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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	2880
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	147
Number of Gates	48000
Voltage - Supply	3V ~ 3.6V, 4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	176-LQFP
Supplier Device Package	176-TQFP (24x24)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a54sx32-1tqg176

SX Family FPGAs

General Description

The Actel SX family of FPGAs features a sea-of-modules architecture that delivers device performance and integration levels not currently achieved by any other FPGA architecture. SX devices greatly simplify design time, enable dramatic reductions in design costs and power consumption, and further decrease time to market for performance-intensive applications.

The Actel SX architecture features two types of logic modules, the combinatorial cell (C-cell) and the register cell (R-cell), each optimized for fast and efficient mapping of synthesized logic functions. The routing and interconnect resources are in the metal layers above the logic modules, providing optimal use of silicon. This enables the entire floor of the device to be spanned with an uninterrupted grid of fine-grained, synthesis-friendly logic modules (or "sea-of-modules"), which reduces the distance signals have to travel between logic modules. To minimize signal propagation delay, SX devices employ both local and general routing resources. The high-speed local routing resources (DirectConnect and FastConnect) enable very fast local signal propagation that is optimal for fast counters, state machines, and datapath logic. The general system of segmented routing tracks allows any logic module in the array to be connected to any other logic or I/O module. Within this system, propagation delay is minimized by limiting the number of antifuse interconnect elements to five (90 percent of connections typically use only three antifuses). The unique local and general routing structure featured in SX devices gives fast and predictable performance, allows 100 percent pin-locking with full logic utilization, enables concurrent PCB development, reduces design time, and allows designers to achieve performance goals with minimum effort.

Further complementing SX's flexible routing structure is a hardwired, constantly loaded clock network that has been tuned to provide fast clock propagation with minimal clock skew. Additionally, the high performance of the internal logic has eliminated the need to embed latches or flip-flops in the I/O cells to achieve fast clock-to-out or fast input setup times. SX devices have easy to use I/O cells that do not require HDL instantiation, facilitating design reuse and reducing design and verification time.

SX Family Architecture

The SX family architecture was designed to satisfy next-generation performance and integration requirements for production-volume designs in a broad range of applications.

Programmable Interconnect Element

The SX family provides efficient use of silicon by locating the routing interconnect resources between the Metal 2 (M2) and Metal 3 (M3) layers (Figure 1-1 on page 1-2). This completely eliminates the channels of routing and interconnect resources between logic modules (as implemented on SRAM FPGAs and previous generations of antifuse FPGAs), and enables the entire floor of the device to be spanned with an uninterrupted grid of logic modules.

Interconnection between these logic modules is achieved using The Actel patented metal-to-metal programmable antifuse interconnect elements, which are embedded between the M2 and M3 layers. The antifuses are normally open circuit and, when programmed, form a permanent low-impedance connection.

The extremely small size of these interconnect elements gives the SX family abundant routing resources and provides excellent protection against design pirating. Reverse engineering is virtually impossible because it is extremely difficult to distinguish between programmed and unprogrammed antifuses, and there is no configuration bitstream to intercept.

Additionally, the interconnect elements (i.e., the antifuses and metal tracks) have lower capacitance and lower resistance than any other device of similar capacity, leading to the fastest signal propagation in the industry.

Logic Module Design

The SX family architecture is described as a "sea-of-modules" architecture because the entire floor of the device is covered with a grid of logic modules with virtually no chip area lost to interconnect elements or routing. The Actel SX family provides two types of logic modules, the register cell (R-cell) and the combinatorial cell (C-cell).

Chip Architecture

The SX family chip architecture provides a unique approach to module organization and chip routing that delivers the best register/logic mix for a wide variety of new and emerging applications.

Module Organization

Actel has arranged all C-cell and R-cell logic modules into horizontal banks called *clusters*. There are two types of *clusters*: Type 1 contains two C-cells and one R-cell, while Type 2 contains one C-cell and two R-cells.

To increase design efficiency and device performance, Actel has further organized these modules into *SuperClusters* (Figure 1-4). SuperCluster 1 is a two-wide grouping of Type 1 clusters. SuperCluster 2 is a two-wide group containing one Type 1 cluster and one Type 2 cluster. SX devices feature more SuperCluster 1 modules than SuperCluster 2 modules because designers typically require significantly more combinatorial logic than flip-flops.

