low to TDO high-Z	—	22.1	ns
J13	$\overline{\text{TRST}}$ assert time	100	—	ns
J14	$\overline{\text{TRST}}$ setup time (negation) to TCLK high	8	—	ns


**Figure 6. Test clock input timing**

**Figure 7. Boundary scan (JTAG) timing**

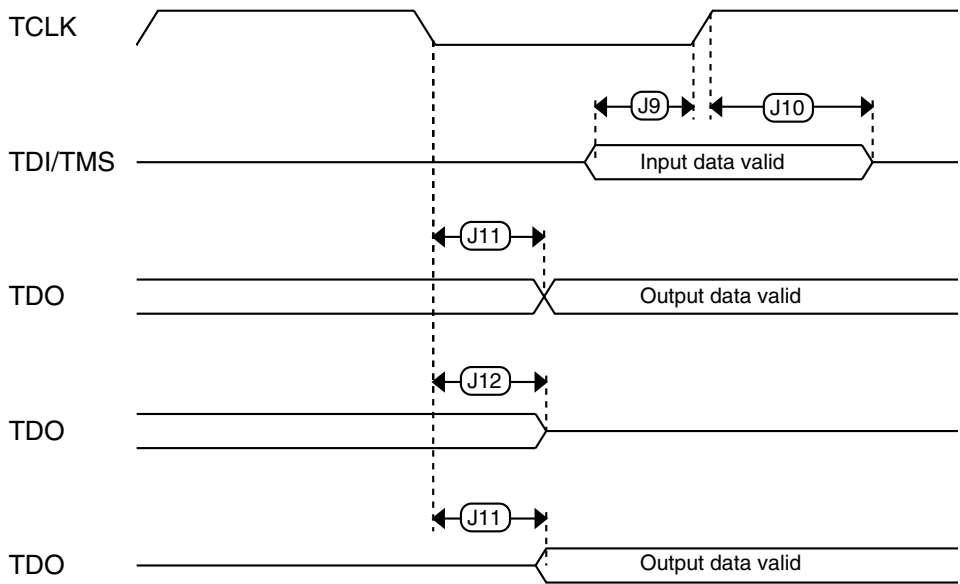


Figure 8. Test Access Port timing

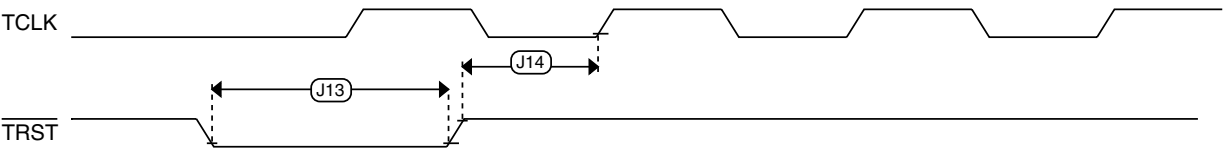


Figure 9.  $\overline{\text{TRST}}$  timing

## 6.2 System modules

There are no specifications necessary for the device's system modules.

## 6.3 Clock modules

### 6.3.2.1 Oscillator DC electrical specifications

**Table 15. Oscillator DC electrical specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{DD}$	Supply voltage	1.71	—	3.6	V	
$I_{DDOSC}$	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> <li>32 kHz</li> <li>4 MHz</li> <li>8 MHz (RANGE=01)</li> <li>16 MHz</li> <li>24 MHz</li> <li>32 MHz</li> </ul>	—	500	—	nA	1
		—	200	—	$\mu$ A	
		—	300	—	$\mu$ A	
		—	950	—	$\mu$ A	
		—	1.2	—	mA	
		—	1.5	—	mA	
$I_{DDOSC}$	Supply current — high gain mode (HGO=1) <ul style="list-style-type: none"> <li>32 kHz</li> <li>4 MHz</li> <li>8 MHz (RANGE=01)</li> <li>16 MHz</li> <li>24 MHz</li> <li>32 MHz</li> </ul>	—	25	—	$\mu$ A	1
		—	400	—	$\mu$ A	
		—	500	—	$\mu$ A	
		—	2.5	—	mA	
		—	3	—	mA	
		—	4	—	mA	
$C_x$	EXTAL load capacitance	—	—	—		2, 3
$C_y$	XTAL load capacitance	—	—	—		2, 3
$R_F$	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	—	—	M $\Omega$	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	—	10	—	M $\Omega$	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	—	—	M $\Omega$	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1	—	M $\Omega$	
$R_S$	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	k $\Omega$	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	k $\Omega$	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	k $\Omega$	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	k $\Omega$	

