Microchip Technology - DSPIC33CH128MP202-E/SS Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit Dual-Core
Speed	180MHz, 200MHz
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	21
Program Memory Size	152KB (152K x 8)
Program Memory Type	FLASH, PRAM
EEPROM Size	-
RAM Size	20K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 23x12b; D/A 4x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ch128mp202-e-ss

TABLE 1: MASTER AND SLAVE CORE FEATURES

Feature	Master Core	Slave Core	Shared
Core Frequency	90 MIPS @ 180 MHz	100 MIPS @ 200 MHz	—
Program Memory	64K-128 Kbytes	24 Kbytes (PRAM)(2)	—
Internal Data RAM	16 Kbytes	4 Kbytes	—
16-Bit Timer	1	1	—
DMA	6	2	—
SCCP (Capture/Compare/Timer)	8	4	—
UART	2	1	—
SPI/I²S	2	1	—
I²C	2	1	—
CAN FD	1	—	—
SENT	2	—	—
CRC	1	—	—
QEI	1	1	—
PTG	1	—	—
CLC	4	4	—
16-Bit High-Speed PWM	4	8	—
ADC 12-Bit	1	3	—
Digital Comparator	4	4	—
12-Bit DAC/Analog CMP Module	1	3	—
Watchdog Timer	1	1	—
Deadman Timer	1	—	—
Input/Output	69	69	69
Simple Breakpoints	5	2	—
PGAs(1)	—	3	3
DAC Output Buffer	—	—	1
Oscillator	1	1	1

Note 1: Slave owns the peripheral/feature, but it is shared with the Master.

2: Dual Partition feature is available on Slave PRAM.

REGISTER 3-18: INTCON1: INTERRUPT CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **NSTDIS:** Interrupt Nesting Disable bit
1 = Interrupt nesting is disabled
0 = Interrupt nesting is enabled

bit 14 **OVAERR:** Accumulator A Overflow Trap Flag bit
1 = Trap was caused by an overflow of Accumulator A
0 = Trap was not caused by an overflow of Accumulator A

bit 13 **OVBERR:** Accumulator B Overflow Trap Flag bit
1 = Trap was caused by an overflow of Accumulator B
0 = Trap was not caused by an overflow of Accumulator B

bit 12 **COVAERR:** Accumulator A Catastrophic Overflow Trap Flag bit
1 = Trap was caused by a catastrophic overflow of Accumulator A
0 = Trap was not caused by a catastrophic overflow of Accumulator A

bit 11 **COVBERR:** Accumulator B Catastrophic Overflow Trap Flag bit
1 = Trap was caused by a catastrophic overflow of Accumulator B
0 = Trap was not caused by a catastrophic overflow of Accumulator B

bit 10 **OVATE:** Accumulator A Overflow Trap Enable bit
1 = Trap overflow of Accumulator A
0 = Trap is disabled

bit 9 **OVBTE:** Accumulator B Overflow Trap Enable bit
1 = Trap overflow of Accumulator B
0 = Trap is disabled

bit 8 **COVTE:** Catastrophic Overflow Trap Enable bit
1 = Trap catastrophic overflow of Accumulator A or B is enabled
0 = Trap is disabled

bit 7 **SFTACERR:** Shift Accumulator Error Status bit
1 = Math error trap was caused by an invalid accumulator shift
0 = Math error trap was not caused by an invalid accumulator shift

REGISTER 3-41: RPINR5: PERIPHERAL PIN SELECT INPUT REGISTER 5

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ICM3R7	ICM3R6	ICM3R5	ICM3R4	ICM3R3	ICM3R2	ICM3R1	ICM3R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TCKI3R7	TCKI3R6	TCKI3R5	TCKI3R4	TCKI3R3	TCKI3R2	TCKI3R1	TCKI3R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **ICM3R<7:0>:** Assign SCCP Capture 3 (ICM3) Input to the Corresponding RPn Pin bits
See Table 3-30.

bit 7-0 **TCKI3R<7:0>:** Assign SCCP Timer3 (TCKI3) Input to the Corresponding RPn Pin bits
See Table 3-30.

REGISTER 3-42: RPINR6: PERIPHERAL PIN SELECT INPUT REGISTER 6

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ICM4R7	ICM4R6	ICM4R5	ICM4R4	ICM4R3	ICM4R2	ICM4R1	ICM4R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TCKI4R7	TCKI4R6	TCKI4R5	TCKI4R4	TCKI4R3	TCKI4R2	TCKI4R1	TCKI4R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **ICM4R<7:0>:** Assign SCCP Capture 4 (ICM4) Input to the Corresponding RPn Pin bits
See Table 3-30.

bit 7-0 **TCKI4R<7:0>:** Assign SCCP Timer4 (TCKI4) Input to the Corresponding RPn Pin bits
See Table 3-30.

REGISTER 3-47: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OCFBR7	OCFBR6	OCFBR5	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OCFAR7	OCFAR6	OCFAR5	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **OCFBR<7:0>:** Assign SCCP Fault B (OCFB) Input to the Corresponding RPn Pin bits
See Table 3-30.

bit 7-0 **OCFAR<7:0>:** Assign SCCP Fault A (OCFA) Input to the Corresponding RPn Pin bits
See Table 3-30.

