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### Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

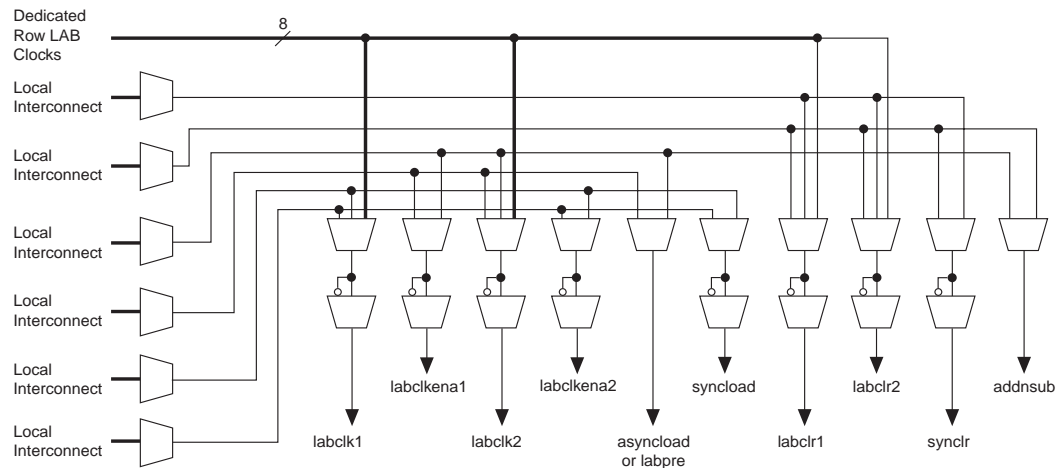
Product Status	Obsolete
Number of LABs/CLBs	1846
Number of Logic Elements/Cells	18460
Total RAM Bits	1669248
Number of I/O	586
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	780-BBGA, FCBGA
Supplier Device Package	780-FBGA (29x29)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep1s20f780c5n">https://www.e-xfl.com/product-detail/intel/ep1s20f780c5n</a>

Chapter	Date/Version	Changes Made
4	October 2003, v2.1	<ul style="list-style-type: none"> <li>• Added -8 speed grade information.</li> <li>• Updated performance information in <a href="#">Table 4–36</a>.</li> <li>• Updated timing information in <a href="#">Tables 4–55 through 4–96</a>.</li> <li>• Updated delay information in <a href="#">Tables 4–103 through 4–108</a>.</li> <li>• Updated programmable delay information in <a href="#">Tables 4–100 and 4–103</a>.</li> </ul>
	July 2003, v2.0	<ul style="list-style-type: none"> <li>• Updated clock rates in <a href="#">Tables 4–114 through 4–123</a>.</li> <li>• Updated speed grade information in the introduction on page 4-1.</li> <li>• Corrected figures 4-1 &amp; 4-2 and Table 4-9 to reflect how VID and VOD are specified.</li> <li>• Added note 6 to Table 4-32.</li> <li>• Updated Stratix Performance Table 4-35.</li> <li>• Updated EP1S60 and EP1S80 timing parameters in Tables 4-82 to 4-93. The Stratix timing models are final for all devices.</li> <li>• Updated Stratix IOE programmable delay chains in Tables 4-100 to 4-101.</li> <li>• Added single-ended I/O standard output pin delay adders for loading in Table 4-102.</li> <li>• Added spec for FPLL[10..7]CLK pins in Tables 4-104 and 4-107.</li> <li>• Updated high-speed I/O specification for J=2 in Tables 4-114 and 4-115.</li> <li>• Updated EPLL specification and fast PLL specification in Tables 4-116 to 4-120.</li> </ul>
5	September 2004, v2.1	<ul style="list-style-type: none"> <li>• Updated reference to device pin-outs on <a href="#">page 5–1</a> to indicate that device pin-outs are no longer included in this manual and are now available on the Altera web site.</li> </ul>
	April 2003, v1.0	<ul style="list-style-type: none"> <li>• No new changes in Stratix Device Handbook v2.0.</li> </ul>

With the LAB-wide addnsub control signal, a single LE can implement a one-bit adder and subtractor. This saves LE resources and improves performance for logic functions such as DSP correlators and signed multipliers that alternate between addition and subtraction depending on data.

The LAB row clocks [7..0] and LAB local interconnect generate the LAB-wide control signals. The MultiTrack™ interconnect's inherent low skew allows clock and control signal distribution in addition to data. [Figure 2–4](#) shows the LAB control signal generation circuit.

