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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	100MHz
Connectivity	EBI/EMI, Ethernet, I²C, IrDA, SD, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	96
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 41x16b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LBGA
Supplier Device Package	144-MAPBGA (13x13)
Purchase URL	<a href="https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=mk52dn512zcmd10">https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=mk52dn512zcmd10</a>

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# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to [freescale.com](http://freescale.com) and perform a part number search for the following device numbers: PK52 and MK52.

# 2 Part identification

## 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

## 2.2 Format

Part numbers for this device have the following format:

Q K## A M FFF R T PP CC N

## 2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"><li>M = Fully qualified, general market flow</li><li>P = Prequalification</li></ul>
K##	Kinetis family	<ul style="list-style-type: none"><li>K52</li></ul>
A	Key attribute	<ul style="list-style-type: none"><li>D = Cortex-M4 w/ DSP</li><li>F = Cortex-M4 w/ DSP and FPU</li></ul>
M	Flash memory type	<ul style="list-style-type: none"><li>N = Program flash only</li><li>X = Program flash and FlexMemory</li></ul>

*Table continues on the next page...*

## 4 Ratings

### 4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$T_{STG}$	Storage temperature	-55	150	°C	<a href="#">1</a>
$T_{SDR}$	Solder temperature, lead-free	—	260	°C	<a href="#">2</a>
	Solder temperature, leaded	—	245		

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	<a href="#">1</a>

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$V_{HBM}$	Electrostatic discharge voltage, human body model	-2000	+2000	V	<a href="#">1</a>
$V_{CDM}$	Electrostatic discharge voltage, charged-device model	-500	+500	V	<a href="#">2</a>
$I_{LAT}$	Latch-up current at ambient temperature of 105°C	-100	+100	mA	<a href="#">3</a>

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.
3. Determined according to JEDEC Standard JESD78, *IC Latch-Up Test*.

### 4.4 Voltage and current operating ratings

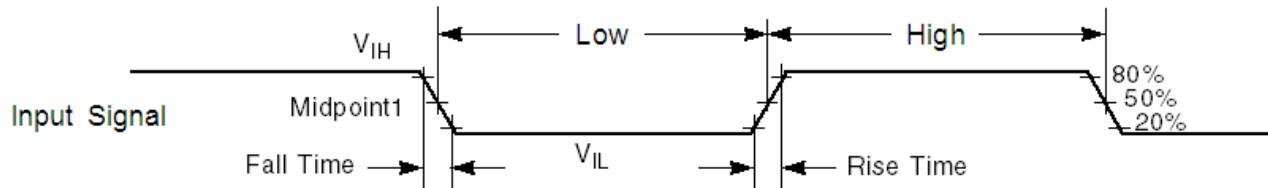
Symbol	Description	Min.	Max.	Unit
$V_{DD}$	Digital supply voltage	-0.3	3.8	V
$I_{DD}$	Digital supply current	—	185	mA
$V_{DIO}$	Digital input voltage (except $\overline{\text{RESET}}$ , EXTAL, and XTAL)	-0.3	5.5	V
$V_{AIO}$	Analog <sup>1</sup> , $\overline{\text{RESET}}$ , EXTAL, and XTAL input voltage	-0.3	$V_{DD} + 0.3$	V
$I_D$	Maximum current single pin limit (applies to all digital pins)	-25	25	mA
$V_{DDA}$	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V
$V_{USB\_DP}$	USB_DP input voltage	-0.3	3.63	V
$V_{USB\_DM}$	USB_DM input voltage	-0.3	3.63	V
$V_{REGIN}$	USB regulator input	-0.3	6.0	V
$V_{BAT}$	RTC battery supply voltage	-0.3	3.8	V

1. Analog pins are defined as pins that do not have an associated general purpose I/O port function.

## 5 General

### 5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.



The midpoint is  $V_{IL} + (V_{IH} - V_{IL})/2$ .

**Figure 1. Input signal measurement reference**

All digital I/O switching characteristics assume:

1. output pins
  - have  $C_L=30\text{pF}$  loads,
  - are configured for fast slew rate ( $\text{PORTx\_PCRn}[SRE]=0$ ), and
  - are configured for high drive strength ( $\text{PORTx\_PCRn}[DSE]=1$ )
2. input pins
  - have their passive filter disabled ( $\text{PORTx\_PCRn}[PFE]=0$ )

**Table 6. Power consumption operating behaviors (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I <sub>DD_VBAT</sub>	Average current when CPU is not accessing RTC registers <ul style="list-style-type: none"> <li>• @ 1.8V               <ul style="list-style-type: none"> <li>• @ -40 to 25°C</li> <li>• @ 70°C</li> <li>• @ 105°C</li> </ul> </li> <li>• @ 3.0V               <ul style="list-style-type: none"> <li>• @ -40 to 25°C</li> <li>• @ 70°C</li> <li>• @ 105°C</li> </ul> </li> </ul>	—	0.71	0.81	µA	10
		—	1.01	1.3	µA	
		—	2.82	4.3	µA	
		—	0.84	0.94	µA	
		—	1.17	1.5	µA	
		—	3.16	4.6	µA	

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. 100MHz core and system clock, 50MHz bus and FlexBus clock, and 25MHz flash clock . MCG configured for FEI mode. All peripheral clocks disabled.
3. 100MHz core and system clock, 50MHz bus and FlexBus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks enabled.
4. Max values are measured with CPU executing DSP instructions.
5. 25MHz core and system clock, 25MHz bus clock, and 12.5MHz FlexBus and flash clock. MCG configured for FEI mode.
6. 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for BLPE mode. All peripheral clocks disabled. Code executing from flash.
7. 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for BLPE mode. All peripheral clocks enabled but peripherals are not in active operation. Code executing from flash.
8. 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for BLPE mode. All peripheral clocks disabled.
9. Data reflects devices with 128 KB of RAM.
10. Includes 32kHz oscillator current and RTC operation.

