



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### Understanding [Embedded - Microprocessors](#)

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

### Applications of [Embedded - Microprocessors](#)

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

#### Details

Product Status	Obsolete
Core Processor	PowerPC e500
Number of Cores/Bus Width	2 Core, 32-Bit
Speed	1.5GHz
Co-Processors/DSP	Signal Processing; SPE, Security; SEC
RAM Controllers	DDR2, DDR3
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100/1000Mbps (4)
SATA	-
USB	-
Voltage - I/O	1.5V, 1.8V, 2.5V, 3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	Cryptography, Random Number Generator
Package / Case	1023-BFBGA, FCBGA
Supplier Device Package	1023-FCBGA (33x33)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/ppc8572evtavnc">https://www.e-xfl.com/product-detail/nxp-semiconductors/ppc8572evtavnc</a>

- Ability to launch DMA from single write transaction
- Serial RapidIO interface unit
  - Supports *RapidIO Interconnect Specification, Revision 1.2*
  - Both 1x and 4x LP-serial link interfaces
  - Long- and short-haul electricals with selectable pre-compensation
  - Transmission rates of 1.25, 2.5, and 3.125 Gbaud (data rates of 1.0, 2.0, and 2.5 Gbps) per lane
  - Auto-detection of 1x- and 4x-mode operation during port initialization
  - Link initialization and synchronization
  - Large and small size transport information field support selectable at initialization time
  - 34-bit addressing
  - Up to 256 bytes data payload
  - All transaction flows and priorities
  - Atomic set/clr/inc/dec for read-modify-write operations
  - Generation of IO\_READ\_HOME and FLUSH with data for accessing cache-coherent data at a remote memory system
  - Receiver-controlled flow control
  - Error detection, recovery, and time-out for packets and control symbols as required by the RapidIO specification
  - Register and register bit extensions as described in part VIII (Error Management) of the RapidIO specification
  - Hardware recovery only
  - Register support is not required for software-mediated error recovery.
  - Accept-all mode of operation for fail-over support
  - Support for RapidIO error injection
  - Internal LP-serial and application interface-level loopback modes
  - Memory and PHY BIST for at-speed production test
- RapidIO-compliant message unit
  - 4 Kbytes of payload per message
  - Up to sixteen 256-byte segments per message
  - Two inbound data message structures within the inbox
  - Capable of receiving three letters at any mailbox
  - Two outbound data message structures within the outbox
  - Capable of sending three letters simultaneously
  - Single segment multicast to up to 32 devIDs
  - Chaining and direct modes in the outbox
  - Single inbound doorbell message structure
  - Facility to accept port-write messages

- Three PCI Express controllers
  - PCI Express 1.0a compatible
  - Supports x8, x4, x2, and x1 link widths (see following bullet for specific width configuration options)
  - Auto-detection of number of connected lanes
  - Selectable operation as root complex or endpoint
  - Both 32- and 64-bit addressing
  - 256-byte maximum payload size
  - Virtual channel 0 only
  - Full 64-bit decode with 36-bit wide windows
- Pin multiplexing for the high-speed I/O interfaces supports one of the following configurations:
  - Single x8/x4/x2/x1 PCI Express
  - Dual x4/x2/x1 PCI Express
  - Single x4/x2/x1 PCI Express and dual x2/x1 PCI Express
  - Single 1x/4x Serial RapidIO and single x4/x2/x1 PCI Express
- Power management
  - Supports power saving modes: doze, nap, and sleep
  - Employs dynamic power management, that automatically minimizes power consumption of blocks when they are idle
- System performance monitor
  - Supports eight 32-bit counters that count the occurrence of selected events
  - Ability to count up to 512 counter-specific events
  - Supports 64 reference events that can be counted on any of the eight counters
  - Supports duration and quantity threshold counting
  - Permits counting of burst events with a programmable time between bursts
  - Triggering and chaining capability
  - Ability to generate an interrupt on overflow
- System access port
  - Uses JTAG interface and a TAP controller to access entire system memory map
  - Supports 32-bit accesses to configuration registers
  - Supports cache-line burst accesses to main memory
  - Supports large block (4-Kbyte) uploads and downloads
  - Supports continuous bit streaming of entire block for fast upload and download
- IEEE Std 1149.1™ compatible, JTAG boundary scan
- 1023 FC-PBGA package

Figure 1 shows the MPC8572E block diagram.

