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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Not For New Designs
Core Processor	-
Core Size	8-Bit
Speed	12MHz
Connectivity	SIO, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	71
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.5V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-30°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	80-BQFP
Supplier Device Package	80-QFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/onsemi/lc87f2c64au-qfp-h

■ Minimum Instruction Cycle Time

- 250ns (12MHz at V_{DD}=3.0 to 5.5V)
- 750ns (4MHz at V_{DD}=2.4 to 5.5V)

■ Temperature Range

- -30 to +70 degree Celsius

■ Ports

- Normal withstand voltage I/O ports
Ports I/O direction can be designated in 1-bit units 71 (P0n, P1n, P2n, P30 to P34, P70 to P73, P8n, PAn, PBn, PCn, Pen, XT2, CF2)
- Normal withstand voltage input port (Oscillator) 2 (XT1, CF1)
- Reset pin 1 (RES)
- Power pins 6 (VSS1 to VSS3, VDD1 to VDD3)

■ Timers

- Timer 0: 16-bit timer/counter with a capture register
 - Mode 0: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) × 2 channels
 - Mode 1: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) + 8-bit counter (with a 8-bit capture register)
 - Mode 2: 16-bit timer with an 8-bit programmable prescaler (with a 16-bit capture register)
 - Mode 3: 16-bit counter (with a 16-bit capture register)
- Timer 1: 16-bit timer/counter that supports PWM/toggle outputs
 - Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/counter with an 8-bit prescaler (with toggle outputs)
 - Mode 1: 8-bit PWM with an 8-bit prescaler × 2 channels
 - Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs) (toggle outputs also possible from the lower-order 8 bits)
 - Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs) (The lower-order 8 bits can be used as PWM.)
- Timer 4: 8-bit timer with a 6-bit prescaler
- Timer 5: 8-bit timer with a 6-bit prescaler
- Timer 6: 8-bit timer with a 6-bit prescaler (with toggle output)
- Timer 7: 8-bit timer with a 6-bit prescaler (with toggle output)
- Base timer
 - 1) The clock is selectable from the sub-clock (32.768kHz crystal oscillation/slow RC oscillation), system clock, and prescaler output from timer 0.
 - 2) Interrupts are programmable in 5 different time schemes.
- Real time clock (RTC)
 - 1) Used with a base timer, it can be used as a century + year + month + day + hour + minute + second counter.
 - 2) Calendar counts up to December 31, 2799 with automatic leap-year calculation.

■ High-speed Clock Counter

- Count clocks with a maximum clock rate of 24MHz (when main clock is 12MHz)
- Real-time output

■SIO

- SIO0: 8-bit synchronous serial interface
 - 1) LSB first/MSB first mode selectable
 - 2) Built-in 8-bit baud rate generator (maximum transfer clock cycle = $4/3$ tCYC)
 - 3) Automatic continuous data transmission (1 to 256 bits specifiable in 1 bit units, suspension and resumption of data transmission possible in 1 byte units)
 - 4) HOLD/X'tal HOLD mode release function by receiving 1-byte (8-bit clock)
- SIO1: 8-bit asynchronous/synchronous serial interface
 - Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
 - Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baud rates)
 - Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 TCYC transfer clocks)
 - Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

■UART: 2 channels

- Full duplex
- 7/8/9 bit data bits selectable
- 1 stop bit (2-bit in continuous data transmission)
- Built-in baudrate generator

■Remote Control Receiver Circuit

- Noise rejection function on P73/INT3/T0IN pin (noise rejection filter's time constant can be selected from 1, 32 or 128 tCYC.)

■AD Converter: 12 bits $\times$ 16 channels

- 12 bits/8 bits AD converter resolution selectable

■PWM: 4 channels

- Multi frequency 12-bit PWM

■Clock Output Function

- Output clock with a frequency $1/1$, $1/2$, $1/4$, $1/8$, $1/16$, $1/32$ or $1/64$ of the source clock of the system clock.
- Output clock of the sub-clock.

■Buzzer Output

- 2kHz or 4kHz buzzer output can be generated using base timer.

■Watchdog Timer

- Watchdog timer can generate interrupt or system reset.
- Two types of watchdog timers are available:
 - (1) External RC watchdog timer
 - (2) Base timer watchdog timer
- Watchdog timer with base timer can select only one period (1, 2, 4 or 8s) by the user option.
Once set the watchdog timer period and start the watchdog timer, the period is not changeable.

■Interrupts

- 28 sources, 10 vector addresses

- (1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
- (2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/INT4/T0L
4	0001BH	H or L	INT3/INT5/Base timer0/ Base timer1/RTC
5	00023H	H or L	T0H
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	SIO0/UART1 receive/UART2 receive
8	0003BH	H or L	SIO1/UART1 transmit/UART2 transmit
9	00043H	H or L	ADC/T6/T7/PWM4, 5/SPI
10	0004BH	H or L	Port0/T4/T5/PWM0, 1

- Priority levels $X > H > L$
- Of interrupts of the same level, the one with the smallest vector address takes precedence.
- IFLG (List of interrupt source flag function)
 - (1) Shows a list of interrupt source flags that caused a branching to a particular vector address (shown in the table above).

■Subroutine Stack Levels

- 1024 levels (Stack is allocated in RAM)

■High-speed Multiplication/Division Instructions

- 16 bits×8 bits (5 tCYC execution time)
- 24 bits×16 bits (12 tCYC execution time)
- 16 bits÷8 bits (8 tCYC execution time)
- 24 bits÷16 bits (12 tCYC execution time)

■Oscillation Circuits

- On-chip fast RC oscillation circuit : For system clock
- On-chip slow RC oscillation circuit : For system clock
- CF oscillation circuit : For system clock, with built in Rf
- Crystal oscillation circuit : For low-speed system clock
- On-chip Frequency variable RC oscillation circuit : For system clock
 - (1) Adjustable by $\pm 4\%$ (typical) step from selected center frequency
 - (2) Frequency measurable by referencing input signal from XT1

■System Clock Divider Function

- Enables low power consumption operation
- The minimum instruction cycle selectable from 250ns, 500ns, 1.0 μ s, 2.0 μ s, 4.0 μ s, 8.0 μ s, 16.0 μ s, 32.0 μ s, and 64 μ s (at a main clock rate of 12MHz).

■Internal Reset Function

- Power-on reset (POR) function
 - (1) POR reset is generated only at power-on.
 - (2) The POR release level can be selected through option configuration.
- Low-voltage detection reset (LVD) function
 - (1) LVD and POR functions are combined to generate resets when power is turned on and when power voltage falls below a certain level.
 - (2) The use/no-use of the LVD function and the low voltage threshold level can be selected through option configuration.

■ Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
 - (1) Oscillation is not halted automatically.
 - (2) There are three ways of resetting the HALT mode.
 - 1) Setting the reset pin to the lower level
 - 2) System resetting by watchdog timer
 - 3) Occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
 - (1) The CF, RC, crystal, and frequency variable RC oscillators automatically stop operation.
 - (2) There are five ways of resetting the HOLD mode.
 - 1) Setting the reset pin to the lower level
 - 2) System resetting by watchdog timer
 - 3) Setting at least one of the INT0, INT1, INT2, INT3, INT4, INT5 pins to the specified level
 - 4) Having an interrupt source established at port 0
 - 5) Having an interrupt source established in SPI receiving 1-byte (8-bit clock)
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer.
 - (1) The CF, RC, and frequency variable RC oscillators automatically stop operation.
 - (2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - (3) Power-save mode is available for even lower current consumption.
 - (4) There are seven ways of resetting the X'tal HOLD mode.
 - 1) Setting the reset pin to the low level
 - 2) System resetting by watchdog timer
 - 3) Setting at least one of the INT0, INT1, INT2, INT3, INT4, INT5 pins to the specified level
 - 4) Having an interrupt source established at port0
 - 5) Having an interrupt source established in the base timer circuit
 - 6) Having an interrupt source established in the RTC
 - 7) Having an interrupt source established in SPI receiving 1-byte (8-bit clock)

■ On-chip Debugging Function (flash ROM version)

- Supports software debugging with the test device installed on the target board.

■ Data Security Function (flash ROM version)

- Protects the program data stored in flash memory from unauthorized read or copy.
Note: The data security function does not necessarily provide an absolute data security.

■ Shipping form

- QFP80 (14×14): Lead-free type
- TQFP80J (12×12): Lead-free type

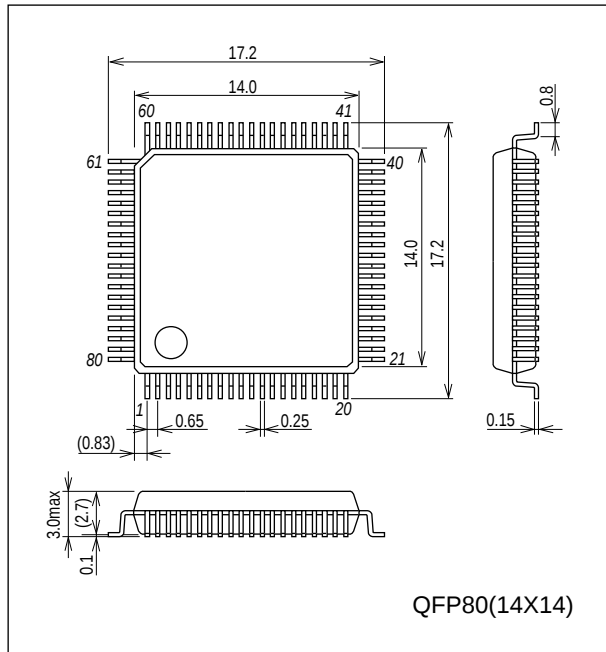
■ Development Tools

- On-chip-debugger: TCB87 TypeB + LC87F2C64A

Package Dimensions

unit : mm (typ)

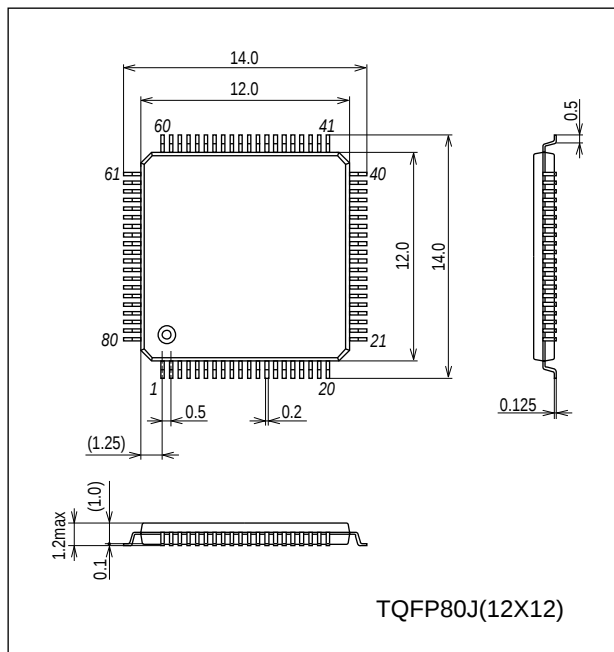
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Package Dimensions

unit : mm (typ)

3290



Pin Description

Pin Name	I/O	Description	Option																		
V _{SS} 1 to V _{SS} 3	-	- Power supply pin	No																		
V _{DD} 1 to V _{DD} 3	-	+ Power supply pin	No																		
V1	-	Open	No																		
VDC	-	Open	No																		
CUP1, CUP2	-	Open	No																		
PORT 0 P00 to P07	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. • HOLD release input • Port 0 interrupt input Other functions: P00: UART1 transmit P01: UART1 receive P02: UART2 transmit P03: UART2 receive P05: System clock output P06: Timer 6 toggle output P07: Timer 7 toggle output	Yes																		
PORT 1 P10 to P17	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: P10: SIO0 data output P11: SIO0 data input/bus I/O P12: SIO0 clock I/O P13: SIO1 data output P14: SIO1 data input/bus I/O P15: SIO1 clock I/O P16: Timer 1PWML output P17: Timer 1PWMH output/beeper output	Yes																		
PORT 2 P20 to P27	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: P20 to P23: INT4 input/HOLD release input/timer 1 event input /timer 0L capture input/timer 0H capture input P24 to P27: INT5 input/HOLD release input/timer 1 event input /timer 0L capture input/timer 0H capture input	Yes																		
		• Interrupt acknowledge type <table><tr><td></td><td>Rising</td><td>Falling</td><td>Rising & Falling</td><td>H level</td><td>L level</td></tr><tr><td>INT4</td><td>Yes</td><td>Yes</td><td>Yes</td><td>No</td><td>No</td></tr><tr><td>INT5</td><td>Yes</td><td>Yes</td><td>Yes</td><td>No</td><td>No</td></tr></table>		Rising	Falling	Rising & Falling	H level	L level	INT4	Yes	Yes	Yes	No	No	INT5	Yes	Yes	Yes	No	No	
	Rising	Falling	Rising & Falling	H level	L level																
INT4	Yes	Yes	Yes	No	No																
INT5	Yes	Yes	Yes	No	No																
PORT 3 P30 to P34	I/O	• 5-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: P30: PWM4 output P31: PWM5 output P32 (DBGP0) to P34 (DBGP2): On-chip-debugger port (Only on Flash version)	Yes																		

Continued on next page.

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Continued from preceding page.