**Figure 2–4. LAB-Wide Control Signals**

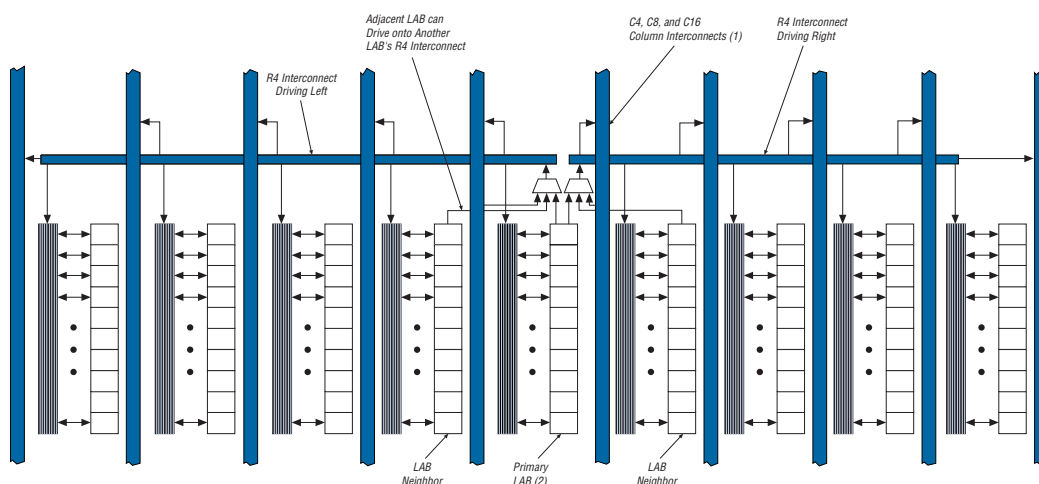


## Logic Elements

The smallest unit of logic in the Stratix architecture, the LE, is compact and provides advanced features with efficient logic utilization. Each LE contains a four-input LUT, which is a function generator that can implement any function of four variables. In addition, each LE contains a programmable register and carry chain with carry select capability. A single LE also supports dynamic single bit addition or subtraction mode selectable by an LAB-wide control signal. Each LE drives all types of interconnects: local, row, column, LUT chain, register chain, and direct link interconnects. See [Figure 2–5](#).

row connections in a four-LAB region. Every LAB has its own set of R4 interconnects to drive either left or right. Figure 2–9 shows R4 interconnect connections from an LAB. R4 interconnects can drive and be driven by DSP blocks and RAM blocks and horizontal IOEs. For LAB interfacing, a primary LAB or LAB neighbor can drive a given R4 interconnect. For R4 interconnects that drive to the right, the primary LAB and right neighbor can drive on to the interconnect. For R4 interconnects that drive to the left, the primary LAB and its left neighbor can drive on to the interconnect. R4 interconnects can drive other R4 interconnects to extend the range of LABs they can drive. R4 interconnects can also drive C4 and C16 interconnects for connections from one row to another. Additionally, R4 interconnects can drive R24 interconnects.

**Figure 2–9. R4 Interconnect Connections**



**Notes to Figure 2–9:**

- (1) C4 interconnects can drive R4 interconnects.
- (2) This pattern is repeated for every LAB in the LAB row.

The R8 interconnects span eight LABs, M512 or M4K RAM blocks, or DSP blocks to the right or left from a source LAB. These resources are used for fast row connections in an eight-LAB region. Every LAB has its own set of R8 interconnects to drive either left or right. R8 interconnect connections between LABs in a row are similar to the R4 connections shown in Figure 2–9, with the exception that they connect to eight LABs to the right or left, not four. Like R4 interconnects, R8 interconnects can drive and be driven by all types of architecture blocks. R8 interconnects

M4K RAM blocks support byte writes when the write port has a data width of 16, 18, 32, or 36 bits. The byte enables allow the input data to be masked so the device can write to specific bytes. The unwritten bytes retain the previous written value. Table 2-7 summarizes the byte selection.

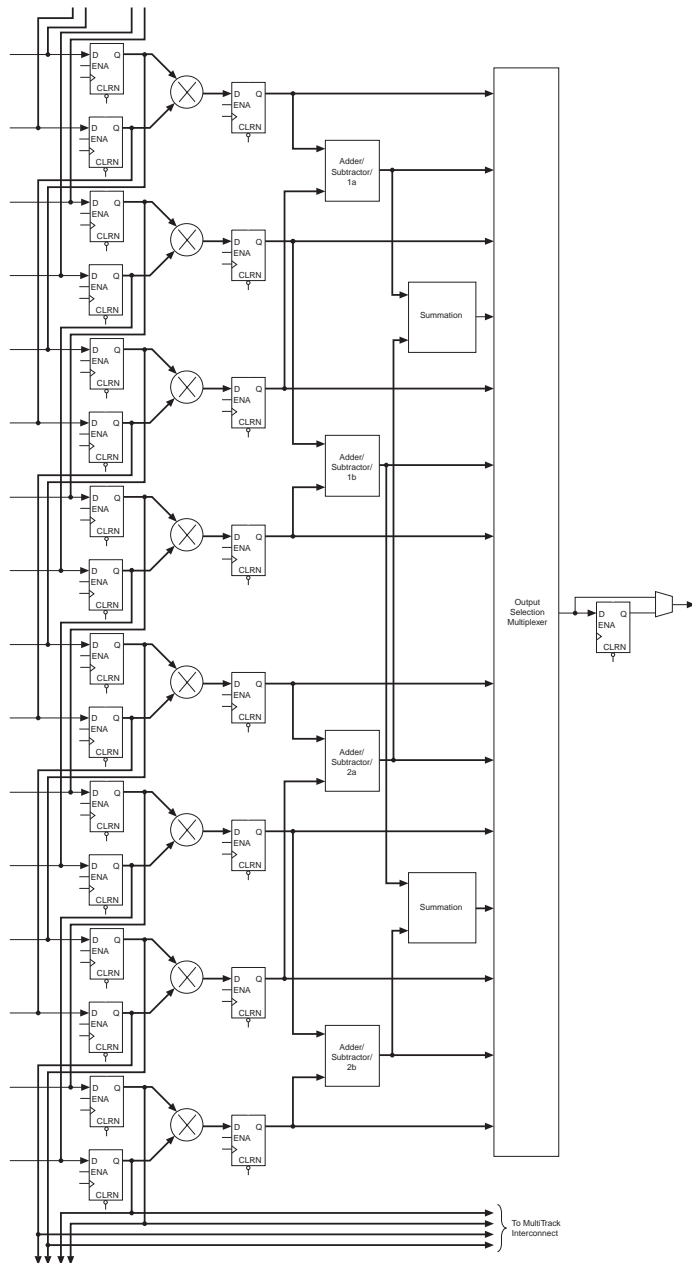
<b>Table 2-7. Byte Enable for M4K Blocks</b> <i>Notes (1), (2)</i>		
<b>byteena[3..0]</b>	<b>datain ×18</b>	<b>datain ×36</b>
[0] = 1	[8..0]	[8..0]
[1] = 1	[17..9]	[17..9]
[2] = 1	–	[26..18]
[3] = 1	–	[35..27]

