Microsemi Corporation - A54SX16-CQ208 Datasheet

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	1452
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	175
Number of Gates	24000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	208-BFCQFP with Tie Bar
Supplier Device Package	208-CQFP (75x75)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a54sx16-cq208

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

SX Family FPGAs

General Description

The Actel SX family of FPGAs features a sea-of-modules architecture that delivers device performance and integration levels not currently achieved by any other FPGA architecture. SX devices greatly simplify design time, enable dramatic reductions in design costs and power consumption, and further decrease time to market for performance-intensive applications.

The Actel SX architecture features two types of logic modules, the combinatorial cell (C-cell) and the register cell (R-cell), each optimized for fast and efficient mapping of synthesized logic functions. The routing and interconnect resources are in the metal layers above the logic modules, providing optimal use of silicon. This enables the entire floor of the device to be spanned with an uninterrupted grid of fine-grained, synthesis-friendly logic modules (or “sea-of-modules”), which reduces the distance signals have to travel between logic modules. To minimize signal propagation delay, SX devices employ both local and general routing resources. The high-speed local routing resources (DirectConnect and FastConnect) enable very fast local signal propagation that is optimal for fast counters, state machines, and datapath logic. The general system of segmented routing tracks allows any logic module in the array to be connected to any other logic or I/O module. Within this system, propagation delay is minimized by limiting the number of antifuse interconnect elements to five (90 percent of connections typically use only three antifuses). The unique local and general routing structure featured in SX devices gives fast and predictable performance, allows 100 percent pin-locking with full logic utilization, enables concurrent PCB development, reduces design time, and allows designers to achieve performance goals with minimum effort.

Further complementing SX’s flexible routing structure is a hardwired, constantly loaded clock network that has been tuned to provide fast clock propagation with minimal clock skew. Additionally, the high performance of the internal logic has eliminated the need to embed latches or flip-flops in the I/O cells to achieve fast clock-to-out or fast input setup times. SX devices have easy to use I/O cells that do not require HDL instantiation, facilitating design reuse and reducing design and verification time.

SX Family Architecture

The SX family architecture was designed to satisfy next-generation performance and integration requirements for production-volume designs in a broad range of applications.

Programmable Interconnect Element

The SX family provides efficient use of silicon by locating the routing interconnect resources between the Metal 2 (M2) and Metal 3 (M3) layers (Figure 1-1 on page 1-2). This completely eliminates the channels of routing and interconnect resources between logic modules (as implemented on SRAM FPGAs and previous generations of antifuse FPGAs), and enables the entire floor of the device to be spanned with an uninterrupted grid of logic modules.

Interconnection between these logic modules is achieved using The Actel patented metal-to-metal programmable antifuse interconnect elements, which are embedded between the M2 and M3 layers. The antifuses are normally open circuit and, when programmed, form a permanent low-impedance connection.

The extremely small size of these interconnect elements gives the SX family abundant routing resources and provides excellent protection against design pirating. Reverse engineering is virtually impossible because it is extremely difficult to distinguish between programmed and unprogrammed antifuses, and there is no configuration bitstream to intercept.

Additionally, the interconnect elements (i.e., the antifuses and metal tracks) have lower capacitance and lower resistance than any other device of similar capacity, leading to the fastest signal propagation in the industry.

Logic Module Design

The SX family architecture is described as a “sea-of-modules” architecture because the entire floor of the device is covered with a grid of logic modules with virtually no chip area lost to interconnect elements or routing. The Actel SX family provides two types of logic modules, the register cell (R-cell) and the combinatorial cell (C-cell).

Routing Resources

Clusters and SuperClusters can be connected through the use of two innovative local routing resources called *FastConnect* and *DirectConnect,* which enable extremely fast and predictable interconnection of modules within clusters and SuperClusters (Figure 1-5 and Figure 1-6). This routing architecture also dramatically reduces the number of antifuses required to complete a circuit, ensuring the highest possible performance.