Table continues on the next page...

**Table 20. Flash command timing specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{\text{vfykey}}$	Verify Backdoor Access Key execution time	—	—	30	$\mu\text{s}$	1
$t_{\text{swapx01}}$	Swap Control execution time	—	200	—	$\mu\text{s}$	
$t_{\text{swapx02}}$	• control code 0x02	—	70	150	$\mu\text{s}$	
$t_{\text{swapx04}}$	• control code 0x04	—	70	150	$\mu\text{s}$	
$t_{\text{swapx08}}$	• control code 0x08	—	—	30	$\mu\text{s}$	
$t_{\text{pgmpart32k}}$	Program Partition for EEPROM execution time	—	70	—	ms	
	• 32 KB FlexNVM					
$t_{\text{setramff}}$	Set FlexRAM Function execution time:	—	50	—	$\mu\text{s}$	
$t_{\text{setram8k}}$	• Control Code 0xFF	—	0.3	0.5	ms	
$t_{\text{setram32k}}$	• 8 KB EEPROM backup	—	0.7	1.0	ms	
	• 32 KB EEPROM backup					
Byte-write to FlexRAM for EEPROM operation						
$t_{\text{eewr8bers}}$	Byte-write to erased FlexRAM location execution time	—	175	260	$\mu\text{s}$	3
$t_{\text{eewr8b8k}}$	Byte-write to FlexRAM execution time:	—	340	1700	$\mu\text{s}$	
$t_{\text{eewr8b16k}}$	• 8 KB EEPROM backup	—	385	1800	$\mu\text{s}$	
$t_{\text{eewr8b32k}}$	• 16 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
	• 32 KB EEPROM backup					
Word-write to FlexRAM for EEPROM operation						
$t_{\text{eewr16bers}}$	Word-write to erased FlexRAM location execution time	—	175	260	$\mu\text{s}$	
$t_{\text{eewr16b8k}}$	Word-write to FlexRAM execution time:	—	340	1700	$\mu\text{s}$	
$t_{\text{eewr16b16k}}$	• 8 KB EEPROM backup	—	385	1800	$\mu\text{s}$	
$t_{\text{eewr16b32k}}$	• 16 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
	• 32 KB EEPROM backup					
Longword-write to FlexRAM for EEPROM operation						
$t_{\text{eewr32bers}}$	Longword-write to erased FlexRAM location execution time	—	360	540	$\mu\text{s}$	
$t_{\text{eewr32b8k}}$	Longword-write to FlexRAM execution time:	—	545	1950	$\mu\text{s}$	
$t_{\text{eewr32b16k}}$	• 8 KB EEPROM backup	—	630	2050	$\mu\text{s}$	
$t_{\text{eewr32b32k}}$	• 16 KB EEPROM backup	—	810	2250	$\mu\text{s}$	
	• 32 KB EEPROM backup					

- Assumes 25 MHz flash clock frequency.
- Maximum times for erase parameters based on expectations at cycling end-of-life.
- For byte-writes to an erased FlexRAM location, the aligned word containing the byte must be erased.

