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Understanding <u>Embedded - FPGAs (Field Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	4125
Number of Logic Elements/Cells	41250
Total RAM Bits	3423744
Number of I/O	822
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1508-BBGA, FCBGA
Supplier Device Package	1508-FBGA, FC (40x40)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1s40f1508c6n

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

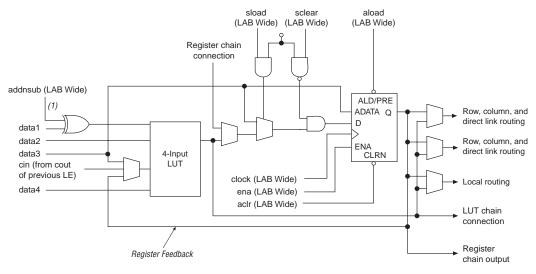
asynchronous preset load, synchronous clear, synchronous load, and clock enable control for the register. These LAB-wide signals are available in all LE modes. The addnsub control signal is allowed in arithmetic mode.

The Quartus II software, in conjunction with parameterized functions such as library of parameterized modules (LPM) functions, automatically chooses the appropriate mode for common functions such as counters, adders, subtractors, and arithmetic functions. If required, you can also create special-purpose functions that specify which LE operating mode to use for optimal performance.

Normal Mode

The normal mode is suitable for general logic applications and combinatorial functions. In normal mode, four data inputs from the LAB local interconnect are inputs to a four-input LUT (see Figure 2–6). The Quartus II Compiler automatically selects the carry-in or the data3 signal as one of the inputs to the LUT. Each LE can use LUT chain connections to drive its combinatorial output directly to the next LE in the LAB. Asynchronous load data for the register comes from the data3 input of the LE. LEs in normal mode support packed registers.

Figure 2-6. LE in Normal Mode



Note to Figure 2-6:

(1) This signal is only allowed in normal mode if the LE is at the end of an adder/subtractor chain.

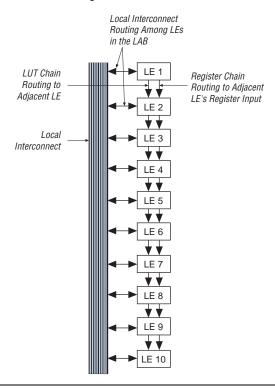


Figure 2-10. LUT Chain & Register Chain Interconnects

The C4 interconnects span four LABs, M512, or M4K blocks up or down from a source LAB. Every LAB has its own set of C4 interconnects to drive either up or down. Figure 2–11 shows the C4 interconnect connections from an LAB in a column. The C4 interconnects can drive and be driven by all types of architecture blocks, including DSP blocks, TriMatrix memory blocks, and vertical IOEs. For LAB interconnection, a primary LAB or its LAB neighbor can drive a given C4 interconnect. C4 interconnects can drive each other to extend their range as well as drive row interconnects for column-to-column connections.

Table 2–3. TriMatrix Memory Features (Part 2 of 2)								
Memory Feature	M512 RAM Block (32 × 18 Bits)	M4K RAM Block (128 × 36 Bits)	M-RAM Block (4K × 144 Bits)					
Configurations	512 × 1 256 × 2 128 × 4 64 × 8 64 × 9 32 × 16 32 × 18	4K × 1 2K × 2 1K × 4 512 × 8 512 × 9 256 × 16 256 × 18 128 × 32 128 × 36	64K × 8 64K × 9 32K × 16 32K × 18 16K × 32 16K × 36 8K × 64 8K × 72 4K × 128 4K × 144					

Notes to Table 2–3:

- (1) See Table 4–36 for maximum performance information.
- (2) The M-RAM block does not support memory initializations. However, the M-RAM block can emulate a ROM function using a dual-port RAM bock. The Stratix device must write to the dual-port memory once and then disable the write-enable ports afterwards.

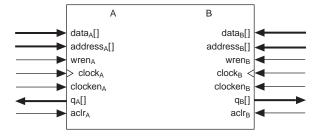


Violating the setup or hold time on the address registers could corrupt the memory contents. This applies to both read and write operations.

