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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	7.3728MHz
Connectivity	UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, WDT
Number of I/O	6
Program Memory Size	1KB (1K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	8-SO
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/p89lpc907fd-112

Table 4: P89LPC907 pin description...*continued*

Symbol	Pin	Type	Description
P1.0 to P1.5			**Port 1:** Port 1 is an I/O port with a user-configurable output types. During reset Port 1 latches are configured in the input only mode with the internal pull-up disabled. The operation of the configurable Port 1 pins as inputs and outputs depends upon the port configuration selected. Each of the configurable port pins are programmed independently. Refer to Section 8.11.1 “Port configurations” and Table 13 “DC electrical characteristics” for details. P1.5 is input only. All pins have Schmitt triggered inputs. Port 1 also provides various special functions as described below:
	5	I/O	**P1.0 —** Port 1 bit 0.
		O	**TxD —** Serial port transmitter data.
	4	I/O	**P1.2 —** Port 1 bit 0.
		I/O	**T0 —** Timer 0 external clock input, toggle output, PWM output.
	1	I	**P1.5 —** Port 1 bit 5 (input only).
		I	**$\overline{\text{RST}}$ —** External Reset input during Power-on or if selected via UCFG1. When functioning as a reset input a LOW on this pin resets the microcontroller, causing I/O ports and peripherals to take on their default states, and the processor begins execution at address 0. Also used during a power-on sequence to force In-System Programming mode.
V_{SS}	2	I	**Ground:** 0 V reference.
V_{DD}	6	I	**Power Supply:** This is the power supply voltage for normal operation as well as Idle and Power-down modes.

Table 5: P89LPC908 pin description

Symbol	Pin	Type	Description
P0.4 to P0.6		I/O	**Port 0:** Port 0 is an I/O port with a user-configurable output types. During reset Port 0 latches are configured in the input only mode with the internal pull-up disabled. The operation of Port 0 pins as inputs and outputs depends upon the port configuration selected. Each port pin is configured independently. Refer to Section 8.11.1 “Port configurations” and Table 13 “DC electrical characteristics” for details. The Keypad Interrupt feature operates with Port 0 pins. All pins have Schmitt triggered inputs. Port 0 also provides various special functions as described below:
	8	I/O	**P0.4 —** Port 0 bit 4.
		I	**CIN1A —** Comparator positive input.
		I	**KBI4 —** Keyboard input 4.
	7	I/O	**P0.5 —** Port 0 bit 5.
		I	**CMPREF —** Comparator reference (negative) input.
		I	**KBI5 —** Keyboard input 5.
	3	I/O	**P0.6 —** Port 0 bit 6.
		O	**CMP1 —** Comparator 1 output.
		I	**KBI6 —** Keyboard input 6.

Table 5: P89LPC908 pin description...*continued*

Symbol	Pin	Type	Description
P1.0 to P1.5			**Port 1:** Port 1 is an I/O port with a user-configurable output types. During reset Port 1 latches are configured in the input only mode with the internal pull-up disabled. The operation of the configurable Port 1 pins as inputs and outputs depends upon the port configuration selected. Each of the configurable port pins are programmed independently. Refer to Section 8.11.1 "Port configurations" and Table 13 "DC electrical characteristics" for details. P1.5 is input only. All pins have Schmitt triggered inputs. Port 1 also provides various special functions as described below:
	5	I/O	**P1.0 —** Port 1 bit 0.
		O	**TxD —** Serial port transmitter data.
	4	I/O	**P1.1 —** Port 1 bit 1.
		I	**RxD —** Serial port receiver data.
	1	I	**P1.5 —** Port 1 bit 5 (input only).
		I	**$\overline{\text{RST}}$ —** External Reset input during Power-on or if selected via UCFG1. When functioning as a reset input a LOW on this pin resets the microcontroller, causing I/O ports and peripherals to take on their default states, and the processor begins execution at address 0. Also used during a power-on sequence to force In-System Programming mode.
V_{SS}	2	I	**Ground:** 0 V reference.
V_{DD}	6	I	**Power Supply:** This is the power supply voltage for normal operation as well as Idle and Power-down modes.

6. Logic symbols

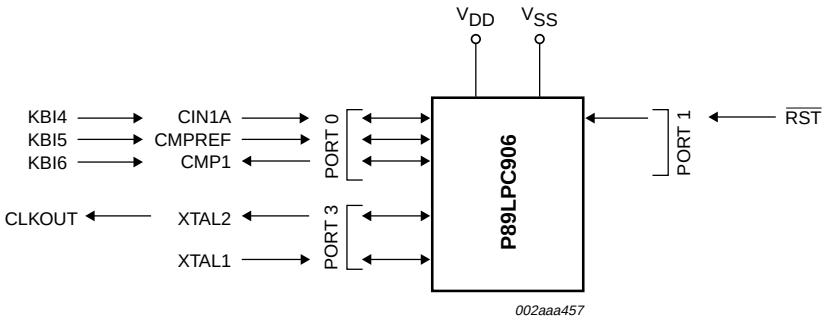


Fig 7. P89LPC906 logic symbol.

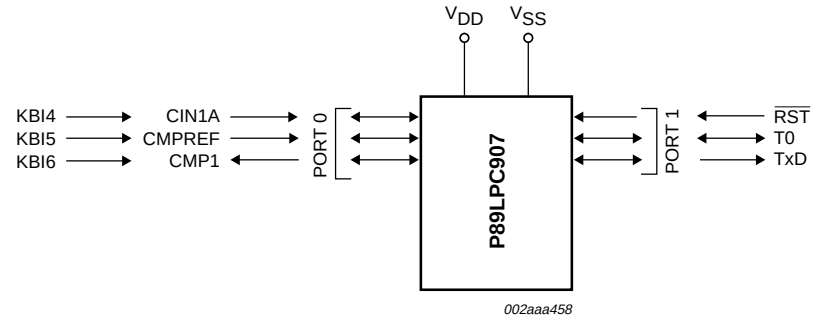


Fig 8. P89LPC907 logic symbol.

