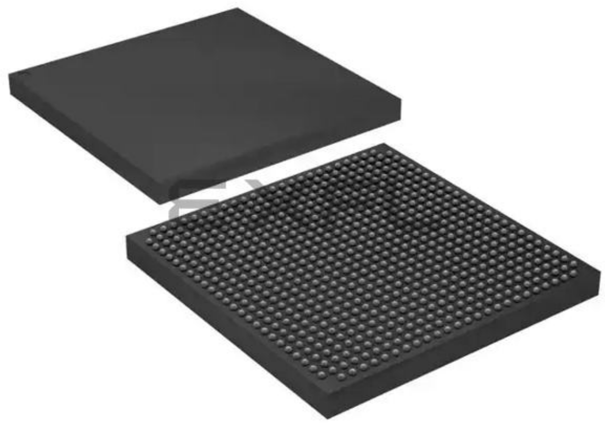

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	1846
Number of Logic Elements/Cells	18460
Total RAM Bits	1669248
Number of I/O	426
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	672-BBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1s20f672i7

Section I. Stratix Device Family Data Sheet

This section provides the data sheet specifications for Stratix® devices. They contain feature definitions of the internal architecture, configuration and JTAG boundary-scan testing information, DC operating conditions, AC timing parameters, a reference to power consumption, and ordering information for Stratix devices.

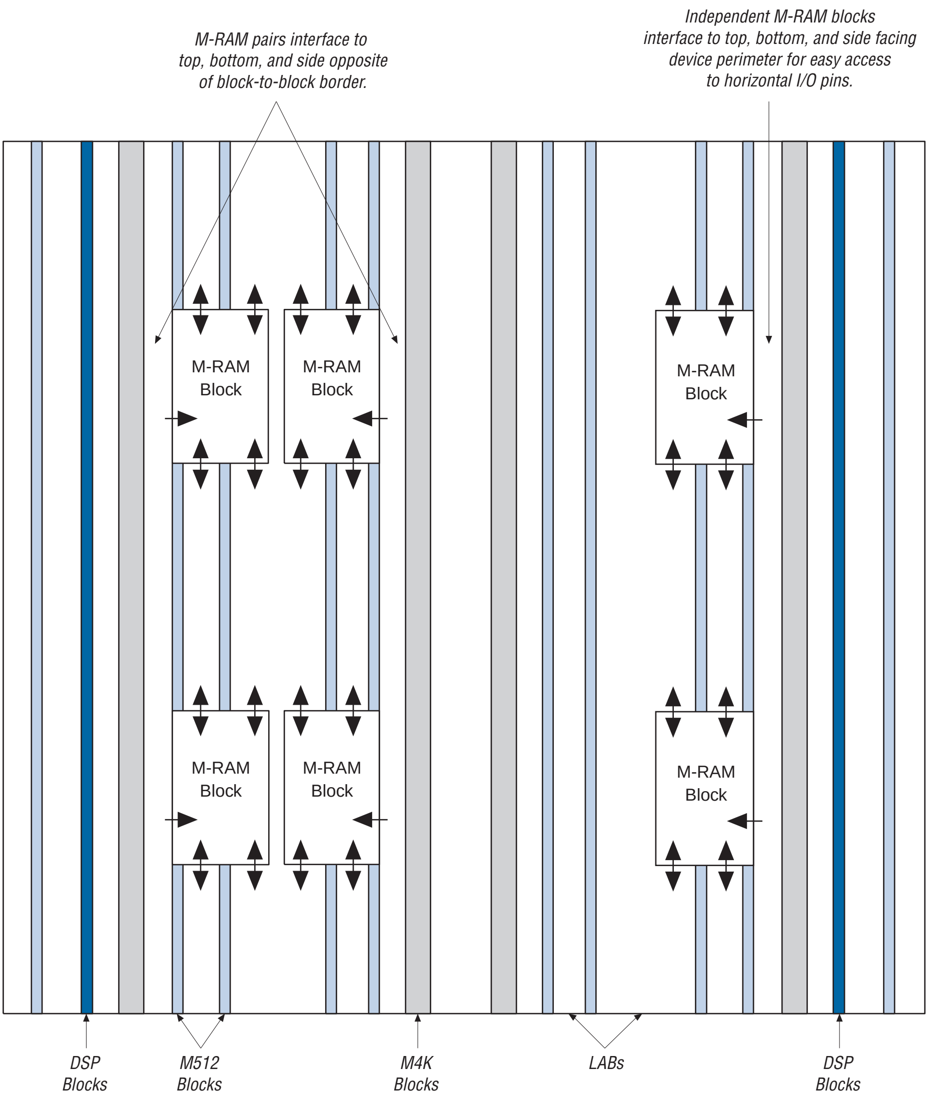
This section contains the following chapters:

Revision History

The table below shows the revision history for Chapters 1 through 5.