### 5.2.5.1 Diagram: Typical IDD\_RUN operating behavior

The following data was measured under these conditions:

- MCG in FBE mode for 50 MHz and lower frequencies. MCG in FEE mode at greater than 50 MHz frequencies.
- USB regulator disabled
- No GPIOs toggled
- Code execution from flash with cache enabled
- For the ALLOFF curve, all peripheral clocks are disabled except FTFL

**Table 16. Oscillator DC electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$R_F$	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	—	—	MΩ	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	—	10	—	MΩ	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	—	—	MΩ	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1	—	MΩ	
$R_S$	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	kΩ	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	kΩ	
$V_{pp}^5$	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	—	$V_{DD}$	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	—	$V_{DD}$	—	V	

1.  $V_{DD}=3.3$  V, Temperature =25 °C
2. See crystal or resonator manufacturer's recommendation
3.  $C_x, C_y$  can be provided by using either the integrated capacitors or by using external components.
4. When low power mode is selected,  $R_F$  is integrated and must not be attached externally.
5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

### 6.3.2.2 Oscillator frequency specifications

**Table 17. Oscillator frequency specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{osc\_lo}$	Oscillator crystal or resonator frequency — low frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
$f_{osc\_hi\_1}$	Oscillator crystal or resonator frequency — high frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	

Table continues on the next page...

### 6.3.3.2 32 kHz oscillator frequency specifications

Table 19. 32 kHz oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{osc\_lo}$	Oscillator crystal	—	32.768	—	kHz	
$t_{start}$	Crystal start-up time	—	1000	—	ms	1
$f_{ec\_extal32}$	Externally provided input clock frequency	—	32.768	—	kHz	2
$V_{ec\_extal32}$	Externally provided input clock amplitude	700	—	$V_{BAT}$	mV	2, 3

- Proper PC board layout procedures must be followed to achieve specifications.
- This specification is for an externally supplied clock driven to EXTAL32 and does not apply to any other clock input. The oscillator remains enabled and XTAL32 must be left unconnected.
- The parameter specified is a peak-to-peak value and  $V_{IH}$  and  $V_{IL}$  specifications do not apply. The voltage of the applied clock must be within the range of  $V_{SS}$  to  $V_{BAT}$ .

## 6.4 Memories and memory interfaces

### 6.4.1 Flash electrical specifications

This section describes the electrical characteristics of the flash memory module.

#### 6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

Table 20. NVM program/erase timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{hvpgm4}$	Longword Program high-voltage time	—	7.5	18	μs	
$t_{hversscr}$	Sector Erase high-voltage time	—	13	113	ms	1
$t_{hversblk256k}$	Erase Block high-voltage time for 256 KB	—	416	3616	ms	1

- Maximum time based on expectations at cycling end-of-life.

#### 6.4.1.2 Flash timing specifications — commands

Table 21. Flash command timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1blk256k}$	Read 1s Block execution time • 256 KB program/data flash	—	—	1.7	ms	
$t_{rd1sec2k}$	Read 1s Section execution time (flash sector)	—	—	60	μs	1

Table continues on the next page...

**Table 23. NVM reliability specifications (continued)**

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
$t_{\text{nvmretd1k}}$	Data retention after up to 1 K cycles	20	100	—	years	
$n_{\text{nvmcycd}}$	Cycling endurance	10 K	50 K	—	cycles	<sup>2</sup>
FlexRAM as EEPROM						
$t_{\text{nvmretee100}}$	Data retention up to 100% of write endurance	5	50	—	years	
$t_{\text{nvmretee10}}$	Data retention up to 10% of write endurance	20	100	—	years	
$n_{\text{nvmwree16}}$	Write endurance	35 K	175 K	—	writes	<sup>3</sup>
$n_{\text{nvmwree128}}$	• EEPROM backup to FlexRAM ratio = 16	315 K	1.6 M	—	writes	
$n_{\text{nvmwree512}}$	• EEPROM backup to FlexRAM ratio = 128	1.27 M	6.4 M	—	writes	
$n_{\text{nvmwree4k}}$	• EEPROM backup to FlexRAM ratio = 512	10 M	50 M	—	writes	
$n_{\text{nvmwree32k}}$	• EEPROM backup to FlexRAM ratio = 32,768	80 M	400 M	—	writes	

1. Typical data retention values are based on measured response accelerated at high temperature and derated to a constant 25°C use profile. Engineering Bulletin EB618 does not apply to this technology. Typical endurance defined in Engineering Bulletin EB619.
2. Cycling endurance represents number of program/erase cycles at -40°C ≤ T<sub>j</sub> ≤ 125°C.
3. Write endurance represents the number of writes to each FlexRAM location at -40°C ≤ T<sub>j</sub> ≤ 125°C influenced by the cycling endurance of the FlexNVM (same value as data flash) and the allocated EEPROM backup per subsystem. Minimum and typical values assume all byte-writes to FlexRAM.

#### 6.4.1.5 Write endurance to FlexRAM for EEPROM

When the FlexNVM partition code is not set to full data flash, the EEPROM data set size can be set to any of several non-zero values.

The bytes not assigned to data flash via the FlexNVM partition code are used by the flash memory module to obtain an effective endurance increase for the EEPROM data. The built-in EEPROM record management system raises the number of program/erase cycles that can be attained prior to device wear-out by cycling the EEPROM data through a larger EEPROM NVM storage space.

While different partitions of the FlexNVM are available, the intention is that a single choice for the FlexNVM partition code and EEPROM data set size is used throughout the entire lifetime of a given application. The EEPROM endurance equation and graph shown below assume that only one configuration is ever used.

$$\text{Writes\_subsystem} = \frac{\text{EEPROM} - 2 \times \text{EEESPLIT} \times \text{EEESIZE}}{\text{EEESPLIT} \times \text{EEESIZE}} \times \text{Write\_efficiency} \times n_{\text{nvmcycd}}$$

where

- Writes\_subsystem — minimum number of writes to each FlexRAM location for subsystem (each subsystem can have different endurance)

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the Flexbus output clock (FB\_CLK). All other timing relationships can be derived from these values.