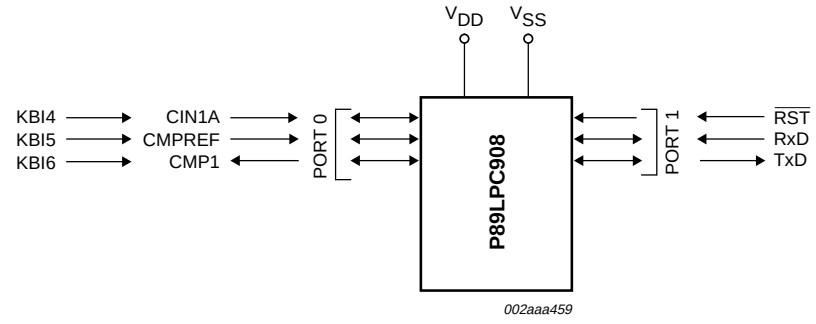


Fig 9. P89LPC908 logic symbol.

7. Special function registers

Remark: Special Function Registers (SFRs) accesses are restricted in the following ways:

- User must **not** attempt to access any SFR locations not defined.
- Accesses to any defined SFR locations must be strictly for the functions for the SFRs.
- SFR bits labeled '-', '0' or '1' can **only** be written and read as follows:
  - '-' Unless otherwise specified, **must** be written with '0', but can return any value when read (even if it was written with '0'). It is a reserved bit and may be used in future derivatives.
  - '0' **must** be written with '0', and will return a '0' when read.
  - '1' **must** be written with '1', and will return a '1' when read.

Table 7: P89LPC906 Special function registers

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
		Bit address	E7	E6	E5	E4	E3	E2	E1	E0		
ACC*	Accumulator	E0H									00	00000000
AUXR1	Auxiliary function register	A2H	CLKLP	-	-	ENT0	SRST	0	-	DPS	00[1]	000000x0
		Bit address	F7	F6	F5	F4	F3	F2	F1	F0		
B*	B register	F0H									00	00000000
CMP1	Comparator 1 control register	ACH	-	-	CE1	-	CN1	OE1	CO1	CMF1	00[1]	xx000000
DIVM	CPU clock divide-by-M control	95H									00	00000000
DPTR	Data pointer (2 bytes)											
DPH	Data pointer high	83H									00	00000000
DPL	Data pointer low	82H									00	00000000
FMADRH	Program Flash address high	E7H									00	00000000
FMADRL	Program Flash address low	E6H									00	00000000
FMCON	Program Flash Control (Read)	E4H	BUSY	-	-	-	HVA	HVE	SV	OI	70	01110000
	Program Flash Control (Write)		FMCMD.7	FMCMD.6	FMCMD.5	FMCMD.4	FMCMD.3	FMCMD.2	FMCMD.1	FMCMD.0		
FMDATA	Program Flash data	E5H									00	00000000
IEN0*	Interrupt enable 0	A8H	EA	EWDRT	EBO	-	ET1	-	ET0	-	00	00000000
		Bit address	EF	EE	ED	EC	EB	EA	E9	E8		
IEN1*	Interrupt enable 1	E8H	-	-	-	-	-	EC	EKBI	-	00[1]	00x00000
		Bit address	BF	BE	BD	BC	BB	BA	B9	B8		
IP0*	Interrupt priority 0	B8H	-	PWDRT	PBO	-	PT1	-	PT0	-	00[1]	x0000000
IP0H	Interrupt priority 0 high	B7H	-	PWDRTH	PBOH	-	PT1H	-	PT0H	-	00[1]	x0000000
		Bit address	FF	FE	FD	FC	FB	FA	F9	F8		
IP1*	Interrupt priority 1	F8H	-	-	-	-	-	PC	PKBI	-	00[1]	00x00000
IP1H	Interrupt priority 1 high	F7H	-	-	-	-	-	PCH	PKBIH	-	00[1]	00x00000
KBCON	Keypad control register	94H	-	-	-	-	-	-	PATN_SEL	KBIF	00[1]	xxxxxx00

Table 7: P89LPC906 Special function registers *...continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
TH0	Timer 0 high	8CH									00	00000000
TH1	Timer 1 high	8DH									00	00000000
TL0	Timer 0 low	8AH									00	00000000
TL1	Timer 1 low	8BH									00	00000000
TMOD	Timer 0 and 1 mode	89H	-	-	T1M1	T1M0	-	-	T0M1	T0M0	00	00000000
TRIM	Internal oscillator trim register	96H	-	ENCLK	TRIM.5	TRIM.4	TRIM.3	TRIM.2	TRIM.1	TRIM.0	[5] [6]	
WDCON	Watchdog control register	A7H	PRE2	PRE1	PRE0	-	-	WDRUN	WDTOF	WDCLK	[4] [6]	
WDL	Watchdog load	C1H									FF	11111111
WFEED1	Watchdog feed 1	C2H										
WFEED2	Watchdog feed 2	C3H										

[1] All ports are in input only (high impedance) state after power-up.

[2] BRGR1 and BRGR0 must only be written if BRGEN in BRGCON SFR is '0'. If any are written while BRGEN = 1, the result is unpredictable.

Unimplemented bits in SFRs (labeled '-') are X (unknown) at all times. Unless otherwise specified, ones should not be written to these bits since they may be used for other purposes in future derivatives. The reset values shown for these bits are '0's although they are unknown when read.

[3] The RSTSRC register reflects the cause of the P89LPC906/907/908 reset. Upon a power-up reset, all reset source flags are cleared except POF and BOF; the power-on reset value is xx110000.

[4] After reset, the value is 111001x1, i.e., PRE2-PRE0 are all '1', WDRUN = 1 and WDCLK = 1. WDTOF bit is '1' after Watchdog reset and is '0' after power-on reset. Other resets will not affect WDTOF.

[5] On power-on reset, the TRIM SFR is initialized with a factory preprogrammed value. Other resets will not cause initialization of the TRIM register.

[6] The only reset source that affects these SFRs is power-on reset.

