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Understanding Embedded - FPGAs (Field Programmable Gate Array)

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Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	1057
Number of Logic Elements/Cells	10570
Total RAM Bits	920448
Number of I/O	345
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1s10f672c6

Chapter Revision Dates

The chapters in this book, *Stratix Device Handbook, Volume 1*, were revised on the following dates. Where chapters or groups of chapters are available separately, part numbers are listed.
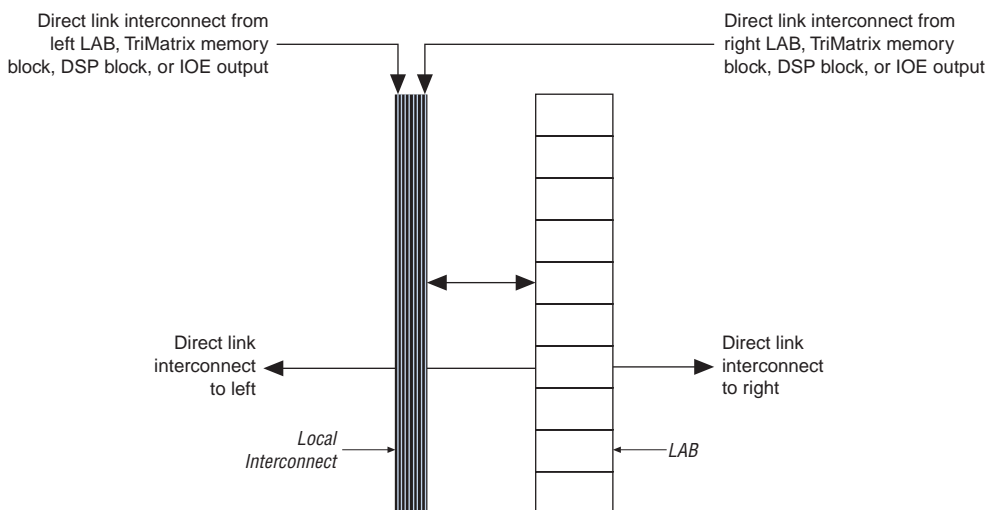
Chapter 1. Introduction
            Revised: *July 2005*
            Part number: *S51001-3.2*

Chapter 2. Stratix Architecture
            Revised: *July 2005*
            Part number: *S51002-3.2*

Chapter 3. Configuration & Testing
            Revised: *July 2005*
            Part number: *S51003-1.3*

Chapter 4. DC & Switching Characteristics
            Revised: *January 2006*
            Part number: *S51004-3.4*

Chapter 5. Reference & Ordering Information
            Revised: *September 2004*
            Part number: *S51005-2.1*

Figure 2–2. Stratix LAB Structure
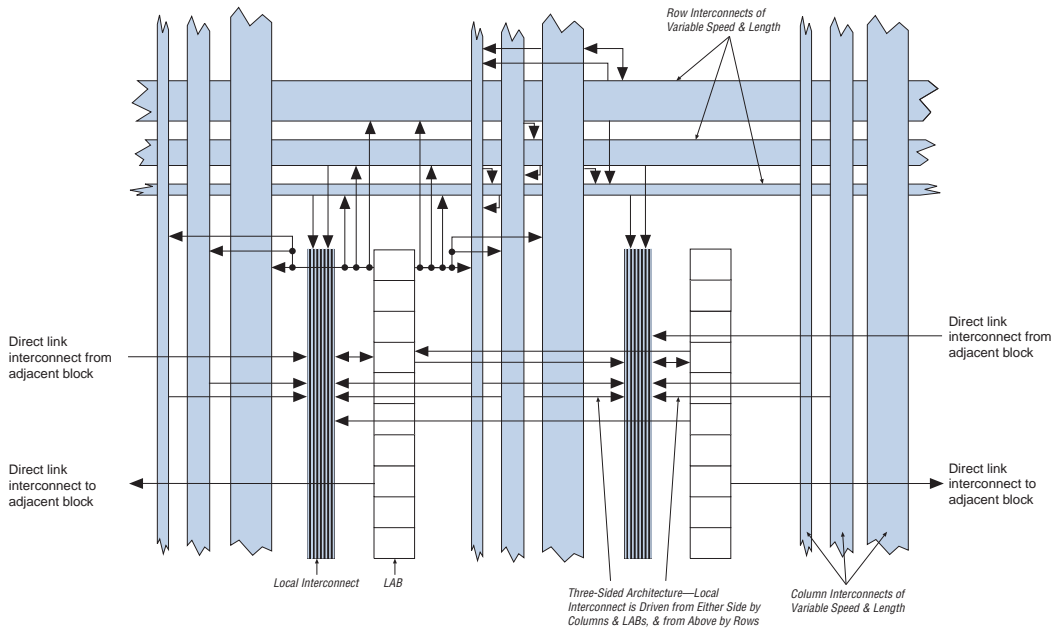
LAB Interconnects