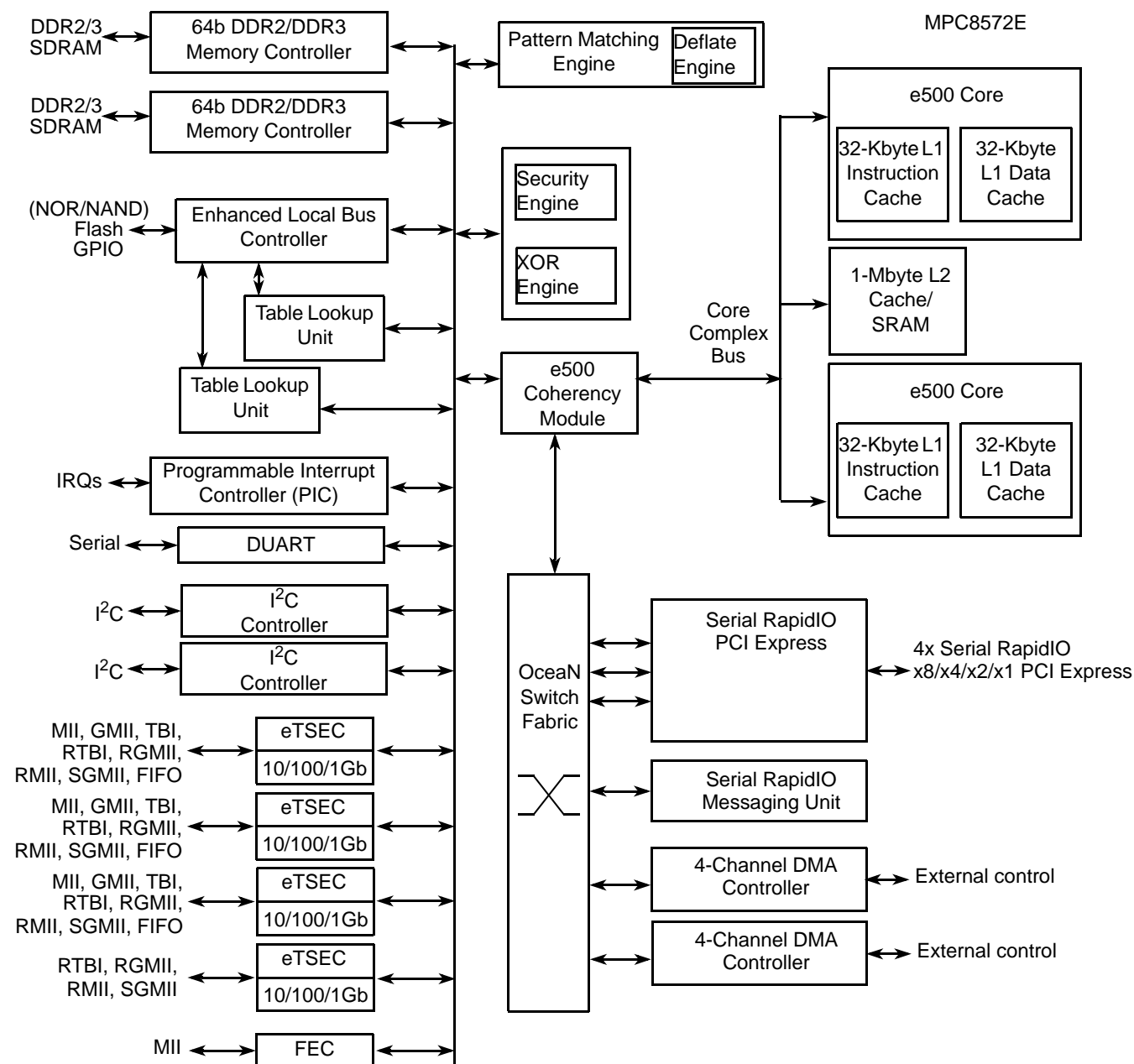


Figure 1. MPC8572E Block Diagram

## 2 Electrical Characteristics

This section provides the AC and DC electrical specifications for the MPC8572E. The MPC8572E is currently targeted to these specifications. Some of these specifications are independent of the I/O cell, but are included for a more complete reference. These are not purely I/O buffer design specifications.

## NOTE

From a system standpoint, if any of the I/O power supplies ramp prior to the VDD core supply, the I/Os associated with that I/O supply may drive a logic one or zero during power-on reset, and extra current may be drawn by the device.

## 3 Power Characteristics

The estimated typical power dissipation for the core complex bus (CCB) versus the core frequency for this family of PowerQUICC III devices with out the L in its part ordering is shown in [Table 4](#).

**Table 4. MPC8572E Power Dissipation <sup>1</sup>**

CCB Frequency	Core Frequency	Typical-65 <sup>2</sup>	Typical-105 <sup>3</sup>	Maximum <sup>4</sup>	Unit
533	1067	12.3	17.8	18.5	W
533	1200	12.3	17.8	18.5	W
533	1333	16.3	22.8	24.5	W
600	1500	17.3	23.9	25.9	W

### Notes:

<sup>1</sup> This reflects the MPC8572E power dissipation excluding the power dissipation from B/G/L/O/T/XV<sub>DD</sub> rails.

<sup>2</sup> Typical-65 is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 65 °C, running Dhrystone.

<sup>3</sup> Typical-105 is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 105 °C, running Dhrystone.

<sup>4</sup> Maximum is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 105 °C, running a smoke test.

The estimated typical power dissipation for the core complex bus (CCB) versus the core frequency for this family of PowerQUICC III devices with the L in its port ordering is shown in [Table 5](#).

**Table 5. MPC8572EL Power Dissipation <sup>1</sup>**

CCB Frequency	Core Frequency	Typical-65 <sup>2</sup>	Typical-105 <sup>3</sup>	Maximum <sup>4</sup>	Unit
533	1067	12	15	15.8	W
533	1200	12	15.5	16.3	W
533	1333	12	15.9	16.9	W
600	1500	13	18.7	20.0	W

### Notes:

<sup>1</sup> This reflects the MPC8572E power dissipation excluding the power dissipation from B/G/L/O/T/XV<sub>DD</sub> rails.

<sup>2</sup> Typical-65 is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 65 °C, running Dhrystone.

<sup>3</sup> Typical-105 is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 105 °C, running Dhrystone.

<sup>4</sup> Maximum is based on V<sub>DD</sub> = 1.1 V, T<sub>j</sub> = 105 °C, running a smoke test.

**Table 25. FIFO Mode Transmit AC Timing Specification (continued)**

At recommended operating conditions with  $V_{DD}/TV_{DD}$  of  $2.5V \pm 5\%$ 

Parameter/Condition	Symbol	Min	Typ	Max	Unit
TX_CLK, GTX_CLK peak-to-peak jitter	$t_{FITJ}$	—	—	250	ps
Rise time TX_CLK (20%–80%)	$t_{FITR}$	—	—	0.75	ns
Fall time TX_CLK (80%–20%)	$t_{FITF}$	—	—	0.75	ns
FIFO data TXD[7:0], TX_ER, TX_EN setup time to GTX_CLK	$t_{FITDV}$	2.0	—	—	ns
GTX_CLK to FIFO data TXD[7:0], TX_ER, TX_EN hold time	$t_{FITDX}$	0.5	—	3.0	ns

**Notes:**

1. The minimum cycle period (or maximum frequency) of the TX\_CLK is dependent on the maximum platform frequency of the speed bins the part belongs to as well as the FIFO mode under operation. Refer to [Section 4.5, “Platform to eTSEC FIFO Restrictions,”](#) for more detailed description.

**Table 26. FIFO Mode Receive AC Timing Specification**

At recommended operating conditions with  $V_{DD}/TV_{DD}$  of  $2.5V \pm 5\%$ 

Parameter/Condition	Symbol	Min	Typ	Max	Unit
RX_CLK clock period <sup>1</sup>	$t_{FIR}$	5.3	8.0	100	ns
RX_CLK duty cycle	$t_{FIRH}/t_{FIR}$	45	50	55	%
RX_CLK peak-to-peak jitter	$t_{FIRJ}$	—	—	250	ps
Rise time RX_CLK (20%–80%)	$t_{FIRR}$	—	—	0.75	ns
Fall time RX_CLK (80%–20%)	$t_{FIRF}$	—	—	0.75	ns
RXD[7:0], RX_DV, RX_ER setup time to RX_CLK	$t_{FIRDV}$	1.5	—	—	ns
RXD[7:0], RX_DV, RX_ER hold time to RX_CLK	$t_{FIRDx}$	0.5	—	—	ns

1. The minimum cycle period (or maximum frequency) of the RX\_CLK is dependent on the maximum platform frequency of the speed bins the part belongs to as well as the FIFO mode under operation. Refer to [Section 4.5, “Platform to eTSEC FIFO Restrictions,”](#) for more detailed description.

Figure 7 and Figure 8 show the FIFO timing diagrams.

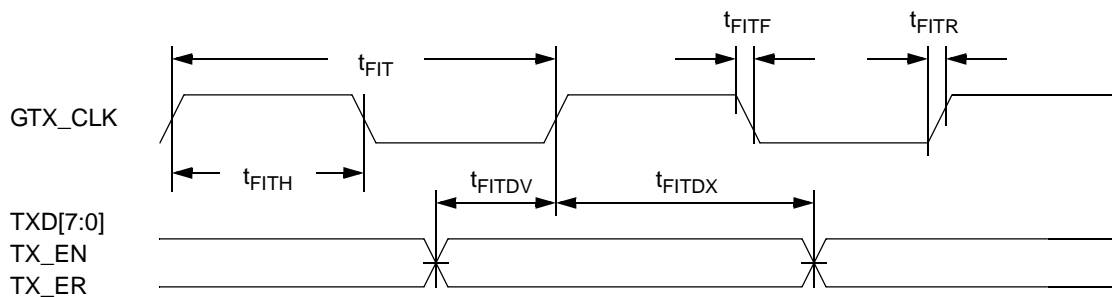

**Figure 7. FIFO Transmit AC Timing Diagram**

Figure 18 shows the RGMII and RTBI AC timing and multiplexing diagrams.

