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# **Understanding Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

#### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	4125
Number of Logic Elements/Cells	41250
Total RAM Bits	3423744
Number of I/O	615
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	780-BBGA, FCBGA
Supplier Device Package	780-FBGA (29x29)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1s40f780c8

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

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## 1. Introduction



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### Introduction

The Stratix® family of FPGAs is based on a 1.5-V, 0.13- $\mu$ m, all-layer copper SRAM process, with densities of up to 79,040 logic elements (LEs) and up to 7.5 Mbits of RAM. Stratix devices offer up to 22 digital signal processing (DSP) blocks with up to 176 (9-bit × 9-bit) embedded multipliers, optimized for DSP applications that enable efficient implementation of high-performance filters and multipliers. Stratix devices support various I/O standards and also offer a complete clock management solution with its hierarchical clock structure with up to 420-MHz performance and up to 12 phase-locked loops (PLLs).

The following shows the main sections in the Stratix Device Family Data Sheet:

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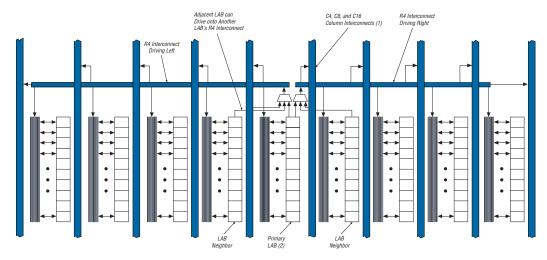
#### **Features**

The Stratix family offers the following features:

- 10,570 to 79,040 LEs; see Table 1–1
- Up to 7,427,520 RAM bits (928,440 bytes) available without reducing logic resources
- TriMatrix<sup>™</sup> memory consisting of three RAM block sizes to implement true dual-port memory and first-in first-out (FIFO) buffers
- High-speed DSP blocks provide dedicated implementation of multipliers (faster than 300 MHz), multiply-accumulate functions, and finite impulse response (FIR) filters
- Up to 16 global clocks with 22 clocking resources per device region
- Up to 12 PLLs (four enhanced PLLs and eight fast PLLs) per device provide spread spectrum, programmable bandwidth, clock switchover, real-time PLL reconfiguration, and advanced multiplication and phase shifting
- Support for numerous single-ended and differential I/O standards
- High-speed differential I/O support on up to 116 channels with up to 80 channels optimized for 840 megabits per second (Mbps)
- Support for high-speed networking and communications bus standards including RapidIO, UTOPIA IV, CSIX, HyperTransport™ technology, 10G Ethernet XSBI, SPI-4 Phase 2 (POS-PHY Level 4), and SFI-4
- Differential on-chip termination support for LVDS
- Support for high-speed external memory, including zero bus turnaround (ZBT) SRAM, quad data rate (QDR and QDRII) SRAM, double data rate (DDR) SDRAM, DDR fast cycle RAM (FCRAM), and single data rate (SDR) SDRAM
- Support for 66-MHz PCI (64 and 32 bit) in -6 and faster speed-grade devices, support for 33-MHz PCI (64 and 32 bit) in -8 and faster speed-grade devices
- Support for 133-MHz PCI-X 1.0 in -5 speed-grade devices
- Support for 100-MHz PCI-X 1.0 in -6 and faster speed-grade devices
- Support for 66-MHz PCI-X 1.0 in -7 speed-grade devices
- Support for multiple intellectual property megafunctions from Altera MegaCore<sup>®</sup> functions and Altera Megafunction Partners Program (AMPP<sup>SM</sup>) megafunctions
- Support for remote configuration updates

row connections in a four-LAB region. Every LAB has its own set of R4 interconnects to drive either left or right. Figure 2–9 shows R4 interconnect connections from an LAB. R4 interconnects can drive and be driven by DSP blocks and RAM blocks and horizontal IOEs. For LAB interfacing, a primary LAB or LAB neighbor can drive a given R4 interconnect. For R4 interconnects that drive to the right, the primary LAB and right neighbor can drive on to the interconnect. For R4 interconnects that drive to the left, the primary LAB and its left neighbor can drive on to the interconnects can drive other R4 interconnects to extend the range of LABs they can drive. R4 interconnects can also drive C4 and C16 interconnects for connections from one row to another. Additionally, R4 interconnects can drive R24 interconnects.

