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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	18MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, LED, POR, WDT
Number of I/O	6
Program Memory Size	1KB (1K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	8-SO
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/p89lpc906fd-112

- Serial Flash In-Circuit Programming (ICP) allows simple production coding with commercial EPROM programmers. Flash security bits prevent reading of sensitive application programs.
- Watchdog timer with separate on-chip oscillator, requiring no external components. The watchdog prescaler is selectable from 8 values.
- Low voltage reset (Brownout detect) allows a graceful system shutdown when power fails. May optionally be configured as an interrupt.
- Idle and two different Power-down reduced power modes. Improved wake-up from Power-down mode (a low interrupt input starts execution). Typical Power-down current is 1 μA (total Power-down with voltage comparators disabled).
- Active-LOW reset. On-chip power-on reset allows operation without external reset components. A reset counter and reset glitch suppression circuitry prevent spurious and incomplete resets. A software reset function is also available.
- Configurable on-chip oscillator with frequency range options selected by user programmed Flash configuration bits. Oscillator options support frequencies from 20 kHz to the maximum operating frequency of 18 MHz (P89LPC906).
- Programmable port output configuration options: quasi-bidirectional, open drain, push-pull, input-only.
- Port ‘input pattern match’ detect. Port 0 may generate an interrupt when the value of the pins match or do not match a programmable pattern.
- LED drive capability (20 mA) on all port pins. A maximum limit is specified for the entire chip.
- Controlled slew rate port outputs to reduce EMI. Outputs have approximately 10 ns minimum ramp times.
- Only power and ground connections are required to operate the P89LPC906/907/908 when internal reset option is selected.
- Four interrupt priority levels.
- Three keypad interrupt inputs.
- Second data pointer.
- Schmitt trigger port inputs.
- Emulation support.

3. Ordering information

Table 1: Ordering information

Type number	Package		
	Name	Description	Version
P89LPC906FD	SO8	plastic small outline package; 8 leads; body width 7.5 mm	SOT96-1
P89LPC907FD			
P89LPC908FD			

3.1 Ordering options

Table 2: Part options

Type number	Temperature range	Frequency
P89LPC906FD	–40 °C to +85 °C	0 MHz to 18 MHz
P89LPC907FD		Internal RC or watchdog
P89LPC908FD		Internal RC or watchdog

4. Block diagram

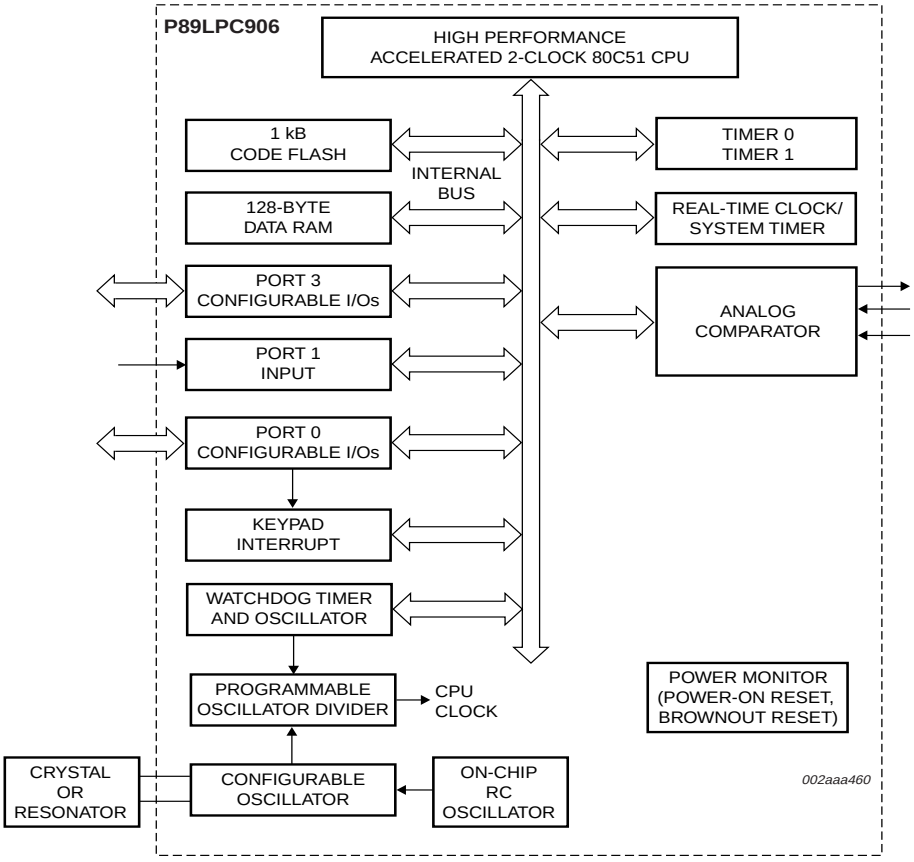


Fig 1. P89LPC906 block diagram.

