AMD Xilinx - XCS20XL-4PQG208C Datasheet

Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	400
Number of Logic Elements/Cells	950
Total RAM Bits	12800
Number of I/O	160
Number of Gates	20000
Voltage - Supply	3V ~ 3.6V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	208-BFQFP
Supplier Device Package	208-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/xilinx/xcs20xl-4pqg208c

The register choice is made by placing the appropriate library symbol. For example, IFD is the basic input flip-flop (rising edge triggered), and ILD is the basic input latch (transparent-High). Variations with inverted clocks are also available. The clock signal inverter is also shown in Figure 5 on the CK line.

The Spartan family IOB data input path has a one-tap delay element: either the delay is inserted (default), or it is not. The Spartan-XL family IOB data input path has a two-tap delay element, with choices of a full delay, a partial delay, or no delay. The added delay guarantees a zero hold time with respect to clocks routed through the global clock buffers. (See **Global Nets and Buffers**, page 12 for a description of the global clock buffers in the Spartan/XL families.) For a shorter input register setup time, with positive hold-time, attach a NODELAY attribute or property to the flip-flop.The output of the input register goes to the routing channels (via I1 and I2 in Figure 6). The I1 and I2 signals that exit the IOB can each carry either the direct or registered input signal.

The 5V Spartan family input buffers can be globally configured for either TTL (1.2V) or CMOS (VCC/2) thresholds, using an option in the bitstream generation software. The Spartan family output levels are also configurable; the two global adjustments of input threshold and output level are independent. The inputs of Spartan devices can be driven by the outputs of any 3.3V device, if the Spartan family inputs are in TTL mode. Input and output thresholds are TTL on all configuration pins until the configuration has been loaded into the device and specifies how they are to be used. Spartan-XL family inputs are TTL compatible and 3.3V CMOS compatible.

Supported sources for Spartan/XL device inputs are shown in Table 4.

Spartan-XL family I/Os are fully 5V tolerant even though the V_{CC} is 3.3V. This allows 5V signals to directly connect to the Spartan-XL family inputs without damage, as shown in Table 4. In addition, the 3.3V V_{CC} can be applied before or after 5V signals are applied to the I/Os. This makes the Spartan-XL devices immune to power supply sequencing problems.

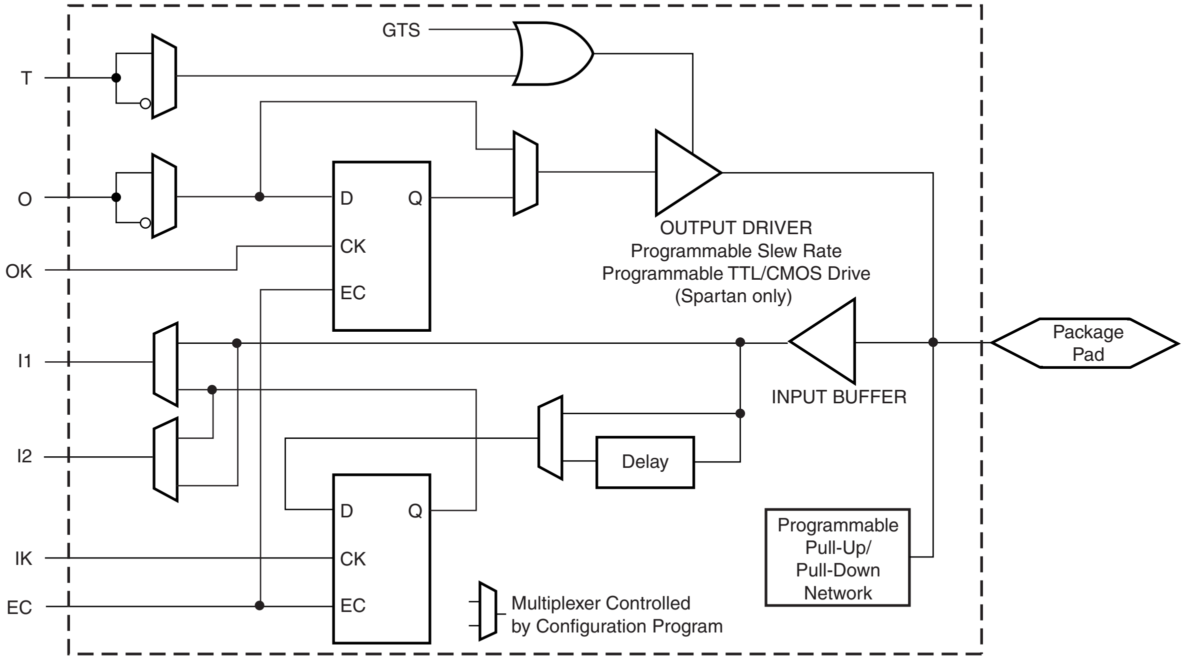

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Figure 6: **Simplified Spartan/XL IOB Block Diagram**

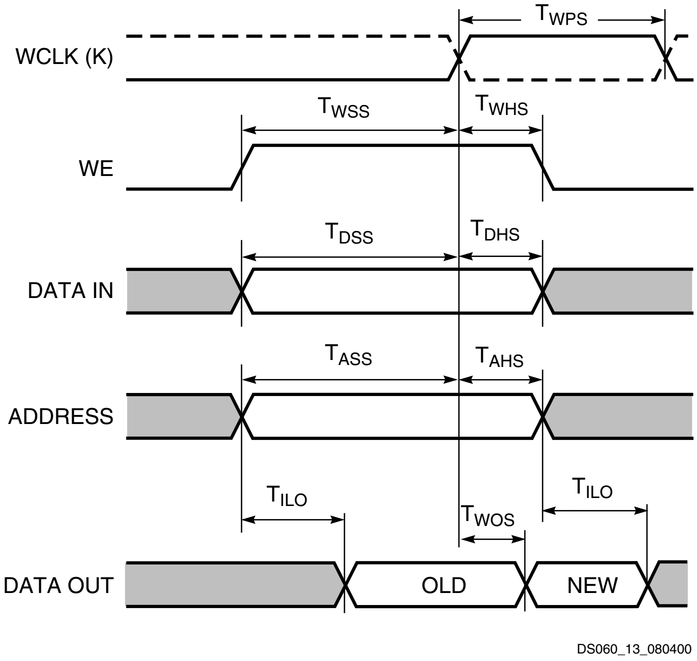


Figure 13: **Data Write and Access Timing for RAM**

WCLK can be configured as active on either the rising edge (default) or the falling edge. While the WCLK input to the RAM accepts the same signal as the clock input to the associated CLB's flip-flops, the sense of this WCLK input can be inverted with respect to the sense of the flip-flop clock inputs. Consequently, within the same CLB, data at the RAM SPO line can be stored in a flip-flop with either the same or the inverse clock polarity used to write data to the RAM.

The WE input is active High and cannot be inverted within the CLB.

Allowing for settling time, the data on the SPO output reflects the contents of the RAM location currently addressed. When the address changes, following the asynchronous delay T_{ILO}, the data stored at the new address location will appear on SPO. If the data at a particular RAM address is overwritten, after the delay T_{WOS}, the new data will appear on SPO.

Dual-Port Mode

In dual-port mode, the function generators (F-LUT and G-LUT) are used to create a 16 x 1 dual-port memory. Of the two data ports available, one permits read and write operations at the address specified by A[3:0] while the second provides only for read operations at the address specified independently by DPRA[3:0]. As a result, simultaneous read/write operations at different addresses (or even at the same address) are supported.