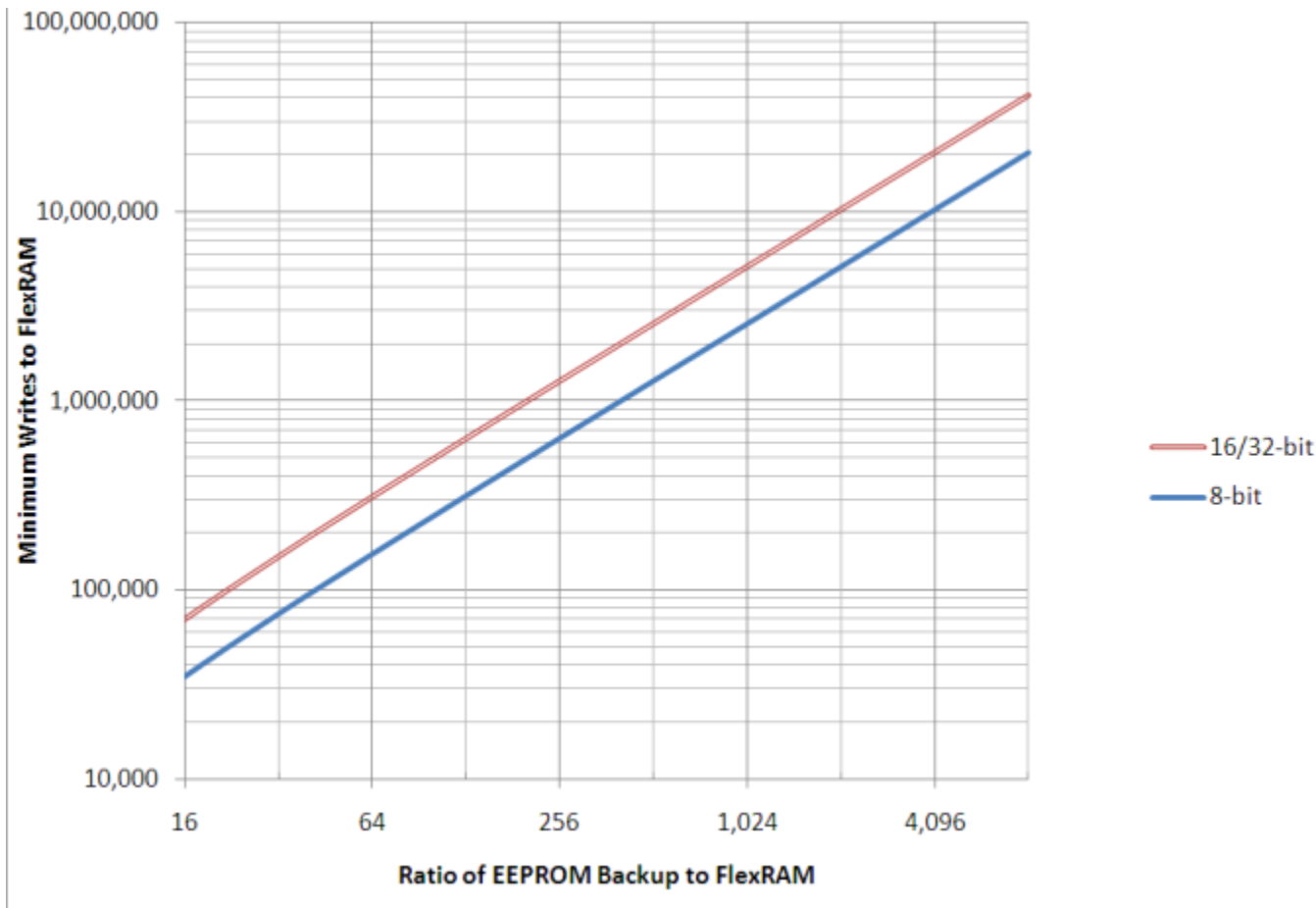


Figure 10. EEPROM backup writes to FlexRAM

## 6.4.2 EzPort Switching Specifications

Table 23. EzPort switching specifications

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
EP1	EZP_CK frequency of operation (all commands except READ)	—	$f_{SYS}/2$	MHz
EP1a	EZP_CK frequency of operation (READ command)	—	$f_{SYS}/8$	MHz
EP2	EZP_CS negation to next EZP_CS assertion	$2 \times t_{EZP\_CK}$	—	ns
EP3	EZP_CS input valid to EZP_CK high (setup)	5	—	ns
EP4	EZP_CK high to EZP_CS input invalid (hold)	5	—	ns
EP5	EZP_D input valid to EZP_CK high (setup)	2	—	ns
EP6	EZP_CK high to EZP_D input invalid (hold)	5	—	ns
EP7	EZP_CK low to EZP_Q output valid	—	16	ns
EP8	EZP_CK low to EZP_Q output invalid (hold)	0	—	ns
EP9	EZP_CS negation to EZP_Q tri-state	—	12	ns

### 6.6.1.3 16-bit ADC with PGA operating conditions

**Table 26. 16-bit ADC with PGA operating conditions**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
V <sub>DDA</sub>	Supply voltage	Absolute	1.71	—	3.6	V	
V <sub>REFPGA</sub>	PGA ref voltage		VREF_OUT	VREF_OUT	VREF_OUT	V	2, 3
V <sub>ADIN</sub>	Input voltage		V <sub>SSA</sub>	—	V <sub>DDA</sub>	V	
V <sub>CM</sub>	Input Common Mode range		V <sub>SSA</sub>	—	V <sub>DDA</sub>	V	
R <sub>PGAD</sub>	Differential input impedance	Gain = 1, 2, 4, 8 Gain = 16, 32 Gain = 64	— — —	128 64 32	— — —	kΩ	IN+ to IN- <sup>4</sup>
R <sub>AS</sub>	Analog source resistance		—	100	—	Ω	5