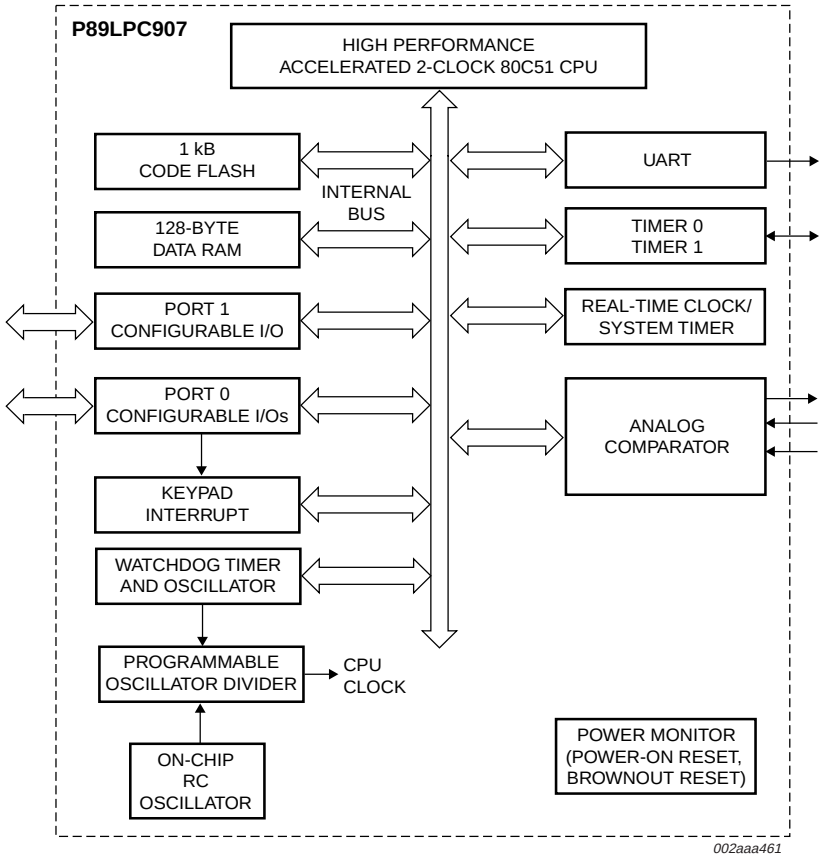


Fig 2. P89LPC907 block diagram.

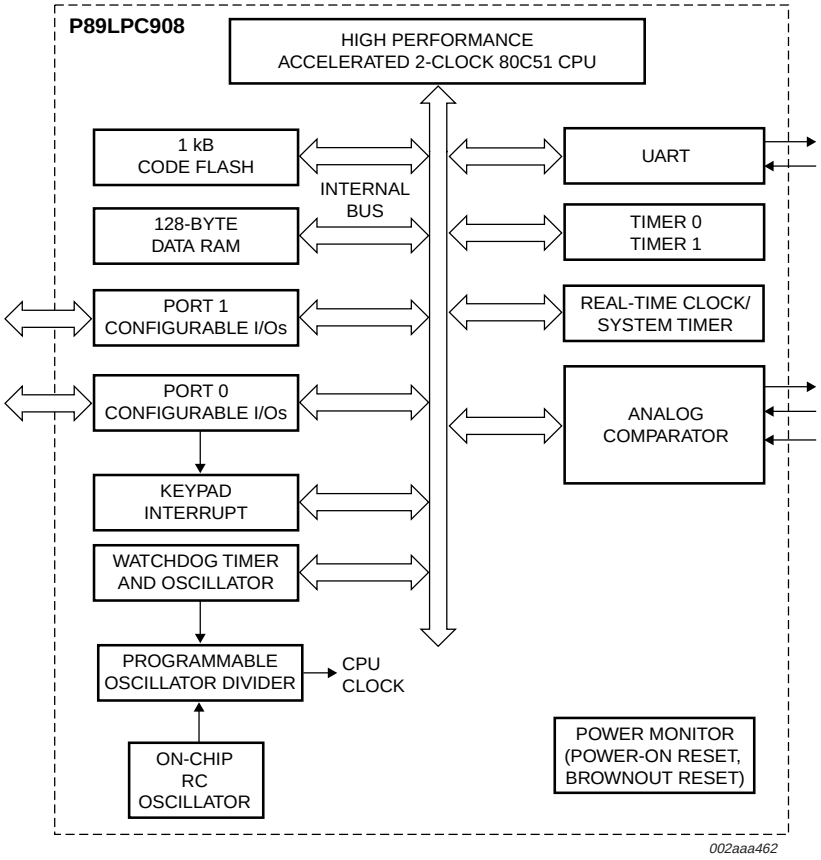


Fig 3. P89LPC908 block diagram.

5. Pinning information

5.1 Pinning

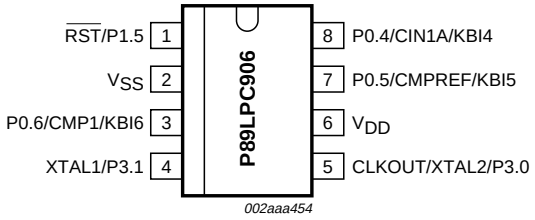


Fig 4. P89LPC906 pinning.

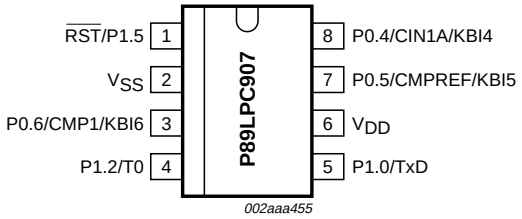


Fig 5. P89LPC907 pinning.

