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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I ² C, LINbus, SIO, SSU, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	47
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 12x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	52-LQFP
Supplier Device Package	52-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f2135cmnfp-50

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R8C/35M Group 1. Overview

Table 1.2 Specifications for R8C/35M Group (2)

Item	Function	Specification
Serial	UARTO, UART1	Clock synchronous serial I/O/UART x 2 channel
Interface	UART2	Clock synchronous serial I/O/UART, I ² C mode (I ² C-bus), multiprocessor communication function
Synchronous S	Serial	1 (shared with I ² C-bus)
Communication	n Unit (SSU)	
I ² C bus		1 (shared with SSU)
LIN Module		Hardware LIN: 1 (timer RA, UART0)
A/D Converter		10-bit resolution x 12 channels, includes sample and hold function, with sweep mode
D/A Converter		8-bit resolution x 2 circuits
Comparator A		2 circuits (shared with voltage monitor 1 and voltage monitor 2)
		External reference voltage input available
Comparator B		2 circuits
Flash Memory		Programming and erasure voltage: VCC = 2.7 to 5.5 V
		Programming and erasure endurance: 10,000 times (data flash)
		1,000 times (program ROM)
		Program security: ROM code protect, ID code check
		Debug functions: On-chip debug, on-board flash rewrite function
		Background operation (BGO) function
Operating Freq	uency/Supply	f(XIN) = 20 MHz (VCC = 2.7 to 5.5 V)
Voltage		f(XIN) = 5 MHz (VCC = 1.8 to 5.5 V)
Current consur	nption	Typ. 6.5 mA (VCC = 5.0 V, f(XIN) = 20 MHz)
		Typ. 3.5 mA (VCC = 3.0 V, f(XIN) = 10 MHz) Typ. 3.5 μA (VCC = 3.0 V, wait mode (f(XCIN) = 32 kHz))
		Typ. 2.0 μ A (VCC = 3.0 V, wall mode (((XCHV) = 62 KH2))
Operating Amb	ient Temperature	-20 to 85°C (N version)
	•	-40 to 85°C (D version) (1)
Package		52-pin LQFP
		Package code: PLQP0052JA-A (previous code: 52P6A-A)

Note:
 1. Specify the D version if D version functions are to be used.

R8C/35M Group 1. Overview

1.3 Block Diagram

Figure 1.2 shows a Block Diagram.

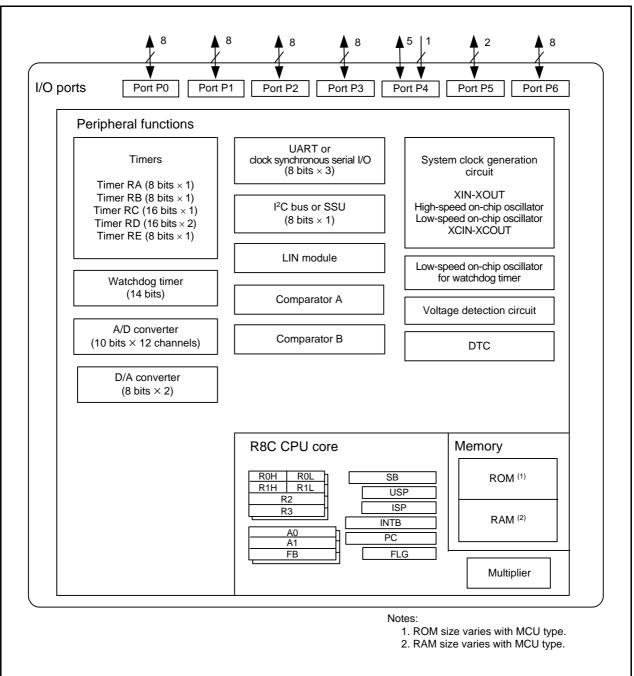


Figure 1.2 Block Diagram

R8C/35M Group 1. Overview

1.4 Pin Assignment

Figure 1.3 shows the Pin Assignment (Top View). Tables 1.4 and 1.5 outline the Pin Name Information by Pin Number.