T <sub>S</sub>	ADC sampling time		1.25	—	—	μs	6
C <sub>rate</sub>	ADC conversion rate	≤ 13 bit modes No ADC hardware averaging Continuous conversions enabled Peripheral clock = 50 MHz	18.484	—	450	Ksps	7
		16 bit modes No ADC hardware averaging Continuous conversions enabled Peripheral clock = 50 MHz	37.037	—	250	Ksps	8

1. Typical values assume V<sub>DDA</sub> = 3.0 V, Temp = 25°C, f<sub>ADCK</sub> = 6 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. ADC must be configured to use the internal voltage reference (VREF\_OUT)
3. PGA reference is internally connected to the VREF\_OUT pin. If the user wishes to drive VREF\_OUT with a voltage other than the output of the VREF module, the VREF module must be disabled.
4. For single ended configurations the input impedance of the driven input is R<sub>PGAD</sub>/2
5. The analog source resistance (R<sub>AS</sub>), external to MCU, should be kept as minimum as possible. Increased R<sub>AS</sub> causes drop in PGA gain without affecting other performances. This is not dependent on ADC clock frequency.
6. The minimum sampling time is dependent on input signal frequency and ADC mode of operation. A minimum of 1.25μs time should be allowed for F<sub>in</sub>=4 kHz at 16-bit differential mode. Recommended ADC setting is: ADLSMP=1, ADLSTS=2 at 8 MHz ADC clock.
7. ADC clock = 18 MHz, ADLSMP = 1, ADLST = 00, ADHSC = 1
8. ADC clock = 12 MHz, ADLSMP = 1, ADLST = 01, ADHSC = 1