**Notes to Table 2-7:**

- (1) Any combination of byte enables is possible.
- (2) Byte enables can be used in the same manner with 8-bit words, i.e., in ×16 and ×32 modes.

The M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (renwe, address, byte enable, datain, and output registers). Only the output register can be bypassed. The eight labclk signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. LEs can also control the clock\_a, clock\_b, renwe\_a, renwe\_b, clr\_a, clr\_b, clocken\_a, and clocken\_b signals, as shown in Figure 2-17.

The R4, R8, C4, C8, and direct link interconnects from adjacent LABs drive the M4K RAM block local interconnect. The M4K RAM blocks can communicate with LABs on either the left or right side through these row resources or with LAB columns on either the right or left with the column resources. Up to 10 direct link input connections to the M4K RAM Block are possible from the left adjacent LABs and another 10 possible from the right adjacent LAB. M4K RAM block outputs can also connect to left and right LABs through 10 direct link interconnects each. Figure 2-18 shows the M4K RAM block to logic array interface.

**Figure 2–31. DSP Block Diagram for  $9 \times 9$ -Bit Configuration**

### *Adder/Subtractor/Accumulator*

The adder/subtractor/accumulator is the first level of the adder/output block and can be used as an accumulator or as an adder/subtractor.

#### **Adder/Subtractor**

Each adder/subtractor/accumulator block can perform addition or subtraction using the `addnsub` independent control signal for each first-level adder in  $18 \times 18$ -bit mode. There are two `addnsub[1..0]` signals available in a DSP block for any configuration. For  $9 \times 9$ -bit mode, one `addnsub[1..0]` signal controls the top two one-level adders and another `addnsub[1..0]` signal controls the bottom two one-level adders. A high `addnsub` signal indicates addition, and a low signal indicates subtraction. The `addnsub` control signal can be unregistered or registered once or twice when feeding the adder blocks to match data path pipelines.

The `signa` and `signb` signals serve the same function as the multiplier block `signa` and `signb` signals. The only difference is that these signals can be registered up to two times. These signals are tied to the same `signa` and `signb` signals from the multiplier and must be connected to the same clocks and control signals.