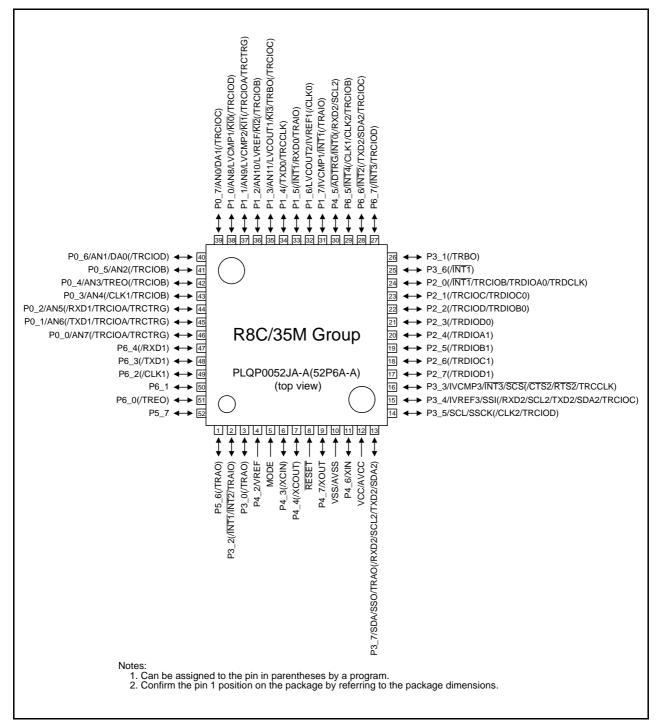


Figure 1.3 Pin Assignment (Top View)

R8C/35M Group 1. Overview

Table 1.5 Pin Name Information by Pin Number (2)

		, ,		•				
	I/O Pin Functions for Peripheral Modules							ıles
Pin Number	Control Pin	Port	Interrupt	Timer	Serial Interface	SSU	I ² C bus	A/D Converter, D/A Converter, Comparator A, Comparator B
36		P1_2	KI2	(TRCIOB)				AN10/LVREF
37		P1_1	KI1	(TRCIOA/ TRCTRG)				AN9/LVCMP2
38		P1_0	KI0	(TRCIOD)				AN8/LVCMP1
39		P0_7		(TRCIOC)				AN0/DA1
40		P0_6		(TRCIOD)				AN1/DA0
41		P0_5		(TRCIOB)				AN2
42		P0_4		TREO (/TRCIOB)				AN3
43		P0_3		(TRCIOB)	(CLK1)			AN4
44		P0_2		(TRCIOA/ TRCTRG)	(RXD1)			AN5
45		P0_1		(TRCIOA/ TRCTRG)	(TXD1)			AN6
46		P0_0		(TRCIOA/ TRCTRG)				AN7
47		P6_4			(RXD1)			
48		P6_3			(TXD1)			
49		P6_2			(CLK1)			
50		P6_1						
51		P6_0		(TREO)				
52		P5_7						

^{1.} Can be assigned to the pin in parentheses by a program.

2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register bank.

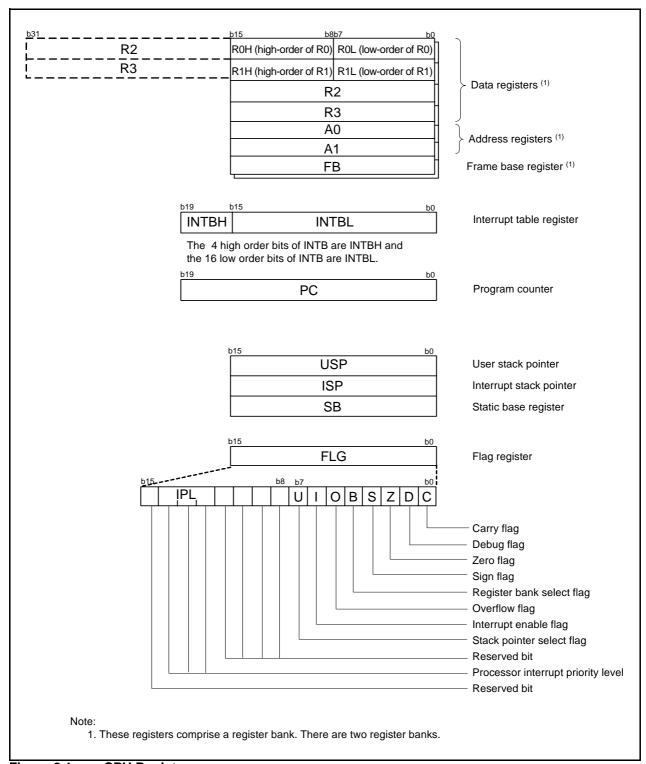


Figure 2.1 CPU Registers

2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the starting address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 **Zero Flag (Z)**

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.