The LAB local interconnect can drive LEs within the same LAB. The LAB local interconnect is driven by column and row interconnects and LE outputs within the same LAB. Neighboring LABs, M512 RAM blocks, M4K RAM blocks, or DSP blocks from the left and right can also drive an LAB's local interconnect through the direct link connection. The direct link connection feature minimizes the use of row and column interconnects, providing higher performance and flexibility. Each LE can drive 30 other LEs through fast local and direct link interconnects. Figure 2–3 shows the direct link connection.

Figure 2–3. Direct Link Connection

Direct link interconnect from left LAB, TriMatrix memory block, DSP block, or IOE output

Direct link interconnect from right LAB, TriMatrix memory block, DSP block, or IOE output

Direct link interconnect to left

Direct link interconnect to right

*Local Interconnect*

LAB

LAB Control Signals

Each LAB contains dedicated logic for driving control signals to its LEs. The control signals include two clocks, two clock enables, two asynchronous clears, synchronous clear, asynchronous preset/load, synchronous load, and add/subtract control signals. This gives a maximum of 10 control signals at a time. Although synchronous load and clear signals are generally used when implementing counters, they can also be used with other functions.

Each LAB can use two clocks and two clock enable signals. Each LAB's clock and clock enable signals are linked. For example, any LE in a particular LAB using the labclk1 signal will also use labclkena1. If the LAB uses both the rising and falling edges of a clock, it also uses both LAB-wide clock signals. De-asserting the clock enable signal will turn off the LAB-wide clock.

Each LAB can use two asynchronous clear signals and an asynchronous load/preset signal. The asynchronous load acts as a preset when the asynchronous load data input is tied high.