Chapter	Date/Version	Changes Made
1	July 2005, v3.2	• Minor content changes.
	September 2004, v3.1	• Updated Table 1–6 on page 1–5.
	April 2004, v3.0	• Main section page numbers changed on first page. • Changed PCI-X to PCI-X 1.0 in "Features" on page 1–2. • Global change from SignalTap to SignalTap II. • The DSP blocks in "Features" on page 1–2 provide dedicated implementation of multipliers that are now "faster than 300 MHz."
	January 2004, v2.2	• Updated -5 speed grade device information in Table 1-6.
	October 2003, v2.1	• Add -8 speed grade device information.
	July 2003, v2.0	• Format changes throughout chapter.

Figure 2–20. EP1S60 Device with M-RAM Interface Locations Note (1)



Note to Figure 2–20:

(1) Device shown is an EP1S60 device. The number and position of M-RAM blocks varies in other devices.

The M-RAM block local interconnect is driven by the R4, R8, C4, C8, and direct link interconnects from adjacent LABs. For independent M-RAM blocks, up to 10 direct link address and control signal input connections to the M-RAM block are possible from the left adjacent LABs for M-RAM

Figure 2–22. M-RAM Row Unit Interface to Interconnect

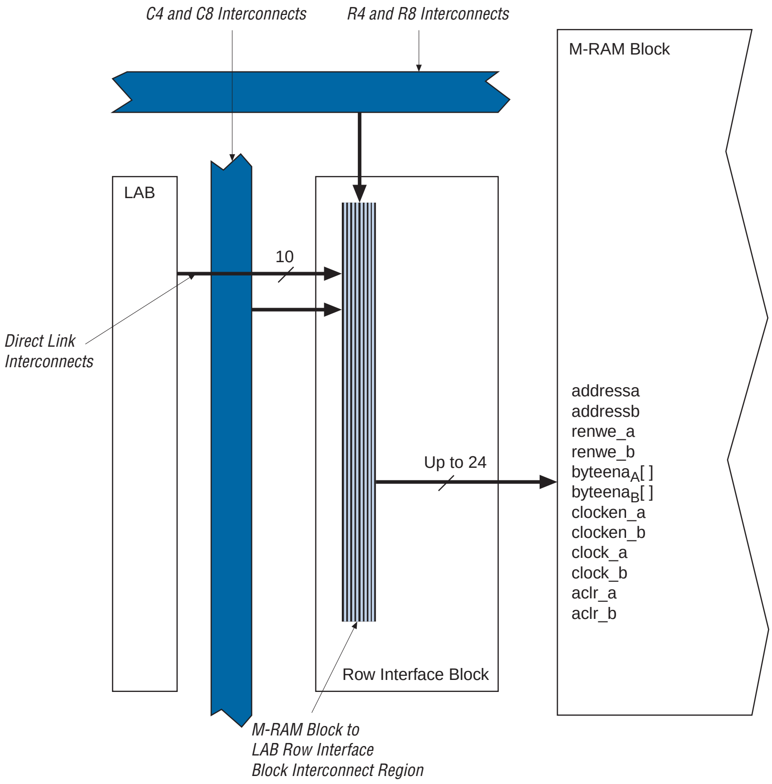


Table 2–12 shows the input and output data signal connections for the column units (B1 to B6 and A1 to A6). It also shows the address and control signal input connections to the row units (R1 to R11).

Table 2–12. M-RAM Row & Column Interface Unit Signals

Unit Interface Block	Input SIgnals	Output Signals
R1	addressa[7..0]	
R2	addressa[15..8]	
R3	byte_enable_a[7..0] renwe_a	
R4	-	
R5	-	
R6	clock_a clocken_a clock_b clocken_b	
R7	-	
R8	-	
R9	byte_enable_b[7..0] renwe_b	
R10	addressb[15..8]	
R11	addressb[7..0]	
B1	datain_b[71..60]	dataout_b[71..60]
B2	datain_b[59..48]	dataout_b[59..48]
B3	datain_b[47..36]	dataout_b[47..36]
B4	datain_b[35..24]	dataout_b[35..24]
B5	datain_b[23..12]	dataout_b[23..12]
B6	datain_b[11..0]	dataout_b[11..0]
A1	datain_a[71..60]	dataout_a[71..60]
A2	datain_a[59..48]	dataout_a[59..48]
A3	datain_a[47..36]	dataout_a[47..36]
A4	datain_a[35..24]	dataout_a[35..24]
A5	datain_a[23..12]	dataout_a[23..12]
A6	datain_a[11..0]	dataout_a[11..0]

Digital Signal Processing Block

The most commonly used DSP functions are finite impulse response (FIR) filters, complex FIR filters, infinite impulse response (IIR) filters, fast Fourier transform (FFT) functions, direct cosine transform (DCT) functions, and correlators. All of these blocks have the same fundamental building block: the multiplier. Additionally, some applications need specialized operations such as multiply-add and multiply-accumulate operations. Stratix devices provide DSP blocks to meet the arithmetic requirements of these functions.