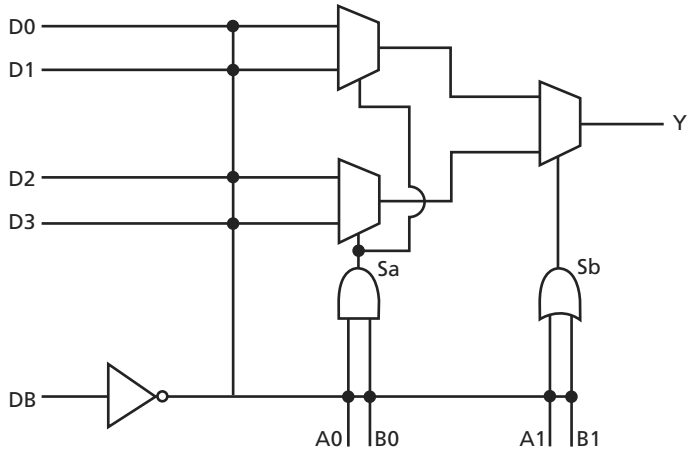


Figure 1-3 • **C-Cell**

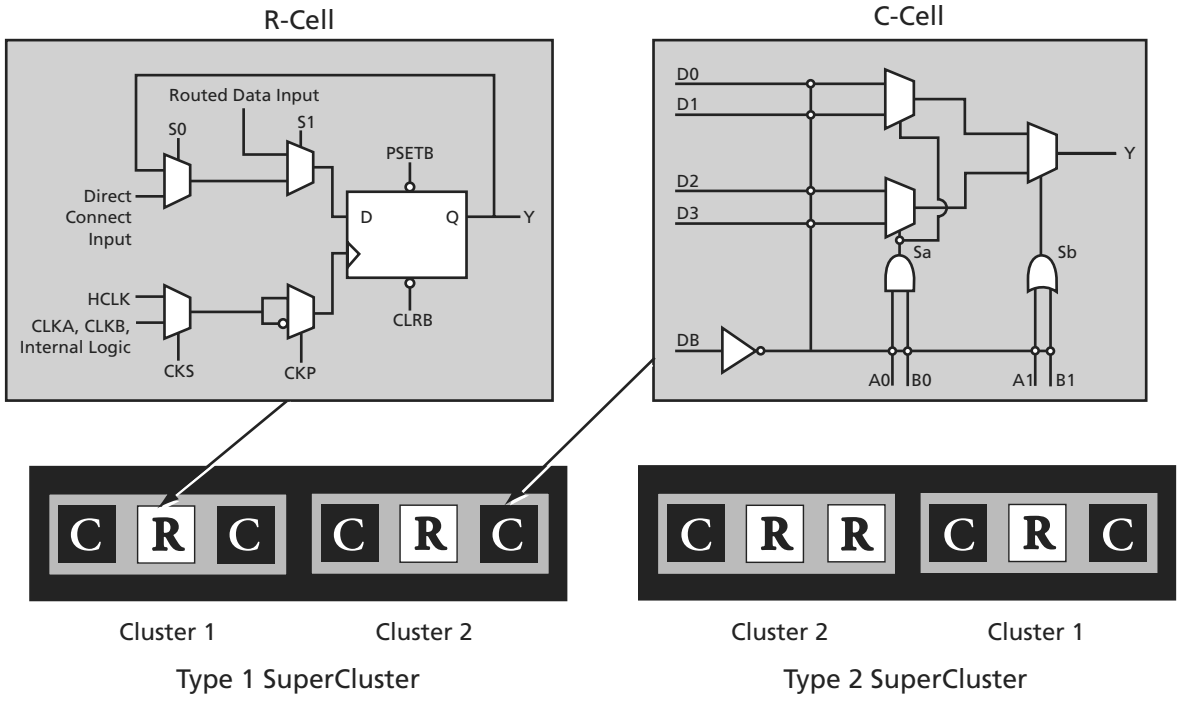


Figure 1-4 • **Cluster Organization**

DirectConnect is a horizontal routing resource that provides connections from a C-cell to its neighboring R-cell in a given SuperCluster. DirectConnect uses a hardwired signal path requiring no programmable interconnection to achieve its fast signal propagation time of less than 0.1 ns.

FastConnect enables horizontal routing between any two logic modules within a given SuperCluster and vertical routing with the SuperCluster immediately below it. Only one programmable connection is used in a FastConnect path, delivering maximum pin-to-pin propagation of 0.4 ns.

In addition to DirectConnect and FastConnect, the architecture makes use of two globally oriented routing resources known as segmented routing and high-drive routing. The Actel segmented routing structure provides a variety of track lengths for extremely fast routing between SuperClusters. The exact combination of track lengths and antifuses within each path is chosen by the 100 percent automatic place-and-route software to minimize signal propagation delays.

The Actel high-drive routing structure provides three clock networks. The first clock, called HCLK, is hardwired from the HCLK buffer to the clock select multiplexer (MUX) in each R-cell. This provides a fast propagation path for the clock signal, enabling the 3.7 ns clock-to-out (pin-to-pin) performance of the SX devices. The hardwired clock is tuned to provide clock skew as low as 0.25 ns. The remaining two clocks (CLKA, CLKB) are global clocks that can be sourced from external pins or from internal logic signals within the SX device.

Other Architectural Features

Technology

The Actel SX family is implemented on a high-voltage twin-well CMOS process using 0.35 µ design rules. The metal-to-metal antifuse is made up of a combination of amorphous silicon and dielectric material with barrier metals and has a programmed ("on" state) resistance of 25 Ω with a capacitance of 1.0 fF for low signal impedance.

Performance

The combination of architectural features described above enables SX devices to operate with internal clock frequencies exceeding 300 MHz, enabling very fast execution of even complex logic functions. Thus, the SX family is an optimal platform upon which to integrate the functionality previously contained in multiple CPLDs. In addition, designs that previously would have required a gate array to meet performance goals can now be integrated into an SX device with dramatic improvements in cost and time to market. Using timing-driven place-and-route tools, designers can achieve highly deterministic device performance. With SX devices, designers do not need to use complicated performance-enhancing design techniques such as the use of redundant logic to reduce fanout on critical nets or the instantiation of macros in HDL code to achieve high performance.

I/O Modules

Each I/O on an SX device can be configured as an input, an output, a tristate output, or a bidirectional pin.

Even without the inclusion of dedicated I/O registers, these I/Os, in combination with array registers, can achieve clock-to-out (pad-to-pad) timing as fast as 3.7 ns. I/O cells that have embedded latches and flip-flops require instantiation in HDL code; this is a design complication not encountered in SX FPGAs. Fast pin-to-pin timing ensures that the device will have little trouble interfacing with any other device in the system, which in turn enables parallel design of system components and reduces overall design time.

Power Requirements

The SX family supports 3.3 V operation and is designed to tolerate 5.0 V inputs. (Table 1-1). Power consumption is extremely low due to the very short distances signals are required to travel to complete a circuit. Power requirements are further reduced because of the small number of low-resistance antifuses in the path. The antifuse architecture does not require active circuitry to hold a charge (as do SRAM or EPROM), making it the lowest power architecture on the market.

Table 1-1 • **Supply Voltages**

Device	V_{CCA}	V_{CCI}	V_{CCR}	Maximum Input Tolerance	Maximum Output Drive
A54SX08 A54SX16 A54SX32	3.3 V	3.3 V	5.0 V	5.0 V	3.3 V
A54SX16-P*	3.3 V	3.3 V	3.3 V	3.3 V	3.3 V
	3.3 V	3.3 V	5.0 V	5.0 V	3.3 V
	3.3 V	5.0 V	5.0 V	5.0 V	5.0 V

Note: **A54SX16-P has three different entries because it is capable of both a 3.3 V and a 5.0 V drive.*

Table 1-4 • **Recommended Operating Conditions**

Parameter	Commercial	Industrial	Military	Units
Temperature Range*	0 to + 70	–40 to + 85	–55 to +125	°C
3.3 V Power Supply Tolerance	±10	±10	±10	%V_{CC}
5.0 V Power Supply Tolerance	±5	±10	±10	%V_{CC}

Note: **Ambient temperature (T_A) is used for commercial and industrial; case temperature (T_C) is used for military.*