Figure 2–27. Read/Write Clock Mode in Simple Dual-Port Mode Notes (1), (2)
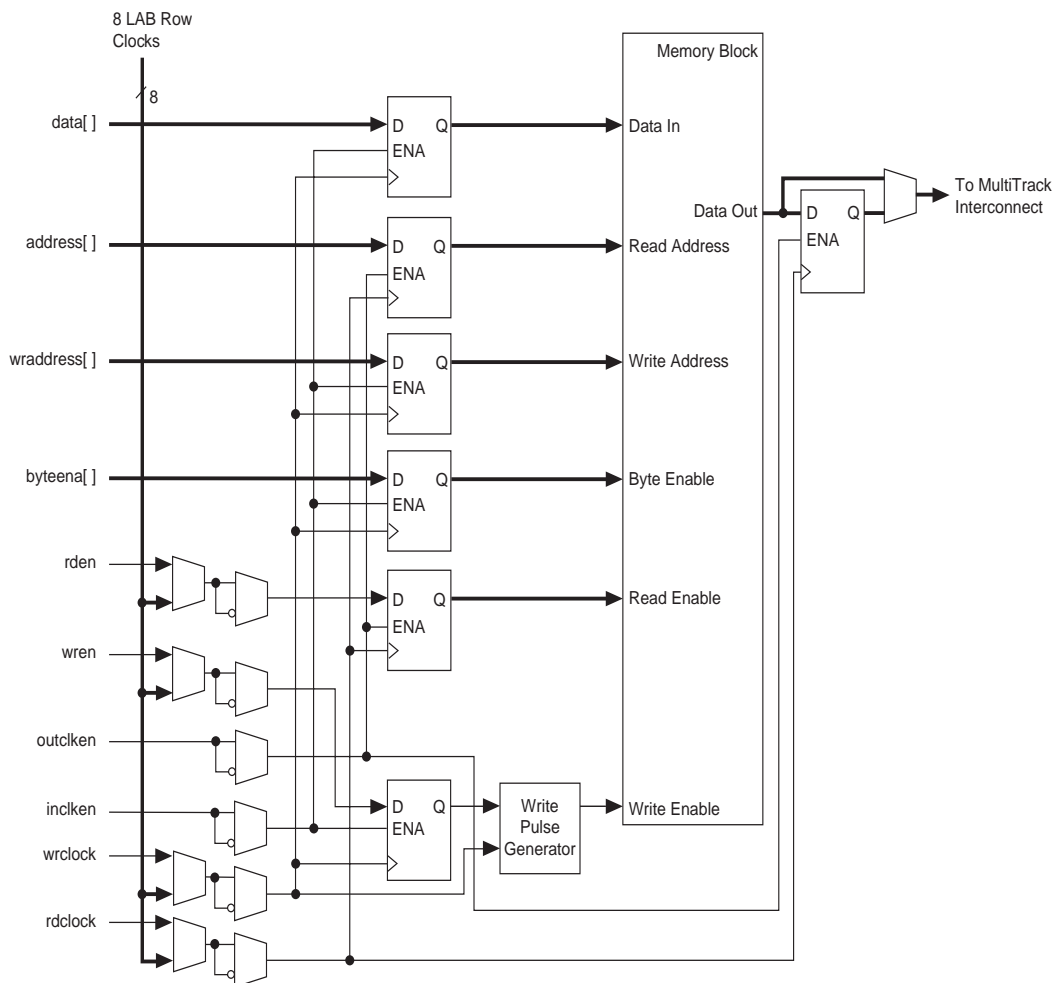
Notes to Figure 2–27:
(1)   All registers shown except the `rden` register have asynchronous clear ports.
(2)   Violating the setup or hold time on the address registers could corrupt the memory contents. This applies to both read and write operations.
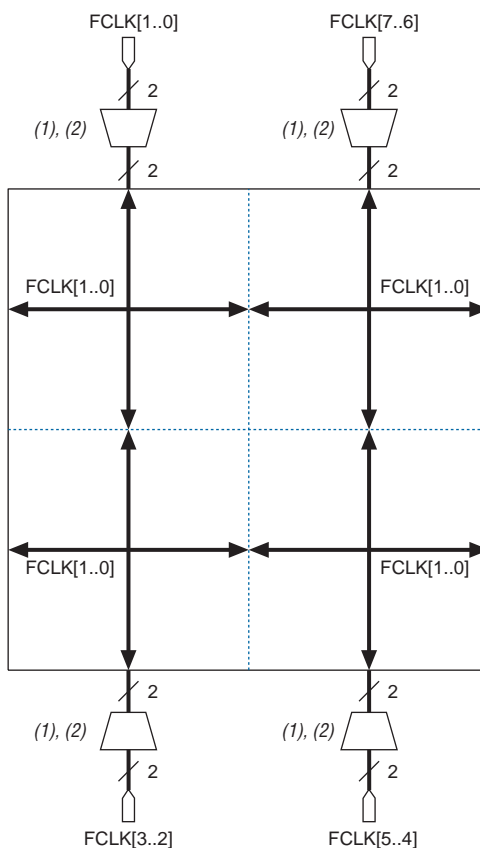
Figure 2–31. DSP Block Diagram for 9 × 9-Bit Configuration
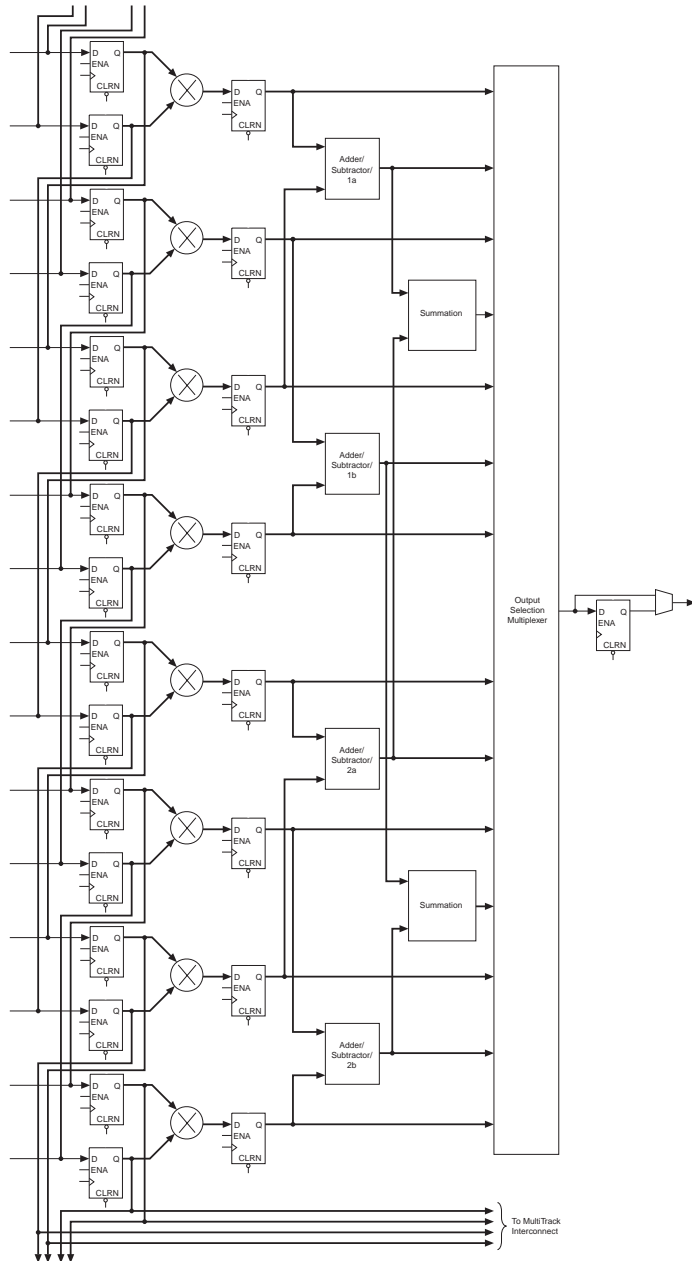
There are 16 dedicated clock pins (CLK[15..0]) to drive either the global or regional clock networks. Four clock pins drive each side of the device, as shown in Figure 2–42. Enhanced and fast PLL outputs can also drive the global and regional clock networks.