Figure 2-9. R4 Interconnect Connections



#### *Notes to Figure 2–9:*

- (1) C4 interconnects can drive R4 interconnects.
- (2) This pattern is repeated for every LAB in the LAB row.

The R8 interconnects span eight LABs, M512 or M4K RAM blocks, or DSP blocks to the right or left from a source LAB. These resources are used for fast row connections in an eight-LAB region. Every LAB has its own set of R8 interconnects to drive either left or right. R8 interconnect connections between LABs in a row are similar to the R4 connections shown in Figure 2–9, with the exception that they connect to eight LABs to the right or left, not four. Like R4 interconnects, R8 interconnects can drive and be driven by all types of architecture blocks. R8 interconnects

## TriMatrix Memory

TriMatrix memory consists of three types of RAM blocks: M512, M4K, and M-RAM blocks. Although these memory blocks are different, they can all implement various types of memory with or without parity, including true dual-port, simple dual-port, and single-port RAM, ROM, and FIFO buffers. Table 2–3 shows the size and features of the different RAM blocks.

Table 2–3. TriMatrix Memory Features (Part 1 of 2)								
Memory Feature	M512 RAM Block (32 × 18 Bits)	M4K RAM Block (128 × 36 Bits)	M-RAM Block (4K × 144 Bits)					
Maximum performance	(1)	(1)	(1)					
True dual-port memory		<b>✓</b>	<b>✓</b>					
Simple dual-port memory	✓	~	<b>✓</b>					
Single-port memory	✓	✓	✓					
Shift register	✓	✓						
ROM	✓	✓	(2)					
FIFO buffer	✓	✓	✓					
Byte enable		✓	✓					
Parity bits	✓	✓	✓					
Mixed clock mode	✓	✓	✓					
Memory initialization	✓	✓						
Simple dual-port memory mixed width support	<b>✓</b>	~	~					
True dual-port memory mixed width support		~	~					
Power-up conditions	Outputs cleared	Outputs cleared	Outputs unknown					
Register clears	Input and output registers	Input and output registers	Output registers					
Mixed-port read- during-write	Unknown output/old data	Unknown output/old data	Unknown output					

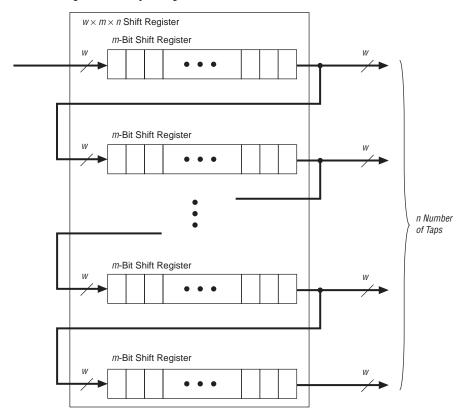


Figure 2-14. Shift Register Memory Configuration

## **Memory Block Size**

TriMatrix memory provides three different memory sizes for efficient application support. The large number of M512 blocks are ideal for designs with many shallow first-in first-out (FIFO) buffers. M4K blocks provide additional resources for channelized functions that do not require large amounts of storage. The M-RAM blocks provide a large single block of RAM ideal for data packet storage. The different-sized blocks allow Stratix devices to efficiently support variable-sized memory in designs.

The Quartus II software automatically partitions the user-defined memory into the embedded memory blocks using the most efficient size combinations. You can also manually assign the memory to a specific block size or a mixture of block sizes.

Table 2–13 shows the number of DSP blocks in each Stratix device.