Table 1-5 • **Electrical Specifications**

		Commercial		Industrial		
Symbol	**Parameter**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
V_{OH}	(I_{OH} = –20 µA) (CMOS) (I_{OH} = –8 mA) (TTL) (I_{OH} = –6 mA) (TTL)	(V_{CCI} – 0.1) 2.4	V_{CCI} V_{CCI}	(V_{CCI} – 0.1) 2.4	V_{CCI} V_{CCI}	V
V_{OL}	(I_{OL}= 20 µA) (CMOS) (I_{OL} = 12 mA) (TTL) (I_{OL} = 8 mA) (TTL)		0.10 0.50		 0.50	V
V_{IL}			0.8		0.8	V
V_{IH}		2.0		2.0		V
t_R, t_F	Input Transition Time t_R, t_F		50		50	ns
C_{IO}	C_{IO} I/O Capacitance		10		10	pF
I_{CC}	Standby Current, I_{CC}		4.0		4.0	mA
$I_{CC(D)}$	$I_{CC(D)}$ $I_{Dynamic}$ V_{CC} Supply Current	See "Evaluating Power in SX Devices" on page 1-16.				

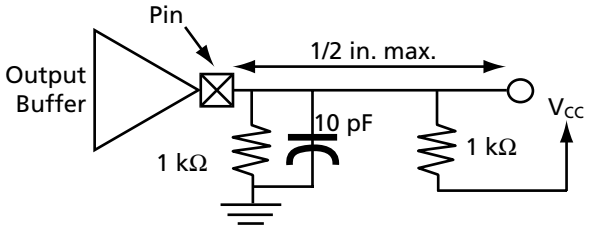
A54SX16P AC Specifications for (PCI Operation)

Table 1-7 • **A54SX16P AC Specifications for (PCI Operation)**

Symbol	Parameter	Condition	Min.	Max.	Units
$I_{OH(AC)}$	Switching Current High	$0 < V_{OUT} \le 1.4$[1]	–44		mA
		$1.4 \le V_{OUT} < 2.4$[1, 2]	$–44 + (V_{OUT} – 1.4)/0.024$		mA
		$3.1 < V_{OUT} < V_{CC}$[1, 3]		EQ 1-1 on page 1-11	
	(Test Point)	$V_{OUT} = 3.1$[3]		–142	mA
$I_{OL(AC)}$	Switching Current High	$V_{OUT} \ge 2.2$[1]	95		mA
		$2.2 > V_{OUT} > 0.55$[1]	$V_{OUT}/0.023$		
		$0.71 > V_{OUT} > 0$[1, 3]		EQ 1-2 on page 1-11	mA
	(Test Point)	$V_{OUT} = 0.71$[3]		206	mA
I_{CL}	Low Clamp Current	$–5 < V_{IN} \le –1$	$–25 + (V_{IN} + 1)/0.015$		mA
$slew_R$	Output Rise Slew Rate	0.4 V to 2.4 V load[4]	1	5	V/ns
$slew_F$	Output Fall Slew Rate	2.4 V to 0.4 V load[4]	1	5	V/ns

Notes:

1. *Refer to the V/I curves in Figure 1-9 on page 1-11. Switching current characteristics for REQ# and GNT# are permitted to be one half of that specified here; i.e., half-size output drivers may be used on these signals. This specification does not apply to CLK and RST#, which are system outputs. "Switching Current High" specifications are not relevant to SERR#, INTA#, INTB#, INTC#, and INTD#, which are open drain outputs.*
2. *Note that this segment of the minimum current curve is drawn from the AC drive point directly to the DC drive point rather than toward the voltage rail (as is done in the pull-down curve). This difference is intended to allow for an optional N-channel pull-up.*
3. *Maximum current requirements must be met as drivers pull beyond the last step voltage. Equations defining these maximums (A and B) are provided with the respective diagrams in Figure 1-9 on page 1-11. The equation defined maxima should be met by design. In order to facilitate component testing, a maximum current test point is defined for each side of the output driver.*
4. *This parameter is to be interpreted as the cumulative edge rate across the specified range, rather than the instantaneous rate at any point within the transition range. The specified load (diagram below) is optional; i.e., the designer may elect to meet this parameter with an unloaded output per revision 2.0 of the PCI Local Bus Specification. However, adherence to both maximum and minimum parameters is now required (the maximum is no longer simply a guideline). Since adherence to the maximum slew rate was not required prior to revision 2.1 of the specification, there may be components in the market for some time that have faster edge rates; therefore, motherboard designers must bear in mind that rise and fall times faster than this specification could occur, and should ensure that signal integrity modeling accounts for this. Rise slew rate does not apply to open drain outputs.*



Power-Up Sequencing

Table 1-10 • **Power-Up Sequencing**

V_{CCA}	V_{CCR}	V_{CCI}	Power-Up Sequence	Comments
A54SX08, A54SX16, A54SX32				
3.3 V	5.0 V	3.3 V	5.0 V First 3.3 V Second	No possible damage to device
			3.3 V First 5.0 V Second	Possible damage to device
A54SX16P				
3.3 V	3.3 V	3.3 V	3.3 V Only	No possible damage to device
3.3 V	5.0 V	3.3 V	5.0 V First 3.3 V Second	No possible damage to device
			3.3 V First 5.0 V Second	Possible damage to device
3.3 V	5.0 V	5.0 V	5.0 V First 3.3 V Second	No possible damage to device
			3.3 V First 5.0 V Second	No possible damage to device

Note: *No inputs should be driven (high or low) before completion of power-up.*

Power-Down Sequencing

Table 1-11 • **Power-Down Sequencing**

V_{CCA}	V_{CCR}	V_{CCI}	Power-Down Sequence	Comments
A54SX08, A54SX16, A54SX32				
3.3 V	5.0 V	3.3 V	5.0 V First 3.3 V Second	Possible damage to device
			3.3 V First 5.0 V Second	No possible damage to device
A54SX16P				
3.3 V	3.3 V	3.3 V	3.3 V Only	No possible damage to device
3.3 V	5.0 V	3.3 V	5.0 V First 3.3 V Second	Possible damage to device
			3.3 V First 5.0 V Second	No possible damage to device
3.3 V	5.0 V	5.0 V	5.0 V First 3.3 V Second	No possible damage to device
			3.3 V First 5.0 V Second	No possible damage to device