Global Clock Network

These clocks drive throughout the entire device, feeding all device quadrants. The global clock networks can be used as clock sources for all resources within the device—IOEs, LEs, DSP blocks, and all memory blocks. These resources can also be used for control signals, such as clock enables and synchronous or asynchronous clears fed from the external pin. The global clock networks can also be driven by internal logic for internally generated global clocks and asynchronous clears, clock enables, or other control signals with large fanout. Figure 2–42 shows the 16 dedicated CLK pins driving global clock networks.

Figure 2–44. EP1S25, EP1S20 & EP1S10 Device Fast Clock Pin Connections to Fast Regional Clocks

FCLK[1..0]

FCLK[7..6]

2

2

(1), (2)

(1), (2)

2

2

FCLK[1..0]

FCLK[1..0]

FCLK[1..0]

FCLK[1..0]

2

2

(1), (2)

(1), (2)

2

2

FCLK[3..2]

FCLK[5..4]

Notes to Figure 2–44:
(1) This is a set of two multiplexers.
(2) In addition to the FCLK pin inputs, there is also an input from the I/O interconnect.

Figure 2–46. Regional Clock Bus
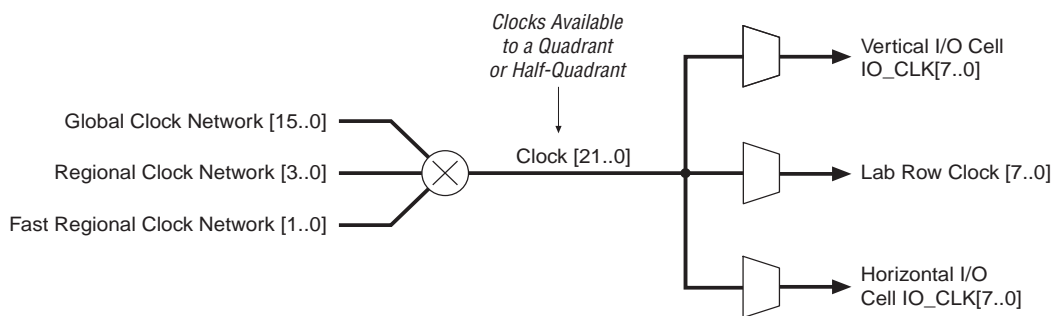
IOE clocks have horizontal and vertical block regions that are clocked by eight I/O clock signals chosen from the 22 quadrant or half-quadrant clock resources. Figures 2–47 and 2–48 show the quadrant and half-quadrant relationship to the I/O clock regions, respectively. The vertical regions (column pins) have less clock delay than the horizontal regions (row pins).

During switchover, the PLL VCO continues to run and will either slow down or speed up, generating frequency drift on the PLL outputs. The clock switchover transitions without any glitches. After the switch, there is a finite resynchronization period to lock onto new clock as the VCO ramps up. The exact amount of time it takes for the PLL to relock relates to the PLL configuration and may be adjusted by using the programmable bandwidth feature of the PLL. The specification for the maximum time to relock is 100 μs.

For more information on clock switchover, see *AN 313, Implementing Clock Switchover in Stratix & Stratix GX Devices*.