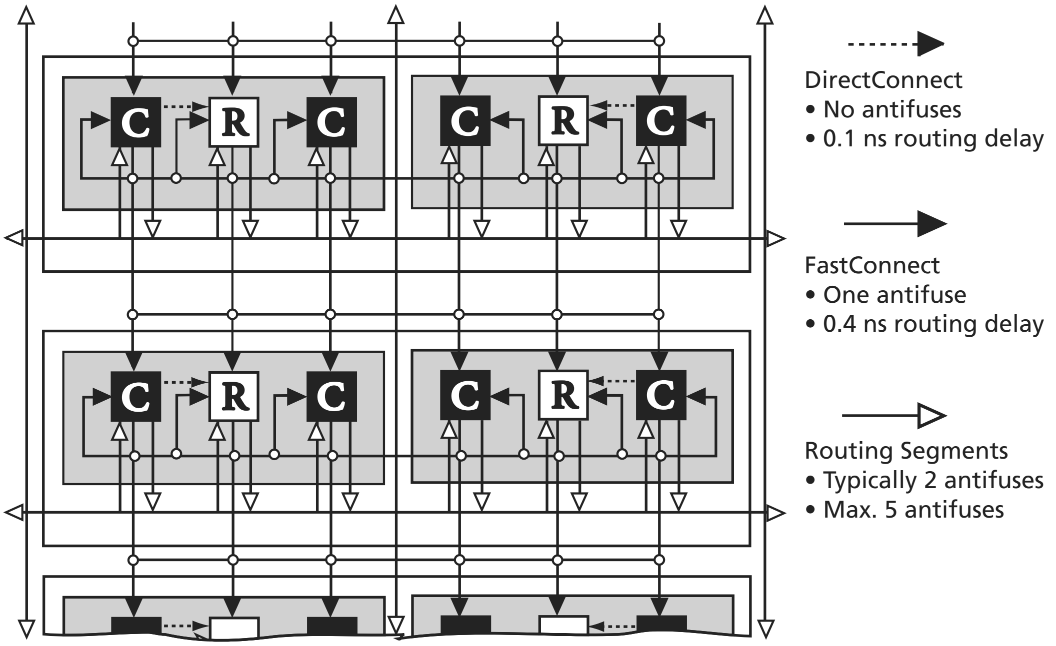


Figure 1-5 • **DirectConnect and FastConnect for Type 1 SuperClusters**

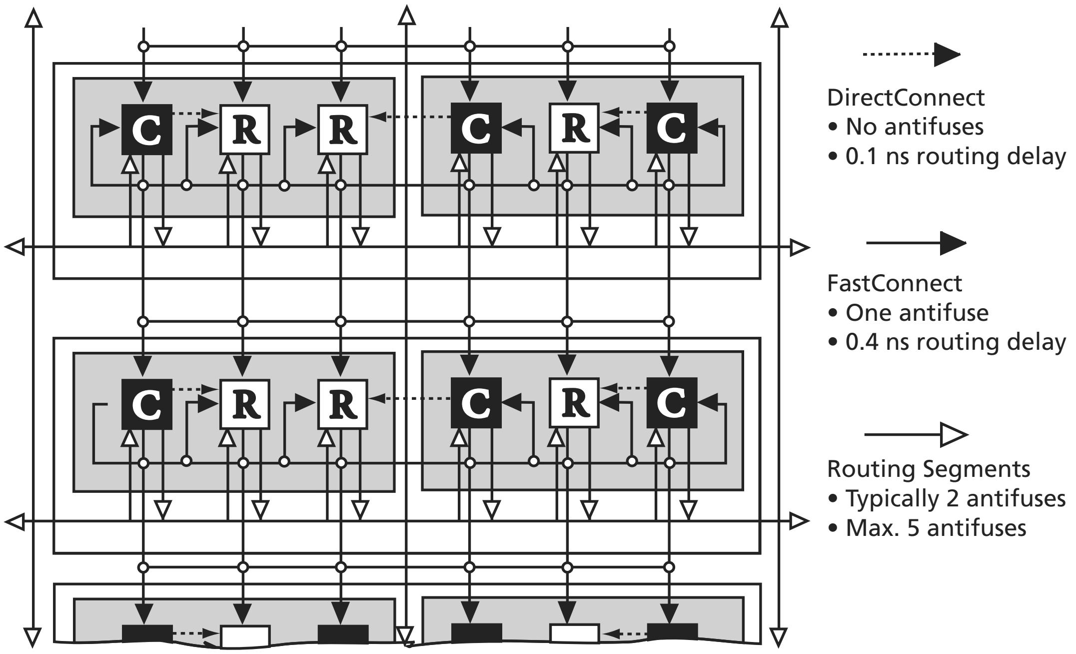


Figure 1-6 • **DirectConnect and FastConnect for Type 2 SuperClusters**

Boundary Scan Testing (BST)

All SX devices are IEEE 1149.1 compliant. SX devices offer superior diagnostic and testing capabilities by providing Boundary Scan Testing (BST) and probing capabilities. These functions are controlled through the special test pins in conjunction with the program fuse. The functionality of each pin is described in Table 1-2. In the dedicated test mode, TCK, TDI, and TDO are dedicated pins and cannot be used as regular I/Os. In flexible mode, TMS should be set HIGH through a pull-up resistor of 10 kΩ. TMS can be pulled LOW to initiate the test sequence.

The program fuse determines whether the device is in dedicated or flexible mode. The default (fuse not blown) is flexible mode.

Table 1-2 • **Boundary Scan Pin Functionality**

Program Fuse Blown (Dedicated Test Mode)	Program Fuse Not Blown (Flexible Mode)
TCK, TDI, TDO are dedicated BST pins.	TCK, TDI, TDO are flexible and may be used as I/Os.
No need for pull-up resistor for TMS	Use a pull-up resistor of 10 kΩ on TMS.

Dedicated Test Mode

In Dedicated mode, all JTAG pins are reserved for BST; designers cannot use them as regular I/Os. An internal pull-up resistor is automatically enabled on both TMS and TDI pins, and the TMS pin will function as defined in the IEEE 1149.1 (JTAG) specification.

To select Dedicated mode, users need to reserve the JTAG pins in Actel's Designer software by checking the "Reserve JTAG" box in "Device Selection Wizard" (Figure 1-7). JTAG pins comply with LVTTL/TTL I/O specification regardless of whether they are used as a user I/O or a JTAG I/O. Refer to the Table 1-5 on page 1-8 for detailed specifications.

Figure 1-7 • **Device Selection Wizard**

Development Tool Support

The SX family of FPGAs is fully supported by both the Actel Libero® Integrated Design Environment (IDE) and Designer FPGA Development software. Actel Libero IDE is a design management environment, seamlessly integrating design tools while guiding the user through the design flow, managing all design and log files, and passing necessary design data among tools. Libero IDE allows users to integrate both schematic and HDL synthesis into a single flow and verify the entire design in a single environment. Libero IDE includes Synplify® for Actel from Synplicity®, ViewDraw® for Actel from Mentor Graphics®, Model*Sim*® HDL Simulator from Mentor Graphics, WaveFormer Lite™ from SynaptiCAD™, and Designer software from Actel. Refer to the Libero IDE flow diagram (located on the Actel website) for more information.

Actel Designer software is a place-and-route tool and provides a comprehensive suite of backend support tools for FPGA development. The Designer software includes timing-driven place-and-route, and a world-class integrated static timing analyzer and constraints editor. With the Designer software, a user can select and lock package pins while only minimally impacting the results of place-and-route. Additionally, the back-annotation flow is compatible with all the major simulators, and the simulation results can be cross-probed with Silicon Explorer II, Actel integrated verification and logic analysis tool. Another tool included in the Designer software is the SmartGen core generator, which easily creates popular and commonly used logic functions for implementation into your schematic or HDL design. Actel Designer software is compatible with the most popular FPGA design entry and verification tools from companies such as Mentor Graphics, Synplicity, Synopsys®, and Cadence® Design Systems. The Designer software is available for both the Windows® and UNIX® operating systems.

Probe Circuit Control Pins

The Silicon Explorer II tool uses the boundary scan ports (TDI, TCK, TMS, and TDO) to select the desired nets for verification. The selected internal nets are assigned to the PRA/PRB pins for observation. Figure 1-8 on page 1-7 illustrates the interconnection between Silicon Explorer II and the FPGA to perform in-circuit verification.

Design Considerations

The TDI, TCK, TDO, PRA, and PRB pins should not be used as input or bidirectional ports. Because these pins are active during probing, critical signals input through these pins are not available while probing. In addition, the Security Fuse should not be programmed because doing so disables the Probe Circuitry.