Memory Modes

TriMatrix memory blocks include input registers that synchronize writes and output registers to pipeline designs and improve system performance. M4K and M-RAM memory blocks offer a true dual-port mode to support any combination of two-port operations: two reads, two writes, or one read and one write at two different clock frequencies. Figure 2–12 shows true dual-port memory.

Figure 2-12. True Dual-Port Memory Configuration



The memory address depths and output widths can be configured as $4,096 \times 1, 2,048 \times 2, 1,024 \times 4,512 \times 8$ (or 512×9 bits), 256×16 (or 256×18 bits), and 128×32 (or 128×36 bits). The 128×32 - or 36-bit configuration is not available in the true dual-port mode. Mixed-width configurations are also possible, allowing different read and write widths. Tables 2–5 and 2–6 summarize the possible M4K RAM block configurations.

Table 2-5. M4	Table 2–5. M4K RAM Block Configurations (Simple Dual-Port)								
Dood Dood		Write Port							
Read Port	4K × 1	2K × 2	1K × 4	512 × 8	256 × 16	128 × 32	512 × 9	256 × 18	128 × 36
4K × 1	✓	✓	✓	✓	✓	✓			
2K × 2	✓	✓	✓	~	✓	✓			
1K × 4	✓	✓	✓	~	✓	✓			
512 × 8	✓	✓	✓	~	✓	✓			
256 × 16	✓	✓	✓	~	✓	✓			
128 × 32	✓	✓	✓	✓	✓	✓			
512 × 9							✓	✓	✓
256 × 18							✓	✓	✓
128 × 36							✓	>	✓

Table 2–6. M4K RAM	able 2–6. M4K RAM Block Configurations (True Dual-Port)										
Don't A		Port B									
Port A	4K × 1	2K × 2	1K × 4	512 × 8	256 × 16	512 × 9	256 × 18				
4K × 1	✓	✓	✓	✓	✓						
2K × 2	✓	✓	✓	✓	✓						
1K × 4	✓	✓	✓	✓	✓						
512 × 8	✓	✓	✓	✓	✓						
256 × 16	✓	✓	✓	✓	✓						
512 × 9						✓	✓				
256 × 18						✓	✓				

When the M4K RAM block is configured as a shift register block, you can create a shift register up to 4,608 bits ($w \times m \times n$).

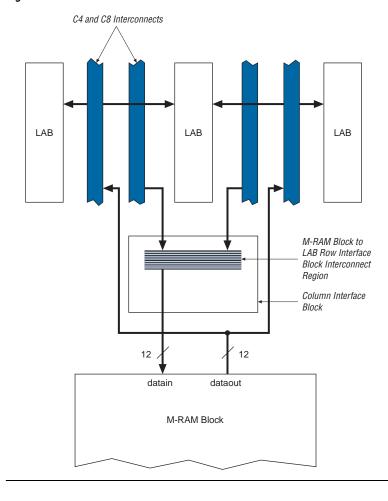


Figure 2–23. M-RAM Column Unit Interface to Interconnect

single DSP block can implement two sums or differences from two 18×18 -bit multipliers each or four sums or differences from two 9×9 -bit multipliers each.

You can use the two-multipliers adder mode for complex multiplications, which are written as:

$$(a+jb)\times(c+jd) = [(a\times c) - (b\times d)] + j\times[(a\times d) + (b\times c)]$$

The two-multipliers adder mode allows a single DSP block to calculate the real part $[(a \times c) - (b \times d)]$ using one subtractor and the imaginary part $[(a \times d) + (b \times c)]$ using one adder, for data widths up to 18 bits. Two complex multiplications are possible for data widths up to 9 bits using four adder/subtractor/accumulator blocks. Figure 2–38 shows an 18-bit two-multipliers adder.

Figure 2–38. Two-Multipliers Adder Mode Implementing Complex Multiply

Four-Multipliers Adder Mode

In the four-multipliers adder mode, the DSP block adds the results of two first -stage adder/subtractor blocks. One sum of four 18×18 -bit multipliers or two different sums of two sets of four 9×9 -bit multipliers can be implemented in a single DSP block. The product width for each multiplier must be the same size. The four-multipliers adder mode is useful for FIR filter applications. Figure 2–39 shows the four multipliers adder mode.