Each Stratix device has two columns of DSP blocks to efficiently implement DSP functions faster than LE-based implementations. Larger Stratix devices have more DSP blocks per column (see Table 2–13). Each DSP block can be configured to support up to:

- Eight 9 × 9-bit multipliers
- Four 18 × 18-bit multipliers
- One 36 × 36-bit multiplier

As indicated, the Stratix DSP block can support one 36 × 36-bit multiplier in a single DSP block. This is true for any matched sign multiplications (either unsigned by unsigned or signed by signed), but the capabilities for dynamic and mixed sign multiplications are handled differently. The following list provides the largest functions that can fit into a single DSP block.

- 36 × 36-bit unsigned by unsigned multiplication
- 36 × 36-bit signed by signed multiplication
- 35 × 36-bit unsigned by signed multiplication
- 36 × 35-bit signed by unsigned multiplication
- 36 × 35-bit signed by dynamic sign multiplication
- 35 × 36-bit dynamic sign by signed multiplication
- 35 × 36-bit unsigned by dynamic sign multiplication
- 36 × 35-bit dynamic sign by unsigned multiplication
- 35 × 35-bit dynamic sign multiplication when the sign controls for each operand are different
- 36 × 36-bit dynamic sign multiplication when the same sign control is used for both operands

☞ This list only shows functions that can fit into a single DSP block. Multiple DSP blocks can support larger multiplication functions.

Figure 2–29 shows one of the columns with surrounding LAB rows.

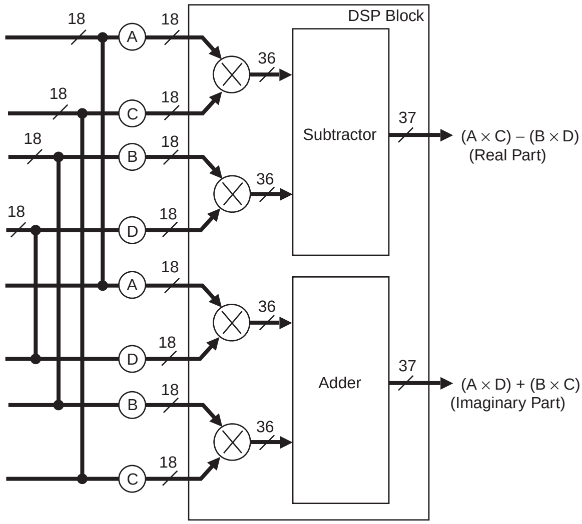
single DSP block can implement two sums or differences from two 18 × 18-bit multipliers each or four sums or differences from two 9 × 9-bit multipliers each.

You can use the two-multipliers adder mode for complex multiplications, which are written as:

$$(a + jb) \times (c + jd) = [(a \times c) - (b \times d)] + j \times [(a \times d) + (b \times c)]$$

The two-multipliers adder mode allows a single DSP block to calculate the real part $[(a \times c) - (b \times d)]$ using one subtractor and the imaginary part $[(a \times d) + (b \times c)]$ using one adder, for data widths up to 18 bits. Two complex multiplications are possible for data widths up to 9 bits using four adder/subtractor/accumulator blocks. Figure 2–38 shows an 18-bit two-multipliers adder.

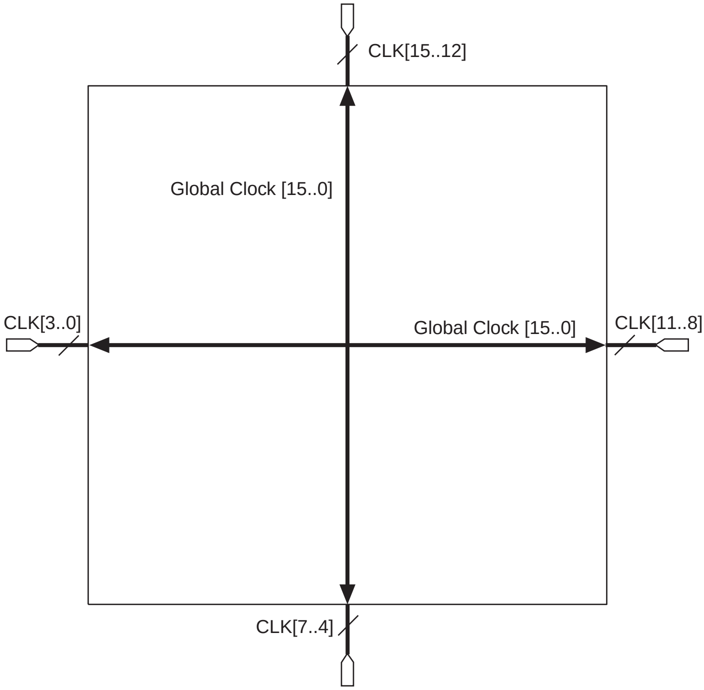
Figure 2–38. Two-Multipliers Adder Mode Implementing Complex Multiply



Four-Multipliers Adder Mode

In the four-multipliers adder mode, the DSP block adds the results of two first -stage adder/subtractor blocks. One sum of four 18 × 18-bit multipliers or two different sums of two sets of four 9 × 9-bit multipliers can be implemented in a single DSP block. The product width for each multiplier must be the same size. The four-multipliers adder mode is useful for FIR filter applications. Figure 2–39 shows the four multipliers adder mode.