SFR Information (2) (1) Table 4.2

Address	Register	Symbol	After Reset
003Ah	Voltage Monitor 2 Circuit Control Register	VW2C	10000010b
003Bh			
003Ch			
003Dh			
003Eh			
003Fh			
0040h			
0041h	Flash Memory Ready Interrupt Control Register	FMRDYIC	XXXXX000b
0042h			
0043h			
0044h			
0045h			
0046h	INT4 Interrupt Control Register	INT4IC	XX00X000b
0047h	Timer RC Interrupt Control Register	TRCIC	XXXXX000b
0048h	Timer RD0 Interrupt Control Register	TRD0IC	XXXXXX000b
0048h	Timer RD1 Interrupt Control Register	TRD1IC	XXXXX000b
004Ah	Timer RE Interrupt Control Register	TREIC	XXXXX000b
004Bh	UART2 Transmit Interrupt Control Register	S2TIC	XXXXX000b
004Ch	UART2 Receive Interrupt Control Register	S2RIC	XXXXX000b
004Dh	Key Input Interrupt Control Register	KUPIC	XXXXX000b
004Eh	A/D Conversion Interrupt Control Register	ADIC	XXXXX000b
004Fh	SSU Interrupt Control Register / IIC bus Interrupt Control Register (2)	SSUIC / IICIC	XXXXX000b
0050h			
0051h	UART0 Transmit Interrupt Control Register	SOTIC	XXXXX000b
0051h	UARTO Receive Interrupt Control Register	SORIC	XXXXX000b XXXXXX000b
0052h	UART1 Transmit Interrupt Control Register	S1TIC	XXXXX000b
	HARTA Receive Interrupt Control Register		
0054h	UART1 Receive Interrupt Control Register	S1RIC	XXXXX000b
0055h	INT2 Interrupt Control Register	INT2IC	XX00X000b
0056h	Timer RA Interrupt Control Register	TRAIC	XXXXX000b
0057h			
0058h	Timer RB Interrupt Control Register	TRBIC	XXXXX000b
0059h	INT1 Interrupt Control Register	INT1IC	XX00X000b
005Ah	INT3 Interrupt Control Register	INT3IC	XX00X000b
005Bh			
005Ch			
005Dh	INT0 Interrupt Control Register	INTOIC	XX00X000b
005Eh	UART2 Bus Collision Detection Interrupt Control Register	U2BCNIC	XXXXX000b
005Fh	Office Data Complete Detection Interrupt Control Register	02501110	70000000
0060h			
0060h			
0062h			
0063h			
0064h			
0065h			
0066h			
0067h			
0068h			
0069h			
006Ah			
006Bh			
006Ch			
006Ch			
006Eh			
006Fh			
0070h			
0071h			
0072h	Voltage Monitor 1/Comparator A1 Interrupt Control Register	VCMP1IC	XXXXX000b
0073h	Voltage Monitor 2/Comparator A2 Interrupt Control Register	VCMP2IC	XXXXX000b
0074h			
0075h			
0076h			
0070H			
0077H			
0079h			
007Ah			
007Bh			
007Ch			
007Dh			
007Eh			
	+		+

X: Undefined

Notes: 1. 2.

- The blank areas are reserved and cannot be accessed by users. Selectable by the IICSEL bit in the SSUIICSR register.