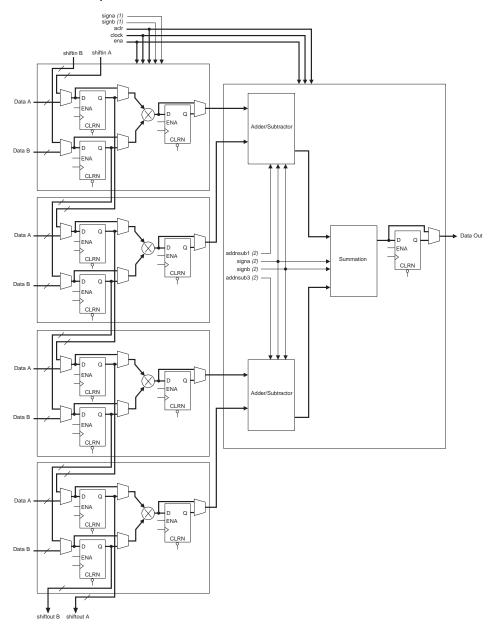


Figure 2-39. Four-Multipliers Adder Mode

Notes to Figure 2-39:

- (1) These signals are not registered or registered once to match the data path pipeline.
- (2) These signals are not registered, registered once, or registered twice for latency to match the data path pipeline.

Any of the four external output counters can drive the single-ended or differential clock outputs for PLLs 5 and 6. This means one counter or frequency can drive all output pins available from PLL 5 or PLL 6. Each pair of output pins (four pins total) has dedicated VCC and GND pins to reduce the output clock's overall jitter by providing improved isolation from switching I/O pins.

For PLLs 5 and 6, each pin of a single-ended output pair can either be in phase or 180° out of phase. The clock output pin pairs support the same I/O standards as standard output pins (in the top and bottom banks) as well as LVDS, LVPECL, 3.3-V PCML, HyperTransport technology, differential HSTL, and differential SSTL. Table 2–20 shows which I/O standards the enhanced PLL clock pins support. When in single-ended or differential mode, the two outputs operate off the same power supply. Both outputs use the same standards in single-ended mode to maintain performance. You can also use the external clock output pins as user output pins if external enhanced PLL clocking is not needed.

Table 2–20. I/O Standards Supported for Enhanced PLL Pins (Part 1 of 2)								
L/O Ctondovd		Input						
I/O Standard	INCLK	FBIN	PLLENABLE	EXTCLK				
LVTTL	✓	✓	✓	✓				
LVCMOS	✓	✓	✓	✓				
2.5 V	✓	✓		✓				
1.8 V	✓	✓		✓				
1.5 V	✓	✓		✓				
3.3-V PCI	✓	✓		✓				
3.3-V PCI-X 1.0	✓	✓		✓				
LVPECL	✓	✓		✓				
3.3-V PCML	✓	✓		✓				
LVDS	✓	✓		✓				
HyperTransport technology	✓	✓		✓				
Differential HSTL	✓			✓				
Differential SSTL				✓				
3.3-V GTL	✓	✓		✓				
3.3-V GTL+	✓	✓		✓				
1.5-V HSTL Class I	✓	✓		✓				

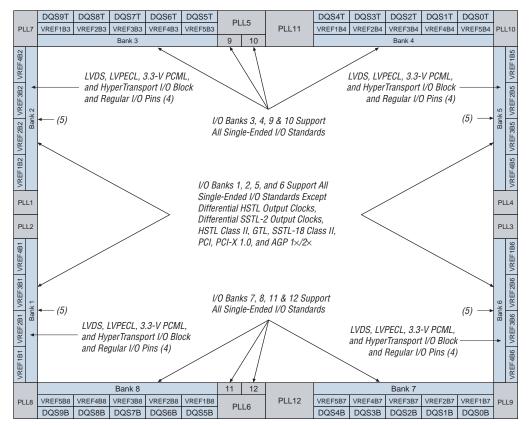


Figure 2–70. Stratix I/O Banks Notes (1), (2), (3)

Notes to Figure 2–70:

- (1) Figure 2–70 is a top view of the silicon die. This will correspond to a top-down view for non-flip-chip packages, but will be a reverse view for flip-chip packages.
- (2) Figure 2–70 is a graphic representation only. See the device pin-outs on the web (www.altera.com) and the Quartus II software for exact locations.
- (3) Banks 9 through 12 are enhanced PLL external clock output banks.
- (4) If the high-speed differential I/O pins are not used for high-speed differential signaling, they can support all of the I/O standards except HSTL Class I and II, GTL, SSTL-18 Class II, PCI, PCI-X 1.0, and AGP 1×/2×.
- (5) For guidelines for placing single-ended I/O pads next to differential I/O pads, see the Selectable I/O Standards in Stratix and Stratix GX Devices chapter in the Stratix Device Handbook, Volume 2.

Table 2–32 shows I/O standard support for each I/O bank.

I/O Standard	Top & Bottom Banks (3, 4, 7 & 8)	Left & Right Banks (1, 2, 5 & 6)	Enhanced PLL External Clock Output Banks (9, 10, 11 & 12)
LVTTL	✓	✓	✓
LVCMOS	✓	✓	✓
2.5 V	✓	✓	✓
1.8 V	✓	✓	✓
1.5 V	✓	✓	✓
3.3-V PCI	✓		✓
3.3-V PCI-X 1.0	✓		✓
LVPECL		✓	✓
3.3-V PCML		✓	✓
LVDS		✓	✓
HyperTransport technology		✓	✓
Differential HSTL (clock inputs)	✓	✓	
Differential HSTL (clock outputs)			✓
Differential SSTL (clock outputs)			✓
3.3-V GTL	✓		✓
3.3-V GTL+	✓	✓	✓
1.5-V HSTL Class I	✓	✓	✓
1.5-V HSTL Class II	✓		✓
1.8-V HSTL Class I	✓	✓	✓
1.8-V HSTL Class II	✓		✓
SSTL-18 Class I	✓	✓	✓
SSTL-18 Class II	✓		✓
SSTL-2 Class I	✓	✓	✓
SSTL-2 Class II	✓	✓	✓
SSTL-3 Class I	✓	✓	✓

Figure 4–2. Transmitter Output Waveforms for Differential I/O Standards

Single-Ended Waveform Positive Channel (p) = V_{OH} V_{CM} Negative Channel (n) = V_{OL} Ground

Differential Waveform $V_{OD} = 0 \text{ V}$ $V_{OD} = 0 \text{ V}$

Tables 4–10 through 4–33 recommend operating conditions, DC operating conditions, and capacitance for 1.5-V Stratix devices.

Table 4–10. 3.3-V LVDS I/O Specifications (Part 1 of 2)									
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit			
V _{CCIO}	I/O supply voltage		3.135	3.3	3.465	V			
V _{ID} (6)	Input differential voltage swing (single-ended)	$0.1 \text{ V} \leq \text{V}_{\text{CM}} < 1.1 \text{ V}$ W = 1 through 10	300		1,000	mV			
		1.1 V \leq V _{CM} \leq 1.6 V $W = 1$	200		1,000	mV			
		1.1 V \leq V _{CM} \leq 1.6 V W = 2 through 10	100		1,000	mV			
		1.6 V < $V_{CM} \le 1.8 \text{ V}$ W = 1 through 10	300		1,000	mV			

Table 4–33. Stratix Device Capacitance Note (5)									
Symbol	Parameter	Minimum	Typical	Maximum	Unit				
C _{IOTB}	Input capacitance on I/O pins in I/O banks 3, 4, 7, and 8.		11.5		pF				
C _{IOLR}	Input capacitance on I/O pins in I/O banks 1, 2, 5, and 6, including high-speed differential receiver and transmitter pins.		8.2		pF				
C _{CLKTB}	Input capacitance on top/bottom clock input pins: CLK [4:7] and CLK [12:15].		11.5		pF				
C _{CLKLR}	Input capacitance on left/right clock inputs: CLK1, CLK3, CLK8, CLK10.		7.8		pF				
C _{CLKLR+}	Input capacitance on left/right clock inputs: CLK0, CLK2, CLK9, and CLK11.		4.4		pF				

Notes to Tables 4–10 through 4–33:

- (1) When $tx_outclock$ port of altlvds_tx megafunction is 717 MHz, $V_{OD(min)} = 235$ mV on the output clock pin.
- (2) Pin pull-up resistance values will lower if an external source drives the pin higher than V_{CCIO}.
- (3) Drive strength is programmable according to the values shown in the *Stratix Architecture* chapter of the *Stratix Device Handbook, Volume 1*.
- (4) V_{REF} specifies the center point of the switching range.
- (5) Capacitance is sample-tested only. Capacitance is measured using time-domain reflections (TDR). Measurement accuracy is within ±0.5 pF.
- (6) V_{IO} and V_{CM} have multiple ranges and values for J=1 through 10.