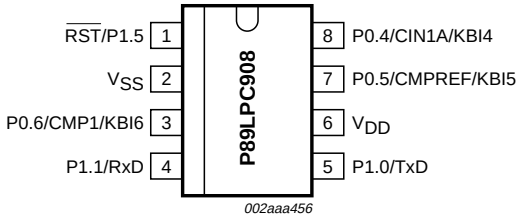


Fig 6. P89LPC908 pinning.

5.2 Pin description

Table 3: P89LPC906 pin description

Symbol	Pin	Type	Description
P0.4 to P0.6		I/O	**Port 0:** Port 0 is an I/O port with a user-configurable output types. During reset Port 0 latches are configured in the input only mode with the internal pull-up disabled. The operation of Port 0 pins as inputs and outputs depends upon the port configuration selected. Each port pin is configured independently. Refer to Section 8.11.1 “Port configurations” and Table 13 “DC electrical characteristics” for details. The Keypad Interrupt feature operates with Port 0 pins. All pins have Schmitt triggered inputs. Port 0 also provides various special functions as described below:
	8	I/O	**P0.4 —** Port 0 bit 4.
		I	**CIN1A —** Comparator positive input.
		I	**KBI4 —** Keyboard input 4.
	7	I/O	**P0.5 —** Port 0 bit 5.
		I	**CMPREF —** Comparator reference (negative) input.
		I	**KBI5 —** Keyboard input 5.
	3	I/O	**P0.6 —** Port 0 bit 6.
		O	**CMP1 —** Comparator 1 output.
		I	**KBI6 —** Keyboard input 6.
P1.5		I	**P1.5 —** Port 1 bit 5 (input only).
	1	I	**$\overline{\text{RST}}$ —** External Reset input during Power-on or if selected via UCFG1. When functioning as a reset input a LOW on this pin resets the microcontroller, causing I/O ports and peripherals to take on their default states, and the processor begins execution at address 0. Also used during a power-on sequence to force In-System Programming mode. **When using an oscillator frequency above 12 MHz, the reset input function of P1.5 must be enabled. An external circuit is required to hold the device in reset at power-up until V_{DD} has reached its specified level. When system power is removed V_{DD} will fall below the minimum specified operating voltage. When using an oscillator frequency above 12 MHz, in some applications, an external brownout detect circuit may be required to hold the device in reset when V_{DD} falls below the minimum specified operating voltage.**

Table 3: P89LPC906 pin description...*continued*

Symbol	Pin	Type	Description
P3.0 to P3.1		I/O	**Port 3:** Port 3 is an I/O port with a user-configurable output types. During reset Port 3 latches are configured in the input only mode with the internal pull-up disabled. The operation of port 3 pins as inputs and outputs depends upon the port configuration selected. Each port pin is configured independently. Refer to Section 8.11.1 "Port configurations" and Table 13 "DC electrical characteristics" for details. All pins have Schmitt triggered inputs. Port 3 also provides various special functions as described below:
	5	I/O	**P3.0 —** Port 3 bit 0.
		O	**XTAL2 —** Output from the oscillator amplifier (when a crystal oscillator option is selected via the FLASH configuration).
		O	**CLKOUT —** CPU clock divided by 2 when enabled via SFR bit (ENCLK to TRIM.6). It can be used if the CPU clock is the internal RC oscillator, Watchdog oscillator or external clock input, except when XTAL1/XTAL2 are used to generate clock source for the real time clock/system timer.
	4	I/O	**P3.1 —** Port 3 bit 1.
		I	**XTAL1 —** Input to the oscillator circuit and internal clock generator circuits (when selected via the FLASH configuration). It can be a port pin if internal RC oscillator or Watchdog oscillator is used as the CPU clock source, **and** if XTAL1/XTAL2 are not used to generate the clock for the real time clock/system timer.
V_{SS}	2	I	**Ground:** 0 V reference.
V_{DD}	6	I	**Power Supply:** This is the power supply voltage for normal operation as well as Idle and Power-down modes.

Table 4: P89LPC907 pin description

Symbol	Pin	Type	Description
P0.4 to P0.6		I/O	**Port 0:** Port 0 is an I/O port with a user-configurable output type. During reset Port 0 latches are configured in the input only mode with the internal pull-up disabled. The operation of Port 0 pins as inputs and outputs depends upon the port configuration selected. Each port pin is configured independently. Refer to Section 8.11.1 "Port configurations" and Table 13 "DC electrical characteristics" for details. The Keypad Interrupt feature operates with Port 0 pins. All pins have Schmitt triggered inputs. Port 0 also provides various special functions as described below:
	8	I/O	**P0.4 —** Port 0 bit 4.
		I	**CIN1A —** Comparator positive input.
		I	**KBI4 —** Keyboard input 4.
	7	I/O	**P0.5 —** Port 0 bit 5.
		I	**CMPREF —** Comparator reference (negative) input.
		I	**KBI5 —** Keyboard input 5.
	3	I/O	**P0.6 —** Port 0 bit 6.
		O	**CMP1 —** Comparator 1 output.
		I	**KBI6 —** Keyboard input 6.

