AMD Xilinx - XCS20XL-4CS144C Datasheet

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	400
Number of Logic Elements/Cells	950
Total RAM Bits	12800
Number of I/O	113
Number of Gates	20000
Voltage - Supply	3V ~ 3.6V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	144-TFBGA, CSPBGA
Supplier Device Package	144-LCSBGA (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/xilinx/xcs20xl-4cs144c

General Overview

Spartan series FPGAs are implemented with a regular, flexible, programmable architecture of Configurable Logic Blocks (CLBs), interconnected by a powerful hierarchy of versatile routing resources (routing channels), and surrounded by a perimeter of programmable Input/Output Blocks (IOBs), as seen in Figure 1. They have generous routing resources to accommodate the most complex interconnect patterns.

The devices are customized by loading configuration data into internal static memory cells. Re-programming is possible an unlimited number of times. The values stored in these memory cells determine the logic functions and interconnections implemented in the FPGA. The FPGA can either actively read its configuration data from an external serial PROM (Master Serial mode), or the configuration data can be written into the FPGA from an external device (Slave Serial mode).

Spartan series FPGAs can be used where hardware must be adapted to different user applications. FPGAs are ideal for shortening design and development cycles, and also offer a cost-effective solution for production rates well beyond 50,000 systems per month.

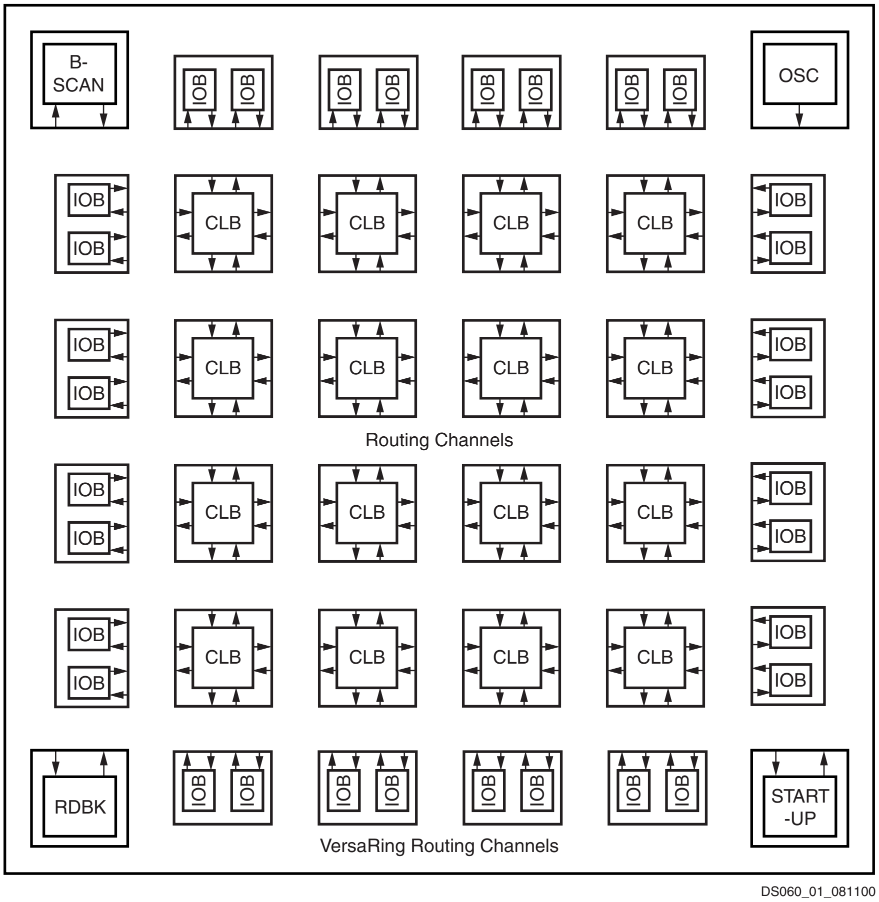


Figure 1: **Basic FPGA Block Diagram**

Table 4: **Supported Sources for Spartan/XL Inputs**

	Spartan Inputs		Spartan-XL Inputs
Source	**5V, TTL**	**5V, CMOS**	**3.3V CMOS**
Any device, V_{CC} = 3.3V, CMOS outputs	√	Unreliable Data	√
Spartan family, V_{CC} = 5V, TTL outputs	√		√
Any device, V_{CC} = 5V, TTL outputs ($V_{OH} \le 3.7V$)	√		√
Any device, V_{CC} = 5V, CMOS outputs	√	√	√ (default mode)

Spartan-XL Family V_{CC} Clamping

Spartan-XL FPGAs have an optional clamping diode connected from each I/O to V_{CC}. When enabled they clamp ringing transients back to the 3.3V supply rail. This clamping action is required in 3.3V PCI applications. V_{CC} clamping is a global option affecting all I/O pins.

Spartan-XL devices are fully 5V TTL I/O compatible if V_{CC} clamping is not enabled. With V_{CC} clamping enabled, the Spartan-XL devices will begin to clamp input voltages to one diode voltage drop above V_{CC}. If enabled, TTL I/O compatibility is maintained but full 5V I/O tolerance is sacrificed. The user may select either 5V tolerance (default) or 3.3V PCI compatibility. In both cases negative voltage is clamped to one diode voltage drop below ground.

Spartan-XL devices are compatible with TTL, LVTTL, PCI 3V, PCI 5V and LVCMOS signalling. The various standards are illustrated in Table 5.

Table 5: **I/O Standards Supported by Spartan-XL FPGAs**

Signaling Standard	VCC Clamping	Output Drive	$V_{IH\ MAX}$	$V_{IH\ MIN}$	$V_{IL\ MAX}$	$V_{OH\ MIN}$	$V_{OL\ MAX}$
TTL	Not allowed	12/24 mA	5.5	2.0	0.8	2.4	0.4
LVTTL	OK	12/24 mA	3.6	2.0	0.8	2.4	0.4
PCI5V	Not allowed	24 mA	5.5	2.0	0.8	2.4	0.4
PCI3V	Required	12 mA	3.6	50% of V_{CC}	30% of V_{CC}	90% of V_{CC}	10% of V_{CC}
LVCMOS 3V	OK	12/24 mA	3.6	50% of V_{CC}	30% of V_{CC}	90% of V_{CC}	10% of V_{CC}

Additional Fast Capture Input Latch (Spartan-XL Family Only)

The Spartan-XL family OB has an additional optional latch on the input. This latch is clocked by the clock used for the output flip-flop rather than the input clock. Therefore, two different clocks can be used to clock the two input storage elements. This additional latch allows the fast capture of input data, which is then synchronized to the internal clock by the IOB flip-flop or latch.

To place the Fast Capture latch in a design, use one of the special library symbols, ILFFX or ILFLX. ILFFX is a transparent-Low Fast Capture latch followed by an active High input flip-flop. ILFLX is a transparent Low Fast Capture latch followed by a transparent High input latch. Any of the clock inputs can be inverted before driving the library element, and the inverter is absorbed into the IOB.

IOB Output Signal Path

Output signals can be optionally inverted within the IOB, and can pass directly to the output buffer or be stored in an edge-triggered flip-flop and then to the output buffer. The functionality of this flip-flop is shown in Table 6.

Table 6: **Output Flip-Flop Functionality**

Mode	Clock	Clock Enable	T	D	Q
Power-Up or GSR	X	X	0*	X	SR
Flip-Flop	X	0	0*	X	Q
	↑	1*	0*	D	D
	X	X	1	X	Z
	0	X	0*	X	Q

Legend:

X	Don't care
↑	Rising edge (clock not inverted).
SR	Set or Reset value. Reset is default.
0*	Input is Low or unconnected (default value)
1*	Input is High or unconnected (default value)
Z	3-state

This high value makes them unsuitable as wired-AND pull-up resistors.

Table 7: **Supported Destinations for Spartan/XL Outputs**

Destination	Spartan-XL Outputs	Spartan Outputs	
	3.3V, CMOS	5V, TTL	5V, CMOS
Any device, V_{CC} = 3.3V, CMOS-threshold inputs	√	√	Some[1]
Any device, V_{CC} = 5V, TTL-threshold inputs	√	√	√
Any device, V_{CC} = 5V, CMOS-threshold inputs	Unreliable Data		√

Notes:
1. Only if destination device has 5V tolerant inputs.