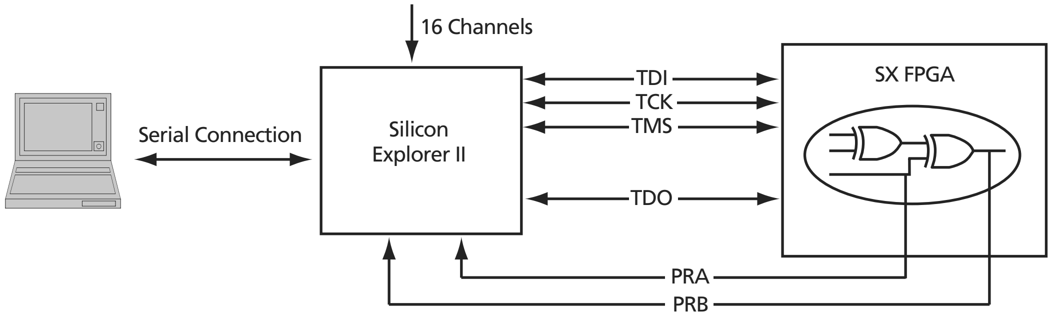


Figure 1-8 • **Probe Setup**

Programming

Device programming is supported through Silicon Sculptor series of programmers. In particular, Silicon Sculptor II are compact, robust, single-site and multi-site device programmer for the PC.

With standalone software, Silicon Sculptor II allows concurrent programming of multiple units from the same PC, ensuring the fastest programming times possible. Each fuse is subsequently verified by Silicon Sculptor II to insure correct programming. In addition, integrity tests ensure that no extra fuses are programmed. Silicon Sculptor II also provides extensive hardware self-testing capability.

The procedure for programming an SX device using Silicon Sculptor II are as follows:

1. Load the .AFM file
2. Select the device to be programmed
3. Begin programming

When the design is ready to go to production, Actel offers device volume-programming services either through distribution partners or via in-house programming from the factory.

For more details on programming SX devices, refer to the *Programming Antifuse Devices* application note and the *Silicon Sculptor II User's Guide*.

3.3 V / 5 V Operating Conditions

Table 1-3 • **Absolute Maximum Ratings**[1]

Symbol	Parameter	Limits	Units
V_{CCR}[2]	DC Supply Voltage[3]	–0.3 to + 6.0	V
V_{CCA}[2]	DC Supply Voltage	–0.3 to + 4.0	V
V_{CCI}[2]	DC Supply Voltage (A54SX08, A54SX16, A54SX32)	–0.3 to + 4.0	V
V_{CCI}[2]	DC Supply Voltage (A54SX16P)	–0.3 to + 6.0	V
V_I	Input Voltage	–0.5 to + 5.5	V
V_O	Output Voltage	–0.5 to + 3.6	V
I_{IO}	I/O Source Sink Current[3]	–30 to + 5.0	mA
T_{STG}	Storage Temperature	–65 to +150	°C

Notes:

1. *Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Device should not be operated outside the Recommended Operating Conditions.*
2. *V_{CCR} in the A54SX16P must be greater than or equal to V_{CCI} during power-up and power-down sequences and during normal operation.*
3. *Device inputs are normally high impedance and draw extremely low current. However, when input voltage is greater than V_{CC} + 0.5 V or less than GND – 0.5 V, the internal protection diodes will forward-bias and can draw excessive current.*

Step 1: Define Terms Used in Formula

	V_{CCA}	3.3
Module		
Number of logic modules switching at f_m (Used 50%)	m	264
Average logic modules switching rate f_m (MHz) (Guidelines: f/10)	f_m	20
Module capacitance C_{EQM} (pF)	C_{EQM}	4.0
Input Buffer		
Number of input buffers switching at f_n	n	1
Average input switching rate f_n (MHz) (Guidelines: f/5)	f_n	40
Input buffer capacitance C_{EQI} (pF)	C_{EQI}	3.4
Output Buffer		
Number of output buffers switching at f_p	p	1
Average output buffers switching rate f_p(MHz) (Guidelines: f/10)	f_p	20
Output buffers buffer capacitance C_{EQO} (pF)	C_{EQO}	4.7
Output Load capacitance C_L (pF)	C_L	35
RCLKA		
Number of Clock loads q_1	q_1	528
Capacitance of routed array clock (pF)	C_{EQCR}	1.6
Average clock rate (MHz)	f_{q1}	200
Fixed capacitance (pF)	r_1	138
RCLKB		
Number of Clock loads q_2	q_2	0
Capacitance of routed array clock (pF)	C_{EQCR}	1.6
Average clock rate (MHz)	f_{q2}	0
Fixed capacitance (pF)	r_2	138
HCLK		
Number of Clock loads	s_1	0
Variable capacitance of dedicated array clock (pF)	C_{EQHV}	0.615
Fixed capacitance of dedicated array clock (pF)	C_{EQHF}	96
Average clock rate (MHz)	f_{s1}	0

Step 2: Calculate Dynamic Power Consumption

$V_{CCA} \times V_{CCA}$	10.89
$m \times f_m \times C_{EQM}$	0.02112
$n \times f_n \times C_{EQI}$	0.000136
$p \times f_p \times (C_{EQO}+C_L)$	0.000794
$0.5\ (q_1 \times C_{EQCR} \times f_{q1}) + (r_1 \times f_{q1})$	0.11208
$0.5(q_2 \times C_{EQCR} \times f_{q2}) + (r_2 \times f_{q2})$	0
$0.5\ (s_1 \times C_{EQHV} \times f_{s1}) + (C_{EQHF} \times f_{s1})$	0

$P_{AC} = 1.461\ \text{W}$

Step 3: Calculate DC Power Dissipation

DC Power Dissipation

$$P_{DC} = (I_{standby}) \times V_{CCA} + (I_{standby}) \times V_{CCR} + (I_{standby}) \times V_{CCI} + X \times V_{OL} \times I_{OL} + Y(V_{CCI} - V_{OH}) \times V_{OH}$$

EQ 1-12

For a rough estimate of DC Power Dissipation, only use $P_{DC} = (I_{standby}) \times V_{CCA}$. The rest of the formula provides a very small number that can be considered negligible.

