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What is "Embedded - Microcontrollers"?

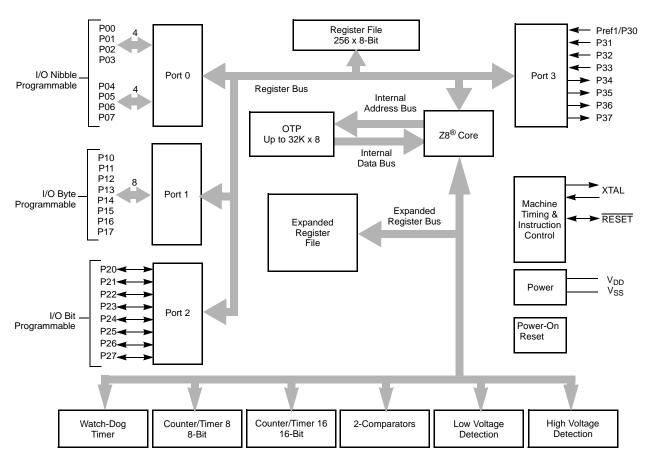
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	16
Program Memory Size	16KB (16K x 8)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323leh2016c00tr

Table 2. Power Connections

Connection	Circuit	Device
Power	V _{CC}	V_{DD}
Ground	GND	V _{SS}



Note: Refer to the specific package for available pins.

Figure 1. Functional Block Diagram



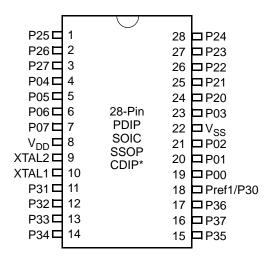


Figure 4. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Configuration

Table 4. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Identification

Pin	Symbol	Direction	Description
1-3	P25-P27	Input/Output	Port 2, Bits 5,6,7
4-7	P04-P07	Input/Output	Port 0, Bits 4,5,6,7
8	V_{DD}		Power supply
9	XTAL2	Output	Crystal, oscillator clock
10	XTAL1	Input	Crystal, oscillator clock
11-13	P31-P33	Input	Port 3, Bits 1,2,3
14	P34	Output	Port 3, Bit 4
15	P35	Output	Port 3, Bit 5
16	P37	Output	Port 3, Bit 7
17	P36	Output	Port 3, Bit 6
18	Pref1/P30	Input	Analog ref input; connect to V _{CC} if not used
	Port 3 Bit 0		Input for Pref1/P30
19-21	P00-P02	Input/Output	Port 0, Bits 0,1,2
22	V_{SS}		Ground
23	P03	Input/Output	Port 0, Bit 3
24-28	P20-P24	Input/Output	Port 2, Bits 0-4

Note: *Windowed Cerdip. These units are intended to be used for engineering code development only. ZiLOG does not recommend/guarantee this package for production use.





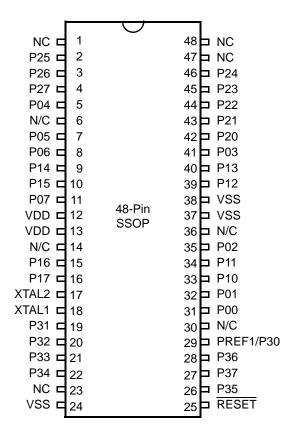


Figure 6. 48-Pin SSOP Pin Configuration

Table 5. 40- and 48-Pin Configuration

40-Pin PDIP/CDIP* #	48-Pin SSOP#	Symbol
26	31	P00
27	32	P01
30	35	P02
34	41	P03
5	5	P04
6	7	P05
7	8	P06
10	11	P07
28	33	P10
29	34	P11
32	39	P12

Absolute Maximum Ratings

Stresses greater than those listed in Table 7 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

Table 6. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	С	
Storage temperature	-65	+150	С	
Voltage on any pin with respect to V _{SS}	-0.3	+5.5	V	1
Voltage on V _{DD} pin with respect to V _{SS}	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	- 5	+5	μA	
Maximum output current from active output pin	-25	+25	mA	
Maximum current into V _{DD} or out of V _{SS}		75	mA	

Notes:

This voltage applies to all pins except the following: V_{DD}, P32, P33 and RESET.

Standard Test Conditions

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 7).