Table 7: P89LPC906 Special function registers

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
		Bit address	E7	E6	E5	E4	E3	E2	E1	E0		
ACC*	Accumulator	E0H									00	00000000
AUXR1	Auxiliary function register	A2H	CLKLP	-	-	ENT0	SRST	0	-	DPS	00[1]	000000x0
		Bit address	F7	F6	F5	F4	F3	F2	F1	F0		
B*	B register	F0H									00	00000000
CMP1	Comparator 1 control register	ACH	-	-	CE1	-	CN1	OE1	CO1	CMF1	00[1]	xx000000
DIVM	CPU clock divide-by-M control	95H									00	00000000
DPTR	Data pointer (2 bytes)											
DPH	Data pointer high	83H									00	00000000
DPL	Data pointer low	82H									00	00000000
FMADRH	Program Flash address high	E7H									00	00000000
FMADRL	Program Flash address low	E6H									00	00000000
FMCON	Program Flash Control (Read)	E4H	BUSY	-	-	-	HVA	HVE	SV	OI	70	01110000
	Program Flash Control (Write)		FMCMD.7	FMCMD.6	FMCMD.5	FMCMD.4	FMCMD.3	FMCMD.2	FMCMD.1	FMCMD.0		
FMDATA	Program Flash data	E5H									00	00000000
IEN0*	Interrupt enable 0	A8H	EA	EWDRT	EBO	-	ET1	-	ET0	-	00	00000000
		Bit address	EF	EE	ED	EC	EB	EA	E9	E8		
IEN1*	Interrupt enable 1	E8H	-	-	-	-	-	EC	EKBI	-	00[1]	00x00000
		Bit address	BF	BE	BD	BC	BB	BA	B9	B8		
IP0*	Interrupt priority 0	B8H	-	PWDRT	PBO	-	PT1	-	PT0	-	00[1]	x0000000
IP0H	Interrupt priority 0 high	B7H	-	PWDRTH	PBOH	-	PT1H	-	PT0H	-	00[1]	x0000000
		Bit address	FF	FE	FD	FC	FB	FA	F9	F8		
IP1*	Interrupt priority 1	F8H	-	-	-	-	-	PC	PKBI	-	00[1]	00x00000
IP1H	Interrupt priority 1 high	F7H	-	-	-	-	-	PCH	PKBIH	-	00[1]	00x00000
KBCON	Keypad control register	94H	-	-	-	-	-	-	PATN_SEL	KBIF	00[1]	xxxxxx00

8. Functional description

Remark: Please refer to the *P89LPC906/907/908 User's Manual* for a more detailed functional description.

8.1 Enhanced CPU

The P89LPC906/907/908 uses an enhanced 80C51 CPU which runs at 6 times the speed of standard 80C51 devices. A machine cycle consists of two CPU clock cycles, and most instructions execute in one or two machine cycles.

8.2 Clocks

8.2.1 Clock definitions

The P89LPC906/907/908 device has several internal clocks as defined below:

OSCCLK — Input to the DIVM clock divider. OSCCLK is selected from one of the clock sources (see Figure 10 and 11) and can also be optionally divided to a slower frequency (see Section 8.7 "CPU CLOCK (CCLK) modification: DIVM register").

Note: f_{osc} is defined as the OSCCLK frequency.

CCLK — CPU clock; output of the clock divider. There are two CCLK cycles per machine cycle, and most instructions are executed in one to two machine cycles (two or four CCLK cycles).

RCCLK — The internal 7.373 MHz RC oscillator output.

PCLK — Clock for the various peripheral devices and is CCLK/2

8.2.2 CPU clock (OSCCLK)

The P89LPC906/907/908 provides several user-selectable oscillator options in generating the CPU clock. This allows optimization for a range of needs from high precision to lowest possible cost. These options are configured when the FLASH is programmed and include an on-chip Watchdog oscillator and an on-chip RC oscillator.

The P89LPC906, in addition, includes an option for an oscillator using an external crystal or an external clock source. The crystal oscillator can be optimized for low, medium, or high frequency crystals covering a range from 20 kHz to 12 MHz.

8.2.3 Low speed oscillator option (P89LPC906)

This option supports an external crystal in the range of 20 kHz to 100 kHz. Ceramic resonators are also supported in this configuration.

8.2.4 Medium speed oscillator option (P89LPC906)

This option supports an external crystal in the range of 100 kHz to 4 MHz. Ceramic resonators are also supported in this configuration.

8.2.5 High speed oscillator option (P89LPC906)

This option supports an external crystal in the range of 4 MHz to 18 MHz. Ceramic resonators are also supported in this configuration. **When using an oscillator frequency above 12 MHz, the reset input function of P1.5 must be enabled. An**

8.11.7 Additional port features

After power-up, all pins are in Input-Only mode. **Please note that this is different from the LPC76x series of devices.**

- After power-up all I/O pins, except P1.5, may be configured by software.
- Pin P1.5 is input only.

Every output on the P89LPC906/907/908 has been designed to sink typical LED drive current. However, there is a maximum total output current for all ports which must not be exceeded. Please refer to Table 13 “DC electrical characteristics” for detailed specifications.

All ports pins that can function as an output have slew rate controlled outputs to limit noise generated by quickly switching output signals. The slew rate is factory-set to approximately 10 ns rise and fall times.

8.12 Power monitoring functions

The P89LPC906/907/908 devices incorporate power monitoring functions designed to prevent incorrect operation during initial power-up and power loss or reduction during operation. This is accomplished with two hardware functions: Power-on Detect and Brownout detect.