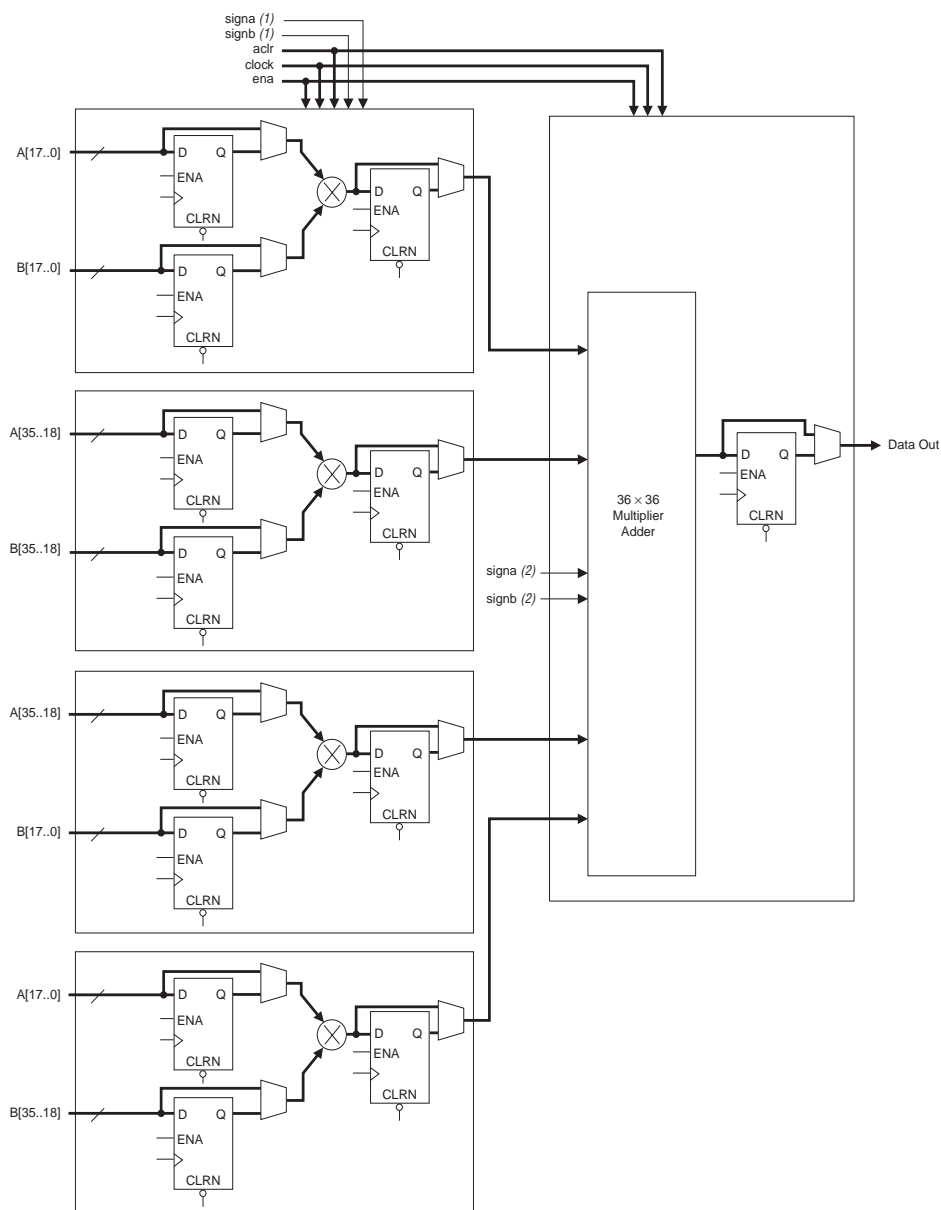
#### **Accumulator**

When configured for accumulation, the adder/output block output feeds back to the accumulator as shown in [Figure 2-34](#). The `accum_sload[1..0]` signal synchronously loads the multiplier result to the accumulator output. This signal can be unregistered or registered once or twice. Additionally, the `overflow` signal indicates the accumulator has overflowed or underflowed in accumulation mode. This signal is always registered and must be externally latched in LEs if the design requires a latched `overflow` signal.

### *Summation*

The output of the adder/subtractor/accumulator block feeds to an optional summation block. This block sums the outputs of the DSP block multipliers. In  $9 \times 9$ -bit mode, there are two summation blocks providing the sums of two sets of four  $9 \times 9$ -bit multipliers. In  $18 \times 18$ -bit mode, there is one summation providing the sum of one set of four  $18 \times 18$ -bit multipliers.

**Figure 2–36.  $36 \times 36$  Multiply Mode**



**Notes to Figure 2–36:**

- (1) These signals are not registered or registered once to match the pipeline.
- (2) These signals are not registered, registered once, or registered twice for latency to match the pipeline.



### *Clock Feedback*

The following four feedback modes in Stratix device enhanced PLLs allow multiplication and/or phase and delay shifting:

- **Zero delay buffer:** The external clock output pin is phase-aligned with the clock input pin for zero delay. Altera recommends using the same I/O standard on the input clock and the output clocks for optimum performance.
- **External feedback:** The external feedback input pin, FBIN, is phase-aligned with the clock input, CLK, pin. Aligning these clocks allows you to remove clock delay and skew between devices. This mode is only possible for PLLs 5 and 6. PLLs 5 and 6 each support feedback for one of the dedicated external outputs, either one single-ended or one differential pair. In this mode, one *e* counter feeds back to the PLL FBIN input, becoming part of the feedback loop. Altera recommends using the same I/O standard on the input clock, the FBIN pin, and the output clocks for optimum performance.
- **Normal mode:** If an internal clock is used in this mode, it is phase-aligned to the input clock pin. The external clock output pin will have a phase delay relative to the clock input pin if connected in this mode. You define which internal clock output from the PLL should be phase-aligned to the internal clock pin.
- **No compensation:** In this mode, the PLL will not compensate for any clock networks or external clock outputs.

### *Phase & Delay Shifting*

Stratix device enhanced PLLs provide advanced programmable phase and clock delay shifting. These parameters are set in the Quartus II software.

#### **Phase Delay**

The Quartus II software automatically sets the phase taps and counter settings according to the phase shift entry. You enter a desired phase shift and the Quartus II software automatically sets the closest setting achievable. This type of phase shift is not reconfigurable during system operation. For phase shifting, enter a phase shift (in degrees or time units) for each PLL clock output port or for all outputs together in one shift. You can select phase-shifting values in time units with a resolution of 156.25 to 416.66 ps. This resolution is a function of frequency input and the multiplication and division factors (that is, it is a function of the VCO period), with the finest step being equal to an eighth ( $\times 0.125$ ) of the VCO period. Each clock output counter can choose a different phase of the

### External Clock Inputs

Each fast PLL supports single-ended or differential inputs for source synchronous transmitters or for general-purpose use. Source-synchronous receivers support differential clock inputs. The fast PLL inputs are fed by CLK [0 . . 3], CLK [8 . . 11], and FPLL [7 . . 10] CLK pins, as shown in [Figure 2–50 on page 2–85](#).

