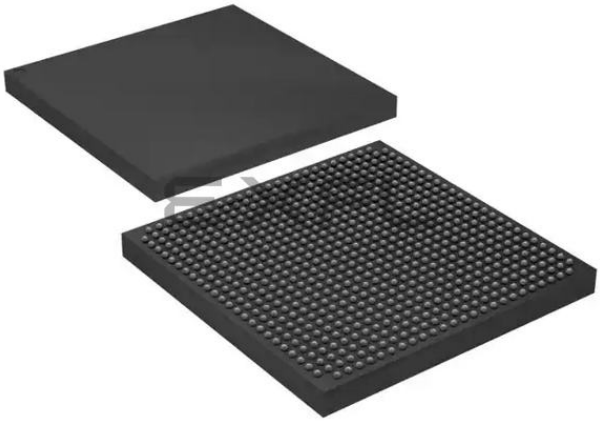

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

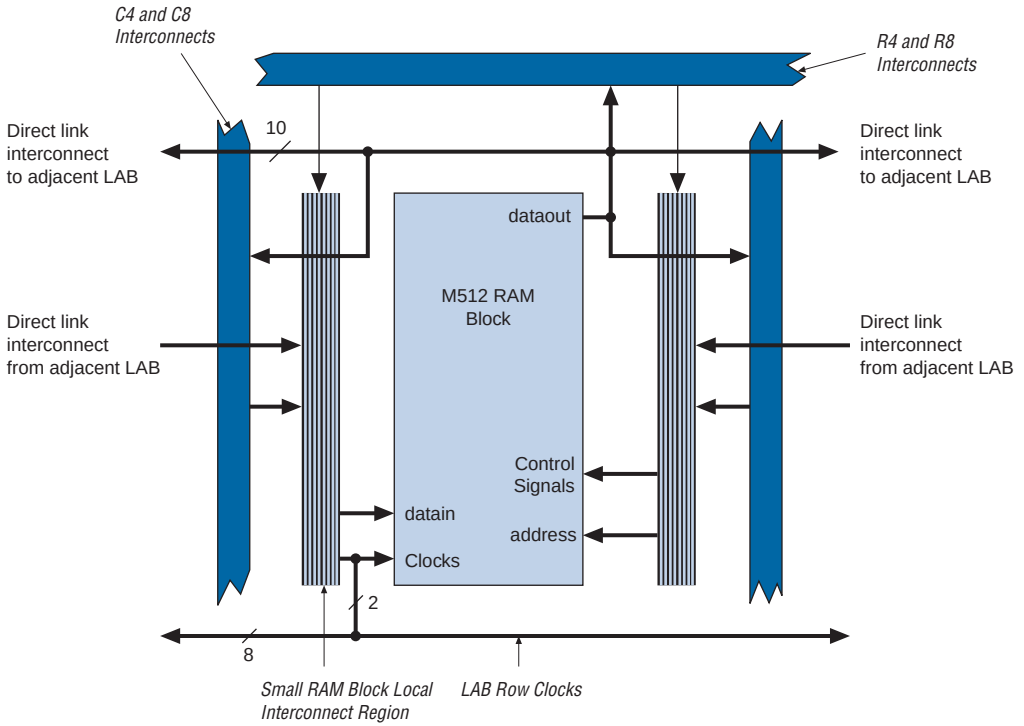
The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	1057
Number of Logic Elements/Cells	10570
Total RAM Bits	920448
Number of I/O	345
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1s10f672c7