8.12.1 Brownout detection

The Brownout detect function determines if the power supply voltage drops below a certain level. The default operation is for a Brownout detection to cause a processor reset, however, it may alternatively be configured to generate an interrupt.

Brownout detection may be enabled or disabled in software.

If Brownout detection is enabled, the brownout condition occurs when V_{DD} falls below the brownout trip voltage, V_{BO} (see Table 13 “DC electrical characteristics”), and is negated when V_{DD} rises above V_{BO}. If the P89LPC906/907/908 device is to operate with a power supply that can be below 2.7 V, BOE should be left in the unprogrammed state so that the device can operate at 2.4 V, otherwise continuous brownout reset may prevent the device from operating.

For correct activation of Brownout detect, the V_{DD} rise and fall times must be observed. Please see Table 13 “DC electrical characteristics” for specifications.

8.12.2 Power-on detection

The Power-on Detect has a function similar to the Brownout detect, but is designed to work as power comes up initially, before the power supply voltage reaches a level where Brownout detect can work. The POF flag in the RSTSRC register is set to indicate an initial power-up condition. The POF flag will remain set until cleared by software.

8.13 Power reduction modes

The P89LPC906/907/908 supports three different power reduction modes. These modes are Idle mode, Power-down mode, and total Power-down mode.

data is received, the 9th data bit goes into RB8 in Special Function Register SCON, while the stop bit is not saved. The baud rate is programmable to either $^1/_{16}$ or $^1/_{32}$ of the CPU clock frequency, as determined by the SMOD1 bit in PCON.

8.17.4 Mode 3

11 bits are transmitted (through TxD) or received (through RxD): a start bit (logical '0'), 8 data bits (LSB first), a programmable 9th data bit, and a stop bit (logical '1'). In fact, Mode 3 is the same as Mode 2 in all respects except baud rate. The baud rate in Mode 3 is variable and is determined by the Timer 1 overflow rate or the Baud Rate Generator (described in section Section 8.17.5 "Baud rate generator and selection").

8.17.5 Baud rate generator and selection

Both devices have an independent Baud Rate Generator. The baud rate is determined by a baud-rate preprogrammed into the BRGR1 and BRGR0 SFRs which together form a 16-bit baud rate divisor value that works in a similar manner as Timer 1. If the baud rate generator is used, Timer 1 can be used for other timing functions.

The UART can use either Timer 1 or the baud rate generator output (see Figure 15). Note that Timer T1 is further divided by 2 if the SMOD1 bit (PCON.7) is cleared. The independent Baud Rate Generator uses CCLK.

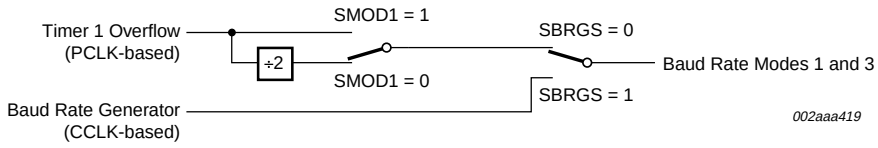


Fig 15. Baud rate sources for UART (Modes 1, 3).

8.17.6 Framing error

Framing error is reported in the status register (SSTAT). In addition, if SMOD0 (PCON.6) is '1', framing errors can be made available in SCON.7, respectively. If SMOD0 is '0', SCON.7 is SM0. It is recommended that SM0 and SM1 (SCON.7:6) are set up when SMOD0 is '0'.

8.17.7 Break detect

Break detect is reported in the status register (SSTAT). A break is detected when 11 consecutive bits are sensed LOW. The break detect can be used to reset the device.

8.17.8 Double buffering

The UART has a transmit double buffer that allows buffering of the next character to be written to SBUF while the first character is being transmitted. Double buffering allows transmission of a string of characters with only one stop bit between any two characters, as long as the next character is written between the start bit and the stop bit of the previous character.

Double buffering can be disabled. If disabled (DBMOD, i.e., SSTAT.7 = '0'), the UART is compatible with the conventional 80C51 UART. If enabled, the UART allows writing to SnBUF while the previous data is being shifted out. Double buffering is only allowed in Modes 1, 2 and 3. When operated in Mode 0, double buffering must be disabled (DBMOD = '0').

8.17.9 Transmit interrupts with double buffering enabled (Modes 1, 2 and 3)

Unlike the conventional UART, in double buffering mode, the Tx interrupt is generated when the double buffer is ready to receive new data.

8.17.10 The 9th bit (bit 8) in double buffering (Modes 1, 2 and 3)

If double buffering is disabled TB8 can be written before or after SBUF is written, as long as TB8 is updated some time before that bit is shifted out. TB8 must not be changed until the bit is shifted out, as indicated by the Tx interrupt.

If double buffering is enabled, TB8 **must** be updated before SBUF is written, as TB8 will be double-buffered together with SBUF data.

8.18 Analog comparator

An analog comparator is provided on the P89LPC906/907/908. Comparator operation is such that the output is a logical one (which may be read in a register) when the positive input is greater than the negative input (selectable from a pin or an internal reference voltage). Otherwise the output is a zero. The comparator may be configured to cause an interrupt when the output value changes.

The connections to the comparator are shown in Figure 16. The comparator functions to V_{DD} = 2.4 V.

When the comparator is first enabled, the comparator output and interrupt flag are not guaranteed to be stable for 10 microseconds. The comparator interrupt should not be enabled during that time, and the comparator interrupt flag must be cleared before the interrupt is enabled in order to prevent an immediate interrupt service.