Note: *No inputs should be driven (high or low) after the beginning of the power-down sequence.*

Step 1: Define Terms Used in Formula

	V_{CCA}	3.3
Module		
Number of logic modules switching at f_m (Used 50%)	m	264
Average logic modules switching rate f_m (MHz) (Guidelines: f/10)	f_m	20
Module capacitance C_{EQM} (pF)	C_{EQM}	4.0
Input Buffer		
Number of input buffers switching at f_n	n	1
Average input switching rate f_n (MHz) (Guidelines: f/5)	f_n	40
Input buffer capacitance C_{EQI} (pF)	C_{EQI}	3.4
Output Buffer		
Number of output buffers switching at f_p	p	1
Average output buffers switching rate f_p(MHz) (Guidelines: f/10)	f_p	20
Output buffers buffer capacitance C_{EQO} (pF)	C_{EQO}	4.7
Output Load capacitance C_L (pF)	C_L	35
RCLKA		
Number of Clock loads q_1	q_1	528
Capacitance of routed array clock (pF)	C_{EQCR}	1.6
Average clock rate (MHz)	f_{q1}	200
Fixed capacitance (pF)	r_1	138
RCLKB		
Number of Clock loads q_2	q_2	0
Capacitance of routed array clock (pF)	C_{EQCR}	1.6
Average clock rate (MHz)	f_{q2}	0
Fixed capacitance (pF)	r_2	138
HCLK		
Number of Clock loads	s_1	0
Variable capacitance of dedicated array clock (pF)	C_{EQHV}	0.615
Fixed capacitance of dedicated array clock (pF)	C_{EQHF}	96
Average clock rate (MHz)	f_{s1}	0

Step 2: Calculate Dynamic Power Consumption

$V_{CCA} \times V_{CCA}$	10.89
$m \times f_m \times C_{EQM}$	0.02112
$n \times f_n \times C_{EQI}$	0.000136
$p \times f_p \times (C_{EQO}+C_L)$	0.000794
$0.5\ (q_1 \times C_{EQCR} \times f_{q1}) + (r_1 \times f_{q1})$	0.11208
$0.5(q_2 \times C_{EQCR} \times f_{q2}) + (r_2 \times f_{q2})$	0
$0.5\ (s_1 \times C_{EQHV} \times f_{s1}) + (C_{EQHF} \times f_{s1})$	0

P_{AC} = 1.461 W

Step 3: Calculate DC Power Dissipation

DC Power Dissipation

$$P_{DC} = (I_{standby}) \times V_{CCA} + (I_{standby}) \times V_{CCR} + (I_{standby}) \times V_{CCI} + X \times V_{OL} \times I_{OL} + Y(V_{CCI} - V_{OH}) \times V_{OH}$$

EQ 1-12

For a rough estimate of DC Power Dissipation, only use $P_{DC} = (I_{standby}) \times V_{CCA}$. The rest of the formula provides a very small number that can be considered negligible.

$P_{DC} = (I_{standby}) \times V_{CCA}$

P_{DC} = .55 mA × 3.3 V

P_{DC} = 0.001815 W

Step 4: Calculate Total Power Consumption

$P_{Total} = P_{AC} + P_{DC}$

P_{Total} = 1.461 + 0.001815

P_{Total} = 1.4628 W

Step 5: Compare Estimated Power Consumption against Characterized Power Consumption

The estimated total power consumption for this design is 1.46 W. The characterized power consumption for this design at 200 MHz is 1.0164 W.

Table 1-15 • **Package Thermal Characteristics**

Package Type	Pin Count	θ_{jc}	θ_{ja} Still Air	θ_{ja} 300 ft/min.	Units
Plastic Leaded Chip Carrier (PLCC)	84	12	32	22	°C/W
Thin Quad Flat Pack (TQFP)	144	11	32	24	°C/W
Thin Quad Flat Pack (TQFP)	176	11	28	21	°C/W
Very Thin Quad Flatpack (VQFP)	100	10	38	32	°C/W
Plastic Quad Flat Pack (PQFP) without Heat Spreader	208	8	30	23	°C/W
Plastic Quad Flat Pack (PQFP) with Heat Spreader	208	3.8	20	17	°C/W
Plastic Ball Grid Array (PBGA)	272	3	20	14.5	°C/W
Plastic Ball Grid Array (PBGA)	313	3	23	17	°C/W
Plastic Ball Grid Array (PBGA)	329	3	18	13.5	°C/W
Fine Pitch Ball Grid Array (FBGA)	144	3.8	38.8	26.7	°C/W

Note: *SX08 does not have a heat spreader.*

Table 1-16 • **Temperature and Voltage Derating Factors***

	Junction Temperature						
V_{CCA}	–55	–40	0	25	70	85	125
3.0	0.75	0.78	0.87	0.89	1.00	1.04	1.16
3.3	0.70	0.73	0.82	0.83	0.93	0.97	1.08
3.6	0.66	0.69	0.77	0.78	0.87	0.92	1.02

Note: **Normalized to worst-case commercial, T_J = 70°C, V_{CCA} = 3.0 V*

A54SX16 Timing Characteristics

Table 1-18 • **A54SX16 Timing Characteristics (Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)**

Parameter	Description	'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
C-Cell Propagation Delays[1]										
t_{PD}	Internal Array Module		0.6		0.7		0.8		0.9	ns
Predicted Routing Delays[2]										
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.4		0.4		0.5	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{RD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{RD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{RD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{RD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{RD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns
R-Cell Timing										
t_{RCO}	Sequential Clock-to-Q		0.8		1.1		1.2		1.4	ns
t_{CLR}	Asynchronous Clear-to-Q		0.5		0.6		0.7		0.8	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.9		1.0	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.5		0.5		0.7		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.4		1.6		1.8		2.1		ns
Input Module Propagation Delays										
t_{INYH}	Input Data Pad-to-Y HIGH		1.5		1.7		1.9		2.2	ns
t_{INYL}	Input Data Pad-to-Y LOW		1.5		1.7		1.9		2.2	ns
Predicted Input Routing Delays[2]										
t_{IRD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{IRD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{IRD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{IRD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{IRD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{IRD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns

Notes:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 35 pF loading, except t_{ENZL} and t_{ENZH}. For t_{ENZL} and t_{ENZH}, the loading is 5 pF.*