9397 750 14467

Table 8: P89LPC907 Special function registers *...continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
SSTAT	Serial port extended status register	BAH	DBMOD	INTLO	CIDIS	DBISEL					00	00000000
SP	Stack pointer	81H									07	00000111
TAMOD	Timer 0 auxiliary mode	8FH	-	-	-	-	-	-	-	T0M2	00	xxx0xxx0
	Bit address		**8F**	**8E**	**8D**	**8C**	**8B**	**8A**	**89**	**88**		
TCON*	Timer 0 and 1 control	88H	TF1	TR1	TF0	TR0	-	-	-	-	00	00000000
TH0	Timer 0 high	8CH									00	00000000
TH1	Timer 1 high	8DH									00	00000000
TL0	Timer 0 low	8AH									00	00000000
TL1	Timer 1 low	8BH									00	00000000
TMOD	Timer 0 and 1 mode	89H	-	-	T1M1	T1M0	-	-	T0M1	T0M0	00	00000000
TRIM	Internal oscillator trim register	96H	-	-	TRIM.5	TRIM.4	TRIM.3	TRIM.2	TRIM.1	TRIM.0	[5] [6]	
WDCON	Watchdog control register	A7H	PRE2	PRE1	PRE0	-	-	WDRUN	WDTOF	WDCLK	[4] [6]	
WDL	Watchdog load	C1H									FF	11111111
WFEED1	Watchdog feed 1	C2H										
WFEED2	Watchdog feed 2	C3H										

[1] All ports are in input only (high impedance) state after power-up.

[2] BRGR1 and BRGR0 must only be written if BRGEN in BRGCON SFR is '0'. If any are written while BRGEN = 1, the result is unpredictable.

Unimplemented bits in SFRs (labeled '-') are X (unknown) at all times. Unless otherwise specified, ones should not be written to these bits since they may be used for other purposes in future derivatives. The reset values shown for these bits are '0's although they are unknown when read.

[3] The RSTSRC register reflects the cause of the P89LPC906/907/908 reset. Upon a power-up reset, all reset source flags are cleared except POF and BOF; the power-on reset value is xx110000.

[4] After reset, the value is 111001x1, i.e., PRE2-PRE0 are all '1', WDRUN = 1 and WDCLK = 1. WDTOF bit is '1' after Watchdog reset and is '0' after power-on reset. Other resets will not affect WDTOF.

[5] On power-on reset, the TRIM SFR is initialized with a factory preprogrammed value. Other resets will not cause initialization of the TRIM register.

[6] The only reset source that affects these SFRs is power-on reset.

9397 750 14467

Table 9: P89LPC908 Special function registers *...continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
IP1H	Interrupt priority 1 high	F7H	-	PSTH	-	-	-	PCH	PKBIH	-	00[1]	00x00000
KBCON	Keypad control register	94H	-	-	-	-	-	-	PATN_SEL	KBIF	00[1]	xxxxxx00
KBMASK	Keypad interrupt mask register	86H									00	00000000
KBPATN	Keypad pattern register	93H									FF	11111111
	Bit address		**87**	**86**	**85**	**84**	**83**	**82**	**81**	**80**		
P0*	Port 0	80H	-	CMP1 /KB6	CMPREF /KB5	CIN1A /KB4	-	KB2	-	-	[1]	
	Bit address		**97**	**96**	**95**	**94**	**93**	**92**	**91**	**90**		
P1*	Port 1	90H	-	-	$\overline{\text{RST}}$	-	-	-	RxD	TxD		
P0M1	Port 0 output mode 1	84H	-	(P0M1.6)	(P0M1.5)	(P0M1.4)	-	(P0M1.2)	-	-	FF	11111111
P0M2	Port 0 output mode 2	85H	-	(P0M2.6)	(P0M2.5)	(P0M2.4)	-	(P0M2.2)	-	-	00	00000000
P1M1	Port 1 output mode 1	91H	-	-	(P1M1.5)	-	-	-	(P1M1.1)	(P1M1.0)	FF[1]	11111111
P1M2	Port 1 output mode 2	92H	-	-	(P1M2.5)	-	-	-	(P1M2.1)	(P1M2.0)	00[1]	00000000
PCON	Power control register	87H	SMOD1	SMOD0	BOPD	BOI	GF1	GF0	PMOD1	PMOD0	00	00000000
PCONA	Power control register A	B5H	RTCPD		VCPD			-	SPD		00[1]	00000000
	Bit address		**D7**	**D6**	**D5**	**D4**	**D3**	**D2**	**D1**	**D0**		
PSW*	Program status word	D0H	CY	AC	F0	RS1	RS0	OV	F1	P	00	00000000
PT0AD	Port 0 digital input disable	F6H	-	-	PT0AD.5	PT0AD.4	-	PT0AD.2	-	-	00	xx00000x
RSTSRC	Reset source register	DFH	-	-	BOF	POF	R_BK	R_WD	R_SF	R_EX	[3]	
RTCCON	Real-time clock control	D1H	RTCF	RTCS1	RTCS0	-	-	-	ERTC	RTCEN	60[1] [6]	011xxx00
RTCH	Real-time clock register high	D2H									00[6]	00000000
RTCL	Real-time clock register low	D3H									00[6]	00000000
SADDR	Serial port address register	A9H									00	00000000
SADEN	Serial port address enable	B9H									00	00000000
SBUF	Serial port data buffer register	99H									xx	xxxxxxxx
	Bit address		**9F**	**9E**	**9D**	**9C**	**9B**	**9A**	**99**	**98**		
SCON*	Serial port control	98H	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI	00	00000000

Table 9: P89LPC908 Special function registers *...continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
SSTAT	Serial port extended status register	BAH	DBMOD	INTLO	CIDIS	DBISEL	FE	BR	OE	STINT	00	00000000
SP	Stack pointer	81H									07	00000111
	Bit address		8F	8E	8D	8C	8B	8A	89	88		
TCON*	Timer 0 and 1 control	88H	TF1	TR1	TF0	TR0	-	-	-	-	00	00000000
TH0	Timer 0 high	8CH									00	00000000
TH1	Timer 1 high	8DH									00	00000000
TL0	Timer 0 low	8AH									00	00000000
TL1	Timer 1 low	8BH									00	00000000
TMOD	Timer 0 and 1 mode	89H	-	-	T1M1	T1M0	-	-	T0M1	T0M0	00	00000000
TRIM	Internal oscillator trim register	96H	-	-	TRIM.5	TRIM.4	TRIM.3	TRIM.2	TRIM.1	TRIM.0	[5] [6]	
WDCON	Watchdog control register	A7H	PRE2	PRE1	PRE0	-	-	WDRUN	WDTOF	WDCLK	[4] [6]	
WDL	Watchdog load	C1H									FF	11111111
WFEED1	Watchdog feed 1	C2H										
WFEED2	Watchdog feed 2	C3H										

[1] All ports are in input only (high impedance) state after power-up.

[2] BRGR1 and BRGR0 must only be written if BRGEN in BRGCON SFR is '0'. If any are written while BRGEN = 1, the result is unpredictable.