The functional organization of the 16 x 1 dual-port RAM is shown in Figure 14. The dual-port RAM signals and the

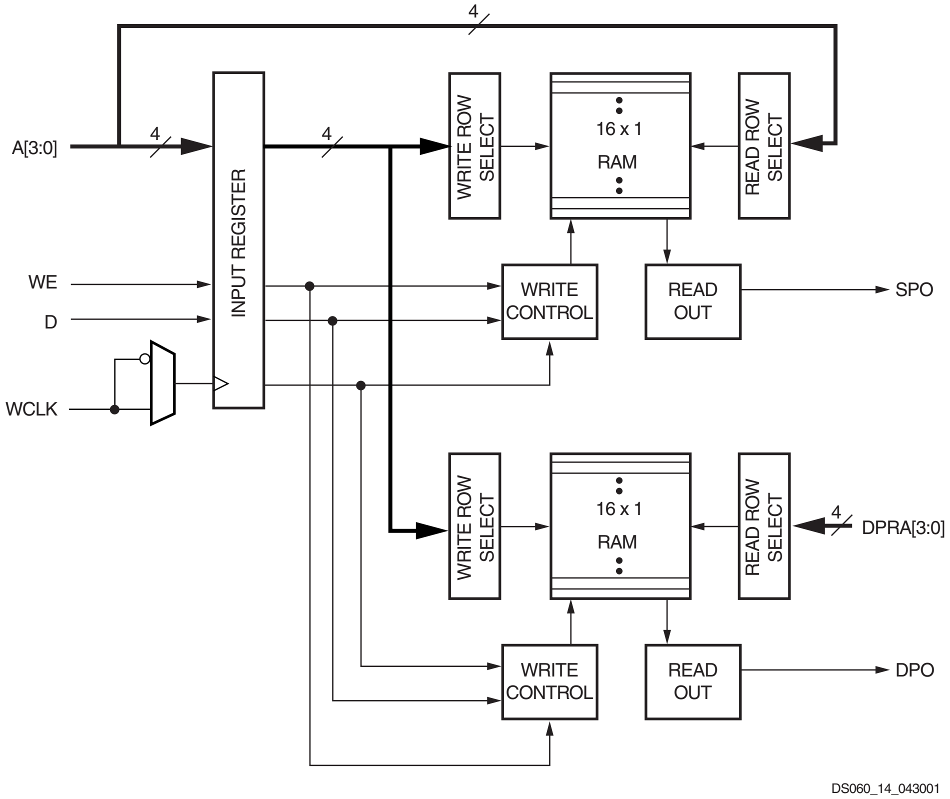


Figure 14: **Logic Diagram for the Dual-Port RAM**

and Spartan-XL families, speeding up arithmetic and counting functions.

The carry chain in 5V Spartan devices can run either up or down. At the top and bottom of the columns where there are no CLBs above and below, the carry is propagated to the right. The default is always to propagate up the column, as shown in the figures. The carry chain in Spartan-XL devices can only run up the column, providing even higher speed.

Figure 16, page 18 shows a Spartan/XL FPGA CLB with dedicated fast carry logic. The carry logic shares operand and control inputs with the function generators. The carry outputs connect to the function generators, where they are combined with the operands to form the sums.

Figure 17, page 19 shows the details of the Spartan/XL FPGA carry logic. This diagram shows the contents of the box labeled "CARRY LOGIC" in Figure 16.

The fast carry logic can be accessed by placing special library symbols, or by using Xilinx Relationally Placed Macros (RPMs) that already include these symbols.

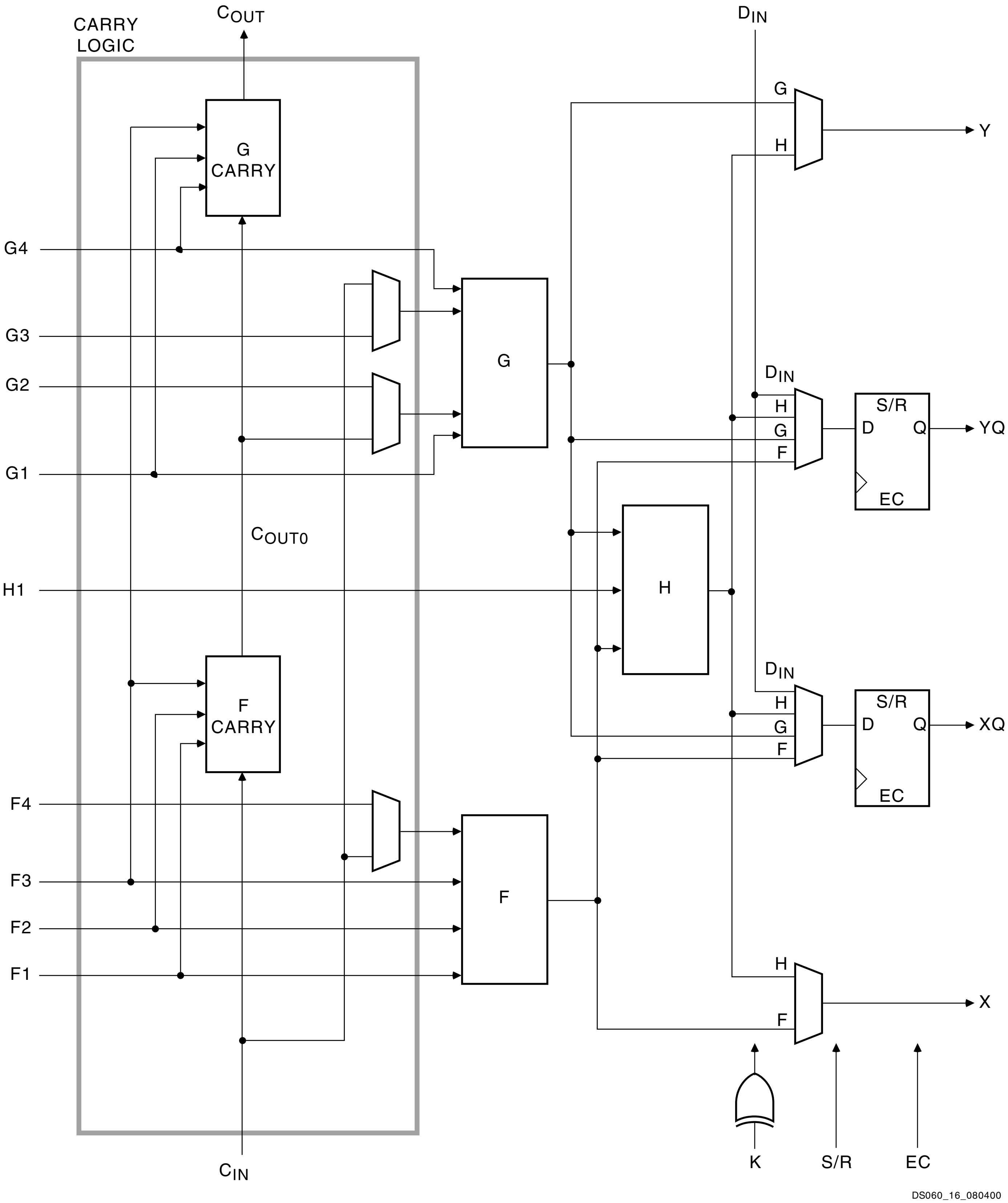


Figure 16: **Fast Carry Logic in Spartan/XL CLB**

On-Chip Oscillator

Spartan/XL devices include an internal oscillator. This oscillator is used to clock the power-on time-out, for configuration memory clearing, and as the source of CCLK in Master configuration mode. The oscillator runs at a nominal 8 MHz frequency that varies with process, V_{CC}, and temperature. The output frequency falls between 4 MHz and 10 MHz.

The oscillator output is optionally available after configuration. Any two of four resynchronized taps of a built-in divider are also available. These taps are at the fourth, ninth, fourteenth and nineteenth bits of the divider. Therefore, if the primary oscillator output is running at the nominal 8 MHz, the user has access to an 8-MHz clock, plus any two of 500 kHz, 16 kHz, 490 Hz and 15 Hz. These frequencies can vary by as much as -50% or +25%.

These signals can be accessed by placing the OSC4 library element in a schematic or in HDL code. The oscillator is automatically disabled after configuration if the OSC4 symbol is not used in the design.

Global Signals: GSR and GTS

Global Set/Reset

A separate Global Set/Reset line, as shown in Figure 3, page 5 for the CLB and Figure 5, page 6 for the IOB, sets or clears each flip-flop during power-up, reconfiguration, or when a dedicated Reset net is driven active. This global net (GSR) does not compete with other routing resources; it uses a dedicated distribution network.

Each flip-flop is configured as either globally set or reset in the same way that the local set/reset (SR) is specified. Therefore, if a flip-flop is set by SR, it is also set by GSR. Similarly, if in reset mode, it is reset by both SR and GSR.