REGISTER 3-48: RPINR12: PERIPHERAL PIN SELECT INPUT REGISTER 12

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCI9R7	PCI9R6	PCI9R5	PCI9R4	PCI9R3	PCI9R2	PCI9R1	PCI9R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCI8R7	PCI8R6	PCI8R5	PCI8R4	PCI8R3	PCI8R2	PCI8R1	PCI8R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **PCI9R<7:0>:** Assign PWM Input 9 (PCI9) to the Corresponding RPn Pin bits
See Table 3-30.

bit 7-0 **PCI8R<7:0>:** Assign PWM Input 8 (PCI8) to the Corresponding RPn Pin bits
See Table 3-30.

3.7 Deadman Timer (DMT) (Master Only)

Note 1: This data sheet summarizes the features of the dsPIC33CH128MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Deadman Timer (DMT)"** (DS70005155) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

2: The Slave core does not have any DMT module; only the Master has the DMT.

The primary function of the Deadman Timer (DMT) is to interrupt the processor in the event of a software malfunction. The DMT, which works on the system clock, is a free-running instruction fetch timer, which is clocked whenever an instruction fetch occurs, until a count match occurs. Instructions are not fetched when the processor is in Sleep mode.

DMT can be enabled in the Configuration fuse or by software in the DMTCON register by setting the ON bit. The DMT consists of a 32-bit counter with a time-out count match value, as specified by the two 16-bit Configuration Fuse registers: FDMTCNTL and FDMTCNTH.

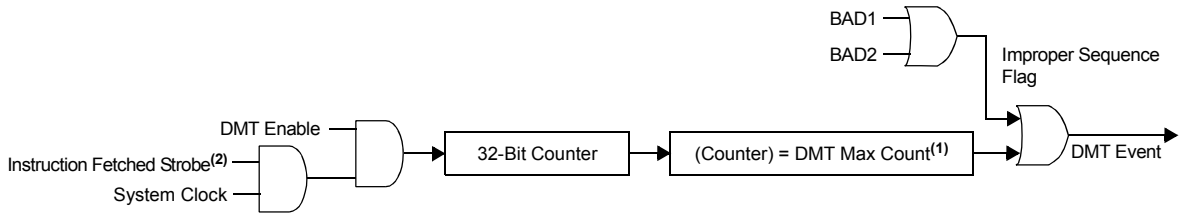
A DMT is typically used in mission-critical and safety-critical applications, where any single failure of the software functionality and sequencing must be detected. Table 3-41 shows an overview of the DMT module.

TABLE 3-41: DMT MODULE OVERVIEW

	No. of DMT Modules	Identical (Modules)
Master Core	1	No
Slave Core	None	NA

Figure 3-22 shows a block diagram of the Deadman Timer module.

FIGURE 3-22: DEADMAN TIMER BLOCK DIAGRAM



Note 1: DMT Max Count is controlled by the initial value of the FDMTCNTL and FDMTCNTH Configuration registers.

2: DMT window interval is controlled by the value of the FDMTIVTL and FDMTIVTH Configuration registers.

REGISTER 3-135: C1FIFOSTAx: CAN FIFO STATUS REGISTER x (x = 1 TO 7)

U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
—	—	—	FIFOCI4(1)	FIFOCI3(1)	FIFOCI2(1)	FIFOCI1(1)	FIFOCI0(1)
bit 15							bit 8

R-0	R-0	R-0	HS/C-0	HS/C-0	R-0	R-0	R-0
TXABT(3)	TXLARB(2)	TXERR(2)	TXATIF	RXOVIF	TFERFFIF	TFHRFHIF	TFNRFNIF
bit 7							bit 0

Legend:	HS = Hardware Settable bit	C = Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **FIFOCI<4:0>:** FIFO Message Index bits(1)

TXEN = 1 (FIFO configured as a transmit buffer):
A read of this register will return an index to the message that the FIFO will next attempt to transmit.

TXEN = 0 (FIFO configured as a receive buffer):
A read of this register will return an index to the message that the FIFO will use to save the next message.

bit 7 **TXABT:** Message Aborted Status bit(3)

1 = Message was aborted
0 = Message completed successfully

bit 6 **TXLARB:** Message Lost Arbitration Status bit(2)

1 = Message lost arbitration while being sent
0 = Message did not lose arbitration while being sent

bit 5 **TXERR:** Error Detected During Transmission bit(2)

1 = A bus error occurred while the message was being sent
0 = A bus error did not occur while the message was being sent

bit 4 **TXATIF:** Transmit Attempts Exhausted Interrupt Pending bit

TXEN = 1 (FIFO configured as a transmit buffer):
1 = Interrupt is pending
0 = Interrupt is not pending

TXEN = 0 (FIFO configured as a receive buffer):
Unused, read as '0'.

bit 3 **RXOVIF:** Receive FIFO Overflow Interrupt Flag bit

TXEN = 1 (FIFO configured as a transmit buffer):
Unused, read as '0'.