SFR Information (7) (1) Table 4.7

	• · · · · · · · · · · · · · · · · · · ·		
Address	Register	Symbol	After Reset
0180h	Timer RA Pin Select Register	TRASR	00h
0181h	Timer RB/RC Pin Select Register	TRBRCSR	00h
0182h	Timer RC Pin Select Register 0	TRCPSR0	00h
0183h	Timer RC Pin Select Register 1	TRCPSR1	00h
0184h	Timer RD Pin Select Register 0	TRDPSR0	00h
0185h	Timer RD Pin Select Register 1	TRDPSR1	00h
0186h	Timer Pin Select Register	TIMSR	00h
0187h	-		
0188h	UART0 Pin Select Register	U0SR	00h
0189h	UART1 Pin Select Register	U1SR	00h
018Ah	UART2 Pin Select Register 0	U2SR0	00h
018Bh	UART2 Pin Select Register 1	U2SR1	00h
018Ch	SSU/IIC Pin Select Register	SSUIICSR	00h
018Dh	Ÿ		
018Eh	INT Interrupt Input Pin Select Register	INTSR	00h
018Fh	I/O Function Pin Select Register	PINSR	00h
0190h	, we construct the great		
0191h			
0192h			
0193h	SS Bit Counter Register	SSBR	11111000b
0193h	SS Transmit Data Register L / IIC bus Transmit Data Register (2)	SSTDR / ICDRT	FFh
		SSTDRH	FFh
0195h	SS Transmit Data Register H (2)		
0196h	SS Receive Data Register L / IIC bus Receive Data Register (2)	SSRDR / ICDRR	FFh
0197h	SS Receive Data Register H (2)	SSRDRH	FFh
0198h	SS Control Register H / IIC bus Control Register 1 (2)	SSCRH / ICCR1	00h
0199h	SS Control Register L / IIC bus Control Register 2 (2)	SSCRL / ICCR2	01111101b
019Ah	SS Mode Register / IIC bus Mode Register (2)	SSMR / ICMR	00010000b / 00011000b
019Bh	SS Enable Register / IIC bus Interrupt Enable Register (2)	SSER / ICIER	00h
019Ch	SS Status Register / IIC bus Status Register (2)	SSSR / ICSR	00h / 0000X000b
019Dh	SS Mode Register 2 / Slave Address Register (2)	SSMR2 / SAR	00h
019Bh	55 Mode Register 27 Stave Address Register (2)	33WK2/3AK	0011
019Fh			
01A0h			
01A1h			
01A2h			
01A3h			
01A4h			
01A5h			
01A6h			
01A7h			
01A8h			
01A9h			
01AAh			
01ABh			
01ACh			
01ADh			
01AEh			
01AFh			
01B0h			
01B1h			
01B2h	Flash Memory Status Register	FST	10000X00b
01B3h			
01B4h	Flash Memory Control Register 0	FMR0	00h
01B5h	Flash Memory Control Register 1	FMR1	00h
01B6h	Flash Memory Control Register 2	FMR2	00h
01B7h			
01B8h			
01B9h			
01BAh			
01BBh			
01BCh			
01BDh			
01BEh			
01BFh			
V: Undefined	L	J	

X: Undefined
Notes:

1. The blank areas are reserved and cannot be accessed by users.
2. Selectable by the IICSEL bit in the SSUIICSR register.

SFR Information (8) (1) Table 4.8

Address	Pogistor	Symbol	After Reset
01C0h	Register Address Match Interrupt Register 0	RMAD0	XXh
01C1h	Address Match Interrupt Register 0	NWADO	XXh
01C1h	_		0000XXXXb
01C3h	Address Match Interrupt Enable Register 0	AIER0	00h
01C3h	Address Match Interrupt Register 1	RMAD1	XXh
01C4H	Address Match Interrupt Register 1	RWADT	XXh
01C6h	4		
01C6h	Address Match Interrupt Enable Register 1	AIER1	0000XXXXb 00h
01C7h	Address Match Interrupt Enable Register 1	AIERI	oon
01C9h 01CAh			
01CAn			
01CCh 01CDh			
01CEh			
01CFh			
01D0h			
01D1h			
01D2h			
01D3h			
01D4h			
01D5h			
01D6h			
01D7h			
01D8h			
01D9h			
01DAh			
01DBh			
01DCh			
01DDh			
01DEh			
01DFh			
01E0h	Pull-Up Control Register 0	PUR0	00h
01E1h	Pull-Up Control Register 1	PUR1	00h
01E2h			
01E3h			
01E4h			
01E5h			
01E6h			
01E7h			
01E8h			
01E9h			
01EAh			
01EBh			
01ECh			+
01EDh			+
01EEh			+
01EFh			+
01F0h	Port P1 Drive Capacity Control Register	P1DRR	00h
01F1h	Port P2 Drive Capacity Control Register	P2DRR	00h
01F1f1	Drive Capacity Control Register 0	DRR0	00h
	Drive Capacity Control Register 1		
01F3h	Drive Capacity Curition Register 1	DRR1	00h
01F4h	Input Throshold Control Bogistor C	IVII TO	00b
01F5h	Input Threshold Control Register 0	VLT0	00h
01F6h	Input Threshold Control Register 1	VLT1	00h
01F7h	Occurrentes D. Control Devictor C	INTOMO	LOOK.
01F8h	Comparator B Control Register 0	INTCMP	00h
01F9h		ļ <u>.</u>	
0.4	External Input Enable Register 0	INTEN	00h
01FAh		INTEN1	00h
01FBh	External Input Enable Register 1		
01FBh 01FCh	INT Input Filter Select Register 0	INTF	00h
01FBh 01FCh 01FDh	INT Input Filter Select Register 0 INT Input Filter Select Register 1	INTF INTF1	00h 00h
01FBh 01FCh	INT Input Filter Select Register 0	INTF	00h

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 5.4 **D/A Converter Characteristics**

