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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details		
Product Status	Obsolete	
Core Processor	Z8	
Core Size	8-Bit	
Speed	8MHz	
Connectivity	-	
Peripherals	HLVD, POR, WDT	
Number of I/O	16	
Program Memory Size	4KB (4K x 8)	
Program Memory Type	OTP	
EEPROM Size	-	
RAM Size	237 x 8	
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V	
Data Converters	-	
Oscillator Type	Internal	
Operating Temperature	-40°C ~ 125°C (TA)	
Mounting Type	Surface Mount	
Package / Case	20-SOIC (0.295", 7.50mm Width)	
Supplier Device Package	-	
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323las2004c	

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



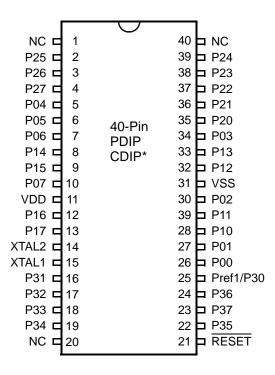


Figure 5. 40-Pin PDIP/CDIP* Pin Configuration

Note: *Windowed Cerdip. These units are intended to be used for engineering code development only. ZiLOG does not recommend/guarantee this package for production use.





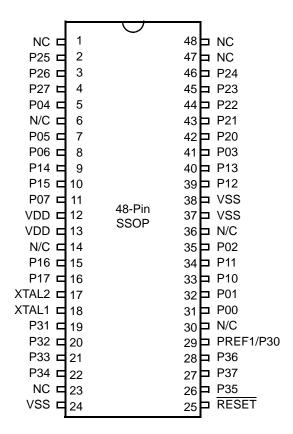


Figure 6. 48-Pin SSOP Pin Configuration

Table 5. 40- and 48-Pin Configuration

40-Pin PDIP/CDIP* #	48-Pin SSOP#	Symbol
26	31	P00
27	32	P01
30	35	P02
34	41	P03
5	5	P04
6	7	P05
7	8	P06
10	11	P07
28	33	P10
29	34	P11
32	39	P12

Absolute Maximum Ratings

Stresses greater than those listed in Table 7 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

Table 6. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	С	
Storage temperature	-65	+150	С	
Voltage on any pin with respect to V _{SS}	-0.3	+5.5	V	1
Voltage on V _{DD} pin with respect to V _{SS}	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	- 5	+5	μA	
Maximum output current from active output pin	-25	+25	mA	
Maximum current into V _{DD} or out of V _{SS}		75	mA	

Notes:

This voltage applies to all pins except the following: V_{DD}, P32, P33 and RESET.

Standard Test Conditions

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 7).

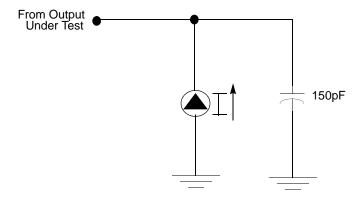


Figure 7. Test Load Diagram



Table 8. DC Characteristics (Continued)

			T _A = 0°	C to +7	70°C			
Symbol	Parameter	V_{CC}	Min	Тур	Max	Units	Conditions	Notes
I _{CC1}	Standby Current	2.0			3	mΑ	$V_{IN} = 0V$, V_{CC} at 8.0MHz	1, 2
	(HALT Mode)	3.6			5		Same as above	1, 2
		2.0			2		Clock Divide-by-16 at 8.0MHz	1, 2
		3.6			4		Same as above	1, 2
I _{CC2}	Standby Current (Stop	2.0			8	μΑ	V _{IN} = 0 V, V _{CC} WDT is not Running	3
	Mode)	3.6			10	μΑ	Same as above	3
		2.0			500	μΑ	$V_{IN} = 0 \text{ V}, V_{CC} \text{ WDT is Running}$	3
		3.6			800	μA	Same as above	3
I _{LV}	Standby Current				10	μΑ	Measured at 1.3V	4
	(Low Voltage)							
V_{BO}	V _{CC} Low Voltage				2.0	V	8MHz maximum	
	Protection						Ext. CLK Freq.	
V_{LVD}	Vcc Low Voltage			2.4		V		
	Detection							
V_{HVD}	Vcc High Voltage			2.7		V		
	Detection							

Notes:

- 1. All outputs unloaded, inputs at rail.
- 2. CL1 = CL2 = 100 pF.
- 3. Oscillator stopped.
- Oscillator stops when V_{CC} falls below V_{BO} limit.
 It is strongly recommended to add a filter capacitor (minimum 0.1 μF), physically close to the V_{DD} and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.