A54SX16P Timing Characteristics

Table 1-19 • **A54SX16P Timing Characteristics (Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)**

Parameter	Description	'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
C-Cell Propagation Delays[1]										
t_{PD}	Internal Array Module		0.6		0.7		0.8		0.9	ns
Predicted Routing Delays[2]										
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.4		0.4		0.5	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{RD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{RD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{RD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{RD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{RD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns
R-Cell Timing										
t_{RCO}	Sequential Clock-to-Q		0.9		1.1		1.3		1.4	ns
t_{CLR}	Asynchronous Clear-to-Q		0.5		0.6		0.7		0.8	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.9		1.0	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.5		0.5		0.7		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.4		1.6		1.8		2.1		ns
Input Module Propagation Delays										
t_{INYH}	Input Data Pad-to-Y HIGH		1.5		1.7		1.9		2.2	ns
t_{INYL}	Input Data Pad-to-Y LOW		1.5		1.7		1.9		2.2	ns
Predicted Input Routing Delays[2]										
t_{IRD1}	FO = 1 Routing Delay		0.3		0.4		0.4		0.5	ns
t_{IRD2}	FO = 2 Routing Delay		0.6		0.7		0.8		0.9	ns
t_{IRD3}	FO = 3 Routing Delay		0.8		0.9		1.0		1.2	ns
t_{IRD4}	FO = 4 Routing Delay		1.0		1.2		1.4		1.6	ns
t_{IRD8}	FO = 8 Routing Delay		1.9		2.2		2.5		2.9	ns
t_{IRD12}	FO = 12 Routing Delay		2.8		3.2		3.7		4.3	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 10 pF loading.*

Table 1-19 • **A54SX16P Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

Parameter	Description	'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
Dedicated (Hardwired) Array Clock Network										
t_{HCKH}	Input LOW to HIGH (pad to R-Cell input)		1.2		1.4		1.5		1.8	ns
t_{HCKL}	Input HIGH to LOW (pad to R-Cell input)		1.2		1.4		1.6		1.9	ns
t_{HPWH}	Minimum Pulse Width HIGH	1.4		1.6		1.8		2.1		ns
t_{HPWL}	Minimum Pulse Width LOW	1.4		1.6		1.8		2.1		ns
t_{HCKSW}	Maximum Skew		0.2		0.2		0.3		0.3	ns
t_{HP}	Minimum Period	2.7		3.1		3.6		4.2		ns
f_{HMAX}	Maximum Frequency		350		320		280		240	MHz
Routed Array Clock Networks										
t_{RCKH}	Input LOW to HIGH (light load) (pad to R-Cell input)		1.6		1.8		2.1		2.5	ns
t_{RCKL}	Input HIGH to LOW (Light Load) (pad to R-Cell input)		1.8		2.0		2.3		2.7	ns
t_{RCKH}	Input LOW to HIGH (50% load) (pad to R-Cell input)		1.8		2.1		2.5		2.8	ns
t_{RCKL}	Input HIGH to LOW (50% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RCKH}	Input LOW to HIGH (100% load) (pad to R-Cell input)		1.8		2.1		2.4		2.8	ns
t_{RCKL}	Input HIGH to LOW (100% load) (pad to R-Cell input)		2.0		2.2		2.5		3.0	ns
t_{RPWH}	Min. Pulse Width HIGH	2.1		2.4		2.7		3.2		ns
t_{RPWL}	Min. Pulse Width LOW	2.1		2.4		2.7		3.2		ns
t_{RCKSW}	Maximum Skew (light load)		0.5		0.5		0.5		0.7	ns
t_{RCKSW}	Maximum Skew (50% load)		0.5		0.6		0.7		0.8	ns
t_{RCKSW}	Maximum Skew (100% load)		0.5		0.6		0.7		0.8	ns
TTL Output Module Timing										
t_{DLH}	Data-to-Pad LOW to HIGH		2.4		2.8		3.1		3.7	ns
t_{DHL}	Data-to-Pad HIGH to LOW		2.3		2.9		3.2		3.8	ns
t_{ENZL}	Enable-to-Pad, Z to L		3.0		3.4		3.9		4.6	ns
t_{ENZH}	Enable-to-Pad, Z to H		3.3		3.8		4.3		5.0	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.3		2.7		3.0		3.5	ns
t_{ENHZ}	Enable-to-Pad, H to Z		2.8		3.2		3.7		4.3	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 10 pF loading.*

Table 1-19 • **A54SX16P Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCR} = 4.75 V, V_{CCA},V_{CCI} = 3.0 V, T_J = 70°C)

Parameter	Description	'–3' Speed		'–2' Speed		'–1' Speed		'Std' Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
TTL/PCI Output Module Timing										
t_{DLH}	Data-to-Pad LOW to HIGH		1.5		1.7		2.0		2.3	ns
t_{DHL}	Data-to-Pad HIGH to LOW		1.9		2.2		2.4		2.9	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.3		2.6		3.0		3.5	ns
t_{ENZH}	Enable-to-Pad, Z to H		1.5		1.7		1.9		2.3	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.7		3.1		3.5		4.1	ns
t_{ENHZ}	Enable-to-Pad, H to Z		2.9		3.3		3.7		4.4	ns
PCI Output Module Timing[3]										
t_{DLH}	Data-to-Pad LOW to HIGH		1.8		2.0		2.3		2.7	ns
t_{DHL}	Data-to-Pad HIGH to LOW		1.7		2.0		2.2		2.6	ns
t_{ENZL}	Enable-to-Pad, Z to L		0.8		1.0		1.1		1.3	ns
t_{ENZH}	Enable-to-Pad, Z to H		1.2		1.2		1.5		1.8	ns
t_{ENLZ}	Enable-to-Pad, L to Z		1.0		1.1		1.3		1.5	ns
t_{ENHZ}	Enable-to-Pad, H to Z		1.1		1.3		1.5		1.7	ns
TTL Output Module Timing										
t_{DLH}	Data-to-Pad LOW to HIGH		2.1		2.5		2.8		3.3	ns
t_{DHL}	Data-to-Pad HIGH to LOW		2.0		2.3		2.6		3.1	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.5		2.9		3.2		3.8	ns
t_{ENZH}	Enable-to-Pad, Z to H		3.0		3.5		3.9		4.6	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.3		2.7		3.1		3.6	ns
t_{ENHZ}	Enable-to-Pad, H to Z		2.9		3.3		3.7		4.4	ns

Note:

1. *For dual-module macros, use t_{PD} + t_{RD1} + t_{PDn}, t_{RCO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}, whichever is appropriate.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*
3. *Delays based on 10 pF loading.*

Pin Description

CLKA/B Clock A and B

These pins are 3.3 V / 5.0 V PCI/TTL clock inputs for clock distribution networks. The clock input is buffered prior to clocking the R-cells. If not used, this pin must be set LOW or HIGH on the board. It must not be left floating. (For A54SX72A, these clocks can be configured as bidirectional.)