Figure 2–42. Global Clocking Note (1)



Note to Figure 2–42:

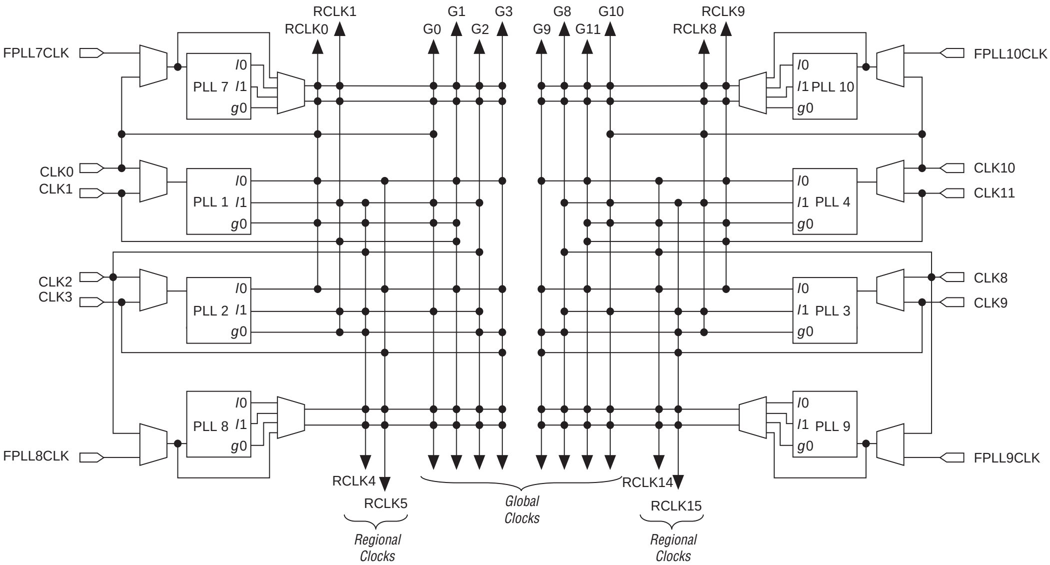
(1) The corner fast PLLs can also be driven through the global or regional clock networks. The global or regional clock input to the fast PLL can be driven by an output from another PLL, a pin-driven global or regional clock, or internally-generated global signals.

Regional Clock Network

There are four regional clock networks within each quadrant of the Stratix device that are driven by the same dedicated `CLK[15..0]` input pins or from PLL outputs. From a top view of the silicon, `RCLK[0..3]` are in the top left quadrant, `RCLK[8..11]` are in the top-right quadrant, `RCLK[4..7]` are in the bottom-left quadrant, and `RCLK[12..15]` are in the bottom-right quadrant. The regional clock networks only pertain to the quadrant they drive into. The regional clock networks provide the lowest clock delay and skew for logic contained within a single quadrant. `RCLK` cannot be driven by internal logic. The `CLK` clock pins symmetrically drive the `RCLK` networks within a particular quadrant, as shown in Figure 2–43. See Figures 2–50 and 2–51 for `RCLK` connections from PLLs and `CLK` pins.

Figure 2–50 shows the global and regional clocking from the PLL outputs and the CLK pins.

Figure 2–50. Global & Regional Clock Connections from Side Pins & Fast PLL Outputs *Note (1), (2)*



Notes to Figure 2–50:

(1) PLLs 1 to 4 and 7 to 10 are fast PLLs. PLLs 5, 6, 11, and 12 are enhanced PLLs.

(2) The global or regional clocks in a fast PLL's quadrant can drive the fast PLL input. A pin or other PLL must drive the global or regional source. The source cannot be driven by internally generated logic before driving the fast PLL.

Figure 2–51 shows the global and regional clocking from enhanced PLL outputs and top `CLK` pins.

While in the factory configuration, the factory-configuration logic performs the following operations:

- Loads a remote update-control register to determine the page address of the new application configuration
- Determines whether to enable a user watchdog timer for the application configuration
- Determines what the watchdog timer setting should be if it is enabled

The user watchdog timer is a counter that must be continually reset within a specific amount of time in the user mode of an application configuration to ensure that valid configuration occurred during a remote update. Only valid application configurations designed for remote update can reset the user watchdog timer in user mode. If a valid application configuration does not reset the user watchdog timer in a specific amount of time, the timer updates a status register and loads the factory configuration. The user watchdog timer is automatically disabled for factory configurations.

If an error occurs in loading the application configuration, the configuration logic writes a status register to specify the cause of the error. Once this occurs, the Stratix device automatically loads the factory configuration, which reads the status register and determines the reason for reconfiguration. Based on the reason, the factory configuration will take appropriate steps and will write the remote update control register to specify the next application configuration page to be loaded.