Symbol	Parameter	Condition		Unit		
Symbol	Faranielei	Condition	Min.	Тур.	Max. 8 2.5 3	Offic
_	Resolution		=	_	8	Bit
_	Absolute accuracy		-	-	2.5	LSB
tsu	Setup time		-	-	3	μs
Ro	Output resistor		-	6	_	kΩ
lVref	Reference power input current	(Note 2)	-	-	1.5	mA

Notes:

- 1. Vcc/AVcc = Vref = 2.7 to 5.5 V and Topr = -20 to $85^{\circ}C$ (N version) / -40 to $85^{\circ}C$ (D version), unless otherwise specified.
- 2. This applies when one D/A converter is used and the value of the DAi register (i = 0 or 1) for the unused D/A converter is 00h. The resistor ladder of the A/D converter is not included.

Table 5.5 **Comparator A Electrical Characteristics**

Symbol	Parameter	Condition		Unit		
Symbol	Farameter	Condition	Min.	Тур.	Max.	Offic
LVREF	External reference voltage input range		1.4	=	Vcc	V
LVCMP1, LVCMP2	External comparison voltage input range		-0.3	_	Vcc + 0.3	V
_	Offset		=	50	200	mV
_	Comparator output delay time (2)	At falling, V _I = Vref – 100 mV	=	3	-	μS
		At falling, V _I = Vref – 1 V or below	=	1.5	-	μS
		At rising, VI = Vref + 100 mV	=	2	-	μS
		At rising, VI = Vref + 1 V or above	=	0.5	=	μS
_	Comparator operating current	Vcc = 5.0 V	_	0.5	_	μΑ

Notes:

- 1. Vcc = 2.7 to 5.5 V, $T_{opr} = -20 \text{ to } 85^{\circ}\text{C}$ (N version) / $-40 \text{ to } 85^{\circ}\text{C}$ (D version), unless otherwise specified.
- 2. When the digital filter is disabled.

Table 5.6 **Comparator B Electrical Characteristics**

Symbol	Parameter	Condition		Unit			
Symbol	Farameter	Condition	Min.	Тур.	Max.	Offic	
Vref	IVREF1, IVREF3 input reference voltage		0	-	Vcc - 1.4	V	
Vı	IVCMP1, IVCMP3 input voltage		-0.3	-	Vcc + 0.3	V	
_	Offset		-	5	100	mV	
td	Comparator output delay time (2)	Vı = Vref ± 100 mV	-	0.1	-	μS	
Ісмр	Comparator operating current	Vcc = 5.0 V	-	17.5	-	μΑ	

- Vcc = 2.7 to 5.5 V, T_{opr} = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
 When the digital filter is disabled.

Table 5.8 Flash Memory (Data flash Block A to Block D) Electrical Characteristics

Symbol	Parameter	Parameter Conditions		Standard			
Syllibol	Farameter	Conditions	Min.	Тур.	Max.	Unit	
_	Program/erase endurance (2)		10,000 (3)	-	-	times	
=	Byte program time (program/erase endurance ≤ 1,000 times)		-	160	1,500	μS	
_	Byte program time (program/erase endurance > 1,000 times)		_	300	1,500	μS	
=	Block erase time (program/erase endurance ≤ 1,000 times)		=	0.2	1	S	
=	Block erase time (program/erase endurance > 1,000 times)		-	0.3	1	S	
td(SR-SUS)	Time delay from suspend request until suspend		-	-	5+CPU clock × 3 cycles	ms	
_	Interval from erase start/restart until following suspend request		0	-	_	μS	
=	Time from suspend until erase restart		=	-	30+CPU clock × 1 cycle	μS	
td(CMDRST- READY)	Time from when command is forcibly terminated until reading is enabled		-	-	30+CPU clock × 1 cycle	μS	
_	Program, erase voltage		2.7	_	5.5	V	
_	Read voltage		1.8	-	5.5	V	
_	Program, erase temperature		-20 (7)	-	85	°C	
_	Data hold time (8)	Ambient temperature = 55 °C	20	-	-	year	

- 1. Vcc = 2.7 to 5.5 V and Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
- 2. Definition of programming/erasure endurance
 - The programming and erasure endurance is defined on a per-block basis.
 - If the programming and erasure endurance is n (n = 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.
 - However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
- 3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
- 4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. In addition, averaging the erasure endurance between blocks A to D can further reduce the actual erasure endurance. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.
- 5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
- 6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- 7. -40°C for D version.
- 8. The data hold time includes time that the power supply is off or the clock is not supplied.