### 6.6.1.4 16-bit ADC with PGA characteristics with Chop enabled (ADC\_PGA[PGACHPb] =0)

Table 27. 16-bit ADC with PGA characteristics

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
I <sub>DDA_PGA</sub>	Supply current	Low power (ADC_PGA[PGALPb]=0)	—	420	644	μA	2
I <sub>DC_PGA</sub>	Input DC current		$\frac{2}{R_{PGAD}} \left( \frac{(V_{REFPGA} \times 0.583) - V_{CM}}{(Gain+1)} \right)$			A	3
		Gain =1, V <sub>REFPGA</sub> =1.2V, V <sub>CM</sub> =0.5V	—	1.54	—	μA	
		Gain =64, V <sub>REFPGA</sub> =1.2V, V <sub>CM</sub> =0.1V	—	0.57	—	μA	
G	Gain <sup>4</sup>	<ul style="list-style-type: none"> <li>PGAG=0</li> <li>PGAG=1</li> <li>PGAG=2</li> <li>PGAG=3</li> <li>PGAG=4</li> <li>PGAG=5</li> <li>PGAG=6</li> </ul>	0.95 1.9 3.8 7.6 15.2 30.0 58.8	1 2 4 8 16 31.6 63.3	1.05 2.1 4.2 8.4 16.6 33.2 67.8		R <sub>AS</sub> < 100Ω
BW	Input signal bandwidth	• 16-bit modes	—	—	4	kHz	
		• < 16-bit modes	—	—	40	kHz	
PSRR	Power supply rejection ratio	Gain=1	—	-84	—	dB	V <sub>DDA</sub> = 3V ±100mV, f <sub>VDDA</sub> = 50Hz, 60Hz
CMRR	Common mode rejection ratio	• Gain=1	—	-84	—	dB	V <sub>CM</sub> = 500mVpp, f <sub>VCM</sub> = 50Hz, 100Hz
		• Gain=64	—	-85	—	dB	
V <sub>OFS</sub>	Input offset voltage		—	0.2	—	mV	Output offset = V <sub>OFS</sub> *(Gain+1)
T <sub>GSW</sub>	Gain switching settling time		—	—	10	μs	5
dG/dT	Gain drift over full temperature range	• Gain=1	—	6	10	ppm/°C	
		• Gain=64	—	31	42	ppm/°C	
dG/dV <sub>DDA</sub>	Gain drift over supply voltage	• Gain=1	—	0.07	0.21	%/V	V <sub>DDA</sub> from 1.71 to 3.6V
		• Gain=64	—	0.14	0.31	%/V	
E <sub>IL</sub>	Input leakage error	All modes	I <sub>in</sub> × R <sub>AS</sub>			mV	I <sub>in</sub> = leakage current (refer to the MCU's voltage and current operating ratings)

Table continues on the next page...



**Table 32. VREF full-range operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{out}$	Voltage reference output with factory trim at nominal $V_{DDA}$ and temperature=25C	1.1915	1.195	1.1977	V	
$V_{out}$	Voltage reference output — factory trim	1.1584	—	1.2376	V	
$V_{out}$	Voltage reference output — user trim	1.193	—	1.197	V	
$V_{step}$	Voltage reference trim step	—	0.5	—	mV	
$V_{tdrift}$	Temperature drift ( $V_{max} - V_{min}$ across the full temperature range)	—	—	80	mV	
$I_{bg}$	Bandgap only current	—	—	80	$\mu A$	1
$I_{lp}$	Low-power buffer current	—	—	360	$\mu A$	1
$I_{hp}$	High-power buffer current	—	—	1	mA	1
$\Delta V_{LOAD}$	Load regulation • current = $\pm 1.0$ mA	—	200	—	$\mu V$	1, 2
$T_{stup}$	Buffer startup time	—	—	100	$\mu s$	
$V_{vdift}$	Voltage drift ( $V_{max} - V_{min}$ across the full voltage range)	—	2	—	mV	1

1. See the chip's Reference Manual for the appropriate settings of the VREF Status and Control register.
2. Load regulation voltage is the difference between the VREF\_OUT voltage with no load vs. voltage with defined load

**Table 33. VREF limited-range operating requirements**

Symbol	Description	Min.	Max.	Unit	Notes
$T_A$	Temperature	0	50	$^{\circ}C$	

**Table 34. VREF limited-range operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
$V_{out}$	Voltage reference output with factory trim	1.173	1.225	V	

## 6.7 Timers

See [General switching specifications](#).