Pin Name	I/O	Description	Option																														
PORT 7 P70 to P73	I/O	• 4-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: P70: INT0 input/HOLD release input/timer 0L capture input /watchdog timer output P71: INT1 input/HOLD release input/timer 0H capture input P72: INT2 input/HOLD release input/timer 0 event input /timer 0L capture input/high speed clock counter input P73: INT3 input (with noise filter)/ HOLD release input /timer 0 event input/timer 0H capture input • Interrupt acknowledge type <table><tr><td></td><td>Rising</td><td>Falling</td><td>Rising & Falling</td><td>H level</td><td>L level</td></tr><tr><td>INT0</td><td>Yes</td><td>Yes</td><td>No</td><td>Yes</td><td>Yes</td></tr><tr><td>INT1</td><td>Yes</td><td>Yes</td><td>No</td><td>Yes</td><td>Yes</td></tr><tr><td>INT2</td><td>Yes</td><td>Yes</td><td>Yes</td><td>No</td><td>No</td></tr><tr><td>INT3</td><td>Yes</td><td>Yes</td><td>Yes</td><td>No</td><td>No</td></tr></table>		Rising	Falling	Rising & Falling	H level	L level	INT0	Yes	Yes	No	Yes	Yes	INT1	Yes	Yes	No	Yes	Yes	INT2	Yes	Yes	Yes	No	No	INT3	Yes	Yes	Yes	No	No	No
	Rising	Falling	Rising & Falling	H level	L level																												
INT0	Yes	Yes	No	Yes	Yes																												
INT1	Yes	Yes	No	Yes	Yes																												
INT2	Yes	Yes	Yes	No	No																												
INT3	Yes	Yes	Yes	No	No																												
PORT 8 P80 to P87	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units Other functions: P80 to P87(AN0 to AN7): AD converter input	No																														
PORT A PA0 to PA7	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: PA0 to PA3: PWM0 output PA4 to PA7: PWM1 output	Yes																														
PORT B PB0 to PB7	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units. Other functions: PB0 to PB7 (AN8 to AN15): AD converter input	Yes																														
PORT C PC0 to PC7	I/O	• 8-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units.	Yes																														
PORT E PE0 to PE3	I/O	• 4-bit I/O port • I/O specifiable in 1 bit units • Pull-up resistors can be turned on and off in 1 bit units.	Yes																														
RES	I/O	External reset input pin/Internal reset output pin	No																														
XT1	I	• Input for 32.768kHz crystal oscillation Other functions: • General purpose input port *Connect to V _{DD1} when the port is not used.	No																														
XT2	I/O	• Output for 32.768kHz crystal oscillation Other functions: • General-purpose I/O port *Must be set for oscillation mode and kept open if not to be used.	No																														
CF1	I	• Input for ceramic resonator Other functions: • General purpose input port *Connect to V _{DD1} when the port is not used.	No																														
CF2	I/O	• Output for ceramic resonator Other functions: • General-purpose I/O port *Must be set for oscillation mode and kept open if not to be used.	No																														

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User Option Table

Option Name	Option to be Applied on	Mask-ROM Version*1	Flash-ROM Version	Option Selected in Units of	Option Selection
Port output type	P00 to P07	Yes	Yes	1 bit	CMOS
					Nch-open drain
	P10 to P17	Yes	Yes	1 bit	CMOS
					Nch-open drain
	P20 to P27	Yes	Yes	1 bit	CMOS
					Nch-open drain
	P30 to P34	Yes	Yes	1 bit	CMOS
					Nch-open drain
	PA0 to PA7	Yes	Yes	1 bit	CMOS
					Nch-open drain
	PB0 to PB7	Yes	Yes	1 bit	CMOS
					Nch-open drain
Program start address	-	No*2	Yes	-	0000H
					FE00H
Base timer Watchdog timer	Watchdog timer period	Yes	Yes	-	1s
					2s
					4s
					8s
Low-Voltage detect function	Detection level (Enable)	-	Yes	-	
	Power-on reset level (Disable)	-	Yes	-	

*1: The option selection cannot to be changed after the mask is created.

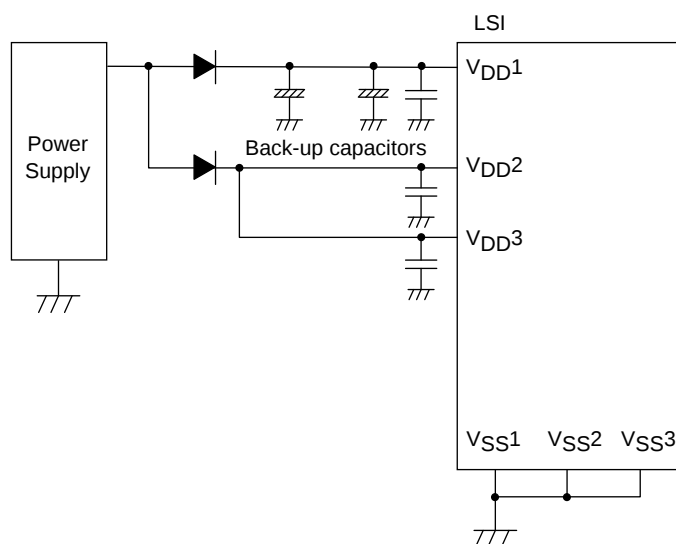
*2: Program start address for the mask-ROM version is 0000H.

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*Note1: Connect the IC as shown below to minimize the noise input to the V_{DD1} . Be sure to electrically short the V_{SS1} , V_{SS2} and V_{SS3} pins.

*Note2: The internal memory is sustained by V_{DD1} . If none of V_{DD2} and V_{DD3} are backed up, the high level output at the ports are unstable in the HOLD backup mode, allowing through current to flow into the input buffer and thus shortening the backup time. Make sure that the port outputs are held at the low level in the HOLD backup mode.

Example of power connection when power-save mode is used



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Absolute Maximum Ratings at Ta=25°C, VSS1=VSS2=VSS3=0V