Chapter 3. Configuration & Testing

Chapter 4. DC & Switching Characteristics

Figure 2–16. M512 RAM Block LAB Row Interface



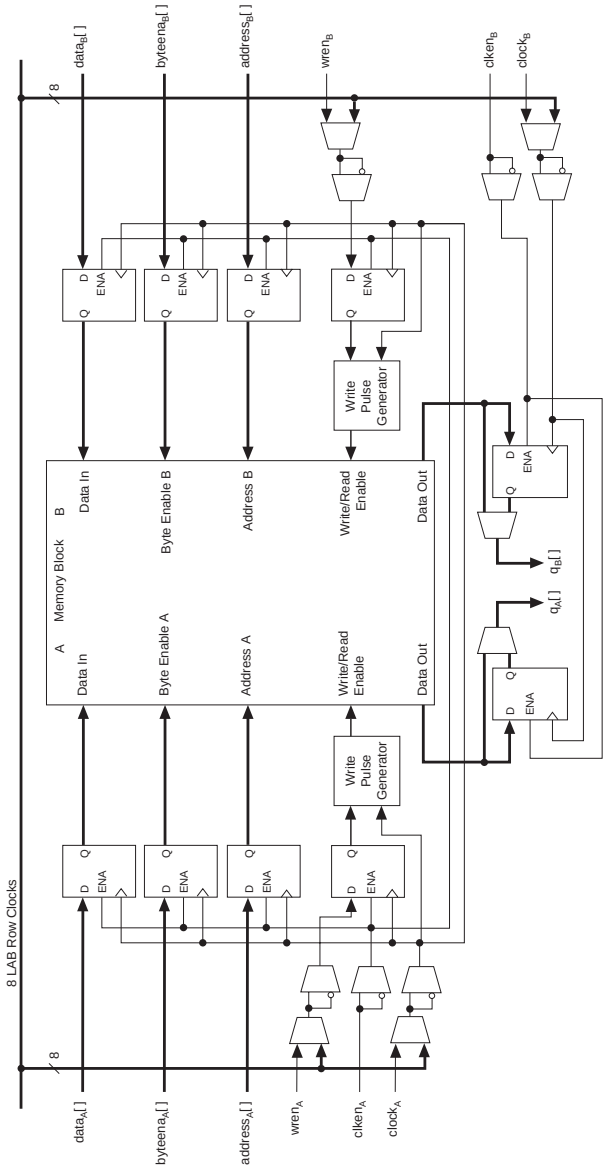
M4K RAM Blocks

The M4K RAM block includes support for true dual-port RAM. The M4K RAM block is used to implement buffers for a wide variety of applications such as storing processor code, implementing lookup schemes, and implementing larger memory applications. Each block contains 4,608 RAM bits (including parity bits). M4K RAM blocks can be configured in the following modes:

- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM
- FIFO
- ROM
- Shift register

When configured as RAM or ROM, you can use an initialization file to pre-load the memory contents.

Figure 2–25. Input/Output Clock Mode in True Dual-Port Mode Notes (1), (2)

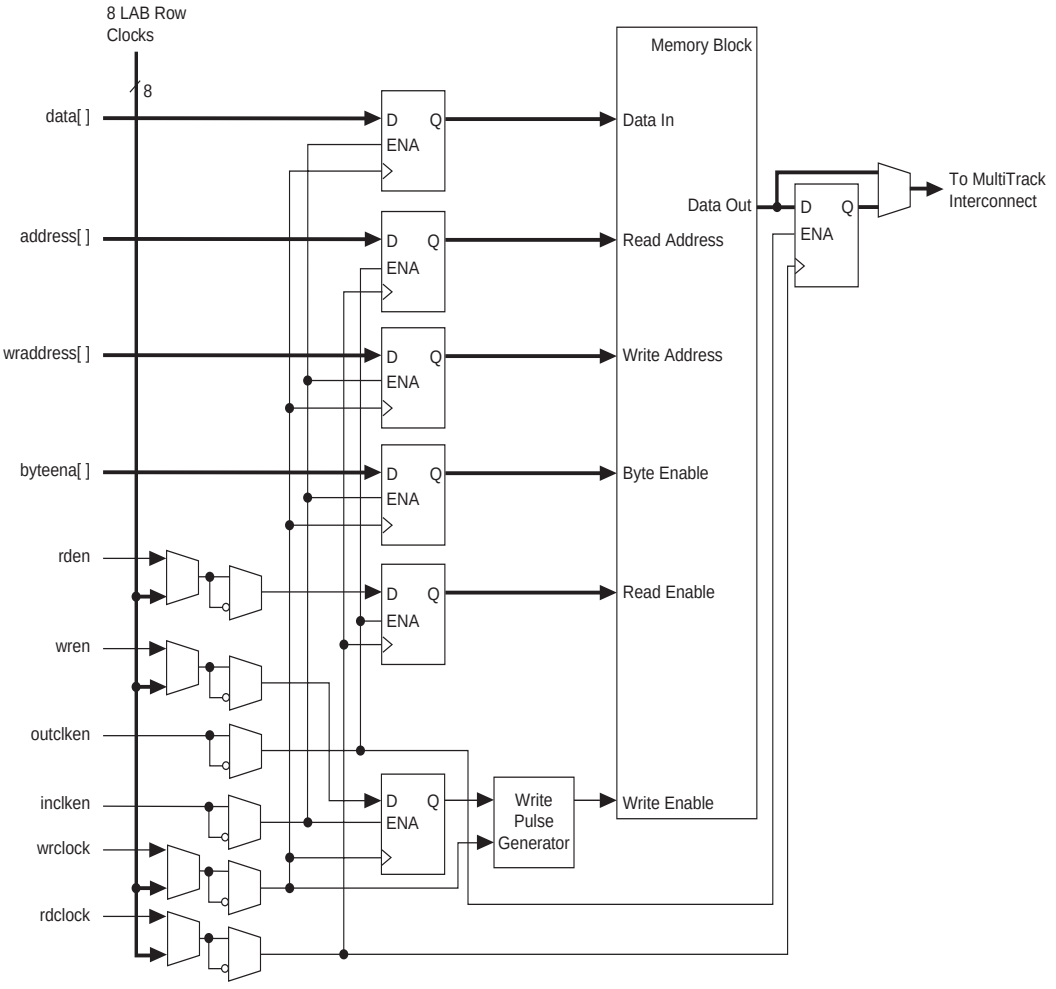


Notes to Figure 2–25:

(1) All registers shown have asynchronous clear ports.