When a comparator is disabled the comparator's output, COx, goes HIGH. If the comparator output was LOW and then is disabled, the resulting transition of the comparator output from a LOW to HIGH state will set the comparator flag, CMFx. This will cause an interrupt if the comparator interrupt is enabled. The user should therefore disable the comparator interrupt prior to disabling the comparator. Additionally, the user should clear the comparator flag, CMFx, after disabling the comparator.

8.19 Internal reference voltage

An internal reference voltage generator may supply a default reference when a single comparator input pin is used. The value of the internal reference voltage, referred to as V_{REF}, is 1.23 V ±10 %.

8.20 Comparator interrupt

Each comparator has an interrupt flag contained in its configuration register. This flag is set whenever the comparator output changes state. The flag may be polled by software or may be used to generate an interrupt.

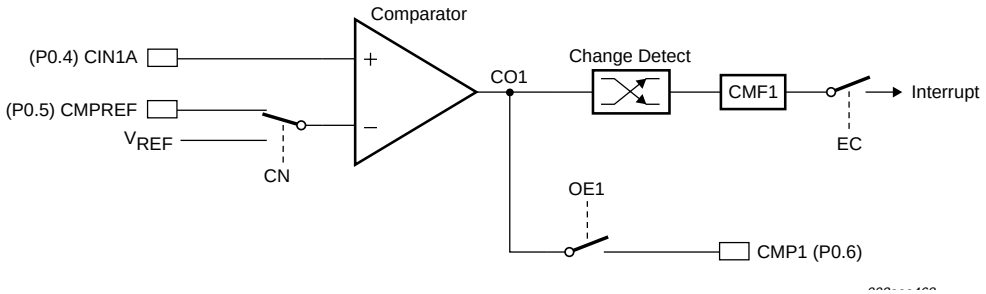


Fig 16. Comparator input and output connections.

8.21 Comparator and power reduction modes

The comparator may remain enabled when Power-down or Idle mode is activated, but the comparator is disabled automatically in Total Power-down mode.

If the comparator interrupt is enabled (except in Total Power-down mode), a change of the comparator output state will generate an interrupt and wake up the processor.

If the comparator output to a pin is enabled, the pin should be configured in the push-pull mode in order to obtain fast switching times while in Power-down mode. The reason is that with the oscillator stopped, the temporary strong pull-up that normally occurs during switching on a quasi-bidirectional port pin does not take place.

The comparator consumes power in Power-down and Idle modes, as well as in the normal operating mode. This fact should be taken into account when system power consumption is an issue. To minimize power consumption, the user can disable the comparator via PCONA.5 or put the device in Total Power-down mode.

8.22 Keypad interrupt (KBI)

The Keypad Interrupt function is intended primarily to allow a single interrupt to be generated when Port 0 is equal to or not equal to a certain pattern. This function can be used for bus address recognition or keypad recognition. The user can configure the port via SFRs for different tasks.

The Keypad Interrupt Mask Register (KBMASK) is used to define which input pins connected to Port 0 can trigger the interrupt. The Keypad Pattern Register (KBPATN) is used to define a pattern that is compared to the value of Port 0. The Keypad Interrupt Flag (KBIF) in the Keypad Interrupt Control Register (KBCON) is set when the condition is matched while the Keypad Interrupt function is active. An interrupt will be generated if enabled. The PATN_SEL bit in the Keypad Interrupt Control Register (KBCON) is used to define equal or not-equal for the comparison.

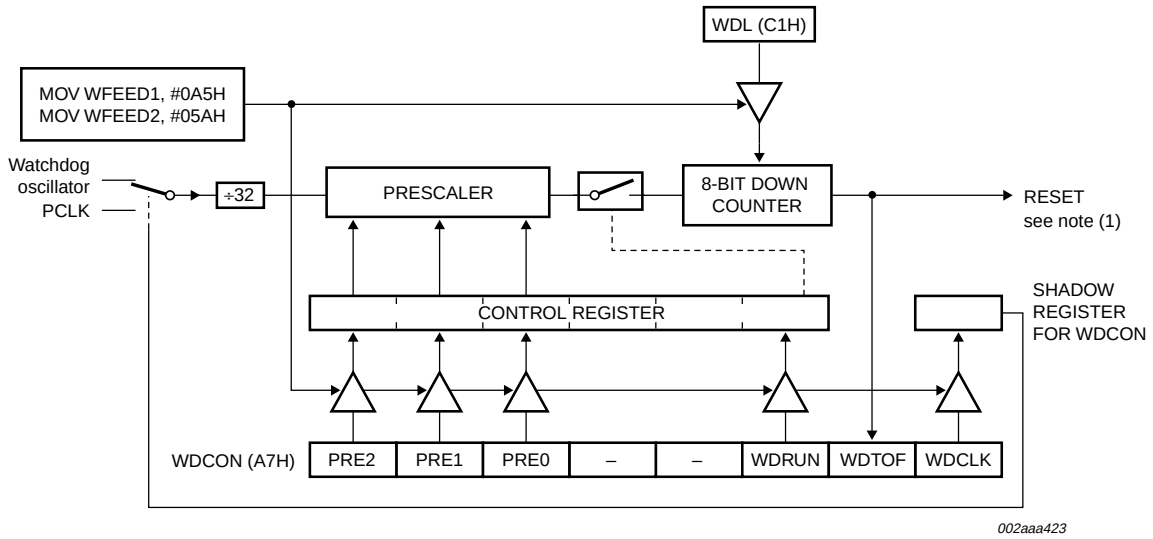
In order to use the Keypad Interrupt as an original KBI function like in 87LPC76x series, the user needs to set KBPATN = 0FFH and PATN_SEL = 1 (not equal), then any key connected to Port 0 which is enabled by the KBMASK register will cause the hardware to set KBIF and generate an interrupt if it has been enabled. The interrupt

may be used to wake up the CPU from Idle or Power down modes. This feature is particularly useful in handheld, battery powered systems that need to carefully manage power consumption yet also need to be convenient to use.