[Table 2–22](#) shows the I/O standards supported by fast PLL input pins.

<b>Table 2–22. Fast PLL Port I/O Standards (Part 1 of 2)</b>		
<b>I/O Standard</b>	<b>Input</b>	
	<b>INCLK</b>	<b>PLEENABLE</b>
LVTTTL	✓	✓
LVC MOS	✓	✓
2.5 V	✓	
1.8 V	✓	
1.5 V	✓	
3.3-V PCI		
3.3-V PCI-X 1.0		
LVPECL	✓	
3.3-V PCML	✓	
LVDS	✓	
HyperTransport technology	✓	
Differential HSTL	✓	
Differential SSTL		
3.3-V GTL		
3.3-V GTL+	✓	
1.5-V HSTL Class I	✓	
1.5-V HSTL Class II		
1.8-V HSTL Class I	✓	
1.8-V HSTL Class II		
SSTL-18 Class I	✓	
SSTL-18 Class II		
SSTL-2 Class I	✓	

### IEEE Std. 1149.1 (JTAG) Boundary-Scan Support

All Stratix® devices provide JTAG BST circuitry that complies with the IEEE Std. 1149.1a-1990 specification. JTAG boundary-scan testing can be performed either before or after, but not during configuration. Stratix devices can also use the JTAG port for configuration together with either the Quartus® II software or hardware using either Jam Files (.jam) or Jam Byte-Code Files (.jbc).

Stratix devices support IOE I/O standard setting reconfiguration through the JTAG BST chain. The JTAG chain can update the I/O standard for all input and output pins any time before or during user mode through the CONFIG\_IO instruction. You can use this ability for JTAG testing before configuration when some of the Stratix pins drive or receive from other devices on the board using voltage-referenced standards. Since the Stratix device may not be configured before JTAG testing, the I/O pins may not be configured for appropriate electrical standards for chip-to-chip communication. Programming those I/O standards via JTAG allows you to fully test the I/O connection to other devices.

The enhanced PLL reconfiguration bits are part of the JTAG chain before configuration and after power-up. After device configuration, the PLL reconfiguration bits are not part of the JTAG chain.

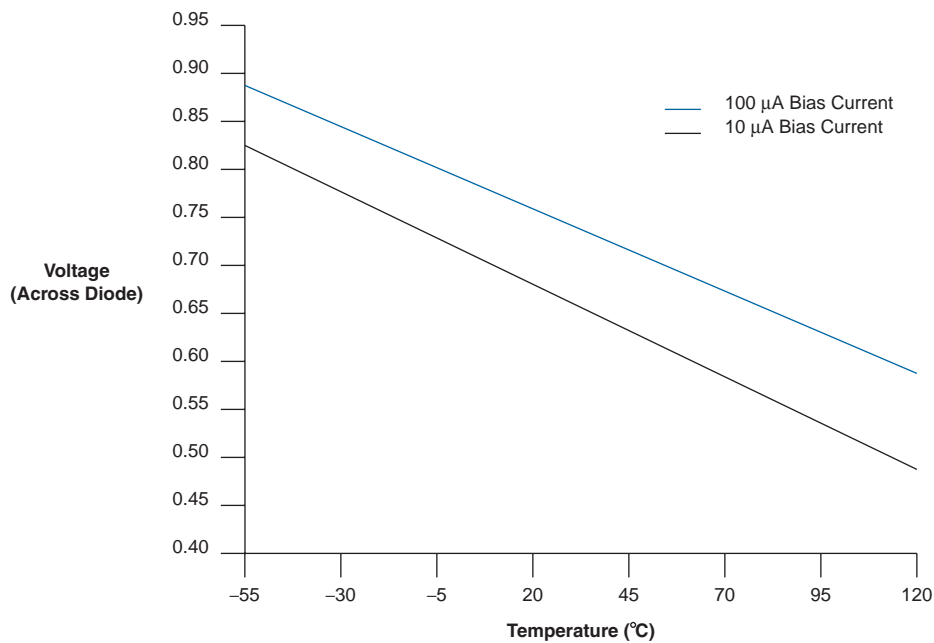
The JTAG pins support 1.5-V/1.8-V or 2.5-V/3.3-V I/O standards. The TDO pin voltage is determined by the V<sub>CCIO</sub> of the bank where it resides. The VCCSEL pin selects whether the JTAG inputs are 1.5-V, 1.8-V, 2.5-V, or 3.3-V compatible.

Stratix devices also use the JTAG port to monitor the logic operation of the device with the SignalTap® II embedded logic analyzer. Stratix devices support the JTAG instructions shown in [Table 3-1](#).