When the Stratix device successfully loads the application configuration, it enters into user mode. The Stratix device then executes the main application of the user. Intellectual property (IP), such as a Nios® (16-bit ISA) and Nios® II (32-bit ISA) embedded processors, can help the Stratix device determine when remote update is coming. The Nios embedded processor or user logic receives incoming data, writes it to the configuration device, and loads the factory configuration. The factory configuration will read the remote update status register and determine the valid application configuration to load. Figure 3–2 shows the Stratix remote update. Figure 3–3 shows the transition diagram for remote update mode.

Table 4–20. SSTL-2 Class I Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		2.375	2.5	2.625	V
V_{TT}	Termination voltage		$V_{REF} - 0.04$	V_{REF}	$V_{REF} + 0.04$	V
V_{REF}	Reference voltage		1.15	1.25	1.35	V
$V_{IH(DC)}$	High-level DC input voltage		$V_{REF} + 0.18$		3.0	V
$V_{IL(DC)}$	Low-level DC input voltage		–0.3		$V_{REF} - 0.18$	V
$V_{IH(AC)}$	High-level AC input voltage		$V_{REF} + 0.35$			V
$V_{IL(AC)}$	Low-level AC input voltage				$V_{REF} - 0.35$	V
V_{OH}	High-level output voltage	$I_{OH} = -8.1$ mA *(3)*	$V_{TT} + 0.57$			V
V_{OL}	Low-level output voltage	$I_{OL} = 8.1$ mA *(3)*			$V_{TT} - 0.57$	V

Table 4–21. SSTL-2 Class II Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		2.375	2.5	2.625	V
V_{TT}	Termination voltage		$V_{REF} - 0.04$	V_{REF}	$V_{REF} + 0.04$	V
V_{REF}	Reference voltage		1.15	1.25	1.35	V
$V_{IH(DC)}$	High-level DC input voltage		$V_{REF} + 0.18$		$V_{CCIO} + 0.3$	V
$V_{IL(DC)}$	Low-level DC input voltage		–0.3		$V_{REF} - 0.18$	V
$V_{IH(AC)}$	High-level AC input voltage		$V_{REF} + 0.35$			V
$V_{IL(AC)}$	Low-level AC input voltage				$V_{REF} - 0.35$	V
V_{OH}	High-level output voltage	$I_{OH} = -16.4$ mA *(3)*	$V_{TT} + 0.76$			V
V_{OL}	Low-level output voltage	$I_{OL} = 16.4$ mA *(3)*			$V_{TT} - 0.76$	V

Table 4–22. SSTL-3 Class I Specifications (Part 1 of 2)

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		3.0	3.3	3.6	V
V_{TT}	Termination voltage		$V_{REF} - 0.05$	V_{REF}	$V_{REF} + 0.05$	V
V_{REF}	Reference voltage		1.3	1.5	1.7	V
$V_{IH(DC)}$	High-level DC input voltage		$V_{REF} + 0.2$		$V_{CCIO} + 0.3$	V
$V_{IL(DC)}$	Low-level DC input voltage		–0.3		$V_{REF} - 0.2$	V
$V_{IH(AC)}$	High-level AC input voltage		$V_{REF} + 0.4$			V

Table 4–25. 3.3-V AGP 1× Specifications (Part 2 of 2)						
Symbol	**Parameter**	**Conditions**	**Minimum**	**Typical**	**Maximum**	**Unit**
V_{OH}	High-level output voltage	I_{OUT} = –0.5 mA	0.9 × V_{CCIO}		3.6	V
V_{OL}	Low-level output voltage	I_{OUT} = 1.5 mA			0.1 × V_{CCIO}	V

Table 4–26. 1.5-V HSTL Class I Specifications						
Symbol	**Parameter**	**Conditions**	**Minimum**	**Typical**	**Maximum**	**Unit**
V_{CCIO}	Output supply voltage		1.4	1.5	1.6	V
V_{REF}	Input reference voltage		0.68	0.75	0.9	V
V_{TT}	Termination voltage		0.7	0.75	0.8	V
V_{IH} (DC)	DC high-level input voltage		V_{REF} + 0.1			V
V_{IL} (DC)	DC low-level input voltage		–0.3		V_{REF} – 0.1	V
V_{IH} (AC)	AC high-level input voltage		V_{REF} + 0.2			V
V_{IL} (AC)	AC low-level input voltage				V_{REF} – 0.2	V
V_{OH}	High-level output voltage	I_{OH} = –8 mA *(3)*	V_{CCIO} – 0.4			V
V_{OL}	Low-level output voltage	I_{OL} = 8 mA *(3)*			0.4	V