Table 2–13. DSP Blocks in Stratix Devices Notes (1), (2)									
Device	DSP Blocks	Total 9 × 9 Multipliers	Total 18 × 18 Multipliers	Total 36 × 36 Multipliers					
EP1S10	6	48	24	6					
EP1S20	10	80	40	10					
EP1S25	10	80	40	10					
EP1S30	12	96	48	12					
EP1S40	14	112	56	14					
EP1S60	18	144	72	18					
EP1S80	22	176	88	22					

#### *Notes to Table 2–13:*

- (1) Each device has either the number of  $9 \times 9$ -,  $18 \times 18$ -, or  $36 \times 36$ -bit multipliers shown. The total number of multipliers for each device is not the sum of all the multipliers.
- (2) The number of supported multiply functions shown is based on signed/signed or unsigned/unsigned implementations.

DSP block multipliers can optionally feed an adder/subtractor or accumulator within the block depending on the configuration. This makes routing to LEs easier, saves LE routing resources, and increases performance, because all connections and blocks are within the DSP block. Additionally, the DSP block input registers can efficiently implement shift registers for FIR filter applications.

Figure 2–30 shows the top-level diagram of the DSP block configured for  $18 \times 18$ -bit multiplier mode. Figure 2–31 shows the  $9 \times 9$ -bit multiplier configuration of the DSP block.

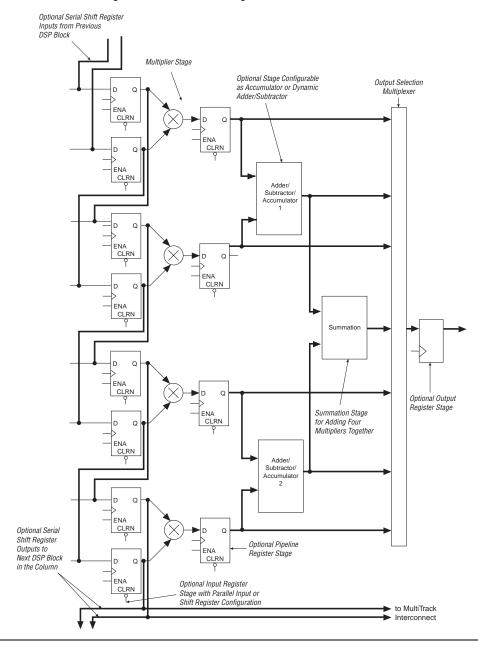


Figure 2–30. DSP Block Diagram for 18 imes 18-Bit Configuration

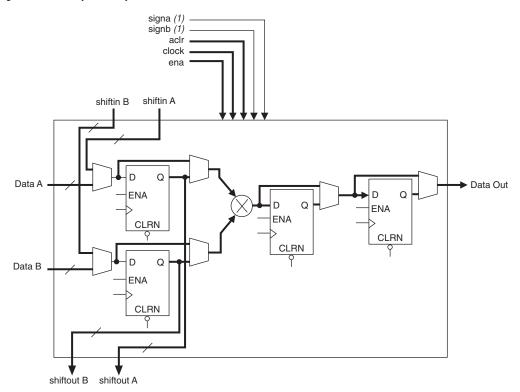


Figure 2-35. Simple Multiplier Mode

*Note to Figure 2–35:* 

(1) These signals are not registered or registered once to match the data path pipeline.

DSP blocks can also implement one  $36 \times 36$ -bit multiplier in multiplier mode. DSP blocks use four  $18 \times 18$ -bit multipliers combined with dedicated adder and internal shift circuitry to achieve 36-bit multiplication. The input shift register feature is not available for the  $36 \times 36$ -bit multiplier. In  $36 \times 36$ -bit mode, the device can use the register that is normally a multiplier-result-output register as a pipeline stage for the  $36 \times 36$ -bit multiplier. Figure 2–36 shows the  $36 \times 36$ -bit multiply mode.