Power Consumption

Altera® offers two ways to calculate power for a design: the Altera web power calculator and the PowerGaugeTM feature in the Quartus® II software.

The interactive power calculator on the Altera web site is typically used prior to designing the FPGA in order to get a magnitude estimate of the device power. The Quartus II software PowerGauge feature allows you to apply test vectors against your design for more accurate power consumption modeling.

In both cases, these calculations should only be used as an estimation of power, not as a specification.

Stratix devices require a certain amount of power-up current to successfully power up because of the small process geometry on which they are fabricated.

Table 4–34 shows the maximum power-up current (I_{CCINT}) required to power a Stratix device. This specification is for commercial operating conditions. Measurements were performed with an isolated Stratix device on the board to characterize the power-up current of an isolated

Timing Model

The DirectDriveTM technology and MultiTrackTM interconnect ensure predictable performance, accurate simulation, and accurate timing analysis across all Stratix device densities and speed grades. This section describes and specifies the performance, internal, external, and PLL timing specifications.

All specifications are representative of worst-case supply voltage and junction temperature conditions.

Preliminary & Final Timing

Timing models can have either preliminary or final status. The Quartus II software issues an informational message during the design compilation if the timing models are preliminary. Table 4–35 shows the status of the Stratix device timing models.

Preliminary status means the timing model is subject to change. Initially, timing numbers are created using simulation results, process data, and other known parameters. These tests are used to make the preliminary numbers as close to the actual timing parameters as possible.

Final timing numbers are based on actual device operation and testing. These numbers reflect the actual performance of the device under worst-case voltage and junction temperature conditions.

Table 4–35. Stratix Device Timing Model Status							
Device	Preliminary	Final					
EP1S10		✓					
EP1S20		✓					
EP1S25		✓					
EP1S30		✓					
EP1S40		✓					
EP1S60		✓					
EP1S80		✓					

Table 4–50. M-RAM Block Internal Timing Microparameters (Part 2 of 2)									
Cumbal	-	-5		-6		7	-8		
Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Unit
t _{MRAMBESU}	25		25		28		33		ps
t _{MRAMBEH}	18		20		23		27		ps
t _{MRAMDATAASU}	25		25		28		33		ps
t _{MRAMDATAAH}	18		20		23		27		ps
t _{MRAMADDRASU}	25		25		28		33		ps
t _{MRAMADDRAH}	18		20		23		27		ps
t _{MRAMDATABSU}	25		25		28		33		ps
t _{MRAMDATABH}	18		20		23		27		ps
t _{MRAMADDRBSU}	25		25		28		33		ps
t _{MRAMADDRBH}	18		20		23		27		ps
t _{MRAMDATACO1}		1,038		1,053		1,210		1,424	ps
t _{MRAMDATACO2}		4,362		4,939		5,678		6,681	ps
t _{MRAMCLKHL}	1,000		1,111		1,190		1,400		ps
t _{MRAMCLR}	135		150		172		202		ps

Table 4-51.	Table 4–51. Routing Delay Internal Timing Parameters										
O	-5		-5			-6		-7		-8	Unit
Symbol	Min	Max	Min	Max	Min	Max	Min	Max			
t _{R4}		268		295		339		390	ps		
t _{R8}		371		349		401		461	ps		
t _{R24}		465		512		588		676	ps		
t _{C4}		440		484		557		641	ps		
t _{C8}		577		634		730		840	ps		
t _{C16}		445		489		563		647	ps		
t _{LOCAL}		313		345		396		455	ps		

Routing delays vary depending on the load on that specific routing line. The Quartus II software reports the routing delay information when running the timing analysis for a design.