GND Ground

LOW supply voltage.

HCLK Dedicated (hardwired) Array Clock

This pin is the 3.3 V / 5.0 V PCI/TTL clock input for sequential modules. This input is directly wired to each R-cell and offers clock speeds independent of the number of R-cells being driven. If not used, this pin must be set LOW or HIGH on the board. It must not be left floating.

I/O Input/Output

The I/O pin functions as an input, output, tristate, or bidirectional buffer. Based on certain configurations, input and output levels are compatible with standard TTL, LVTTL, 3.3 V PCI or 5.0 V PCI specifications. Unused I/O pins are automatically tristated by the Designer Series software.

NC No Connection

This pin is not connected to circuitry within the device.

PRA, I/O Probe A

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when verification has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality.

PRB, I/O Probe B

The Probe B pin is used to output data from any node within the device. This diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when verification has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality.

TCK Test Clock

Test clock input for diagnostic probe and device programming. In flexible mode, TCK becomes active when the TMS pin is set LOW (refer to Table 1-2 on page 1-6). This pin functions as an I/O when the boundary scan state machine reaches the "logic reset" state.

TDI Test Data Input

Serial input for boundary scan testing and diagnostic probe. In flexible mode, TDI is active when the TMS pin is set LOW (refer to Table 1-2 on page 1-6). This pin functions as an I/O when the boundary scan state machine reaches the "logic reset" state.

TDO Test Data Output

Serial output for boundary scan testing. In flexible mode, TDO is active when the TMS pin is set LOW (refer to Table 1-2 on page 1-6). This pin functions as an I/O when the boundary scan state machine reaches the "logic reset" state.

TMS Test Mode Select

The TMS pin controls the use of the IEEE 1149.1 Boundary Scan pins (TCK, TDI, TDO). In flexible mode when the TMS pin is set LOW, the TCK, TDI, and TDO pins are boundary scan pins (refer to Table 1-2 on page 1-6). Once the boundary scan pins are in test mode, they will remain in that mode until the internal boundary scan state machine reaches the "logic reset" state. At this point, the boundary scan pins will be released and will function as regular I/O pins. The "logic reset" state is reached 5 TCK cycles after the TMS pin is set HIGH. In dedicated test mode, TMS functions as specified in the IEEE 1149.1 specifications.

V_{CCI} Supply Voltage

Supply voltage for I/Os. See Table 1-1 on page 1-5.

V_{CCA} Supply Voltage

Supply voltage for Array. See Table 1-1 on page 1-5.

V_{CCR} Supply Voltage

Supply voltage for input tolerance (required for internal biasing). See Table 1-1 on page 1-5.

Package Pin Assignments

84-Pin PLCC

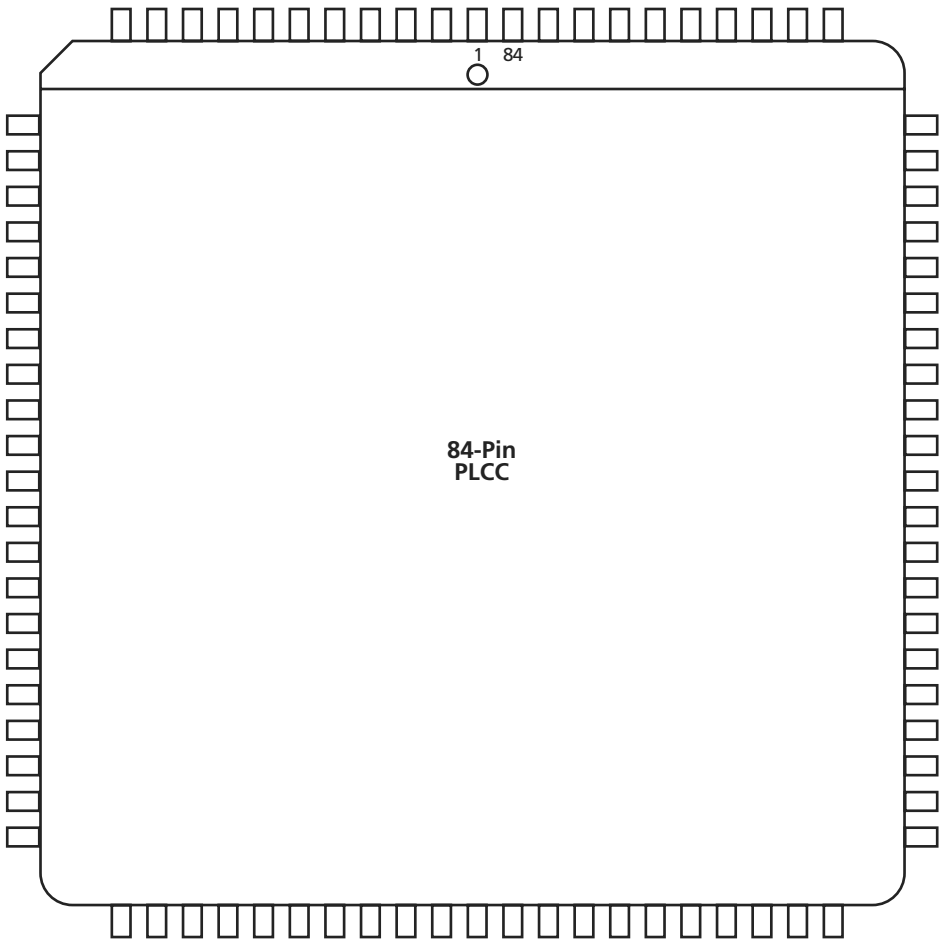


Figure 2-1 • **84-Pin PLCC (Top View)**

Note

For Package Manufacturing and Environmental information, visit the Package Resource center at http://www.actel.com/products/rescenter/package/index.html.