(2) Violating the setup or hold time on the address registers could corrupt the memory contents. This applies to both read and write operations.

Figure 2–27. Read/Write Clock Mode in Simple Dual-Port Mode Notes (1), (2)

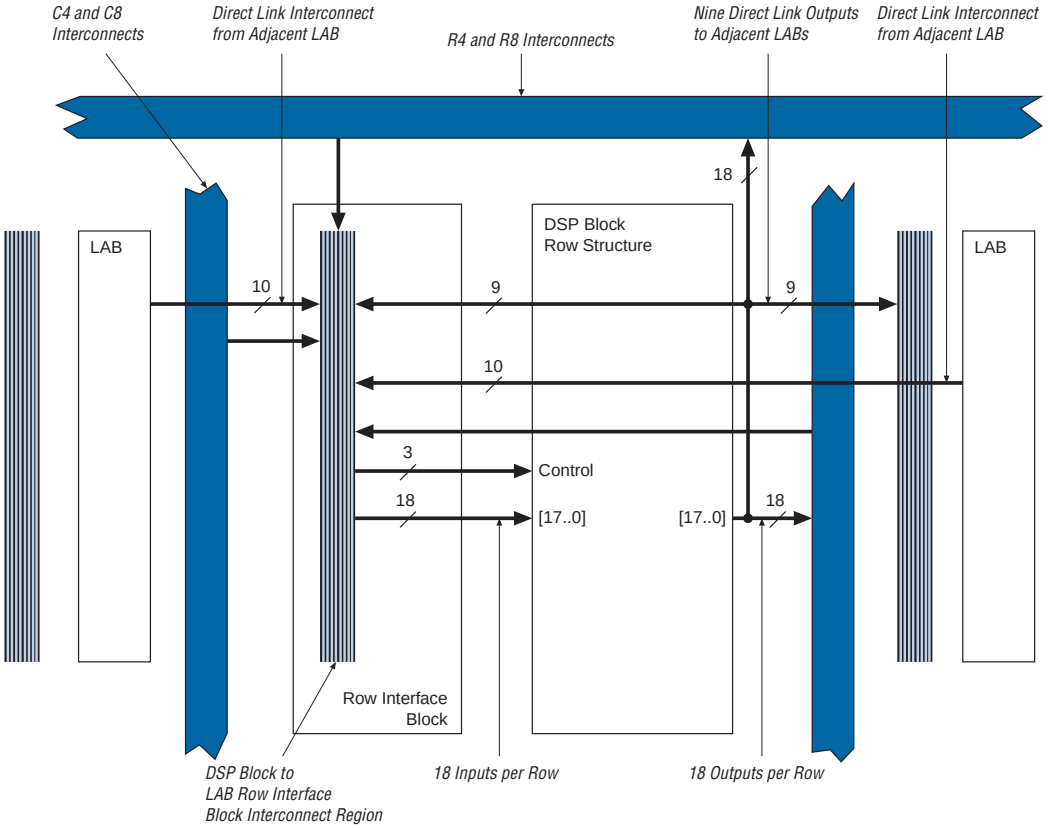


Notes to Figure 2–27:

(1) All registers shown except the `rden` register have asynchronous clear ports.

(2) Violating the setup or hold time on the address registers could corrupt the memory contents. This applies to both read and write operations.

Figure 2–41. DSP Block Interface to Interconnect



A bus of 18 control signals feeds the entire DSP block. These signals include `clock[0..3]` clocks, `aclr[0..3]` asynchronous clears, `ena[1..4]` clock enables, `signa`, `signb` signed/unsigned control signals, `addnsub1` and `addnsub3` addition and subtraction control signals, and `accum_sload[0..1]` accumulator synchronous loads. The

bandwidth is tuned by varying the charge pump current, loop filter resistor value, high frequency capacitor value, and *m* counter value. You can manually adjust these values if desired. Bandwidth is programmable from 200 kHz to 1.5 MHz.

External Clock Outputs

Enhanced PLLs 5 and 6 each support up to eight single-ended clock outputs (or four differential pairs). Differential SSTL and HSTL outputs are implemented using 2 single-ended output buffers which are programmed to have opposite polarity. In Quartus II software, simply assign the appropriate differential I/O standard and the software will implement the inversion. See Figure 2–55.

and/or output enable registers. A programmable delay exists to increase the t_{ZX} delay to the output pin, which is required for ZBT interfaces. Table 2–24 shows the programmable delays for Stratix devices.