Z8 GP OTP 4 — Port 0 (I/O)

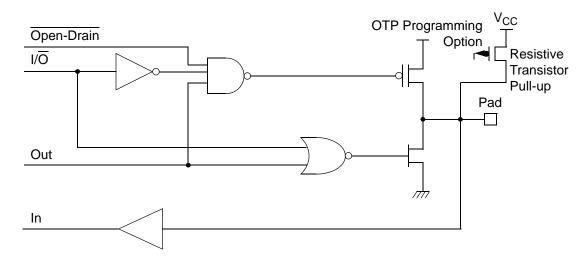
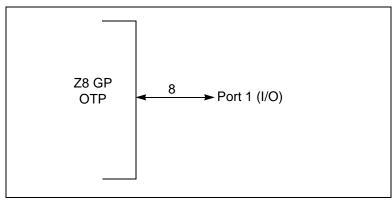


Figure 9. Port 0 Configuration

Port 1 (P17-P10)

Port 1 (see Figure 10) Port 1 can be configured for standard port input or output mode. After POR, Port 1 is configured as an input port. The output drivers are either push-pull or open-drain and are controlled by bit D1 in the PCON register.

Note: The Port 1 direction is reset to be input following an SMR.



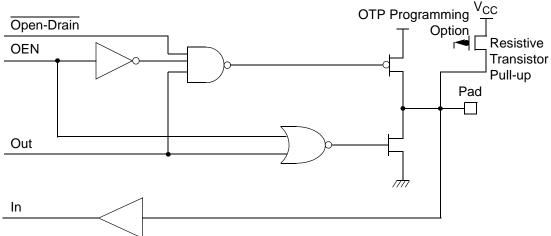


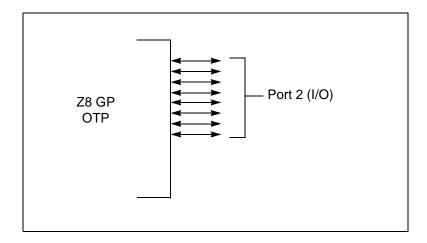
Figure 10. Port 1 Configuration

Port 2 (P27-P20)

Port 2 is an 8-bit, bidirectional, CMOS-compatible I/O port (see Figure 11). These eight I/O lines can be independently configured under software control as inputs or outputs. Port 2 is always available for I/O operation. A mask option is available to connect eight pull-up transistors on this port. Bits programmed as outputs are globally programmed as either push-pull or open-drain. The POR resets with the eight bits of Port 2 configured as inputs.

Port 2 also has an 8-bit input OR and AND gate, which can be used to wake up the part. P20 can be programmed to access the edge-detection circuitry in demodulation mode.





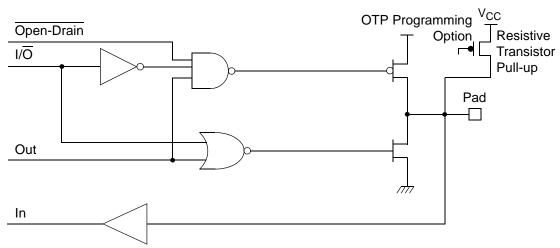


Figure 11. Port 2 Configuration

Port 3 (P37-P30)

Port 3 is a 8-bit, CMOS-compatible fixed I/O port (see Figure 12). Port 3 consists of four fixed input (P33–P30) and four fixed output (P37–P34), which can be configured under software control for interrupt and as output from the counter/timers. P30, P31, P32, and P33 are standard CMOS inputs; P34, P35, P36, and P37 are push-pull outputs.

Comparator Inputs

In analog mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 12 on page 20. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.

Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery source, these inputs must be placed into digital mode.

Comparator Outputs

These channels can be programmed to be output on P34 and P37 through the PCON register.

RESET (Input, Active Low)

Reset initializes the MCU and is accomplished either through Power-On, Watch-Dog Timer, Stop Mode Recovery, Low-Voltage detection, or external reset. During Power-On Reset and Watch-Dog Timer Reset, the internally generated reset drives the reset pin Low for the POR time. Any devices driving the external reset line must be open-drain to avoid damage from a possible conflict during reset conditions. Pull-up is provided internally.