GSR can be driven from any user-programmable pin as a global reset input. To use this global net, place an input pad and input buffer in the schematic or HDL code, driving the GSR pin of the STARTUP symbol. (See Figure 19.) A specific pin location can be assigned to this input using a LOC attribute or property, just as with any other user-programmable pad. An inverter can optionally be inserted after the input buffer to invert the sense of the GSR signal. Alternatively, GSR can be driven from any internal node.

Global 3-State

A separate Global 3-state line (GTS) as shown in Figure 6, page 7 forces all FPGA outputs to the high-impedance state, unless boundary scan is enabled and is executing an EXTEST instruction. GTS does not compete with other routing resources; it uses a dedicated distribution network.

GTS can be driven from any user-programmable pin as a global 3-state input. To use this global net, place an input pad and input buffer in the schematic or HDL code, driving the GTS pin of the STARTUP symbol. This is similar to what is shown in Figure 19 for GSR except the IBUF would be connected to GTS. A specific pin location can be assigned to this input using a LOC attribute or property, just as with any other user-programmable pad. An inverter can optionally be inserted after the input buffer to invert the sense of the Global 3-state signal. Alternatively, GTS can be driven from any internal node.

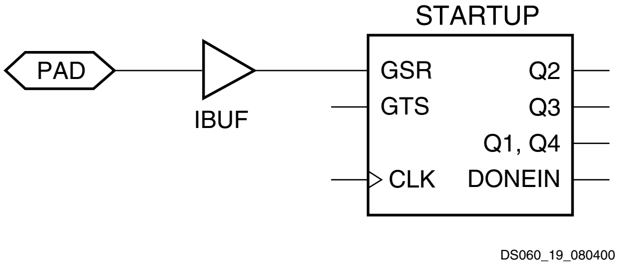


Figure 19: **Symbols for Global Set/Reset**

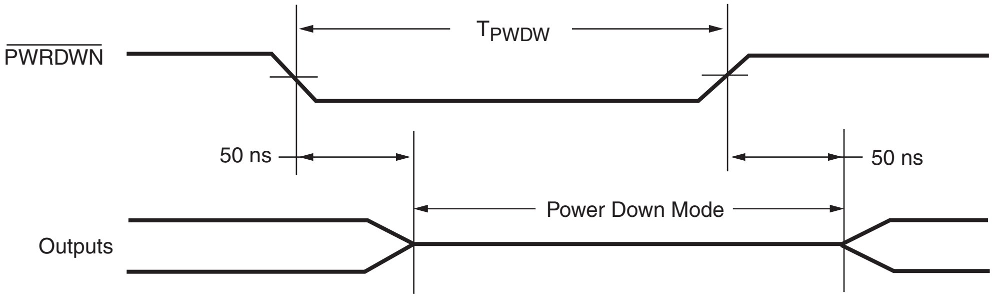
Boundary Scan

The "bed of nails" has been the traditional method of testing electronic assemblies. This approach has become less appropriate, due to closer pin spacing and more sophisticated assembly methods like surface-mount technology and multi-layer boards. The IEEE Boundary Scan Standard 1149.1 was developed to facilitate board-level testing of electronic assemblies. Design and test engineers can embed a standard test logic structure in their device to achieve high fault coverage for I/O and internal logic. This structure is easily implemented with a four-pin interface on any boundary scan compatible device. IEEE 1149.1-compatible devices may be serial daisy-chained together, connected in parallel, or a combination of the two.

The Spartan and Spartan-XL families implement IEEE 1149.1-compatible BYPASS, PRELOAD/SAMPLE and EXTEST boundary scan instructions. When the boundary scan configuration option is selected, three normal user I/O pins become dedicated inputs for these functions. Another user output pin becomes the dedicated boundary scan output. The details of how to enable this circuitry are covered later in this section.

By exercising these input signals, the user can serially load commands and data into these devices to control the driving of their outputs and to examine their inputs. This method is an improvement over bed-of-nails testing. It avoids the need to over-drive device outputs, and it reduces the user interface to four pins. An optional fifth pin, a reset for the control logic, is described in the standard but is not implemented in the Spartan/XL devices.

The dedicated on-chip logic implementing the IEEE 1149.1 functions includes a 16-state machine, an instruction register and a number of data registers. The functional details can be found in the IEEE 1149.1 specification and are also discussed in the Xilinx application note: "*Boundary Scan in FPGA Devices.*"



Description	Symbol	Min
Power Down Time	T_{PWD}	50 ns
Power Down Pulse Width	T_{PWDW}	50 ns

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Figure 23: **$\overline{\text{PWRDWN}}$ Pulse Timing**

Power-down retains the configuration, but loses all data stored in the device flip-flops. All inputs are interpreted as Low, but the internal combinatorial logic is fully functional. Make sure that the combination of all inputs Low and all flip-flops set or reset in your design will not generate internal oscillations, or create permanent bus contention by activating internal bus drivers with conflicting data onto the same long line.

During configuration, the $\overline{\text{PWRDWN}}$ pin must be High. If the Power Down state is entered before or during configuration, the device will restart configuration once the $\overline{\text{PWRDWN}}$ signal is removed. Note that the configuration pins are affected by Power Down and may not reflect their normal function. If there is an external pull-up resistor on the DONE pin, it will be High during Power Down even if the device is not yet configured. Similarly, if $\overline{\text{PWRDWN}}$ is asserted before configuration is completed, the $\overline{\text{INIT}}$ pin will not indicate status information.

Note that the $\overline{\text{PWRDWN}}$ pin is not part of the Boundary Scan chain. Therefore, the Spartan-XL family has a separate set of BSDL files than the 5V Spartan family. Boundary scan logic is not usable during Power Down.

Configuration and Test

Configuration is the process of loading design-specific programming data into one or more FPGAs to define the functional operation of the internal blocks and their interconnections. This is somewhat like loading the command registers of a programmable peripheral chip. Spartan/XL devices use several hundred bits of configuration data per CLB and its associated interconnects. Each configuration bit defines the state of a static memory cell that controls either a function look-up table bit, a multiplexer input, or an interconnect pass transistor. The Xilinx development system translates the design into a netlist file. It automatically partitions, places and routes the logic and generates the configuration data in PROM format.

Configuration Mode Control

5V Spartan devices have two configuration modes.

- MODE = 1 sets Slave Serial mode
- MODE = 0 sets Master Serial mode

3V Spartan-XL devices have three configuration modes.

- M1/M0 = 11 sets Slave Serial mode
- M1/M0 = 10 sets Master Serial mode
- M1/M0 = 0X sets Express mode

In addition to these modes, the device can be configured through the Boundary Scan logic (See "Configuration Through the Boundary Scan Pins" on page 37.).

The Mode pins are sampled prior to starting configuration to determine the configuration mode. After configuration, these pin are unused. The Mode pins have a weak pull-up resistor turned on during configuration. With the Mode pins High, Slave Serial mode is selected, which is the most popular configuration mode. Therefore, for the most common configuration mode, the Mode pins can be left unconnected. If the Master Serial mode is desired, the MODE/M0 pin should be connected directly to GND, or through a pull-down resistor of 1 KΩ or less.

During configuration, some of the I/O pins are used temporarily for the configuration process. All pins used during con-

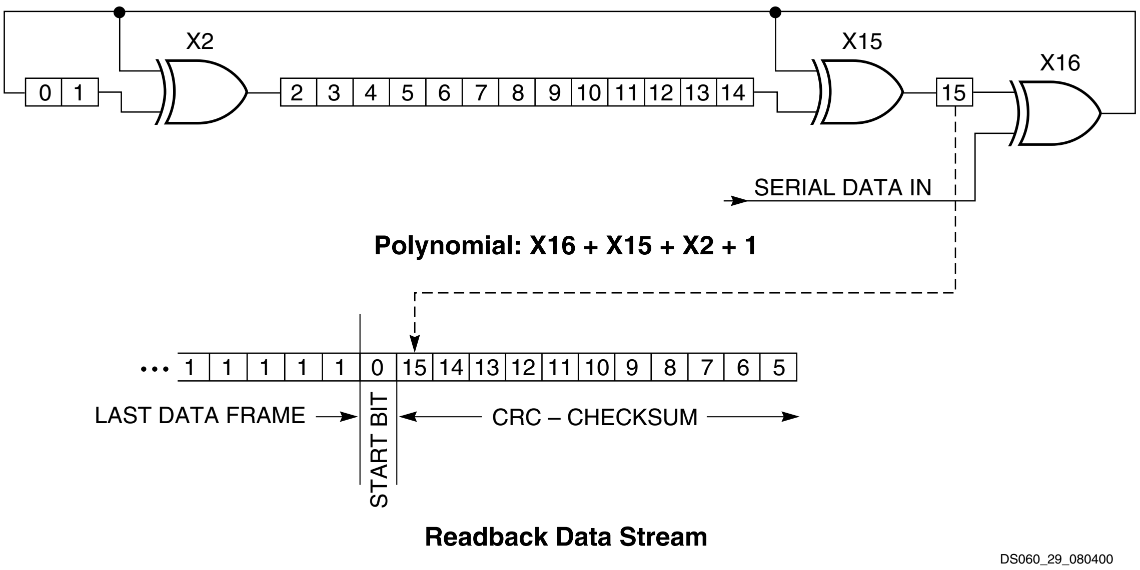

Figure 29: **Circuit for Generating CRC-16**

Configuration Sequence

There are four major steps in the Spartan/XL FPGA power-up configuration sequence.