Parameter		Symbol	Pin/Remarks	Conditions	Specification			
					VDD[V]	min	typ	max
Maximum supply voltage		VDD max	VDD1, VDD2, VDD3	• VDD1=VDD2=VDD3		-0.3		+6.5
Input voltage		VI	XT1, CF1, RES			-0.3		VDD+0.3
Input/output voltage		VIO	Ports 0, 1, 2, 3, 7, 8, A, B, C, E, XT2, CF2			-0.3		VDD+0.3
High level output current	Peak output current	IOPH(1)	Ports 0, 1, 2, 3, A, B, C, E	• CMOS output select • Per 1 applicable pin		-10		
		IOPH(2)	P71, P72, P73	• Per 1 applicable pin		-5		
	Mean output current (Note 1-1)	IOMH(1)	Ports 0, 1, 2, 3, A, B, C, E	• CMOS output select • Per 1 applicable pin		-7.5		
		IOMH(2)	P71, P72, P73	• Per 1 applicable pin		-3		
	Total output current	ΣIOAH(1)	Port 0, P14 to P17	• Total of all applicable pins		-25		
		ΣIOAH(2)	Port 3, A	• Total of all applicable pins		-25		
		ΣIOAH(3)	Port 0, 3, A P14 to P17	• Total of all applicable pins		-45		
		ΣIOAH(4)	Port 2 P10 to P13, PE3	• Total of all applicable pins		-25		
		ΣIOAH(5)	Port B, C, PE0 to PE2	• Total of all applicable pins		-25		
		ΣIOAH(6)	Port 2, B, C, E P10 to P13	• Total of all applicable pins		-45		
		ΣIOAH(7)	P71, P72, P73	• Total of all applicable pins		-5		
Low level output current	Peak output current	IOPL(1)	Ports 0, 1, 2, 3, A, B, C, E	• Per 1 applicable pin				20
		IOPL(2)	Port 7, 8 XT2, CF2	• Per 1 applicable pin				10
	Mean output current (Note 1-1)	IOML(1)	Ports 0, 1, 2, 3, A, B, C, E	• Per 1 applicable pin				15
		IOML(2)	Port 7, 8 XT2, CF2	• Per 1 applicable pin				7.5
	Total output current	ΣIOAL(1)	Port 0, P14 to P17	• Total of all applicable pins				45
		ΣIOAL(2)	Port 3, A	• Total of all applicable pins				45
		ΣIOAL(3)	Port 0, 3, A P14 to P17	• Total of all applicable pins				80
		ΣIOAL(4)	Port 2 P10 to P13, PE3	• Total of all applicable pins				45
		ΣIOAL(5)	Port B, C, PE0 to PE2	• Total of all applicable pins				45
		ΣIOAL(6)	Port 2, B, C, E P10 to P13	• Total of all applicable pins				80
		ΣIOAL(7)	Port 7, XT2	• Total of all applicable pins				15
		ΣIOAL(8)	Port 8, CF2	• Total of all applicable pins				15
		ΣIOAL(9)	Port 7, 8, XT2, CF2	• Total of all applicable pins				20
Power dissipation	Pd max(1)	QFP80		• Ta=-30 to +70°C • Package only				T.B.D
				• Ta=-30 to +70°C • Package with thermal resistance board (Note 1-2)				T.B.D
	Pd max(2)	TQFP80J		• Ta=-30 to +70°C • Package only				T.B.D
				• Ta=-30 to +70°C • Package with thermal resistance board (Note 1-2)				T.B.D
Operating ambient temperature	Topr					-30		+70
Storage ambient temperature	Tstg					-55		+125

Note 1-1: The mean output current is a mean value measured over 100ms.

Note 1-2: SEMI standards thermal resistance board (size: 76.1×114.3×1.6mm, glass epoxy) is used.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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Allowable Operating Conditions at Ta=-30 to +70°C, V_{SS1}=V_{SS2}=V_{SS3}=0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Operating supply voltage (Note 2-1)	V _{DD} (1)	V _{DD} 1=V _{DD} 2 =V _{DD} 3	• 0.245μs≤tCYC≤200μs		3.0		5.5	V
	V _{DD} (2)		• 0.735μs≤tCYC≤200μs		2.4		5.5	
Memory sustaining supply voltage	V _{HD}	V _{DD} 1	• RAM and register contents sustained in HOLD mode.		2.2		5.5	
High level input voltage	V _{IH} (1)	Ports 0, 1, 2, 3, 8, A, B, C, E, P71, P72, P73 P70 port input /interrupt side	• Output disabled	2.4 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (2)	Port 70 watchdog timer side	• Output disabled	2.4 to 5.5	0.9V _{DD}		V _{DD}	
	V _{IH} (3)	XT1, XT2, CF1, CF2, $\overline{\text{RES}}$		2.4 to 5.5	0.75V _{DD}		V _{DD}	
Low level input voltage	V _{IL} (1)	Ports 0, 1, 2, 3, 8, A, B, C, E, P71, P72, P73 P70 port input /interrupt side	• Output disabled	2.4 to 5.5	V _{SS}		0.1V _{DD} +0.4	
	V _{IL} (2)	Port 70 watchdog timer side	• Output disabled	2.4 to 5.5	V _{SS}		0.8V _{DD} -1.0	
	V _{IL} (3)	XT1, XT2, CF1, CF2, $\overline{\text{RES}}$		2.4 to 5.5	V _{SS}		0.25V _{DD}	
Instruction cycle time (Note 2-1)	tCYC (Note 2-2)			3.0 to 5.5	0.245		200	μs
				2.4 to 5.5	0.735		200	
External system clock frequency	FEXCF	CF1	• CF2 pin open	3.0 to 5.5	0.1		12	MHz
			• System clock frequency division ratio = 1/1					
			• External system clock duty = 50±5%	2.4 to 5.5	0.1		4	
			• CF2 pin open	3.0 to 5.5	0.2		24	
• System clock frequency division ratio = 1/2								
• External system clock duty = 50±5%	2.4 to 5.5	0.2		8				
Oscillation frequency range (Note 2-3)	FmCF(1)	CF1, CF2	• 12MHz ceramic oscillation • See Fig. 1.	3.0 to 5.5		12		MHz
	FmCF(2)	CF1, CF2	• 4MHz ceramic oscillation • See Fig. 1.	2.4 to 5.5		4		
	FmVMRC(1)		• Frequency variable RC source oscillation • VMRAJ2 to 0 = 4 • VMFAJ2 to 0 = 0 • VMSL4M = 0	3.0 to 5.5		10		
	FmVMRC(2)		• Frequency variable RC source oscillation • VMRAJ2 to 0 = 4 • VMFAJ2 to 0 = 0 • VMSL4M=1	2.4 to 5.5		4		
	FmRC		• Internal fast RC oscillation	2.4 to 5.5		500		kHz
	FsRC		• Internal slow RC oscillation	2.4 to 5.5		50		
	FsX'tal	XT1, XT2	• 32.768kHz crystal oscillation • See Fig. 2.	2.4 to 5.5		32.768		

Note 2-1: V_{DD} must be held greater than or equal to 3.0V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Note 2-3: See Table 1, 2 for the oscillation constants

Continued on next page.

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Serial I/O Characteristics at Ta=-30 to +70°C, V_{SS1}=V_{SS2}=V_{SS3}=0V

1. SIO0 Serial I/O Characteristics (Note 4-1-1)

Parameter			Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification			
							min	typ	max	unit
Serial clock	Input clock	Frequency	tSCK(1)	SCK0(P12)	See Fig. 6.	2.4 to 5.5	2			tCYC
		Low level pulse width	tSCKL(1)				1			
		High level pulse width	tSCKH(1)				1			
			tSCKHA(1)				4			
	Output clock	Frequency	tSCK(2)	SCK0(P12)	- CMOS output selected - See Fig. 6.	2.4 to 5.5	4/3			tSCK
		Low level pulse width	tSCKL(2)				1/2			
		High level pulse width	tSCKH(2)				1/2			
			tSCKHA(2)				tSCKH(2) +2tCYC		tSCKH(2) +(10/3) tCYC	
Serial input	Data setup time		tsDI	SB0(P11), SIO(P11)	- Must be specified with respect to rising edge of SIOCLK. - See Fig. 6.	2.4 to 5.5	0.03			
	Data hold time		thDI				0.03			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	- Continuous data transmission/reception mode (Note 4-1-3)	2.4 to 5.5			(1/3)tCYC +0.05	μs
			tdD0(2)		- Synchronous 8-bit mode (Note 4-1-3)				1tCYC +0.05	
	Output clock		tdD0(3)		(Note 4-1-3)				(1/3)tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: When using serial clock input under continuous data transmission/reception mode, the time from SIO₀RUN is set while serial clock is “H” to the first falling edge of serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 6.