After configuration, voltage levels of unused pads, bonded or unbonded, must be valid logic levels, to reduce noise sensitivity and avoid excess current. Therefore, by default, unused pads are configured with the internal pull-up resistor active. Alternatively, they can be individually configured with the pull-down resistor, or as a driven output, or to be driven by an external source. To activate the internal pull-up, attach the PULLUP library component to the net attached to the pad. To activate the internal pull-down, attach the PULLDOWN library component to the net attached to the pad.

Set/Reset

As with the CLB registers, the GSR signal can be used to set or clear the input and output registers, depending on the value of the INIT attribute or property. The two flip-flops can be individually configured to set or clear on reset and after configuration. Other than the global GSR net, no user-controlled set/reset signal is available to the I/O flip-flops (Figure 5). The choice of set or reset applies to both the initial state of the flip-flop and the response to the GSR pulse.

Independent Clocks

Separate clock signals are provided for the input (IK) and output (OK) flip-flops. The clock can be independently inverted for each flip-flop within the IOB, generating either falling-edge or rising-edge triggered flip-flops. The clock inputs for each IOB are independent.

Common Clock Enables

The input and output flip-flops in each IOB have a common clock enable input (see EC signal in Figure 5), which through configuration, can be activated individually for the input or output flip-flop, or both. This clock enable operates exactly like the EC signal on the Spartan/XL FPGA CLB. It cannot be inverted within the IOB.

Routing Channel Description

All internal routing channels are composed of metal segments with programmable switching points and switching matrices to implement the desired routing. A structured, hierarchical matrix of routing channels is provided to achieve efficient automated routing.

This section describes the routing channels available in Spartan/XL devices. Figure 8 shows a general block diagram of the CLB routing channels. The implementation software automatically assigns the appropriate resources based on the density and timing requirements of the design. The following description of the routing channels is for information only and is simplified with some minor details omitted. For an exact interconnect description the designer should open a design in the FPGA Editor and review the actual connections in this tool.

The routing channels will be discussed as follows;

- CLB routing channels which run along each row and column of the CLB array.
- IOB routing channels which form a ring (called a VersaRing) around the outside of the CLB array. It connects the I/O with the CLB routing channels.
- Global routing consists of dedicated networks primarily designed to distribute clocks throughout the device with minimum delay and skew. Global routing can also be used for other high-fanout signals.

CLB Routing Channels

The routing channels around the CLB are derived from three types of interconnects; single-length, double-length, and longlines. At the intersection of each vertical and horizontal routing channel is a signal steering matrix called a Programmable Switch Matrix (PSM). Figure 8 shows the basic routing channel configuration showing single-length lines, double-length lines and longlines as well as the CLBs and PSMs. The CLB to routing channel interface is shown as well as how the PSMs interface at the channel intersections.

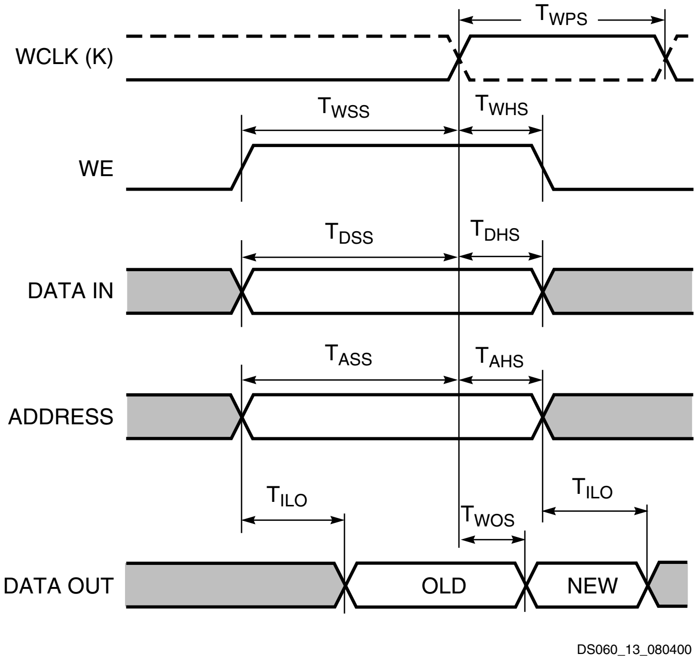


Figure 13: **Data Write and Access Timing for RAM**

WCLK can be configured as active on either the rising edge (default) or the falling edge. While the WCLK input to the RAM accepts the same signal as the clock input to the associated CLB's flip-flops, the sense of this WCLK input can be inverted with respect to the sense of the flip-flop clock inputs. Consequently, within the same CLB, data at the RAM SPO line can be stored in a flip-flop with either the same or the inverse clock polarity used to write data to the RAM.

The WE input is active High and cannot be inverted within the CLB.

Allowing for settling time, the data on the SPO output reflects the contents of the RAM location currently addressed. When the address changes, following the asynchronous delay T_{ILO}, the data stored at the new address location will appear on SPO. If the data at a particular RAM address is overwritten, after the delay T_{WOS}, the new data will appear on SPO.

Dual-Port Mode

In dual-port mode, the function generators (F-LUT and G-LUT) are used to create a 16 x 1 dual-port memory. Of the two data ports available, one permits read and write operations at the address specified by A[3:0] while the second provides only for read operations at the address specified independently by DPRA[3:0]. As a result, simultaneous read/write operations at different addresses (or even at the same address) are supported.

The functional organization of the 16 x 1 dual-port RAM is shown in Figure 14. The dual-port RAM signals and the

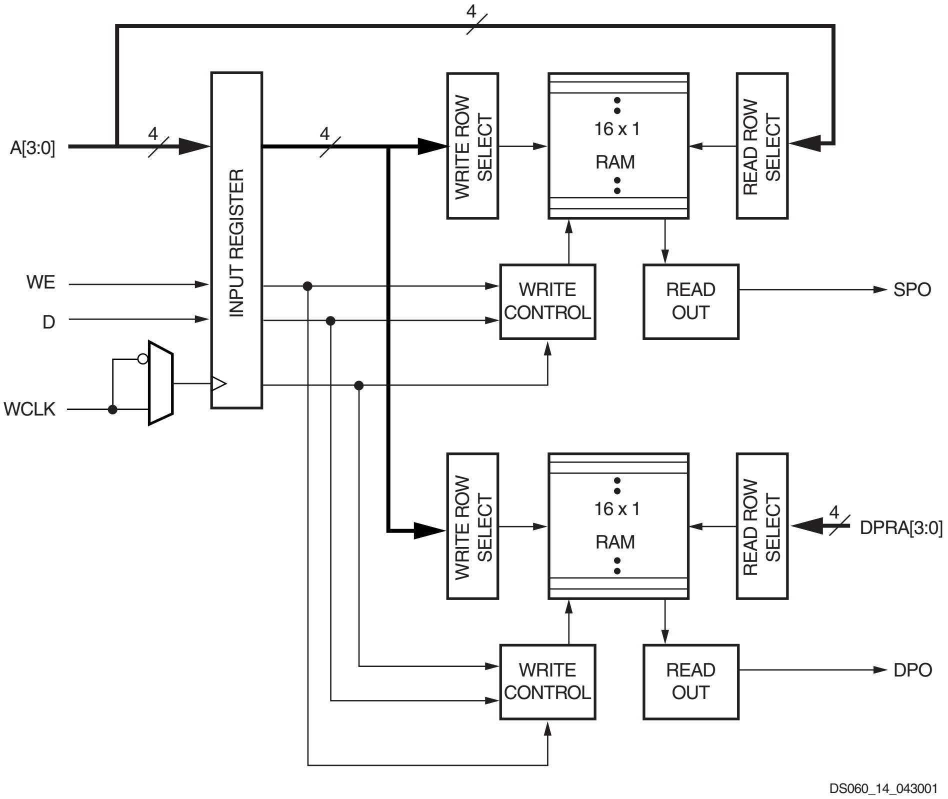


Figure 14: **Logic Diagram for the Dual-Port RAM**

and Spartan-XL families, speeding up arithmetic and counting functions.