- Configuration Memory Clear
- Initialization
- Configuration
- Start-up

The full process is illustrated in Figure 30.

Configuration Memory Clear

When power is first applied or is reapplied to an FPGA, an internal circuit forces initialization of the configuration logic. When V_{CC} reaches an operational level, and the circuit passes the write and read test of a sample pair of configuration bits, a time delay is started. This time delay is nominally 16 ms. The delay is four times as long when in Master Serial Mode to allow ample time for all slaves to reach a stable V_{CC}. When all $\overline{\text{INIT}}$ pins are tied together, as recommended, the longest delay takes precedence. Therefore, devices with different time delays can easily be mixed and matched in a daisy chain.

This delay is applied only on power-up. It is not applied when reconfiguring an FPGA by pulsing the $\overline{\text{PROGRAM}}$ pin Low. During this time delay, or as long as the $\overline{\text{PROGRAM}}$ input is asserted, the configuration logic is held in a Configuration Memory Clear state. The configuration-memory frames are consecutively initialized, using the internal oscillator.

At the end of each complete pass through the frame addressing, the power-on time-out delay circuitry and the level of the $\overline{\text{PROGRAM}}$ pin are tested. If neither is asserted, the logic initiates one additional clearing of the configuration frames and then tests the $\overline{\text{INIT}}$ input.

Initialization

During initialization and configuration, user pins HDC, $\overline{\text{LDC}}$, $\overline{\text{INIT}}$ and DONE provide status outputs for the system interface. The outputs $\overline{\text{LDC}}$, $\overline{\text{INIT}}$ and DONE are held Low and HDC is held High starting at the initial application of power.

The open drain $\overline{\text{INIT}}$ pin is released after the final initialization pass through the frame addresses. There is a deliberate delay before a Master-mode device recognizes an inactive $\overline{\text{INIT}}$. Two internal clocks after the $\overline{\text{INIT}}$ pin is recognized as High, the device samples the MODE pin to determine the configuration mode. The appropriate interface lines become active and the configuration preamble and data can be loaded.

to wait after completing the configuration memory clear operation. When $\overline{\text{INIT}}$ is no longer held Low externally, the device determines its configuration mode by capturing the state of the Mode pins, and is ready to start the configuration process. A master device waits up to an additional 300 µs to make sure that any slaves in the optional daisy chain have seen that $\overline{\text{INIT}}$ is High.

For more details on Configuration, refer to the Xilinx Application Note "FPGA Configuration Guidelines" (XAPP090).

Start-Up

Start-up is the transition from the configuration process to the intended user operation. This transition involves a change from one clock source to another, and a change from interfacing parallel or serial configuration data where most outputs are 3-stated, to normal operation with I/O pins active in the user system. Start-up must make sure that the user logic ‘wakes up’ gracefully, that the outputs become active without causing contention with the configuration signals, and that the internal flip-flops are released from the Global Set/Reset (GSR) at the right time.

Start-Up Initiation

Two conditions have to be met in order for the start-up sequence to begin:

- The chip's internal memory must be full, and
- The configuration length count must be met, exactly.

In all configuration modes except Express mode, Spartan/XL devices read the expected length count from the bitstream and store it in an internal register. The length count varies according to the number of devices and the composition of the daisy chain. Each device also counts the number of CCLKs during configuration.

In Express mode, there is no length count. The start-up sequence for each device begins when the device has received its quota of configuration data. Wiring the DONE pins of several devices together delays start-up of all devices until all are fully configured.

Start-Up Events

The device can be programmed to control three start-up events.

- The release of the open-drain DONE output
- The termination of the Global Three-State and the change of configuration-related pins to the user function, activating all IOBs.
- The termination of the Global Set/Reset initialization of all CLB and IOB storage elements.

Figure 31 describes start-up timing in detail. The three events — DONE going High, the internal GSR being de-activated, and the user I/O going active — can all occur in any arbitrary sequence. This relative timing is selected by options in the bitstream generation software. Heavy lines in Figure 31 show the default timing. The thin lines indicate all other possible timing options. The start-up logic must be clocked until the "F" (Finished) state is reached.

The default option, and the most practical one, is for DONE to go High first, disconnecting the configuration data source and avoiding any contention when the I/Os become active one clock later. GSR is then released another clock period later to make sure that user operation starts from stable internal conditions. This is the most common sequence, shown with heavy lines in Figure 31, but the designer can modify it to meet particular requirements.

Start-Up Clock

Normally, the start-up sequence is controlled by the internal device oscillator (CCLK), which is asynchronous to the system clock. As a configuration option, they can be triggered by an on-chip user net called UCLK. This user net can be accessed by placing the STARTUP library symbol, and the start-up modes are known as UCLK_NOSYNC or UCLK_SYNC. This allows the device to wake up in synchronism with the user system.

DONE Pin

Note that DONE is an open-drain output and does not go High unless an internal pull-up is activated or an external pull-up is attached. The internal pull-up is activated as the default by the bitstream generation software.

The DONE pin can also be wire-ANDed with DONE pins of other FPGAs or with other external signals, and can then be used as input to the start-up control logic. This is called “Start-up Timing Synchronous to Done In” and is selected by either CCLK_SYNC or UCLK_SYNC. When DONE is not used as an input, the operation is called “Start-up Timing Not Synchronous to DONE In,” and is selected by either CCLK_NOSYNC or UCLK_NOSYNC. Express mode configuration always uses either CCLK_SYNC or UCLK_SYNC timing, while the other configuration modes can use any of the four timing sequences.

When the UCLK_SYNC option is enabled, the user can externally hold the open-drain DONE output Low, and thus stall all further progress in the start-up sequence until DONE is released and has gone High. This option can be used to force synchronization of several FPGAs to a common user clock, or to guarantee that all devices are successfully configured before any I/Os go active.

Readback Switching Characteristics Guidelines

The following guidelines reflect worst-case values over the recommended operating conditions.