$P_{DC} = (I_{standby}) \times V_{CCA}$

$P_{DC} = .55\ \text{mA} \times 3.3\ \text{V}$

$P_{DC} = 0.001815\ \text{W}$

Step 4: Calculate Total Power Consumption

$P_{Total} = P_{AC} + P_{DC}$

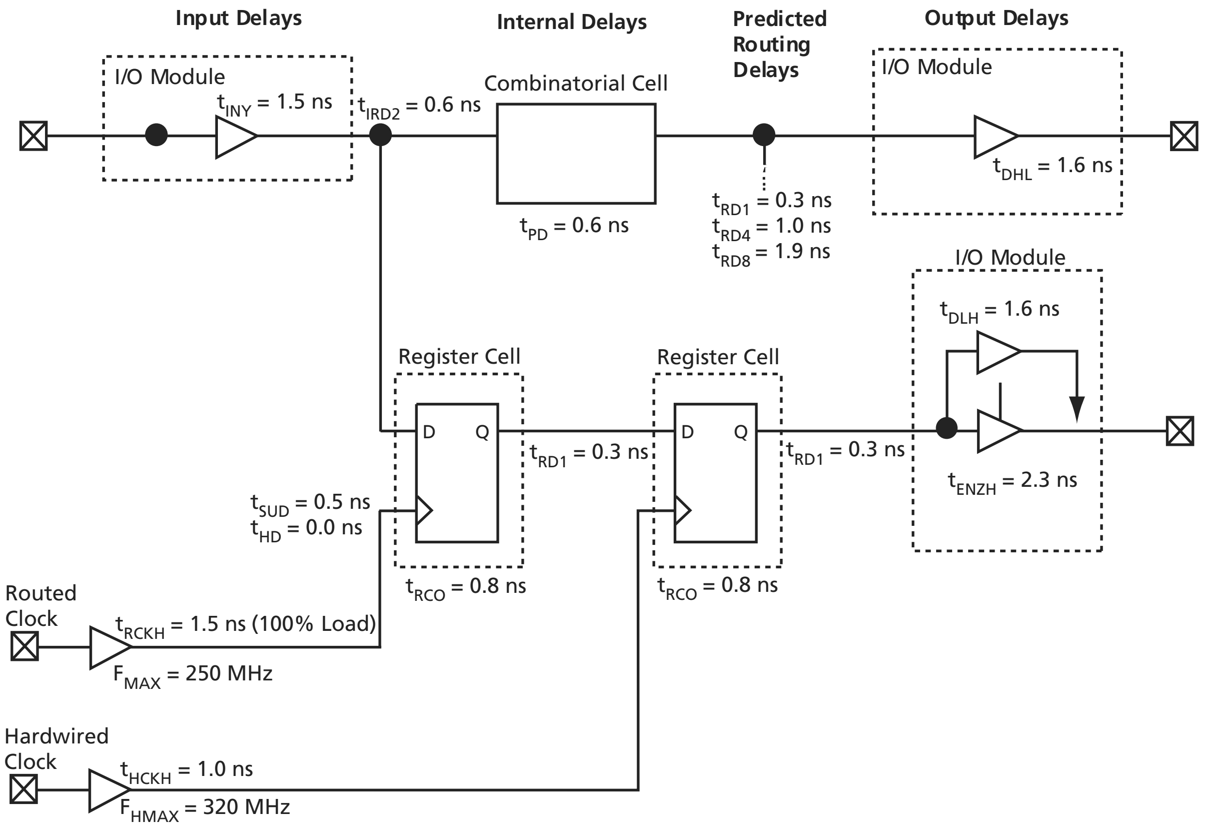
$P_{Total} = 1.461 + 0.001815$

$P_{Total} = 1.4628\ \text{W}$

Step 5: Compare Estimated Power Consumption against Characterized Power Consumption

The estimated total power consumption for this design is 1.46 W. The characterized power consumption for this design at 200 MHz is 1.0164 W.

SX Timing Model



Note: *Values shown for A54SX08-3, worst-case commercial conditions.*

Figure 1-12 • **SX Timing Model**

Hardwired Clock

External Setup $= t_{INY} + t_{IRD1} + t_{SUD} - t_{HCKH}$

$= 1.5 + 0.3 + 0.5 - 1.0 = 1.3$ ns

EQ 1-15

Clock-to-Out (Pin-to-Pin)

$= t_{HCKH} + t_{RCO} + t_{RD1} + t_{DHL}$

$= 1.0 + 0.8 + 0.3 + 1.6 = 3.7$ ns

EQ 1-16

Routed Clock

External Setup $= t_{INY} + t_{IRD1} + t_{SUD} - t_{RCKH}$

$= 1.5 + 0.3 + 0.5 - 1.5 = 0.8$ ns

EQ 1-17

Clock-to-Out (Pin-to-Pin)