Table 2–24. Stratix Programmable Delay Chain

Programmable Delays	Quartus II Logic Option
Input pin to logic array delay	Decrease input delay to internal cells
Input pin to input register delay	Decrease input delay to input register
Output pin delay	Increase delay to output pin
Output enable register t_{CO} delay	Increase delay to output enable pin
Output t_{ZX} delay	Increase t_{ZX} delay to output pin
Output clock enable delay	Increase output clock enable delay
Input clock enable delay	Increase input clock enable delay
Logic array to output register delay	Decrease input delay to output register
Output enable clock enable delay	Increase output enable clock enable delay

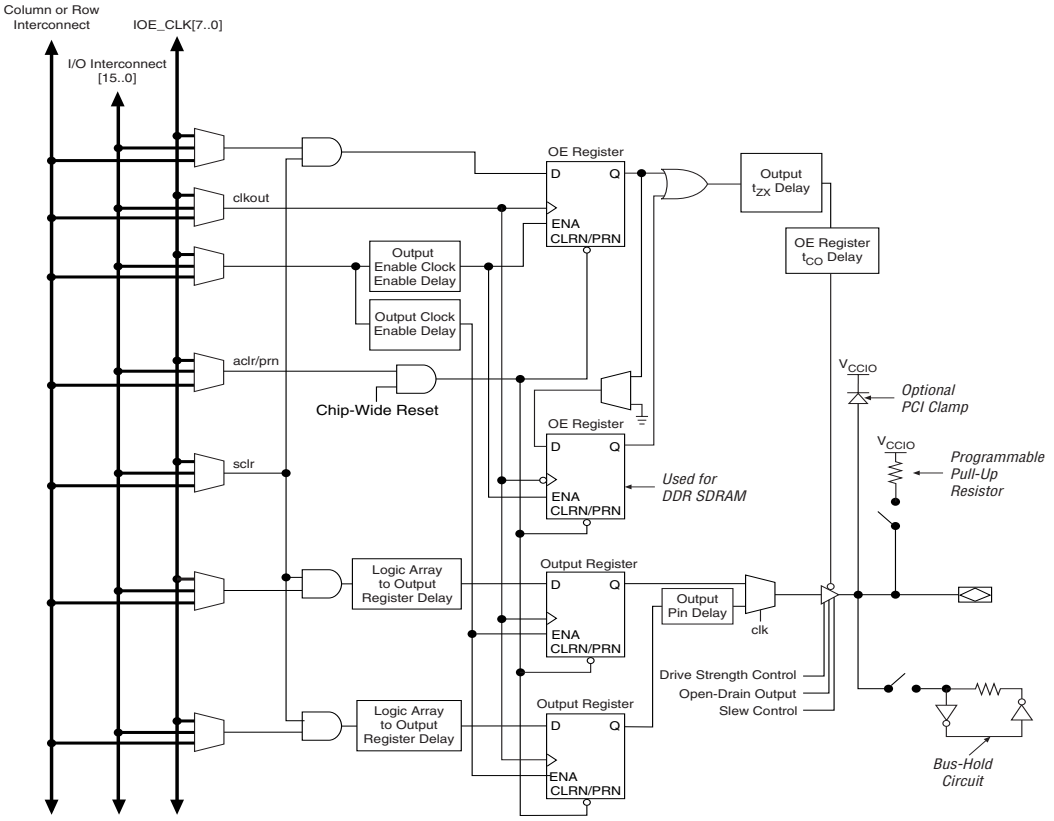
The IOE registers in Stratix devices share the same source for clear or preset. You can program preset or clear for each individual IOE. You can also program the registers to power up high or low after configuration is complete. If programmed to power up low, an asynchronous clear can control the registers. If programmed to power up high, an asynchronous preset can control the registers. This feature prevents the inadvertent activation of another device's active-low input upon power-up. If one register in an IOE uses a preset or clear signal then all registers in the IOE must use that same signal if they require preset or clear. Additionally a synchronous reset signal is available for the IOE registers.

Double-Data Rate I/O Pins

Stratix devices have six registers in the IOE, which support DDR interfacing by clocking data on both positive and negative clock edges. The IOEs in Stratix devices support DDR inputs, DDR outputs, and bidirectional DDR modes.

When using the IOE for DDR inputs, the two input registers clock double rate input data on alternating edges. An input latch is also used within the IOE for DDR input acquisition. The latch holds the data that is present during the clock high times. This allows both bits of data to be synchronous with the same clock edge (either rising or falling). Figure 2–65 shows an IOE configured for DDR input. Figure 2–66 shows the DDR input timing diagram.