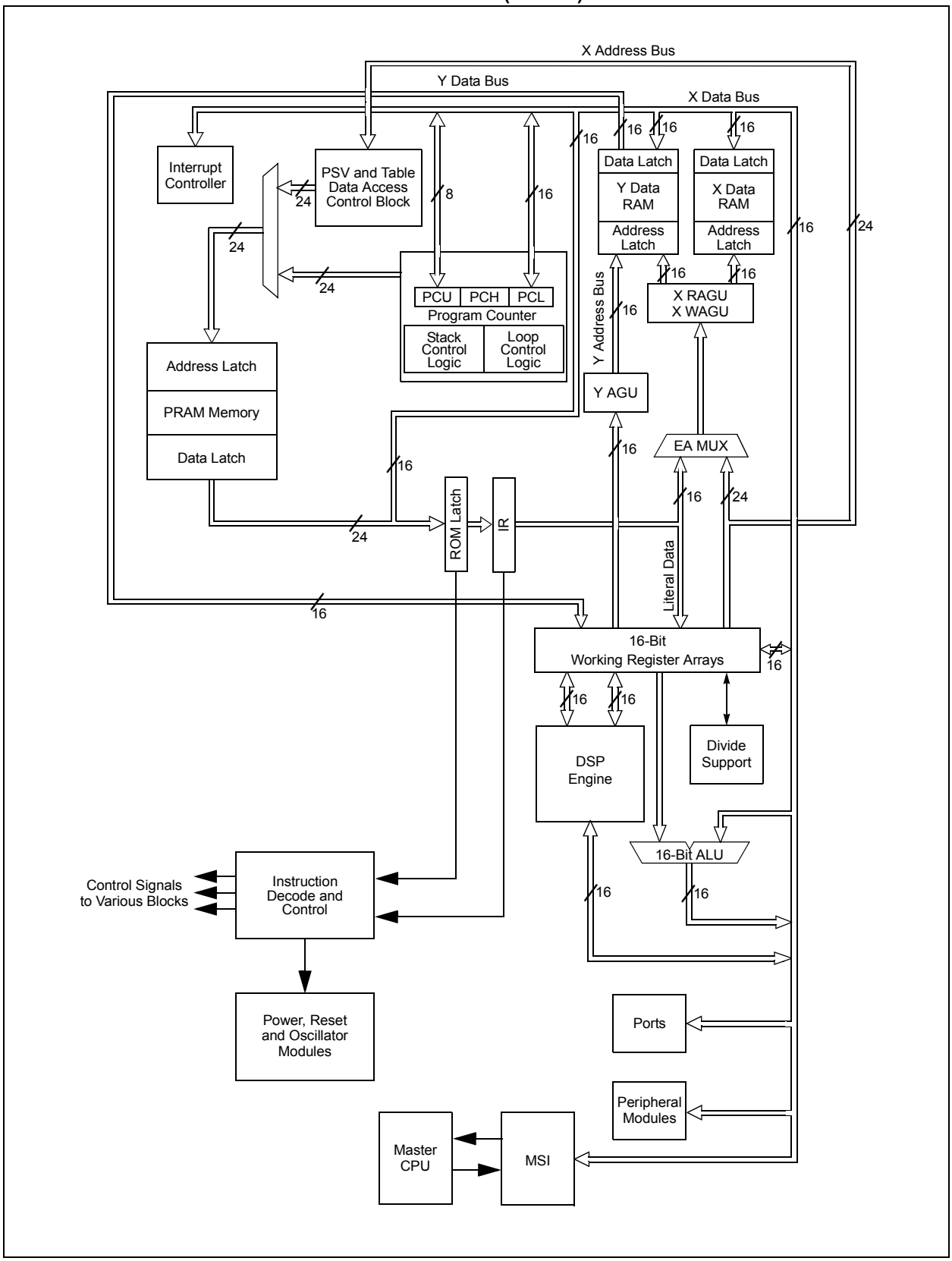
TXEN = 0 (FIFO configured as a receive buffer):
1 = Overflow event has occurred
0 = No overflow event has occurred

Note 1: FIFOCI<4:0> gives a zero-indexed value to the message in the FIFO. If the FIFO is four messages deep (FSIZE<4:0> = 3), FIFOCIx will take on a value of 0 to 3, depending on the state of the FIFO.

2: These bits are updated when a message completes (or aborts) or when the FIFO is reset.

3: This bit is reset on any read of this register or when the TXQ is reset. The bits are cleared when TXREQ is set or using an SPI write.

FIGURE 4-1: dsPIC33CH128MP508S1 FAMILY (SLAVE) CPU BLOCK DIAGRAM



4.6 Slave I/O Ports

Note 1: This data sheet summarizes the features of the dsPIC33CH128MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"I/O Ports with Edge Detect"** (DS70005322) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

2: The I/O ports are shared by the Master core and Slave core. All input goes to both the Master and Slave. The I/O ownership is defined by the Configuration bits.

3: The TMS pin function may be active multiple times during ICSP™ device erase, programming and debugging. When the TMS function is active, the integrated pull-up resistor will pull the pin to VDD. Proper care should be taken if there are sensitive circuits connected on the TMS pin during programming/erase and debugging.

Many of the device pins are shared among the peripherals and the Parallel I/O ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity. The Master and the Slave have the same number of I/O ports and are shared. The Master PORT registers are located in the Master SFR and the Slave PORT registers are located in the Slave SFR, respectively.

All of the input goes to both Master and Slave. For example, a high in RA0 can be read as high on both Master and Slave as long as the TRISA0 bit is maintained as an input of both Master and Slave. The ownership of the output functionality is assigned by the Configuration registers, FCFGPRA0 to FCFGPRE0. Setting the bits in the FCFGPRA0 to FCFGPRE0 registers assigns ownership to the Master or Slave pin.

4.6.1 PARALLEL I/O (PIO) PORTS

Generally, a Parallel I/O port that shares a pin with a peripheral is subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port has ownership of the output data and control signals of the I/O pin. The logic also prevents "loop through", in which a port's digital output can drive the input of a peripheral that shares the same pin. Figure 4-17 illustrates how ports are shared with other peripherals and the associated I/O pin to which they are connected.

When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin can be read, but the output driver for the parallel port bit is disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin can be driven by a port.