In order to set the flag and cause an interrupt, the pattern on Port 0 must be held longer than 6 CCLKs.

8.23 Watchdog timer

The watchdog timer causes a system reset when it underflows as a result of a failure to feed the timer prior to the timer reaching its terminal count. It consists of a programmable 12-bit prescaler, and an 8-bit down counter. The down counter is decremented by a tap taken from the prescaler. The clock source for the prescaler is either the PCLK or the nominal 400 kHz Watchdog oscillator. The watchdog timer can only be reset by a power-on reset. When the Watchdog feature is disabled, it can be used as an interval timer and may generate an interrupt. Figure 17 shows the watchdog timer in Watchdog mode. Feeding the Watchdog requires a two-byte sequence. If PCLK is selected as the Watchdog clock and the CPU is powered-down, the watchdog is disabled. The watchdog timer has a time-out period that ranges from a few µs to a few seconds. Please refer to the *P89LPC906/907/908 User's Manual* for more details.



(1) Watchdog reset can also be caused by an invalid feed sequence, or by writing to WDCON not immediately followed by a feed sequence.

Fig 17. Watchdog timer in Watchdog mode (WDTE = '1').

8.24 Additional features

8.24.1 Software reset

The SRST bit in AUXR1 gives software the opportunity to reset the processor completely, as if an external reset or Watchdog reset had occurred. Care should be taken when writing to AUXR1 to avoid accidental software resets.

data interface using a commercially available EPROM programmer which supports this device. This device does not provide for direct verification of code memory contents. Instead this device provides a 32-bit CRC result on either a sector or the entire 1 KB of user code space.

8.25.5 In-circuit programming (ICP)

In-Circuit Programming is performed without removing the microcontroller from the system. The In-Circuit Programming facility consists of internal hardware resources to facilitate remote programming of the P89LPC906/907/908 through a two-wire serial interface. The Philips In-Circuit Programming facility has made in-circuit programming in an embedded application, using commercially available programmers, possible with a minimum of additional expense in components and circuit board area. The ICP function uses five pins. Only a small connector (with V_{DD}, V_{SS}, RST, clock, and data signals) needs to be available to interface your application to a commercial programmer in order to use this feature. Additional details may be found in the *P89LPC906/907/908 User's Manual*.

8.25.6 In-application programming (IAP-Lite)

In-Application Programming is performed in the application under the control of the microcontroller's firmware. The IAP-Lite facility consists of internal hardware resources to facilitate programming and erasing. The Philips In-Application Programming Lite has made in-application programming in an embedded application possible without additional components. This is accomplished through the use of four SFRs consisting of a control/status register, a data register, and two address registers. Additional details may be found in the *P89LPC906/907/908 User's Manual*.

8.25.7 Using flash as data storage

The Flash code memory array of this device supports **individual** byte erasing and programming. Any byte in the code memory array may be read using the MOVC instruction, provided that the sector containing the byte has not been secured (a MOVC instruction is not allowed to read code memory contents of a secured sector). Thus any byte in a non-secured sector may be used for non-volatile data storage.

8.25.8 User configuration bytes

Some user-configurable features of the P89LPC906/907/908 must be defined at power-up and therefore cannot be set by the program after start of execution. These features are configured through the use of the Flash byte UCFG1. Please see the *P89LPC906/907/908 User's Manual* for additional details.

8.25.9 User sector security bytes

There are four User Sector Security Bytes, each corresponding to one sector. Please see the *P89LPC906/907/908 User's Manual* for additional details.

9. Limiting values

Table 12: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).[1]

Symbol	Parameter	Conditions	Min	Max	Unit
$T_{amb(bias)}$	operating bias ambient temperature		–55	+125	°C
T_{stg}	storage temperature range		–65	+150	°C
V_{xtal}	voltage on XTAL1, XTAL2 pin to V_{SS}, as applicable		-	V_{DD} + 0.5	V
V_n	voltage on any pin (except XTAL1, XTAL2) to V_{SS}		–0.5	+5.5	V
$I_{OH(I/O)}$	HIGH-level output current per I/O pin		-	8	mA
$I_{OL(I/O)}$	LOW-level output current per I/O pin		-	20	mA
$I_{I/O(tot)(max)}$	maximum total I/O current		-	120	mA
$P_{tot(pack)}$	total power dissipation per package	based on package heat transfer, not device power consumption	-	1.5	W

[1] The following applies to Limiting values:

a) Stresses above those listed under Table 12 may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any conditions other than those described in Table 13 “DC electrical characteristics”, Table 14 “AC characteristics” and Table 15 “AC characteristics (P89LPC906)” of this specification are not implied.

b) This product includes circuitry specifically designed for the protection of its internal devices from the damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying greater than the rated maximum.

c) Parameters are valid over operating temperature range unless otherwise specified. All voltages are with respect to V_{SS} unless otherwise noted.