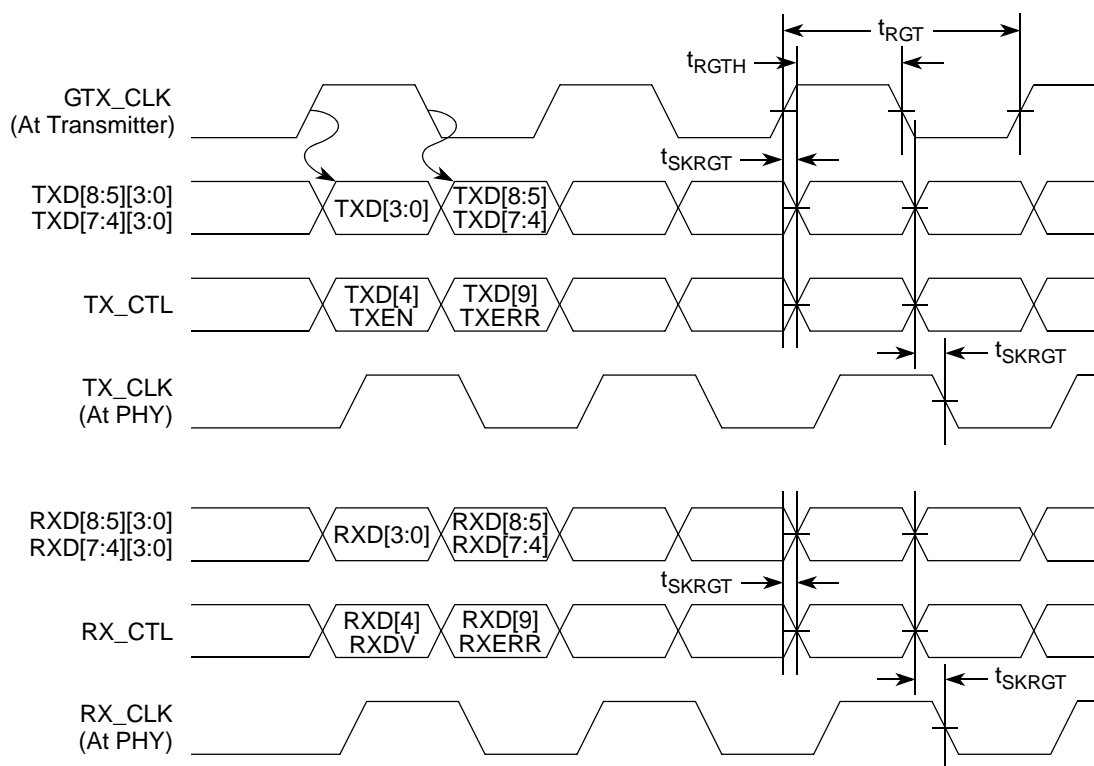


Figure 18. RGMII and RTBI AC Timing and Multiplexing Diagrams

## 8.2.7 RMII AC Timing Specifications

This section describes the RMII transmit and receive AC timing specifications.

### 8.2.7.1 RMII Transmit AC Timing Specifications

Table 35 shows the RMII transmit AC timing specifications.

Table 35. RMII Transmit AC Timing Specifications

At recommended operating conditions with  $V_{DD}/TV_{DD}$  of 2.5/ 3.3 V  $\pm$  5%.

Parameter/Condition	Symbol <sup>1</sup>	Min	Typ	Max	Unit
TSECn_TX_CLK clock period	$t_{RMT}$	15.0	20.0	25.0	ns
TSECn_TX_CLK duty cycle	$t_{RMTH}$	35	50	65	%
TSECn_TX_CLK peak-to-peak jitter	$t_{RMTJ}$	—	—	250	ps
Rise time TSECn_TX_CLK (20%–80%)	$t_{RMTR}$	1.0	—	2.0	ns
Fall time TSECn_TX_CLK (80%–20%)	$t_{RMTF}$	1.0	—	2.0	ns

described in [Section 21.5, “Connection Recommendations,”](#) as long as such termination does not violate the desired POR configuration requirement on these pins, if applicable.

When operating in SGMII mode, the eTSEC EC\_GTX\_CLK125 clock is not required for this port. Instead, SerDes reference clock is required on SD2\_REF\_CLK and SD2\_REF\_CLK pins.

### 8.3.1 DC Requirements for SGMII SD2\_REF\_CLK and SD2\_REF\_CLK

The characteristics and DC requirements of the separate SerDes reference clock are described in [Section 15, “High-Speed Serial Interfaces \(HSSI\).”](#)

### 8.3.2 AC Requirements for SGMII SD2\_REF\_CLK and SD2\_REF\_CLK

[Table 37](#) lists the SGMII SerDes reference clock AC requirements. Note that SD2\_REF\_CLK and SD2\_REF\_CLK are not intended to be used with, and should not be clocked by, a spread spectrum clock source.

**Table 37. SD2\_REF\_CLK and SD2\_REF\_CLK AC Requirements**

Symbol	Parameter Description	Min	Typical	Max	Units	Notes
t <sub>REF</sub>	REFCLK cycle time	—	10 (8)	—	ns	1
t <sub>REFCJ</sub>	REFCLK cycle-to-cycle jitter. Difference in the period of any two adjacent REFCLK cycles	—	—	100	ps	—
t <sub>REFPJ</sub>	Phase jitter. Deviation in edge location with respect to mean edge location	–50	—	50	ps	—

**Note:**

1. 8 ns applies only when 125 MHz SerDes2 reference clock frequency is selected through `cfg_srds_sgmmi_refclk` during POR.



## 10 Local Bus Controller (eLBC)

This section describes the DC and AC electrical specifications for the local bus interface of the MPC8572E.

### 10.1 Local Bus DC Electrical Characteristics

[Table 46](#) provides the DC electrical characteristics for the local bus interface operating at  $BV_{DD} = 3.3 \text{ V}$  DC.

**Table 46. Local Bus DC Electrical Characteristics (3.3 V DC)**

Parameter	Symbol	Min	Max	Unit
Supply voltage 3.3V	$BV_{DD}$	3.13	3.47	V
High-level input voltage	$V_{IH}$	2	$BV_{DD} + 0.3$	V
Low-level input voltage	$V_{IL}$	-0.3	0.8	V
Input current ( $BV_{IN}^1 = 0 \text{ V}$ or $BV_{IN} = BV_{DD}$ )	$I_{IN}$	—	$\pm 5$	$\mu\text{A}$
High-level output voltage ( $BV_{DD} = \text{min}$ , $I_{OH} = -2 \text{ mA}$ )	$V_{OH}$	$BV_{DD} - 0.2$	—	V
Low-level output voltage ( $BV_{DD} = \text{min}$ , $I_{OL} = 2 \text{ mA}$ )	$V_{OL}$	—	0.2	V

**Note:**

- Note that the symbol  $BV_{IN}$ , in this case, represents the  $BV_{IN}$  symbol referenced in [Table 1](#).

[Table 47](#) provides the DC electrical characteristics for the local bus interface operating at  $BV_{DD} = 2.5 \text{ V}$  DC.