The carry chain in 5V Spartan devices can run either up or down. At the top and bottom of the columns where there are no CLBs above and below, the carry is propagated to the right. The default is always to propagate up the column, as shown in the figures. The carry chain in Spartan-XL devices can only run up the column, providing even higher speed.

Figure 16, page 18 shows a Spartan/XL FPGA CLB with dedicated fast carry logic. The carry logic shares operand and control inputs with the function generators. The carry outputs connect to the function generators, where they are combined with the operands to form the sums.

Figure 17, page 19 shows the details of the Spartan/XL FPGA carry logic. This diagram shows the contents of the box labeled "CARRY LOGIC" in Figure 16.

The fast carry logic can be accessed by placing special library symbols, or by using Xilinx Relationally Placed Macros (RPMs) that already include these symbols.

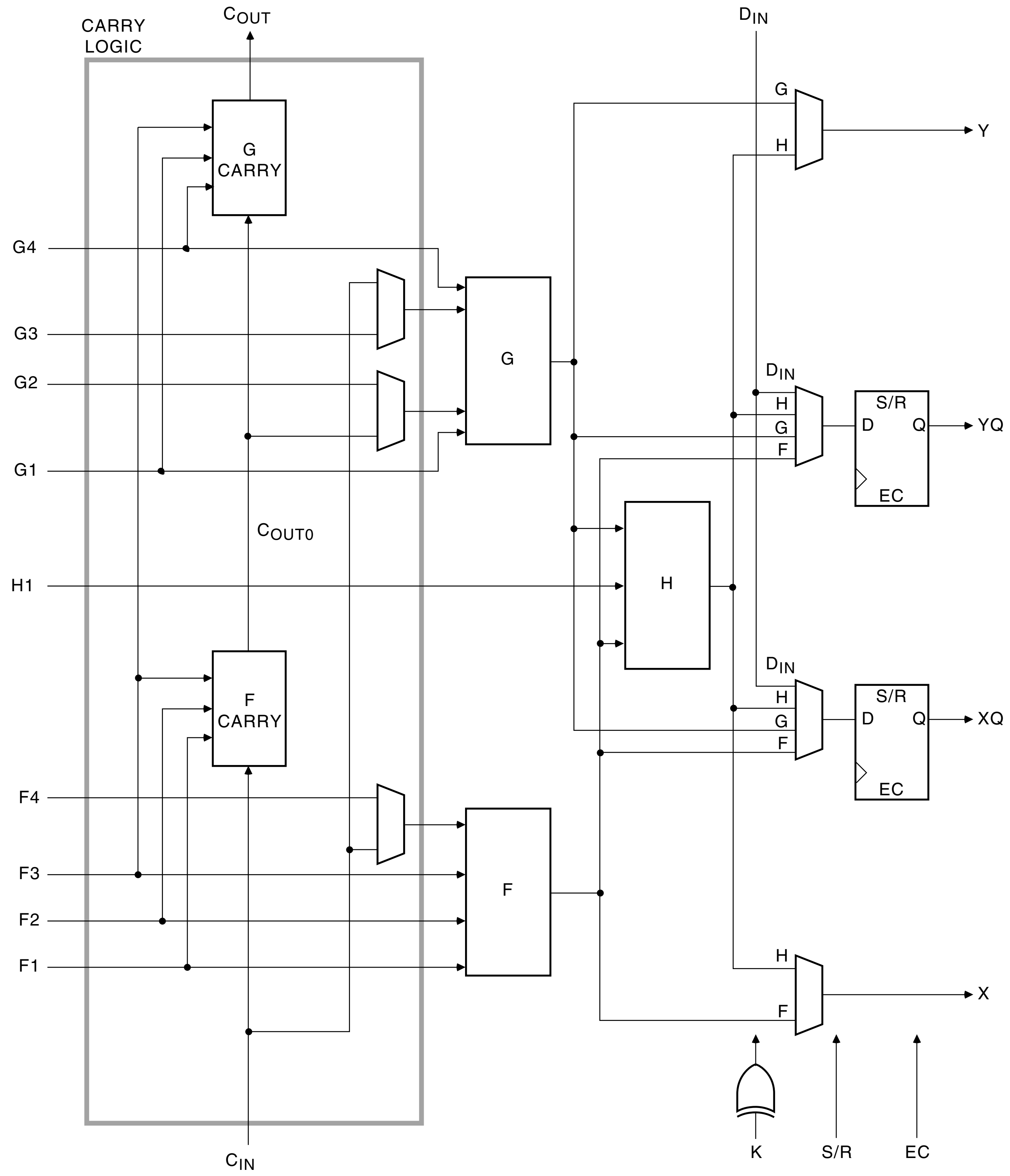


Figure 16: **Fast Carry Logic in Spartan/XL CLB**

Even if the boundary scan symbol is used in a design, the input pins TMS, TCK, and TDI can still be used as inputs to be routed to internal logic. Care must be taken not to force the chip into an undesired boundary scan state by inadvertently applying boundary scan input patterns to these pins. The simplest way to prevent this is to keep TMS High, and then apply whatever signal is desired to TDI and TCK.

Avoiding Inadvertent Boundary Scan

If TMS or TCK is used as user I/O, care must be taken to ensure that at least one of these pins is held constant during configuration. In some applications, a situation may occur where TMS or TCK is driven during configuration. This may cause the device to go into boundary scan mode and disrupt the configuration process.

To prevent activation of boundary scan during configuration, do either of the following:

- TMS: Tie High to put the Test Access Port controller in a benign RESET state.
- TCK: Tie High or Low—do not toggle this clock input.

For more information regarding boundary scan, refer to the Xilinx Application Note, "*Boundary Scan in FPGA Devices*."

Boundary Scan Enhancements (Spartan-XL Family Only)

Spartan-XL devices have improved boundary scan functionality and performance in the following areas:

IDCODE: The IDCODE register is supported. By using the IDCODE, the device connected to the JTAG port can be determined. The use of the IDCODE enables selective configuration dependent on the FPGA found.

The IDCODE register has the following binary format:

```
vvvv:ffff:fffa:aaaa:aaaa:cccc:cccc:ccc1
```

where

c = the company code (49h for Xilinx)

a = the array dimension in CLBs (ranges from 0Ah for XCS05XL to 1Ch for XCS40XL)

f = the family code (02h for Spartan-XL family)

v = the die version number

Table 13: **IDCODEs Assigned to Spartan-XL FPGAs**

FPGA	IDCODE
XCS05XL	0040A093h
XCS10XL	0040E093h
XCS20XL	00414093h
XCS30XL	00418093h
XCS40XL	0041C093h

Configuration State: The configuration state is available to JTAG controllers.

Configuration Disable: The JTAG port can be prevented from configuring the FPGA.

TCK Startup: TCK can now be used to clock the start-up block in addition to other user clocks.

CCLK Holdoff: Changed the requirement for Boundary Scan Configure or EXTEST to be issued prior to the release of INIT pin and CCLK cycling.

Reissue Configure: The Boundary Scan Configure can be reissued to recover from an unfinished attempt to configure the device.