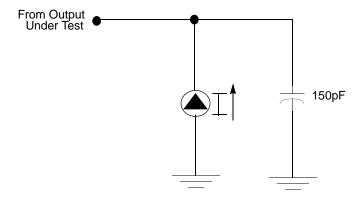


Figure 7. Test Load Diagram



Table 8. DC Characteristics (Continued)

T _A = 0°C to +70°C								
Symbol	Parameter	V_{CC}	Min	Тур	Max	Units	Conditions	Notes
I _{CC1}	Standby Current	2.0			3	mΑ	$V_{IN} = 0V$, V_{CC} at 8.0MHz	1, 2
	(HALT Mode)	3.6			5		Same as above	1, 2
		2.0			2		Clock Divide-by-16 at 8.0MHz	1, 2
		3.6			4		Same as above	1, 2
I _{CC2}	Standby Current (Stop	2.0			8	μΑ	V _{IN} = 0 V, V _{CC} WDT is not Running	3
	Mode)	3.6			10	μΑ	Same as above	3
		2.0			500	μΑ	$V_{IN} = 0 \text{ V}, V_{CC} \text{ WDT is Running}$	3
		3.6			800	μA	Same as above	3
I _{LV}	Standby Current				10	μΑ	Measured at 1.3V	4
	(Low Voltage)							
V _{BO}	V _{CC} Low Voltage				2.0	V	8MHz maximum	
	Protection						Ext. CLK Freq.	
V_{LVD}	Vcc Low Voltage			2.4		V		
	Detection							
V_{HVD}	Vcc High Voltage			2.7		V		
	Detection							

Notes:

- 1. All outputs unloaded, inputs at rail.
- 2. CL1 = CL2 = 100 pF.
- 3. Oscillator stopped.
- Oscillator stops when V_{CC} falls below V_{BO} limit.
 It is strongly recommended to add a filter capacitor (minimum 0.1 μF), physically close to the V_{DD} and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.

AC Characteristics

Figure 8 and Table 10 describe the Alternating Current (AC) characteristics.

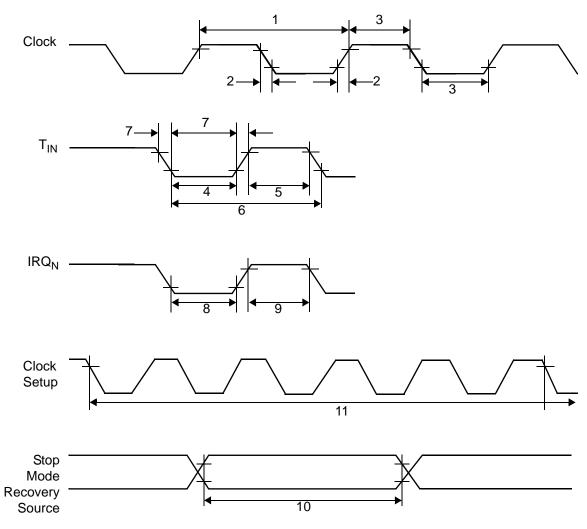


Figure 8. AC Timing Diagram

Comparator Inputs

In analog mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 12 on page 20. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.

Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery source, these inputs must be placed into digital mode.

Comparator Outputs

These channels can be programmed to be output on P34 and P37 through the PCON register.

RESET (Input, Active Low)

Reset initializes the MCU and is accomplished either through Power-On, Watch-Dog Timer, Stop Mode Recovery, Low-Voltage detection, or external reset. During Power-On Reset and Watch-Dog Timer Reset, the internally generated reset drives the reset pin Low for the POR time. Any devices driving the external reset line must be open-drain to avoid damage from a possible conflict during reset conditions. Pull-up is provided internally.

When the Z8 GP^{TM} asserts (Low) the \overline{RESET} pin, the internal pull-up is disabled. The Z8 GP^{TM} does not assert the \overline{RESET} pin when under VBO.

Note: The external Reset does not initiate an exit from STOP mode.

Functional Description

This device incorporates special functions to enhance the Z8[®], functionality in consumer and battery-operated applications.

Program Memory

This device addresses up to 32KB of OTP memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts.

RAM

This device features 256B of RAM. See Figure 14.

T8/T16_Logic/Edge _Detect

In TRANSMIT Mode, this field defines how the outputs of T8 and T16 are combined (AND, OR, NOR, NAND).