**Table 47. Local Bus DC Electrical Characteristics (2.5 V DC)**

Parameter	Symbol	Min	Max	Unit
Supply voltage 2.5V	$BV_{DD}$	2.37	2.63	V
High-level input voltage	$V_{IH}$	1.70	$BV_{DD} + 0.3$	V
Low-level input voltage	$V_{IL}$	-0.3	0.7	V
Input current ( $BV_{IN}^1 = 0 \text{ V}$ or $BV_{IN} = BV_{DD}$ )	$I_{IH}$	—	10	$\mu\text{A}$
	$I_{IL}$		-15	
High-level output voltage ( $BV_{DD} = \text{min}$ , $I_{OH} = -1 \text{ mA}$ )	$V_{OH}$	2.0	$BV_{DD} + 0.3$	V
Low-level output voltage ( $BV_{DD} = \text{min}$ , $I_{OL} = 1 \text{ mA}$ )	$V_{OL}$	GND - 0.3	0.4	V

**Note:**

- The symbol  $BV_{IN}$ , in this case, represents the  $BV_{IN}$  symbol referenced in [Table 1](#).

**Table 50. Local Bus General Timing Parameters ( $BV_{DD} = 2.5 \text{ V DC}$ )—PLL Enabled (continued)**

At recommended operating conditions with  $BV_{DD}$  of  $2.5 \text{ V} \pm 5\%$  (continued)

Parameter	Symbol <sup>1</sup>	Min	Max	Unit	Notes
Local bus clock to output valid (except LAD/LDP and LALE)	$t_{LBKHOV1}$	—	2.4	ns	—
Local bus clock to data valid for LAD/LDP	$t_{LBKHOV2}$	—	2.5	ns	3
Local bus clock to address valid for LAD	$t_{LBKHOV3}$	—	2.4	ns	3
Local bus clock to LALE assertion	$t_{LBKHOV4}$	—	2.4	ns	3
Output hold from local bus clock (except LAD/LDP and LALE)	$t_{LBKHOX1}$	0.8	—	ns	3
Output hold from local bus clock for LAD/LDP	$t_{LBKHOX2}$	0.8	—	ns	3
Local bus clock to output high Impedance (except LAD/LDP and LALE)	$t_{LBKHOZ1}$	—	2.6	ns	5
Local bus clock to output high impedance for LAD/LDP	$t_{LBKHOZ2}$	—	2.6	ns	5

**Note:**

- The symbols used for timing specifications herein follow the pattern of  $t_{(\text{First two letters of functional block})(\text{signal})(\text{state})(\text{reference})(\text{state})}$  for inputs and  $t_{(\text{First two letters of functional block})(\text{reference})(\text{state})(\text{signal})(\text{state})}$  for outputs. For example,  $t_{LBIXKH1}$  symbolizes local bus timing (LB) for the input (I) to go invalid (X) with respect to the time the  $t_{LBK}$  clock reference (K) goes high (H), in this case for clock one(1). Also,  $t_{LBKHOX}$  symbolizes local bus timing (LB) for the  $t_{LBK}$  clock reference (K) to go high (H), with respect to the output (O) going invalid (X) or output hold time.
- All timings are in reference to LSYNC\_IN for PLL enabled and internal local bus clock for PLL bypass mode.
- All signals are measured from  $BV_{DD}/2$  of the rising edge of LSYNC\_IN for PLL enabled or internal local bus clock for PLL bypass mode to  $0.4 \times BV_{DD}$  of the signal in question for 2.5-V signaling levels.
- Input timings are measured at the pin.
- For purposes of active/float timing measurements, the Hi-Z or off state is defined to be when the total current delivered through the component pin is less than or equal to the leakage current specification.
- $t_{LBOTOT}$  is a measurement of the minimum time between the negation of LALE and any change in LAD.  $t_{LBOTOT}$  is programmed with the LBCR[AHD] parameter.
- Maximum possible clock skew between a clock LCLK[m] and a relative clock LCLK[n]. Skew measured between complementary signals at  $BV_{DD}/2$ .
- Guaranteed by design.

Table 51 describes the general timing parameters of the local bus interface at  $BV_{DD} = 1.8 \text{ V DC}$

**Table 51. Local Bus General Timing Parameters ( $BV_{DD} = 1.8 \text{ V DC}$ )—PLL Enabled**

At recommended operating conditions with  $BV_{DD}$  of  $1.8 \text{ V} \pm 5\%$ 

Parameter	Symbol <sup>1</sup>	Min	Max	Unit	Notes
Local bus cycle time	$t_{LBK}$	6.67	12	ns	2
Local bus duty cycle	$t_{LBKH}/t_{LBK}$	43	57	%	—
LCLK[n] skew to LCLK[m] or LSYNC_OUT	$t_{LBKSKEW}$	—	150	ps	7, 8
Input setup to local bus clock (except LGTA/LUPWAIT)	$t_{LBIVKH1}$	2.4	—	ns	3, 4
LGTA/LUPWAIT input setup to local bus clock	$t_{LBIVKH2}$	1.9	—	ns	3, 4
Input hold from local bus clock (except LGTA/LUPWAIT)	$t_{LBIXKH1}$	1.1	—	ns	3, 4

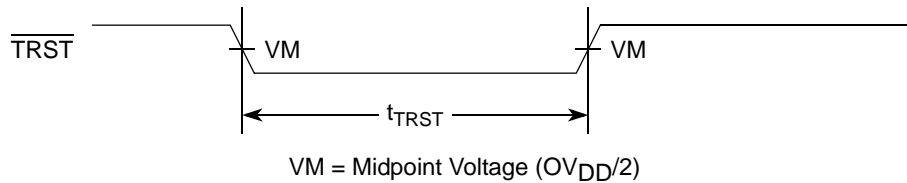


Figure 38. TRST Timing Diagram

Figure 39 provides the boundary-scan timing diagram.

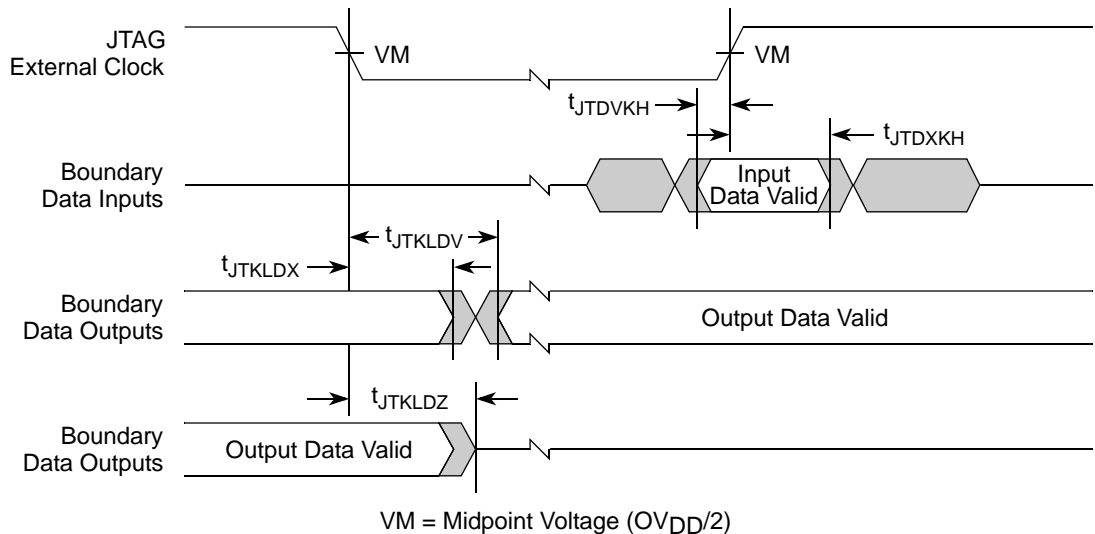


Figure 39. Boundary-Scan Timing Diagram

## 13 I<sup>2</sup>C

This section describes the DC and AC electrical characteristics for the I<sup>2</sup>C interfaces of the MPC8572E.