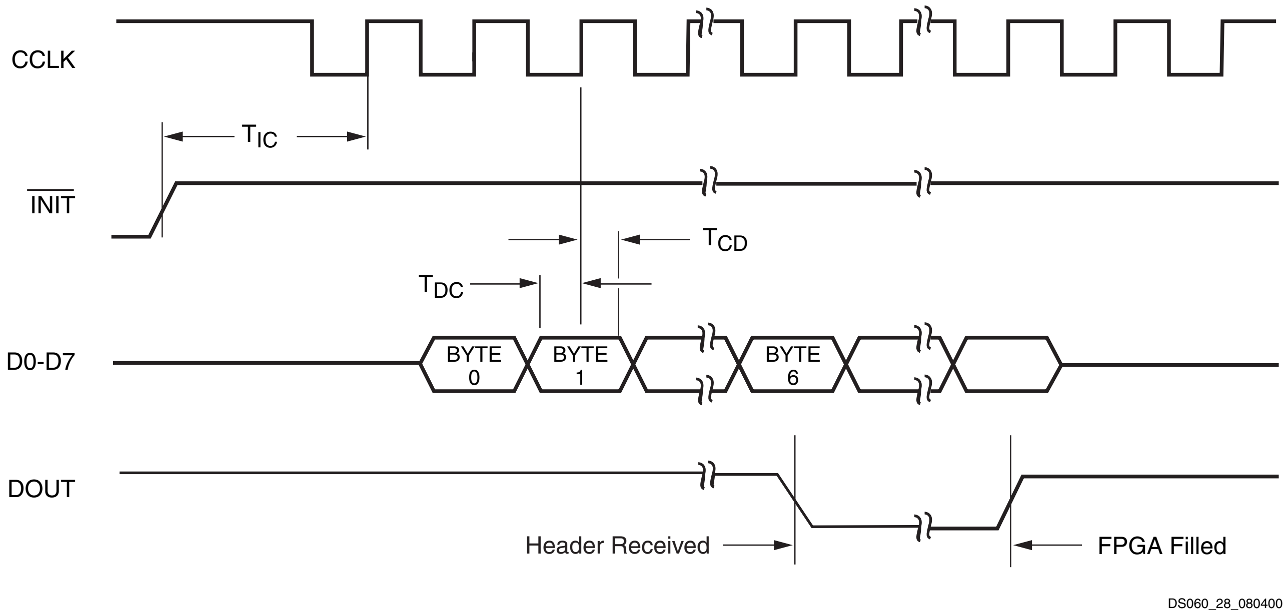
Bypass FF: Bypass FF and IOB is modified to provide DRCLOCK only during BYPASS for the bypass flip-flop, and during EXTEST or SAMPLE/PRELOAD for the IOB register.

Power-Down (Spartan-XL Family Only)

All Spartan/XL devices use a combination of efficient segmented routing and advanced process technology to provide low power consumption under all conditions. The 3.3V Spartan-XL family adds a dedicated active Low power-down pin ($\overline{\text{PWRDWN}}$) to reduce supply current to 100 µA typical. The $\overline{\text{PWRDWN}}$ pin takes advantage of one of the unused No Connect locations on the 5V Spartan device. The user must de-select the "5V Tolerant I/Os" option in the Configuration Options to achieve the specified Power Down current. The $\overline{\text{PWRDWN}}$ pin has a default internal pull-up resistor, allowing it to be left unconnected if unused.

V_{CC} must continue to be supplied during Power-down, and configuration data is maintained. When the $\overline{\text{PWRDWN}}$ pin is pulled Low, the input and output buffers are disabled. The inputs are internally forced to a logic Low level, including the MODE pins, DONE, CCLK, and TDO, and all internal pull-up resistors are turned off. The $\overline{\text{PROGRAM}}$ pin is not affected by Power Down. The GSR net is asserted during Power Down, initializing all the flip-flops to their start-up state.

$\overline{\text{PWRDWN}}$ has a minimum pulse width of 50 ns (Figure 23). On entering the Power-down state, the inputs will be disabled and the flip-flops set/reset, and then the outputs are disabled about 10 ns later. The user may prefer to assert the GTS or GSR signals before $\overline{\text{PWRDWN}}$ to affect the order of events. When the $\overline{\text{PWRDWN}}$ signal is returned High, the inputs will be enabled first, followed immediately by the release of the GSR signal initializing the flip-flops. About 10 ns later, the outputs will be enabled. Allow 50 ns after the release of $\overline{\text{PWRDWN}}$ before using the device.



Symbol		Description	Min	Max	Units
T_{IC}	CCLK	$\overline{\text{INIT}}$ (High) setup time	5	-	µs
T_{DC}		D0-D7 setup time	20	-	ns
T_{CD}		D0-D7 hold time	0	-	ns
T_{CCH}		CCLK High time	45	-	ns
T_{CCL}		CCLK Low time	45	-	ns
F_{CC}		CCLK Frequency	-	10	MHz

Notes:

1. If not driven by the preceding DOUT, CS1 *must* remain High until the device is fully configured.

Figure 28: **Express Mode Programming Switching Characteristics**

Setting CCLK Frequency

In Master mode, CCLK can be generated in either of two frequencies. In the default slow mode, the frequency ranges from 0.5 MHz to 1.25 MHz for Spartan/XL devices. In fast CCLK mode, the frequency ranges from 4 MHz to 10 MHz for Spartan/XL devices. The frequency is changed to fast by an option when running the bitstream generation software.

Data Stream Format

The data stream ("bitstream") format is identical for both serial configuration modes, but different for the Spartan-XL family Express mode. In Express mode, the device becomes active when DONE goes High, therefore no length count is required. Additionally, CRC error checking is not supported in Express mode. The data stream format is shown in Table 16. Bit-serial data is read from left to right. Express mode data is shown with D0 at the left and D7 at the right.

The configuration data stream begins with a string of eight ones, a preamble code, followed by a 24-bit length count and a separator field of ones (or 24 fill bits, in Spartan-XL family Express mode). This header is followed by the actual configuration data in frames. The length and number of frames depends on the device type (see Table 17). Each frame begins with a start field and ends with an error check. In serial modes, a postamble code is required to signal the end of data for a single device. In all cases, additional start-up bytes of data are required to provide four clocks for the startup sequence at the end of configuration. Long daisy chains require additional startup bytes to shift the last data through the chain. All start-up bytes are "don't cares".

Readback Abort

When the Readback Abort option is selected, a High-to-Low transition on RDBK.TRIG terminates the Readback operation and prepares the logic to accept another trigger.

After an aborted Readback, additional clocks (up to one Readback clock per configuration frame) may be required to re-initialize the control logic. The status of Readback is indicated by the output control net RDBK.RIP. RDBK.RIP is High whenever a readback is in progress.

Clock Select

CCLK is the default clock. However, the user can insert another clock on RDBK.CLK. Readback control and data are clocked on rising edges of RDBK.CLK. If Readback must be inhibited for security reasons, the Readback control nets are simply not connected. RDBK.CLK is located in the lower right chip corner.

Violating the Maximum High and Low Time Specification for the Readback Clock

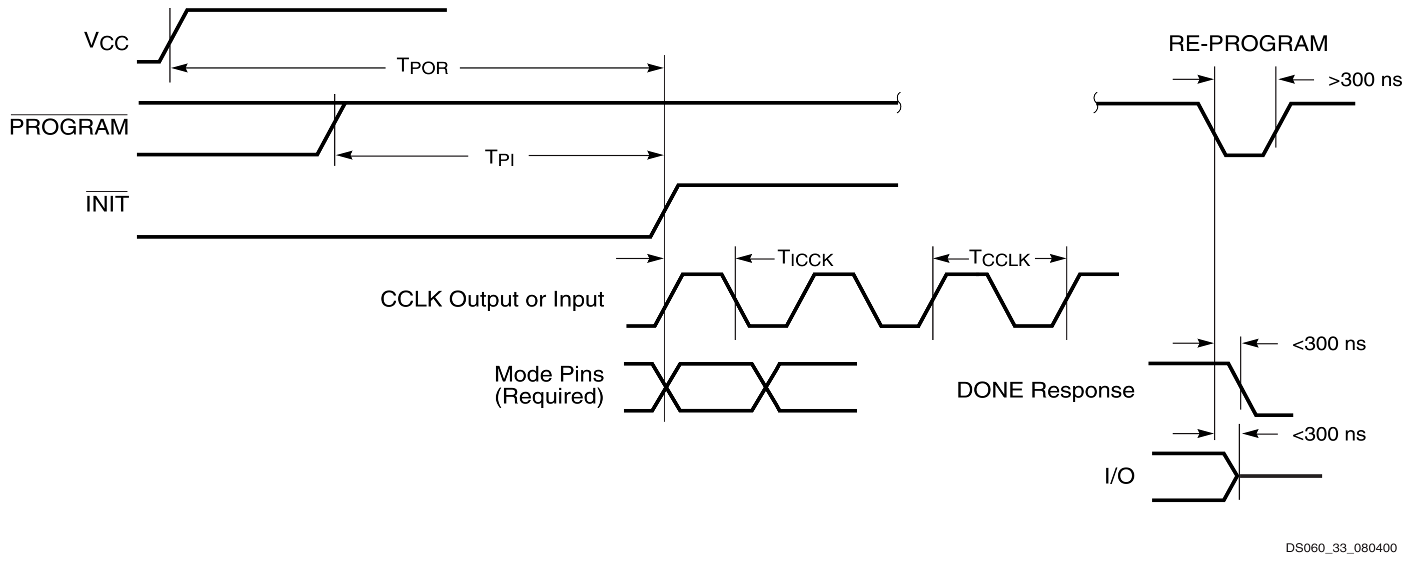
The Readback clock has a maximum High and Low time specification. In some cases, this specification cannot be met. For example, if a processor is controlling Readback, an interrupt may force it to stop in the middle of a readback. This necessitates stopping the clock, and thus violating the specification.