In DEMODULATION Mode, this field defines which edge should be detected by the edge detector.

Transmit_Submode/Glitch Filter

In Transmit Mode, this field defines whether T8 and T16 are in the PING-PONG mode or in independent normal operation mode. Setting this field to "NORMAL OPERATION Mode" terminates the "PING-PONG Mode" operation. When set to 10, T16 is immediately forced to a 0; a setting of 11 forces T16 to output a 1.

In DEMODULATION Mode, this field defines the width of the glitch that must be filtered out.

Initial_T8_Out/Rising_Edge

In TRANSMIT Mode, if 0, the output of T8 is set to 0 when it starts to count. If 1, the output of T8 is set to 1 when it starts to count. When the counter is not enabled and this bit is set to 1 or 0, T8_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D1.

In DEMODULATION Mode, this bit is set to 1 when a rising edge is detected in the input signal. In order to reset the mode, a 1 should be written to this location.

Initial_T16 Out/Falling _Edge

In TRANSMIT Mode, if it is 0, the output of T16 is set to 0 when it starts to count. If it is 1, the output of T16 is set to 1 when it starts to count. This bit is effective only in Normal or PING-PONG Mode (CTR1, D3; D2). When the counter is not enabled and this bit is set, T16_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D0.

In DEMODULATION Mode, this bit is set to 1 when a falling edge is detected in the input signal. In order to reset it, a 1 should be written to this location.

Note: Modifying CTR1 (D1 or D0) while the counters are enabled causes unpredictable output from T8/16_OUT.

CTR2 Counter/Timer 16 Control Register—CTR2(D)02H

Table 14 lists and briefly describes the fields for this register.

In Demodulation Mode, when set to 0, T16 captures and reloads on detection of all the edges. When set to 1, T16 captures and detects on the first edge but ignores the subsequent edges. For details, see the description of T16 Demodulation Mode on page 45.

Time Out

This bit is set when T16 times out (terminal count reached). To reset the bit, write a 1 to this location.

T16 Clock

This bit defines the frequency of the input signal to Counter/Timer16.

Capture_INT_Mask

This bit is set to allow an interrupt when data is captured into LO16 and HI16.

Counter_INT_Mask

Set this bit to allow an interrupt when T16 times out.

P35_Out

This bit defines whether P35 is used as a normal output pin or T16 output.

CTR3 T8/T16 Control Register—CTR3(D)03H

Table 15 lists and briefly describes the fields for this register. This register allows the T_8 and T_{16} counters to be synchronized.

Table 15. CTR3 (D)03H: T8/T16 Control Register

Field	Bit Position		Value	Description
T ₁₆ Enable	7	R	0*	Counter Disabled
		R	1	Counter Enabled
		W	0	Stop Counter
		W	1	Enable Counter
T ₈ Enable	-6	R	0*	Counter Disabled
-		R	1	Counter Enabled
		W	0	Stop Counter
		W	1	Enable Counter
Sync Mode	5	R/W	0**	Disable Sync Mode
•			1	Enable Sync Mode

into LO8; if it is a negative edge, data is put into HI8. From that point, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt can be generated if enabled (CTR0, D2). Meanwhile, T8 is loaded with FFh and starts counting again. If T8 reaches 0, the timeout status bit (CTR0, D5) is set, and an interrupt can be generated if enabled (CTR0, D1). T8 then continues counting from FFH (see Figure 23 and Figure 24).

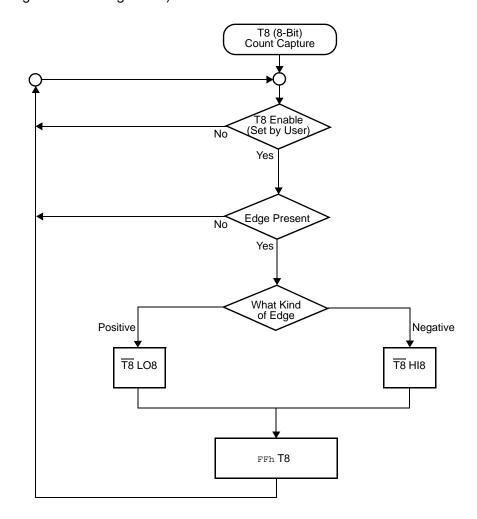


Figure 23. Demodulation Mode Count Capture Flowchart



48

During PING-PONG Mode

The enable bits of T8 and T16 (CTR0, D7; CTR2, D7) are set and cleared alternately by hardware. The timeout bits (CTR0, D5; CTR2, D5) are set every time the counter/timers reach the terminal count.