Figure 2–67. Stratix IOE in DDR Output I/O Configuration Notes (1), (2)



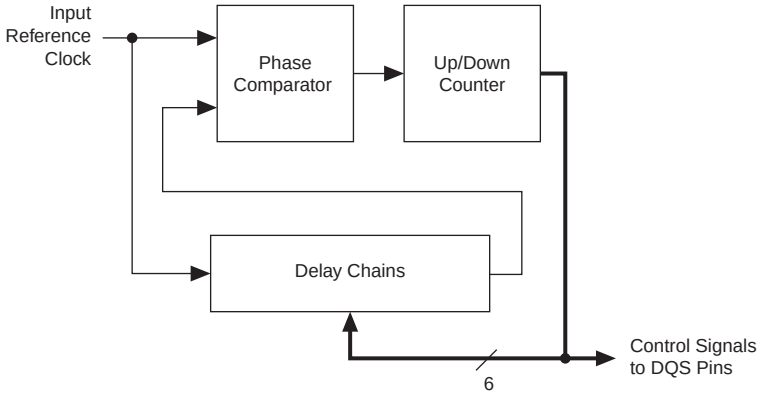
Notes to Figure 2–67:

(1) All input signals to the IOE can be inverted at the IOE.

(2) The tristate is by default active high. It can, however, be designed to be active low.

shift by the same degree amount. For example, all 10 DQS pins on the top of the device can be shifted by 90° and all 10 DQS pins on the bottom of the device can be shifted by 72°. The reference circuits require a maximum of 256 system reference clock cycles to set the correct phase on the DQS delay elements. Figure 2–69 illustrates the phase-shift reference circuit control of each DQS delay shift on the top of the device. This same circuit is duplicated on the bottom of the device.

Figure 2–69. Simplified Diagram of the DQS Phase-Shift Circuitry

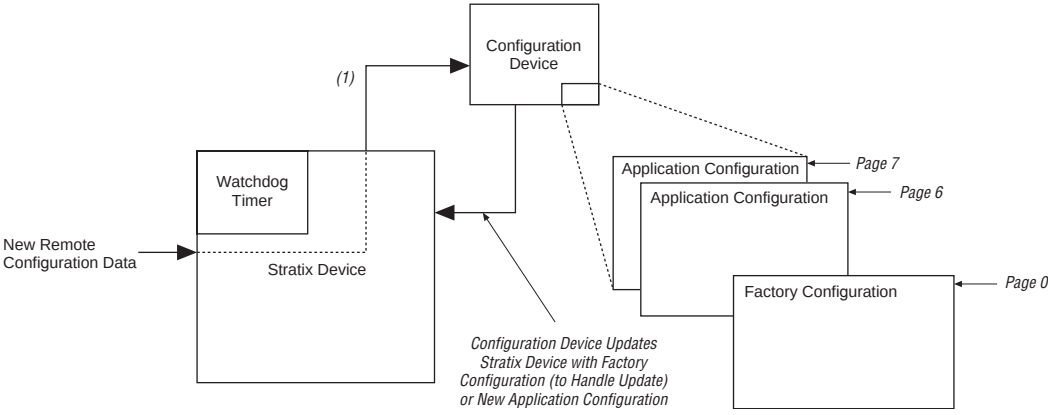


See the *External Memory Interfaces* chapter in the *Stratix Device Handbook, Volume 2* for more information on external memory interfaces.

Programmable Drive Strength

The output buffer for each Stratix device I/O pin has a programmable drive strength control for certain I/O standards. The LVTTL and LVCMOS standard has several levels of drive strength that the user can control. SSTL-3 Class I and II, SSTL-2 Class I and II, HSTL Class I and II, and 3.3-V GTL+ support a minimum setting, the lowest drive strength that guarantees the I_{OH}/I_{OL} of the standard. Using minimum settings provides signal slew rate control to reduce system noise and signal overshoot.

Figure 3–2. Stratix Device Remote Update



Note to Figure 3–2:

(1) When the Stratix device is configured with the factory configuration, it can handle update data from EPC16, EPC8, or EPC4 configuration device pages and point to the next page in the configuration device.

Table 4–18. SSTL-18 Class I Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		1.65	1.8	1.95	V
V_{REF}	Reference voltage		0.8	0.9	1.0	V
V_{TT}	Termination voltage		V_{REF} – 0.04	V_{REF}	V_{REF} + 0.04	V
$V_{IH(DC)}$	High-level DC input voltage		V_{REF} + 0.125			V
$V_{IL(DC)}$	Low-level DC input voltage				V_{REF} – 0.125	V
$V_{IH(AC)}$	High-level AC input voltage		V_{REF} + 0.275			V
$V_{IL(AC)}$	Low-level AC input voltage				V_{REF} – 0.275	V
V_{OH}	High-level output voltage	I_{OH} = –6.7 mA *(3)*	V_{TT} + 0.475			V
V_{OL}	Low-level output voltage	I_{OL} = 6.7 mA *(3)*			V_{TT} – 0.475	V