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2. SIO1 Serial I/O Characteristics (Note 4-2-1)

Parameter			Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification			
							min	typ	max	unit
Serial clock	Input clock	Frequency	tSCK(3)	SCK1(P15)	• See Fig. 6.	2.4 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
	Output clock	Frequency	tSCK(4)	SCK1(P15)	• CMOS output selected • See Fig. 6.	2.4 to 5.5	2			tSCK
		Low level pulse width	tSCKL(4)				1/2			
		High level pulse width	tSCKH(4)				1/2			
Serial input	Data setup time		tsDI(2)	SB1(P14), SI1(P14)	• Must be specified with respect to rising edge of SIOCLK. • See Fig. 6.	2.4 to 5.5	0.03			
	Data hold time		thDI(2)				0.03			
Serial output	Output delay time		tdD0(4)	SO1(P13), SB1(P14)	• Must be specified with respect to falling edge of SIOCLK. • Must be specified as the time to the beginning of output state change in open drain output mode. • See Fig. 6.	2.4 to 5.5			(1/3)tCYC +0.05	μs

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Pulse Input Conditions at Ta=-30 to +70°C, V_{SS1}=V_{SS2}=V_{SS3}=0V

Parameter		Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification			
						min	typ	max	unit
High/low level pulse width	tPIH(1) tPIL(1)		INT0(P70) INT1(P71) INT2(P72) INT3(P73) INT4(P20 to P23) INT5(P24 to P27)	• Interrupt source flag can be set. • Event inputs for timer 0 or 1 are enabled.	2.4 to 5.5	1			tCYC
	tPIH(2) tPIL(2)		INT3(P73) when noise filter time constant is 1/1	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.4 to 5.5	2			
	tPIH(3) tPIL(3)		INT3(P73) when noise filter time constant is 1/32	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.4 to 5.5	64			
	tPIH(4) tPIL(4)		INT3(P73) when noise filter time constant is 1/128	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.4 to 5.5	256			
	tPIH(5) tPIL(5)		NKIN(P72)	• High speed clock counter countable	2.4 to 5.5	1/12			
	tPIL(6)		RES	• External reset input mode • Resetting is enabled	2.4 to 5.5	200			μs

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AD Converter Characteristics at $V_{SS1}=V_{SS2}=V_{SS3}=0V$

<12bits AD Converter Mode / $T_a=-30$ to $+70^{\circ}C$ >

Parameter	Symbol	Pin/Remarks	Conditions	$V_{DD}[V]$	Specification			
					min	typ	max	unit
Resolution	N	AN0(P80) to		3.0 to 5.5		12		bit
Absolute accuracy	ET	AN7(P87)	(Note 6-1)	3.0 to 5.5			± 16	LSB
Conversion time	tCAD	AN8(PB0) to AN15(PB7)	• See Conversion time calculation formulas. (Note 6-2)	4.0 to 5.5	32		115	μs
				3.0 to 5.5	64		115	
Analog input voltage range	VAIN			3.0 to 5.5	V_{SS}		V_{DD}	V
Analog port input current	I _{AINH}		• $V_{AIN}=V_{DD}$	3.0 to 5.5			1	μA
	I _{AINL}		• $V_{AIN}=V_{SS}$	3.0 to 5.5	-1			

<8bits AD Converter Mode / $T_a=-30$ to $+70^{\circ}C$ >

Parameter	Symbol	Pin/Remarks	Conditions	$V_{DD}[V]$	Specification			
					min	typ	max	unit
Resolution	N	AN0(P80) to		3.0 to 5.5		8		bit
Absolute accuracy	ET	AN7(P87)	(Note 6-1)	3.0 to 5.5			± 1.5	LSB
Conversion time	tCAD	AN8(PB0) to AN15(PB7)	• See Conversion time calculation formulas. (Note 6-2)	4.0 to 5.5	20		95	μs
				3.0 to 5.5	40		95	
Analog input voltage range	VAIN			3.0 to 5.5	V_{SS}		V_{DD}	V
Analog port input current	I _{AINH}		• $V_{AIN}=V_{DD}$	3.0 to 5.5			1	μA
	I _{AINL}		• $V_{AIN}=V_{SS}$	3.0 to 5.5	-1			

Conversion time calculation formulas:

12bits AD Converter Mode : $TCAD(\text{Conversion time}) = ((52/(\text{AD division ratio}))+2) \times (1/3) \times tCYC$

8bits AD Converter Mode : $TCAD(\text{Conversion time}) = ((32/(\text{AD division ratio}))+2) \times (1/3) \times tCYC$

External oscillation (FmCF)	Operating supply voltage range (V_{DD})	System division ratio (SYSDIV)	Cycle time (tCYC)	AD division ratio (ADDIV)	AD conversion time (TCAD)	
					12bit AD	8bit AD
CF-12MHz	4.0V to 5.5V	1/1	250ns	1/8	34.8 μs	21.5 μs
	3.0V to 5.5V	1/1	250ns	1/16	69.5 μs	42.8 μs
CF-4MHz	3.0V to 5.5V	1/1	750ns	1/8	104.5 μs	64.5 μs

Note 6-1: The quantization error ($\pm 1/2LSB$) must be excluded from the absolute accuracy. The absolute accuracy must be measured in the microcontroller's state in which no I/O operations occur at the pins adjacent to the analog input channel.

Note 6-2: The conversion time refers to the period from the time an instruction for starting a conversion process till the time the conversion results register(s) are loaded with a complete digital conversion value corresponding to the analog input value.

The conversion time is 2 times the normal-time conversion time when:

- The first AD conversion is performed in the 12-bit AD conversion mode after a system reset.
- The first AD conversion is performed after the AD conversion mode is switched from 8-bit to 12-bit conversion mode.

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Continued from preceding page.