## 6.8 Communication interfaces

## 6.8.1 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit <http://www.usb.org>.

## 6.8.2 USB DCD electrical specifications

**Table 35. USB DCD electrical specifications**

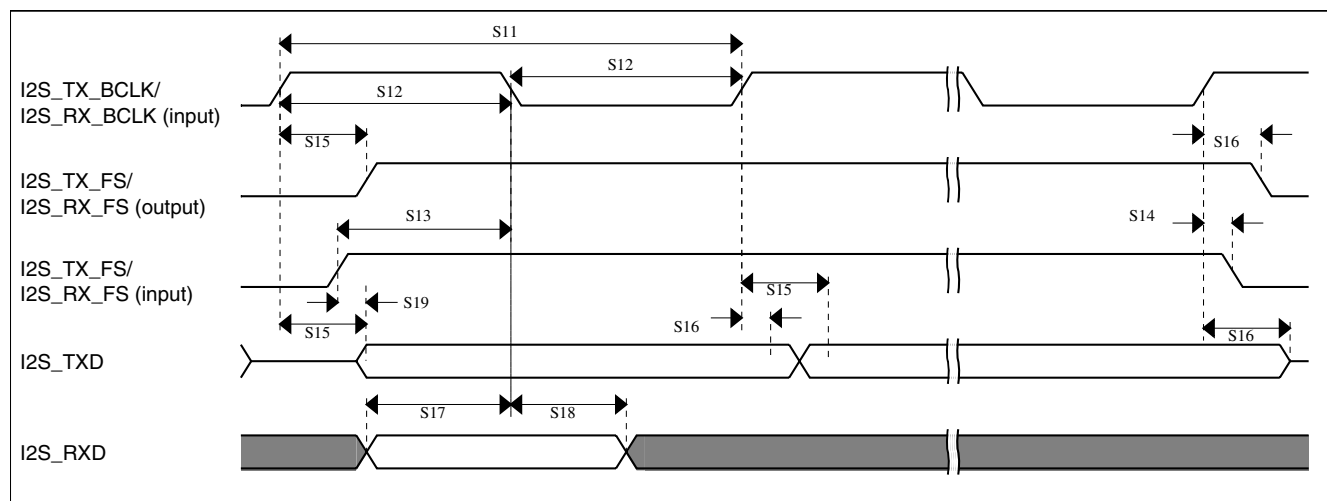
Symbol	Description	Min.	Typ.	Max.	Unit
V <sub>DP_SRC</sub>	USB_DP source voltage (up to 250 $\mu$ A)	0.5	—	0.7	V
V <sub>LGC</sub>	Threshold voltage for logic high	0.8	—	2.0	V
I <sub>DP_SRC</sub>	USB_DP source current	7	10	13	$\mu$ A
I <sub>DM_SINK</sub>	USB_DM sink current	50	100	150	$\mu$ A
R <sub>DM_DWN</sub>	D- pulldown resistance for data pin contact detect	14.25	—	24.8	k $\Omega$
V <sub>DAT_REF</sub>	Data detect voltage	0.25	0.33	0.4	V

## 6.8.3 USB VREG electrical specifications

**Table 36. USB VREG electrical specifications**

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
V <sub>REGIN</sub>	Input supply voltage	2.7	—	5.5	V	
I <sub>DDon</sub>	Quiescent current — Run mode, load current equal zero, input supply (V <sub>REGIN</sub> ) > 3.6 V	—	120	186	$\mu$ A	
I <sub>DDstby</sub>	Quiescent current — Standby mode, load current equal zero	—	1.1	10	$\mu$ A	
I <sub>DDoff</sub>	Quiescent current — Shutdown mode <ul style="list-style-type: none"> <li>V<sub>REGIN</sub> = 5.0 V and temperature=25C</li> <li>Across operating voltage and temperature</li> </ul>	—	650	—	nA	
		—	—	4	$\mu$ A	
I <sub>LOADrun</sub>	Maximum load current — Run mode	—	—	120	mA	
I <sub>LOADstby</sub>	Maximum load current — Standby mode	—	—	1	mA	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (V <sub>REGIN</sub> ) > 3.6 V <ul style="list-style-type: none"> <li>Run mode</li> <li>Standby mode</li> </ul>	3	3.3	3.6	V	
		2.1	2.8	3.6	V	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (V <sub>REGIN</sub> ) < 3.6 V, pass-through mode	2.1	—	3.6	V	2
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	$\mu$ F	
ESR	External output capacitor equivalent series resistance	1	—	100	m $\Omega$	

Table continues on the next page...