$= t_{RCKH} + t_{RCO} + t_{RD1} + t_{DHL}$

$= 1.52+ 0.8 + 0.3 + 1.6 = 4.2$ ns

EQ 1-18

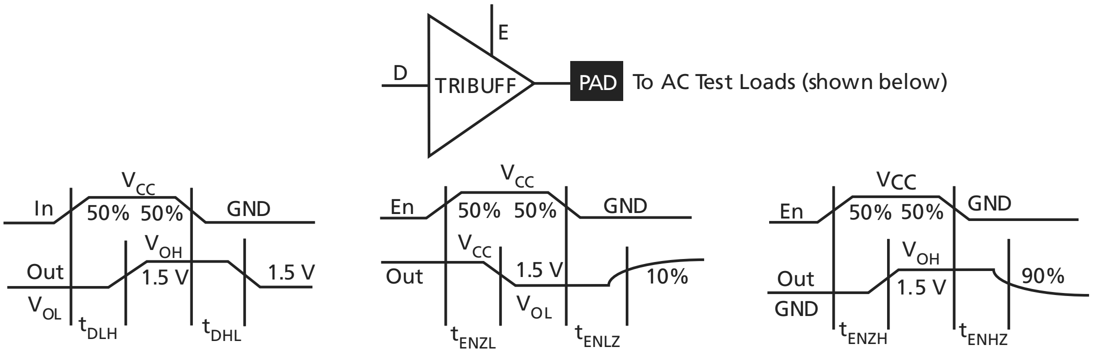


Figure 1-13 • **Output Buffer Delays**

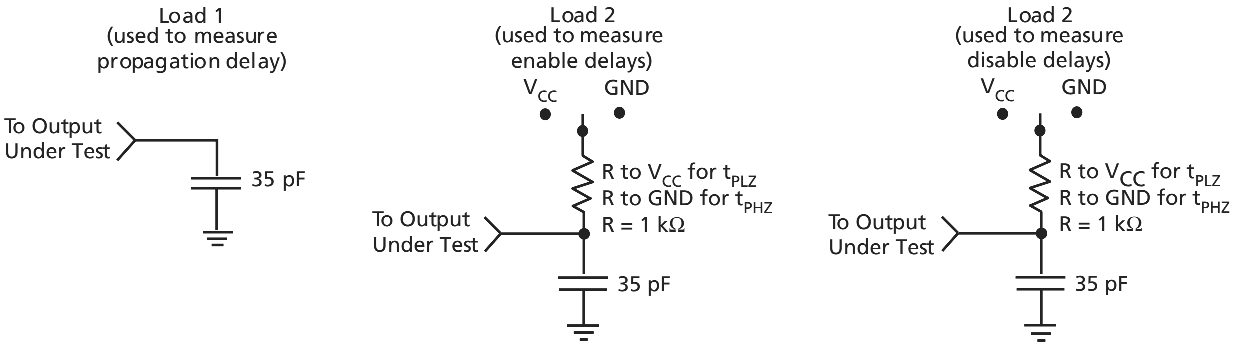


Figure 1-14 • **AC Test Loads**

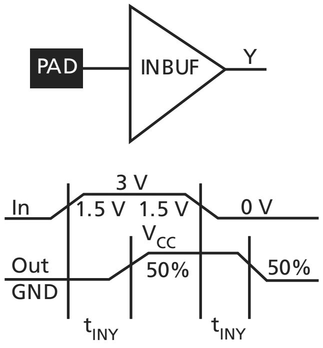


Figure 1-15 • **Input Buffer Delays**

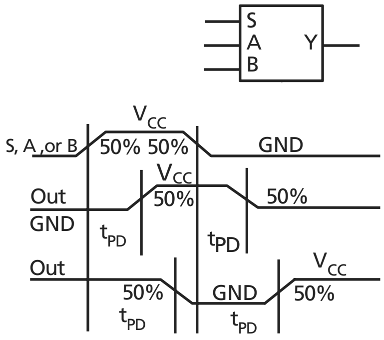


Figure 1-16 • **C-Cell Delays**

Register Cell Timing Characteristics

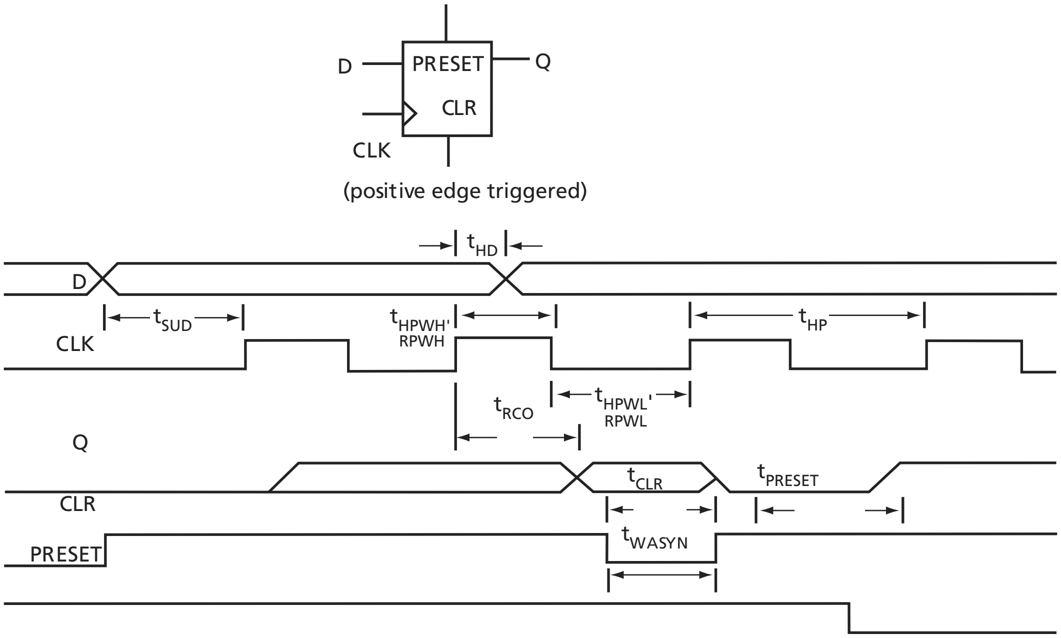


Figure 1-17 • **Flip-Flops**

Timing Characteristics

Timing characteristics for SX devices fall into three categories: family-dependent, device-dependent, and design-dependent. The input and output buffer characteristics are common to all SX family members. Internal routing delays are device-dependent. Design dependency means actual delays are not determined until after placement and routing of the user's design is complete. Delay values may then be determined by using the DirectTime Analyzer utility or performing simulation with post-layout delays.

Critical Nets and Typical Nets

Propagation delays are expressed only for typical nets, which are used for initial design performance evaluation. Critical net delays can then be applied to the most time-critical paths. Critical nets are determined by net property assignment prior to placement and routing. Up to 6% of the nets in a design may be designated as critical, while 90% of the nets in a design are typical.

Long Tracks

Some nets in the design use long tracks. Long tracks are special routing resources that span multiple rows, columns, or modules. Long tracks employ three and sometimes five antifuse connections. This increases capacitance and resistance, resulting in longer net delays for macros connected to long tracks. Typically up to 6 percent of nets in a fully utilized device require long tracks. Long tracks contribute approximately 4 ns to 8.4 ns delay. This additional delay is represented statistically in higher fanout (FO = 24) routing delays in the datasheet specifications section.

Timing Derating

SX devices are manufactured in a CMOS process. Therefore, device performance varies according to temperature, voltage, and process variations. Minimum timing parameters reflect maximum operating voltage, minimum operating temperature, and best-case processing. Maximum timing parameters reflect minimum operating voltage, maximum operating temperature, and worst-case processing.

A54SX08 Timing Characteristics

Table 1-17 • **A54SX08 Timing Characteristics**
(Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

Parameter	Description	'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
C-Cell Propagation Delays[1]										
t_{PD}	Internal Array Module		0.6		0.7		0.8		0.9	ns
Predicted Routing Delays[2]										
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.4		0.4		0.5	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{RD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{RD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{RD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{RD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{RD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns
R-Cell Timing										
t_{RCO}	Sequential Clock-to-Q		0.8		1.1		1.2		1.4	ns
t_{CLR}	Asynchronous Clear-to-Q		0.5		0.6		0.7		0.8	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.9		1.0	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.5		0.5		0.7		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.4		1.6		1.8		2.1		ns
Input Module Propagation Delays										
t_{INYH}	Input Data Pad-to-Y HIGH		1.5		1.7		1.9		2.2	ns
t_{INYL}	Input Data Pad-to-Y LOW		1.5		1.7		1.9		2.2	ns
Input Module Predicted Routing Delays[2]										
t_{IRD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{IRD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{IRD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{IRD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{IRD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{IRD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