Table 4–19. SSTL-18 Class II Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		1.65	1.8	1.95	V
V_{REF}	Reference voltage		0.8	0.9	1.0	V
V_{TT}	Termination voltage		V_{REF} – 0.04	V_{REF}	V_{REF} + 0.04	V
$V_{IH(DC)}$	High-level DC input voltage		V_{REF} + 0.125			V
$V_{IL(DC)}$	Low-level DC input voltage				V_{REF} – 0.125	V
$V_{IH(AC)}$	High-level AC input voltage		V_{REF} + 0.275			V
$V_{IL(AC)}$	Low-level AC input voltage				V_{REF} – 0.275	V
V_{OH}	High-level output voltage	I_{OH} = –13.4 mA *(3)*	V_{TT} + 0.630			V
V_{OL}	Low-level output voltage	I_{OL} = 13.4 mA *(3)*			V_{TT} – 0.630	V

Internal Timing Parameters

Internal timing parameters are specified on a speed grade basis independent of device density. Tables 4–37 through 4–42 describe the Stratix device internal timing microparameters for LEs, IOEs, TriMatrix™ memory structures, DSP blocks, and MultiTrack interconnects.

Table 4–37. LE Internal Timing Microparameter Descriptions

Symbol	Parameter
t_{SU}	LE register setup time before clock
t_{H}	LE register hold time after clock
t_{CO}	LE register clock-to-output delay
t_{LUT}	LE combinatorial LUT delay for data-in to data-out
t_{CLR}	Minimum clear pulse width
t_{PRE}	Minimum preset pulse width
t_{CLKHL}	Register minimum clock high or low time. The maximum core clock frequency can be calculated by $1/(2 \times t_{CLKHL})$.

Table 4–38. IOE Internal Timing Microparameter Descriptions

Symbol	Parameter
t_{SU_R}	Row IOE input register setup time
t_{SU_C}	Column IOE input register setup time
t_{H}	IOE input and output register hold time after clock
t_{CO_R}	Row IOE input and output register clock-to-output delay
t_{CO_C}	Column IOE input and output register clock-to-output delay
$t_{PIN2COMBOUT\_R}$	Row input pin to IOE combinatorial output
$t_{PIN2COMBOUT\_C}$	Column input pin to IOE combinatorial output
$t_{COMBIN2PIN\_R}$	Row IOE data input to combinatorial output pin
$t_{COMBIN2PIN\_C}$	Column IOE data input to combinatorial output pin
t_{CLR}	Minimum clear pulse width
t_{PRE}	Minimum preset pulse width
t_{CLKHL}	Register minimum clock high or low time. The maximum I/O clock frequency can be calculated by $1/(2 \times t_{CLKHL})$. Performance may also be affected by I/O timing, use of PLL, and I/O programmable settings.

Tables 4–67 through 4–72 show the external timing parameters on column and row pins for EP1S25 devices.

Table 4–67. EP1S25 External I/O Timing on Column Pins Using Fast Regional Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.412		2.613		2.968		3.468		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.196	4.475	2.196	4.748	2.196	5.118	2.196	5.603	ns
t_{XZ}	2.136	4.349	2.136	4.616	2.136	4.994	2.136	5.488	ns
t_{ZX}	2.136	4.349	2.136	4.616	2.136	4.994	2.136	5.488	ns

Table 4–68. EP1S25 External I/O Timing on Column Pins Using Regional Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	1.535		1.661		1.877		2.125		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.739	5.396	2.739	5.746	2.739	6.262	2.739	6.946	ns
t_{XZ}	2.679	5.270	2.679	5.614	2.679	6.138	2.679	6.831	ns
t_{ZX}	2.679	5.270	2.679	5.614	2.679	6.138	2.679	6.831	ns
$t_{INSUPLL}$	0.934		0.980		1.092		1.231		ns
t_{INHPLL}	0.000		0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	1.316	2.733	1.316	2.839	1.316	2.921	1.316	3.110	ns
t^{XZPLL}	1.256	2.607	1.256	2.707	1.256	2.797	1.256	2.995	ns
t_{ZXPLL}	1.256	2.607	1.256	2.707	1.256	2.797	1.256	2.995	ns