Unimplemented bits in SFRs (labeled '-') are X (unknown) at all times. Unless otherwise specified, ones should not be written to these bits since they may be used for other purposes in future derivatives. The reset values shown for these bits are '0's although they are unknown when read.

[3] The RSTSRC register reflects the cause of the P89LPC906/907/908 reset. Upon a power-up reset, all reset source flags are cleared except POF and BOF; the power-on reset value is xx110000.

[4] After reset, the value is 111001x1, i.e., PRE2-PRE0 are all '1', WDRUN = 1 and WDCLK = 1. WDTOF bit is '1' after Watchdog reset and is '0' after power-on reset. Other resets will not affect WDTOF.

[5] On power-on reset, the TRIM SFR is initialized with a factory preprogrammed value. Other resets will not cause initialization of the TRIM register.

[6] The only reset source that affects these SFRs is power-on reset.

9397 750 14467

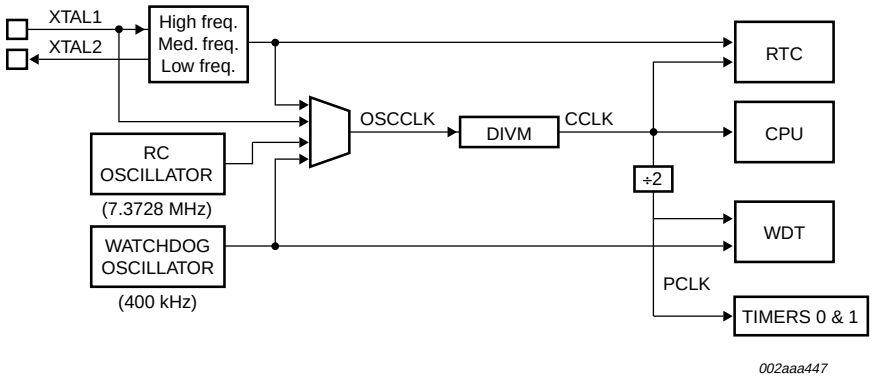


Fig 10. Block diagram of oscillator control (P89LPC906).

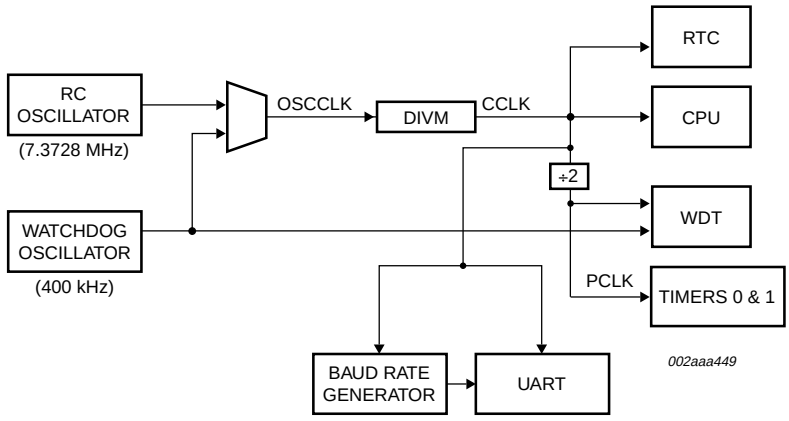


Fig 11. Block diagram of oscillator control (P89LPC907, P89LPC908).

8.6 CPU CLock (CCLK) wake-up delay

The P89LPC906/907/908 has an internal wake-up timer that delays the clock until it stabilizes depending to the clock source used. If the clock source is any of the three crystal selections (P89LPC906) the delay is 992 OSCCLK cycles plus 60 to 100 µs.

8.7 CPU CLOCK (CCLK) modification: DIVM register

The OSCCLK frequency can be divided down up to 510 times by configuring a dividing register, DIVM, to generate CCLK. This feature makes it possible to temporarily run the CPU at a lower rate, reducing power consumption. By dividing the clock, the CPU can retain the ability to respond to events that would not exit Idle mode by executing its normal program at a lower rate. This can also allow bypassing the oscillator start-up time in cases where Power-down mode would otherwise be used. The value of DIVM may be changed by the program at any time without interrupting code execution.

8.8 Low power select

The P89LPC906 is designed to run at 18 MHz (CCLK) maximum. However, if CCLK is 8 MHz or slower, the CLKLP SFR bit (AUXR1.7) can be set to ‘1’ to lower the power consumption further. On any reset, CLKLP is ‘0’ allowing highest performance access. This bit can then be set in software if CCLK is running at 8 MHz or slower.

8.9 Memory organization

The various P89LPC906/907/908 memory spaces are as follows:

- DATA

  128 bytes of internal data memory space (00h:7Fh) accessed via direct or indirect addressing, using instructions other than MOVX and MOVC. All or part of the Stack may be in this area.

- SFR

  Special Function Registers. Selected CPU registers and peripheral control and status registers, accessible only via direct addressing.

- CODE

  64 kB of Code memory space, accessed as part of program execution and via the MOVC instruction. The P89LPC906/907/908 has 1 kB of on-chip Code memory.

8.9.1 Data RAM arrangement

The 128 bytes of on-chip RAM is organized as follows:

Table 10: On-chip data memory usages

Type	Data RAM	Size (Bytes)
DATA	Memory that can be addressed directly and indirectly	128

8.10 Interrupts

The P89LPC906/907/908 uses a four priority level interrupt structure. This allows great flexibility in controlling the handling of the many interrupt sources.