Timer Output

The output logic for the timers is illustrated in Figure 29. P34 is used to output T8-OUT when D0 of CTR0 is set. P35 is used to output the value of TI6-OUT when D0 of CTR2 is set. When D6 of CTR1 is set, P36 outputs the logic combination of T8-OUT and T16-OUT determined by D5 and D4 of CTR1.

Interrupts

The Z8 GPTM OTP MCU Family features six different interrupts (Table 16). The interrupts are maskable and prioritized (Figure 30). The six sources are divided as follows: three sources are claimed by Port 3 lines P33–P31, two by the counter/timers (Table 16) and one for low voltage detection. The Interrupt Mask Register (globally or individually) enables or disables the six interrupt requests.

The source for IRQ is determined by bit 1 of the Port 3 mode register (P3M). When in digital mode, Pin P33 is the source. When in analog mode the output of the Stop mode recovery source logic is used as the source for the interrupt. See Figure 35, Stop Mode Recovery Source, on page 57.



Port 0 Output Mode (D2)

Bit 2 controls the output mode of port 0. A 1 in this location sets the output to push-pull, and a 0 sets the output to open-drain.

Stop-Mode Recovery Register (SMR)

This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 33). All bits are write only except bit 7, which is read only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level at the XORgate input (Figure 35 on page 57) is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits D2, D3, and D4 of the SMR register specify the source of the Stop Mode Recovery signal. Bits D0 determines if SCLK/ TCLK are divided by 16 or not. The SMR is located in Bank F of the Expanded Register Group at address OBH.



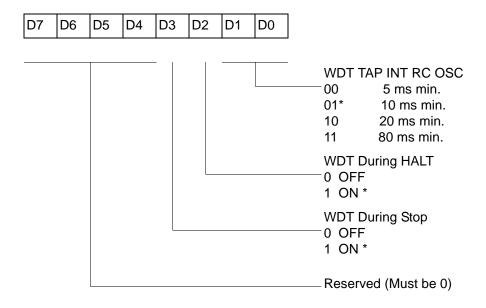
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Watch-Dog Timer Mode Register (WDTMR)

The Watch-Dog Timer (WDT) is a retriggerable one-shot timer that resets the Z8[®] CPU if it reaches its terminal count. The WDT must initially be enabled by executing the WDT instruction. On subsequent executions of the WDT instruction, the WDT is refreshed. The WDT circuit is driven by an on-board RC-oscillator. The WDT instruction affects the Zero (Z), Sign (S), and Overflow (V) flags.

The POR clock source the internal RC-oscillator. Bits 0 and 1 of the WDT register control a tap circuit that determines the minimum timeout period. Bit 2 determines whether the WDT is active during HALT, and Bit 3 determines WDT activity during Stop. Bits 4 through 7 are reserved (Figure 37). This register is accessible only during the first 60 processor cycles (120 XTAL clocks) from the execution of the first instruction after Power-On-Reset, Watch-Dog Reset, or a Stop-Mode Recovery (Figure 36). After this point, the register cannot be modified by any means (intentional or otherwise). The WDTMR cannot be read. The register is located in Bank F of the Expanded Register Group at address location <code>0Fh</code>. It is organized as shown in Figure 37.

WDTMR(0F)0Fh



^{*} Default setting after reset

Figure 37. Watch-Dog Timer Mode Register (Write Only)

WDT Time Select (D0, D1)

This bit selects the WDT time period. It is configured as indicated in Table 20.

WDTMR During STOP (D3)

This bit determines whether or not the WDT is active during STOP Mode. Because the XTAL clock is stopped during STOP Mode, the on-board RC has to be selected as the clock source to the WDT/POR counter. A 1 indicates active during Stop. The default is 1.

EPROM Selectable Options

There are seven EPROM Selectable Options to choose from based on ROM code requirements. These options are listed in Table 21.