### 13.1 I<sup>2</sup>C DC Electrical Characteristics

Table 54 provides the DC electrical characteristics for the I<sup>2</sup>C interfaces.

Table 54. I<sup>2</sup>C DC Electrical Characteristics

Parameter	Symbol	Min	Max	Unit	Notes
Input high voltage level	$V_{IH}$	$0.7 \times OV_{DD}$	$OV_{DD} + 0.3$	V	—
Input low voltage level	$V_{IL}$	-0.3	$0.3 \times OV_{DD}$	V	—
Low level output voltage	$V_{OL}$	0	0.4	V	1
Pulse width of spikes which must be suppressed by the input filter	$t_{I2KHKL}$	0	50	ns	2
Input current each I/O pin (input voltage is between $0.1 \times OV_{DD}$ and $0.9 \times OV_{DD}(\max)$ )	$I_I$	-10	10	$\mu A$	3

**Table 54. I<sup>2</sup>C DC Electrical Characteristics (continued)**

Capacitance for each I/O pin	C <sub>I</sub>	—	10	pF	—
------------------------------	----------------	---	----	----	---

**Notes:**

1. Output voltage (open drain or open collector) condition = 3 mA sink current.
2. Refer to the *MPC8572E PowerQUICC™ III Integrated Host Processor Family Reference Manual* for information on the digital filter used.
3. I/O pins will obstruct the SDA and SCL lines if OV<sub>DD</sub> is switched off.

## 13.2 I<sup>2</sup>C AC Electrical Specifications

Table 55 provides the AC timing parameters for the I<sup>2</sup>C interfaces.

**Table 55. I<sup>2</sup>C AC Electrical Specifications**

At recommended operating conditions with OV<sub>DD</sub> of 3.3 V ± 5%. All values refer to V<sub>IH</sub> (min) and V<sub>IL</sub> (max) levels (see Table 2).

Parameter	Symbol <sup>1</sup>	Min	Max	Unit
SCL clock frequency	f <sub>I2C</sub>	0	400	kHz <sup>4</sup>
Low period of the SCL clock	t <sub>I2CL</sub>	1.3	—	μs
High period of the SCL clock	t <sub>I2CH</sub>	0.6	—	μs
Setup time for a repeated START condition	t <sub>I2SVKH</sub>	0.6	—	μs
Hold time (repeated) START condition (after this period, the first clock pulse is generated)	t <sub>I2SXKL</sub>	0.6	—	μs
Data setup time	t <sub>I2DVKH</sub>	100	—	ns
Data input hold time: CBUS compatible masters I <sup>2</sup> C bus devices	t <sub>I2DXKL</sub>	— 0 <sup>2</sup>	— —	μs
Data output delay time	t <sub>I2OVKL</sub>	—	0.9 <sup>3</sup>	μs
Setup time for STOP condition	t <sub>I2PVKH</sub>	0.6	—	μs
Bus free time between a STOP and START condition	t <sub>I2KHDX</sub>	1.3	—	μs
Noise margin at the LOW level for each connected device (including hysteresis)	V <sub>NL</sub>	0.1 × OV <sub>DD</sub>	—	V
Noise margin at the HIGH level for each connected device (including hysteresis)	V <sub>NH</sub>	0.2 × OV <sub>DD</sub>	—	V

Figure 48 shows the SerDes reference clock connection reference circuits for HCSL type clock driver. It assumes that the DC levels of the clock driver chip is compatible with MPC8572E SerDes reference clock input's DC requirement.

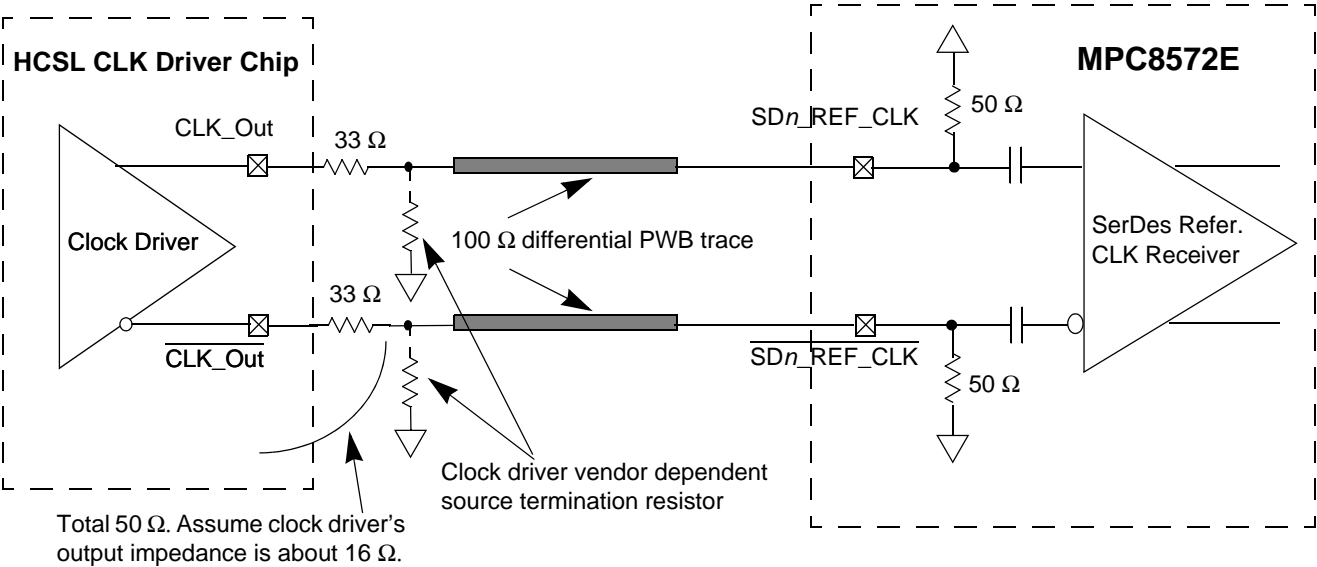
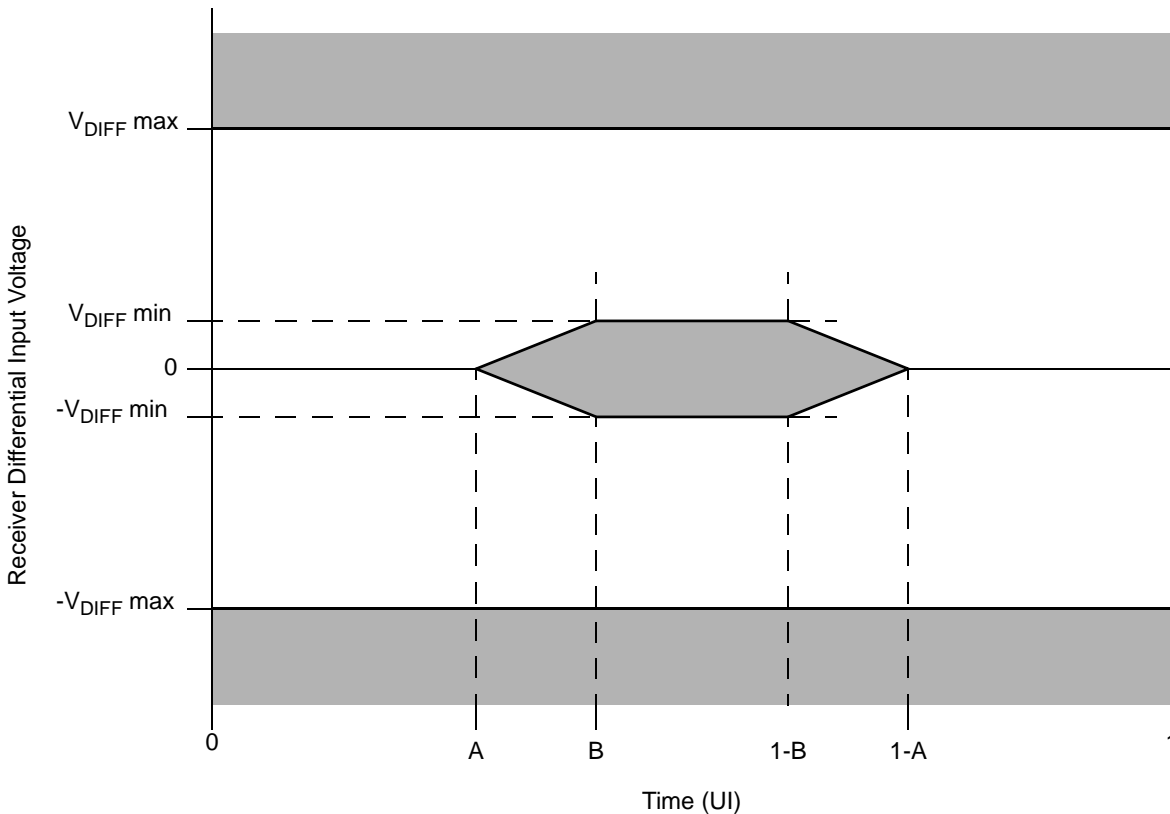