Table 1-18 • **A54SX16 Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

		'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Dedicated (Hardwired) Array Clock Network										
t_{HCKH}	Input LOW to HIGH (pad to R-Cell input)		1.2		1.4		1.5		1.8	ns
t_{HCKL}	Input HIGH to LOW (pad to R-Cell input)		1.2		1.4		1.6		1.9	ns
t_{HPWH}	Minimum Pulse Width HIGH	1.4		1.6		1.8		2.1		ns
t_{HPWL}	Minimum Pulse Width LOW	1.4		1.6		1.8		2.1		ns
t_{HCKSW}	Maximum Skew		0.2		0.2		0.3		0.3	ns
t_{HP}	Minimum Period	2.7		3.1		3.6		4.2		ns
f_{HMAX}	Maximum Frequency		350		320		280		240	MHz
Routed Array Clock Networks										
t_{RCKH}	Input LOW to HIGH (light load) (pad to R-Cell input)		1.6		1.8		2.1		2.5	ns
t_{RCKL}	Input HIGH to LOW (light load) (pad to R-Cell input)		1.8		2.0		2.3		2.7	ns
t_{RCKH}	Input LOW to HIGH (50% load) (pad to R-Cell input)		1.8		2.1		2.5		2.8	ns
t_{RCKL}	Input HIGH to LOW (50% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RCKH}	Input LOW to HIGH (100% load) (pad to R-Cell input)		1.8		2.1		2.4		2.8	ns
t_{RCKL}	Input HIGH to LOW (100% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RPWH}	Min. Pulse Width HIGH	2.1		2.4		2.7		3.2		ns
t_{RPWL}	Min. Pulse Width LOW	2.1		2.4		2.7		3.2		ns
t_{RCKSW}	Maximum Skew (light load)		0.5		0.5		0.5		0.7	ns
t_{RCKSW}	Maximum Skew (50% load)		0.5		0.6		0.7		0.8	ns
t_{RCKSW}	Maximum Skew (100% load)		0.5		0.6		0.7		0.8	ns
TTL Output Module Timing[3]										
t_{DLH}	Data-to-Pad LOW to HIGH		1.6		1.9		2.1		2.5	ns
t_{DHL}	Data-to-Pad HIGH to LOW		1.6		1.9		2.1		2.5	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.1		2.4		2.8		3.2	ns
t_{ENZH}	Enable-to-Pad, Z to H		2.3		2.7		3.1		3.6	ns
t_{ENLZ}	Enable-to-Pad, L to Z		1.4		1.7		1.9		2.2	ns
t_{ENHZ}	Enable-to-Pad, H to Z		1.3		1.5		1.7		2.0	ns

Notes:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 35 pF loading, except t_{ENZL} and t_{ENZH}. For t_{ENZL} and t_{ENZH}, the loading is 5 pF.*

A54SX16P Timing Characteristics

Table 1-19 • **A54SX16P Timing Characteristics**
(Worst-Case Commercial Conditions, $V_{CCR} = 4.75$ V, V_{CCA},$V_{CCI} = 3.0$ V, $T_J = 70°C$)

		'–3' Speed		**'–2' Speed**		**'–1' Speed**		**'Std' Speed**		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
C-Cell Propagation Delays[1]										
t_{PD}	Internal Array Module		0.6		0.7		0.8		0.9	ns
Predicted Routing Delays[2]										
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.4		0.4		0.5	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{RD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{RD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{RD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{RD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{RD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns
R-Cell Timing										
t_{RCO}	Sequential Clock-to-Q		0.9		1.1		1.3		1.4	ns
t_{CLR}	Asynchronous Clear-to-Q		0.5		0.6		0.7		0.8	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.9		1.0	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.5		0.5		0.7		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.4		1.6		1.8		2.1		ns
Input Module Propagation Delays										
t_{INYH}	Input Data Pad-to-Y HIGH		1.5		1.7		1.9		2.2	ns
t_{INYL}	Input Data Pad-to-Y LOW		1.5		1.7		1.9		2.2	ns
Predicted Input Routing Delays[2]										
t_{IRD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{IRD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{IRD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{IRD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{IRD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{IRD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns

Note:

1. *For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn}$, $t_{RCO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 10 pF loading.*

Table 1-19 • **A54SX16P Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

		'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Dedicated (Hardwired) Array Clock Network										
t_{HCKH}	Input LOW to HIGH (pad to R-Cell input)		1.2		1.4		1.5		1.8	ns
t_{HCKL}	Input HIGH to LOW (pad to R-Cell input)		1.2		1.4		1.6		1.9	ns
t_{HPWH}	Minimum Pulse Width HIGH	1.4		1.6		1.8		2.1		ns
t_{HPWL}	Minimum Pulse Width LOW	1.4		1.6		1.8		2.1		ns
t_{HCKSW}	Maximum Skew		0.2		0.2		0.3		0.3	ns
t_{HP}	Minimum Period	2.7		3.1		3.6		4.2		ns
f_{HMAX}	Maximum Frequency		350		320		280		240	MHz
Routed Array Clock Networks										
t_{RCKH}	Input LOW to HIGH (light load) (pad to R-Cell input)		1.6		1.8		2.1		2.5	ns
t_{RCKL}	Input HIGH to LOW (Light Load) (pad to R-Cell input)		1.8		2.0		2.3		2.7	ns
t_{RCKH}	Input LOW to HIGH (50% load) (pad to R-Cell input)		1.8		2.1		2.5		2.8	ns
t_{RCKL}	Input HIGH to LOW (50% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RCKH}	Input LOW to HIGH (100% load) (pad to R-Cell input)		1.8		2.1		2.4		2.8	ns
t_{RCKL}	Input HIGH to LOW (100% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RPWH}	Min. Pulse Width HIGH	2.1		2.4		2.7		3.2		ns
t_{RPWL}	Min. Pulse Width LOW	2.1		2.4		2.7		3.2		ns
t_{RCKSW}	Maximum Skew (light load)		0.5		0.5		0.5		0.7	ns
t_{RCKSW}	Maximum Skew (50% load)		0.5		0.6		0.7		0.8	ns
t_{RCKSW}	Maximum Skew (100% load)		0.5		0.6		0.7		0.8	ns
TTL Output Module Timing										
t_{DLH}	Data-to-Pad LOW to HIGH		2.4		2.8		3.1		3.7	ns
t_{DHL}	Data-to-Pad HIGH to LOW		2.3		2.9		3.2		3.8	ns
t_{ENZL}	Enable-to-Pad, Z to L		3.0		3.4		3.9		4.6	ns
t_{ENZH}	Enable-to-Pad, Z to H		3.3		3.8		4.3		5.0	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.3		2.7		3.0		3.5	ns
t_{ENHZ}	Enable-to-Pad, H to Z		2.8		3.2		3.7		4.3	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 10 pF loading.*

A54SX32 Timing Characteristics

Table 1-20 • **A54SX32 Timing Characteristics**
(Worst-Case Commercial Conditions, V_{CCR}= 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