Table 21. EPROM Selectable Options

Port 00–03 Pull-Ups	On/Off
Port 04–07 Pull-Ups	On/Off
Port 10–13 Pull-Ups	On/Off
Port 14–17 Pull-Ups	On/Off
Port 20–27 Pull-Ups	On/Off
EPROM Protection	On/Off
Watch-Dog Timer at Power-On Reset	On/Off

Voltage Brown-Out/Standby

An on-chip Voltage Comparator checks that the V_{DD} is at the required level for correct operation of the device. Reset is globally driven when V_{DD} falls below V_{BO}. A small drop in V_{DD} causes the XTAL1 and XTAL2 circuitry to stop the crystal or resonator clock. If the V_{DD} is allowed to stay above V_{RAM}, the RAM content is preserved. When the power level is returned to above V_{BO}, the device performs a POR and functions normally.

CTR1(0D)01H D7 D6 D5 D3 D1 D0 D4 D2 Transmit Mode* R/W 0 T16_OUT is 0 initially* 1 T16_OUT is 1 initially **Demodulation Mode** R 0 No Falling Edge Detection R 1 Falling Edge Detection W 0 No Effect W 1 Reset Flag to 0 Transmit Mode* R/W 0 T8_OUT is 0 initially* 1 T8_OUT is 1 initially **Demodulation Mode** R 0 No Rising Edge Detection R 1 Rising Edge Detection W 0 No Effect W 1 Reset Flag to 0 Transmit Mode* 0 0 Normal Operation* 0 1 Ping-Pong Mode 1 0 T16_OUT = 0 1 1 T16_OUT = 1 **Demodulation Mode** 0 0 No Filter 0 1 4 SCLK Cycle Filter 1 0 8 SCLK Cycle Filter 1 1 Reserved Transmit Mode/T8/T16 Logic 0 0 AND** 0 1 OR 1 0 NOR 1 1 NAND **Demodulation Mode** 0 0 Falling Edge Detection 0 1 Rising Edge Detection 1 0 Both Edge Detection 1 1 Reserved Transmit Mode 0 P36 as Port Output * 1 P36 as T8/T16_OUT **Demodulation Mode** 0 P31 as Demodulator Input 1 P20 as Demodulator Input Transmit/Demodulation Mode 0 Transmit Mode * * Default setting after reset **Default setting after reset. Not reset with Stop Mode 1 Demodulation Mode

Figure 40. T8 and T16 Common Control Functions ((0D)01H: Read/Write)

recovery

CTR2(0D)02H

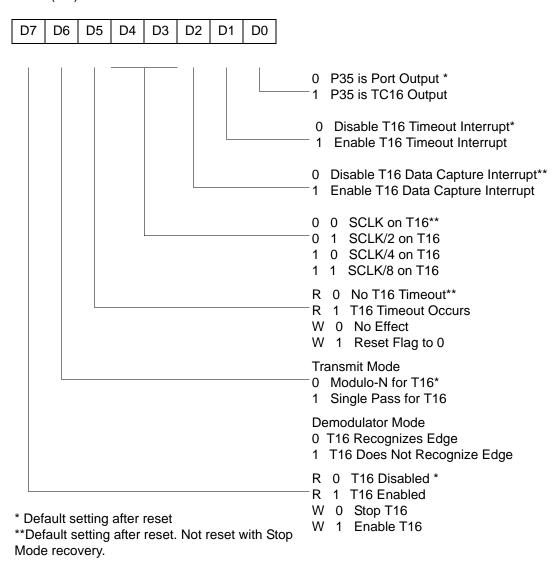
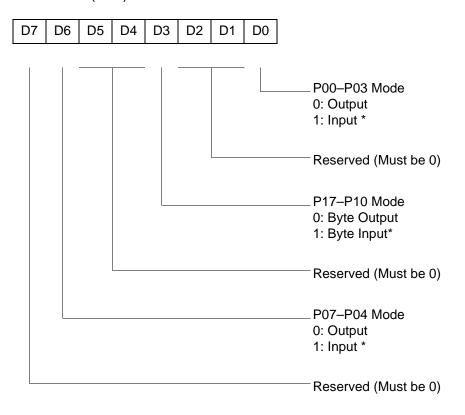


Figure 41. T16 Control Register ((0D) 2H: Read/Write Except Where Noted)

R248 P01M(F8H)



^{*} Default setting after reset; only P00, P01 and P07 are available in 20-pin configurations.