Table 4–27. 1.5-V HSTL Class II Specifications						
Symbol	**Parameter**	**Conditions**	**Minimum**	**Typical**	**Maximum**	**Unit**
V_{CCIO}	Output supply voltage		1.4	1.5	1.6	V
V_{REF}	Input reference voltage		0.68	0.75	0.9	V
V_{TT}	Termination voltage		0.7	0.75	0.8	V
V_{IH} (DC)	DC high-level input voltage		V_{REF} + 0.1			V
V_{IL} (DC)	DC low-level input voltage		–0.3		V_{REF} – 0.1	V
V_{IH} (AC)	AC high-level input voltage		V_{REF} + 0.2			V
V_{IL} (AC)	AC low-level input voltage				V_{REF} – 0.2	V
V_{OH}	High-level output voltage	I_{OH} = –16 mA *(3)*	V_{CCIO} – 0.4			V
V_{OL}	Low-level output voltage	I_{OL} = 16 mA *(3)*			0.4	V

Table 4–39. DSP Block Internal Timing Microparameter Descriptions

Symbol	Parameter
t_{SU}	Input, pipeline, and output register setup time before clock
t_H	Input, pipeline, and output register hold time after clock
t_{CO}	Input, pipeline, and output register clock-to-output delay
$t_{INREG2PIPE9}$	Input Register to DSP Block pipeline register in 9 × 9-bit mode
$t_{INREG2PIPE18}$	Input Register to DSP Block pipeline register in 18 × 18-bit mode
$t_{PIPE2OUTREG2ADD}$	DSP Block Pipeline Register to output register delay in Two-Multipliers Adder mode
$t_{PIPE2OUTREG4ADD}$	DSP Block Pipeline Register to output register delay in Four-Multipliers Adder mode
t_{PD9}	Combinatorial input to output delay for 9 × 9
t_{PD18}	Combinatorial input to output delay for 18 × 18
t_{PD36}	Combinatorial input to output delay for 36 × 36
t_{CLR}	Minimum clear pulse width
t_{CLKHL}	Register minimum clock high or low time. This is a limit on the min time for the clock on the registers in these blocks. The actual performance is dependent upon the internal point-to-point delays in the blocks and may give slower performance as shown in Table 4–36 on page 4–20 and as reported by the timing analyzer in the Quartus II software.

Table 4–45. IOE Internal TSU Microparameter by Device Density (Part 2 of 2)										
Device	**Symbol**	**-5**		**-6**		**-7**		**-8**		**Unit**
		Min	**Max**	**Min**	**Max**	**Min**	**Max**	**Min**	**Max**	
EP1S40	t_{SU_R}	76		80		80		80		ps
	t_{SU_C}	376		380		380		380		ps
EP1S60	t_{SU_R}	276		280		280		280		ps
	t_{SU_C}	276		280		280		280		ps
EP1S80	t_{SU_R}	426		430		430		430		ps
	t_{SU_C}	76		80		80		80		ps

Table 4–46. IOE Internal Timing Microparameters									
Symbol	**-5**		**-6**		**-7**		**-8**		**Unit**
	Min	**Max**	**Min**	**Max**	**Min**	**Max**	**Min**	**Max**	
t_H	68		71		82		96		ps
t_{CO_R}		171		179		206		242	ps
t_{CO_C}		171		179		206		242	ps
$t_{PIN2COMBOUT\_R}$		1,234		1,295		1,490		1,753	ps
$t_{PIN2COMBOUT\_C}$		1,087		1,141		1,312		1,544	ps
$t_{COMBIN2PIN\_R}$		3,894		4,089		4,089		4,089	ps
$t_{COMBIN2PIN\_C}$		4,299		4,494		4,494		4,494	ps
t_{CLR}	276		289		333		392		ps
t_{PRE}	260		273		313		369		ps
t_{CLKHL}	1,000		1,111		1,190		1,400		ps

Table 4–47. DSP Block Internal Timing Microparameters (Part 1 of 2)									
Symbol	**-5**		**-6**		**-7**		**-8**		**Unit**
	Min	**Max**	**Min**	**Max**	**Min**	**Max**	**Min**	**Max**	
t_{SU}	0		0		0		0		ps
t_H	67		75		86		101		ps
t_{CO}		142		158		181		214	ps
$t_{INREG2PIPE9}$		2,613		2,982		3,429		4,035	ps
$t_{INREG2PIPE18}$		3,390		3,993		4,591		5,402	ps

Tables 4–73 through 4–78 show the external timing parameters on column and row pins for EP1S30 devices.