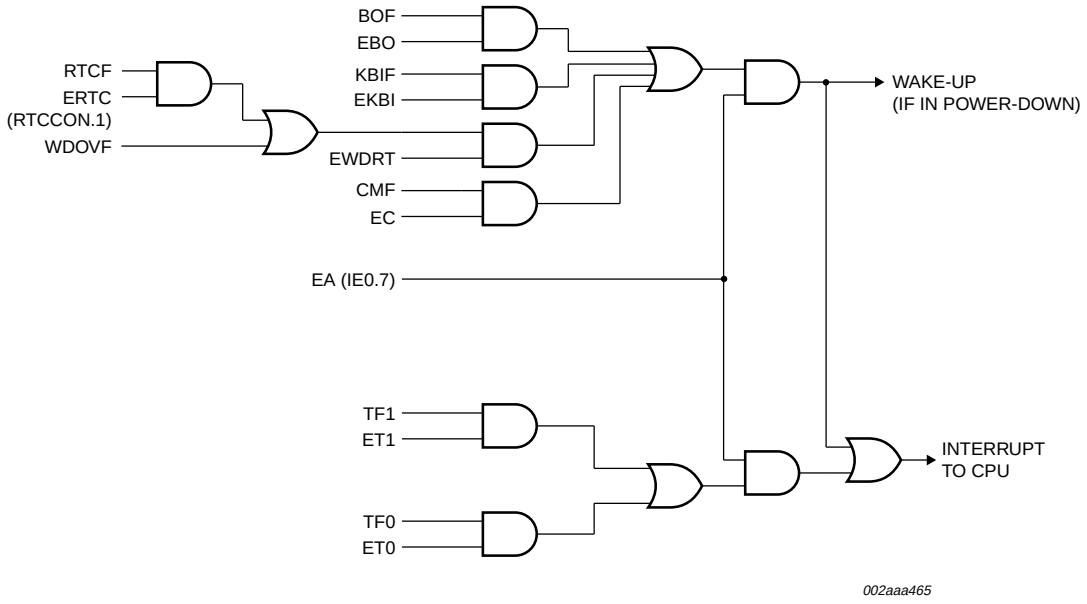


Fig 12. Interrupt sources, interrupt enables, and power-down wake-up sources (P89LPC906).

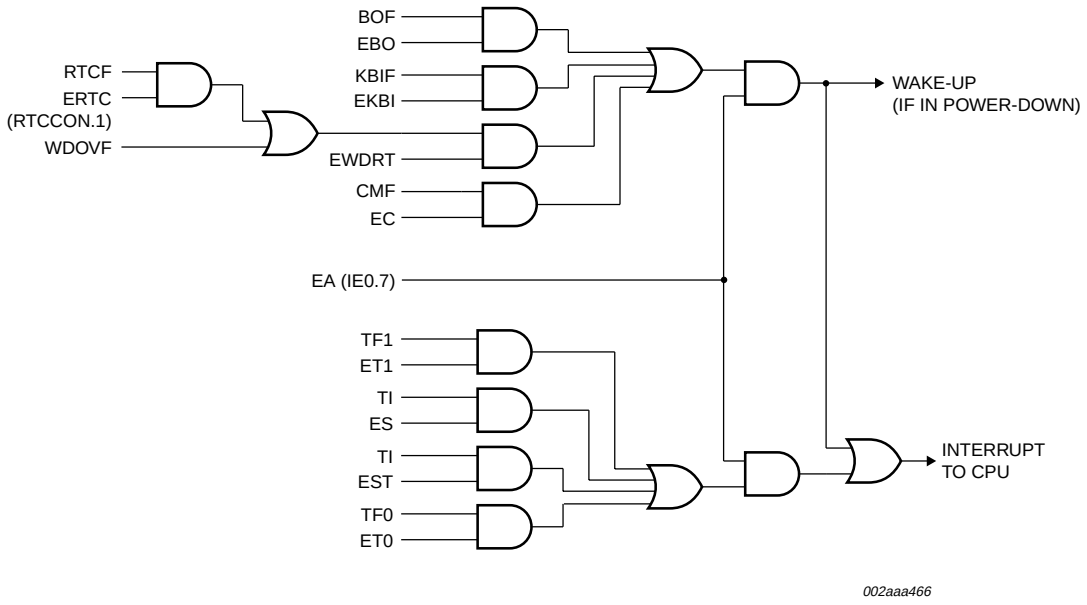


Fig 13. Interrupt sources, interrupt enables, and power-down wake-up sources (P89LPC907).

8.11.2 Quasi-bidirectional output configuration

Quasi-bidirectional output type can be used as both an input and output without the need to reconfigure the port. This is possible because when the port outputs a logic HIGH, it is weakly driven, allowing an external device to pull the pin LOW. When the pin is driven LOW, it is driven strongly and able to sink a fairly large current. These features are somewhat similar to an open-drain output except that there are three pull-up transistors in the quasi-bidirectional output that serve different purposes.

The P89LPC906/907/908 are 3 V devices, however, the pins are 5 V-tolerant (except for XTAL1 and XTAL2). In quasi-bidirectional mode, if a user applies 5 V on the pin, there will be a current flowing from the pin to V_{DD}, causing extra power consumption. Therefore, applying 5 V in quasi-bidirectional mode is discouraged.

A quasi-bidirectional port pin has a Schmitt-triggered input that also has a glitch suppression circuit.

8.11.3 Open-drain output configuration

The open-drain output configuration turns off all pull-ups and only drives the pull-down transistor of the port driver when the port latch contains a logic ‘0’. To be used as a logic output, a port configured in this manner must have an external pull-up, typically a resistor tied to V_{DD}.

An open-drain port pin has a Schmitt-triggered input that also has a glitch suppression circuit.

8.11.4 Input-only configuration

The input-only port configuration has no output drivers. It is a Schmitt-triggered input that also has a glitch suppression circuit.

8.11.5 Push-pull output configuration

The push-pull output configuration has the same pull-down structure as both the open-drain and the quasi-bidirectional output modes, but provides a continuous strong pull-up when the port latch contains a logic ‘1’. The push-pull mode may be used when more source current is needed from a port output. A push-pull port pin has a Schmitt-triggered input that also has a glitch suppression circuit.

8.11.6 Port 0 analog functions

The P89LPC906/907/908 incorporates an Analog Comparator. In order to give the best analog function performance and to minimize power consumption, pins that are being used for analog functions must have the digital outputs and digital inputs disabled.

Digital outputs are disabled by putting the port output into the Input-Only (high impedance) mode as described in Section 8.11.4 “Input-only configuration”.

Digital inputs on Port 0 may be disabled through the use of the PT0AD register. On any reset, the PT0AD bits default to ‘0’s to enable digital functions.

8.13.1 Idle mode

Idle mode leaves peripherals running in order to allow them to activate the processor when an interrupt is generated. Any enabled interrupt source or reset may terminate Idle mode.

8.13.2 Power-down mode

The Power-down mode stops the oscillator in order to minimize power consumption. The P89LPC906/907/908 exits Power-down mode via any reset, or certain interrupts. In Power-down mode, the power supply voltage may be reduced to the RAM keep-alive voltage V_{RAM}. This retains the RAM contents at the point where Power-down mode was entered. SFR contents are not guaranteed after V_{DD} has been lowered to V_{RAM}, therefore it is highly recommended to wake up the processor via reset in this case. V_{DD} must be raised to within the operating range before the Power-down mode is exited.