Table 4–53. Stratix Regional Clock External I/O Ti	iming Parameters (Part 2
of 2) Notes (1), (2)	

Symbol	Parameter
t _{XZPLL}	Synchronous IOE output enable register to output pin disable delay using regional clock fed by Enhanced PLL with default phase setting
t _{ZXPLL}	Synchronous IOE output enable register to output pin enable delay using regional clock fed by Enhanced PLL with default phase setting

Notes to Table 4–53:

- (1) These timing parameters are sample-tested only.
- (2) These timing parameters are for column and row IOE pins. You should use the Quartus II software to verify the external timing for any pin.

Table 4–54 shows the external I/O timing parameters when using global clock networks.

Table 4–3 (2)	54. Stratix Global Clock External I/O Timing Parameters Notes (1),
Symbol	Parameter
t _{INSU}	Setup time for input or bidirectional pin using IOE input register with global clock fed by ${\tt CLK}$ pin
t _{INH}	Hold time for input or bidirectional pin using IOE input register with global clock fed by ${\tt CLK}$ pin
t _{OUTCO}	Clock-to-output delay output or bidirectional pin using IOE output register with global clock fed by CLK pin
t _{INSUPLL}	Setup time for input or bidirectional pin using IOE input register with global clock fed by Enhanced PLL with default phase setting
t _{INHPLL}	Hold time for input or bidirectional pin using IOE input register with global clock fed by Enhanced PLL with default phase setting
t _{OUTCOPLL}	Clock-to-output delay output or bidirectional pin using IOE output register with global clock Enhanced PLL with default phase setting
t _{XZPLL}	Synchronous IOE output enable register to output pin disable delay using global clock fed by Enhanced PLL with default phase setting
t _{ZXPLL}	Synchronous IOE output enable register to output pin enable delay using global clock fed by Enhanced PLL with default phase setting

Notes to Table 4-54:

- (1) These timing parameters are sample-tested only.
- (2) These timing parameters are for column and row IOE pins. You should use the Quartus II software to verify the external timing for any pin.

Table 4-65. I	Table 4–65. EP1S20 External I/O Timing on Row Pins Using Regional Clock Networks Note (1)									
Davamatav	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		11	
Parameter	Min	Max	Min	Max	Min	Max	Min	Max	Unit	
t _{INSU}	1.815		1.967		2.258		NA		ns	
t _{INH}	0.000		0.000		0.000		NA		ns	
t _{OUTCO}	2.633	5.235	2.663	5.595	2.663	6.070	NA	NA	ns	
t _{XZ}	2.660	5.289	2.660	5.651	2.660	6.138	NA	NA	ns	
t _{ZX}	2.660	5.289	2.660	5.651	2.660	6.138	NA	NA	ns	
t _{INSUPLL}	1.060		1.112		1.277		NA		ns	
t _{INHPLL}	0.000		0.000		0.000		NA		ns	
t _{OUTCOPLL}	1.325	2.770	1.325	2.908	1.325	2.978	NA	NA	ns	
t _{XZPLL}	1.352	2.824	1.352	2.964	1.352	3.046	NA	NA	ns	
t _{ZXPLL}	1.352	2.824	1.352	2.964	1.352	3.046	NA	NA	ns	

Table 4–66. I	Table 4–66. EP1S20 External I/O Timing on Row Pins Using Global Clock Networks Note (1)									
Parameter	-5 Speed Grade		-6 Spee	-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		
Parameter	Min	Max	Min	Max	Min	Max	Min	Max	Unit	
t _{INSU}	1.742		1.887		2.170		NA		ns	
t _{INH}	0.000		0.000		0.000		NA		ns	
t _{OUTCO}	2.674	5.308	2.674	5.675	2.674	6.158	NA	NA	ns	
t _{XZ}	2.701	5.362	2.701	5.731	2.701	6.226	NA	NA	ns	
t _{ZX}	2.701	5.362	2.701	5.731	2.701	6.226	NA	NA	ns	
t _{INSUPLL}	1.353		1.418		1.613		NA		ns	
t _{INHPLL}	0.000		0.000		0.000		NA		ns	
t _{OUTCOPLL}	1.158	2.447	1.158	2.602	1.158	2.642	NA	NA	ns	
t _{XZPLL}	1.185	2.531	1.158	2.602	1.185	2.710	NA	NA	ns	
t _{ZXPLL}	1.185	2.531	1.158	2.602	1.185	2.710	NA	NA	ns	

Note to Tables 4–61 to 4–66:

⁽¹⁾ Only EP1S25, EP1S30, and EP1S40 have a speed grade of -8.