When the Z8 GP^{TM} asserts (Low) the \overline{RESET} pin, the internal pull-up is disabled. The Z8 GP^{TM} does not assert the \overline{RESET} pin when under VBO.

Note: The external Reset does not initiate an exit from STOP mode.

Functional Description

This device incorporates special functions to enhance the Z8[®], functionality in consumer and battery-operated applications.

Program Memory

This device addresses up to 32KB of OTP memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts.

RAM

This device features 256B of RAM. See Figure 14.

In Demodulation Mode, when set to 0, T16 captures and reloads on detection of all the edges. When set to 1, T16 captures and detects on the first edge but ignores the subsequent edges. For details, see the description of T16 Demodulation Mode on page 45.

Time Out

This bit is set when T16 times out (terminal count reached). To reset the bit, write a 1 to this location.

T16 Clock

This bit defines the frequency of the input signal to Counter/Timer16.

Capture_INT_Mask

This bit is set to allow an interrupt when data is captured into LO16 and HI16.

Counter_INT_Mask

Set this bit to allow an interrupt when T16 times out.

P35_Out

This bit defines whether P35 is used as a normal output pin or T16 output.

CTR3 T8/T16 Control Register—CTR3(D)03H

Table 15 lists and briefly describes the fields for this register. This register allows the T_8 and T_{16} counters to be synchronized.

Table 15. CTR3 (D)03H: T8/T16 Control Register

Field	Bit Position		Value	Description
T ₁₆ Enable	7	R	0*	Counter Disabled
		R	1	Counter Enabled
		W	0	Stop Counter
		W	1	Enable Counter
T ₈ Enable	-6	R	0*	Counter Disabled
		R	1	Counter Enabled
		W	0	Stop Counter
		W	1	Enable Counter
Sync Mode	5	R/W	0**	Disable Sync Mode
•			1	Enable Sync Mode



Note: The letter h denotes hexadecimal values.

Transition from 0 to FFh is not a timeout condition.



Caution: Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur. See Figure 21 and Figure 22.

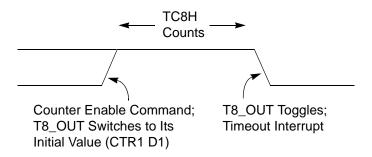


Figure 21. T8_OUT in Single-Pass Mode

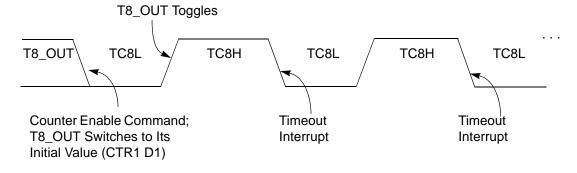


Figure 22. T8_OUT in Modulo-N Mode

T8 Demodulation Mode

The user must program TC8L and TC8H to FFH. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put

into LO8; if it is a negative edge, data is put into HI8. From that point, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt can be generated if enabled (CTR0, D2). Meanwhile, T8 is loaded with FFh and starts counting again. If T8 reaches 0, the timeout status bit (CTR0, D5) is set, and an interrupt can be generated if enabled (CTR0, D1). T8 then continues counting from FFH (see Figure 23 and Figure 24).

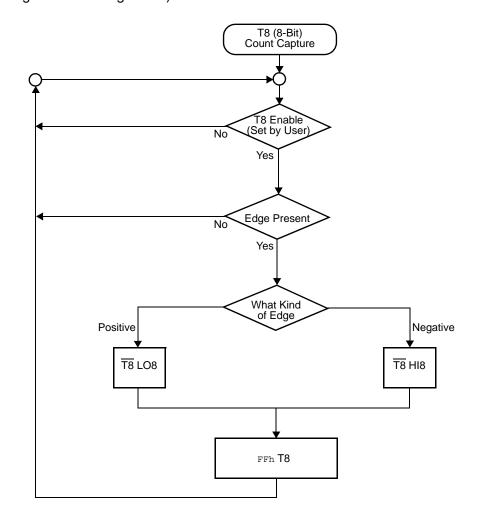


Figure 23. Demodulation Mode Count Capture Flowchart



During PING-PONG Mode

The enable bits of T8 and T16 (CTR0, D7; CTR2, D7) are set and cleared alternately by hardware. The timeout bits (CTR0, D5; CTR2, D5) are set every time the counter/timers reach the terminal count.