84-Pin PLCC	
Pin Number	**A54SX08 Function**
1	V_{CCR}
2	GND
3	V_{CCA}
4	PRA, I/O
5	I/O
6	I/O
7	V_{CCI}
8	I/O
9	I/O
10	I/O
11	TCK, I/O
12	TDI, I/O
13	I/O
14	I/O
15	I/O
16	TMS
17	I/O
18	I/O
19	I/O
20	I/O
21	I/O
22	I/O
23	I/O
24	I/O
25	I/O
26	I/O
27	GND
28	V_{CCI}
29	I/O
30	I/O
31	I/O
32	I/O
33	I/O
34	I/O
35	I/O

84-Pin PLCC	
Pin Number	**A54SX08 Function**
36	I/O
37	I/O
38	I/O
39	I/O
40	PRB, I/O
41	V_{CCA}
42	GND
43	V_{CCR}
44	I/O
45	HCLK
46	I/O
47	I/O
48	I/O
49	I/O
50	I/O
51	I/O
52	TDO, I/O
53	I/O
54	I/O
55	I/O
56	I/O
57	I/O
58	I/O
59	V_{CCA}
60	V_{CCI}
61	GND
62	I/O
63	I/O
64	I/O
65	I/O
66	I/O
67	I/O
68	V_{CCA}
69	GND
70	I/O

84-Pin PLCC	
Pin Number	**A54SX08 Function**
71	I/O
72	I/O
73	I/O
74	I/O
75	I/O
76	I/O
77	I/O
78	I/O
79	I/O
80	I/O
81	I/O
82	I/O
83	CLKA
84	CLKB

176-Pin TQFP			
Pin Number	A54SX08 Function	A54SX16, A54SX16P Function	A54SX32 Function
69	HCLK	HCLK	HCLK
70	I/O	I/O	I/O
71	I/O	I/O	I/O
72	I/O	I/O	I/O
73	I/O	I/O	I/O
74	I/O	I/O	I/O
75	I/O	I/O	I/O
76	I/O	I/O	I/O
77	I/O	I/O	I/O
78	I/O	I/O	I/O
79	NC	I/O	I/O
80	I/O	I/O	I/O
81	NC	I/O	I/O
82	V_{CCI}	V_{CCI}	V_{CCI}
83	I/O	I/O	I/O
84	I/O	I/O	I/O
85	I/O	I/O	I/O
86	I/O	I/O	I/O
87	TDO, I/O	TDO, I/O	TDO, I/O
88	I/O	I/O	I/O
89	GND	GND	GND
90	NC	I/O	I/O
91	NC	I/O	I/O
92	I/O	I/O	I/O
93	I/O	I/O	I/O
94	I/O	I/O	I/O
95	I/O	I/O	I/O
96	I/O	I/O	I/O
97	I/O	I/O	I/O
98	V_{CCA}	V_{CCA}	V_{CCA}
99	V_{CCI}	V_{CCI}	V_{CCI}
100	I/O	I/O	I/O
101	I/O	I/O	I/O
102	I/O	I/O	I/O

176-Pin TQFP			
Pin Number	A54SX08 Function	A54SX16, A54SX16P Function	A54SX32 Function
103	I/O	I/O	I/O
104	I/O	I/O	I/O
105	I/O	I/O	I/O
106	I/O	I/O	I/O
107	I/O	I/O	I/O
108	GND	GND	GND
109	V_{CCA}	V_{CCA}	V_{CCA}
110	GND	GND	GND
111	I/O	I/O	I/O
112	I/O	I/O	I/O
113	I/O	I/O	I/O
114	I/O	I/O	I/O
115	I/O	I/O	I/O
116	I/O	I/O	I/O
117	I/O	I/O	I/O
118	NC	I/O	I/O
119	I/O	I/O	I/O
120	NC	I/O	I/O
121	NC	I/O	I/O
122	V_{CCA}	V_{CCA}	V_{CCA}
123	GND	GND	GND
124	V_{CCI}	V_{CCI}	V_{CCI}
125	I/O	I/O	I/O
126	I/O	I/O	I/O
127	I/O	I/O	I/O
128	I/O	I/O	I/O
129	I/O	I/O	I/O
130	I/O	I/O	I/O
131	NC	I/O	I/O
132	NC	I/O	I/O
133	GND	GND	GND
134	I/O	I/O	I/O
135	I/O	I/O	I/O
136	I/O	I/O	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
A1	GND
A3	NC
A5	I/O
A7	I/O
A9	I/O
A11	I/O
A13	V_{CCR}
A15	I/O
A17	I/O
A19	I/O
A21	I/O
A23	NC
A25	GND
AA1	I/O
AA3	I/O
AA5	NC
AA7	I/O
AA9	NC
AA11	I/O
AA13	I/O
AA15	I/O
AA17	I/O
AA19	I/O
AA21	I/O
AA23	NC
AA25	I/O
AB2	NC
AB4	NC
AB6	I/O
AB8	I/O
AB10	I/O
AB12	I/O
AB14	I/O
AB16	I/O
AB18	V_{CCI}
AB20	NC
AB22	I/O
AB24	I/O
AC1	I/O
AC3	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
AC5	I/O
AC7	I/O
AC9	I/O
AC11	I/O
AC13	V_{CCR}
AC15	I/O
AC17	I/O
AC19	I/O
AC21	I/O
AC23	I/O
AC25	NC
AD2	GND
AD4	I/O
AD6	V_{CCI}
AD8	I/O
AD10	I/O
AD12	PRB, I/O
AD14	I/O
AD16	I/O
AD18	I/O
AD20	I/O
AD22	NC
AD24	I/O
AE1	NC
AE3	I/O
AE5	I/O
AE7	I/O
AE9	I/O
AE11	I/O
AE13	V_{CCA}
AE15	I/O
AE17	I/O
AE19	I/O
AE21	I/O
AE23	TDO, I/O
AE25	GND
B2	TCK, I/O
B4	I/O
B6	I/O
B8	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
B10	I/O
B12	I/O
B14	I/O
B16	I/O
B18	I/O
B20	I/O
B22	I/O
B24	I/O
C1	TDI, I/O
C3	I/O
C5	NC
C7	I/O
C9	I/O
C11	I/O
C13	V_{CCI}
C15	I/O
C17	I/O
C19	V_{CCI}
C21	I/O
C23	I/O
C25	NC
D2	I/O
D4	NC
D6	I/O
D8	I/O
D10	I/O
D12	I/O
D14	I/O
D16	I/O
D18	I/O
D20	I/O
D22	I/O
D24	NC
E1	I/O
E3	NC
E5	I/O
E7	I/O
E9	I/O
E11	I/O
E13	V_{CCA}