Tables 4–105 through 4–108 show the output adder delays associated with column and row I/O pins for both fast and slow slew rates. If an I/O standard is selected other than 3.3-V LVTTL 4mA or LVCMOS 2 mA with a fast slew rate, add the selected delay to the external $t_{\rm OUTCO}$, $t_{\rm OUTCOPLL}$, $t_{\rm XZ}$, $t_{\rm XZPLL}$, and $t_{\rm ZXPLL}$ I/O parameters shown in Table 4–55 on page 4–36 through Table 4–96 on page 4–56.

Table 4–105.	Stratix I/O S	Standard	Output De	lay Adde	rs for Fas	t Slew Ra	ate on Col	umn Pins	(Part 1 o	f 2)
Donomo		-5 Speed Grade -6		-6 Spee	-6 Speed Grade		-7 Speed Grade		-8 Speed Grade	
Parameter		Min	Max	Min	Max	Min	Max	Min	Max	Unit
LVCMOS	2 mA		1,895		1,990		1,990		1,990	ps
	4 mA		956		1,004		1,004		1,004	ps
	8 mA		189		198		198		198	ps
	12 mA		0		0		0		0	ps
	24 mA		-157		-165		-165		-165	ps
3.3-V LVTTL	4 mA		1,895		1,990		1,990		1,990	ps
	8 mA		1,347		1,414		1,414		1,414	ps
	12 mA		636		668		668		668	ps
	16 mA		561		589		589		589	ps
	24 mA		0		0		0		0	ps
2.5-V LVTTL	2 mA		2,517		2,643		2,643		2,643	ps
	8 mA		834		875		875		875	ps
	12 mA		504		529		529		529	ps
	16 mA		194		203		203		203	ps
1.8-V LVTTL	2 mA		1,304		1,369		1,369		1,369	ps
	8 mA		960		1,008		1,008		1,008	ps
	12 mA		960		1,008		1,008		1,008	ps
1.5-V LVTTL	2 mA		6,680		7,014		7,014		7,014	ps
	4 mA		3,275		3,439		3,439		3,439	ps
	8 mA		1,589		1,668		1,668		1,668	ps
GTL			16		17		17		17	ps
GTL+			9		9		9		9	ps
3.3-V PCI			50		52		52		52	ps
3.3-V PCI-X 1.0)		50		52		52		52	ps
Compact PCI			50		52		52		52	ps
AGP 1×			50		52		52		52	ps
AGP 2×			1,895		1,990		1,990		1,990	ps

Table 4–116. Stratix Maximum Input Clock Rate for CLK[1, 3, 8, 10] Pins in Flip-Chip Packages

I/O Standard	-5 Speed Grade	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVTTL	422	422	390	390	MHz
2.5 V	422	422	390	390	MHz
1.8 V	422	422	390	390	MHz
1.5 V	422	422	390	390	MHz
LVCMOS	422	422	390	390	MHz
GTL+	300	250	200	200	MHz
SSTL-3 Class I	400	350	300	300	MHz
SSTL-3 Class II	400	350	300	300	MHz
SSTL-2 Class I	400	350	300	300	MHz
SSTL-2 Class II	400	350	300	300	MHz
SSTL-18 Class I	400	350	300	300	MHz
SSTL-18 Class II	400	350	300	300	MHz
1.5-V HSTL Class I	400	350	300	300	MHz
1.8-V HSTL Class I	400	350	300	300	MHz
СТТ	300	250	200	200	MHz
Differential 1.5-V HSTL C1	400	350	300	300	MHz
LVPECL (1)	645	645	640	640	MHz
PCML (1)	300	275	275	275	MHz
LVDS (1)	645	645	640	640	MHz
HyperTransport technology (1)	500	500	450	450	MHz