The specification is mandatory only on clocking data at the end of a frame prior to the next start bit. The transfer mechanism will load the data to a shift register during the last six clock cycles of the frame, prior to the start bit of the following frame. This loading process is dynamic, and is the source of the maximum High and Low time requirements.

Therefore, the specification only applies to the six clock cycles prior to and including any start bit, including the clocks before the first start bit in the Readback data stream. At other times, the frame data is already in the register and the register is not dynamic. Thus, it can be shifted out just like a regular shift register.

The user must precisely calculate the location of the Readback data relative to the frame. The system must keep track of the position within a data frame, and disable interrupts before frame boundaries. Frame lengths and data formats are listed in Table 16 and Table 17.

Configuration Switching Characteristics



Master Mode

Symbol	Description	Min	Max	Units
T_{POR}	Power-on reset	40	130	ms
T_{PI}	Program Latency	30	200	µs per CLB column
T_{ICCK}	CCLK (output) delay	40	250	µs
T_{CCLK}	CCLK (output) period, slow	640	2000	ns
T_{CCLK}	CCLK (output) period, fast	100	250	ns

Slave Mode

Symbol	Description	Min	Max	Units
T_{POR}	Power-on reset	10	33	ms
T_{PI}	Program latency	30	200	µs per CLB column
T_{ICCK}	CCLK (input) delay (required)	4	-	µs
T_{CCLK}	CCLK (input) period (required)	80	-	ns

Spartan Family CLB Switching Characteristic Guidelines

All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all Spartan devices and expressed in nanoseconds unless otherwise noted.

Symbol	Description	Speed Grade -4 Min	Speed Grade -4 Max	Speed Grade -3 Min	Speed Grade -3 Max	Units
Clocks						
T_{CH}	Clock High time	3.0	-	4.0	-	ns
T_{CL}	Clock Low time	3.0	-	4.0	-	ns
Combinatorial Delays						
T_{ILO}	F/G inputs to X/Y outputs	-	1.2	-	1.6	ns
T_{IHO}	F/G inputs via H to X/Y outputs	-	2.0	-	2.7	ns
T_{HH1O}	C inputs via H1 via H to X/Y outputs	-	1.7	-	2.2	ns
CLB Fast Carry Logic						
T_{OPCY}	Operand inputs (F1, F2, G1, G4) to C_{OUT}	-	1.7	-	2.1	ns
T_{ASCY}	Add/Subtract input (F3) to C_{OUT}	-	2.8	-	3.7	ns
T_{INCY}	Initialization inputs (F1, F3) to C_{OUT}	-	1.2	-	1.4	ns
T_{SUM}	C_{IN} through function generators to X/Y outputs	-	2.0	-	2.6	ns
T_{BYP}	C_{IN} to C_{OUT}, bypass function generators	-	0.5	-	0.6	ns
Sequential Delays						
T_{CKO}	Clock K to Flip-Flop outputs Q	-	2.1	-	2.8	ns
Setup Time before Clock K						
T_{ICK}	F/G inputs	1.8	-	2.4	-	ns
T_{IHCK}	F/G inputs via H	2.9	-	3.9	-	ns
T_{HH1CK}	C inputs via H1 through H	2.3	-	3.3	-	ns
T_{DICK}	C inputs via DIN	1.3	-	2.0	-	ns
T_{ECCK}	C inputs via EC	2.0	-	2.6	-	ns
T_{RCK}	C inputs via S/R, going Low (inactive)	2.5	-	4.0	-	ns
Hold Time after Clock K						
	All Hold times, all devices	0.0	-	0.0	-	ns
Set/Reset Direct						
T_{RPW}	Width (High)	3.0	-	4.0	-	ns
T_{RIO}	Delay from C inputs via S/R, going High to Q	-	3.0	-	4.0	ns
Global Set/Reset						
T_{MRW}	Minimum GSR pulse width	11.5	-	13.5	-	ns
T_{MRQ}	Delay from GSR input to any Q	See page 50 for T_{RRI} values per device.				
F_{TOG}	Toggle Frequency (MHz) (for export control purposes)	-	166	-	125	MHz

Spartan Family CLB RAM Synchronous (Edge-Triggered) Write Operation Guidelines

All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all Spartan devices and are expressed in nanoseconds unless otherwise noted.

Symbol	Single Port RAM	Size(1)	Speed Grade -4 Min	-4 Max	-3 Min	-3 Max	Units
Write Operation							
T_{WCS}	Address write cycle time (clock K period)	16x2	8.0	-	11.6	-	ns
T_{WCTS}		32x1	8.0	-	11.6	-	ns
T_{WPS}	Clock K pulse width (active edge)	16x2	4.0	-	5.8	-	ns
T_{WPTS}		32x1	4.0	-	5.8	-	ns
T_{ASS}	Address setup time before clock K	16x2	1.5	-	2.0	-	ns
T_{ASTS}		32x1	1.5	-	2.0	-	ns
T_{AHS}	Address hold time after clock K	16x2	0.0	-	0.0	-	ns
T_{AHTS}		32x1	0.0	-	0.0	-	ns
T_{DSS}	DIN setup time before clock K	16x2	1.5	-	2.7	-	ns
T_{DSTS}		32x1	1.5	-	1.7	-	ns
T_{DHS}	DIN hold time after clock K	16x2	0.0	-	0.0	-	ns
T_{DHTS}		32x1	0.0	-	0.0	-	ns
T_{WSS}	WE setup time before clock K	16x2	1.5	-	1.6	-	ns
T_{WSTS}		32x1	1.5	-	1.6	-	ns
T_{WHS}	WE hold time after clock K	16x2	0.0	-	0.0	-	ns
T_{WHTS}		32x1	0.0	-	0.0	-	ns
T_{WOS}	Data valid after clock K	16x2	-	6.5	-	7.9	ns
T_{WOTS}		32x1	-	7.0	-	9.3	ns
Read Operation							
T_{RC}	Address read cycle time	16x2	2.6	-	2.6	-	ns
T_{RCT}		32x1	3.8	-	3.8	-	ns
T_{ILO}	Data valid after address change (no Write Enable)	16x2	-	1.2	-	1.6	ns
T_{IHO}		32x1	-	2.0	-	2.7	ns
T_{ICK}	Address setup time before clock K	16x2	1.8	-	2.4	-	ns
T_{IHCK}		32x1	2.9	-	3.9	-	ns

Notes:
1. Timing for 16 x 1 RAM option is identical to 16 x 2 RAM timing.

Spartan-XL Family Detailed Specifications

Definition of Terms

In the following tables, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

Advance: Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or device families. Values are subject to change. Use as estimates, not for production.
Preliminary: Based on preliminary characterization. Further changes are not expected.
Unmarked: Specifications not identified as either Advance or Preliminary are to be considered Final.

Notwithstanding the definition of the above terms, all specifications are subject to change without notice.

Except for pin-to-pin input and output parameters, the AC parameter delay specifications included in this document are derived from measuring internal test patterns. All specifications are representative of worst-case supply voltage and junction temperature conditions. The parameters included are common to popular designs and typical applications.