**Table 25. Flexbus limited voltage range switching specifications**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	20	—	ns	
FB2	Address, data, and control output valid	—	11.5	ns	1
FB3	Address, data, and control output hold	0.5	—	ns	1
FB4	Data and FB_TA input setup	8.5	—	ns	2
FB5	Data and FB_TA input hold	0.5	—	ns	2

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWE<sub>n</sub>, FB\_CS<sub>n</sub>, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

**Table 26. Flexbus full voltage range switching specifications**

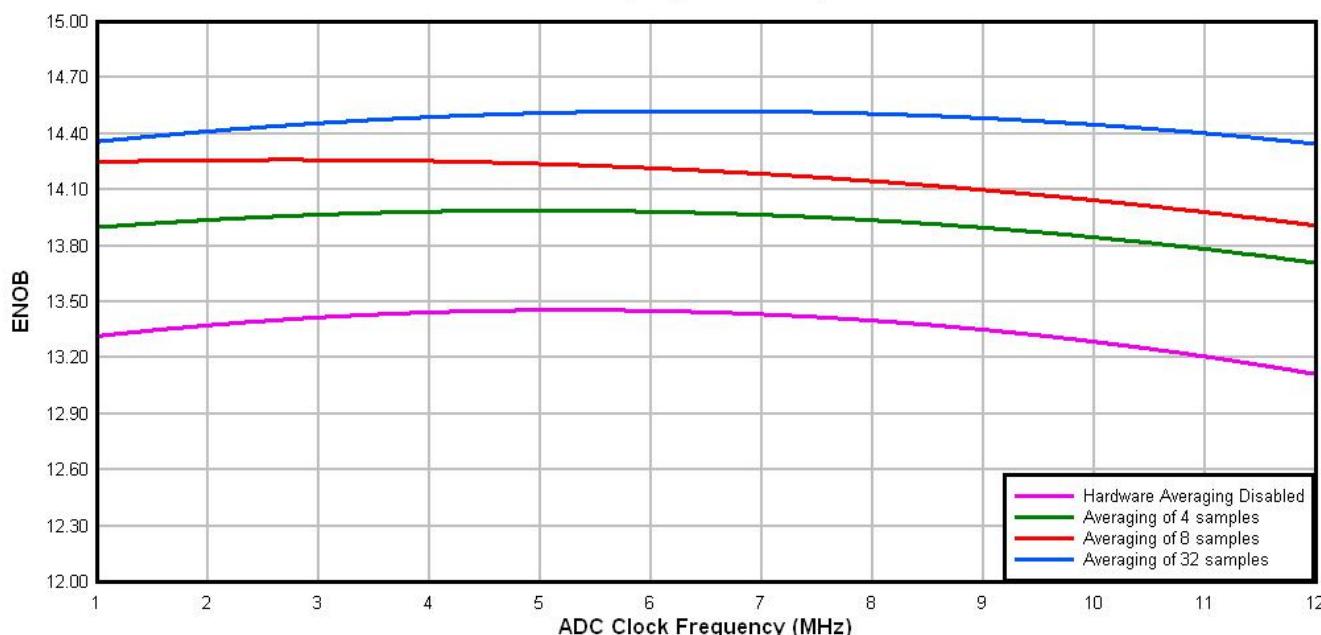
Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	1/FB_CLK	—	ns	
FB2	Address, data, and control output valid	—	13.5	ns	1
FB3	Address, data, and control output hold	0	—	ns	1
FB4	Data and FB_TA input setup	13.7	—	ns	2
FB5	Data and FB_TA input hold	0.5	—	ns	2

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWE<sub>n</sub>, FB\_CS<sub>n</sub>, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

**Table 28. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$E_{IL}$	Input leakage error			$I_{In} \times R_{AS}$		mV	$I_{In}$ = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	1.55	1.62	1.69	mV/°C	
$V_{TEMP25}$	Temp sensor voltage	25 °C	706	716	726	mV	

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit must be set, the HSC bit must be clear with 1 MHz ADC conversion clock speed.
4. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
6. Input data is 100 Hz sine wave. ADC conversion clock < 12 MHz.
7. Input data is 1 kHz sine wave. ADC conversion clock < 12 MHz.

**Typical ADC 16-bit Differential ENOB vs ADC Clock  
100Hz, 90% FS Sine Input****Figure 14. Typical ENOB vs. ADC\_CLK for 16-bit differential mode**