Parameter	Symbol	Pin/ Remarks	Conditions	V _{DD} [V]	Specification			
					min	typ	max	unit
Current consumption during HALT mode (Note 9-1)	IDDHALT(1)	V _{DD1} = V _{DD2} = V _{DD3}	HALT mode • FmCF=12MHz Ceramic resonator oscillation • FsX'tal=32.768kHz crystal oscillation • Frequency variable RC oscillation stopped. • Internal RC oscillation stopped. • System clock: CF oscillation 12MHz • Divider : 1/1	4.5 to 5.5		3.3	8.4	mA
				3.0 to 3.6		1.7	4.3	
	IDDHALT(2)		HALT mode • FmCF=4MHz Ceramic resonator oscillation • FsX'tal=32.768kHz crystal oscillation • Frequency variable RC oscillation stopped. • Internal RC oscillation stopped. • System clock: CF oscillation 4MHz • Divider : 1/1	4.5 to 5.5		0.3	4.1	
				2.4 to 3.6		0.1	1.8	
	IDDHALT(3)		HALT mode • FmCF=0Hz (No oscillation) • FsX'tal=32.768kHz crystal oscillation • FmVMRC=10MHz Frequency variable RC oscillation • Internal RC oscillation stopped. • System clock: Frequency variable RC oscillation 10MHz • Divider :1/1	4.5 to 5.5		2.3	5.8	
				2.4 to 3.6		1.3	3.2	
	IDDHALT(4)		HALT mode • FmCF=0Hz (No oscillation) • FsX'tal=32.768kHz crystal oscillation • FmVMRC=4MHz Frequency variable RC oscillation • Internal RC oscillation stopped. • System clock: Frequency variable RC oscillation 4MHz • Divider :1/1	4.5 to 5.5		1.0	2.5	
				2.4 to 3.6		0.5	1.3	
	IDDHALT(5)		HALT mode • FmCF=0Hz (No oscillation) • FsX'tal=32.768kHz crystal oscillation • Frequency variable RC oscillation stopped. • Internal RC oscillation=Fast RC oscillation • System clock: Fast RC oscillation • Divider :1/1	4.5 to 5.5		200	500	μA
				2.4 to 3.6		100	200	
	IDDHALT(6)		HALT mode • FmCF=0Hz (No oscillation) • FsX'tal=32.768kHz crystal oscillation • Frequency variable RC oscillation stopped. • Internal RC oscillation stopped. • System clock: 32.768kHz • Divider :1/1	4.5 to 5.5		57.2	230.9	
				2.4 to 3.6		13.6	83.2	

Note 9-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

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Continued from preceding page

Parameter	Symbol	Pin/ Remarks	Conditions		Specification			
				V _{DD} [V]	min	typ	max	unit
Current consumption during HOLD mode (Note 9-1)	IDDHOLD(1)	V _{DD1} = V _{DD2} = V _{DD3}	HOLD mode • CF1=V _{DD} or open (when using external clock)	4.5 to 5.5		0.1	52	μA
				2.4 to 3.6		0.04	22	
Current consumption during Date/time clock HOLD mode (Note 9-1)	IDDHOLD(3)		Date/time clock HOLD mode • CF1=V _{DD} or open (when using external clock) • FmX'tal=32.768kHz crystal oscillation • Normal mode	4.5 to 5.5		49.9	213	
				2.4 to 3.6		9.6	73.4	
	IDDHOLD(4)		Date/time clock HOLD mode • CF1=V _{DD} or open (when using external clock) • FmX'tal=32.768kHz crystal oscillation • Power save mode	4.5 to 5.5		1.0	94.3	
				2.4 to 3.6		0.76	39.3	

Note9-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

F-ROM Programming Characteristics at Ta = +10°C to +55°C, V_{SS1} = V_{SS2} = V_{SS3} = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Onboard programming current	IDDFW	V _{DD1}	• Current of the Flash module	3.0 to 5.5		5	10	mA
Programming time	tFW(1)		• Erase time	3.0 to 5.5		20	30	ms
	tFW(2)		• Program time			40	60	μs

UART (Full Duplex) Operating Conditions at Ta = -30°C to +70°C, V_{SS1} = V_{SS2} = V_{SS3} = 0V

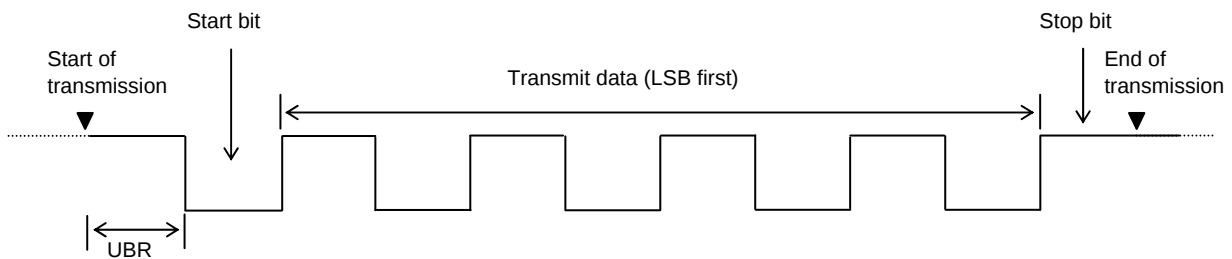
Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Transfer rate	UBR	UTX1(P00), URX1(P01) UTX2(P02), URX2(P03)		2.4 to 5.5	16/3		8192/3	tCYC

Data length: 7, 8, and 9 bits (LSB first)

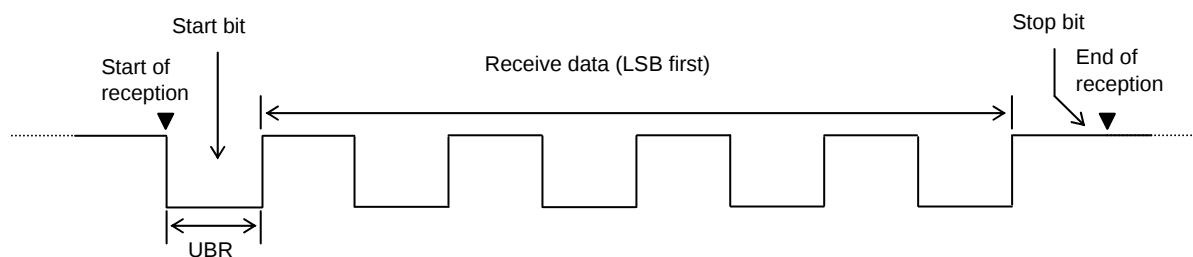
Stop bits: 1 bit (2-bit in continuous data transmission)