Some chip functions continue to operate and draw power during Power-down mode, increasing the total power used during Power-down. These include: Brownout detect, Watchdog Timer, Comparator (**Note**: Comparator can be powered-down separately), and Real-Time Clock (RTC)/System Timer. The internal RC oscillator is disabled unless both the RC oscillator has been selected as the system clock **and** the RTC is enabled.

8.13.3 Total Power-down mode

This is the same as Power-down mode except that the brownout detection circuitry and the voltage comparators are also disabled to conserve additional power. The internal RC oscillator is disabled unless both the RC oscillator has been selected as the system clock **and** the RTC is enabled. If the internal RC oscillator is used to clock the RTC during Power-down, there will be high power consumption. Please use an external low frequency clock to achieve low power with the Real-Time Clock running during Power-down.

8.14 Reset

The P1.5/$\overline{\text{RST}}$ pin can function as either an active-LOW reset input or as a digital input, P1.5. The RPE (Reset Pin Enable) bit in UCFG1, when set to ‘1’, enables the external reset input function on P1.5. When cleared, P1.5 may be used as an input pin.

Remark: During a power-up sequence, the RPE selection is overridden and this pin will always function as a reset input. **An external circuit connected to this pin should not hold this pin LOW during a power-on sequence as this will keep the device in reset.** After power-up this input will function either as an external reset input or as a digital input as defined by the RPE bit. Only a power-up reset will temporarily override the selection defined by RPE bit. Other sources of reset will not override the RPE bit.

Remark: During a power cycle, V_{DD} must fall below V_{POR} (see Table 13 “DC electrical characteristics”) before power is reapplied, in order to ensure a power-on reset.

8.15.6 Timer overflow toggle output (P89LPC907)

Timers 0 and 1 can be configured to automatically toggle a port output whenever a timer overflow occurs. The same device pins that are used for the T0 and T1 count inputs are also used for the timer toggle outputs. The port outputs will be a logic 1 prior to the first timer overflow when this mode is turned on.

8.16 Real-Time clock/system timer

The P89LPC906/907/908 has a simple Real-Time clock that allows a user to continue running an accurate timer while the rest of the device is powered-down. The Real-Time clock can be a wake-up or an interrupt source. The Real-Time clock is a 23-bit down counter comprised of a 7-bit prescaler and a 16-bit loadable down counter. When it reaches all ‘0’s, the counter will be reloaded again and the RTCF flag will be set. The clock source for this counter can be either the CPU clock (CCLK) or the XTAL oscillator, provided that the XTAL oscillator is not being used as the CPU clock. If the XTAL oscillator is used as the CPU clock, then the RTC will use CCLK as its clock source. Only power-on reset will reset the Real-Time clock and its associated SFRs to the default state.

8.17 UART (P89LPC908)

The P89LPC907 and P89LPC908 devices have an enhanced UART that is compatible with the conventional 80C51 UART except that Timer 2 overflow cannot be used as a baud rate source. The P89LPC907 does not have an RxD pin and thus receiver functions described in this section do not apply to the P89LPC907. Both devices include an independent Baud Rate Generator. The baud rate can be selected from the OSCCLK (divided by a constant), Timer 1 overflow, or the independent Baud Rate Generator. In addition to the baud rate generation, enhancements over the standard 80C51 UART include Framing Error detection, automatic address recognition, selectable double buffering and several interrupt options. The UART can be operated in 4 modes: shift register, 8-bit UART, 9-bit UART, and CCLK/32 or CCLK/16.

8.17.1 Mode 0

Serial data enters and exits through RxD. TxD outputs the shift clock. 8 bits are transmitted or received, LSB first. The baud rate is fixed at $\frac{1}{16}$ of the CPU clock frequency.

8.17.2 Mode 1

10 bits are transmitted (through TxD) or received (through RxD): a start bit (logical ‘0’), 8 data bits (LSB first), and a stop bit (logical ‘1’). When data is received, the stop bit is stored in RB8 in Special Function Register SCON. The baud rate is variable and is determined by the Timer 1 overflow rate or the Baud Rate Generator (described in Section 8.17.5 “Baud rate generator and selection”).

8.17.3 Mode 2

11 bits are transmitted (through TxD) or received (through RxD): start bit (logical ‘0’), 8 data bits (LSB first), a programmable 9th data bit, and a stop bit (logical ‘1’). When data is transmitted, the 9th data bit (TB8 in SCON) can be assigned the value of ‘0’ or ‘1’. Or, for example, the parity bit (P, in the PSW) could be moved into TB8. When

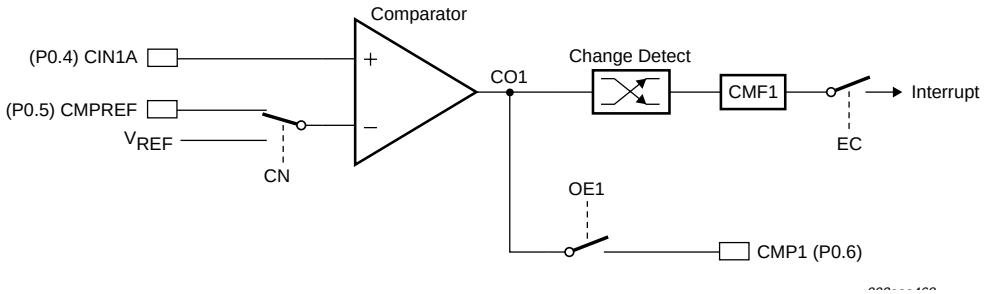


Fig 16. Comparator input and output connections.

8.21 Comparator and power reduction modes

The comparator may remain enabled when Power-down or Idle mode is activated, but the comparator is disabled automatically in Total Power-down mode.

If the comparator interrupt is enabled (except in Total Power-down mode), a change of the comparator output state will generate an interrupt and wake up the processor.

If the comparator output to a pin is enabled, the pin should be configured in the push-pull mode in order to obtain fast switching times while in Power-down mode. The reason is that with the oscillator stopped, the temporary strong pull-up that normally occurs during switching on a quasi-bidirectional port pin does not take place.