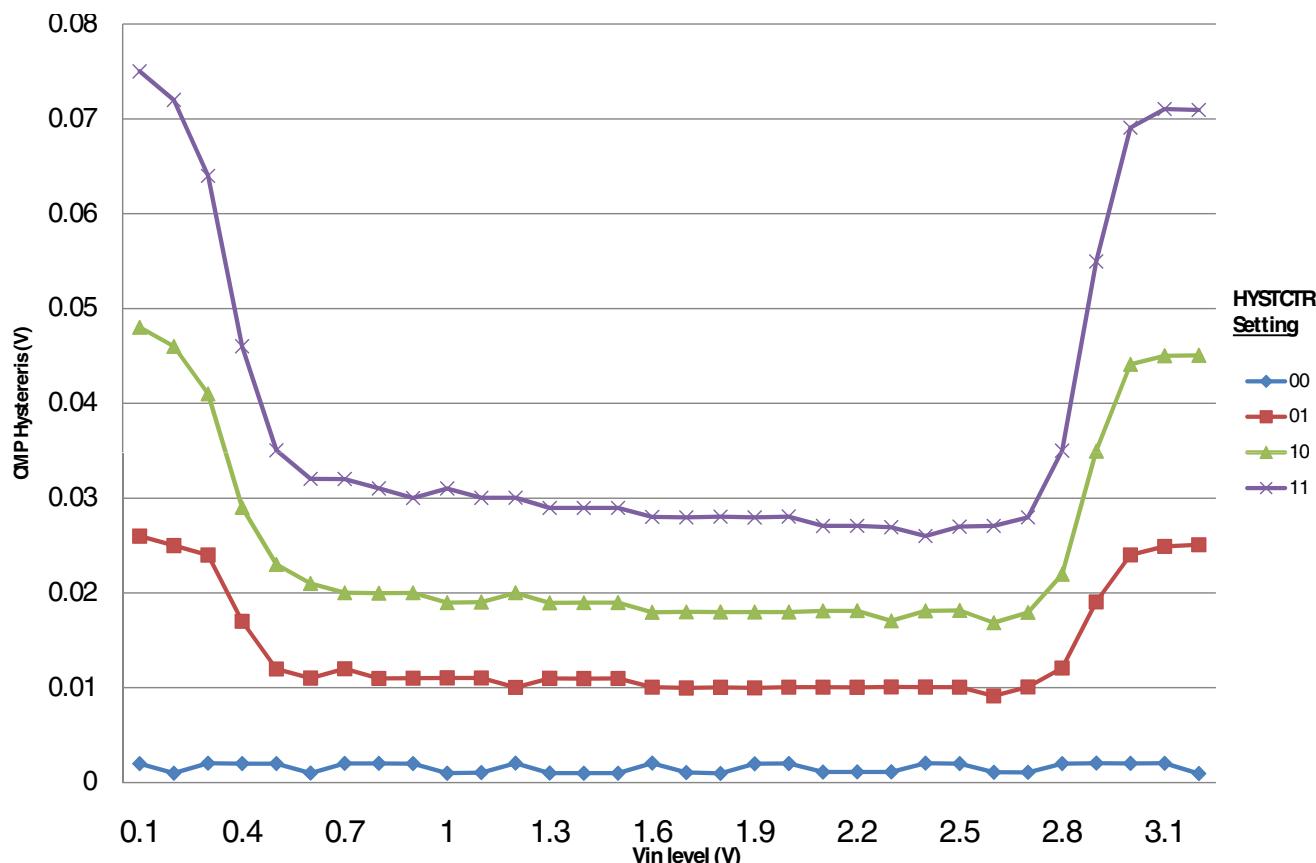
**Table 31. Comparator and 6-bit DAC electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit
$t_{DLS}$	Propagation delay, low-speed mode (EN=1, PMODE=0)	80	250	600	ns
	Analog comparator initialization delay <sup>2</sup>	—	—	40	μs
$I_{DAC6b}$	6-bit DAC current adder (enabled)	—	7	—	μA
INL	6-bit DAC integral non-linearity	-0.5	—	0.5	LSB <sup>3</sup>
DNL	6-bit DAC differential non-linearity	-0.3	—	0.3	LSB

1. Typical hysteresis is measured with input voltage range limited to 0.6 to  $V_{DD}$ -0.6 V.

2. Comparator initialization delay is defined as the time between software writes to change control inputs (Writes to DACEN, VRSEL, PSEL, MSEL, VOSEL) and the comparator output settling to a stable level.

3. 1 LSB =  $V_{reference}/64$

**Figure 16. Typical hysteresis vs. Vin level ( $V_{DD}=3.3V$ , PMODE=0)**

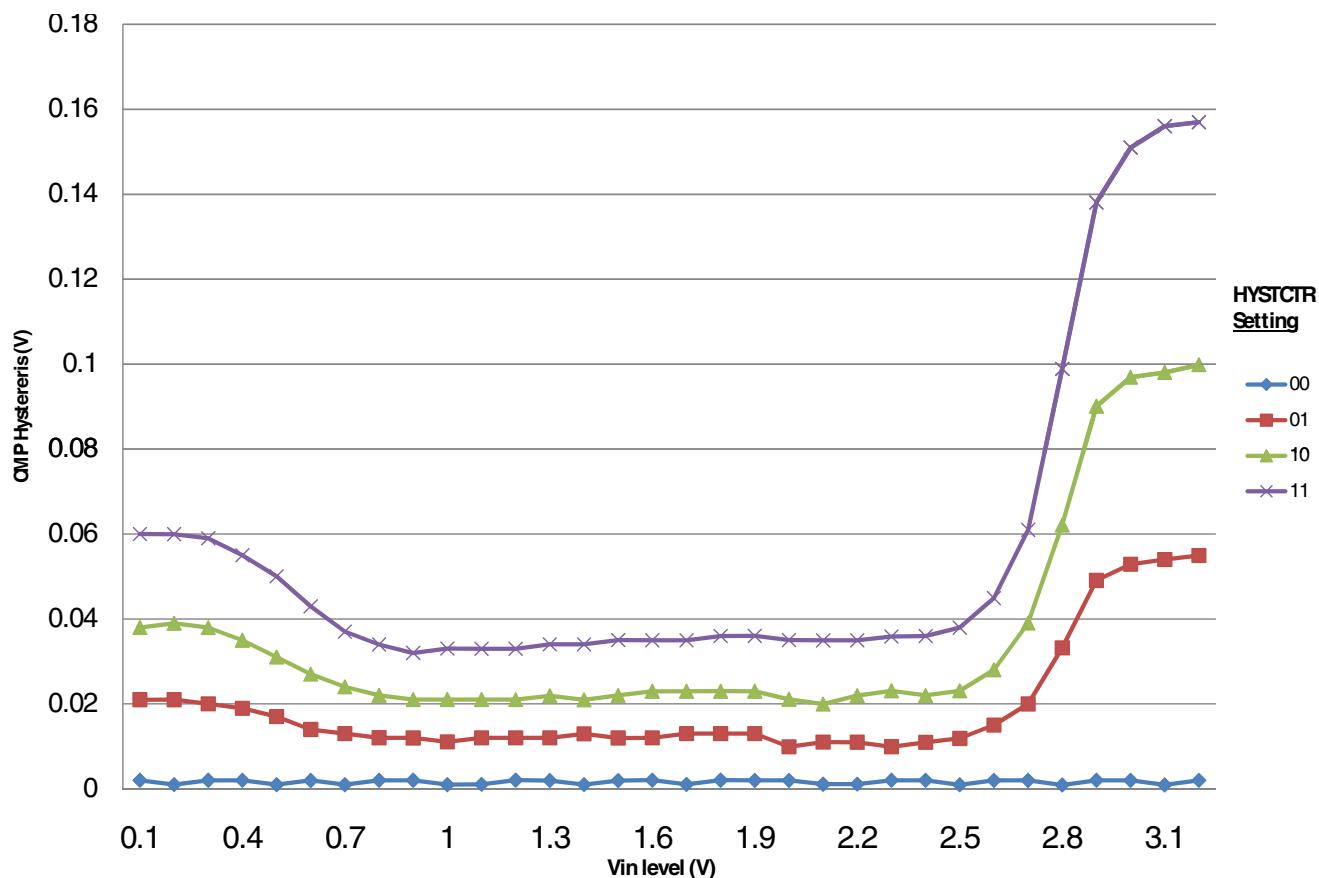


Figure 17. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=1)