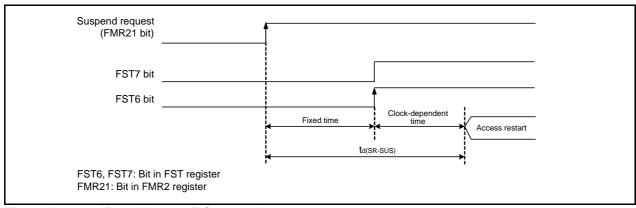


Figure 5.2 Time delay until Suspend

Table 5.16 Timing Requirements of Synchronous Serial Communication Unit (SSU) (1)

Symbol	Parameter		Conditions		Standard			
Symbol	Paramete	er	Conditions	Min.	Тур.	Max.	Unit	
tsucyc	SSCK clock cycle tim	e		4	1	-	tcyc (2)	
tHI	SSCK clock "H" width)		0.4	_	0.6	tsucyc	
tLO	SSCK clock "L" width			0.4	1	0.6	tsucyc	
trise	SSCK clock rising	Master		=	1	1	tcyc (2)	
	time	Slave		-	1	1	μS	
tFALL	SSCK clock falling	Master		=	_	1	tcyc (2)	
	time	Slave		-	_	1	μS	
tsu	SSO, SSI data input	setup time		100	1	-	ns	
tH	SSO, SSI data input hold time			1	_	=	tcyc (2)	
tLEAD	SCS setup time	Slave		1tcyc + 50	-	_	ns	
tLAG	SCS hold time	Slave		1tcyc + 50	=	=	ns	
top	SCS setup time Slave SCS hold time Slave SSO, SSI data output delay time			=	1	1	tcyc (2)	
tsa	SSI slave access time	е	2.7 V ≤ Vcc ≤ 5.5 V	-	1	1.5tcyc + 100	ns	
			1.8 V ≤ Vcc < 2.7 V	-	_	1.5tcyc + 200	ns	
tor	SSI slave out open ti	me	2.7 V ≤ Vcc ≤ 5.5 V	-	-	1.5tcyc + 100	ns	
			1.8 V ≤ Vcc < 2.7 V	-	=	1.5tcyc + 200	ns	

^{1.} Vcc = 1.8 to 5.5 V, Vss = 0 V and Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.

^{2.} 1tcyc = 1/f1(s)

R8C/35M Group 5. Electrical Characteristics

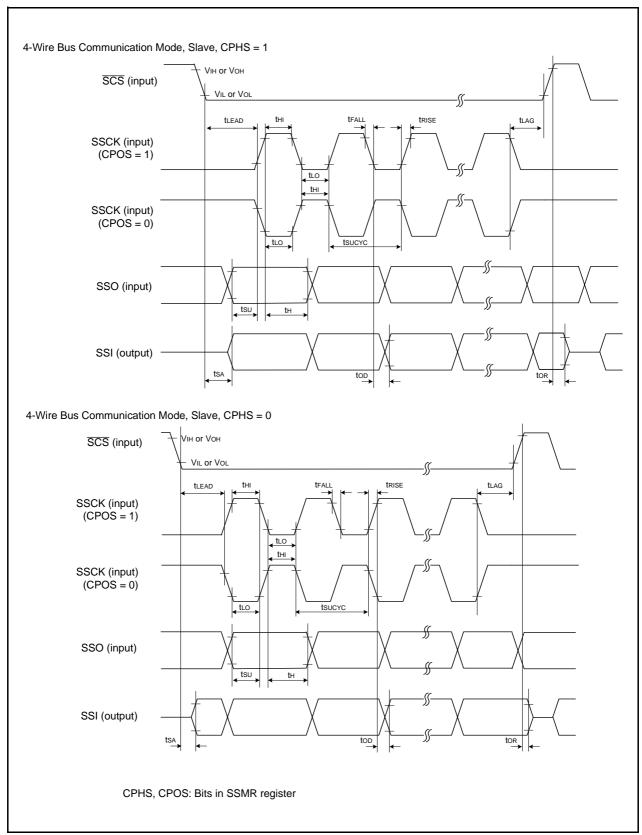


Figure 5.5 I/O Timing of Synchronous Serial Communication Unit (SSU) (Slave)