All port pins have twelve registers directly associated with their operation as digital I/Os. The Data Direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', then the pin is an input.

All port pins are defined as inputs after a Reset. Reads from the latch (LATx), read the latch. Writes to the latch, write the latch. Reads from the port (PORTx), read the port pins, while writes to the port pins, write the latch. Any bit and its associated data and control registers that are not valid for a particular device are disabled. This means the corresponding LATx and TRISx registers, and the port pin are read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless regarded as a dedicated port because there is no other competing source of outputs. Table 4-24 shows the pin availability. Table 4-25 shows the 5V input tolerant pins across this device.

4.6.5 PERIPHERAL PIN SELECT (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features, while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient work arounds in application code, or a complete redesign, may be the only option.

Peripheral Pin Select configuration provides an alternative to these choices by enabling peripheral set selection and placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to any one of these I/O pins. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

4.6.5.1 Available Pins

The number of available pins is dependent on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the label, “S1RPn”, in their full pin designation, where “n” is the remappable pin number. “S1RP” is used to designate pins that support both remappable input and output functions.

4.6.5.2 Available Peripherals

The peripherals managed by the Peripheral Pin Select are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and interrupt-on-change inputs.

In comparison, some digital only peripheral modules are never included in the Peripheral Pin Select feature. This is because the peripheral’s function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. One example includes I^2C modules. A similar requirement excludes all modules with analog inputs, such as the ADC Converter.

A key difference between remappable and non-remappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/Os and digital communication peripherals associated with the pin. Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

4.6.5.3 Controlling Peripheral Pin Select

Peripheral Pin Select features are controlled through two sets of SFRs: one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral’s input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

REGISTER 4-57: RPINR45: PERIPHERAL PIN SELECT INPUT REGISTER 45

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CLCINAR7	CLCINAR6	CLCINAR5	CLCINAR4	CLCINAR3	CLCINAR2	CLCINAR1	CLCINAR0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **CLCINAR<7:0>:** Assign CLC Input A (S1CLCINA) to the Corresponding S1RPn Pin bits
See Table 4-27.

bit 7-0 **Unimplemented:** Read as '0'

REGISTER 4-58: RPINR46: PERIPHERAL PIN SELECT INPUT REGISTER 46

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CLCINCR7	CLCINCR6	CLCINCR5	CLCINCR4	CLCINCR3	CLCINCR2	CLCINCR1	CLCINCR0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CLCINBR7	CLCINBR6	CLCINBR5	CLCINBR4	CLCINBR3	CLCINBR2	CLCINBR1	CLCINBR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **CLCINCR<7:0>:** Assign CLC Input C (S1CLCINC) to the Corresponding S1RPn Pin bits
See Table 4-27.

bit 7-0 **CLCINBR<7:0>:** Assign CLC Input B (S1CLCINB) to the Corresponding S1RPn Pin bits
See Table 4-27.

REGISTER 4-90: ADCON4H: ADC CONTROL REGISTER 4 HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	C1CHS1	C1CHS0	C0CHS1	C0CHS0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4 **Unimplemented:** Read as '0'

bit 3-2 **C1CHS<1:0>:** Dedicated ADC Core 1 Input Channel Selection bits
11 = S1ANC1
10 = SPGA2
01 = S1ANA1
00 = S1AN1

bit 1-0 **C0CHS<1:0>:** Dedicated ADC Core 0 Input Channel Selection bits
11 = S1ANC0
10 = SPGA1
01 = S1ANA0
00 = S1AN0

REGISTER 5-13: SI1FIFOCS: MSI1 SLAVE FIFO STATUS REGISTER

R-0	U-0	U-0	U-0	R-0	R/C-0	R-0	R-1
SRFEN	—	—	—	SRFOF	SRFUF	SRFFULL	SRFEMPTY
bit 15							bit 8

R-0	U-0	U-0	U-0	R/C-0	R-0	R-0	R-1
SWFEN	—	—	—	SWFOF	SWFUF	SWFFULL	SWFEMPTY
bit 7							bit 0

Legend:	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **SRFEN:** Slave Read (Master Write) FIFO Enable bit
1 = Enables Slave Read (Master Write) FIFO
0 = Disables Slave Read (Master Write) FIFO

bit 14-12 **Unimplemented:** Read as '0'

bit 11 **SRFOF:** Slave Read (Master Write) FIFO Overflow bit
1 = Slave Read FIFO overflow is detected
0 = No Slave Read FIFO overflow is detected

bit 10 **SRFUF:** Slave Read (Master Write) FIFO Underflow bit
1 = Slave Read (Master Write) FIFO underflow is detected
0 = No Slave Read (Master Write) FIFO underflow is detected

bit 9 **SRFFULL:** Slave Read (Master Write) FIFO Full Status bit
1 = Slave Read (Master Write) FIFO is full; last write by Master to Slave Read FIFO (SRMWFDATA) was into the last free location
0 = Slave Read (Master Write) FIFO is not full

bit 8 **SRFEMPTY:** Slave Read (Master Write) FIFO Empty Status bit
1 = Slave Read (Master Write) FIFO is empty; last read by Slave from Read FIFO (SRMWFDATA) emptied the FIFO of all valid data or FIFO is disabled (and initialized to the empty state)
0 = Slave Read (Master Write) FIFO contains valid data not yet read by the Slave

bit 7 **SWFEN:** Slave Write (Master Read) FIFO Enable bit
1 = Enables Slave Write (Master Read) FIFO
0 = Disables Slave Write (Master Read) FIFO