The comparator consumes power in Power-down and Idle modes, as well as in the normal operating mode. This fact should be taken into account when system power consumption is an issue. To minimize power consumption, the user can disable the comparator via PCONA.5 or put the device in Total Power-down mode.

8.22 Keypad interrupt (KBI)

The Keypad Interrupt function is intended primarily to allow a single interrupt to be generated when Port 0 is equal to or not equal to a certain pattern. This function can be used for bus address recognition or keypad recognition. The user can configure the port via SFRs for different tasks.

The Keypad Interrupt Mask Register (KBMASK) is used to define which input pins connected to Port 0 can trigger the interrupt. The Keypad Pattern Register (KBPATN) is used to define a pattern that is compared to the value of Port 0. The Keypad Interrupt Flag (KBIF) in the Keypad Interrupt Control Register (KBCON) is set when the condition is matched while the Keypad Interrupt function is active. An interrupt will be generated if enabled. The PATN_SEL bit in the Keypad Interrupt Control Register (KBCON) is used to define equal or not-equal for the comparison.

In order to use the Keypad Interrupt as an original KBI function like in 87LPC76x series, the user needs to set KBPATN = 0FFH and PATN_SEL = 1 (not equal), then any key connected to Port 0 which is enabled by the KBMASK register will cause the hardware to set KBIF and generate an interrupt if it has been enabled. The interrupt

10. Static characteristics

Table 13: DC electrical characteristics

V_{DD} = 2.4 V to 3.6 V unless otherwise specified.
T_{amb} = −40 °C to +85 °C for industrial, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ[1]	Max	Unit
$I_{DD(oper)}$	power supply current, operating (P89LPC906)	3.6 V; 12 MHz	[2]	-	11	18	mA
		3.6 V; 18 MHz	[2]	-	14	23	mA
$I_{DD(idle)}$	power supply current, Idle mode (P89LPC906)	3.6 V; 12 MHz	[2]	-	1	4	mA
		3.6 V; 18 MHz	[2]	-	1.5	5.6	mA
$I_{DD(oper)}$	power supply current, operating (P89LPC907, P89LPC908)	3.6 V; 7.373 MHz	[3]	-	4	8	mA
$I_{DD(idle)}$	power supply current, Idle mode (P89LPC907, P89LPC908)	3.6 V; 7.373 MHz	[3]	-	1	3	mA
$I_{DD(PD)}$	Power supply current, Power-down mode, voltage comparators powered-down	3.6 V	[2][3]	-	-	70	µA
$I_{DD(TPD)}$	Power supply current, Total Power-down mode	3.6 V	[2][3]	-	1	5	µA
$(dV_{DD}/dt)_r$	V_{DD} rise rate			-	-	2	mV/µs
$(dV_{DD}/dt)_f$	V_{DD} fall rate			-	-	50	mV/µs
V_{POR}	Power-on reset detect voltage			-	-	0.2	V
V_{RAM}	RAM keep-alive voltage			1.5	-	-	V
$V_{th(HL)}$	negative-going threshold voltage (Schmitt input)			$0.22V_{DD}$	$0.4V_{DD}$	-	V
$V_{th(LH)}$	positive-going threshold voltage (Schmitt input)			-	$0.6V_{DD}$	$0.7V_{DD}$	V
V_{hys}	hysteresis voltage			-	$0.2V_{DD}$	-	V
V_{OL}	LOW-level output voltage; all ports, all modes except Hi-Z	I_{OL} = 20 mA		-	0.6	1.0	V
		I_{OL} = 10 mA		-	0.3	0.5	V
		I_{OL} = 3.2 mA		-	0.2	0.3	V
V_{OH}	HIGH-level output voltage, all ports	I_{OH} = −8 mA; push-pull mode		V_{DD} − 0.1	-	-	V
		I_{OH} = −3.2 mA; push-pull mode		V_{DD} − 0.7	V_{DD} − 0.4	-	V
		I_{OH} = −20 µA; quasi-bidirectional mode		V_{DD} − 0.3	V_{DD} − 0.2	-	V
C_{ig}	input/output pin capacitance		[4]	-	-	15	pF
I_{IL}	logical 0 input current, all ports	V_{IN} = 0.4 V	[5]	-	-	−80	µA
I_{LI}	input leakage current, all ports	V_{IN} = V_{IL} or V_{IH}	[6]	-	-	±10	µA
I_{TL}	logical 1-to-0 transition current, all ports	V_{IN} = 2.0 V at V_{DD} = 3.6 V	[7][8]	−30	-	−450	µA
R_{RST}	internal reset pull-up resistor			10	-	30	kΩ

Table 15: AC characteristics (P89LPC906)

V_{DD} = 3.0 V to 3.6 V, unless otherwise specified.

T_{amb} = −40 °C to +85 °C for industrial, unless otherwise specified.[1]

Symbol	Parameter	Conditions	Variable clock		f_{osc} = 18 MHz		Unit
			Min	Max	Min	Max	
f_{RCOSC}	internal RC oscillator frequency (nominal f = 7.3728 MHz) trimmed to ±1 % at T_{amb} = 25 °C		7.189	7.557	7.189	7.557	MHz
f_{WDOSC}	internal Watchdog oscillator frequency (nominal f = 400 kHz)		320	520	320	520	kHz
Crystal oscillator							
f_{osc}	oscillator frequency	[2]	0	12	-	-	MHz
t_{CLCL}	clock cycle	see Figure 19	83	-	-	-	ns
f_{CLKP}	CLKLP active frequency		0	8	-	-	MHz
Glitch filter							
	glitch rejection, P1.5/$\overline{RST}$ pin		-	50	-	50	ns
	signal acceptance, P1.5/$\overline{RST}$ pin		125	-	125	-	ns
	glitch rejection, any pin except P1.5/$\overline{RST}$		-	15	-	15	ns
	signal acceptance, any pin except P1.5/$\overline{RST}$		50	-	50	-	ns
External clock							
t_{CHCX}	HIGH time	see Figure 19	22	$t_{CLCL} - t_{CLCX}$	22	-	ns
t_{CLCX}	LOW time	see Figure 19	22	$t_{CLCL} - t_{CHCX}$	22	-	ns
t_{CLCH}	rise time	see Figure 19	-	5	-	5	ns
t_{CHCL}	fall time	see Figure 19	-	5	-	5	ns

[1] Parameters are valid over operating temperature range unless otherwise specified. Parts are tested to 2 MHz, but are guaranteed to operate down to 0 Hz.