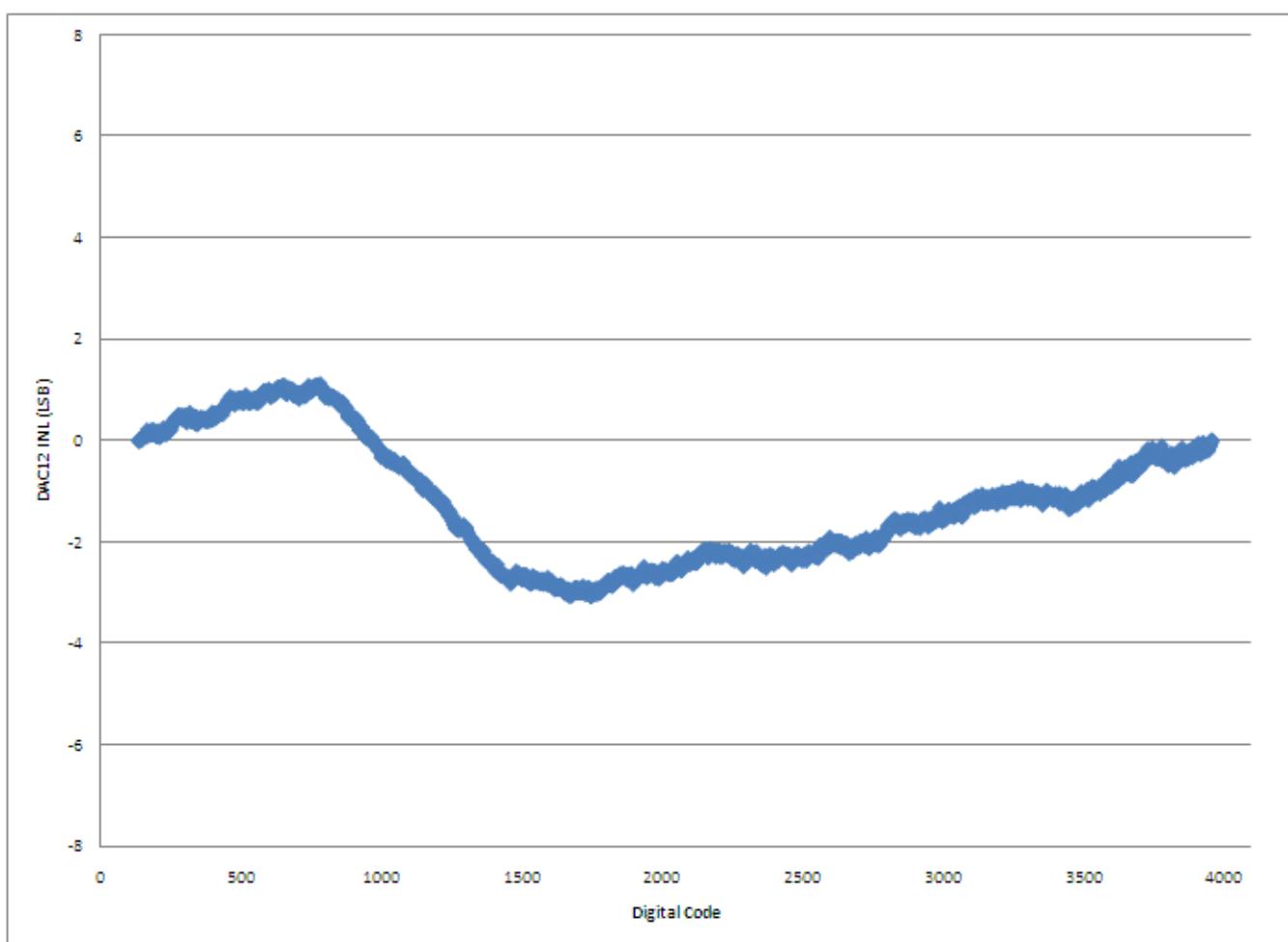
### 6.6.3 12-bit DAC electrical characteristics

#### 6.6.3.1 12-bit DAC operating requirements

Table 32. 12-bit DAC operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
$V_{DDA}$	Supply voltage	1.71	3.6	V	
$V_{DACP}$	Reference voltage	1.13	3.6	V	1
$T_A$	Temperature	Operating temperature range of the device		°C	
$C_L$	Output load capacitance	—	100	pF	2
$I_L$	Output load current	—	1	mA	

1. The DAC reference can be selected to be  $V_{DDA}$  or the voltage output of the VREF module (VREF\_OUT)
2. A small load capacitance (47 pF) can improve the bandwidth performance of the DAC