R8C/35M Group 5. Electrical Characteristics

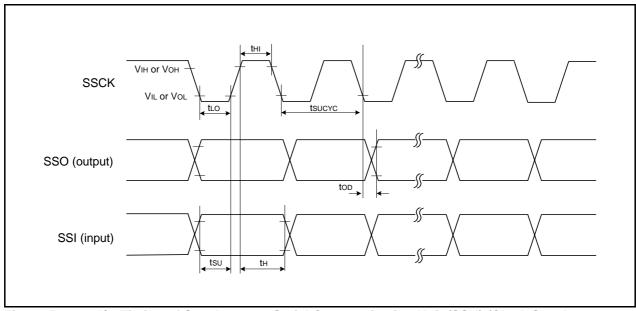


Figure 5.6 I/O Timing of Synchronous Serial Communication Unit (SSU) (Clock Synchronous Communication Mode)

Table 5.17 Timing Requirements of I²C bus Interface (1)

Symbol	Dorometer	Condition	Sta	Standard			
Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit	
tscl	SCL input cycle time		12tcyc + 600 (2)	=	-	ns	
tsclh	SCL input "H" width		3tcyc + 300 (2)	=	-	ns	
tscll	SCL input "L" width		5tcyc + 500 (2)	=.	-	ns	
tsf	SCL, SDA input fall time		-	-	300	ns	
tsp	SCL, SDA input spike pulse rejection time		-	=	1tcyc (2)	ns	
tBUF	SDA input bus-free time		5tcyc (2)	=	-	ns	
tstah	Start condition input hold time		3tcyc (2)	=	-	ns	
tstas	Retransmit start condition input setup time		3tcyc (2)	-	-	ns	
tstop	Stop condition input setup time		3tcyc (2)	=	-	ns	
tsdas	Data input setup time		1tcyc + 40 (2)	-	_	ns	
tsdah	Data input hold time		10	_	-	ns	

- 1. Vcc = 1.8 to 5.5 V, Vss = 0 V and $T_{opr} = -20$ to $85^{\circ}C$ (N version) / -40 to $85^{\circ}C$ (D version), unless otherwise specified.
- 2. 1 tcyc = 1/f1(s)

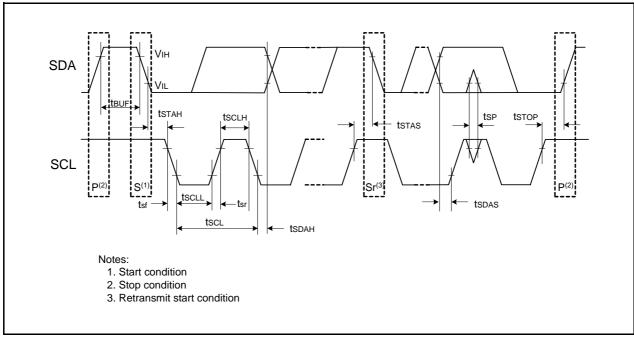


Figure 5.7 I/O Timing of I²C bus Interface

Table 5.18 Electrical Characteristics (1) [4.2 V \leq Vcc \leq 5.5 V]

Symbol	Parameter		Condition		Standard			Unit
Syllibol					Min.	Тур.	Max.	Offic
Vон	Output "H"	Other than XOUT	Drive capacity High Vcc = 5 V	lон = −20 mA	Vcc - 2.0	=	Vcc	V
	voltage		Drive capacity Low Vcc = 5 V	Iон = −5 mA	Vcc - 2.0	=	Vcc	V
1		XOUT	Vcc = 5 V	IOH = -200 μA	1.0	-	Vcc	V
Vol	Output "L"	Other than XOUT	Drive capacity High Vcc = 5 V	IoL = 20 mA	-	-	2.0	V
	voltage		Drive capacity Low Vcc = 5 V	IoL = 5 mA	-	-	2.0	V
		XOUT	Vcc = 5 V	IoL = 200 μA	=.	-	0.5	V
VT+-VT-	Hysteresis	INTO, INT1, INT2, INT3, INT4, KIO, KI1, KI2, KI3, TRAIO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOAO, TRDIOBO, TRDIOCO, TRDIODO, TRDIOA1, TRDIOB1, TRDIOC1, TRDIOD1, TRCTRG, TRCCLK, ADTRG, RXD0, RXD1, RXD2, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO	Vcc = 5.0 V		0.1	1.2	-	V
		RESET	Vcc = 5.0 V		0.1	1.2	-	V
Iн	Input "H" current		VI = 5 V, Vcc = 5.0 V		=		5.0	μА
lı∟	Input "L" current		VI = 0 V, Vcc = 5.0 V		=		-5.0	μА
RPULLUP	Pull-up resistance		VI = 0 V, Vcc = 5.0 V		25	50	100	kΩ
RfXIN	Feedback resistance	XIN				0.3	-	ΜΩ
Rfxcin	Feedback resistance	XCIN			_	8	-	ΜΩ
VRAM	RAM hold voltage		During stop mode		1.8	1	_	V

^{1. 4.2} V ≤ Vcc ≤ 5.5 V and Topr = −20 to 85°C (N version) / −40 to 85°C (D version), f(XIN) = 20 MHz, unless otherwise specified.