[2] When using an oscillator frequency above 12 MHz, the reset input function of P1.5 must be enabled. An external circuit is required to hold the device in reset at power-up until V_{DD} has reached its specified level. When system power is removed V_{DD} will fall below the minimum specified operating voltage. When using an oscillator frequency above 12 MHz, in some applications, an external brownout detect circuit may be required to hold the device in reset when V_{DD} falls below the minimum specified operating voltage.

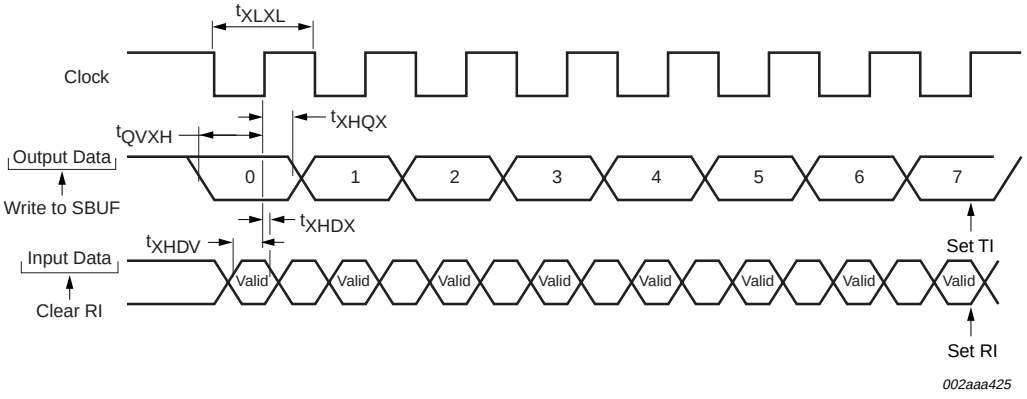
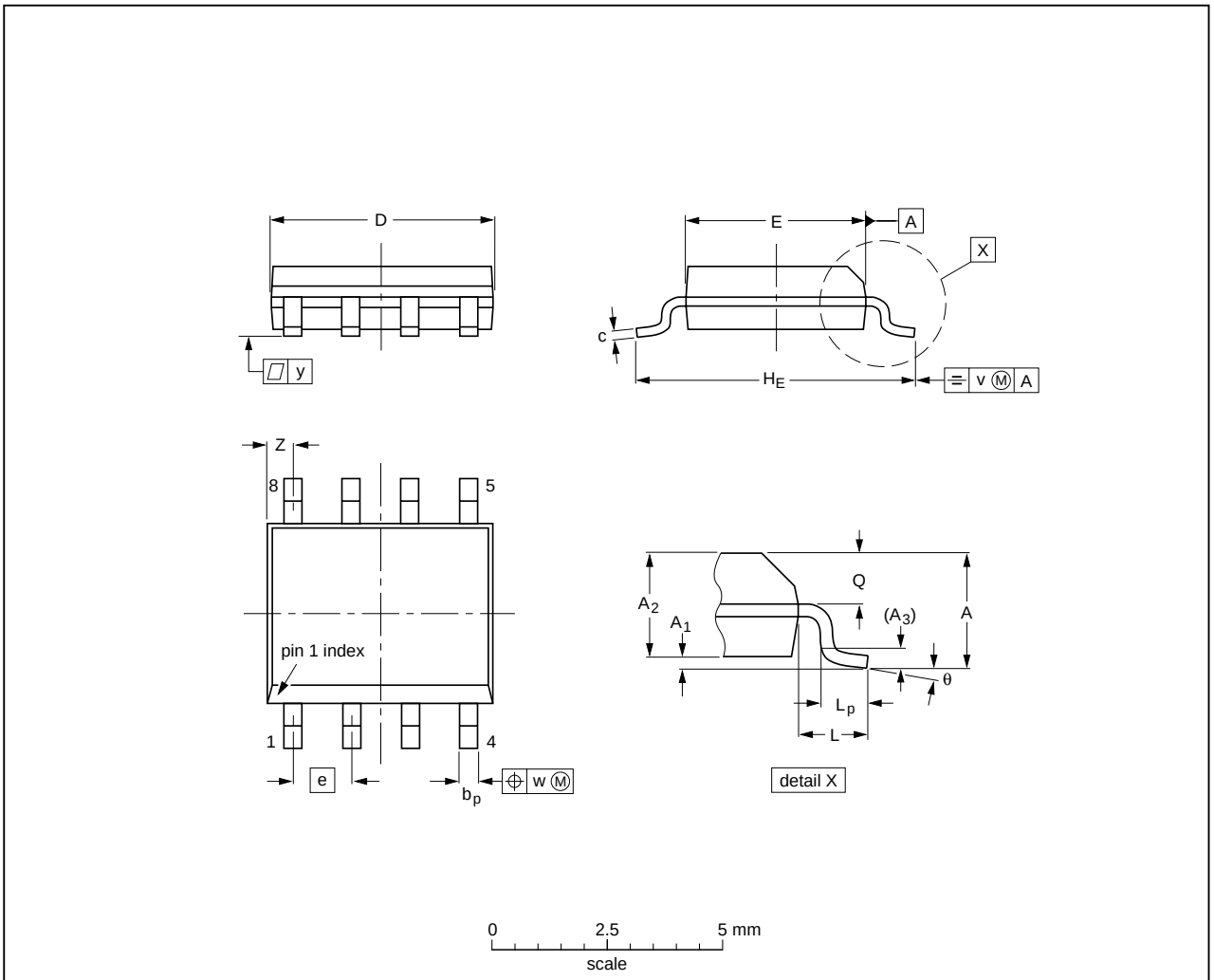


Fig 18. Shift register mode timing.

13. Package outline

SO8: plastic small outline package; 8 leads; body width 3.9 mm **SOT96-1**



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A_1	A_2	A_3	b_p	c	$D^{(1)}$	$E^{(2)}$	e	H_E	L	L_p	Q	v	w	y	$Z^{(1)}$	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8^o 0^o
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.20 0.19	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	

Notes

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.
2. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT96-1	076E03	MS-012				~~99-12-27~~ 03-02-18

Fig 20. SOT96-1 (SO8).

15. Data sheet status

Level	Data sheet status[1]	Product status[2][3]	Definition
I	Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
II	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
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[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

16. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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