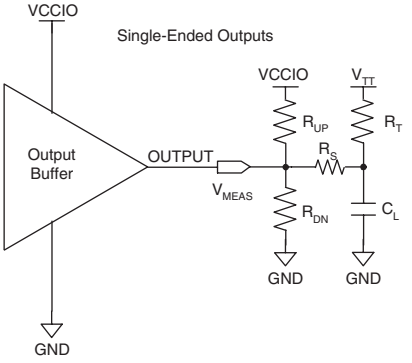
Table 4–81. EP1S40 External I/O Timing on Column Pins Using Global Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.126		2.268		2.558		2.930		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.856	5.585	2.856	5.987	2.856	6.541	2.847	7.253	ns
t_{XZ}	2.796	5.459	2.796	5.855	2.796	6.417	2.787	7.138	ns
t_{ZX}	2.796	5.459	2.796	5.855	2.796	6.417	2.787	7.138	ns
$t_{INSUPLL}$	1.466		1.455		1.711		1.906		ns
t_{INHPLL}	0.000		0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	1.092	2.345	1.092	2.510	1.092	2.455	1.089	2.473	ns
t_{XZPLL}	1.032	2.219	1.032	2.378	1.032	2.331	1.029	2.358	ns
t_{ZXPLL}	1.032	2.219	1.032	2.378	1.032	2.331	1.029	2.358	ns

Table 4–82. EP1S40 External I/O Timing on Row Pins Using Fast Regional Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.472		2.685		3.083		3.056		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.631	5.258	2.631	5.625	2.631	6.105	2.745	7.324	ns
t_{XZ}	2.658	5.312	2.658	5.681	2.658	6.173	2.772	7.406	ns
t_{ZX}	2.658	5.312	2.658	5.681	2.658	6.173	2.772	7.406	ns

Figure 4–7. Output Delay Timing Reporting Setup Modeled by Quartus II



Notes to Figure 4–7:

(1) Output pin timing is reported at the output pin of the FPGA device. Additional delays for loading and board trace delay need to be accounted for with IBIS model simulations.

(2) V_{CCINT} is 1.42-V unless otherwise specified.

Table 4–101. Reporting Methodology For Maximum Timing For Single-Ended Output Pins (Part 1 of 2)
Notes (1), (2), (3)

I/O Standard	Loading and Termination							Measurement Point
	R_{UP} Ω	R_{DN} Ω	R_S Ω	R_T Ω	V_{CCIO} (V)	VTT (V)	C_L (pF)	V_{MEAS}
3.3-V LVTTL	–	–	0	–	2.950	2.95	10	1.500
2.5-V LVTTL	–	–	0	–	2.370	2.37	10	1.200
1.8-V LVTTL	–	–	0	–	1.650	1.65	10	0.880
1.5-V LVTTL	–	–	0	–	1.400	1.40	10	0.750
3.3-V LVCMOS	–	–	0	–	2.950	2.95	10	1.500
2.5-V LVCMOS	–	–	0	–	2.370	2.37	10	1.200
1.8-V LVCMOS	–	–	0	–	1.650	1.65	10	0.880
1.5-V LVCMOS	–	–	0	–	1.400	1.40	10	0.750
3.3-V GTL	–	–	0	25	2.950	1.14	30	0.740
2.5-V GTL	–	–	0	25	2.370	1.14	30	0.740
3.3-V GTL+	–	–	0	25	2.950	1.35	30	0.880
2.5-V GTL+	–	–	0	25	2.370	1.35	30	0.880
3.3-V SSTL-3 Class II	–	–	25	25	2.950	1.25	30	1.250

Table 4–117. Stratix Maximum Input Clock Rate for CLK[7..4] & CLK[15..12] Pins in Wire-Bond Packages (Part 2 of 2)

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
GTL+	250	200	200	MHz
SSTL-3 Class I	300	250	250	MHz
SSTL-3 Class II	300	250	250	MHz
SSTL-2 Class I	300	250	250	MHz
SSTL-2 Class II	300	250	250	MHz
SSTL-18 Class I	300	250	250	MHz
SSTL-18 Class II	300	250	250	MHz
1.5-V HSTL Class I	300	180	180	MHz
1.5-V HSTL Class II	300	180	180	MHz
1.8-V HSTL Class I	300	180	180	MHz
1.8-V HSTL Class II	300	180	180	MHz
3.3-V PCI	422	390	390	MHz
3.3-V PCI-X 1.0	422	390	390	MHz
Compact PCI	422	390	390	MHz
AGP 1×	422	390	390	MHz
AGP 2×	422	390	390	MHz
CTT	250	180	180	MHz
Differential 1.5-V HSTL C1	300	180	180	MHz
LVPECL *(1)*	422	400	400	MHz
PCML *(1)*	215	200	200	MHz
LVDS *(1)*	422	400	400	MHz
HyperTransport technology *(1)*	422	400	400	MHz

Table 4–118. Stratix Maximum Input Clock Rate for CLK[0, 2, 9, 11] Pins & FPLL[10..7]CLK Pins in Wire-Bond Packages (Part 1 of 2)

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVTTL	422	390	390	MHz
2.5 V	422	390	390	MHz
1.8 V	422	390	390	MHz
1.5 V	422	390	390	MHz

High-Speed I/O Specification

Table 4–124 provides high-speed timing specifications definitions.