10. Static characteristics

Table 13: DC electrical characteristics

V_{DD} = 2.4 V to 3.6 V unless otherwise specified.
T_{amb} = −40 °C to +85 °C for industrial, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ[1]	Max	Unit
$I_{DD(oper)}$	power supply current, operating (P89LPC906)	3.6 V; 12 MHz	[2]	-	11	18	mA
		3.6 V; 18 MHz	[2]	-	14	23	mA
$I_{DD(idle)}$	power supply current, Idle mode (P89LPC906)	3.6 V; 12 MHz	[2]	-	1	4	mA
		3.6 V; 18 MHz	[2]	-	1.5	5.6	mA
$I_{DD(oper)}$	power supply current, operating (P89LPC907, P89LPC908)	3.6 V; 7.373 MHz	[3]	-	4	8	mA
$I_{DD(idle)}$	power supply current, Idle mode (P89LPC907, P89LPC908)	3.6 V; 7.373 MHz	[3]	-	1	3	mA
$I_{DD(PD)}$	Power supply current, Power-down mode, voltage comparators powered-down	3.6 V	[2][3]	-	-	70	µA
$I_{DD(TPD)}$	Power supply current, Total Power-down mode	3.6 V	[2][3]	-	1	5	µA
$(dV_{DD}/dt)_r$	V_{DD} rise rate			-	-	2	mV/µs
$(dV_{DD}/dt)_f$	V_{DD} fall rate			-	-	50	mV/µs
V_{POR}	Power-on reset detect voltage			-	-	0.2	V
V_{RAM}	RAM keep-alive voltage			1.5	-	-	V
$V_{th(HL)}$	negative-going threshold voltage (Schmitt input)			$0.22V_{DD}$	$0.4V_{DD}$	-	V
$V_{th(LH)}$	positive-going threshold voltage (Schmitt input)			-	$0.6V_{DD}$	$0.7V_{DD}$	V
V_{hys}	hysteresis voltage			-	$0.2V_{DD}$	-	V
V_{OL}	LOW-level output voltage; all ports, all modes except Hi-Z	I_{OL} = 20 mA		-	0.6	1.0	V
		I_{OL} = 10 mA		-	0.3	0.5	V
		I_{OL} = 3.2 mA		-	0.2	0.3	V
V_{OH}	HIGH-level output voltage, all ports	I_{OH} = −8 mA; push-pull mode		V_{DD} − 0.1	-	-	V
		I_{OH} = −3.2 mA; push-pull mode		V_{DD} − 0.7	V_{DD} − 0.4	-	V
		I_{OH} = −20 µA; quasi-bidirectional mode		V_{DD} − 0.3	V_{DD} − 0.2	-	V
C_{ig}	input/output pin capacitance		[4]	-	-	15	pF
I_{IL}	logical 0 input current, all ports	V_{IN} = 0.4 V	[5]	-	-	−80	µA
I_{LI}	input leakage current, all ports	V_{IN} = V_{IL} or V_{IH}	[6]	-	-	±10	µA
I_{TL}	logical 1-to-0 transition current, all ports	V_{IN} = 2.0 V at V_{DD} = 3.6 V	[7][8]	−30	-	−450	µA
R_{RST}	internal reset pull-up resistor			10	-	30	kΩ

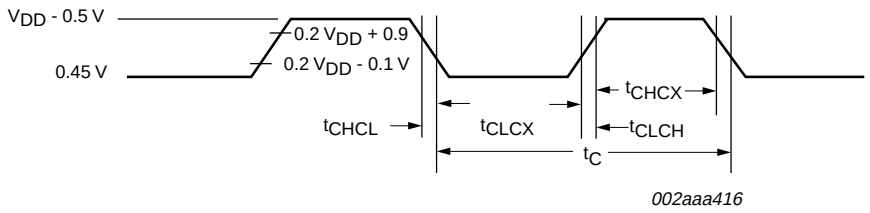


Fig 19. External clock timing.

12. Comparator electrical characteristics

Table 16: Comparator electrical characteristics

V_{DD} = 2.4 V to 3.6 V, unless otherwise specified.
T_{amb} = –40 °C to +85 °C for industrial, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{IO}	offset voltage comparator inputs			-	-	±20	mV
V_{CR}	common mode range comparator inputs			0	-	V_{DD} – 0.3	V
CMRR	common mode rejection ratio		[1]	-	-	–50	dB
	response time			-	250	500	ns
	comparator enable to output valid			-	-	10	µs
I_{IL}	input leakage current, comparator	$0 < V_{IN} < V_{DD}$		-	-	±10	µA

[1] This parameter is characterized, but not tested in production.

15. Data sheet status

Level	Data sheet status[1]	Product status[2][3]	Definition
I	Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
II	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
III	Product data	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Relevant changes will be communicated via a Customer Product/Process Change Notification (CPCN).

[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

16. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Contact information

For additional information, please visit **http://www.semiconductors.philips.com**.
For sales office addresses, send e-mail to: **sales.addresses@www.semiconductors.philips.com**. **Fax: +31 40 27 24825**

9397 750 14467