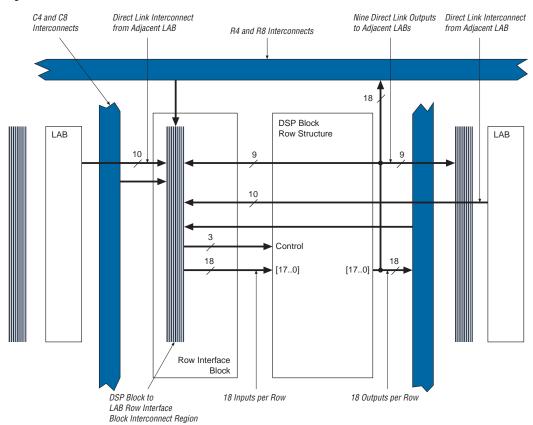


Figure 2-41. DSP Block Interface to Interconnect

A bus of 18 control signals feeds the entire DSP block. These signals include clock[0..3] clocks, aclr[0..3] asynchronous clears, ena[1..4] clock enables, signa, signb signed/unsigned control signals, addnsub1 and addnsub3 addition and subtraction control signals, and accum sload[0..1] accumulator synchronous loads. The

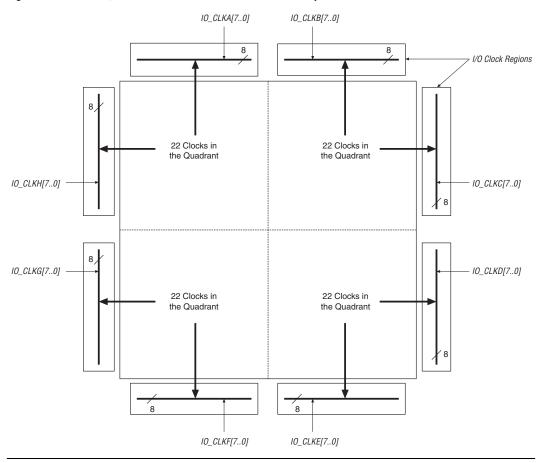


Figure 2-47. EP1S10, EP1S20 & EP1S25 Device I/O Clock Groups

VCO period from up to eight taps for individual fine step selection. Also, each clock output counter can use a unique initial count setting to achieve individual coarse shift selection in steps of one VCO period. The combination of coarse and fine shifts allows phase shifting for the entire input clock period.

The equation to determine the precision of the phase shifting in degrees is:  $45^{\circ}$  ÷ post-scale counter value. Therefore, the maximum step size is  $45^{\circ}$ , and smaller steps are possible depending on the multiplication and division ratio necessary on the output counter port.

This type of phase shift provides the highest precision since it is the least sensitive to process, supply, and temperature variation.

#### **Clock Delay**

In addition to the phase shift feature, the ability to fine tune the  $\Delta t$  clock delay provides advanced time delay shift control on each of the four PLL outputs. There are time delays for each post-scale counter (e, g, or l) from the PLL, the n counter, and m counter. Each of these can shift in 250-ps increments for a range of 3.0 ns. The m delay shifts all outputs earlier in time, while n delay shifts all outputs later in time. Individual delays on post-scale counters (e, g, and l) provide positive delay for each output. Table 2–21 shows the combined delay for each output for normal or zero delay buffer mode where  $\Delta t_e$ ,  $\Delta t_o$ , or  $\Delta t_l$  is unique for each PLL output.

The  $t_{OUTPUT}$  for a single output can range from -3 ns to +6 ns. The total delay shift difference between any two PLL outputs, however, must be less than  $\pm 3$  ns. For example, shifts on two outputs of -1 and +2 ns is allowed, but not -1 and +2.5 ns because these shifts would result in a difference of 3.5 ns. If the design uses external feedback, the  $\Delta t_e$  delay will remove delay from outputs, represented by a negative sign (see Table 2–21). This effect occurs because the  $\Delta t_e$  delay is then part of the feedback loop.