The Quartus II software has an Auto Usercode feature where you can choose to use the checksum value of a programming file as the JTAG user code. If selected, the checksum is automatically loaded to the USERCODE register. In the Settings dialog box in the Assignments menu, click **Device & Pin Options**, then **General**, and then turn on the **Auto Usercode** option.

The temperature-sensing diode works for the entire operating range shown in Figure 3–6.

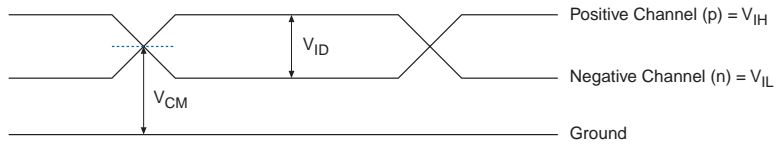
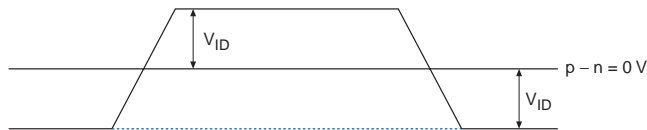
**Figure 3–6. Temperature vs. Temperature-Sensing Diode Voltage**



**Table 4–9. Overshoot Input Voltage with Respect to Duty Cycle (Part 2 of 2)**

V <sub>in</sub> (V)	Maximum Duty Cycle (%)
4.3	30
4.4	17
4.5	10

Figures 4–1 and 4–2 show receiver input and transmitter output waveforms, respectively, for all differential I/O standards (LVDS, 3.3-V PCML, LVPECL, and HyperTransport technology).

**Figure 4–1. Receiver Input Waveforms for Differential I/O Standards****Single-Ended Waveform****Differential Waveform**

**Table 4–41. M4K Block Internal Timing Microparameter Descriptions (Part 2 of 2)**

Symbol	Parameter
$t_{M4KDATAAH}$	A port data hold time after clock
$t_{M4KADDRASU}$	A port address setup time before clock
$t_{M4KADDRAH}$	A port address hold time after clock
$t_{M4KDATABSU}$	B port data setup time before clock
$t_{M4KDATABH}$	B port data hold time after clock
$t_{M4KADDRBSU}$	B port address setup time before clock
$t_{M4KADDRBH}$	B port address hold time after clock
$t_{M4KDATAO1}$	Clock-to-output delay when using output registers
$t_{M4KDATAO2}$	Clock-to-output delay without output registers
$t_{M4KCLKHL}$	Register minimum clock high or low time. This is a limit on the min time for the clock on the registers in these blocks. The actual performance is dependent upon the internal point-to-point delays in the blocks and may give slower performance as shown in <a href="#">Table 4–36 on page 4–20</a> and as reported by the timing analyzer in the Quartus II software.
$t_{M4KCLR}$	Minimum clear pulse width

**Table 4–42. M-RAM Block Internal Timing Microparameter Descriptions (Part 1 of 2)**

Symbol	Parameter
$t_{MRAMRC}$	Synchronous read cycle time
$t_{MRAMWC}$	Synchronous write cycle time
$t_{MRAMWERESU}$	Write or read enable setup time before clock
$t_{MRAMWEREH}$	Write or read enable hold time after clock
$t_{MRAMCLKENSU}$	Clock enable setup time before clock
$t_{MRAMCLKENH}$	Clock enable hold time after clock
$t_{MRAMBESU}$	Byte enable setup time before clock
$t_{MRAMBEH}$	Byte enable hold time after clock
$t_{MRAMDATAASU}$	A port data setup time before clock
$t_{MRAMDATAAH}$	A port data hold time after clock
$t_{MRAMADDRASU}$	A port address setup time before clock
$t_{MRAMADDRAH}$	A port address hold time after clock
$t_{MRAMDATABSU}$	B port setup time before clock

**Table 4–42. M-RAM Block Internal Timing Microparameter Descriptions (Part 2 of 2)**

Symbol	Parameter
$t_{\text{MRAMDATA BH}}$	B port hold time after clock
$t_{\text{MRAMADDR BSU}}$	B port address setup time before clock
$t_{\text{MRAMADDR BH}}$	B port address hold time after clock
$t_{\text{MRAMDATA CO1}}$	Clock-to-output delay when using output registers
$t_{\text{MRAMDATA CO2}}$	Clock-to-output delay without output registers
$t_{\text{MRAMCLK HL}}$	Register minimum clock high or low time. This is a limit on the min time for the clock on the registers in these blocks. The actual performance is dependent upon the internal point-to-point delays in the blocks and may give slower performance as shown in <a href="#">Table 4–36 on page 4–20</a> and as reported by the timing analyzer in the Quartus II software.
$t_{\text{MRAMCLR}}$	Minimum clear pulse width.