Table	5.22	Serial Interface

Symbol	Parameter		Standard		Unit
Symbol			Min.	Max.	Utill
tc(CK)	CLKi input cycle time	When external clock is selected	200	-	ns
tW(CKH)	CLKi input "H" width		100	-	ns
tW(CKL)	CLKi input "L" width		100	-	ns
td(C-Q)	TXDi output delay time		=	90	ns
th(C-Q)	TXDi hold time		0	-	ns
tsu(D-C)	RXDi input setup time		10	-	ns
th(C-D)	RXDi input hold time		90	-	ns
td(C-Q)	TXDi output delay time	When internal clock is selected	=	10	ns
tsu(D-C)	RXDi input setup time]	90	_	ns
th(C-D)	RXDi input hold time		90	-	ns

i = 0 to 2

Note:

1. Vcc = 5 V and $Topr = -20 \text{ to } 85 \,^{\circ}\text{C}$ (N version)/ $-40 \text{ to } 85 \,^{\circ}\text{C}$ (D version), unless otherwise specified.

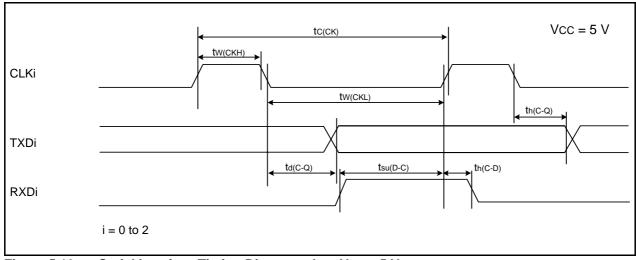


Figure 5.10 Serial Interface Timing Diagram when Vcc = 5 V

Table 5.23 External Interrupt INTi (i = 0 to 4) Input, Key Input Interrupt Kli (i = 0 to 3)

Symbol	Parameter		Standard	
			Max.	Unit
tw(INH)	ĪNTi input "H" width, Kli input "H" width	250 ⁽¹⁾	-	ns
tw(INL)	ĪNTi input "L" width, Kli input "L" width	250 (2)	ı	ns

- 1. When selecting the digital filter by the $\overline{\text{INTi}}$ input filter select bit, use an $\overline{\text{INTi}}$ input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.
- 2. When selecting the digital filter by the $\overline{\text{INTi}}$ input filter select bit, use an $\overline{\text{INTi}}$ input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

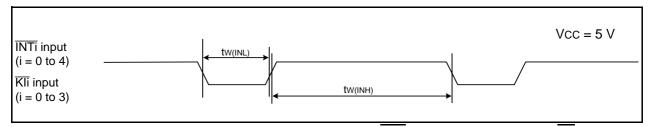
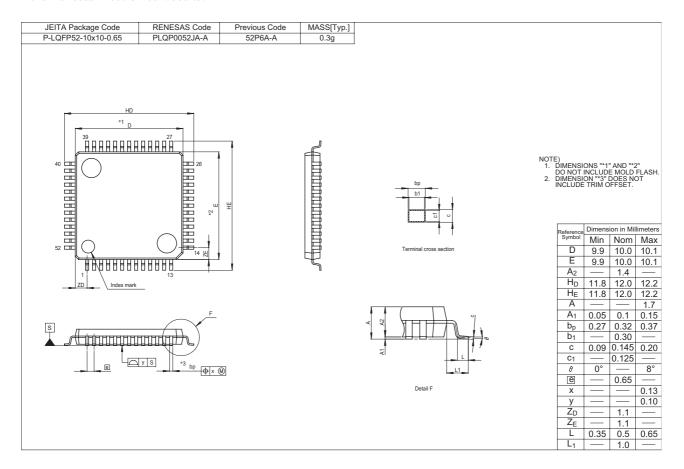


Figure 5.11 Input Timing Diagram for External Interrupt INTi and Key Input Interrupt Kli when Vcc = 5 V

R8C/35M Group Package Dimensions

Package Dimensions

Diagrams showing the latest package dimensions and mounting information are available in the "Packages" section of the Renesas Electronics website.



General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

— The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
In a finished product where the reset signal is applied to the external reset pin, the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

 The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

— When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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