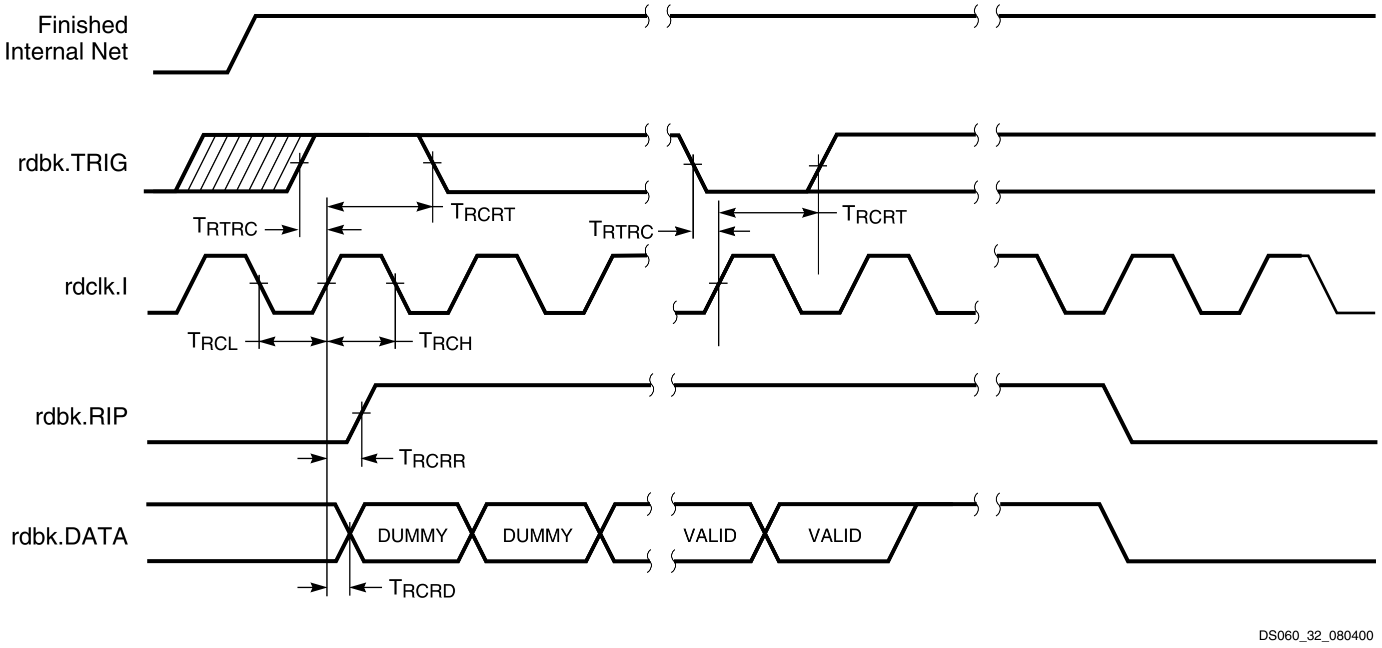

Figure 33: **Spartan and Spartan-XL Readback Timing Diagram**

Spartan and Spartan-XL Readback Switching Characteristics

Symbol		Description	Min	Max	Units
T_{RTRC}	rdbk.TRIG	rdbk.TRIG setup to initiate and abort Readback	200	-	ns
T_{RCRT}		rdbk.TRIG hold to initiate and abort Readback	50	-	ns
T_{RCRD}	rdclk.I	rdbk.DATA delay	-	250	ns
T_{RCRR}		rdbk.RIP delay	-	250	ns
T_{RCH}		High time	250	500	ns
T_{RCL}		Low time	250	500	ns

Notes:

1. Timing parameters apply to all speed grades.
2. If rdbk.TRIG is High prior to Finished, Finished will trigger the first Readback.

Spartan Family Detailed Specifications

Definition of Terms

In the following tables, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

Advance: Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or families. Values are subject to change. Use as estimates, not for production.

Preliminary: Based on preliminary characterization. Further changes are not expected.

Unmarked: Specifications not identified as either Advance or Preliminary are to be considered Final.

Notwithstanding the definition of the above terms, all specifications are subject to change without notice.

Except for pin-to-pin input and output parameters, the AC parameter delay specifications included in this document are derived from measuring internal test patterns. All specifications are representative of worst-case supply voltage and junction temperature conditions. The parameters included are common to popular designs and typical applications.

Spartan Family Absolute Maximum Ratings(1)

Symbol	Description		Value	Units
V_{CC}	Supply voltage relative to GND		–0.5 to +7.0	V
V_{IN}	Input voltage relative to GND(2,3)		–0.5 to V_{CC} +0.5	V
V_{TS}	Voltage applied to 3-state output(2,3)		–0.5 to V_{CC} +0.5	V
T_{STG}	Storage temperature (ambient)		–65 to +150	°C
T_J	Junction temperature	Plastic packages	+125	°C

Notes:
1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.
2. Maximum DC overshoot (above V_{CC}) or undershoot (below GND) must be limited to either 0.5V or 10 mA, whichever is easier to achieve.
3. Maximum AC (during transitions) conditions are as follows; the device pins may undershoot to –2.0V or overshoot to +7.0V, provided this overshoot or undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
4. For soldering guidelines, see the Package Information on the Xilinx website.

Spartan Family Recommended Operating Conditions

Symbol	Description		Min	Max	Units
V_{CC}	Supply voltage relative to GND, T_J = 0°C to +85°C	Commercial	4.75	5.25	V
	Supply voltage relative to GND, T_J = –40°C to +100°C(1)	Industrial	4.5	5.5	V
V_{IH}	High-level input voltage(2)	TTL inputs	2.0	V_{CC}	V
		CMOS inputs	70%	100%	V_{CC}
V_{IL}	Low-level input voltage(2)	TTL inputs	0	0.8	V
		CMOS inputs	0	20%	V_{CC}
T_{IN}	Input signal transition time		-	250	ns

Notes:
1. At junction temperatures above those listed as Recommended Operating Conditions, all delay parameters increase by 0.35% per °C.
2. Input and output measurement thresholds are: 1.5V for TTL and 2.5V for CMOS.

Spartan Family IOB Input Switching Characteristic Guidelines

All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature).

Symbol	Description	Device	Speed Grade -4 Min	Speed Grade -4 Max	Speed Grade -3 Min	Speed Grade -3 Max	Units
Setup Times - TTL Inputs[1]							
T_{ECIK}	Clock Enable (EC) to Clock (IK), no delay	All devices	1.6	-	2.1	-	ns
T_{PICK}	Pad to Clock (IK), no delay	All devices	1.5	-	2.0	-	ns
Hold Times							
T_{IKEC}	Clock Enable (EC) to Clock (IK), no delay	All devices	0.0	-	0.9	-	ns
	All Other Hold Times	All devices	0.0	-	0.0	-	ns
Propagation Delays - TTL Inputs[1]							
T_{PID}	Pad to I1, I2	All devices	-	1.5	-	2.0	ns
T_{PLI}	Pad to I1, I2 via transparent input latch, no delay	All devices	-	2.8	-	3.6	ns
T_{IKRI}	Clock (IK) to I1, I2 (flip-flop)	All devices	-	2.7	-	2.8	ns
T_{IKLI}	Clock (IK) to I1, I2 (latch enable, active Low)	All devices	-	3.2	-	3.9	ns
Delay Adder for Input with Delay Option							
T_{Delay}	$T_{ECIKD} = T_{ECIK} + T_{Delay}$ $T_{PICKD} = T_{PICK} + T_{Delay}$ $T_{PDLI} = T_{PLI} + T_{Delay}$	XCS05	3.6	-	4.0	-	ns
		XCS10	3.7	-	4.1	-	ns
		XCS20	3.8	-	4.2	-	ns
		XCS30	4.5	-	5.0	-	ns
		XCS40	5.5	-	5.5	-	ns
Global Set/Reset							
T_{MRW}	Minimum GSR pulse width	All devices	11.5	-	13.5	-	ns
T_{RRI}	Delay from GSR input to any Q	XCS05	-	9.0	-	11.3	ns
		XCS10	-	9.5	-	11.9	ns
		XCS20	-	10.0	-	12.5	ns
		XCS30	-	10.5	-	13.1	ns
		XCS40	-	11.0	-	13.8	ns

Notes:

1. Delay adder for CMOS Inputs option: for -3 speed grade, add 0.4 ns; for -4 speed grade, add 0.2 ns.
2. Input pad setup and hold times are specified with respect to the internal clock (IK). For setup and hold times with respect to the clock input, see the pin-to-pin parameters in the Pin-to-Pin Input Parameters table.
3. Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

Spartan-XL Family Detailed Specifications

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Spartan-XL Family Absolute Maximum Ratings(1)

Symbol	Description		Value	Units
V_{CC}	Supply voltage relative to GND		–0.5 to 4.0	V
V_{IN}	Input voltage relative to GND	5V Tolerant I/O Checked(2, 3)	–0.5 to 5.5	V
		Not 5V Tolerant I/Os(4, 5)	–0.5 to V_{CC} + 0.5	V
V_{TS}	Voltage applied to 3-state output	5V Tolerant I/O Checked(2, 3)	–0.5 to 5.5	V
		Not 5V Tolerant I/Os(4, 5)	–0.5 to V_{CC} + 0.5	V
T_{STG}	Storage temperature (ambient)		–65 to +150	°C
T_J	Junction temperature	Plastic packages	+125	°C

Notes:

1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.
2. With 5V Tolerant I/Os selected, the Maximum DC overshoot must be limited to either +5.5V or 10 mA and undershoot (below GND) must be limited to either 0.5V or 10 mA, whichever is easier to achieve.
3. With 5V Tolerant I/Os selected, the Maximum AC (during transitions) conditions are as follows; the device pins may undershoot to –2.0V or overshoot to + 7.0V, provided this overshoot or undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
4. Without 5V Tolerant I/Os selected, the Maximum DC overshoot or undershoot must be limited to either 0.5V or 10 mA, whichever is easier to achieve.
5. Without 5V Tolerant I/Os selected, the Maximum AC conditions are as follows; the device pins may undershoot to –2.0V or overshoot to V_{CC} + 2.0V, provided this overshoot or undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
6. For soldering guidelines, see the Package Information on the Xilinx website.

