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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	16
Program Memory Size	4KB (4K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
/oltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323lap2004g

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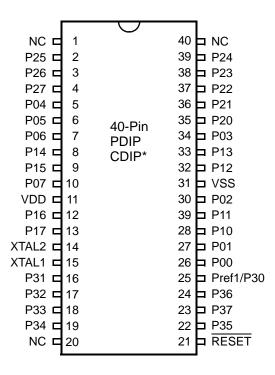


Figure 5. 40-Pin PDIP/CDIP\* Pin Configuration

Note: \*Windowed Cerdip. These units are intended to be used for engineering code development only. ZiLOG does not recommend/guarantee this package for production use.

## **Absolute Maximum Ratings**

Stresses greater than those listed in Table 7 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

**Table 6. Absolute Maximum Ratings** 

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	С	
Storage temperature	-65	+150	С	
Voltage on any pin with respect to V <sub>SS</sub>	-0.3	+5.5	V	1
Voltage on V <sub>DD</sub> pin with respect to V <sub>SS</sub>	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	<b>-</b> 5	+5	μA	
Maximum output current from active output pin	-25	+25	mA	
Maximum current into V <sub>DD</sub> or out of V <sub>SS</sub>		75	mA	

Notes:

This voltage applies to all pins except the following: V<sub>DD</sub>, P32, P33 and RESET.

#### **Standard Test Conditions**

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 7).

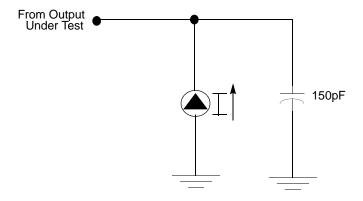


Figure 7. Test Load Diagram



Table 9. EPROM/OTP Characteristics

Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes
	Erase Time	15			Minutes	1,3
	Data Retention @ use years		10		Years	2
	Program/Erase Endurance	25			Cycles	1

#### Notes:

- 1. For windowed cerdip package only.
- 2. Standard: 0°C to 70°C; Extended: -40°C to +105°C; Automotive: -40°C to +125°C. Determined using the Arrhenius model, which is an industry standard for estimating data retention of floating gate technologies:

AF = exp[(Ea/k)\*(1/Tuse - 1/TStress)]

Where:

Ea is the intrinsic activation energy (eV; typ. 0.8)

k is Boltzman's constant (8.67 x 10-5 eV/°K)

°K = -273.16°C

Tuse = Use Temperature in °K

TStress = Stress Temperature in °K

3. At a stable UV Lamp output of 20mW/CM<sup>2</sup>

#### **Comparator Inputs**

In analog mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 12 on page 20. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.

Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery source, these inputs must be placed into digital mode.

#### **Comparator Outputs**

These channels can be programmed to be output on P34 and P37 through the PCON register.

### **RESET (Input, Active Low)**

Reset initializes the MCU and is accomplished either through Power-On, Watch-Dog Timer, Stop Mode Recovery, Low-Voltage detection, or external reset. During Power-On Reset and Watch-Dog Timer Reset, the internally generated reset drives the reset pin Low for the POR time. Any devices driving the external reset line must be open-drain to avoid damage from a possible conflict during reset conditions. Pull-up is provided internally.

When the Z8  $GP^{TM}$  asserts (Low) the  $\overline{RESET}$  pin, the internal pull-up is disabled. The Z8  $GP^{TM}$  does not assert the  $\overline{RESET}$  pin when under VBO.

Note: The external Reset does not initiate an exit from STOP mode.

## **Functional Description**

This device incorporates special functions to enhance the Z8<sup>®</sup>, functionality in consumer and battery-operated applications.

## **Program Memory**

This device addresses up to 32KB of OTP memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts.

#### **RAM**

This device features 256B of RAM. See Figure 14.

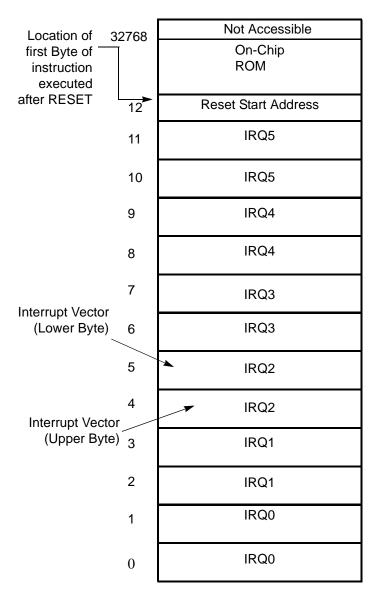


Figure 14. Program Memory Map (32K OTP)