bit 6-4 **Unimplemented:** Read as '0'

bit 3 **SWFOF:** Slave Write (Master Read) FIFO Overflow bit
1 = Slave Write (Master Read) FIFO overflow is detected
0 = No Slave Write (Master Read) FIFO overflow is detected

bit 2 **SWFUF:** Slave Write (Master Read) FIFO Underflow bit
1 = Slave Write (Master Read) FIFO underflow is detected
0 = No Slave Write (Master Read) FIFO underflow is detected

bit 1 **SWFFULL:** Slave Write (Master Read) FIFO Full Status bit
1 = Slave Write (Master Read) FIFO is full; last write by Slave to FIFO (SWMRFDATA) was into the last free location
0 = Slave Write (Master Read) FIFO is not full

bit 0 **SWFEMPTY:** Slave Write (Master Read) FIFO Empty Status bit
1 = Slave Write (Master Read) FIFO is empty; last read by Master from Read FIFO emptied the FIFO of all valid data or FIFO is disabled (and initialized to the empty state)
0 = Slave Write (Master Read) FIFO contains valid data not yet read by the Master

REGISTER 6-7: APLLFBD1: APLL FEEDBACK DIVIDER REGISTER (MASTER)

U-0	U-0	U-0	U-0	r-0	r-0	r-0	r-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1	R/W-1	R/W-0
APLLFBDIV<7:0>							
bit 7							bit 0

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'

bit 11-8 **Reserved:** Maintain as '0'

bit 7-0 **APLLFBDIV<7:0>:** APLL Feedback Divider bits

11111111 = Reserved
...
11001000 = 200 maximum(1)
...
10010110 = 150 (default)
...
00010000 = 16 minimum(1)
...
00000010 = Reserved
00000001 = Reserved
00000000 = Reserved

Note 1: The allowed range is 16-200 (decimal). The rest of the values are reserved and should be avoided. The power-on default feedback divider is 150 (decimal) with an 8 MHz FRC input clock; the VCO frequency is 1.2 GHz.

REGISTER 13-16: UxSCINT: UARTx SMART CARD INTERRUPT REGISTER

U-0	U-0	HS/R/W-0	HS/R/W-0	U-0	HS/R/W-0	HS/R/W-0	HS/R/W-0
—	—	RXRPTIF	TXRPTIF	—	BTCIF	WTCIF	GTCIF
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
—	—	RXRPTIE	TXRPTIE	—	BTCIE	WTCIE	GTCIE
bit 7							bit 0

Legend:	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **RXRPTIF:** Receive Repeat Interrupt Flag bit
1 = Parity error has persisted after the same character has been received five times (four retransmits)
0 = Flag is cleared

bit 12 **TXRPTIF:** Transmit Repeat Interrupt Flag bit
1 = Line error has been detected after the last retransmit per TXRPT<1:0>
0 = Flag is cleared

bit 11 **Unimplemented:** Read as '0'

bit 10 **BTCIF:** Block Time Counter Interrupt Flag bit
1 = Block Time Counter has reached 0
0 = Block Time Counter has not reached 0

bit 9 **WTCIF:** Waiting Time Counter Interrupt Flag bit
1 = Waiting Time Counter has reached 0
0 = Waiting Time Counter has not reached 0

bit 8 **GTCIF:** Guard Time Counter Interrupt Flag bit
1 = Guard Time Counter has reached 0
0 = Guard Time Counter has not reached 0

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **RXRPTIE:** Receive Repeat Interrupt Enable bit
1 = An interrupt is invoked when a parity error has persisted after the same character has been received five times (four retransmits)
0 = Interrupt is disabled

bit 4 **TXRPTIE:** Transmit Repeat Interrupt Enable bit
1 = An interrupt is invoked when a line error is detected after the last retransmit per TXRPT<1:0> has been completed
0 = Interrupt is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2 **BTCIE:** Block Time Counter Interrupt Enable bit
1 = Block Time Counter interrupt is enabled
0 = Block Time Counter interrupt is disabled

bit 1 **WTCIE:** Waiting Time Counter Interrupt Enable bit
1 = Waiting Time Counter interrupt is enabled
0 = Waiting Time Counter Interrupt is disabled

bit 0 **GTCIE:** Guard Time Counter interrupt enable bit
1 = Guard Time Counter interrupt is enabled
0 = Guard Time Counter interrupt is disabled