**Table 4–45. IOE Internal TSU Microparameter by Device Density (Part 2 of 2)**

Device	Symbol	-5		-6		-7		-8		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
EP1S40	t <sub>SU_R</sub>	76		80		80		80		ps
	t <sub>SU_C</sub>	376		380		380		380		ps
EP1S60	t <sub>SU_R</sub>	276		280		280		280		ps
	t <sub>SU_C</sub>	276		280		280		280		ps
EP1S80	t <sub>SU_R</sub>	426		430		430		430		ps
	t <sub>SU_C</sub>	76		80		80		80		ps

**Table 4–46. IOE Internal Timing Microparameters**

Symbol	-5		-6		-7		-8		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>H</sub>	68		71		82		96		ps
t <sub>CO_R</sub>		171		179		206		242	ps
t <sub>CO_C</sub>		171		179		206		242	ps
t <sub>PIN2COMBOUT_R</sub>		1,234		1,295		1,490		1,753	ps
t <sub>PIN2COMBOUT_C</sub>		1,087		1,141		1,312		1,544	ps
t <sub>COMBIN2PIN_R</sub>		3,894		4,089		4,089		4,089	ps
t <sub>COMBIN2PIN_C</sub>		4,299		4,494		4,494		4,494	ps
t <sub>CLR</sub>	276		289		333		392		ps
t <sub>PRE</sub>	260		273		313		369		ps
t <sub>CLKHL</sub>	1,000		1,111		1,190		1,400		ps

**Table 4–47. DSP Block Internal Timing Microparameters (Part 1 of 2)**

Symbol	-5		-6		-7		-8		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>SU</sub>	0		0		0		0		ps
t <sub>H</sub>	67		75		86		101		ps
t <sub>CO</sub>		142		158		181		214	ps
t <sub>INREG2PIPE9</sub>		2,613		2,982		3,429		4,035	ps
t <sub>INREG2PIPE18</sub>		3,390		3,993		4,591		5,402	ps



**Table 4–77. EP1S30 External I/O Timing on Row Pins Using Regional Clock Networks**

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{\text{INSU}}$	2.322		2.467		2.828		3.342		ns
$t_{\text{INH}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCO}}$	2.731	5.408	2.731	5.843	2.731	6.360	2.731	7.036	ns
$t_{\text{XZ}}$	2.758	5.462	2.758	5.899	2.758	6.428	2.758	7.118	ns
$t_{\text{ZX}}$	2.758	5.462	2.758	5.899	2.758	6.428	2.758	7.118	ns
$t_{\text{INSUPLL}}$	1.291		1.283		1.469		1.832		ns
$t_{\text{INHPLL}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCOPLL}}$	1.192	2.539	1.192	2.737	1.192	2.786	1.192	2.742	ns
$t_{\text{XZPLL}}$	1.219	2.539	1.219	2.793	1.219	2.854	1.219	2.824	ns
$t_{\text{ZXPLL}}$	1.219	2.539	1.219	2.793	1.219	2.854	1.219	2.824	ns

**Table 4–78. EP1S30 External I/O Timing on Row Pins Using Global Clock Networks**

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{\text{INSU}}$	1.995		2.089		2.398		2.830		ns
$t_{\text{INH}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCO}}$	2.917	5.735	2.917	6.221	2.917	6.790	2.917	7.548	ns
$t_{\text{XZ}}$	2.944	5.789	2.944	6.277	2.944	6.858	2.944	7.630	ns
$t_{\text{ZX}}$	2.944	5.789	2.944	6.277	2.944	6.858	2.944	7.630	ns
$t_{\text{INSUPLL}}$	1.337		1.312		1.508		1.902		ns
$t_{\text{INHPLL}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCOPLL}}$	1.164	2.493	1.164	2.708	1.164	2.747	1.164	2.672	ns
$t_{\text{XZPLL}}$	1.191	2.547	1.191	2.764	1.191	2.815	1.191	2.754	ns
$t_{\text{ZXPLL}}$	1.191	2.547	1.191	2.764	1.191	2.815	1.191	2.754	ns

Tables 4–79 through 4–84 show the external timing parameters on column and row pins for EP1S40 devices.

**Table 4–79. EP1S40 External I/O Timing on Column Pins Using Fast Regional Clock Networks**

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{\text{INSU}}$	2.696		2.907		3.290		2.899		ns
$t_{\text{INH}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCO}}$	2.506	5.015	2.506	5.348	2.506	5.809	2.698	7.286	ns
$t_{\text{xZ}}$	2.446	4.889	2.446	5.216	2.446	5.685	2.638	7.171	ns
$t_{\text{ZX}}$	2.446	4.889	2.446	5.216	2.446	5.685	2.638	7.171	ns

**Table 4–80. EP1S40 External I/O Timing on Column Pins Using Regional Clock Networks**

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{\text{INSU}}$	2.413		2.581		2.914		2.938		ns
$t_{\text{INH}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCO}}$	2.668	5.254	2.668	5.628	2.668	6.132	2.869	7.307	ns
$t_{\text{xZ}}$	2.608	5.128	2.608	5.496	2.608	6.008	2.809	7.192	ns
$t_{\text{ZX}}$	2.608	5.128	2.608	5.496	2.608	6.008	2.809	7.192	ns
$t_{\text{INSUPLL}}$	1.385		1.376		1.609		1.837		ns
$t_{\text{INHPLL}}$	0.000		0.000		0.000		0.000		ns
$t_{\text{OUTCOPLL}}$	1.117	2.382	1.117	2.552	1.117	2.504	1.117	2.542	ns
$t_{\text{xZPLL}}$	1.057	2.256	1,057	2.420	1.057	2.380	1.057	2.427	ns
$t_{\text{ZXPLL}}$	1.057	2.256	1,057	2.420	1.057	2.380	1.057	2.427	ns