## **Expanded Register File**

The register file has been expanded to allow for additional system control registers and for mapping of additional peripheral devices into the register address area. The Z8<sup>®</sup> register address space (R0 through R15) has been implemented as 16 banks, with 16 registers per bank. These register groups are known as the

Table 13. CTR1(0D)01H T8 and T16 Common Functions (Continued)

Field	Bit Position		Value	Description
Transmit_Submode/	32	R/W		Transmit Mode
Glitch_Filter			00*	Normal Operation
			01	Ping-Pong Mode
			10	T16_Out = 0
			11	T16_Out = 1
				Demodulation Mode
			00*	No Filter
			01	4 SCLK Cycle
			10	8 SCLK Cycle
			11	Reserved
Initial_T8_Out/	1-			Transmit Mode
Rising Edge		R/W	0*	T8_OUT is 0 Initially
			1	T8_OUT is 1 Initially
				Demodulation Mode
		R	0*	No Rising Edge
			1	Rising Edge Detected
		W	0	No Effect
			1	Reset Flag to 0
Initial_T16_Out/	0			Transmit Mode
Falling_Edge		R/W	0*	T16_OUT is 0 Initially
			1	T16_OUT is 1 Initially
				Demodulation Mode
		R	0*	No Falling Edge
			1	Falling Edge Detected
		W	0	No Effect
			1	Reset Flag to 0

#### Note:

#### Mode

If the result is 0, the counter/timers are in TRANSMIT mode; otherwise, they are in DEMODULATION mode.

#### P36\_Out/Demodulator\_Input

In TRANSMIT Mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In DEMODULATION Mode, this bit defines whether the input signal to the Counter/Timers is from P20 or P31.

If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

<sup>\*</sup>Default at Power-On Reset.

<sup>\*\*</sup>Default at Power-On Reset.Not reset with Stop Mode recovery.



#### If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from FFFFh. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

#### **Ping-Pong Mode**

This operation mode is only valid in TRANSMIT Mode. T8 and T16 must be programmed in Single-Pass mode (CTR0, D6; CTR2, D6), and Ping-Pong mode must be programmed in CTR1, D3; D2. The user can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8\_OUT is set to this initial value (CTR1, D1). According to T8\_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16\_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the ping-pong operation, write 00 to bits D3 and D2 of CTR1. See Figure 28.



**Note:** Enabling ping-pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status flags before instituting this operation.



#### **During PING-PONG Mode**

The enable bits of T8 and T16 (CTR0, D7; CTR2, D7) are set and cleared alternately by hardware. The timeout bits (CTR0, D5; CTR2, D5) are set every time the counter/timers reach the terminal count.

#### **Timer Output**

The output logic for the timers is illustrated in Figure 29. P34 is used to output T8-OUT when D0 of CTR0 is set. P35 is used to output the value of TI6-OUT when D0 of CTR2 is set. When D6 of CTR1 is set, P36 outputs the logic combination of T8-OUT and T16-OUT determined by D5 and D4 of CTR1.

#### Interrupts

The Z8 GP<sup>TM</sup> OTP MCU Family features six different interrupts (Table 16). The interrupts are maskable and prioritized (Figure 30). The six sources are divided as follows: three sources are claimed by Port 3 lines P33–P31, two by the counter/timers (Table 16) and one for low voltage detection. The Interrupt Mask Register (globally or individually) enables or disables the six interrupt requests.

The source for IRQ is determined by bit 1 of the Port 3 mode register (P3M). When in digital mode, Pin P33 is the source. When in analog mode the output of the Stop mode recovery source logic is used as the source for the interrupt. See Figure 35, Stop Mode Recovery Source, on page 57.



Stop Mode Recovery Source P33 \_ D1 of P3M Register P31 P32 IRQ Register Low-Voltage Interrupt Edge D6, D7 Timer 8 Timer 16 Detection Select IRQ2 IRQ4 IRQ5 IRQ0 IRQ1 IRQ3 **IRQ IMR** 5 **IPR** Global Interrupt Enable Interrupt Priority Request Logic **Vector Select** 

Figure 30. Interrupt Block Diagram



#### Port 0 Output Mode (D2)

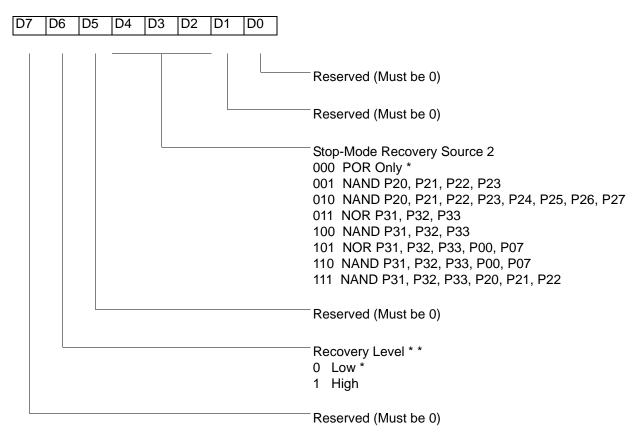
Bit 2 controls the output mode of port 0. A 1 in this location sets the output to push-pull, and a 0 sets the output to open-drain.