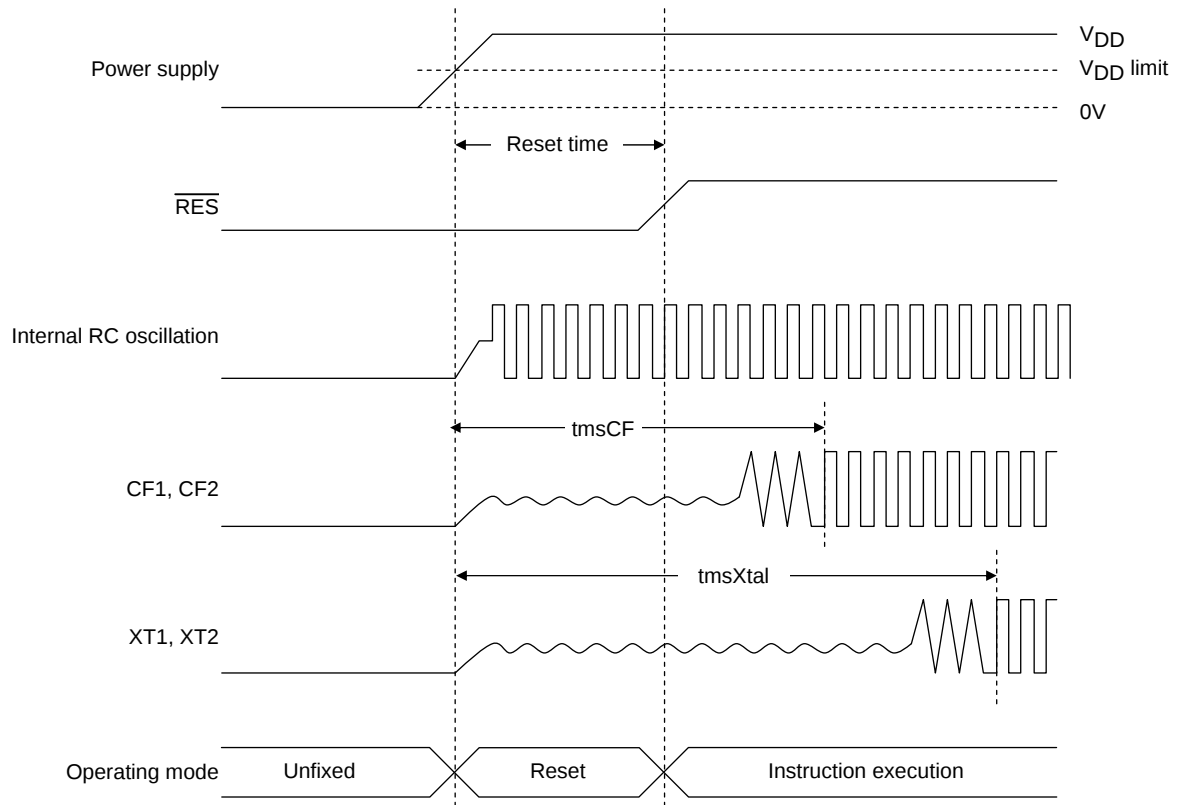
Parity bits: None

Example of Continuous 8-bit Data Transmission Mode Processing (first transmit data=55H)

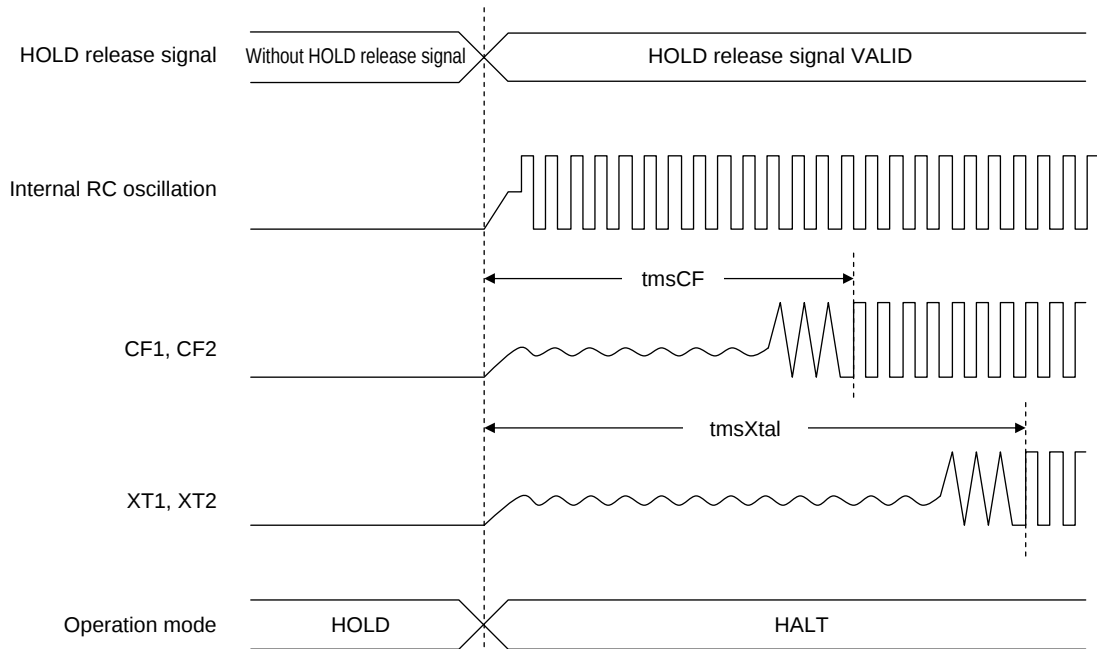


Example of Continuous 8-bit Data Reception Mode Processing (first receive data=55H)



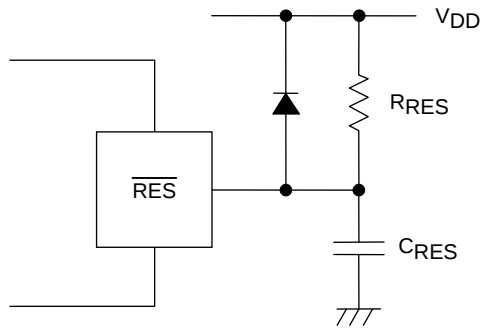


Reset Time and Oscillation Stable Time



HOLD Release Signal and Oscillation Stable Time

Figure 4 Oscillation Stabilization Times



Note:

External circuits for reset may vary depending on the usage of POR and LVD. Please refer to the user's manual for more information.