**Figure 18. Typical INL error vs. digital code**

**Table 36. TRIAMP full range operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I <sub>SUPPLY</sub>	Supply current ( $I_{OUT}=0mA$ , $CL=0$ ) — Low-power mode	—	60	80	µA	
I <sub>SUPPLY</sub>	Supply current ( $I_{OUT}=0mA$ , $CL=0$ ) — High-speed mode	—	280	450	µA	
V <sub>OS</sub>	Input offset voltage	—	±3	±5	mV	
α <sub>VOS</sub>	Input offset voltage temperature coefficient	—	4.8	—	µV/C	
I <sub>OS</sub>	Input offset current	—	±0.3	±5	nA	
I <sub>BIAS</sub>	Input bias current	—	±0.3	±5	nA	
R <sub>IN</sub>	Input resistance	500	—	—	MΩ	
C <sub>IN</sub>	Input capacitance	—	17	—	pF	
R <sub>OUT</sub>	Output AC impedance	—	—	1500	Ω	@ 100kHz, High speed mode
X <sub>IN</sub>	AC input impedance ( $f_{IN}=100kHz$ )	—	159	—	kΩ	
CMRR	Input common mode rejection ratio	60	—	—	dB	
PSRR	Power supply rejection ratio	60	—	—	dB	
SR	Slew rate ( $\Delta V_{IN}=100mV$ ) — Low-power mode	0.1	—	—	V/µs	
SR	Slew rate ( $\Delta V_{IN}=100mV$ ) — High speed mode	1	—	—	V/µs	
GBW	Unity gain bandwidth — Low-power mode 50pF	0.15	—	—	MHz	
GBW	Unity gain bandwidth — High speed mode 50pF	1	—	—	MHz	
A <sub>V</sub>	DC open-loop voltage gain	80	—	—	dB	
V <sub>OUT</sub>	Output voltage range	0.15	—	V <sub>DD</sub> -0.15	V	
I <sub>OUT</sub>	Output load current	—	±0.5	—	mA	
GM	Gain margin	—	20	—	dB	
PM	Phase margin	50	60	—	deg	
V <sub>n</sub>	Voltage noise density (noise floor) 1kHz	—	280	—	nV/√Hz	
V <sub>n</sub>	Voltage noise density (noise floor) 10kHz	—	100	—	nV/√Hz	

## 6.6.6 Transimpedance amplifier electrical specifications — limited range

**Table 37. TRIAMP limited range operating requirements**

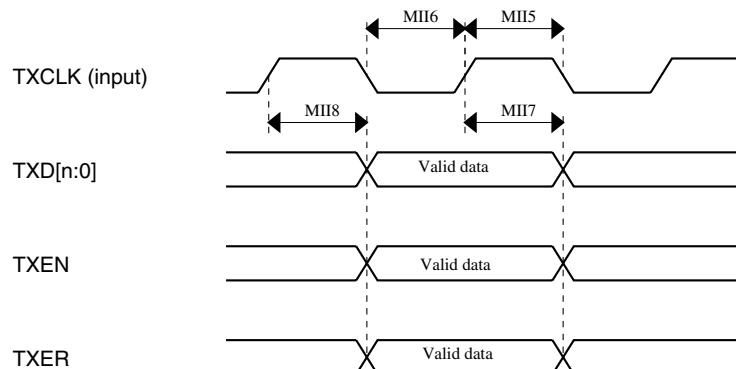
Symbol	Description	Min.	Max.	Unit	Notes
V <sub>DDA</sub>	Supply voltage	2.4	3.3	V	
V <sub>IN</sub>	Input voltage range	0.1	V <sub>DDA</sub> -1.4	V	
T <sub>A</sub>	Temperature	0	50	C	
C <sub>L</sub>	Output load capacitance	—	100	pf	

### 6.8.1.1 MII signal switching specifications

The following timing specs meet the requirements for MII style interfaces for a range of transceiver devices.

**Table 43. MII signal switching specifications**

Symbol	Description	Min.	Max.	Unit
—	RXCLK frequency	—	25	MHz
MII1	RXCLK pulse width high	35%	65%	RXCLK period
MII2	RXCLK pulse width low	35%	65%	RXCLK period
MII3	RXD[3:0], RXDV, RXER to RXCLK setup	5	—	ns
MII4	RXCLK to RXD[3:0], RXDV, RXER hold	5	—	ns
—	TXCLK frequency	—	25	MHz
MII5	TXCLK pulse width high	35%	65%	TXCLK period
MII6	TXCLK pulse width low	35%	65%	TXCLK period
MII7	TXCLK to TXD[3:0], TXEN, TXER invalid	2	—	ns
MII8	TXCLK to TXD[3:0], TXEN, TXER valid	—	25	ns



**Figure 20. MII transmit signal timing diagram**

### 6.8.3 USB DCD electrical specifications

Table 45. USB DCD electrical specifications

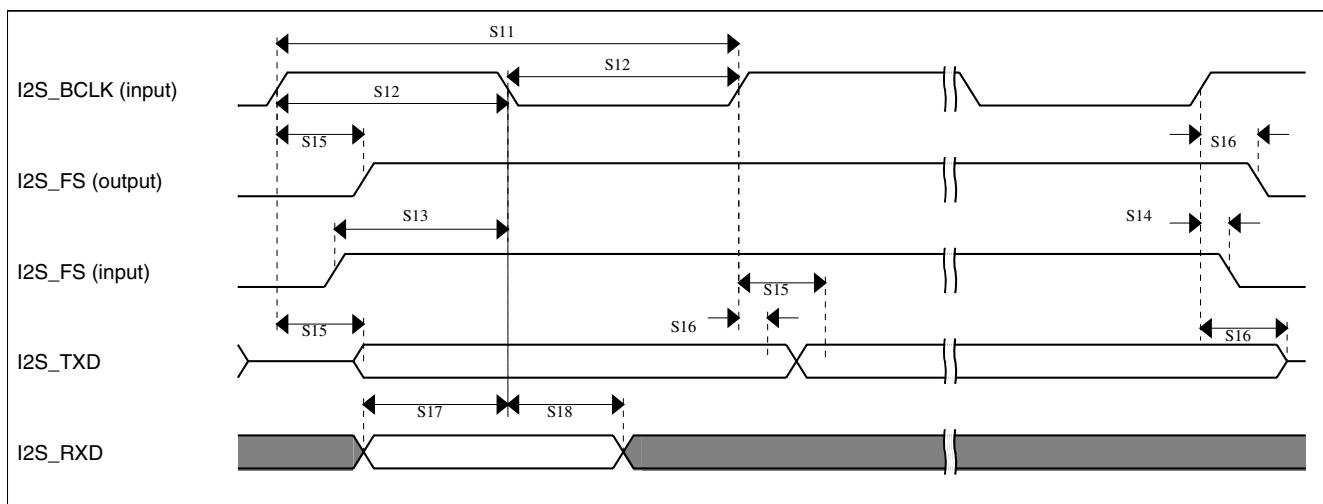
Symbol	Description	Min.	Typ.	Max.	Unit
V <sub>DP_SRC</sub>	USB_DP source voltage (up to 250 $\mu$ A)	0.5	—	0.7	V
V <sub>LGC</sub>	Threshold voltage for logic high	0.8	—	2.0	V
I <sub>DP_SRC</sub>	USB_DP source current	7	10	13	$\mu$ A
I <sub>DM_SINK</sub>	USB_DM sink current	50	100	150	$\mu$ A
R <sub>DM_DWN</sub>	D-pulldown resistance for data pin contact detect	14.25	—	24.8	k $\Omega$
V <sub>DAT_REF</sub>	Data detect voltage	0.25	0.33	0.4	V