PLL Reconfiguration

The PLL reconfiguration feature enables system logic to change Stratix device enhanced PLL counters and delay elements without reloading a Programmer Object File (**.pof**). This provides considerable flexibility for frequency synthesis, allowing real-time PLL frequency and output clock delay variation. You can sweep the PLL output frequencies and clock delay in prototype environments. The PLL reconfiguration feature can also dynamically or intelligently control system clock speeds or t_{CO} delays in end systems.

Clock delay elements at each PLL output port implement variable delay. Figure 2–54 shows a diagram of the overall dynamic PLL control feature for the counters and the clock delay elements. The configuration time is less than 20 μs for the enhanced PLL using a input shift clock rate of 22 MHz. The charge pump, loop filter components, and phase shifting using VCO phase taps cannot be dynamically adjusted.

Any of the four external output counters can drive the single-ended or differential clock outputs for PLLs 5 and 6. This means one counter or frequency can drive all output pins available from PLL 5 or PLL 6. Each pair of output pins (four pins total) has dedicated VCC and GND pins to reduce the output clock's overall jitter by providing improved isolation from switching I/O pins.

For PLLs 5 and 6, each pin of a single-ended output pair can either be in phase or 180° out of phase. The clock output pin pairs support the same I/O standards as standard output pins (in the top and bottom banks) as well as LVDS, LVPECL, 3.3-V PCML, HyperTransport technology, differential HSTL, and differential SSTL. Table 2–20 shows which I/O standards the enhanced PLL clock pins support. When in single-ended or differential mode, the two outputs operate off the same power supply. Both outputs use the same standards in single-ended mode to maintain performance. You can also use the external clock output pins as user output pins if external enhanced PLL clocking is not needed.

Table 2–20. I/O Standards Supported for Enhanced PLL Pins (Part 1 of 2)				
I/O Standard	**Input**			**Output**
	INCLK	**FBIN**	**PLLENABLE**	**EXTCLK**
LVTTL	✓	✓	✓	✓
LVCMOS	✓	✓	✓	✓
2.5 V	✓	✓		✓
1.8 V	✓	✓		✓
1.5 V	✓	✓		✓
3.3-V PCI	✓	✓		✓
3.3-V PCI-X 1.0	✓	✓		✓
LVPECL	✓	✓		✓
3.3-V PCML	✓	✓		✓
LVDS	✓	✓		✓
HyperTransport technology	✓	✓		✓
Differential HSTL	✓			✓
Differential SSTL				✓
3.3-V GTL	✓	✓		✓
3.3-V GTL+	✓	✓		✓
1.5-V HSTL Class I	✓	✓		✓

Figure 2–66. Input Timing Diagram in DDR Mode
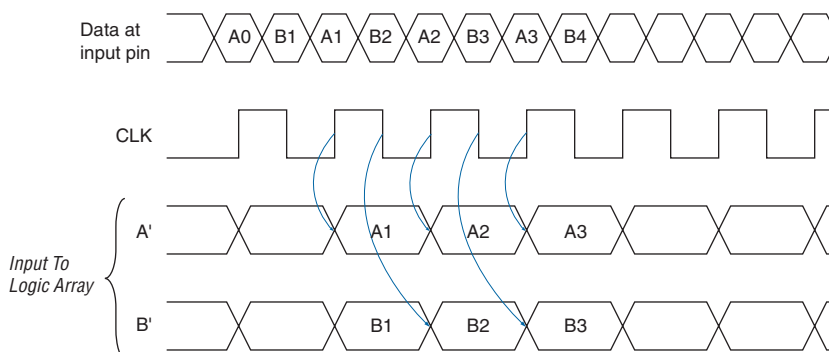
When using the IOE for DDR outputs, the two output registers are configured to clock two data paths from LEs on rising clock edges. These output registers are multiplexed by the clock to drive the output pin at a ×2 rate. One output register clocks the first bit out on the clock high time, while the other output register clocks the second bit out on the clock low time. Figure 2–67 shows the IOE configured for DDR output. Figure 2–68 shows the DDR output timing diagram.

Table 2–28 shows the possible settings for the I/O standards with drive strength control.

Table 2–28. Programmable Drive Strength	
I/O Standard	**I_{OH} / I_{OL} Current Strength Setting (mA)**
3.3-V LVTTL	24 *(1)*, 16, 12, 8, 4
3.3-V LVCMOS	24 *(2)*, 12 *(1)*, 8, 4, 2
2.5-V LVTTL/LVCMOS	16 *(1)*, 12, 8, 2
1.8-V LVTTL/LVCMOS	12 *(1)*, 8, 2
1.5-V LVCMOS	8 *(1)*, 4, 2
GTL/GTL+ 1.5-V HSTL Class I and II 1.8-V HSTL Class I and II SSTL-3 Class I and II SSTL-2 Class I and II SSTL-18 Class I and II	Support max and min strength

Notes to Table 2–28:

(1)   This is the Quartus II software default current setting.