Figure 48. DC-Coupled Differential Connection with HCSL Clock Driver (Reference Only)



**Figure 60. Receiver Input Compliance Mask**

**Table 75. Receiver Input Compliance Mask Parameters Exclusive of Sinusoidal Jitter**

Receiver Type	$V_{DIFFmin}$ (mV)	$V_{DIFFmax}$ (mV)	A (UI)	B (UI)
1.25 GBaud	100	800	0.275	0.400
2.5 GBaud	100	800	0.275	0.400
3.125 GBaud	100	800	0.275	0.400

## 17.8 Measurement and Test Requirements

Because the LP-Serial electrical specification are guided by the XAUI electrical interface specified in Clause 47 of IEEE 802.3ae-2002, the measurement and test requirements defined here are similarly guided by Clause 47. Additionally, the CJPAT test pattern defined in Annex 48A of IEEE 802.3ae-2002 is specified as the test pattern for use in eye pattern and jitter measurements. Annex 48B of IEEE 802.3ae-2002 is recommended as a reference for additional information on jitter test methods.

### 17.8.1 Eye Template Measurements

For the purpose of eye template measurements, the effects of a single-pole high pass filter with a 3 dB point at (Baud Frequency)/1667 is applied to the jitter. The data pattern for template measurements is the Continuous Jitter Test Pattern (CJPAT) defined in Annex 48A of IEEE 802.3ae. All lanes of the LP-Serial

# 18.1 Package Parameters for the MPC8572E FC-PBGA

The package parameters are as provided in the following list. The package type is 33 mm × 33 mm, 1023 flip chip plastic ball grid array (FC-PBGA).

Package outline	33 mm × 33 mm
Interconnects	1023
Ball Pitch	1 mm
Ball Diameter (Typical)	0.6 mm
Solder Balls	63% Sn
	37% Pb
Solder Balls (Lead-Free)	96.5% Sn
	3.5% Ag

5. Datum A, the seating plane, is determined by the spherical crowns of the solder balls.
6. Parallelism measurement shall exclude any effect of mark on top surface of package.

## 18.3 Pinout Listings

Table 76 provides the pin-out listing for the MPC8572E 1023 FC-PBGA package.

**Table 76. MPC8572E Pinout Listing**

Signal	Signal Name	Package Pin Number	Pin Type	Power Supply	Notes
<b>DDR SDRAM Memory Interface 1</b>					
D1_MDQ[0:63]	Data	D15, A14, B12, D12, A15, B15, B13, C13, C11, D11, D9, A8, A12, A11, A9, B9, F11, G12, K11, K12, E10, E9, J11, J10, G8, H10, L10, M11, F10, G9, K9, K8, AC6, AC7, AG8, AH9, AB6, AB8, AE9, AF9, AL8, AM8, AM10, AK11, AH8, AK8, AJ10, AK10, AL12, AJ12, AL14, AK14, AL11, AM11, AK13, AM14, AM15, AJ16, AL18, AM18, AJ15, AL15, AK17, AM17	I/O	GV <sub>DD</sub>	—
D1_MECC[0:7]	Error Correcting Code	M10, M7, R8, T11, L12, L11, P9, R10	I/O	GV <sub>DD</sub>	—
D1_MAPAR_ERR	Address Parity Error	P6	I	GV <sub>DD</sub>	—
D1_MAPAR_OUT	Address Parity Out	W6	O	GV <sub>DD</sub>	—
D1_MDM[0:8]	Data Mask	C14, A10, G11, H9, AD7, AJ9, AM12, AK16, N11	O	GV <sub>DD</sub>	—
D1_MDQS[0:8]	Data Strobe	A13, C10, H12, J7, AE8, AM9, AM13, AL17, N9	I/O	GV <sub>DD</sub>	—
D1_MDQS[0:8]	Data Strobe	D14, B10, H13, J8, AD8, AL9, AJ13, AM16, P10	I/O	GV <sub>DD</sub>	—
D1_MA[0:15]	Address	Y7, W8, U6, W9, U7, V8, Y11, V10, T6, V11, AA10, U9, U10, AD11, T8, P7	O	GV <sub>DD</sub>	—
D1_MBA[0:2]	Bank Select	AA7, AA8, R7	O	GV <sub>DD</sub>	—
D1_MWE	Write Enable	AC12	O	GV <sub>DD</sub>	—



Table 76. MPC8572E Pinout Listing (continued)