FIGURE 14-6: SPIx MASTER, FRAME SLAVE CONNECTION DIAGRAM

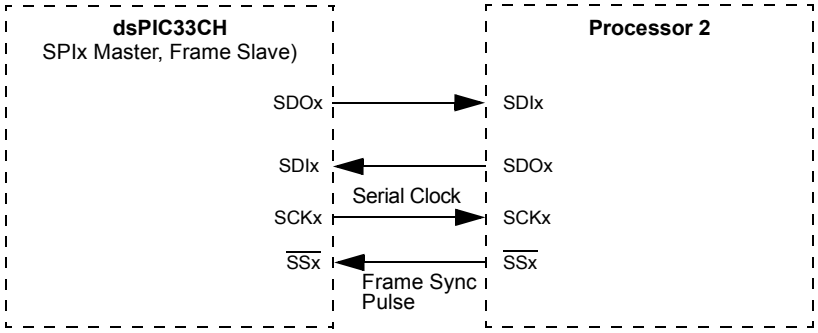


FIGURE 14-7: SPIx SLAVE, FRAME MASTER CONNECTION DIAGRAM

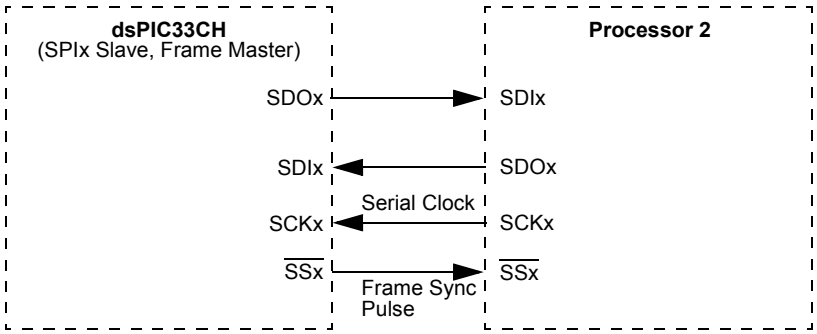
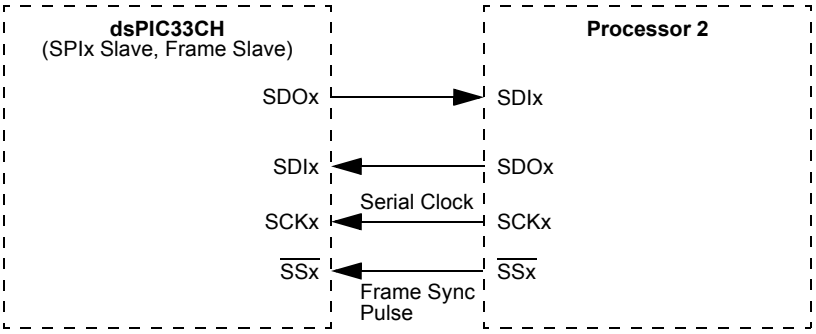


FIGURE 14-8: SPIx SLAVE, FRAME SLAVE CONNECTION DIAGRAM



EQUATION 14-1: RELATIONSHIP BETWEEN DEVICE AND SPIx CLOCK SPEED

$$Baud\ Rate = \frac{FPB}{(2 * (SPIxBRG + 1))}$$

Where:

FPB is the Peripheral Bus Clock Frequency.

15.2 Setting Baud Rate When Operating as a Bus Master

To compute the Baud Rate Generator reload value, use Equation 15-1.

EQUATION 15-1: COMPUTING BAUD RATE RELOAD VALUE(1,2,3,4)

$$I2CxBRG = ((1/F_{SCL} - Delay) \bullet F_{CY}/2) - 2$$

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

2: These clock rate values are for guidance only. The actual clock rate can be affected by various system-level parameters. The actual clock rate should be measured in its intended application.

3: Typical value of delay varies from 110 ns to 150 ns.

4: I2CxBRG values of 0 to 3 are expressly forbidden. The user should never program the I2CxBRG with a value of 0x0, 0x1, 0x2 or 0x3 as indeterminate results may occur.

15.3 Slave Address Masking

The I2CxMSK register (Register 15-4) designates address bit positions as “don’t care” for both 7-Bit and 10-Bit Addressing modes. Setting a particular bit location (= 1) in the I2CxMSK register causes the Slave module to respond, whether the corresponding address bit value is a ‘0’ or a ‘1’. For example, when I2CxMSK is set to ‘0010000000’, the Slave module will detect both addresses, ‘0000000000’ and ‘0010000000’.

To enable address masking, the Intelligent Peripheral Management Interface (IPMI) must be disabled by clearing the STRICT bit (I2CxCONL<11>).

Note: As a result of changes in the I^2C protocol, the addresses in Table 15-2 are reserved and will not be Acknowledged in Slave mode. This includes any address mask settings that include any of these addresses.

TABLE 15-1: I2Cx CLOCK RATES(1,2)

FCY	FSCL	I2CxBRG Value	
		Decimal	Hexadecimal
100 MHz	1 MHz	41	29
100 MHz	400 kHz	116	74
100 MHz	100 kHz	491	1EB
80 MHz	1 MHz	32	20
80 MHz	400 kHz	92	5C
80 MHz	100 kHz	392	188
60 MHz	1 MHz	24	18
60 MHz	400 kHz	69	45
60 MHz	100 kHz	294	126
40 MHz	1 MHz	15	0F
40 MHz	400 kHz	45	2D
40 MHz	100 kHz	195	C3
20 MHz	1 MHz	7	7
20 MHz	400 kHz	22	16
20 MHz	100 kHz	97	61

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

2: These clock rate values are for guidance only. The actual clock rate can be affected by various system-level parameters. The actual clock rate should be measured in its intended application.