(2)   I/O banks 1, 2, 5, and 6 do not support this setting.

Quartus II software version 4.2 and later will report current strength as "PCI Compliant" for 3.3-V PCI, 3.3-V PCI-X 1.0, and Compact PCI I/O standards.

Stratix devices support series on-chip termination (OCT) using programmable drive strength. For more information, contact your Altera Support Representative.

Open-Drain Output

Stratix devices provide an optional open-drain (equivalent to an open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write-enable signals) that can be asserted by any of several devices.

Slew-Rate Control

The output buffer for each Stratix device I/O pin has a programmable output slew-rate control that can be configured for low-noise or high-speed performance. A faster slew rate provides high-speed transitions for high-performance systems. However, these fast transitions may introduce noise transients into the system. A slow slew rate reduces system noise, but adds a nominal delay to rising and falling edges. Each

Table 4–2. Stratix Device Recommended Operating Conditions (Part 2 of 2)					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
V_{CCIO}	Supply voltage for output buffers, 3.3-V operation	*(4)*, *(5)*	3.00 (3.135)	3.60 (3.465)	V
	Supply voltage for output buffers, 2.5-V operation	*(4)*	2.375	2.625	V
	Supply voltage for output buffers, 1.8-V operation	*(4)*	1.71	1.89	V
	Supply voltage for output buffers, 1.5-V operation	*(4)*	1.4	1.6	V
V_I	Input voltage	*(3)*, *(6)*	−0.5	4.0	V
V_O	Output voltage		0	V_{CCIO}	V
T_J	Operating junction temperature	For commercial use	0	85	°C
		For industrial use	−40	100	°C

Table 4–3. Stratix Device DC Operating Conditions *Note (7)* (Part 1 of 2)						
Symbol	**Parameter**	**Conditions**	**Minimum**	**Typical**	**Maximum**	**Unit**
I_I	Input pin leakage current	$V_I = V_{CCIOmax}$ to 0 V *(8)*	−10		10	µA
I_{OZ}	Tri-stated I/O pin leakage current	$V_O = V_{CCIOmax}$ to 0 V *(8)*	−10		10	µA
I_{CC0}	V_{CC} supply current (standby) (All memory blocks in power-down mode)	V_I = ground, no load, no toggling inputs				mA
		EP1S10. V_I = ground, no load, no toggling inputs		37		mA
		EP1S20. V_I = ground, no load, no toggling inputs		65		mA
		EP1S25. V_I = ground, no load, no toggling inputs		90		mA
		EP1S30. V_I = ground, no load, no toggling inputs		114		mA
		EP1S40. V_I = ground, no load, no toggling inputs		145		mA
		EP1S60. V_I = ground, no load, no toggling inputs		200		mA
		EP1S80. V_I = ground, no load, no toggling inputs		277		mA

Table 4–3. Stratix Device DC Operating Conditions *Note (7)* *(Part 2 of 2)*						
Symbol	**Parameter**	**Conditions**	**Minimum**	**Typical**	**Maximum**	**Unit**
R$_{CONF}$	Value of I/O pin pull-up resistor before and during configuration	V$_{CCIO}$ = 3.0 V *(9)*	20		50	kΩ
		V$_{CCIO}$ = 2.375 V *(9)*	30		80	kΩ
		V$_{CCIO}$ = 1.71 V *(9)*	60		150	kΩ

Table 4–4. LVTTL Specifications					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
V$_{CCIO}$	Output supply voltage		3.0	3.6	V
V$_{IH}$	High-level input voltage		1.7	4.1	V
V$_{IL}$	Low-level input voltage		−0.5	0.7	V
V$_{OH}$	High-level output voltage	I$_{OH}$ = −4 to −24 mA *(10)*	2.4		V
V$_{OL}$	Low-level output voltage	I$_{OL}$ = 4 to 24 mA *(10)*		0.45	V

Table 4–5. LVCMOS Specifications					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
V$_{CCIO}$	Output supply voltage		3.0	3.6	V
V$_{IH}$	High-level input voltage		1.7	4.1	V
V$_{IL}$	Low-level input voltage		−0.5	0.7	V
V$_{OH}$	High-level output voltage	V$_{CCIO}$ = 3.0, I$_{OH}$ = −0.1 mA	V$_{CCIO}$ − 0.2		V
V$_{OL}$	Low-level output voltage	V$_{CCIO}$ = 3.0, I$_{OL}$ = 0.1 mA		0.2	V