**Figure 24. I2S/SAI timing — slave modes**

## 6.8.9.2 VLPR, VLPW, and VLPS mode performance over the full operating voltage range

This section provides the operating performance over the full operating voltage for the device in VLPR, VLPW, and VLPS modes.

**Table 43. I2S/SAI master mode timing in VLPR, VLPW, and VLPS modes (full voltage range)**

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S1	I2S_MCLK cycle time	62.5	—	ns
S2	I2S_MCLK pulse width high/low	45%	55%	MCLK period
S3	I2S_TX_BCLK/I2S_RX_BCLK cycle time (output)	250	—	ns
S4	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low	45%	55%	BCLK period
S5	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/ I2S_RX_FS output valid	—	45	ns
S6	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/ I2S_RX_FS output invalid	0	—	ns
S7	I2S_TX_BCLK to I2S_TXD valid	—	45	ns
S8	I2S_TX_BCLK to I2S_TXD invalid	0	—	ns
S9	I2S_RXD/I2S_RX_FS input setup before I2S_RX_BCLK	53	—	ns
S10	I2S_RXD/I2S_RX_FS input hold after I2S_RX_BCLK	0	—	ns

1. The TSI module is functional with capacitance values outside this range. However, optimal performance is not guaranteed.
2. Fixed external capacitance of 20 pF.
3. REFCHRG = 2, EXTCHRG=0.
4. REFCHRG = 0, EXTCHRG = 10.
5.  $V_{DD} = 3.0\text{ V}$ .
6. The programmable current source value is generated by multiplying the SCANC[REFCHRG] value and the base current.
7. The programmable current source value is generated by multiplying the SCANC[EXTCHRG] value and the base current.
8. Measured with a 5 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 8; I<sub>ext</sub> = 16.
9. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 2; I<sub>ext</sub> = 16.
10. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 16, NSCN = 3; I<sub>ext</sub> = 16.
11. Sensitivity defines the minimum capacitance change when a single count from the TSI module changes. Sensitivity depends on the configuration used. The documented values are provided as examples calculated for a specific configuration of operating conditions using the following equation:  $(C_{ref} * I_{ext}) / (I_{ref} * PS * NSCN)$

The typical value is calculated with the following configuration:

$I_{ext} = 6\text{ }\mu\text{A}$  (EXTCHRG = 2), PS = 128, NSCN = 2,  $I_{ref} = 16\text{ }\mu\text{A}$  (REFCHRG = 7),  $C_{ref} = 1.0\text{ pF}$

The minimum value is calculated with the following configuration:

$I_{ext} = 2\text{ }\mu\text{A}$  (EXTCHRG = 0), PS = 128, NSCN = 32,  $I_{ref} = 32\text{ }\mu\text{A}$  (REFCHRG = 15),  $C_{ref} = 0.5\text{ pF}$

The highest possible sensitivity is the minimum value because it represents the smallest possible capacitance that can be measured by a single count.

12. Time to do one complete measurement of the electrode. Sensitivity resolution of 0.0133 pF, PS = 0, NSCN = 0, 1 electrode, EXTCHRG = 7.
13. REFCHRG=0, EXTCHRG=4, PS=7, NSCN=0F, LPSCNITV=F, LPO is selected (1 kHz), and fixed external capacitance of 20 pF. Data is captured with an average of 7 periods window.

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to [www.freescale.com](http://www.freescale.com) and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
64-pin LQFP	98ASS23234W

## 8 Pinout

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