		'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
C-Cell Propagation Delays[1]										
t_{PD}	Internal Array Module		0.6		0.7		0.8		0.9	ns
Predicted Routing Delays[2]										
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.4		0.4		0.5	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{RD2}	FO = 2 Routing Delay		0.7		0.8		0.9		1.0	ns
t_{RD3}	FO = 3 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{RD4}	FO = 4 Routing Delay		1.4		1.6		1.8		2.1	ns
t_{RD8}	FO = 8 Routing Delay		2.7		3.1		3.5		4.1	ns
t_{RD12}	FO = 12 Routing Delay		4.0		4.7		5.3		6.2	ns
R-Cell Timing										
t_{RCO}	Sequential Clock-to-Q		0.8		1.1		1.3		1.4	ns
t_{CLR}	Asynchronous Clear-to-Q		0.5		0.6		0.7		0.8	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.9		1.0	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.5		0.6		0.7		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.4		1.6		1.8		2.1		ns
Input Module Propagation Delays										
t_{INYH}	Input Data Pad-to-Y HIGH		1.5		1.7		1.9		2.2	ns
t_{INYL}	Input Data Pad-to-Y LOW		1.5		1.7		1.9		2.2	ns
Predicted Input Routing Delays[2]										
t_{IRD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{IRD2}	FO = 2 Routing Delay		0.7		0.8		0.9		1.0	ns
t_{IRD3}	FO = 3 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{IRD4}	FO = 4 Routing Delay		1.4		1.6		1.8		2.1	ns
t_{IRD8}	FO = 8 Routing Delay		2.7		3.1		3.5		4.1	ns
t_{IRD12}	FO = 12 Routing Delay		4.0		4.7		5.3		6.2	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 35 pF loading, except t_{ENZL} and t_{ENZH}. For t_{ENZL} and t_{ENZH} the loading is 5 pF.*

Table 1-20 • **A54SX32 Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCR}= 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

		'–3' Speed		**'–2' Speed**		**'–1' Speed**		**'Std' Speed**		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
Dedicated (Hardwired) Array Clock Network										
t_{HCKH}	Input LOW to HIGH (pad to R-Cell input)		1.9		2.1		2.4		2.8	ns
t_{HCKL}	Input HIGH to LOW (pad to R-Cell input)		1.9		2.1		2.4		2.8	ns
t_{HPWH}	Minimum Pulse Width HIGH	1.4		1.6		1.8		2.1		ns
t_{HPWL}	Minimum Pulse Width LOW	1.4		1.6		1.8		2.1		ns
t_{HCKSW}	Maximum Skew		0.3		0.4		0.4		0.5	ns
t_{HP}	Minimum Period	2.7		3.1		3.6		4.2		ns
f_{HMAX}	Maximum Frequency		350		320		280		240	MHz
Routed Array Clock Networks										
t_{RCKH}	Input LOW to HIGH (light load) (pad to R-Cell input)		2.4		2.7		3.0		3.5	ns
t_{RCKL}	Input HIGH to LOW (light load) (pad to R-Cell input)		2.4		2.7		3.1		3.6	ns
t_{RCKH}	Input LOW to HIGH (50% load) (pad to R-Cell input)		2.7		3.0		3.5		4.1	ns
t_{RCKL}	Input HIGH to LOW (50% load) (pad to R-Cell input)		2.7		3.1		3.6		4.2	ns
t_{RCKH}	Input LOW to HIGH (100% load) (pad to R-Cell input)		2.7		3.1		3.5		4.1	ns
t_{RCKL}	Input HIGH to LOW (100% load) (pad to R-Cell input)		2.8		3.2		3.6		4.3	ns
t_{RPWH}	Min. Pulse Width HIGH	2.1		2.4		2.7		3.2		ns
t_{RPWL}	Min. Pulse Width LOW	2.1		2.4		2.7		3.2		ns
t_{RCKSW}	Maximum Skew (light load)		0.85		0.98		1.1		1.3	ns
t_{RCKSW}	Maximum Skew (50% load)		1.23		1.4		1.6		1.9	ns
t_{RCKSW}	Maximum Skew (100% load)		1.30		1.5		1.7		2.0	ns
TTL Output Module Timing[3]										
t_{DLH}	Data-to-Pad LOW to HIGH		1.6		1.9		2.1		2.5	ns
t_{DHL}	Data-to-Pad HIGH to LOW		1.6		1.9		2.1		2.5	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.1		2.4		2.8		3.2	ns
t_{ENZH}	Enable-to-Pad, Z to H		2.3		2.7		3.1		3.6	ns
t_{ENLZ}	Enable-to-Pad, L to Z		1.4		1.7		1.9		2.2	ns
t_{ENHZ}	Enable-to-Pad, H to Z		1.3		1.5		1.7		2.0	ns

Note:

1. *For dual-module macros, use* t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, *or* t_{PD1} + t_{RD1} + t_{SUD}, *whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 35 pF loading, except* t_{ENZL} *and* t_{ENZH}. *For* t_{ENZL} *and* t_{ENZH} *the loading is 5 pF.*

208-Pin PQFP			
Pin Number	A54SX08 Function	A54SX16, A54SX16P Function	A54SX32 Function
73	NC	I/O	I/O
74	I/O	I/O	I/O
75	NC	I/O	I/O
76	PRB, I/O	PRB, I/O	PRB, I/O
77	GND	GND	GND
78	V_{CCA}	V_{CCA}	V_{CCA}
79	GND	GND	GND
80	V_{CCR}	V_{CCR}	V_{CCR}
81	I/O	I/O	I/O
82	HCLK	HCLK	HCLK
83	I/O	I/O	I/O
84	I/O	I/O	I/O
85	NC	I/O	I/O
86	I/O	I/O	I/O
87	I/O	I/O	I/O
88	NC	I/O	I/O
89	I/O	I/O	I/O
90	I/O	I/O	I/O
91	NC	I/O	I/O
92	I/O	I/O	I/O
93	I/O	I/O	I/O
94	NC	I/O	I/O
95	I/O	I/O	I/O
96	I/O	I/O	I/O
97	NC	I/O	I/O
98	V_{CCI}	V_{CCI}	V_{CCI}
99	I/O	I/O	I/O
100	I/O	I/O	I/O
101	I/O	I/O	I/O
102	I/O	I/O	I/O
103	TDO, I/O	TDO, I/O	TDO, I/O
104	I/O	I/O	I/O
105	GND	GND	GND
106	NC	I/O	I/O
107	I/O	I/O	I/O
108	NC	I/O	I/O
109	I/O	I/O	I/O
110	I/O	I/O	I/O
111	I/O	I/O	I/O
112	I/O	I/O	I/O
113	I/O	I/O	I/O
114	V_{CCA}	V_{CCA}	V_{CCA}
115	V_{CCI}	V_{CCI}	V_{CCI}
116	NC	I/O	I/O
117	I/O	I/O	I/O
118	I/O	I/O	I/O
119	NC	I/O	I/O
120	I/O	I/O	I/O
121	I/O	I/O	I/O
122	NC	I/O	I/O
123	I/O	I/O	I/O
124	I/O	I/O	I/O
125	NC	I/O	I/O
126	I/O	I/O	I/O
127	I/O	I/O	I/O
128	I/O	I/O	I/O
129	GND	GND	GND
130	V_{CCA}	V_{CCA}	V_{CCA}
131	GND	GND	GND
132	V_{CCR}	V_{CCR}	V_{CCR}
133	I/O	I/O	I/O
134	I/O	I/O	I/O
135	NC	I/O	I/O
136	I/O	I/O	I/O
137	I/O	I/O	I/O
138	NC	I/O	I/O
139	I/O	I/O	I/O
140	I/O	I/O	I/O
141	NC	I/O	I/O
142	I/O	I/O	I/O
143	NC	I/O	I/O
144	I/O	I/O	I/O