Table 4–6. 2.5-V I/O Specifications					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
V$_{CCIO}$	Output supply voltage		2.375	2.625	V
V$_{IH}$	High-level input voltage		1.7	4.1	V
V$_{IL}$	Low-level input voltage		−0.5	0.7	V
V$_{OH}$	High-level output voltage	I$_{OH}$ = −1 mA *(10)*	2.0		V
V$_{OL}$	Low-level output voltage	I$_{OL}$ = 1 mA *(10)*		0.4	V

Table 4–31. CTT I/O Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		2.05	3.3	3.6	V
V_{TT}/V_{REF}	Termination and input reference voltage		1.35	1.5	1.65	V
V_{IH}	High-level input voltage		V_{REF} + 0.2			V
V_{IL}	Low-level input voltage				V_{REF} − 0.2	V
V_{OH}	High-level output voltage	I_{OH} = −8 mA	V_{REF} + 0.4			V
V_{OL}	Low-level output voltage	I_{OL} = 8 mA			V_{REF} − 0.4	V
I_O	Output leakage current (when output is high *Z*)	GND ≤V_{OUT} ≤ V_{CCIO}	−10		10	µA

Table 4–32. Bus Hold Parameters

Parameter	Conditions	V_{CCIO} Level								Unit
		1.5 V		1.8 V		2.5 V		3.3 V		
		Min	Max	Min	Max	Min	Max	Min	Max	
Low sustaining current	$V_{IN} > V_{IL}$ (maximum)	25		30		50		70		µA
High sustaining current	$V_{IN} < V_{IH}$ (minimum)	-25		−30		−50		−70		µA
Low overdrive current	0 V < V_{IN} < V_{CCIO}		160		200		300		500	µA
High overdrive current	0 V < V_{IN} < V_{CCIO}		-160		−200		−300		−500	µA
Bus-hold trip point		0.5	1.0	0.68	1.07	0.7	1.7	0.8	2.0	V

Table 4–63. EP1S20 External I/O Timing on Column Pins Using Global Clock Networks *Note (1)*

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	1.351		1.479		1.699		NA		ns
t_{INH}	0.000		0.000		0.000		NA		ns
t_{OUTCO}	2.732	5.380	2.732	5.728	2.732	6.240	NA	NA	ns
t_{XZ}	2.672	5.254	2.672	5.596	2.672	6.116	NA	NA	ns
t_{ZX}	2.672	5.254	2.672	5.596	2.672	6.116	NA	NA	ns
$t_{INSUPLL}$	0.923		0.971		1.098		NA		ns
t_{INHPLL}	0.000		0.000		0.000		NA		ns
$t_{OUTCOPLL}$	1.210	2.544	1.210	2.648	1.210	2.715	NA	NA	ns
t_{XZPLL}	1.150	2.418	1.150	2.516	1.150	2.591	NA	NA	ns
t_{ZXPLL}	1.150	2.418	1.150	2.516	1.150	2.591	NA	NA	ns

Table 4–64. EP1S20 External I/O Timing on Row Pins Using Fast Regional Clock Networks *Note (1)*

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.032		2.207		2.535		NA		ns
t_{INH}	0.000		0.000		0.000		NA		ns
t_{OUTCO}	2.492	5.018	2.492	5.355	2.492	5.793	NA	NA	ns
t_{XZ}	2.519	5.072	2.519	5.411	2.519	5.861	NA	NA	ns
t_{ZX}	2.519	5.072	2.519	5.411	2.519	5.861	NA	NA	ns

Skew on Input Pins

Table 4–99 shows the package skews that were considered to get the worst case I/O skew value. You can use these values, for example, when calculating the timing budget on the input (read) side of a memory interface.

Table 4–99. Package Skew on Input Pins	
Package Parameter	**Worst-Case Skew (ps)**
Pins in the same I/O bank	50
Pins in top/bottom (vertical I/O) banks	50
Pins in left/right side (horizontal I/O) banks	50
Pins across the entire device	100

PLL Counter & Clock Network Skews

Table 4–100 shows the clock skews between different clock outputs from the Stratix device PLL.

Table 4–100. PLL Counter & Clock Network Skews	
Parameter	**Worst-Case Skew (ps)**
Clock skew between two external clock outputs driven by the same counter	100
Clock skew between two external clock outputs driven by the different counters with the same settings	150
Dual-purpose PLL dedicated clock output used as I/O pin vs. regular I/O pin	270 *(1)*
Clock skew between any two outputs of the PLL that drive global clock networks	150

Note to Table 4–100:
(1) The Quartus II software models 270 ps of delay on the PLL dedicated clock output (`PLL6_OUT[3..0]p/n` and `PLL5_OUT[3..0]p/n`) pins both when used as clocks and when used as I/O pins.