Table 4–117. Stratix Maximum Input Clock Rate for CLK[7..4] & CLK[15..12] Pins in Wire-Bond Packages (Part 1 of 2)

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVTTL	422	390	390	MHz
2.5 V	422	390	390	MHz
1.8 V	422	390	390	MHz
1.5 V	422	390	390	MHz
LVCMOS	422	390	390	MHz
GTL	250	200	200	MHz

Table 4–118. Stratix Maximum Input Clock Rate for CLK[0, 2, 9, 11] Pins & FPLL[10..7]CLK Pins in Wire-Bond Packages (Part 2 of 2)

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVCMOS	422	390	390	MHz
GTL+	250	200	200	MHz
SSTL-3 Class I	350	300	300	MHz
SSTL-3 Class II	350	300	300	MHz
SSTL-2 Class I	350	300	300	MHz
SSTL-2 Class II	350	300	300	MHz
SSTL-18 Class I	350	300	300	MHz
SSTL-18 Class II	350	300	300	MHz
1.5-V HSTL Class I	350	300	300	MHz
1.8-V HSTL Class I	350	300	300	MHz
CTT	250	200	200	MHz
Differential 1.5-V HSTL C1	350	300	300	MHz
LVPECL (1)	717	640	640	MHz
PCML (1)	375	350	350	MHz
LVDS (1)	717	640	640	MHz
HyperTransport technology (1)	717	640	640	MHz

Table 4–119. Stratix Maximum Input Clock Rate for CLK[1, 3, 8, 10] Pins in Wire-Bond Packages (Part 1 of 2)

I/O Standard	-6 Speed Grade	-7 Speed Grade	-8 Speed Grade	Unit
LVTTL	422	390	390	MHz
2.5 V	422	390	390	MHz
1.8 V	422	390	390	MHz
1.5 V	422	390	390	MHz
LVCMOS	422	390	390	MHz
GTL+	250	200	200	MHz
SSTL-3 Class I	350	300	300	MHz
SSTL-3 Class II	350	300	300	MHz
SSTL-2 Class I	350	300	300	MHz
SSTL-2 Class II	350	300	300	MHz

Table 4–127. Enhanced PLL Specifications for -5 Speed Grades (Part 2 of 2)								
Symbol	Parameter	Min	Тур	Max	Unit			
t _{SKEW}	Clock skew between two external clock outputs driven by the different counters with the same settings		±75		ps			
f _{SS}	Spread spectrum modulation frequency	30		150	kHz			
% spread	Percentage spread for spread spectrum frequency (10)	0.4	0.5	0.6	%			
t _{ARESET}	Minimum pulse width on areset signal	10			ns			
tareset_recon fig	Minimum pulse width on the areset signal when using PLL reconfiguration. Reset the PLL after scandataout goes high.	500			ns			

Table 4–1.	28. Enhanced PLL Specifications for -6	Speed C	irades	(Part 1 of 2)	
Symbol	Parameter	Min	Тур	Max	Unit
f_{IN}	Input clock frequency	3 (1), (2)		650	MHz
f _{INPFD}	Input frequency to PFD	3		420	MHz
f _{INDUTY}	Input clock duty cycle	40		60	%
f _{EINDUTY}	External feedback clock input duty cycle	40		60	%
t _{INJITTER}	Input clock period jitter			±200 (3)	ps
t _{EINJITTER}	External feedback clock period jitter			±200 (3)	ps
t _{FCOMP}	External feedback clock compensation time (4)			6	ns
f _{OUT}	Output frequency for internal global or regional clock	0.3		450	MHz
f _{OUT_EXT}	Output frequency for external clock (3)	0.3		500	MHz
t _{OUTDUTY}	Duty cycle for external clock output (when set to 50%)	45		55	%
t _{JITTER}	Period jitter for external clock output (6)			±100 ps for >200-MHz outclk ±20 mUI for <200-MHz outclk	ps or mUI
t _{CONFIG5,6}	Time required to reconfigure the scan chains for PLLs 5 and 6			289/f _{SCANCLK}	
t _{CONFIG11,12}	Time required to reconfigure the scan chains for PLLs 11 and 12			193/f _{SCANCLK}	