Spartan-XL Family Absolute Maximum Ratings(1)

Symbol	Description		Value	Units
V_{CC}	Supply voltage relative to GND		–0.5 to 4.0	V
V_{IN}	Input voltage relative to GND	5V Tolerant I/O Checked(2, 3)	–0.5 to 5.5	V
		Not 5V Tolerant I/Os(4, 5)	–0.5 to V_{CC} + 0.5	V
V_{TS}	Voltage applied to 3-state output	5V Tolerant I/O Checked(2, 3)	–0.5 to 5.5	V
		Not 5V Tolerant I/Os(4, 5)	–0.5 to V_{CC} + 0.5	V
T_{STG}	Storage temperature (ambient)		–65 to +150	°C
T_J	Junction temperature	Plastic packages	+125	°C

Notes:
1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.
2. With 5V Tolerant I/Os selected, the Maximum DC overshoot must be limited to either +5.5V or 10 mA and undershoot (below GND) must be limited to either 0.5V or 10 mA, whichever is easier to achieve.
3. With 5V Tolerant I/Os selected, the Maximum AC (during transitions) conditions are as follows; the device pins may undershoot to –2.0V or overshoot to + 7.0V, provided this overshoot or undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
4. Without 5V Tolerant I/Os selected, the Maximum DC overshoot or undershoot must be limited to either 0.5V or 10 mA, whichever is easier to achieve.
5. Without 5V Tolerant I/Os selected, the Maximum AC conditions are as follows; the device pins may undershoot to –2.0V or overshoot to V_{CC} + 2.0V, provided this overshoot or undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
6. For soldering guidelines, see the Package Information on the Xilinx website.

Spartan-XL Family Recommended Operating Conditions

Symbol	Description		Min	Max	Units
V_{CC}	Supply voltage relative to GND, T_J = 0°C to +85°C	Commercial	3.0	3.6	V
	Supply voltage relative to GND, T_J = –40°C to +100°C(1)	Industrial	3.0	3.6	V
V_{IH}	High-level input voltage(2)		50% of V_{CC}	5.5	V
V_{IL}	Low-level input voltage(2)		0	30% of V_{CC}	V
T_{IN}	Input signal transition time		-	250	ns

Notes:
1. At junction temperatures above those listed as Operating Conditions, all delay parameters increase by 0.35% per °C.
2. Input and output measurement threshold is ~50% of V_{CC}.

Spartan-XL Family IOB Output Switching Characteristic Guidelines

All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values are expressed in nanoseconds unless otherwise noted.

Symbol	Description	Device	Speed Grade -5 Min	Speed Grade -5 Max	Speed Grade -4 Min	Speed Grade -4 Max	Units
Propagation Delays							
T_{OKPOF}	Clock (OK) to Pad, fast	All devices	-	3.2	-	3.7	ns
T_{OPF}	Output (O) to Pad, fast	All devices	-	2.5	-	2.9	ns
T_{TSHZ}	3-state to Pad High-Z (slew-rate independent)	All devices	-	2.8	-	3.3	ns
T_{TSONF}	3-state to Pad active and valid, fast	All devices	-	2.6	-	3.0	ns
T_{OFPF}	Output (O) to Pad via Output MUX, fast	All devices	-	3.7	-	4.4	ns
T_{OKFPF}	Select (OK) to Pad via Output MUX, fast	All devices	-	3.3	-	3.9	ns
T_{SLOW}	For Output SLOW option add	All devices	-	1.5	-	1.7	ns
Setup and Hold Times							
T_{OOK}	Output (O) to clock (OK) setup time	All devices	0.5	-	0.5	-	ns
T_{OKO}	Output (O) to clock (OK) hold time	All devices	0.0	-	0.0	-	ns
T_{ECOK}	Clock Enable (EC) to clock (OK) setup time	All devices	0.0	-	0.0	-	ns
T_{OKEC}	Clock Enable (EC) to clock (OK) hold time	All devices	0.1	-	0.2	-	ns
Global Set/Reset							
T_{MRW}	Minimum GSR pulse width	All devices	10.5	-	11.5	-	ns
T_{RPO}	Delay from GSR input to any Pad	XCS05XL	-	11.9	-	14.0	ns
		XCS10XL	-	12.4	-	14.5	ns
		XCS20XL	-	12.9	-	15.0	ns
		XCS30XL	-	13.9	-	16.0	ns
		XCS40XL	-	14.9	-	17.0	ns

Notes:

1. Output timing is measured at ~50% V_{CC} threshold, with 50 pF external capacitive loads including test fixture. Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times.
2. Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

XCS30 and XCS30XL Device Pinouts *(Continued)*

XCS30/XL Pad Name	VQ100[(5)]	TQ144	PQ208	PQ240	BG256[(5)]	CS280[(2,5)]	Bndry Scan
I/O	-	P5	P5	P5	D3	C1	155
I/O, TDI	P4	P6	P6	P6	E4	D4	158
I/O, TCK	P5	P7	P7	P7	C1	D3	161
I/O	-	-	P8	P8	D1	E2	164
I/O	-	-	P9	P9	E3	E4	167
I/O	-	-	P10	P10	E2	E1	170
I/O	-	-	P11	P11	E1	F5	173
I/O	-	-	P12	P12	F3	F3	176
I/O	-	-	-	P13	F2	F2	179
GND	-	P8	P13	P14	GND[(4)]	GND[(4)]	-
I/O	-	P9	P14	P15	G3	F4	182
I/O	-	P10	P15	P16	G2	F1	185
I/O, TMS	P6	P11	P16	P17	G1	G3	188
I/O	P7	P12	P17	P18	H3	G2	191
VCC	-	-	P18	P19	VCC[(4)]	G1	-
I/O	-	-	-	P20	H2	G4	194
I/O	-	-	-	P21	H1	H1	197
I/O	-	-	P19	P23	J2	H4	200
I/O	-	-	P20	P24	J1	J1	203
I/O	-	P13	P21	P25	K2	J2	206
I/O	P8	P14	P22	P26	K3	J3	209
I/O	P9	P15	P23	P27	K1	J4	212
I/O	P10	P16	P24	P28	L1	K1	215
GND	P11	P17	P25	P29	GND[(4)]	GND[(4)]	-
VCC	P12	P18	P26	P30	VCC[(4)]	K2	-
I/O	P13	P19	P27	P31	L2	K3	218
I/O	P14	P20	P28	P32	L3	K4	221
I/O	P15	P21	P29	P33	L4	K5	224
I/O	-	P22	P30	P34	M1	L1	227
I/O	-	-	P31	P35	M2	L2	230
I/O	-	-	P32	P36	M3	L3	233
I/O	-	-	-	P38	N1	M2	236
I/O	-	-	-	P39	N2	M3	239
VCC	-	-	P33	P40	VCC[(4)]	M4	-
I/O	P16	P23	P34	P41	P1	N1	242
I/O	P17	P24	P35	P42	P2	N2	245
I/O	-	P25	P36	P43	R1	N3	248
I/O	-	P26	P37	P44	P3	N4	251
GND	-	P27	P38	P45	GND[(4)]	GND[(4)]	-
I/O	-	-	-	P46	T1	P1	254
I/O	-	-	P39	P47	R3	P2	257
I/O	-	-	P40	P48	T2	P3	260
I/O	-	-	P41	P49	U1	P4	263
I/O	-	-	P42	P50	T3	P5	266
I/O	-	-	P43	P51	U2	R1	269