313-Pin PBGA	
Pin Number	**A54SX32 Function**
E15	I/O
E17	I/O
E19	I/O
E21	I/O
E23	I/O
E25	I/O
F2	I/O
F4	I/O
F6	NC
F8	I/O
F10	NC
F12	I/O
F14	I/O
F16	NC
F18	I/O
F20	I/O
F22	I/O
F24	I/O
G1	I/O
G3	TMS
G5	I/O
G7	I/O
G9	V_{CCI}
G11	I/O
G13	CLKB
G15	I/O
G17	I/O
G19	I/O
G21	I/O
G23	I/O
G25	I/O
H2	I/O
H4	I/O
H6	I/O
H8	I/O
H10	I/O
H12	PRA, I/O
H14	I/O
H16	I/O
H18	NC

313-Pin PBGA	
Pin Number	**A54SX32 Function**
H20	I/O
H22	V_{CCI}
H24	I/O
J1	I/O
J3	I/O
J5	I/O
J7	NC
J9	I/O
J11	I/O
J13	CLKA
J15	I/O
J17	I/O
J19	I/O
J21	GND
J23	I/O
J25	I/O
K2	I/O
K4	I/O
K6	I/O
K8	V_{CCI}
K10	I/O
K12	I/O
K14	I/O
K16	I/O
K18	I/O
K20	V_{CCA}
K22	I/O
K24	I/O
L1	I/O
L3	I/O
L5	I/O
L7	I/O
L9	I/O
L11	I/O
L13	GND
L15	I/O
L17	I/O
L19	I/O
L21	I/O
L23	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
L25	I/O
M2	I/O
M4	I/O
M6	I/O
M8	I/O
M10	I/O
M12	GND
M14	GND
M16	V_{CCI}
M18	I/O
M20	I/O
M22	I/O
M24	I/O
N1	I/O
N3	V_{CCA}
N5	V_{CCR}
N7	I/O
N9	V_{CCI}
N11	GND
N13	GND
N15	GND
N17	I/O
N19	I/O
N21	I/O
N23	V_{CCR}
N25	V_{CCA}
P2	I/O
P4	I/O
P6	I/O
P8	I/O
P10	I/O
P12	GND
P14	GND
P16	I/O
P18	I/O
P20	NC
P22	I/O
P24	I/O
R1	I/O
R3	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
R5	I/O
R7	I/O
R9	I/O
R11	I/O
R13	GND
R15	I/O
R17	I/O
R19	I/O
R21	I/O
R23	I/O
R25	I/O
T2	I/O
T4	I/O
T6	I/O
T8	I/O
T10	I/O
T12	I/O
T14	HCLK
T16	I/O
T18	I/O
T20	I/O
T22	I/O
T24	I/O
U1	I/O
U3	I/O
U5	V_{CCI}
U7	I/O
U9	I/O
U11	I/O
U13	I/O
U15	I/O
U17	I/O
U19	I/O
U21	I/O
U23	I/O
U25	I/O
V2	V_{CCA}
V4	I/O
V6	I/O
V8	I/O

313-Pin PBGA	
Pin Number	**A54SX32 Function**
V10	I/O
V12	I/O
V14	I/O
V16	NC
V18	I/O
V20	I/O
V22	V_{CCA}
V24	V_{CCI}
W1	I/O
W3	I/O
W5	I/O
W7	NC
W9	I/O
W11	I/O
W13	V_{CCI}
W15	I/O
W17	I/O
W19	I/O
W21	I/O
W23	I/O
W25	I/O
Y2	I/O
Y4	I/O
Y6	I/O
Y8	I/O
Y10	I/O
Y12	I/O
Y14	I/O
Y16	I/O
Y18	I/O
Y20	NC
Y22	I/O
Y24	NC

329-Pin PBGA	
Pin Number	**A54SX32 Function**
T22	I/O
T23	I/O
U1	I/O
U2	I/O
U3	V_{CCA}
U4	I/O
U20	I/O
U21	V_{CCA}
U22	I/O
U23	I/O
V1	V_{CCI}
V2	I/O
V3	I/O

329-Pin PBGA	
Pin Number	**A54SX32 Function**
V4	I/O
V20	I/O
V21	I/O
V22	I/O
V23	I/O
W1	I/O
W2	I/O
W3	I/O
W4	I/O
W20	I/O
W21	I/O
W22	I/O

329-Pin PBGA	
Pin Number	**A54SX32 Function**
W23	NC
Y1	NC
Y2	I/O
Y3	I/O
Y4	GND
Y5	I/O
Y6	I/O
Y7	I/O
Y8	I/O
Y9	I/O
Y10	I/O
Y11	I/O

329-Pin PBGA	
Pin Number	**A54SX32 Function**
Y12	V_{CCA}
Y13	V_{CCR}
Y14	I/O
Y15	I/O
Y16	I/O
Y17	I/O
Y18	I/O
Y19	I/O
Y20	GND
Y21	I/O
Y22	I/O
Y23	I/O

www.actel.com

Actel Corporation

2061 Stierlin Court
Mountain View, CA
94043-4655 USA
Phone 650.318.4200
Fax 650.318.4600

Actel Europe Ltd.

Dunlop House, Riverside Way
Camberley, Surrey GU15 3YL
United Kingdom
Phone +44 (0) 1276 401 450
Fax +44 (0) 1276 401 490

Actel Japan
www.jp.actel.com

EXOS Ebisu Bldg. 4F
1-24-14 Ebisu Shibuya-ku
Tokyo 150 Japan
Phone +81.03.3445.7671
Fax +81.03.3445.7668

Actel Hong Kong
www.actel.com.cn

Suite 2114, Two Pacific Place
88 Queensway, Admiralty
Hong Kong
Phone +852 2185 6460
Fax +852 2185 6488

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