Figure 50. Port 0 and 1 Mode Register (F8H: Write Only)

 $P31\uparrow\downarrow$ $P32\uparrow\downarrow=11$

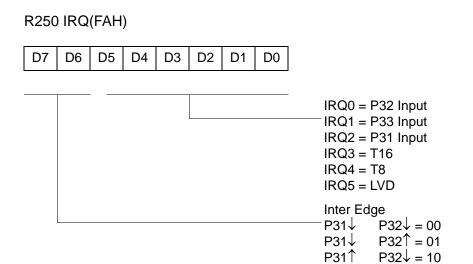
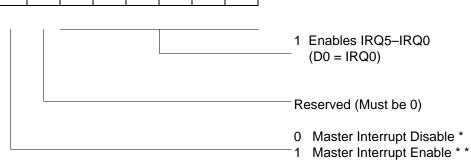


Figure 52. Interrupt Request Register (FAH: Read/Write)

D7 D6 D5 D4 D3 D2 D1 D0



^{*} Default setting after reset

R251 IMR(FBH)

Figure 53. Interrupt Mask Register (FBH: Read/Write)

^{* *} Only by using EI, DI instruction; DI is required before changing the IMR register

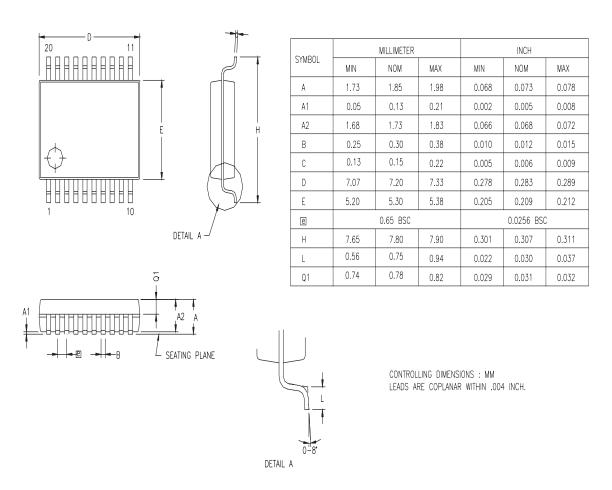


Figure 61. 20-Pin SSOP Package Diagram



96

Index

Numerics	Counter/timer
16-bit counter/timer circuits 44	16-bit circuits 44
20-pin DIP package diagram 81	8-bit circuits 40
20-pin SSOP package diagram 82	brown-out voltage/standby 62
28-pin DIP package diagram 85	clock 51
28-pin SOICpackage diagram 84	demodulation mode count capture flow-
28-pin SSOP package diagram 86	chart 42
40-pin DIP package diagram 87	demodulation mode flowchart 43
48-pin SSOP package diagram 88	EPROM selectable options 62
8-bit counter/timer circuits 40	glitch filter circuitry 38
	halt instruction 52
	input circuit 38
A	interrupt block diagram 49
absolute maximum ratings 10	interrupt types, sources and vectors 50
AC	oscillator configuration 51
characteristics 14	output circuit 47
timing diagram 14	ping-pong mode 46
address spaces, basic 2	port configuration register 53
architecture 2	resets and WDT 61
expanded register file 26	SCLK circuit 56
	stop instruction 52
	stop mode recovery register 55
В	stop mode recovery register 2 59
basic address spaces 2	stop mode recovery source 57
block diagram, ZLP32300 functional 3	T16 demodulation mode 45
block diagram, ZEI 32300 farictional 3	T16 transmit mode 44
	T16_OUT in modulo-N mode 45
С	T16_OUT in single-pass mode 45
	T8 demodulation mode 41
capacitance 11 characteristics	T8 transmit mode 38
AC 14	T8_OUT in modulo-N mode 41
DC 11	T8_OUT in single-pass mode 41
clock 51	transmit mode flowchart 39
comparator inputs/outputs 23	voltage detection and flags 63
configuration	watch-dog timer mode register 60
port 0 17	watch-dog timer time select 61
port 1 18	CTR(D)01h T8 and T16 Common Functions 33
port 2 19	
port 3 20	
port 3 counter/timer 22	
port 3 counter/timel 22	