Timer Output

The output logic for the timers is illustrated in Figure 29. P34 is used to output T8-OUT when D0 of CTR0 is set. P35 is used to output the value of TI6-OUT when D0 of CTR2 is set. When D6 of CTR1 is set, P36 outputs the logic combination of T8-OUT and T16-OUT determined by D5 and D4 of CTR1.

Interrupts

The Z8 GPTM OTP MCU Family features six different interrupts (Table 16). The interrupts are maskable and prioritized (Figure 30). The six sources are divided as follows: three sources are claimed by Port 3 lines P33–P31, two by the counter/timers (Table 16) and one for low voltage detection. The Interrupt Mask Register (globally or individually) enables or disables the six interrupt requests.

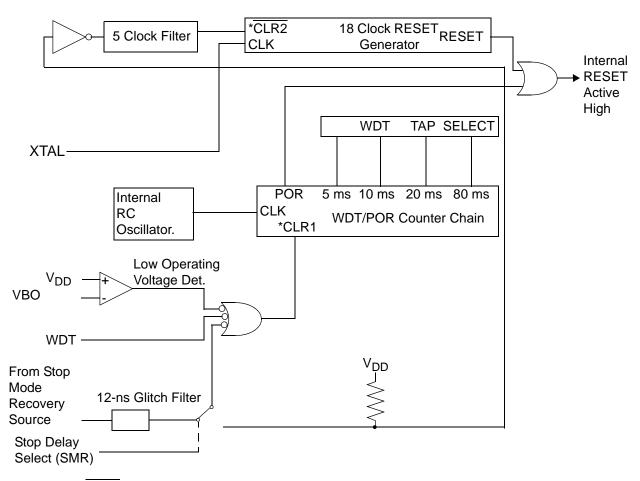
The source for IRQ is determined by bit 1 of the Port 3 mode register (P3M). When in digital mode, Pin P33 is the source. When in analog mode the output of the Stop mode recovery source logic is used as the source for the interrupt. See Figure 35, Stop Mode Recovery Source, on page 57.

Table 20. Watch-Dog Timer Time Select

D1	D0	Timeout of Internal RC-Oscillator
0	0	5ms min.
0	1	10ms min.
1	0	20ms min.
1	1	80ms min.

WDTMR During Halt (D2)

This bit determines whether or not the WDT is active during HALT Mode. A 1 indicates active during HALT. The default is 1. See Figure 38.



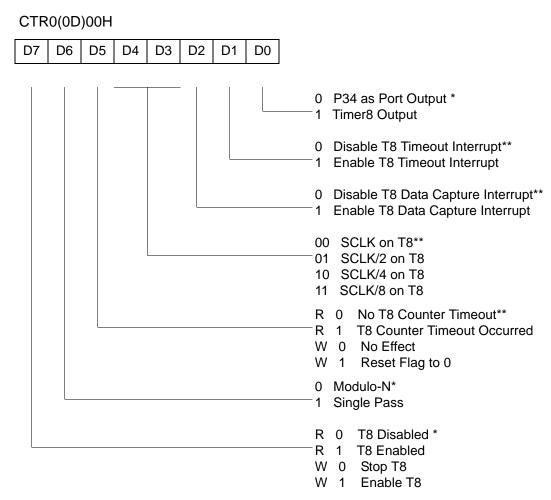
^{*} CLR1 and CLR2 enable the WDT/POR and 18 Clock Reset timers respectively upon a Low-to-High input translation.

Figure 38. Resets and WDT



Expanded Register File Control Registers (0D)

The expanded register file control registers (0D) are depicted in Figure 39 through Figure 43.



^{*} Default setting after reset

Figure 39. TC8 Control Register ((0D)O0H: Read/Write Except Where Noted)

^{**}Default setting after reset. Not reset with Stop Mode recovery.