Table 2–21. Output Clock Delay for Enhanced PLLs						
Normal or Zero Delay Buffer Mode	External Feedback Mode					
$\begin{split} \Delta t_{e \text{OUTPUT}} &= \Delta t_n - \!\!\! \Delta t_m + \Delta t_e \\ \Delta t_{g \text{OUTPUT}} &= \Delta t_n - \!\!\! \Delta t_m + \Delta t_g \\ \Delta t_{l \text{OUTPUT}} &= \Delta t_n - \!\!\! \Delta t_m + \Delta t_l \end{split}$	$\begin{split} \Delta \mathbf{t}_{\text{OUTPUT}} &= \Delta \mathbf{t}_{n} - \Delta \mathbf{t}_{m} - \Delta \mathbf{t}_{e} \ (1) \\ \Delta \mathbf{t}_{\text{gOUTPUT}} &= \Delta \mathbf{t}_{n} - \Delta \mathbf{t}_{m} + \Delta \mathbf{t}_{g} \\ \Delta \mathbf{t}_{\text{DUTPUT}} &= \Delta \mathbf{t}_{n} - \Delta \mathbf{t}_{m} + \Delta \mathbf{t}_{l} \end{split}$					

Note to Table 2-21:

(1)  $\Delta t_e$  removes delay from outputs in external feedback mode.

The variation due to process, voltage, and temperature is about ±15% on the delay settings. PLL reconfiguration can control the clock delay shift elements, but not the VCO phase shift multiplexers, during system operation.

#### Spread-Spectrum Clocking

Stratix device enhanced PLLs use spread-spectrum technology to reduce electromagnetic interference generation from a system by distributing the energy over a broader frequency range. The enhanced PLL typically provides 0.5% down spread modulation using a triangular profile. The modulation frequency is programmable. Enabling spread-spectrum for a PLL affects all of its outputs.

#### Lock Detect

The lock output indicates that there is a stable clock output signal in phase with the reference clock. Without any additional circuitry, the lock signal may toggle as the PLL begins tracking the reference clock. You may need to gate the lock signal for use as a system control. The lock signal from the locked port can drive the logic array or an output pin.

Whenever the PLL loses lock (for example, inclk jitter, clock switchover, PLL reconfiguration, power supply noise, and so on), the PLL must be reset with the areset signal to guarantee correct phase relationship between the PLL output clocks. If the phase relationship between the input clock versus output clock, and between different output clocks from the PLL is not important in the design, then the PLL need not be reset.



See the *Stratix FPGA Errata Sheet* for more information on implementing the gated lock signal in a design.

#### Programmable Duty Cycle

The programmable duty cycle allows enhanced PLLs to generate clock outputs with a variable duty cycle. This feature is supported on each enhanced PLL post-scale counter (*g*0..*g*3, *l*0..*l*3, *e*0..*e*3). The duty cycle setting is achieved by a low and high time count setting for the post-scale dividers. The Quartus II software uses the frequency input and the required multiply or divide rate to determine the duty cycle choices.

#### Advanced Clear & Enable Control

There are several control signals for clearing and enabling PLLs and their outputs. You can use these signals to control PLL resynchronization and gate PLL output clocks for low-power applications.

Table 2-	Table 2–37. EP1S10, EP1S20 & EP1S25 Device Differential Channels (Part 2 of 2) Note (1)										
		Transmitter/	Total	Maximum	Center Fast PLLs						
Device	Package	Receiver	Channels	Speed (Mbps)	PLL 1	PLL 2		PLL 4			
EP1S25	672-pin FineLine BGA	Transmitter (2)	56	624 (4)	14	14	14	14			
	672-pin BGA			624 (3)	28	28	28	28			
		Receiver	58	624 (4)	14	15	15	14			
				624 (3)	29	29	29	29			
	780-pin FineLine BGA	Transmitter (2)	70	840 (4)	18	17	17	18			
				840 (3)	35	35	35	35			
		Receiver	66	840 (4)	17	16	16	17			
				840 (3)	33	33	33	33			
	1,020-pin FineLine	Transmitter (2)	78	840 (4)	19	20	20	19			
	BGA			840 (3)	39	39	39	39			
		Receiver	78	840 (4)	19	20	20	19			
				840 (3)	39	39	39	39			