Signal	Signal Name	Package Pin Number	Pin Type	Power Supply	Notes
$\overline{D1\_MCAS}$	Column Address Strobe	AC9	O	GV <sub>DD</sub>	—
$\overline{D1\_MRAS}$	Row Address Strobe	AB12	O	GV <sub>DD</sub>	—
D1_MCKE[0:3]	Clock Enable	M8, L9, T9, N8	O	GV <sub>DD</sub>	11
$\overline{D1\_MCS}$ [0:3]	Chip Select	AB9, AF10, AB11, AE11	O	GV <sub>DD</sub>	—
D1_MCK[0:5]	Clock	V7, E13, AH11, Y9, F14, AG10	O	GV <sub>DD</sub>	—
$\overline{D1\_MCK}$ [0:5]	Clock Complements	Y10, E12, AH12, AA11, F13, AG11	O	GV <sub>DD</sub>	—
D1_MODT[0:3]	On Die Termination	AD10, AF12, AC10, AE12	O	GV <sub>DD</sub>	—
D1_MDIC[0:1]	Driver Impedance Calibration	E15, G14	I/O	GV <sub>DD</sub>	25
<b>DDR SDRAM Memory Interface 2</b>					
D2_MDQ[0:63]	Data	A6, B7, C5, D5, A7, C8, D8, D6, C4, A3, D3, D2, B4, A4, B1, C1, E3, E1, G2, G6, D1, E4, G5, G3, J4, J2, P4, R5, H3, H1, N5, N3, Y6, Y4, AC3, AD2, V5, W5, AB2, AB3, AD5, AE3, AF6, AG7, AC4, AD4, AF4, AF7, AH5, AJ1, AL2, AM3, AH3, AH6, AM1, AL3, AK5, AL5, AJ7, AK7, AK4, AM4, AL6, AM7	I/O	GV <sub>DD</sub>	—
D2_MECC[0:7]	Error Correcting Code	J5, H7, L7, N6, H4, H6, M4, M5	I/O	GV <sub>DD</sub>	—
$\overline{D2\_MAPAR\_ERR}$	Address Parity Error	N1	I	GV <sub>DD</sub>	—
D2_MAPAR_OUT	Address Parity Out	W2	O	GV <sub>DD</sub>	—
D2_MDM[0:8]	Data Mask	A5, B3, F4, J1, AA4, AE5, AK1, AM5, K5	O	GV <sub>DD</sub>	—
D2_MDQS[0:8]	Data Strobe	B6, C2, F5, L4, AB5, AF3, AL1, AM6, L6	I/O	GV <sub>DD</sub>	—
$\overline{D2\_MDQS}$ [0:8]	Data Strobe	C7, A2, F2, K3, AA5, AE6, AK2, AJ6, K6	I/O	GV <sub>DD</sub>	—
D2_MA[0:15]	Address	W1, U4, U3, T1, T2, T3, R1, R2, T5, R4, Y3, P1, N2, AF1, M2, M1	O	GV <sub>DD</sub>	—

Table 76. MPC8572E Pinout Listing (continued)

Signal	Signal Name	Package Pin Number	Pin Type	Power Supply	Notes
$\overline{\text{SD2\_RX}}[3:0]$	Receive Data (negative)	AK31, AJ29, AF29, AE31	I	XV <sub>DD_SR</sub> DS2	—
SD2_TX[3]	SGMII Tx Data eTSEC4	AH26	O	XV <sub>DD_SR</sub> DS2	—
SD2_TX[2]	SGMII Tx Data eTSEC3	AG24	O	XV <sub>DD_SR</sub> DS2	—
SD2_TX[1]	SGMII Tx Data eTSEC2	AE24	O	XV <sub>DD_SR</sub> DS2	—
SD2_TX[0]	SGMII Tx Data eTSEC1	AD26	O	XV <sub>DD_SR</sub> DS2	—
$\overline{\text{SD2\_TX}}[3:0]$	Transmit Data (negative)	AH27, AG25, AE25, AD27	O	XV <sub>DD_SR</sub> DS2	—
SD2_PLL_TPD	PLL Test Point Digital	AH32	O	XV <sub>DD_SR</sub> DS2	17
SD2_REF_CLK	PLL Reference Clock	AG32	I	XV <sub>DD_SR</sub> DS2	—
$\overline{\text{SD2\_REF\_CLK}}$	PLL Reference Clock Complement	AG31	I	XV <sub>DD_SR</sub> DS2	—
Reserved	—	AF26, AF27	—	—	28
<b>General-Purpose Input/Output</b>					
GPINOUT[0:7]	General Purpose Input / Output	B27, A28, B31, A32, B30, A31, B28, B29	I/O	BV <sub>DD</sub>	—
<b>System Control</b>					
$\overline{\text{HRESET}}$	Hard Reset	AC31	I	OV <sub>DD</sub>	—
$\overline{\text{HRESET\_REQ}}$	Hard Reset Request	L23	O	OV <sub>DD</sub>	21
$\overline{\text{SRESET}}$	Soft Reset	P24	I	OV <sub>DD</sub>	—
$\overline{\text{CKSTP\_IN0}}$	Checkstop In Processor 0	N26	I	OV <sub>DD</sub>	—
$\overline{\text{CKSTP\_IN1}}$	Checkstop In Processor 1	N25	I	OV <sub>DD</sub>	—
$\overline{\text{CKSTP\_OUT0}}$	Checkstop Out Processor 0	U29	O	OV <sub>DD</sub>	2, 4
$\overline{\text{CKSTP\_OUT1}}$	Checkstop Out Processor 1	T25	O	OV <sub>DD</sub>	2, 4
<b>Debug</b>					
TRIG_IN	Trigger In	P26	I	OV <sub>DD</sub>	—
$\overline{\text{TRIG\_OUT/READY\_P0/QUIESCE}}$	Trigger Out / Ready Processor 0/ Quiesce	P25	O	OV <sub>DD</sub>	21
READY_P1	Ready Processor 1	N28	O	OV <sub>DD</sub>	5, 9

Table 81 describes the clock ratio between e500 Core1 and the e500 core complex bus (CCB). This ratio is determined by the binary value of  $\overline{\text{LWE}}[0]/\text{LBS}[0]/\text{LFWE}$ ,  $\text{UART\_SOUT}[1]$ , and  $\text{READY\_P1}$  signals at power up, as shown in Table 81.

**Table 81. e500 Core1 to CCB Clock Ratio**

Binary Value of $\overline{\text{LWE}}[0]/\text{LBS}[0]/$ $\text{LFWE}$ , $\text{UART\_SOUT}[1]$ , $\text{READY\_P1}$ Signals	e500 Core1:CCB Clock Ratio	Binary Value of $\overline{\text{LWE}}[0]/\text{LBS}[0]/$ $\text{LFWE}$ , $\text{UART\_SOUT}[1]$ , $\text{READY\_P1}$ Signals	e500 Core1:CCB Clock Ratio
000	Reserved	100	2:1
001	Reserved	101	5:2 (2.5:1)
010	Reserved	110	3:1
011	3:2 (1.5:1)	111	7:2 (3.5:1)

## 19.4 DDR/DDRCLK PLL Ratio

The dual DDR memory controller complexes can be synchronous with, or asynchronous to, the CCB, depending on configuration.

Table 82 describes the clock ratio between the DDR memory controller complexes and the DDR PLL reference clock,  $\text{DDRCLK}$ , which is not the memory bus clock. The DDR memory controller complexes clock frequency is equal to the DDR data rate.

When synchronous mode is selected, the memory buses are clocked at half the CCB clock rate. The default mode of operation is for the DDR data rate for both DDR controllers to be equal to the CCB clock rate in synchronous mode, or the resulting DDR PLL rate in asynchronous mode.

In asynchronous mode, the DDR PLL rate to  $\text{DDRCLK}$  ratios listed in Table 82 reflects the DDR data rate to  $\text{DDRCLK}$  ratio, because the DDR PLL rate in asynchronous mode means the DDR data rate resulting from DDR PLL output.