Spartan-XL Family Recommended Operating Conditions

Symbol	Description		Min	Max	Units
V_{CC}	Supply voltage relative to GND, T_J = 0°C to +85°C	Commercial	3.0	3.6	V
	Supply voltage relative to GND, T_J = –40°C to +100°C(1)	Industrial	3.0	3.6	V
V_{IH}	High-level input voltage(2)		50% of V_{CC}	5.5	V
V_{IL}	Low-level input voltage(2)		0	30% of V_{CC}	V
T_{IN}	Input signal transition time		-	250	ns

Notes:

1. At junction temperatures above those listed as Operating Conditions, all delay parameters increase by 0.35% per °C.
2. Input and output measurement threshold is ~50% of V_{CC}.

Spartan-XL Family Pin-to-Pin Output Parameter Guidelines

All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading.

Spartan-XL Family Output Flip-Flop, Clock-to-Out

Symbol	Description	Device	Speed Grade -5 Max	Speed Grade -4 Max	Units
Global Clock to Output using OFF					
T_{ICKOF}	Fast	XCS05XL	4.6	5.2	ns
		XCS10XL	4.9	5.5	ns
		XCS20XL	5.2	5.8	ns
		XCS30XL	5.5	6.2	ns
		XCS40XL	5.8	6.5	ns
Slew Rate Adjustment					
T_{SLOW}	For Output SLOW option add	All Devices	1.5	1.7	ns

Notes:

1. Output delays are representative values where one global clock input drives one vertical clock line in each accessible column, and where all accessible IOB and CLB flip-flops are clocked by the global clock net.
2. Output timing is measured at ~50% V_{CC} threshold with 50 pF external capacitive load.
3. OFF = Output Flip Flop

Pin Descriptions

There are three types of pins in the Spartan/XL devices:

- Permanently dedicated pins
- User I/O pins that can have special functions
- Unrestricted user-programmable I/O pins.

Before and during configuration, all outputs not used for the configuration process are 3-stated with the I/O pull-up resistor network activated. After configuration, if an IOB is unused it is configured as an input with the I/O pull-up resistor network remaining activated.

Any user I/O can be configured to drive the Global Set/Reset net GSR or the global three-state net GTS. See **Global Signals: GSR and GTS**, page 20 for more information.

Device pins for Spartan/XL devices are described in Table 18.

Some Spartan-XL devices are available in Pb-free package options. The Pb-free package options have the same pinouts as the standard package options.

Table 18: **Pin Descriptions**

Pin Name	I/O During Config.	I/O After Config.	Pin Description
Permanently Dedicated Pins			
V_{CC}	X	X	Eight or more (depending on package) connections to the nominal +5V supply voltage (+3.3V for Spartan-XL devices). All must be connected, and each must be decoupled with a 0.01 –0.1 µF capacitor to Ground.
GND	X	X	Eight or more (depending on package type) connections to Ground. All must be connected.
CCLK	I or O	I	During configuration, Configuration Clock (CCLK) is an output in Master mode and is an input in Slave mode. After configuration, CCLK has a weak pull-up resistor and can be selected as the Readback Clock. There is no CCLK High or Low time restriction on Spartan/XL devices, except during Readback. See **Violating the Maximum High and Low Time Specification for the Readback Clock**, page 39 for an explanation of this exception.
DONE	I/O	O	DONE is a bidirectional signal with an optional internal pull-up resistor. As an open-drain output, it indicates the completion of the configuration process. As an input, a Low level on DONE can be configured to delay the global logic initialization and the enabling of outputs. The optional pull-up resistor is selected as an option in the program that creates the configuration bitstream. The resistor is included by default.
$\overline{\text{PROGRAM}}$	I	I	$\overline{\text{PROGRAM}}$ is an active Low input that forces the FPGA to clear its configuration memory. It is used to initiate a configuration cycle. When $\overline{\text{PROGRAM}}$ goes High, the FPGA finishes the current clear cycle and executes another complete clear cycle, before it goes into a WAIT state and releases $\overline{\text{INIT}}$. The $\overline{\text{PROGRAM}}$ pin has a permanent weak pull-up, so it need not be externally pulled up to VCC.
MODE (Spartan) M0, M1 (Spartan-XL)	I	X	The Mode input(s) are sampled after $\overline{\text{INIT}}$ goes High to determine the configuration mode to be used. During configuration, these pins have a weak pull-up resistor. For the most popular configuration mode, Slave Serial, the mode pins can be left unconnected. For Master Serial mode, connect the Mode/M0 pin directly to system ground.

Device-Specific Pinout Tables

Device-specific tables include all packages for each Spartan and Spartan-XL device. They follow the pad locations around the die, and include boundary scan register locations.

Some Spartan-XL devices are available in Pb-free package options. The Pb-free package options have the same pinouts as the standard package options.

XCS05 and XCS05XL Device Pinouts

XCS05/XL Pad Name	PC84(4)	VQ100	Bndry Scan
VCC	P2	P89	-
I/O	P3	P90	32
I/O	P4	P91	35
I/O	-	P92	38
I/O	-	P93	41
I/O	P5	P94	44
I/O	P6	P95	47
I/O	P7	P96	50
I/O	P8	P97	53
I/O	P9	P98	56
I/O, SGCK1(1), GCK8(2)	P10	P99	59
VCC	P11	P100	-
GND	P12	P1	-
I/O, PGCK1(1), GCK1(2)	P13	P2	62
I/O	P14	P3	65
I/O, TDI	P15	P4	68
I/O, TCK	P16	P5	71
I/O, TMS	P17	P6	74
I/O	P18	P7	77
I/O	-	P8	83
I/O	P19	P9	86
I/O	P20	P10	89
GND	P21	P11	-
VCC	P22	P12	-
I/O	P23	P13	92
I/O	P24	P14	95
I/O	-	P15	98
I/O	P25	P16	104
I/O	P26	P17	107
I/O	P27	P18	110
I/O	-	P19	113
I/O	P28	P20	116
I/O, SGCK2(1), GCK2(2)	P29	P21	119
Not Connected(1), M1(2)	P30	P22	122
GND	P31	P23	-
MODE(1), M0 (2)	P32	P24	125
VCC	P33	P25	-
Not Connected(1), PWRDWN(2)	P34	P26	126(1)
I/O, PGCK2(1), GCK3 (2)	P35	P27	127(3)
I/O (HDC)	P36	P28	130(3)
I/O	-	P29	133(3)
I/O (LDC)	P37	P30	136(3)
I/O	P38	P31	139(3)
I/O	P39	P32	142(3)
I/O	-	P33	145(3)
I/O	-	P34	148(3)
I/O	P40	P35	151(3)
I/O (INIT)	P41	P36	154(3)
VCC	P42	P37	-
GND	P43	P38	-
I/O	P44	P39	157(3)
I/O	P45	P40	160(3)
I/O	-	P41	163(3)
I/O	-	P42	166(3)
I/O	P46	P43	169(3)
I/O	P47	P44	172(3)
I/O	P48	P45	175(3)
I/O	P49	P46	178(3)
I/O	P50	P47	181(3)
I/O, SGCK3(1), GCK4(2)	P51	P48	184(3)
GND	P52	P49	-
DONE	P53	P50	-
VCC	P54	P51	-
PROGRAM	P55	P52	-
I/O (D7(2))	P56	P53	187(3)
I/O, PGCK3(1), GCK5(2)	P57	P54	190(3)
I/O (D6(2))	P58	P55	193(3)
I/O	-	P56	196(3)
I/O (D5(2))	P59	P57	199(3)
I/O	P60	P58	202(3)
I/O	-	P59	205(3)
I/O	-	P60	208(3)
I/O (D4(2))	P61	P61	211(3)
I/O	P62	P62	214(3)
VCC	P63	P63	-
GND	P64	P64	-
I/O (D3(2))	P65	P65	217(3)
I/O	P66	P66	220(3)
I/O	-	P67	223(3)
I/O (D2(2))	P67	P68	229(3)
I/O	P68	P69	232(3)
I/O (D1(2))	P69	P70	235(3)