TABLE 24-7: DC CHARACTERISTICS: OPERATING CURRENT (IDD) (MASTER RUN/SLAVE SLEEP)

DC CHARACTERISTICS	Master (Run) + Slave (Sleep)		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	**Typ.**	**Max.**	**Units**	**Conditions**		
Operating Current (IDD)(1)						
DC20b	7.9	9.8	mA	-40°C	3.3V	10 MIPS (N = 1, N2 = 5, N3 = 2, M = 50, FVCO = 400 MHz, FPLLO = 40 MHz)
	8.0	13.4	mA	+25°C		
	8.2	19.5	mA	+85°C		
	12.2	26.3	mA	+125°C		
DC21b	10.3	12.4	mA	-40°C	3.3V	20 MIPS (N = 1, N2 = 5, N3 = 1, M = 50, FVCO = 400 MHz, FPLLO = 80 MHz)
	10.5	16.0	mA	+25°C		
	10.6	22.1	mA	+85°C		
	14.6	28.7	mA	+125°C		
DC22b	14.2	16.5	mA	-40°C	3.3V	40 MIPS (N = 1, N2 = 3, N3 = 1, M = 60, FVCO = 480 MHz, FPLLO = 160 MHz)
	14.4	20.3	mA	+25°C		
	14.5	26.3	mA	+85°C		
	18.4	32.6	mA	+125°C		
DC23b	22.3	25.4	mA	-40°C	3.3V	70 MIPS (N = 1, N2 = 2, N3 = 1, M = 70, FVCO = 560 MHz, FPLLO = 280 MHz)
	22.5	29.4	mA	+25°C		
	22.4	34.9	mA	+85°C		
	26.4	40.7	mA	+125°C		
DC24b	25.6	29.0	mA	-40°C	3.3V	90 MIPS (N = 1, N2 = 2, N3 = 1, M = 90, FVCO = 720 MHz, FPLLO = 360 MHz)
	25.8	33.1	mA	+25°C		
	25.7	38.2	mA	+85°C		
	29.4	43.8	mA	+125°C		

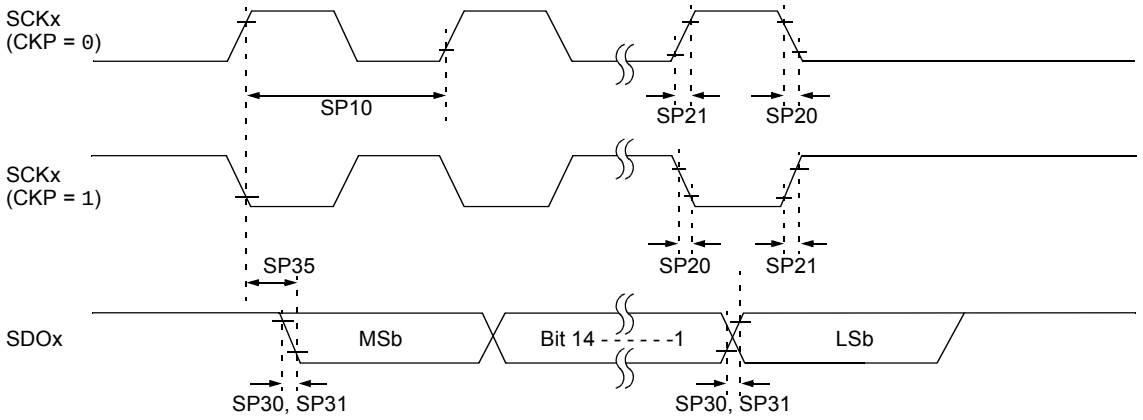
Note 1: IDD is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows:

- FIN = 8 MHz, FPFD = 8 MHz
- CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as output low
- $\overline{\text{MCLR}}$ = VDD, WDT and FSCM are disabled
- CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating or being clocked (all defined PMDx bits are set)
- CPU is executing `while(1)` statement
- JTAG is disabled

TABLE 24-34: SPIx MAXIMUM DATA/CLOCK RATE SUMMARY

SPI Master Transmit Only (Half-Duplex)	SPI Master Transmit/Receive (Full-Duplex)	SPI Slave Transmit/Receive (Full-Duplex)	CKE	Maximum Data Rate (MHz)	Condition
Figure 24-7 Table 24-35	—	—	0	15	Using PPS
				40	Dedicated Pin
Figure 24-8 Table 24-35	—	—	1	15	Using PPS
				40	Dedicated Pin
—	Figure 24-9 Table 24-36	—	0	9	Using PPS
				40	Dedicated Pin
—	Figure 24-10 Table 24-37	—	1	9	Using PPS
				40	Dedicated Pin
—	—	Figure 24-12 Table 24-39	0	15	Using PPS
				40	Dedicated Pin
—	—	Figure 24-13 Table 24-38	1	15	Using PPS
				40	Dedicated Pin

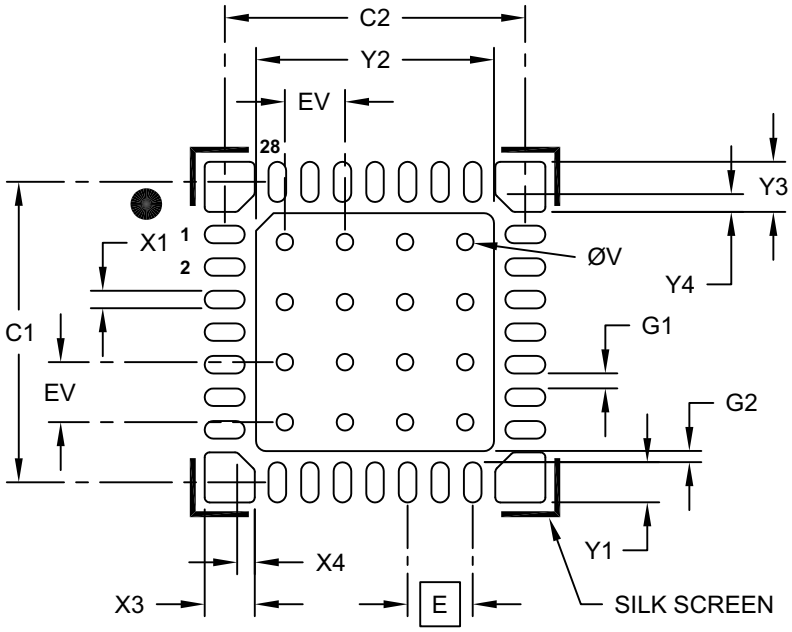
FIGURE 24-7: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS



Note: Refer to Figure 24-1 for load conditions.