Table 4–73. EP1S30 External I/O Timing on Column Pins Using Fast Regional Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.502		2.680		3.062		3.591		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.473	4.965	2.473	5.329	2.473	5.784	2.473	6.392	ns
t_{XZ}	2.413	4.839	2.413	5.197	2.413	5.660	2.413	6.277	ns
t_{ZX}	2.413	4.839	2.413	5.197	2.413	5.660	2.413	6.277	ns

Table 4–74. EP1S30 External I/O Timing on Column Pins Using Regional Clock Networks

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.286		2.426		2.769		3.249		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.641	5.225	2.641	5.629	2.641	6.130	2.641	6.796	ns
t_{XZ}	2.581	5.099	2.581	5.497	2.581	6.006	2.581	6.681	ns
t_{ZX}	2.581	5.099	2.581	5.497	2.581	6.006	2.581	6.681	ns
$t_{INSUPLL}$	1.200		1.185		1.344		1.662		ns
t_{INHPLL}	0.000		0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	1.108	2.367	1.108	2.534	1.108	2.569	1.108	2.517	ns
t_{XZPLL}	1.048	2.241	1.048	2.402	1.048	2.445	1.048	2.402	ns
t_{ZXPLL}	1.048	2.241	1.048	2.402	1.048	2.445	1.048	2.402	ns

Table 4–75. EP1S30 External I/O Timing on Column Pins Using Global Clock Networks (Part 1 of 2)

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	1.935		2.029		2.310		2.709		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.814	5.532	2.814	5.980	2.814	6.536	2.814	7.274	ns

Table 4–77. EP1S30 External I/O Timing on Row Pins Using Regional Clock Networks									
Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.322		2.467		2.828		3.342		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.731	5.408	2.731	5.843	2.731	6.360	2.731	7.036	ns
t_{XZ}	2.758	5.462	2.758	5.899	2.758	6.428	2.758	7.118	ns
t_{ZX}	2.758	5.462	2.758	5.899	2.758	6.428	2.758	7.118	ns
$t_{INSUPLL}$	1.291		1.283		1.469		1.832		ns
t_{INHPLL}	0.000		0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	1.192	2.539	1.192	2.737	1.192	2.786	1.192	2.742	ns
t_{XZPLL}	1.219	2.539	1.219	2.793	1.219	2.854	1.219	2.824	ns
t_{ZXPLL}	1.219	2.539	1.219	2.793	1.219	2.854	1.219	2.824	ns

Table 4–78. EP1S30 External I/O Timing on Row Pins Using Global Clock Networks									
Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	1.995		2.089		2.398		2.830		ns
t_{INH}	0.000		0.000		0.000		0.000		ns
t_{OUTCO}	2.917	5.735	2.917	6.221	2.917	6.790	2.917	7.548	ns
t_{XZ}	2.944	5.789	2.944	6.277	2.944	6.858	2.944	7.630	ns
t_{ZX}	2.944	5.789	2.944	6.277	2.944	6.858	2.944	7.630	ns
$t_{INSUPLL}$	1.337		1.312		1.508		1.902		ns
t_{INHPLL}	0.000		0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	1.164	2.493	1.164	2.708	1.164	2.747	1.164	2.672	ns
t_{XZPLL}	1.191	2.547	1.191	2.764	1.191	2.815	1.191	2.754	ns
t_{ZXPLL}	1.191	2.547	1.191	2.764	1.191	2.815	1.191	2.754	ns

Table 4–89. EP1S60 External I/O Timing on Row Pins Using Regional Clock Networks Note (1)

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.775		2.990		3.407		NA		ns
t_{INH}	0.000		0.000		0.000		NA		ns
t_{OUTCO}	2.867	5.644	2.867	6.057	2.867	6.600	NA	NA	ns
t_{XZ}	2.894	5.698	2.894	6.113	2.894	6.668	NA	NA	ns
t_{ZX}	2.894	5.698	2.894	6.113	2.894	6.668	NA	NA	ns
$t_{INSUPLL}$	1.523		1.577		1.791		NA		ns
t_{INHPLL}	0.000		0.000		0.000		NA		ns
$t_{OUTCOPLL}$	1.174	2.507	1.174	2.643	1.174	2.664	NA	NA	ns
t_{XZPLL}	1.201	2.561	1.201	2.699	1.201	2.732	NA	NA	ns
t_{ZXPLL}	1.201	2.561	1.201	2.699	1.201	2.732	NA	NA	ns

Table 4–90. EP1S60 External I/O Timing on Row Pins Using Global Clock Networks Note (1)

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.232		2.393		2.721		NA		ns
t_{INH}	0.000		0.000		0.000		NA		ns
t_{OUTCO}	3.182	6.187	3.182	6.654	3.182	7.286	NA	NA	ns
t_{XZ}	3.209	6.241	3.209	6.710	3.209	7.354	NA	NA	ns
t_{ZX}	3.209	6.241	3.209	6.710	3.209	7.354	NA	NA	ns
$t_{INSUPLL}$	1.651		1.612		1.833		NA		ns
t_{INHPLL}	0.000		0.000		0.000		NA		ns
$t_{OUTCOPLL}$	1.154	2.469	1.154	2.608	1.154	2.622	NA	NA	ns
t_{XZPLL}	1.181	2.523	1.181	2.664	1.181	2.690	NA	NA	ns
t_{ZXPLL}	1.181	2.523	1.181	2.664	1.181	2.690	NA	NA	ns

Note to Tables 4–85 to 4–90:

(1) Only EP1S25, EP1S30, and EP1S40 devices have the -8 speed grade.