XCS30 and XCS30XL Device Pinouts *(Continued)*

XCS30/XL Pad Name	VQ100(5)	TQ144	PQ208	PQ240	BG256(5)	CS280(2,5)	Bndry Scan
I/O	P18	P28	P44	P52	V1	T1	272
I/O	P19	P29	P45	P53	T4	T2	275
I/O	-	P30	P46	P54	U3	T3	278
I/O	-	P31	P47	P55	V2	U1	281
I/O	P20	P32	P48	P56	W1	V1	284
I/O, SGCK2(1), GCK2(2)	P21	P33	P49	P57	V3	U2	287
Not Connected(1), M1(2)	P22	P34	P50	P58	W2	V2	290
GND	P23	P35	P51	P59	GND(4)	GND(4)	-
MODE(1), M0(2)	P24	P36	P52	P60	Y1	W1	293
VCC	P25	P37	P53	P61	VCC(4)	U3	-
Not Connected (1), PWRDWN(2)	P26	P38	P54	P62	W3	V3	294 (1)
I/O, PGCK2(1), GCK3(2)	P27	P39	P55	P63	Y2	W2	295 (3)
I/O (HDC)	P28	P40	P56	P64	W4	W3	298 (3)
I/O	-	P41	P57	P65	V4	T4	301 (3)
I/O	-	P42	P58	P66	U5	U4	304 (3)
I/O	P29	P43	P59	P67	Y3	V4	307 (3)
I/O (LDC)	P30	P44	P60	P68	Y4	W4	310 (3)
I/O	-	-	P61	P69	V5	T5	313 (3)
I/O	-	-	P62	P70	W5	W5	316 (3)
I/O	-	-	P63	P71	Y5	R6	319 (3)
I/O	-	-	P64	P72	V6	U6	322 (3)
I/O	-	-	P65	P73	W6	V6	325 (3)
I/O	-	-	-	P74	Y6	T6	328 (3)
GND	-	P45	P66	P75	GND(4)	GND(4)	-
I/O	-	P46	P67	P76	W7	W6	331 (3)
I/O	-	P47	P68	P77	Y7	U7	334 (3)
I/O	P31	P48	P69	P78	V8	V7	337 (3)
I/O	P32	P49	P70	P79	W8	W7	340 (3)
VCC	-	-	P71	P80	VCC(4)	T7	-
I/O	-	-	P72	P81	Y8	W8	343 (3)
I/O	-	-	P73	P82	U9	U8	346 (3)
I/O	-	-	-	P84	Y9	W9	349 (3)
I/O	-	-	-	P85	W10	V9	352 (3)
I/O	P33	P50	P74	P86	V10	U9	355 (3)
I/O	P34	P51	P75	P87	Y10	T9	358 (3)
I/O	P35	P52	P76	P88	Y11	W10	361 (3)
I/O (INIT)	P36	P53	P77	P89	W11	V10	364 (3)
VCC	P37	P54	P78	P90	VCC(4)	U10	-
GND	P38	P55	P79	P91	GND(4)	GND(4)	-
I/O	P39	P56	P80	P92	V11	T10	367 (3)
I/O	P40	P57	P81	P93	U11	R10	370 (3)
I/O	P41	P58	P82	P94	Y12	W11	373 (3)
I/O	P42	P59	P83	P95	W12	V11	376 (3)
I/O	-	-	P84	P96	V12	U11	379 (3)

XCS30 and XCS30XL Device Pinouts *(Continued)*

XCS30/XL Pad Name	VQ100(5)	TQ144	PQ208	PQ240	BG256(5)	CS280(2,5)	Bndry Scan
I/O	-	-	P124	P144	M20	L19	493 (3)
I/O	-	-	P125	P145	L19	L18	496 (3)
I/O	P59	P86	P126	P146	L18	L17	499 (3)
I/O	P60	P87	P127	P147	L20	L16	502 (3)
I/O (D4(2))	P61	P88	P128	P148	K20	K19	505 (3)
I/O	P62	P89	P129	P149	K19	K18	508 (3)
VCC	P63	P90	P130	P150	VCC(4)	K17	-
GND	P64	P91	P131	P151	GND(4)	GND(4)	-
I/O (D3(2))	P65	P92	P132	P152	K18	K16	511 (3)
I/O	P66	P93	P133	P153	K17	K15	514 (3)
I/O	P67	P94	P134	P154	J20	J19	517 (3)
I/O	-	P95	P135	P155	J19	J18	520 (3)
I/O	-	-	P136	P156	J18	J17	523 (3)
I/O	-	-	P137	P157	J17	J16	526 (3)
I/O (D2(2))	P68	P96	P138	P159	H19	H17	529 (3)
I/O	P69	P97	P139	P160	H18	H16	532 (3)
VCC	-	-	P140	P161	VCC(4)	G19	-
I/O	-	P98	P141	P162	G19	G18	535 (3)
I/O	-	P99	P142	P163	F20	G17	538 (3)
I/O	-	-	-	P164	G18	G16	541 (3)
I/O	-	-	-	P165	F19	F19	544 (3)
GND	-	P100	P143	P166	GND(4)	GND(4)	-
I/O	-	-	-	P167	F18	F18	547 (3)
I/O	-	-	P144	P168	E19	F17	550 (3)
I/O	-	-	P145	P169	D20	F16	553 (3)
I/O	-	-	P146	P170	E18	F15	556 (3)
I/O	-	-	P147	P171	D19	E19	559 (3)
I/O	-	-	P148	P172	C20	E17	562 (3)
I/O (D1(2))	P70	P101	P149	P173	E17	E16	565 (3)
I/O	P71	P102	P150	P174	D18	D19	568 (3)
I/O	-	P103	P151	P175	C19	C19	571 (3)
I/O	-	P104	P152	P176	B20	B19	574 (3)
I/O (D0(2), DIN)	P72	P105	P153	P177	C18	C18	577 (3)
I/O, SGCK4(1), GCK6(2) (DOUT)	P73	P106	P154	P178	B19	B18	580 (3)
CCLK	P74	P107	P155	P179	A20	A19	-
VCC	P75	P108	P156	P180	VCC(4)	C17	-
O, TDO	P76	P109	P157	P181	A19	B17	0
GND	P77	P110	P158	P182	GND(4)	GND(4)	-
I/O	P78	P111	P159	P183	B18	A18	2
I/O, PGCK4(1), GCK7(2)	P79	P112	P160	P184	B17	A17	5
I/O	-	P113	P161	P185	C17	D16	8
I/O	-	P114	P162	P186	D16	C16	11
I/O (CS1)(2)	P80	P115	P163	P187	A18	B16	14
I/O	P81	P116	P164	P188	A17	A16	17
I/O	-	-	P165	P189	C16	D15	20

XCS40 and XCS40XL Device Pinouts

XCS40/XL Pad Name	PQ208	PQ240	BG256	CS280(2,5)	Bndry Scan
GND	P25	P29	GND(4)	GND(4)	-
VCC	P26	P30	VCC(4)	VCC(4)	-
I/O	P27	P31	L2	K3	254
I/O	P28	P32	L3	K4	257
I/O	P29	P33	L4	K5	260
I/O	P30	P34	M1	L1	263
I/O	P31	P35	M2	L2	266
I/O	P32	P36	M3	L3	269
I/O	-	-	M4	L4	272
I/O	-	-	-	M1	275
I/O	-	P38	N1	M2	278
I/O	-	P39	N2	M3	281
VCC	P33	P40	VCC(4)	VCC(4)	-
I/O	P34	P41	P1	N1	284
I/O	P35	P42	P2	N2	287
I/O	P36	P43	R1	N3	290
I/O	P37	P44	P3	N4	293
GND	P38	P45	GND(4)	GND(4)	-
I/O	-	P46	T1	P1	296
I/O	P39	P47	R3	P2	299
I/O	P40	P48	T2	P3	302
I/O	P41	P49	U1	P4	305
I/O	P42	P50	T3	P5	308
I/O	P43	P51	U2	R1	311
I/O	-	-	-	R2	314
I/O	-	-	-	R4	317
I/O	P44	P52	V1	T1	320
I/O	P45	P53	T4	T2	323
I/O	P46	P54	U3	T3	326
I/O	P47	P55	V2	U1	329
I/O	P48	P56	W1	V1	332
I/O, SGCK2(1), GCK2 (2)	P49	P57	V3	U2	335
Not Connected(1) M1(2)	P50	P58	W2	V2	338
GND	P51	P59	GND(4)	GND(4)	-
MODE(1), M0(2)	P52	P60	Y1	W1	341
VCC	P53	P61	VCC(4)	VCC(4)	-
Not Connected(1) $\overline{\text{PWRDWN}}$(2)	P54	P62	W3	V3	342(1)
I/O, PGCK2(1), GCK3(2)	P55	P63	Y2	W2	343 (3)