#### Stop-Mode Recovery Register (SMR)

This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 33). All bits are write only except bit 7, which is read only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level at the XORgate input (Figure 35 on page 57) is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits D2, D3, and D4 of the SMR register specify the source of the Stop Mode Recovery signal. Bits D0 determines if SCLK/ TCLK are divided by 16 or not. The SMR is located in Bank F of the Expanded Register Group at address OBH.

#### **Stop Mode Recovery Register 2 (SMR2)**

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 36). SMR2(0F)DH



Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

Figure 36. Stop Mode Recovery Register 2 ((0F)DH:D2-D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.

**Note:** Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.

<sup>\*</sup> Default setting after reset

<sup>\* \*</sup> At the XOR gate input

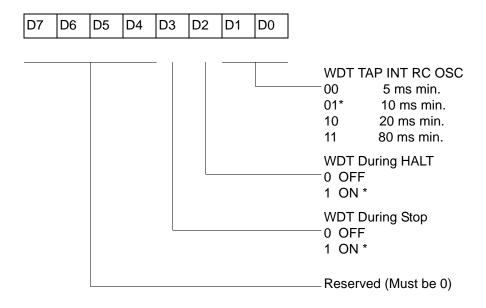


#### Watch-Dog Timer Mode Register (WDTMR)

The Watch-Dog Timer (WDT) is a retriggerable one-shot timer that resets the Z8<sup>®</sup> CPU if it reaches its terminal count. The WDT must initially be enabled by executing the WDT instruction. On subsequent executions of the WDT instruction, the WDT is refreshed. The WDT circuit is driven by an on-board RC-oscillator. The WDT instruction affects the Zero (Z), Sign (S), and Overflow (V) flags.

The POR clock source the internal RC-oscillator. Bits 0 and 1 of the WDT register control a tap circuit that determines the minimum timeout period. Bit 2 determines whether the WDT is active during HALT, and Bit 3 determines WDT activity during Stop. Bits 4 through 7 are reserved (Figure 37). This register is accessible only during the first 60 processor cycles (120 XTAL clocks) from the execution of the first instruction after Power-On-Reset, Watch-Dog Reset, or a Stop-Mode Recovery (Figure 36). After this point, the register cannot be modified by any means (intentional or otherwise). The WDTMR cannot be read. The register is located in Bank F of the Expanded Register Group at address location <code>0Fh</code>. It is organized as shown in Figure 37.

#### WDTMR(0F)0Fh



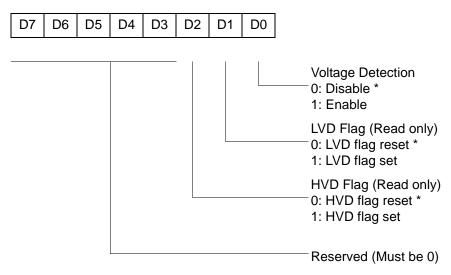
<sup>\*</sup> Default setting after reset

Figure 37. Watch-Dog Timer Mode Register (Write Only)

#### WDT Time Select (D0, D1)

This bit selects the WDT time period. It is configured as indicated in Table 20.

#### LVD(0D)0CH



<sup>\*</sup> Default

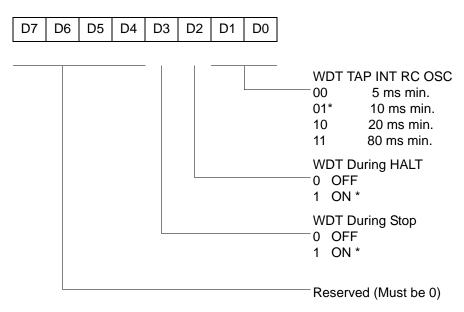
Figure 43. Voltage Detection Register

Note: Do not modify register P01M while checking a low-voltage condition. Switching noise of both ports 0 and 1 together might trigger the LVD flag.

## **Expanded Register File Control Registers (0F)**

The expanded register file control registers (0F) are depicted in Figures 44 through Figure 57.