#### Notes to Table 2–37:

- (1) The first row for each transmitter or receiver reports the number of channels driven directly by the PLL. The second row below it shows the maximum channels a PLL can drive if cross bank channels are used from the adjacent center PLL. For example, in the 484-pin FineLine BGA EP1S10 device, PLL 1 can drive a maximum of five channels at 840 Mbps or a maximum of 10 channels at 840 Mbps. The Quartus II software may also merge receiver and transmitter PLLs when a receiver is driving a transmitter. In this case, one fast PLL can drive both the maximum numbers of receiver and transmitter channels.
- (2) The number of channels listed includes the transmitter clock output (tx\_outclock) channel. If the design requires a DDR clock, it can use an extra data channel.
- (3) These channels span across two I/O banks per side of the device. When a center PLL clocks channels in the opposite bank on the same side of the device it is called cross-bank PLL support. Both center PLLs can clock cross-bank channels simultaneously if, for example, PLL\_1 is clocking all receiver channels and PLL\_2 is clocking all transmitter channels. You cannot have two adjacent PLLs simultaneously clocking cross-bank receiver channels or two adjacent PLLs simultaneously clocking transmitter channels. Cross-bank allows for all receiver channels on one side of the device to be clocked on one clock while all transmitter channels on the device are clocked on the other center PLL. Crossbank PLLs are supported at full-speed, 840 Mbps. For wire-bond devices, the full-speed is 624 Mbps.
- (4) These values show the channels available for each PLL without crossing another bank.

When you span two I/O banks using cross-bank support, you can route only two load enable signals total between the PLLs. When you enable rx\_data\_align, you use both rxloadena and txloadena of a PLL. That leaves no loadena for the second PLL.

Table 4–9. Overshoot Input Voltage with Respect to Duty Cycle (Part 2 of 2)						
Vin (V)	Maximum Duty Cycle (%)					
4.3	30					
4.4	17					
4.5	10					

Figures 4–1 and 4–2 show receiver input and transmitter output waveforms, respectively, for all differential I/O standards (LVDS, 3.3-V PCML, LVPECL, and HyperTransport technology).

Figure 4-1. Receiver Input Waveforms for Differential I/O Standards

# Single-Ended Waveform Positive Channel (p) = $V_{IH}$ Negative Channel (n) = $V_{IL}$

#### **Differential Waveform**



Table 4–20. SSTL-2 Class I Specifications									
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit			
$V_{\text{CCIO}}$	Output supply voltage		2.375	2.5	2.625	٧			
$V_{TT}$	Termination voltage		V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04	V			
$V_{REF}$	Reference voltage		1.15	1.25	1.35	٧			
V <sub>IH(DC)</sub>	High-level DC input voltage		V <sub>REF</sub> + 0.18		3.0	V			
V <sub>IL(DC)</sub>	Low-level DC input voltage		-0.3		V <sub>REF</sub> – 0.18	٧			
V <sub>IH(AC)</sub>	High-level AC input voltage		V <sub>REF</sub> + 0.35			V			
V <sub>IL(AC)</sub>	Low-level AC input voltage				V <sub>REF</sub> - 0.35	V			
V <sub>OH</sub>	High-level output voltage	$I_{OH} = -8.1 \text{ mA}$ (3)	V <sub>TT</sub> + 0.57			V			
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 8.1 mA (3)			V <sub>TT</sub> – 0.57	٧			