XCS40 and XCS40XL Device Pinouts

XCS40/XL Pad Name	PQ208	PQ240	BG256	CS280(2,5)	Bndry Scan
I/O (HDC)	P56	P64	W4	W3	346 (3)
I/O	P57	P65	V4	T4	349 (3)
I/O	P58	P66	U5	U4	352 (3)
I/O	P59	P67	Y3	V4	355 (3)
I/O ($\overline{\text{LDC}}$)	P60	P68	Y4	W4	358 (3)
I/O	-	-	-	R5	361 (3)
I/O	-	-	-	U5	364 (3)
I/O	P61	P69	V5	T5	367 (3)
I/O	P62	P70	W5	W5	370 (3)
I/O	P63	P71	Y5	R6	373 (3)
I/O	P64	P72	V6	U6	376 (3)
I/O	P65	P73	W6	V6	379 (3)
I/O	-	P74	Y6	T6	382 (3)
GND	P66	P75	GND(4)	GND(4)	-
I/O	P67	P76	W7	W6	385 (3)
I/O	P68	P77	Y7	U7	388 (3)
I/O	P69	P78	V8	V7	391 (3)
I/O	P70	P79	W8	W7	394 (3)
VCC	P71	P80	VCC(4)	VCC(4)	-
I/O	P72	P81	Y8	W8	397 (3)
I/O	P73	P82	U9	U8	400 (3)
I/O	-	-	V9	V8	403 (3)
I/O	-	-	W9	T8	406 (3)
I/O	-	P84	Y9	W9	409 (3)
I/O	-	P85	W10	V9	412 (3)
I/O	P74	P86	V10	U9	415 (3)
I/O	P75	P87	Y10	T9	418 (3)
I/O	P76	P88	Y11	W10	421 (3)
I/O ($\overline{\text{INIT}}$)	P77	P89	W11	V10	424 (3)
VCC	P78	P90	VCC(4)	VCC(4)	VCC(4)
GND	P79	P91	GND(4)	GND(4)	-
I/O	P80	P92	V11	T10	427 (3)
I/O	P81	P93	U11	R10	430 (3)
I/O	P82	P94	Y12	W11	433 (3)
I/O	P83	P95	W12	V11	436 (3)
I/O	P84	P96	V12	U11	439 (3)
I/O	P85	P97	U12	T11	442 (3)
I/O	-	-	Y13	W12	445 (3)
I/O	-	-	W13	V12	448 (3)
I/O	-	P99	V13	U12	451 (3)
I/O	-	P100	Y14	T12	454 (3)
VCC	P86	P101	VCC(4)	VCC(4)	-
I/O	P87	P102	Y15	V13	457 (3)
I/O	P88	P103	V14	U13	460 (3)
I/O	P89	P104	W15	T13	463 (3)

XCS40 and XCS40XL Device Pinouts

XCS40/XL Pad Name	PQ208	PQ240	BG256	CS280(2,5)	Bndry Scan
I/O	P90	P105	Y16	W14	466 (3)
GND	P91	P106	GND(4)	GND(4)	-
I/O	-	P107	V15	V14	469 (3)
I/O	P92	P108	W16	U14	472 (3)
I/O	P93	P109	Y17	T14	475 (3)
I/O	P94	P110	V16	R14	478 (3)
I/O	P95	P111	W17	W15	481 (3)
I/O	P96	P112	Y18	U15	484 (3)
I/O	-	-	-	T15	487 (3)
I/O	-	-	-	W16	490 (3)
I/O	P97	P113	U16	V16	493 (3)
I/O	P98	P114	V17	U16	496 (3)
I/O	P99	P115	W18	W17	499 (3)
I/O	P100	P116	Y19	W18	502 (3)
I/O	P101	P117	V18	V17	505 (3)
I/O, SGCK3(1), GCK4(2)	P102	P118	W19	V18	508 (3)
GND	P103	P119	GND(4)	GND(4)	-
DONE	P104	P120	Y20	W19	-
VCC	P105	P121	VCC(4)	VCC(4)	-
$\overline{\text{PROGRAM}}$	P106	P122	V19	U18	-
I/O (D7(2))	P107	P123	U19	V19	511 (3)
I/O, PGCK3(1), GCK5(2)	P108	P124	U18	U19	514 (3)
I/O	P109	P125	T17	T16	517 (3)
I/O	P110	P126	V20	T17	520 (3)
I/O	-	P127	U20	T18	523 (3)
I/O	P111	P128	T18	T19	526 (3)
I/O	-	-	-	R15	529 (3)
I/O	-	-	-	R17	523 (3)
I/O (D6(2))	P112	P129	T19	R16	535 (3)
I/O	P113	P130	T20	R19	538 (3)
I/O	P114	P131	R18	P15	541 (3)
I/O	P115	P132	R19	P17	544 (3)
I/O	P116	P133	R20	P18	547 (3)
I/O	P117	P134	P18	P16	550 (3)
GND	P118	P135	GND(4)	GND(4)	-
I/O	-	P136	P20	P19	553 (3)
I/O	-	P137	N18	N17	556 (3)
I/O	P119	P138	N19	N18	559 (3)
I/O	P120	P139	N20	N19	562 (3)
VCC	P121	P140	VCC(4)	VCC(4)	-
I/O (D5(2))	P122	P141	M17	M19	565 (3)
I/O	P123	P142	M18	M17	568 (3)
I/O	-	-	-	M18	571 (3)
I/O	-	-	M19	M16	574 (3)
I/O	P124	P144	M20	L19	577 (3)
I/O	P125	P145	L19	L18	580 (3)
I/O	P126	P146	L18	L17	583 (3)
I/O	P127	P147	L20	L16	586 (3)
I/O (D4(2))	P128	P148	K20	K19	589 (3)
I/O	P129	P149	K19	K18	592 (3)
VCC	P130	P150	VCC(4)	VCC(4)	-
GND	P131	P151	GND(4)	GND(4)	-
I/O (D3(2))	P132	P152	K18	K16	595 (3)
I/O	P133	P153	K17	K15	598 (3)
I/O	P134	P154	J20	J19	601 (3)
I/O	P135	P155	J19	J18	604 (3)
I/O	P136	P156	J18	J17	607 (3)
I/O	P137	P157	J17	J16	610 (3)
I/O	-	-	H20	H19	613 (3)
I/O	-	-	-	H18	616 (3)
I/O (D2(2))	P138	P159	H19	H17	619 (3)
I/O	P139	P160	H18	H16	622 (3)
VCC	P140	P161	VCC(4)	VCC(4)	-
I/O	P141	P162	G19	G18	625 (3)
I/O	P142	P163	F20	G17	628 (3)
I/O	-	P164	G18	G16	631 (3)
I/O	-	P165	F19	F19	634 (3)
GND	P143	P166	GND(4)	GND(4)	-
I/O	-	P167	F18	F18	637 (3)
I/O	P144	P168	E19	F17	640 (3)
I/O	P145	P169	D20	F16	643 (3)
I/O	P146	P170	E18	F15	646 (3)
I/O	P147	P171	D19	E19	649 (3)
I/O	P148	P172	C20	E17	652 (3)
I/O (D1(2))	P149	P173	E17	E16	655 (3)
I/O	P150	P174	D18	D19	658 (3)
I/O	-	-	-	D18	661 (3)
I/O	-	-	-	D17	664 (3)
I/O	P151	P175	C19	C19	667 (3)
I/O	P152	P176	B20	B19	670 (3)
I/O (D0(2), DIN)	P153	P177	C18	C18	673 (3)
I/O, SGCK4(1), GCK6(2) (DOUT)	P154	P178	B19	B18	676 (3)
CCLK	P155	P179	A20	A19	-
VCC	P156	P180	VCC(4)	VCC(4)	-

Revision History

The following table shows the revision history for this document.

Date	Version	Description
11/20/98	1.3	Added Spartan-XL specs and Power Down.
01/06/99	1.4	All Spartan-XL -4 specs designated Preliminary with no changes.
03/02/00	1.5	Added CS package, updated Spartan-XL specs to Final.
09/19/01	1.6	Reformatted, updated power specs, clarified configuration information. Removed T_{SOL} soldering information from Absolute Maximum Ratings table. Changed Figure 26: Slave Serial Mode Characteristics: T_{CCH}, T_{CCL} from 45 to 40 ns. Changed Master Mode Configuration Switching Characteristics: T_{CCLK} min. from 80 to 100 ns. Added Total Dist. RAM Bits to Table 1; added **Start-Up**, page 36 characteristics.
06/27/02	1.7	Clarified Express Mode pseudo daisy chain. Added new Industrial options. Clarified XCS30XL CS280 V_{CC} pinout.
06/26/08	1.8	Noted that PC84, CS144, and CS280 packages, and VQ100 and BG256 packages for XCS30 only, are discontinued by **PDN2004-01**. Extended description of recommended maximum delay of reconfiguration in **Delaying Configuration After Power-Up**, page 35. Added reference to Pb-free package options and provided link to **Package Specifications**, page 81. Updated links.
03/01/13	2.0	The products listed in this data sheet are obsolete. See **XCN10016** and **XCN11010** for further information.