**Table 4–105. Stratix I/O Standard Output Delay Adders for Fast Slew Rate on Column Pins (Part 2 of 2)**

Parameter	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
CTT		973		1,021		1,021		1,021	ps
SSTL-3 Class I		719		755		755		755	ps
SSTL-3 Class II		146		153		153		153	ps
SSTL-2 Class I		678		712		712		712	ps
SSTL-2 Class II		223		234		234		234	ps
SSTL-18 Class I		1,032		1,083		1,083		1,083	ps
SSTL-18 Class II		447		469		469		469	ps
1.5-V HSTL Class I		660		693		693		693	ps
1.5-V HSTL Class II		537		564		564		564	ps
1.8-V HSTL Class I		304		319		319		319	ps
1.8-V HSTL Class II		231		242		242		242	ps

**Table 4–106. Stratix I/O Standard Output Delay Adders for Fast Slew Rate on Row Pins (Part 1 of 2)**

Parameter		-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
LVCMOS	2 mA		1,518		1,594		1,594		1,594	ps
	4 mA		746		783		783		783	ps
	8 mA		96		100		100		100	ps
	12 mA		0		0		0		0	ps
3.3-V LVTTTL	4 mA		1,518		1,594		1,594		1,594	ps
	8 mA		1,038		1,090		1,090		1,090	ps
	12 mA		521		547		547		547	ps
	16 mA		414		434		434		434	ps
	24 mA		0		0		0		0	ps
2.5-V LVTTTL	2 mA		2,032		2,133		2,133		2,133	ps
	8 mA		699		734		734		734	ps
	12 mA		374		392		392		392	ps
	16 mA		165		173		173		173	ps
1.8-V LVTTTL	2 mA		3,714		3,899		3,899		3,899	ps
	8 mA		1,055		1,107		1,107		1,107	ps
	12 mA		830		871		871		871	ps

**Table 4–123. Stratix Maximum Output Clock Rate (Using I/O Pins) for PLL[1, 2, 3, 4] Pins in Wire-Bond Packages (Part 2 of 2)**

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVDS (2)	400	311	311	MHz
HyperTransport technology (2)	420	400	400	MHz

**Notes to Tables 4–120 through 4–123:**

- (1) Differential SSTL-2 outputs are only available on column clock pins.
- (2) These parameters are only available on row I/O pins.
- (3) SSTL-2 in maximum drive strength condition. See Table 4–101 on page 4–62 for more information on exact loading conditions for each I/O standard.
- (4) SSTL-2 in minimum drive strength with  $\leq 10$ pF output load condition.
- (5) SSTL-2 in minimum drive strength with  $> 10$ pF output load condition.
- (6) Differential SSTL-2 outputs are only supported on column clock pins.

**Table 4–129. Enhanced PLL Specifications for -7 Speed Grade (Part 2 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{OUTDUTY}}$	Duty cycle for external clock output (when set to 50%)	45		55	%
$t_{\text{JITTER}}$	Period jitter for external clock output (6)			$\pm 100$ ps for >200-MHz $\text{outclk}$ $\pm 20$ mUI for <200-MHz $\text{outclk}$	ps or mUI
$t_{\text{CONFIG5,6}}$	Time required to reconfigure the scan chains for PLLs 5 and 6			$289/f_{\text{SCANCLK}}$	
$t_{\text{CONFIG11,12}}$	Time required to reconfigure the scan chains for PLLs 11 and 12			$193/f_{\text{SCANCLK}}$	
$t_{\text{SCANCLK}}$	$\text{scanclk}$ frequency (5)			22	MHz
$t_{\text{DLOCK}}$	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays) (7) (11)	(9)		100	$\mu\text{s}$
$t_{\text{LOCK}}$	Time required to lock from end of device configuration (11)	10		400	$\mu\text{s}$
$f_{\text{VCO}}$	PLL internal VCO operating range	300		600 (8)	MHz
$t_{\text{LSKEW}}$	Clock skew between two external clock outputs driven by the same counter		$\pm 50$		ps
$t_{\text{SKEW}}$	Clock skew between two external clock outputs driven by the different counters with the same settings		$\pm 75$		ps
$f_{\text{SS}}$	Spread spectrum modulation frequency	30		150	kHz
% spread	Percentage spread for spread spectrum frequency (10)	0.5		0.6	%
$t_{\text{ARESET}}$	Minimum pulse width on $\text{areset}$ signal	10			ns

**Table 4–130. Enhanced PLL Specifications for -8 Speed Grade (Part 1 of 3)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{\text{IN}}$	Input clock frequency	3 (1), (2)		480	MHz
$f_{\text{INPFD}}$	Input frequency to PFD	3		420	MHz
$f_{\text{INDUTY}}$	Input clock duty cycle	40		60	%
$f_{\text{EINDUTY}}$	External feedback clock input duty cycle	40		60	%
$t_{\text{INJITTER}}$	Input clock period jitter			$\pm 200$ (3)	ps