XCS10 and XCS10XL Device Pinouts

XCS10/XL Pad Name	PC84(4)	VQ100	CS144(2,4)	TQ144	Bndry Scan
VCC	P33	P25	N1	P37	-
Not Connected(1) PWRDWN(2)	P34	P26	N2	P38	174 (1)
I/O, PGCK2(1) GCK3(2)	P35	P27	M3	P39	175(3)
I/O (HDC)	P36	P28	N3	P40	178 (3)
I/O	-	-	K4	P41	181 (3)
I/O	-	-	L4	P42	184 (3)
I/O	-	P29	M4	P43	187 (3)
I/O (LDC)	P37	P30	N4	P44	190 (3)
GND	-	-	K5	P45	-
I/O	-	-	L5	P46	193 (3)
I/O	-	-	M5	P47	196 (3)
I/O	P38	P31	N5	P48	199 (3)
I/O	P39	P32	K6	P49	202 (3)
I/O	-	P33	L6	P50	205 (3)
I/O	-	P34	M6	P51	208 (3)
I/O	P40	P35	N6	P52	211 (3)
I/O (INIT)	P41	P36	M7	P53	214 (3)
VCC	P42	P37	N7	P54	-
GND	P43	P38	L7	P55	-
I/O	P44	P39	K7	P56	217 (3)
I/O	P45	P40	N8	P57	220 (3)
I/O	-	P41	M8	P58	223 (3)
I/O	-	P42	L8	P59	226 (3)
I/O	P46	P43	K8	P60	229 (3)
I/O	P47	P44	N9	P61	232 (3)
I/O	-	-	M9	P62	235 (3)
I/O	-	-	L9	P63	238 (3)
GND	-	-	K9	P64	-
I/O	P48	P45	N10	P65	241 (3)
I/O	P49	P46	M10	P66	244 (3)
I/O	-	-	L10	P67	247 (3)
I/O	-	-	N11	P68	250 (3)
I/O	P50	P47	M11	P69	253 (3)
I/O, SGCK3(1) GCK4(2)	P51	P48	L11	P70	256 (3)
GND	P52	P49	N12	P71	-
DONE	P53	P50	M12	P72	-
VCC	P54	P51	N13	P73	-
PROGRAM	P55	P52	M13	P74	-
I/O (D7(2))	P56	P53	L12	P75	259 (3)

XCS10 and XCS10XL Device Pinouts

XCS10/XL Pad Name	PC84(4)	VQ100	CS144(2,4)	TQ144	Bndry Scan
I/O, PGCK3(1) GCK5(2)	P57	P54	L13	P76	262 (3)
I/O	-	-	K10	P77	265 (3)
I/O	-	-	K11	P78	268 (3)
I/O (D6(2))	P58	P55	K12	P79	271 (3)
I/O	-	P56	K13	P80	274 (3)
GND	-	-	J10	P81	-
I/O	-	-	J11	P82	277 (3)
I/O	-	-	J12	P83	280 (3)
I/O (D5(2))	P59	P57	J13	P84	283 (3)
I/O	P60	P58	H10	P85	286 (3)
I/O	-	P59	H11	P86	289 (3)
I/O	-	P60	H12	P87	292 (3)
I/O (D4(2))	P61	P61	H13	P88	295 (3)
I/O	P62	P62	G12	P89	298 (3)
VCC	P63	P63	G13	P90	-
GND	P64	P64	G11	P91	-
I/O (D3(2))	P65	P65	G10	P92	301 (3)
I/O	P66	P66	F13	P93	304 (3)
I/O	-	P67	F12	P94	307 (3)
I/O	-	-	F11	P95	310 (3)
I/O (D2(2))	P67	P68	F10	P96	313 (3)
I/O	P68	P69	E13	P97	316 (3)
I/O	-	-	E12	P98	319 (3)
I/O	-	-	E11	P99	322 (3)
GND	-	-	E10	P100	-
I/O (D1(2))	P69	P70	D13	P101	325 (3)
I/O	P70	P71	D12	P102	328 (3)
I/O	-	-	D11	P103	331 (3)
I/O	-	-	C13	P104	334 (3)
I/O (D0(2), DIN)	P71	P72	C12	P105	337 (3)
I/O, SGCK4(1) GCK6(2) (DOUT)	P72	P73	C11	P106	340 (3)
CCLK	P73	P74	B13	P107	-
VCC	P74	P75	B12	P108	-
O, TDO	P75	P76	A13	P109	0
GND	P76	P77	A12	P110	-
I/O	P77	P78	B11	P111	2
I/O, PGCK4(1) GCK7(2)	P78	P79	A11	P112	5
I/O	-	-	D10	P113	8
I/O	-	-	C10	P114	11
I/O (CS1(2))	P79	P80	B10	P115	14

XCS30 and XCS30XL Device Pinouts *(Continued)*

XCS30/XL Pad Name	VQ100(5)	TQ144	PQ208	PQ240	BG256(5)	CS280(2,5)	Bndry Scan
I/O	-	-	P85	P97	U12	T11	382 (3)
I/O	-	-	-	P99	V13	U12	385 (3)
I/O	-	-	-	P100	Y14	T12	388 (3)
VCC	-	-	P86	P101	VCC(4)	W13	-
I/O	P43	P60	P87	P102	Y15	V13	391 (3)
I/O	P44	P61	P88	P103	V14	U13	394 (3)
I/O	-	P62	P89	P104	W15	T13	397 (3)
I/O	-	P63	P90	P105	Y16	W14	400 (3)
GND	-	P64	P91	P106	GND(4)	GND(4)	-
I/O	-	-	-	P107	V15	V14	403 (3)
I/O	-	-	P92	P108	W16	U14	406 (3)
I/O	-	-	P93	P109	Y17	T14	409 (3)
I/O	-	-	P94	P110	V16	R14	412 (3)
I/O	-	-	P95	P111	W17	W15	415 (3)
I/O	-	-	P96	P112	Y18	U15	418 (3)
I/O	P45	P65	P97	P113	U16	V16	421 (3)
I/O	P46	P66	P98	P114	V17	U16	424 (3)
I/O	-	P67	P99	P115	W18	W17	427 (3)
I/O	-	P68	P100	P116	Y19	W18	430 (3)
I/O	P47	P69	P101	P117	V18	V17	433 (3)
I/O, SGCK3(1), GCK4(2)	P48	P70	P102	P118	W19	V18	436 (3)
GND	P49	P71	P103	P119	GND(4)	GND(4)	-
DONE	P50	P72	P104	P120	Y20	W19	-
VCC	P51	P73	P105	P121	VCC(4)	U17	-
$\overline{\text{PROGRAM}}$	P52	P74	P106	P122	V19	U18	-
I/O (D7(2))	P53	P75	P107	P123	U19	V19	439 (3)
I/O, PGCK3(1), GCK5(2)	P54	P76	P108	P124	U18	U19	442 (3)
I/O	-	P77	P109	P125	T17	T16	445 (3)
I/O	-	P78	P110	P126	V20	T17	448 (3)
I/O	-	-	-	P127	U20	T18	451 (3)
I/O	-	-	P111	P128	T18	T19	454 (3)
I/O (D6(2))	P55	P79	P112	P129	T19	R16	457 (3)
I/O	P56	P80	P113	P130	T20	R19	460 (3)
I/O	-	-	P114	P131	R18	P15	463 (3)
I/O	-	-	P115	P132	R19	P17	466 (3)
I/O	-	-	P116	P133	R20	P18	469 (3)
I/O	-	-	P117	P134	P18	P16	472 (3)
GND	-	P81	P118	P135	GND(4)	GND(4)	-
I/O	-	-	-	P136	P20	P19	475 (3)
I/O	-	-	-	P137	N18	N17	478 (3)
I/O	-	P82	P119	P138	N19	N18	481 (3)
I/O	-	P83	P120	P139	N20	N19	484 (3)
VCC	-	-	P121	P140	VCC(4)	N16	-
I/O (D5(2))	P57	P84	P122	P141	M17	M19	487 (3)
I/O	P58	P85	P123	P142	M18	M17	490 (3)