I/O Timing Measurement Methodology

Different I/O standards require different baseline loading techniques for reporting timing delays. Altera characterizes timing delays with the required termination and loading for each I/O standard. The timing information is specified from the input clock pin up to the output pin of

Figure 4–7. Output Delay Timing Reporting Setup Modeled by Quartus II
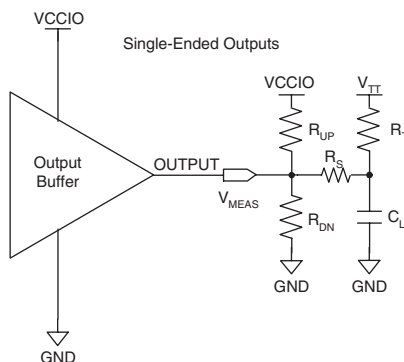
Notes to Figure 4–7:
(1) Output pin timing is reported at the output pin of the FPGA device. Additional delays for loading and board trace delay need to be accounted for with IBIS model simulations.
(2) V_{CCINT} is 1.42-V unless otherwise specified.

Table 4–101. Reporting Methodology For Maximum Timing For Single-Ended Output Pins   (Part 1 of 2)
Notes (1), (2), (3)

I/O Standard	Loading and Termination							Measurement Point
	R_{UP} Ω	R_{DN} Ω	R_S Ω	R_T Ω	V_{CCIO} (V)	VTT (V)	C_L (pF)	V_{MEAS}
3.3-V LVTTL	–	–	0	–	2.950	2.95	10	1.500
2.5-V LVTTL	–	–	0	–	2.370	2.37	10	1.200
1.8-V LVTTL	–	–	0	–	1.650	1.65	10	0.880
1.5-V LVTTL	–	–	0	–	1.400	1.40	10	0.750
3.3-V LVCMOS	–	–	0	–	2.950	2.95	10	1.500
2.5-V LVCMOS	–	–	0	–	2.370	2.37	10	1.200
1.8-V LVCMOS	–	–	0	–	1.650	1.65	10	0.880
1.5-V LVCMOS	–	–	0	–	1.400	1.40	10	0.750
3.3-V GTL	–	–	0	25	2.950	1.14	30	0.740
2.5-V GTL	–	–	0	25	2.370	1.14	30	0.740
3.3-V GTL+	–	–	0	25	2.950	1.35	30	0.880
2.5-V GTL+	–	–	0	25	2.370	1.35	30	0.880
3.3-V SSTL-3 Class II	–	–	25	25	2.950	1.25	30	1.250

Table 4–110. Stratix IOE Programmable Delays on Row Pins *Note (1)*

Parameter	Setting	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
Decrease input delay to internal cells	Off		3,970		4,367		5,022		5,908	ps
	Small		3,390		3,729		4,288		5,045	ps
	Medium		2,810		3,091		3,554		4,181	ps
	Large		173		181		208		245	ps
	On		173		181		208		245	ps
Decrease input delay to input register	Off		3,900		4,290		4,933		5,804	ps
	On		0		0		0		0	ps
Decrease input delay to output register	Off		1,240		1,364		1,568		1,845	ps
	On		0		0		0		0	ps
Increase delay to output pin	Off		0		0		0		0	ps
	On		397		417		417		417	ps
Increase delay to output enable pin	Off		0		0		0		0	ps
	On		348		383		441		518	ps
Increase output clock enable delay	Off		0		0		0		0	ps
	Small		180		198		227		267	ps
	Large		260		286		328		386	ps
	On		260		286		328		386	ps
Increase input clock enable delay	Off		0		0		0		0	ps
	Small		180		198		227		267	ps
	Large		260		286		328		386	ps
	On		260		286		328		386	ps
Increase output enable clock enable delay	Off		0		0		0		0	ps
	Small		540		594		683		804	ps
	Large		1,016		1,118		1,285		1,512	ps
	On		1,016		1,118		1,285		1,512	ps
Increase t_{ZX} delay to output pin	Off		0		0		0		0	ps
	On		1,993		2,092		2,092		2,092	ps

Note to Table 4–109 and Table 4–110:

(1) The delay chain delays vary for different device densities. These timing values only apply to EP1S30 and EP1S40 devices. Reference the timing information reported by the Quartus II software for other devices.