CTR1(0D)01H D7 D6 D5 D3 D1 D0 D4 D2 Transmit Mode* R/W 0 T16_OUT is 0 initially* 1 T16_OUT is 1 initially **Demodulation Mode** R 0 No Falling Edge Detection R 1 Falling Edge Detection W 0 No Effect W 1 Reset Flag to 0 Transmit Mode* R/W 0 T8_OUT is 0 initially* 1 T8_OUT is 1 initially **Demodulation Mode** R 0 No Rising Edge Detection R 1 Rising Edge Detection W 0 No Effect W 1 Reset Flag to 0 Transmit Mode* 0 0 Normal Operation* 0 1 Ping-Pong Mode 1 0 T16_OUT = 0 1 1 T16_OUT = 1 **Demodulation Mode** 0 0 No Filter 0 1 4 SCLK Cycle Filter 1 0 8 SCLK Cycle Filter 1 1 Reserved Transmit Mode/T8/T16 Logic 0 0 AND** 0 1 OR 1 0 NOR 1 1 NAND **Demodulation Mode** 0 0 Falling Edge Detection 0 1 Rising Edge Detection 1 0 Both Edge Detection 1 1 Reserved Transmit Mode 0 P36 as Port Output * 1 P36 as T8/T16_OUT **Demodulation Mode** 0 P31 as Demodulator Input 1 P20 as Demodulator Input Transmit/Demodulation Mode 0 Transmit Mode * * Default setting after reset **Default setting after reset. Not reset with Stop Mode 1 Demodulation Mode

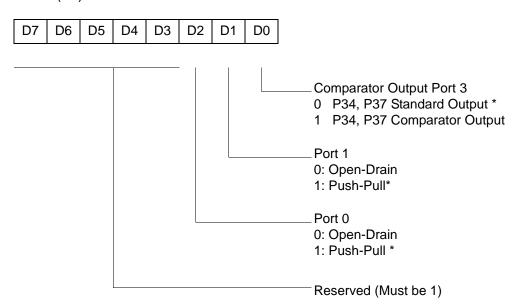
Figure 40. T8 and T16 Common Control Functions ((0D)01H: Read/Write)

recovery

Notes: Take care in differentiating the Transmit Mode from Demodulation Mode. Depending on which of these two modes is operating, the CTR1 bit has different functions.

> Changing from one mode to another cannot be performed without disabling the counter/timers.

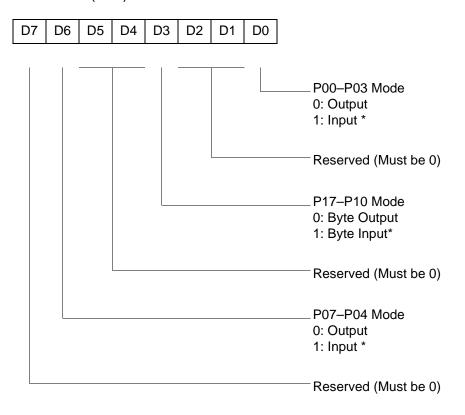
PCON(0F)00H



^{*} Default setting after reset

Figure 44. Port Configuration Register (PCON)(0F)00H: Write Only)

R248 P01M(F8H)



^{*} Default setting after reset; only P00, P01 and P07 are available in 20-pin configurations.

Figure 50. Port 0 and 1 Mode Register (F8H: Write Only)



R249 IPR(F9H)

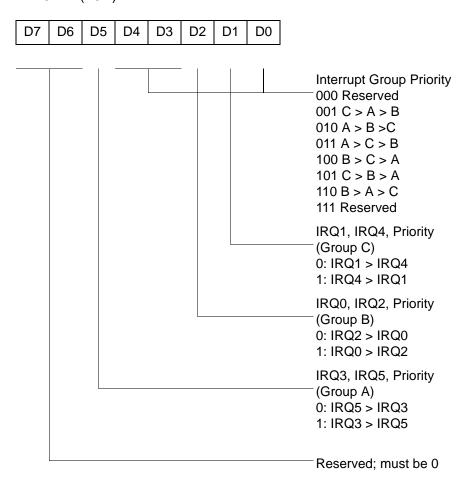
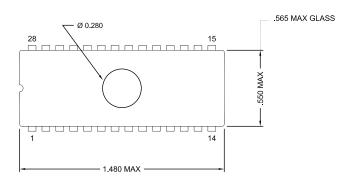
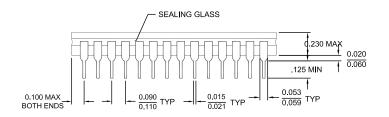


Figure 51. Interrupt Priority Register (F9H: Write Only)

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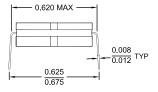


Figure 62. 28-Pin CDIP Package