Figure 5 Reset Circuit

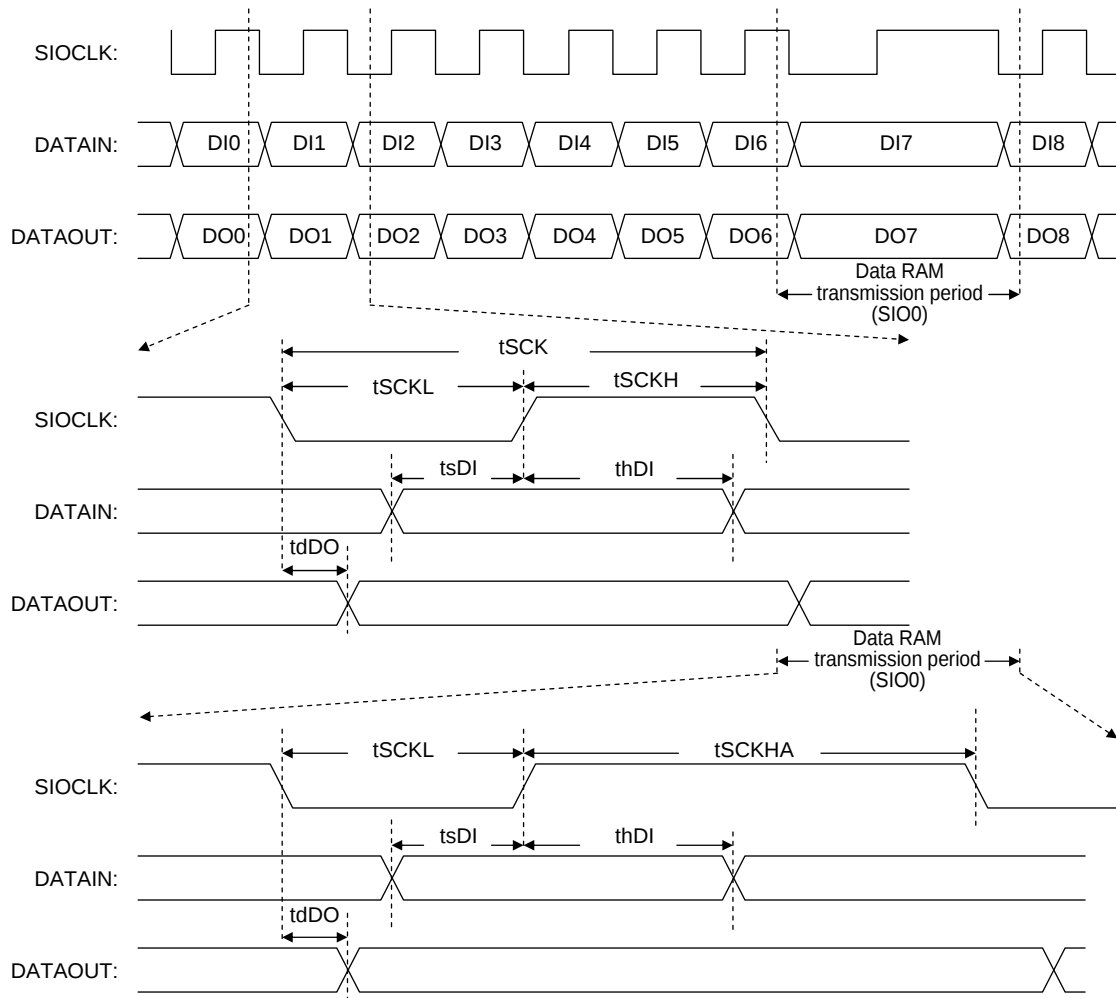


Figure 6 Serial I/O Output Waveforms

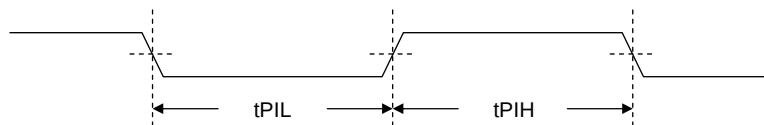


Figure 7 Pulse Input Timing Signal Waveform

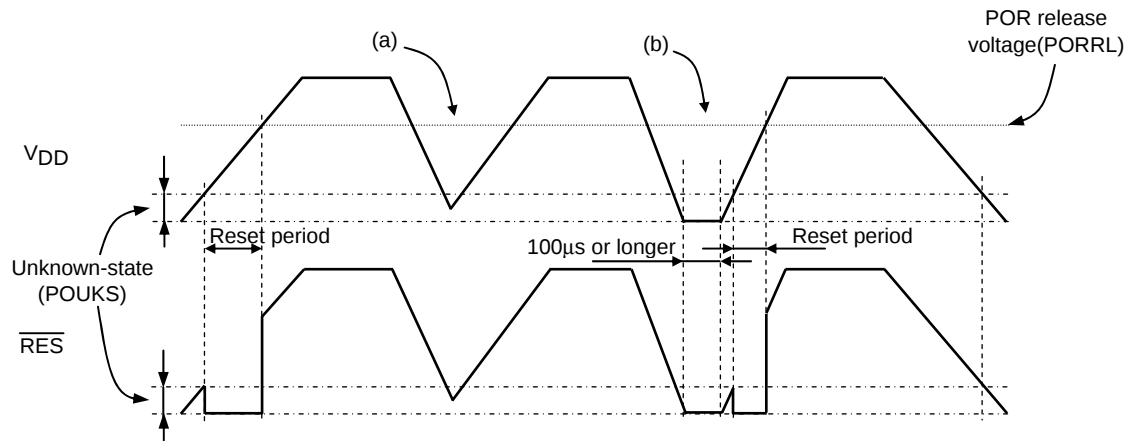


Figure 8 Waveform observed when only POR is used (LVD not used)
(RESET pin: Pull-up resistor R_{RES} only)

- The POR function generates a reset only when power is turned on starting at the V_{SS} level.
- No stable reset will be generated if power is turned on again when the power level does not go down to the V_{SS} level as shown in (a). If such a case is anticipated, use the LVD function together with the POR function or implement an external reset circuit.
- A reset is generated only when the power level goes down to the V_{SS} level as shown in (b) and power is turned on again after this condition continues for 100µs or longer.

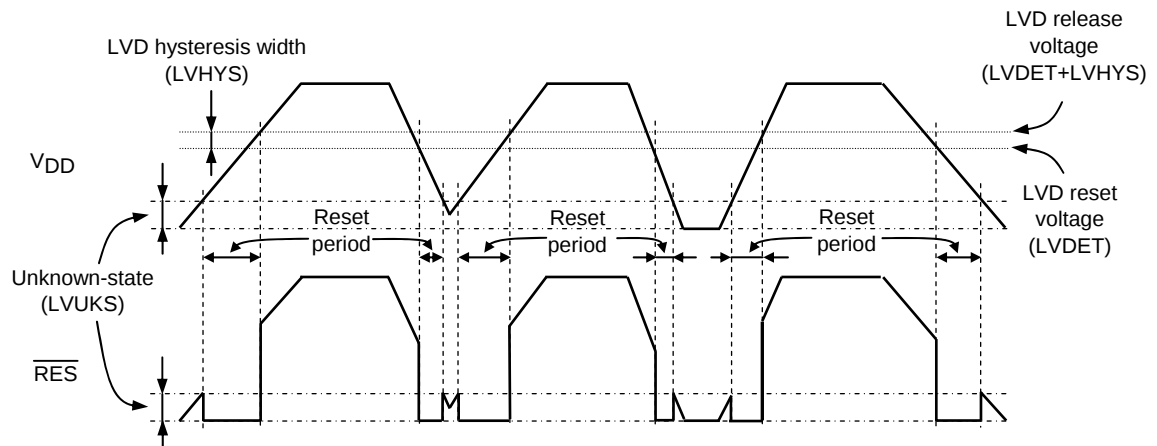


Figure 9 Waveform observed when both POR and LVD functions are used
(RESET pin: Pull-up resistor R_{RES} only)

- Resets are generated both when power is turned on and when the power level lowers.
- A hysteresis width (LVHYS) is provided to prevent the repetitions of reset release and entry cycles near the detection level.

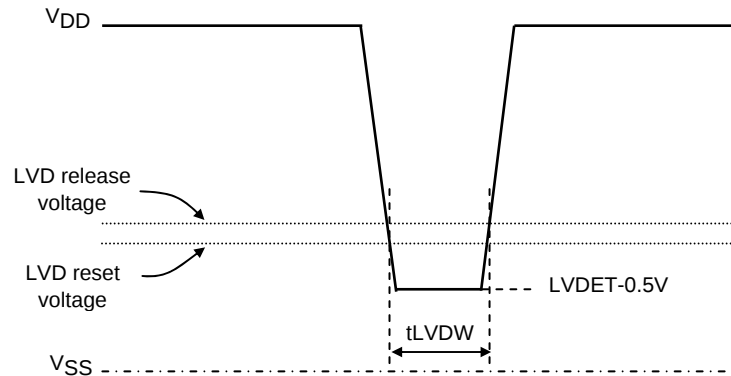


Figure 10 Low voltage detection minimum width
(Example of momentary power loss/Voltage variation waveform)

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