Table 4–21	Table 4–21. SSTL-2 Class II Specifications										
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit					
V <sub>CCIO</sub>	Output supply voltage		2.375	2.5	2.625	٧					
V <sub>TT</sub>	Termination voltage		V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04	V					
V <sub>REF</sub>	Reference voltage		1.15	1.25	1.35	V					
V <sub>IH(DC)</sub>	High-level DC input voltage		V <sub>REF</sub> + 0.18		V <sub>CCIO</sub> + 0.3	V					
V <sub>IL(DC)</sub>	Low-level DC input voltage		-0.3		V <sub>REF</sub> – 0.18	V					
V <sub>IH(AC)</sub>	High-level AC input voltage		V <sub>REF</sub> + 0.35			V					
V <sub>IL(AC)</sub>	Low-level AC input voltage				V <sub>REF</sub> – 0.35	V					
V <sub>OH</sub>	High-level output voltage	$I_{OH} = -16.4 \text{ mA}$ (3)	V <sub>TT</sub> + 0.76			V					
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 16.4 mA (3)			V <sub>TT</sub> – 0.76	V					

Table 4–22. SSTL-3 Class I Specifications (Part 1 of 2)										
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit				
V <sub>CCIO</sub>	Output supply voltage		3.0	3.3	3.6	V				
V <sub>TT</sub>	Termination voltage		V <sub>REF</sub> - 0.05	$V_{REF}$	V <sub>REF</sub> + 0.05	V				
V <sub>REF</sub>	Reference voltage		1.3	1.5	1.7	V				
V <sub>IH(DC)</sub>	High-level DC input voltage		V <sub>REF</sub> + 0.2		V <sub>CCIO</sub> + 0.3	V				
V <sub>IL(DC)</sub>	Low-level DC input voltage		-0.3		V <sub>REF</sub> - 0.2	V				
V <sub>IH(AC)</sub>	High-level AC input voltage		V <sub>REF</sub> + 0.4			V				

Table 4–105. Stratix I/O Standard Output Delay Adders for Fast Slew Rate on Column Pins (Part 2 of 2)									
Dt	-5 Spee	ed Grade	-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		T
Parameter	Min	Max	Min	Max	Min	Max	Min	Max	Unit
CTT		973		1,021		1,021		1,021	ps
SSTL-3 Class I		719		755		755		755	ps
SSTL-3 Class II		146		153		153		153	ps
SSTL-2 Class I		678		712		712		712	ps
SSTL-2 Class II		223		234		234		234	ps
SSTL-18 Class I		1,032		1,083		1,083		1,083	ps
SSTL-18 Class II		447		469		469		469	ps
1.5-V HSTL Class I		660		693		693		693	ps
1.5-V HSTL Class II		537		564		564		564	ps
1.8-V HSTL Class I		304		319		319		319	ps
1.8-V HSTL Class II		231		242		242		242	ps

Table 4–106. Stratix I/O Standard Output Delay Adders for Fast Slew Rate on Row Pins (Part 1 of 2)										2)
Рокото	-5 Speed Grade		-6 Spee	-6 Speed Grade		-7 Speed Grade		-8 Speed Grade		
Parameter		Min	Max	Min	Max	Min	Max	Min	Max	Unit
LVCMOS	2 mA		1,518		1,594		1,594		1,594	ps
	4 mA		746		783		783		783	ps
	8 mA		96		100		100		100	ps
	12 mA		0		0		0		0	ps
3.3-V LVTTL	4 mA		1,518		1,594		1,594		1,594	ps
	8 mA		1,038		1,090		1,090		1,090	ps
	12 mA		521		547		547		547	ps
	16 mA		414		434		434		434	ps
	24 mA		0		0		0		0	ps
2.5-V LVTTL	2 mA		2,032		2,133		2,133		2,133	ps
	8 mA		699		734		734		734	ps
	12 mA		374		392		392		392	ps
	16 mA		165		173		173		173	ps
1.8-V LVTTL	2 mA		3,714		3,899		3,899		3,899	ps
	8 mA		1,055		1,107		1,107		1,107	ps
	12 mA		830		871		871		871	ps

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