CS280

VCC Pins					
E5	E7	E8	E9	E11	E12
E13	G5	G15	H5	H15	J5
J15	L5	L15	M5	M15	N5
N15	R7	R8	R9	R11	R12
R13	-	-	-	-	-
Not Connected Pins					
A4	A12	C8	C12	C15	D1
D2	D5	D8	D17	D18	E15
H2	H3	H18	H19	L4	M1
M16	M18	R2	R4	R5	R15
R17	T8	T15	U5	V8	V12
W12	W16	-	-	-	-
Not Connected Pins (VCC in XCS40XL)					
B5	B15	E3	E18	R3	R18
V5	V15	-	-	-	-

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XCS40 and XCS40XL Device Pinouts

XCS40/XL Pad Name	PQ208	PQ240	BG256	CS280(2,5)	Bndry Scan
VCC	P183	P212	VCC(4)	VCC(4)	-
I/O	P184	P213	C10	D10	86
I/O	P185	P214	D10	E10	89
I/O	P186	P215	A9	A9	92
I/O	P187	P216	B9	B9	95
I/O	P188	P217	C9	C9	98
I/O	P189	P218	D9	D9	101
I/O	P190	P220	A8	A8	104
I/O	P191	P221	B8	B8	107
I/O	-	-	C8	C8	110
I/O	-	-	A7	D8	113
VCC	P192	P222	VCC(4)	VCC(4)	-
I/O	-	P223	A6	B7	116
I/O	-	P224	C7	C7	119
I/O	P193	P225	B6	D7	122
I/O	P194	P226	A5	A6	125
GND	P195	P227	GND(4)	GND(4)	-
I/O	P196	P228	C6	B6	128
I/O	P197	P229	B5	C6	131
I/O	P198	P230	A4	D6	134
I/O	P199	P231	C5	E6	137
I/O	P200	P232	B4	A5	140
I/O	P201	P233	A3	C5	143
I/O	-	-	-	D5	146
I/O	-	-	-	A4	149
I/O	P202	P234	D5	B4	152
I/O	P203	P235	C4	C4	155
I/O	P204	P236	B3	A3	158
I/O	P205	P237	B2	A2	161
I/O	P206	P238	A2	B3	164
I/O, SGCK1(1), GCK8(2)	P207	P239	C3	B2	167
VCC	P208	P240	VCC(4)	VCC(4)	-
GND	P1	P1	GND(4)	GND(4)	-
I/O, PGCK1(1), GCK1(2)	P2	P2	B1	C3	170
I/O	P3	P3	C2	C2	173
I/O	P4	P4	D2	B1	176
I/O	P5	P5	D3	C1	179
I/O, TDI	P6	P6	E4	D4	182
I/O, TCK	P7	P7	C1	D3	185
I/O	-	-	-	D2	188
I/O	-	-	-	D1	191
I/O	P8	P8	D1	E2	194
I/O	P9	P9	E3	E4	197
I/O	P10	P10	E2	E1	200
I/O	P11	P11	E1	F5	203
I/O	P12	P12	F3	F3	206
I/O	-	P13	F2	F2	209
GND	P13	P14	GND(4)	GND(4)	-
I/O	P14	P15	G3	F4	212
I/O	P15	P16	G2	F1	215
I/O, TMS	P16	P17	G1	G3	218
I/O	P17	P18	H3	G2	221
VCC	P18	P19	VCC(4)	VCC(4)	-
I/O	-	P20	H2	G4	224
I/O	-	P21	H1	H1	227
I/O	-	-	J4	H3	230
I/O	-	-	J3	H2	233
I/O	P19	P23	J2	H4	236
I/O	P20	P24	J1	J1	239
I/O	P21	P25	K2	J2	242
I/O	P22	P26	K3	J3	245
I/O	P23	P27	K1	J4	248
I/O	P24	P28	L1	K1	251

Product Availability

Table 19 shows the packages and speed grades for Spartan/XL devices. Table 20 shows the number of user I/Os available for each device/package combination.

Table 19: **Component Availability Chart for Spartan/XL FPGAs**

	Pins	**84**	**100**	**144**	**144**	**208**	**240**	**256**	**280**
	Type	**Plastic PLCC**	**Plastic VQFP**	**Chip Scale**	**Plastic TQFP**	**Plastic PQFP**	**Plastic PQFP**	**Plastic BGA**	**Chip Scale**
Device	**Code**	**PC84(3)**	**VQ100(3)**	**CS144(3)**	**TQ144**	**PQ208**	**PQ240**	**BG256(3)**	**CS280(3)**
XCS05	-3	C(3)	C, I	-	-	-	-	-	-
	-4	C(3)	C	-	-	-	-	-	-
XCS10	-3	C(3)	C, I	-	C	-	-	-	-
	-4	C(3)	C	-	C	-	-	-	-
XCS20	-3	-	C	-	C, I	C, I	-	-	-
	-4	-	C	-	C	C	-	-	-
XCS30	-3	-	C(3)	-	C, I	C, I	C	C(3)	-
	-4	-	C(3)	-	C	C	C	C(3)	-
XCS40	-3	-	-	-	-	C, I	C	C	-
	-4	-	-	-	-	C	C	C	-
XCS05XL	-4	C(3)	C, I	-	-	-	-	-	-
	-5	C(3)	C	-	-	-	-	-	-
XCS10XL	-4	C(3)	C, I	C(3)	C	-	-	-	-
	-5	C(3)	C	C(3)	C	-	-	-	-
XCS20XL	-4	-	C, I	C(3)	C, I	C, I	-	-	-
	-5	-	C	C(3)	C	C	-	-	-
XCS30XL	-4	-	C, I	-	C, I	C, I	C	C	C(3)
	-5	-	C	-	C	C	C	C	C(3)
XCS40XL	-4	-	-	-	-	C, I	C	C, I	C(3)
	-5	-	-	-	-	C	C	C	C(3)

6/25/08

Notes:

1. C = Commercial $T_J = 0° \text{ to } +85°C$
2. I = Industrial $T_J = –40°C \text{ to } +100°C$
3. PC84, CS144, and CS280 packages, and VQ100 and BG256 packages for XCS30 only, discontinued by **PDN2004-01**
4. Some Spartan-XL devices are available in Pb-free package options. The Pb-free packages insert a "G" in the package code. Contact Xilinx for availability.

Package Specifications

Package drawings and material declaration data sheets for the Spartan/XL devices can be found on the Xilinx website at:

www.xilinx.com/support/documentation/spartan-xl.htm#19687

Thermal data for the Spartan/XL packages can be found using the thermal query tool on the Xilinx website at:

www.xilinx.com/cgi-bin/thermal/thermal.pl

Revision History

The following table shows the revision history for this document.

Date	Version	Description
11/20/98	1.3	Added Spartan-XL specs and Power Down.
01/06/99	1.4	All Spartan-XL -4 specs designated Preliminary with no changes.
03/02/00	1.5	Added CS package, updated Spartan-XL specs to Final.
09/19/01	1.6	Reformatted, updated power specs, clarified configuration information. Removed T_{SOL} soldering information from Absolute Maximum Ratings table. Changed Figure 26: Slave Serial Mode Characteristics: T_{CCH}, T_{CCL} from 45 to 40 ns. Changed Master Mode Configuration Switching Characteristics: T_{CCLK} min. from 80 to 100 ns. Added Total Dist. RAM Bits to Table 1; added **Start-Up**, page 36 characteristics.
06/27/02	1.7	Clarified Express Mode pseudo daisy chain. Added new Industrial options. Clarified XCS30XL CS280 V_{CC} pinout.
06/26/08	1.8	Noted that PC84, CS144, and CS280 packages, and VQ100 and BG256 packages for XCS30 only, are discontinued by **PDN2004-01**. Extended description of recommended maximum delay of reconfiguration in **Delaying Configuration After Power-Up**, page 35. Added reference to Pb-free package options and provided link to **Package Specifications**, page 81. Updated links.
03/01/13	2.0	The products listed in this data sheet are obsolete. See **XCN10016** and **XCN11010** for further information.