#### WDTMR(0F)0FH

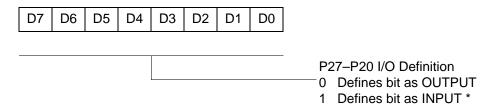


<sup>\*</sup> Default setting after reset

Figure 47. Watch-Dog Timer Register ((0F) 0FH: Write Only)

## **Standard Control Registers**

R246 P2M(F6H)



<sup>\*</sup> Default setting after reset

Figure 48. Port 2 Mode Register (F6H: Write Only)

 $P31\uparrow\downarrow$   $P32\uparrow\downarrow=11$ 

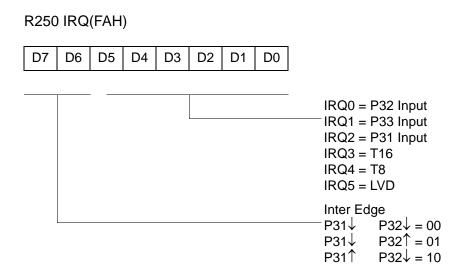
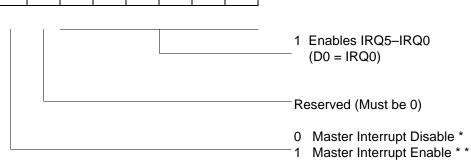


Figure 52. Interrupt Request Register (FAH: Read/Write)

# D7 D6 D5 D4 D3 D2 D1 D0

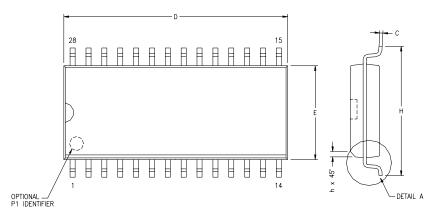


<sup>\*</sup> Default setting after reset

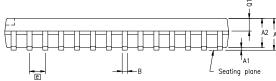
R251 IMR(FBH)

Figure 53. Interrupt Mask Register (FBH: Read/Write)

<sup>\* \*</sup> Only by using EI, DI instruction; DI is required before changing the IMR register



SYMBOL	MILLI	METER	INCH		
SYMBOL	MIN	MAX	MIN	MAX	
Α	2.40	2.64	.094	.104	
A1	0.10	0.30	.004	.012	
A2	2.24	2.44	.088	.096	
В	0.36	0.46	.014	.018	
С	0.23	0.30	.009	.012	
D	17.78	18.00	.700	.710	
E	7.40	7.60	.291	.299	
е	1.27	1.27 BSC		D BSC	
Н	10.00	10.65	.394	.419	
h	0.30	0.71	.012	.028	
L	0.61	1.00	.024	.039	
Q1	0.97	1.09	.038	.043	



CONTROLLING DIMENSIONS : MM LEADS ARE COPLANAR WITHIN .004 INCH.

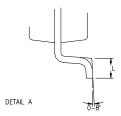


Figure 63. 28-Pin SOIC Package Diagram

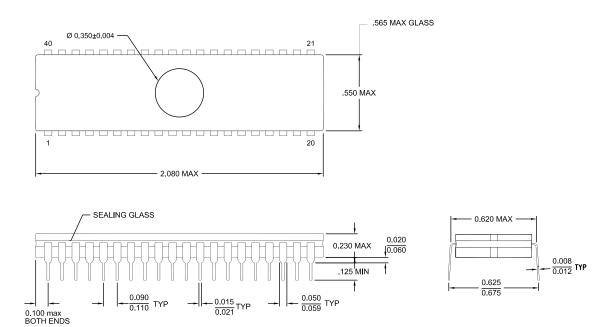


Figure 66. 40-Pin CDIP Package

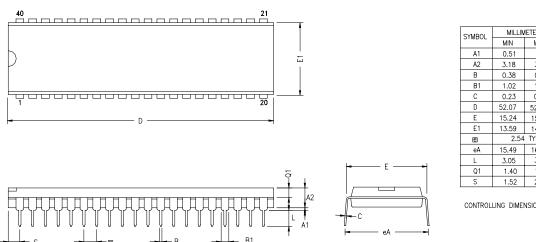


Figure 67. 40-Pin PDIP Package Diagram

SYMBOL	MILLIN	METER	INCH	
SIMIDOL	MIN	MAX	MIN	MAX
A1	0.51	1.02	.020	.040
A2	3.18	3.94	.125	.155
В	0.38	0.53	.015	.021
B1	1.02	1.52	.040	.060
С	0.23	0.38	.009	.015
D	52.07	52.58	2.050	2.070
E	15.24	15.75	.600	.620
E1	13.59	14.22	.535	.560
e	2.54 TYP		.100	TYP
eA	15.49	16.76	.610	.660
L	3.05	3.81	.120	.150
Q1	1.40	1.91	.055	.075
S	1.52	2.29	.060	.090

CONTROLLING DIMENSIONS : INCH



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