### 6.8.4 USB VREG electrical specifications

Table 46. USB VREG electrical specifications

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
VREGIN	Input supply voltage	2.7	—	5.5	V	
I <sub>DDon</sub>	Quiescent current — Run mode, load current equal zero, input supply (VREGIN) > 3.6 V	—	120	186	$\mu$ A	
I <sub>DDstby</sub>	Quiescent current — Standby mode, load current equal zero	—	1.27	30	$\mu$ A	
I <sub>DDoff</sub>	Quiescent current — Shutdown mode <ul style="list-style-type: none"> <li>• VREGIN = 5.0 V and temperature=25 °C</li> <li>• Across operating voltage and temperature</li> </ul>	— —	650 —	— 4	nA $\mu$ A	
I <sub>LOADrun</sub>	Maximum load current — Run mode	—	—	120	mA	
I <sub>LOADstby</sub>	Maximum load current — Standby mode	—	—	1	mA	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) > 3.6 V <ul style="list-style-type: none"> <li>• Run mode</li> <li>• Standby mode</li> </ul>	3 2.1	3.3 2.8	3.6 3.6	V V	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) < 3.6 V, pass-through mode	2.1	—	3.6	V	<sup>2</sup>
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	$\mu$ F	
ESR	External output capacitor equivalent series resistance	1	—	100	m $\Omega$	
I <sub>LIM</sub>	Short circuit current	—	290	—	mA	

1. Typical values assume VREGIN = 5.0 V, Temp = 25 °C unless otherwise stated.
2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

**Figure 29. I<sup>2</sup>S timing — slave modes****Table 55. I<sup>2</sup>S master mode timing (full voltage range)**

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S1	I2S_MCLK cycle time	$2 \times t_{SYS}$		ns
S2	I2S_MCLK pulse width high/low	45%	55%	MCLK period
S3	I2S_BCLK cycle time	$5 \times t_{SYS}$	—	ns
S4	I2S_BCLK pulse width high/low	45%	55%	BCLK period
S5	I2S_BCLK to I2S_FS output valid	—	15	ns
S6	I2S_BCLK to I2S_FS output invalid	-4.3	—	ns
S7	I2S_BCLK to I2S_TXD valid	—	15	ns
S8	I2S_BCLK to I2S_TXD invalid	-4.6	—	ns
S9	I2S_RXD/I2S_FS input setup before I2S_BCLK	23.9	—	ns
S10	I2S_RXD/I2S_FS input hold after I2S_BCLK	0	—	ns

**Table 56. I<sup>2</sup>S slave mode timing (full voltage range)**

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S11	I2S_BCLK cycle time (input)	$8 \times t_{SYS}$	—	ns
S12	I2S_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_FS input setup before I2S_BCLK	10	—	ns
S14	I2S_FS input hold after I2S_BCLK	3.5	—	ns
S15	I2S_BCLK to I2S_TXD/I2S_FS output valid	—	28.6	ns
S16	I2S_BCLK to I2S_TXD/I2S_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_BCLK	10	—	ns
S18	I2S_RXD hold after I2S_BCLK	2	—	ns

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to [freescale.com](http://freescale.com) and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
144-pin LQFP	98ASS23177W
144-pin MAPBGA	98ASA00222D

## 8 Pinout

### 8.1 K52 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
—	C10	NC	NC	NC								
—	B10	NC	NC	NC								
—	A10	NC	NC	NC								
1	D3	PTE0	ADC1_SE4a	ADC1_SE4a	PTE0	SPI1_PCS1	UART1_TX	SDHC0_D1		I2C1_SDA		
2	D2	PTE1/ LLWU_P0	ADC1_SE5a	ADC1_SE5a	PTE1/ LLWU_P0	SPI1_SOUT	UART1_RX	SDHC0_D0		I2C1_SCL		
3	D1	PTE2/ LLWU_P1	ADC1_SE6a	ADC1_SE6a	PTE2/ LLWU_P1	SPI1_SCK	UART1_CTS_b	SDHC0_DCLK				
4	E4	PTE3	ADC1_SE7a	ADC1_SE7a	PTE3	SPI1_SIN	UART1_RTS_b	SDHC0_CMD				
5	E5	VDD	VDD	VDD								
6	F6	VSS	VSS	VSS								
7	E3	PTE4/ LLWU_P2	DISABLED		PTE4/ LLWU_P2	SPI1_PCS0	UART3_TX	SDHC0_D3				
8	E2	PTE5	DISABLED		PTE5	SPI1_PCS2	UART3_RX	SDHC0_D2				