Note: ** Note that Pin 65 in the A54SX32—PQ208 is a no connect (NC).*

208-Pin PQFP			
Pin Number	A54SX08 Function	A54SX16, A54SX16P Function	A54SX32 Function
145	V_{CCA}	V_{CCA}	V_{CCA}
146	GND	GND	GND
147	I/O	I/O	I/O
148	V_{CCI}	V_{CCI}	V_{CCI}
149	I/O	I/O	I/O
150	I/O	I/O	I/O
151	I/O	I/O	I/O
152	I/O	I/O	I/O
153	I/O	I/O	I/O
154	I/O	I/O	I/O
155	NC	I/O	I/O
156	NC	I/O	I/O
157	GND	GND	GND
158	I/O	I/O	I/O
159	I/O	I/O	I/O
160	I/O	I/O	I/O
161	I/O	I/O	I/O
162	I/O	I/O	I/O
163	I/O	I/O	I/O
164	V_{CCI}	V_{CCI}	V_{CCI}
165	I/O	I/O	I/O
166	I/O	I/O	I/O
167	NC	I/O	I/O
168	I/O	I/O	I/O
169	I/O	I/O	I/O
170	NC	I/O	I/O
171	I/O	I/O	I/O
172	I/O	I/O	I/O
173	NC	I/O	I/O
174	I/O	I/O	I/O
175	I/O	I/O	I/O
176	NC	I/O	I/O
177	I/O	I/O	I/O
178	I/O	I/O	I/O
179	I/O	I/O	I/O
180	CLKA	CLKA	CLKA

208-Pin PQFP			
Pin Number	A54SX08 Function	A54SX16, A54SX16P Function	A54SX32 Function
181	CLKB	CLKB	CLKB
182	V_{CCR}	V_{CCR}	V_{CCR}
183	GND	GND	GND
184	V_{CCA}	V_{CCA}	V_{CCA}
185	GND	GND	GND
186	PRA, I/O	PRA, I/O	PRA, I/O
187	I/O	I/O	I/O
188	I/O	I/O	I/O
189	NC	I/O	I/O
190	I/O	I/O	I/O
191	I/O	I/O	I/O
192	NC	I/O	I/O
193	I/O	I/O	I/O
194	I/O	I/O	I/O
195	NC	I/O	I/O
196	I/O	I/O	I/O
197	I/O	I/O	I/O
198	NC	I/O	I/O
199	I/O	I/O	I/O
200	I/O	I/O	I/O
201	V_{CCI}	V_{CCI}	V_{CCI}
202	NC	I/O	I/O
203	NC	I/O	I/O
204	I/O	I/O	I/O
205	NC	I/O	I/O
206	I/O	I/O	I/O
207	I/O	I/O	I/O
208	TCK, I/O	TCK, I/O	TCK, I/O

Note: ** Note that Pin 65 in the A54SX32—PQ208 is a no connect (NC).*

313-Pin PBGA	
Pin Number	A54SX32 Function
H20	I/O
H22	V_{CCI}
H24	I/O
J1	I/O
J3	I/O
J5	I/O
J7	NC
J9	I/O
J11	I/O
J13	CLKA
J15	I/O
J17	I/O
J19	I/O
J21	GND
J23	I/O
J25	I/O
K2	I/O
K4	I/O
K6	I/O
K8	V_{CCI}
K10	I/O
K12	I/O
K14	I/O
K16	I/O
K18	I/O
K20	V_{CCA}
K22	I/O
K24	I/O
L1	I/O
L3	I/O
L5	I/O
L7	I/O
L9	I/O
L11	I/O
L13	GND
L15	I/O
L17	I/O
L19	I/O
L21	I/O
L23	I/O
L25	I/O
M2	I/O
M4	I/O
M6	I/O
M8	I/O
M10	I/O
M12	GND
M14	GND
M16	V_{CCI}
M18	I/O
M20	I/O
M22	I/O
M24	I/O
N1	I/O
N3	V_{CCA}
N5	V_{CCR}
N7	I/O
N9	V_{CCI}
N11	GND
N13	GND
N15	GND
N17	I/O
N19	I/O
N21	I/O
N23	V_{CCR}
N25	V_{CCA}
P2	I/O
P4	I/O
P6	I/O
P8	I/O
P10	I/O
P12	GND
P14	GND
P16	I/O
P18	I/O
P20	NC
P22	I/O
P24	I/O
R1	I/O
R3	I/O
R5	I/O
R7	I/O
R9	I/O
R11	I/O
R13	GND
R15	I/O
R17	I/O
R19	I/O
R21	I/O
R23	I/O
R25	I/O
T2	I/O
T4	I/O
T6	I/O
T8	I/O
T10	I/O
T12	I/O
T14	HCLK
T16	I/O
T18	I/O
T20	I/O
T22	I/O
T24	I/O
U1	I/O
U3	I/O
U5	V_{CCI}
U7	I/O
U9	I/O
U11	I/O
U13	I/O
U15	I/O
U17	I/O
U19	I/O
U21	I/O
U23	I/O
U25	I/O
V2	V_{CCA}
V4	I/O
V6	I/O
V8	I/O
V10	I/O
V12	I/O
V14	I/O
V16	NC
V18	I/O
V20	I/O
V22	V_{CCA}
V24	V_{CCI}
W1	I/O
W3	I/O
W5	I/O
W7	NC
W9	I/O
W11	I/O
W13	V_{CCI}
W15	I/O
W17	I/O
W19	I/O
W21	I/O
W23	I/O
W25	I/O
Y2	I/O
Y4	I/O
Y6	I/O
Y8	I/O
Y10	I/O
Y12	I/O
Y14	I/O
Y16	I/O
Y18	I/O
Y20	NC
Y22	I/O
Y24	NC

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