Table 4–124. High-Speed Timing Specifications & Terminology

High-Speed Timing Specification	Terminology
t_C	High-speed receiver/transmitter input and output clock period.
f_{HSCLK}	High-speed receiver/transmitter input and output clock frequency.
t_{RISE}	Low-to-high transmission time.
t_{FALL}	High-to-low transmission time.
Timing unit interval (TUI)	The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = 1/(Receiver Input Clock Frequency × Multiplication Factor) = t_C/w).
f_{HSDR}	Maximum LVDS data transfer rate (f_{HSDR} = 1/TUI).
Channel-to-channel skew (TCCS)	The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement.
Sampling window (SW)	The period of time during which the data must be valid to be captured correctly. The setup and hold times determine the ideal strobe position within the sampling window. SW = t_{SW} (max) – t_{SW} (min).
Input jitter (peak-to-peak)	Peak-to-peak input jitter on high-speed PLLs.
Output jitter (peak-to-peak)	Peak-to-peak output jitter on high-speed PLLs.
t_{DUTY}	Duty cycle on high-speed transmitter output clock.
t_{LOCK}	Lock time for high-speed transmitter and receiver PLLs.
J	Deserialization factor (width of internal data bus).
W	PLL multiplication factor.

Table 4–126. High-Speed I/O Specifications for Wire-Bond Packages (Part 1 of 2)

Symbol	Conditions	-6 Speed Grade			-7 Speed Grade			-8 Speed Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
f_{HSCLK} (Clock frequency) (LVDS,LVPECL, HyperTransport technology) $f_{HSCLK} = f_{HSDR} / W$	*W* = 4 to 30 (Serdes used)	10		156	10		115.5	10		115.5	MHz
	W = 2 (Serdes bypass)	50		231	50		231	50		231	MHz
	W = 2 (Serdes used)	150		312	150		231	150		231	MHz
	W = 1 (Serdes bypass)	100		311	100		270	100		270	MHz
	W = 1 (Serdes used)	300		624	300		462	300		462	MHz
f_{HSDR} Device operation, (LVDS,LVPECL, HyperTransport technology)	J = 10	300		624	300		462	300		462	Mbps
	J = 8	300		624	300		462	300		462	Mbps
	J = 7	300		624	300		462	300		462	Mbps
	J = 4	300		624	300		462	300		462	Mbps
	J = 2	100		462	100		462	100		462	Mbps
	J = 1 (LVDS and LVPECL only)	100		311	100		270	100		270	Mbps
f_{HSCLK} (Clock frequency) (PCML) $f_{HSCLK} = f_{HSDR} / W$	*W* = 4 to 30 (Serdes used)	10		77.75							MHz
	W = 2 (Serdes bypass)	50		150	50		77.5	50		77.5	MHz
	W = 2 (Serdes used)	150		155.5							MHz
	W = 1 (Serdes bypass)	100		200	100		155	100		155	MHz
	W = 1 (Serdes used)	300		311							MHz
Device operation, f_{HSDR} (PCML)	J = 10	300		311							Mbps
	J = 8	300		311							Mbps
	J = 7	300		311							Mbps
	J = 4	300		311							Mbps
	J = 2	100		300	100		155	100		155	Mbps
	J = 1	100		200	100		155	100		155	Mbps
TCCS	All			400			400			400	ps

Table 4–130. Enhanced PLL Specifications for -8 Speed Grade (Part 2 of 3)

Symbol	Parameter	Min	Typ	Max	Unit
$t_{EINJITTER}$	External feedback clock period jitter			±200 *(3)*	ps
t_{FCOMP}	External feedback clock compensation time *(4)*			6	ns
f_{OUT}	Output frequency for internal global or regional clock	0.3		357	MHz
f_{OUT_EXT}	Output frequency for external clock *(3)*	0.3		369	MHz
$t_{OUTDUTY}$	Duty cycle for external clock output (when set to 50%)	45		55	%
t_{JITTER}	Period jitter for external clock output *(6)*			±100 ps for >200-MHz `outclk` ±20 mUI for <200-MHz `outclk`	ps or mUI
$t_{CONFIG5,6}$	Time required to reconfigure the scan chains for PLLs 5 and 6			$289/f_{SCANCLK}$	
$t_{CONFIG11,12}$	Time required to reconfigure the scan chains for PLLs 11 and 12			$193/f_{SCANCLK}$	
$t_{SCANCLK}$	`scanclk` frequency *(5)*			22	MHz
t_{DLOCK}	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays) *(7)* *(11)*	*(9)*		100	µs
t_{LOCK}	Time required to lock from end of device configuration *(11)*	10		400	µs
f_{VCO}	PLL internal VCO operating range	300		600 *(8)*	MHz