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
82	H9	PTB1	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	PTB1	I2C0_SDA	FTM1_CH1	RMII0_MDC/ MII0_MDC		FTM1_QD_ PHB		
83	G12	PTB2	ADC0_SE12/ TSI0_CH7	ADC0_SE12/ TSI0_CH7	PTB2	I2C0_SCL	UART0_RTS_ b	ENET0_1588_ TMR0		FTM0_FLT3		
84	G11	PTB3	ADC0_SE13/ TSI0_CH8	ADC0_SE13/ TSI0_CH8	PTB3	I2C0_SDA	UART0_CTS_ b	ENET0_1588_ TMR1		FTM0_FLT0		
85	G10	PTB4	ADC1_SE10	ADC1_SE10	PTB4			ENET0_1588_ TMR2		FTM1_FLT0		
86	G9	PTB5	ADC1_SE11	ADC1_SE11	PTB5			ENET0_1588_ TMR3		FTM2_FLT0		
87	F12	PTB6	ADC1_SE12	ADC1_SE12	PTB6				FB_AD23			
88	F11	PTB7	ADC1_SE13	ADC1_SE13	PTB7				FB_AD22			
89	F10	PTB8			PTB8		UART3_RTS_ b		FB_AD21			
90	F9	PTB9			PTB9	SPI1_PCS1	UART3_CTS_ b		FB_AD20			
91	E12	PTB10	ADC1_SE14	ADC1_SE14	PTB10	SPI1_PCS0	UART3_RX		FB_AD19	FTM0_FLT1		
92	E11	PTB11	ADC1_SE15	ADC1_SE15	PTB11	SPI1_SCK	UART3_TX		FB_AD18	FTM0_FLT2		
93	H7	VSS	VSS	VSS								
94	F5	VDD	VDD	VDD								
95	E10	PTB16	TSI0_CH9	TSI0_CH9	PTB16	SPI1_SOUT	UART0_RX		FB_AD17	EWM_IN		
96	E9	PTB17	TSI0_CH10	TSI0_CH10	PTB17	SPI1_SIN	UART0_TX		FB_AD16	EWM_OUT_b		
97	D12	PTB18	TSI0_CH11	TSI0_CH11	PTB18		FTM2_CH0	I2S0_TX_ BCLK	FB_AD15	FTM2_QD_ PHA		
98	D11	PTB19	TSI0_CH12	TSI0_CH12	PTB19		FTM2_CH1	I2S0_TX_FS	FB_OE_b	FTM2_QD_ PHB		
99	D10	PTB20			PTB20	SPI2_PCS0			FB_AD31	CMP0_OUT		
100	D9	PTB21			PTB21	SPI2_SCK			FB_AD30	CMP1_OUT		
101	C12	PTB22			PTB22	SPI2_SOUT			FB_AD29	CMP2_OUT		
102	C11	PTB23			PTB23	SPI2_SIN	SPI0_PCS5		FB_AD28			
103	B12	PTC0	ADC0_SE14/ TSI0_CH13	ADC0_SE14/ TSI0_CH13	PTC0	SPI0_PCS4	PDB0_EXTRG	I2S0_TXD	FB_AD14			
104	B11	PTC1/ LLWU_P6	ADC0_SE15/ TSI0_CH14	ADC0_SE15/ TSI0_CH14	PTC1/ LLWU_P6	SPI0_PCS3	UART1_RTS_ b	FTM0_CH0	FB_AD13			
105	A12	PTC2	ADC0_SE4b/ CMP1_IN0/ TSI0_CH15	ADC0_SE4b/ CMP1_IN0/ TSI0_CH15	PTC2	SPI0_PCS2	UART1_CTS_ b	FTM0_CH1	FB_AD12			
106	A11	PTC3/ LLWU_P7	CMP1_IN1	CMP1_IN1	PTC3/ LLWU_P7	SPI0_PCS1	UART1_RX	FTM0_CH2	FB_CLKOUT			
107	H8	VSS	VSS	VSS								
108	—	VDD	VDD	VDD								
109	A9	PTC4/ LLWU_P8			PTC4/ LLWU_P8	SPI0_PCS0	UART1_TX	FTM0_CH3	FB_AD11	CMP1_OUT		

	1	2	3	4	5	6	7	8	9	10	11	12	
A	PTD7	PTD6	PTD5	PTD4	PTD0	PTC16	PTC12	PTC8	PTC4	NC	PTC3	PTC2	A
B	PTD12	PTD11	PTD10	PTD3	PTC19	PTC15	PTC11	PTC7	PTD9	NC	PTC1	PTC0	B
C	PTD15	PTD14	PTD13	PTD2	PTC18	PTC14	PTC10	PTC6	PTD8	NC	PTB23	PTB22	C
D	PTE2	PTE1	PTE0	PTD1	PTC17	PTC13	PTC9	PTC5	PTB21	PTB20	PTB19	PTB18	D
E	PTE6	PTE5	PTE4	PTE3	VDD	VDD	VDD	VDD	PTB17	PTB16	PTB11	PTB10	E
F	PTE10	PTE9	PTE8	PTE7	VDD	VSS	VSS	VDD	PTB9	PTB8	PTB7	PTB6	F
G	VOUT33	VREGIN	PTE12	PTE11	VREFH	VREFL	VSS	VSS	PTB5	PTB4	PTB3	PTB2	G
H	USB0_DP	USB0_DM	VSS	PTE28	VDDA	VSSA	VSS	VSS	PTB1	PTB0	PTA29	PTA28	H
J	ADC0_DP1/ OP0_DP0	ADC0_DM1/ OP0_DM0	ADC0_SE16/ OP0_OUT/ CMP1_IN2/ ADC0_SE21/ OP0_DP1/ OP1_DP1	DAC1_OUT/ CMP2_IN3/ ADC1_SE23/ OP0_DP5/ OP1_DP5	PTA0	PTA1	PTA6	PTA7	PTA13	PTA27	PTA26	PTA25	J
K	ADC1_DP1/ OP1_DP0/ OP1_DM1	ADC1_DM1/ OP1_DM0	ADC1_SE16/ OP1_OUT/ CMP2_IN0/ ADC0_SE22/ OP0_DP2/ OP1_DP2	DAC0_OUT/ CMP1_IN3/ ADC0_SE23/ OP0_DP4/ OP1_DP4	TRI1_OUT/ CMP2_IN5/ ADC1_SE22	PTA2	PTA3	PTA8	PTA12	PTA16	PTA17	PTA24	K
L	PGA0_DP/ ADC0_DP0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3	TRI0_OUT/ OP1_DM2	TRI0_DM	TRI1_DM	VBAT	PTA4	PTA9	PTA11	PTA14	PTA15	RESET_b	L
M	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DM/ ADC1_DM0/ ADC0_DM3	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE18	TRI0_DP	TRI1_DP	EXTAL32	XTAL32	PTA5	PTA10	VSS	PTA19	PTA18	M

Figure 31. K52 144 MAPBGA Pinout Diagram

## 9 Revision History

The following table provides a revision history for this document.

Table 58. Revision History

Rev. No.	Date	Substantial Changes
2	3/2011	Initial public revision

Table continues on the next page...