Table 4–101. Reporting Methodology For Maximum Timing For Single-Ended Output Pins (Part 2 of 2) Notes (1), (2), (3)

I/O Standard	Loading and Termination							Measurement Point
	R_{UP} Ω	R_{DN} Ω	R_S Ω	R_T Ω	V_{CCIO} (V)	VTT (V)	C_L (pF)	V_{MEAS}
3.3-V SSTL-3 Class I	–	–	25	50	2.950	1.250	30	1.250
2.5-V SSTL-2 Class II	–	–	25	25	2.370	1.110	30	1.110
2.5-V SSTL-2 Class I	–	–	25	50	2.370	1.110	30	1.110
1.8-V SSTL-18 Class II	–	–	25	25	1.650	0.760	30	0.760
1.8-V SSTL-18 Class I	–	–	25	50	1.650	0.760	30	0.760
1.5-V HSTL Class II	–	–	0	25	1.400	0.700	20	0.680
1.5-V HSTL Class I	–	–	0	50	1.400	0.700	20	0.680
1.8-V HSTL Class II	–	–	0	25	1.650	0.700	20	0.880
1.8-V HSTL Class I	–	–	0	50	1.650	0.700	20	0.880
3.3-V PCI *(4)*	–/25	25/–	0	–	2.950	2.950	10	0.841/1.814
3.3-V PCI-X 1.0 *(4)*	–/25	25/–	0	–	2.950	2.950	10	0.841/1.814
3.3-V Compact PCI *(4)*	–/25	25/–	0	–	2.950	2.950	10	0.841/1.814
3.3-V AGP 1X *(4)*	–/25	25/–	0	–	2.950	2.950	10	0.841/1.814
3.3-V CTT	–	–	25	50	2.050	1.350	30	1.350

Notes to Table 4–101:

(1) Input measurement point at internal node is 0.5 × V_{CCINT}.

(2) Output measuring point for data is V_{MEAS}.

(3) Input stimulus edge rate is 0 to V_{CCINT} in 0.5 ns (internal signal) from the driver preceding the IO buffer.

(4) The first value is for output rising edge and the second value is for output falling edge. The hyphen (-) indicates infinite resistance or disconnection.

Table 4–125. High-Speed I/O Specifications for Flip-Chip Packages (Part 4 of 4) *Notes (1), (2)*

Symbol	Conditions	-5 Speed Grade			-6 Speed Grade			-7 Speed Grade			-8 Speed Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
t_{DUTY}	LVDS (*J* = 2 through 10)	47.5	50	52.5	47.5	50	52.5	47.5	50	52.5	47.5	50	52.5	%
	LVDS (*J* =1) and LVPECL, PCML, HyperTransport technology	45	50	55	45	50	55	45	50	55	45	50	55	%
t_{LOCK}	All			100			100			100			100	µs

Notes to Table 4–125:

(1) When J = 4, 7, 8, and 10, the SERDES block is used.

(2) When J = 2 or J = 1, the SERDES is bypassed.

PLL Specifications

Tables 4–127 through 4–129 describe the Stratix device enhanced PLL specifications.

Table 4–127. Enhanced PLL Specifications for -5 Speed Grades (Part 1 of 2)

Symbol	Parameter	Min	Typ	Max	Unit
f_{IN}	Input clock frequency	3 *(1)*, *(2)*		684	MHz
f_{INPFD}	Input frequency to PFD	3		420	MHz
f_{INDUTY}	Input clock duty cycle	40		60	%
$f_{EINDUTY}$	External feedback clock input duty cycle	40		60	%
$t_{INJITTER}$	Input clock period jitter			±200 *(3)*	ps
$t_{EINJITTER}$	External feedback clock period jitter			±200 *(3)*	ps
t_{FCOMP}	External feedback clock compensation time *(4)*			6	ns
f_{OUT}	Output frequency for internal global or regional clock	0.3		500	MHz
f_{OUT_EXT}	Output frequency for external clock *(3)*	0.3		526	MHz
$t_{OUTDUTY}$	Duty cycle for external clock output (when set to 50%)	45		55	%
t_{JITTER}	Period jitter for external clock output *(6)*			±100 ps for >200-MHz `outclk` ±20 mUI for <200-MHz `outclk`	ps or mUI
$t_{CONFIG5,6}$	Time required to reconfigure the scan chains for PLLs 5 and 6			$289/f_{SCANCLK}$	
$t_{CONFIG11,12}$	Time required to reconfigure the scan chains for PLLs 11 and 12			$193/f_{SCANCLK}$	
$t_{SCANCLK}$	`scanclk` frequency *(5)*			22	MHz
t_{DLOCK}	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays) *(7)*			100	μs
t_{LOCK}	Time required to lock from end of device configuration	10		400	μs
f_{VCO}	PLL internal VCO operating range	300		800 *(8)*	MHz
t_{LSKEW}	Clock skew between two external clock outputs driven by the same counter		±50		ps

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