Note that the DDR PLL reference clock input,  $\text{DDRCLK}$ , is only required in asynchronous mode. MPC8572E does not support running one DDR controller in synchronous mode and the other in asynchronous mode.

**Table 82. DDR Clock Ratio**

Binary Value of $\text{TSEC\_1588\_CLK\_OUT}$ , $\text{TSEC\_1588\_PULSE\_OUT1}$ , $\text{TSEC\_1588\_PULSE\_OUT2}$ Signals	DDR:DDRCLK Ratio
000	3:1
001	4:1
010	6:1
011	8:1
100	10:1

Figure 66. JTAG Interface Connection

## 21.10 Guidelines for High-Speed Interface Termination

### 21.10.1 SerDes 1 Interface Entirely Unused

If the high-speed SerDes 1 interface is not used at all, the unused pin should be terminated as described in this section.

The following pins must be left unconnected (float):

- SD1\_TX[7:0]
- $\overline{\text{SD1\_TX}}$ [7:0]
- Reserved pins C24, C25, H26, H27

The following pins must be connected to XGND\_SRDS1:

- SD1\_RX[7:0]
- $\overline{\text{SD1\_RX}}$ [7:0]
- SD1\_REF\_CLK
- $\overline{\text{SD1\_REF\_CLK}}$

Pins K32 and C29 must be tied to  $\text{XV}_{\text{DD\_SRDS1}}$ . Pins K31 and C30 must be tied to XGND\_SRDS1 through a 300- $\Omega$  resistor.

The POR configuration pin `cfg_srds1_en` on TSEC2\_TXD[5] can be used to power down SerDes 1 block for power saving. Note that both SVDD\_SRDS1 and XVDD\_SRDS1 must remain powered.

### 21.10.2 SerDes 1 Interface Partly Unused

If only part of the high speed SerDes 1 interface pins are used, the remaining high-speed serial I/O pins should be terminated as described in this section.

The following pins must be left unconnected (float) if not used:

- SD1\_TX[7:0]
- $\overline{\text{SD1\_TX}}$ [7:0]
- Reserved pins: C24, C25, H26, H27

The following pins must be connected to XGND\_SRDS1 if not used:

- SD1\_RX[7:0]
- $\overline{\text{SD1\_RX}}$ [7:0]

Pins K32 and C29 must be tied to  $\text{XV}_{\text{DD\_SRDS1}}$ . Pins K31 and C30 must be tied to XGND\_SRDS1 through a 300- $\Omega$  resistor.

**Table 90. Document Revision History (continued)**

Rev. Number	Date	Substantive Change(s)
6	06/2014	<ul style="list-style-type: none"> <li>Updated <a href="#">Table 76</a>, “MPC8572E Pinout Listing,” TDO signal is not driven during HRSET* assertion.</li> <li>In <a href="#">Table 86</a>, “Part Numbering Nomenclature—Rev 2.2.1,” added full Pb-free part code.</li> </ul>
5	01/2011	<ul style="list-style-type: none"> <li>Editorial changes throughout</li> <li>Updated <a href="#">Table 4</a>, “MPC8572E Power Dissipation,” to include low power product.</li> <li>In <a href="#">Section 22.1</a>, “Part Numbers Fully Addressed by this Document,” defined PPC as “Prototype” and changed table headings to say “Package Sphere Type”.</li> <li>Added <a href="#">Table 86</a>, “Part Numbering Nomenclature—Rev 2.2.1.”</li> </ul>
4	06/2010	<ul style="list-style-type: none"> <li>In <a href="#">Section 18.3</a>, “Pinout Listings,” updated <a href="#">Table 76</a> showing GPINOUT power rail as BVDD.</li> <li>Updated <a href="#">Section 14.1</a>, “GPIO DC Electrical Characteristics.”</li> </ul>
3	03/2010	<ul style="list-style-type: none"> <li>In <a href="#">Section 2.1</a>, “Overall DC Electrical Characteristics,” changed GPIO power from OVDD to BVDD.</li> <li>In <a href="#">Section 22.1</a>, “Part Numbers Fully Addressed by this Document,” added <a href="#">Table 87</a> for Rev 2.1 silicon.</li> <li>In <a href="#">Section 22.1</a>, “Part Numbers Fully Addressed by this Document,” updated <a href="#">Table 88</a> for Rev 1.1.1 silicon.</li> </ul>
2	06/2009	<ul style="list-style-type: none"> <li>In <a href="#">Section 3</a>, “Power Characteristics,” updated CCB Max to 533MHz for 1200MHz core device in <a href="#">Table 5</a>, “MPC8572EL Power Dissipation.”</li> <li>In <a href="#">Section 4.4</a>, “DDR Clock Timing,” changed DDRCLK Max to 100MHz. This change was announced in Product Bulletin #13572.</li> <li>Clarified restrictions in <a href="#">Section 4.5</a>, “Platform to eTSEC FIFO Restrictions.”</li> <li>In <a href="#">Table 9</a>, “RESET Initialization Timing Specifications,” added note 2.</li> <li>Added <a href="#">Section 14</a>, “GPIO.”</li> <li>In <a href="#">Section 18.1</a>, “Package Parameters for the MPC8572E FC-PBGA,” updated material composition to 63% Sn, 37% Pb.</li> <li>In <a href="#">Section 18.2</a>, “Mechanical Dimensions of the MPC8572E FC-PBGA,” updated <a href="#">Figure 61</a> to correct the package thickness and top view.</li> <li>In <a href="#">Section 19.1</a>, “Clock Ranges,” updated CCB Max to 533MHz for 1200MHz core device in <a href="#">Table 77</a>, “MPC8572E Processor Core Clocking Specifications.”</li> <li>In <a href="#">Section 19.5.2</a>, “Minimum Platform Frequency Requirements for High-Speed Interfaces,” changed minimum CCB clock frequency for proper PCI Express operation.</li> <li>Added LPBSE to description of LGPL4/LGTA/LUPWAIT/LPBSE/LFRB signal in <a href="#">Table 76</a>, “MPC8572E Pinout Listing.”</li> <li>Corrected supply voltage for GPIO pins in <a href="#">Table 76</a>, “MPC8572E Pinout Listing.”</li> <li>Applied note to SD1_PLL_TPA in <a href="#">Table 76</a>, “MPC8572E Pinout Listing.”</li> <li>Updated note regarding MDIC in <a href="#">Table 76</a>, “MPC8572E Pinout Listing.”</li> <li>Added note for LAD pins in <a href="#">Table 76</a>, “MPC8572E Pinout Listing.”</li> <li>Updated <a href="#">Table 88</a>, “Part Numbering Nomenclature—Rev 1.1.1” with Rev 2.0 and Rev 2.1 part number information. Added note indicating that silicon version 2.0 is available for prototype purposes only and will not be available as a qualified device.</li> </ul>
1	08/2008	<ul style="list-style-type: none"> <li>In <a href="#">Section 22.1</a>, “Part Numbers Fully Addressed by this Document,” added SVR information in, <a href="#">Table 88</a> “Part Numbering Nomenclature—Rev 1.1.1,” for devices without Security Engine feature.</li> </ul>
0	07/2008	<ul style="list-style-type: none"> <li>Initial release.</li> </ul>