28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (2N) - 6x6x0.55 mm Body [UQFN] With 4.65x4.65 mm Exposed Pad and Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.65 BSC	
Optional Center Pad Width	X2			4.75
Optional Center Pad Length	Y2			4.75
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.35
Contact Pad Length (X28)	Y1			0.80
Corner Anchor (X4)	X3			1.00
Corner Anchor (X4)	Y3			1.00
Corner Anchor Chamfer (X4)	X4			0.35
Corner Anchor Chamfer (X4)	Y4			0.35
Contact Pad to Pad (X28)	G1	0.20		
Contact Pad to Center Pad (X28)	G2	0.20		
Thermal Via Diameter	V		0.33	
Thermal Via Pitch	EV		1.20	

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

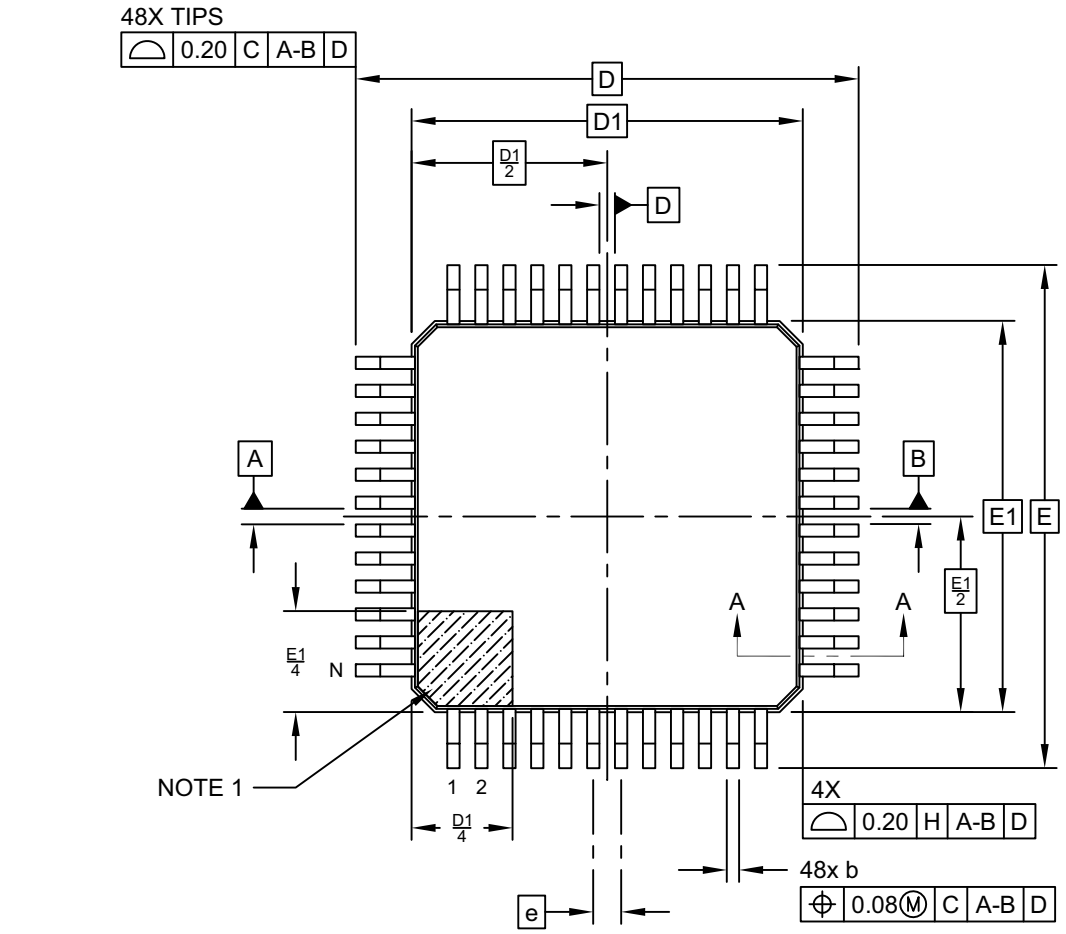
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

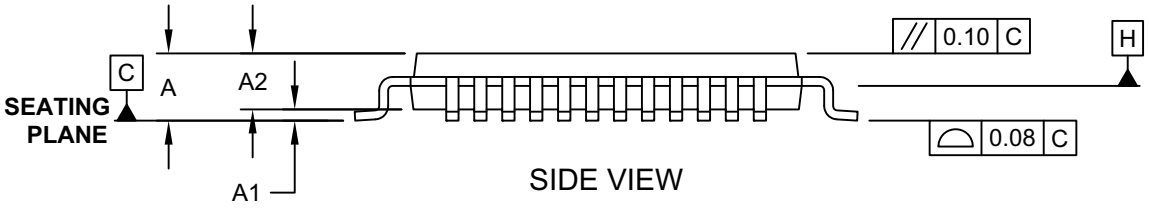
Microchip Technology Drawing C04-2385B

48-Lead Thin Quad Flatpack (PT) - 7x7x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



TOP VIEW



SIDE VIEW

Microchip Technology Drawing C04-300-PT Rev A Sheet 1 of 2