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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit Dual-Core
Speed	180MHz, 200MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	27
Program Memory Size	152KB (152K x 8)
Program Memory Type	FLASH, PRAM
EEPROM Size	
RAM Size	20K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 31x12b; D/A 4x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	36-UFQFN Exposed Pad
Supplier Device Package	36-UQFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ch128mp203-e-m5

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

FIGURE 1-1: SLAVE CORE CODE TRANSFER BLOCK DIAGRAM Before a POR: **Master Flash** Slave PRAM Code to Transfer the Slave Master Slave Code to the Slave PRAM CPU CPU No Code Master Code Master Slave **RAM** RAM Slave Code After a POR, it is Master code's responsibility to load the Slave PRAM with the Slave code. Once the Slave code is loaded to PRAM, the Master can enable the Slave to start Slave code execution: **Master Flash** Slave PRAM Code to Transfer the Slave Master Slave Code to the Slave PRAM CPU CPU Slave Code Master Code Master Slave RAM **RAM** Slave Code

3.2.1.1 Program Memory Organization

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 3-5).

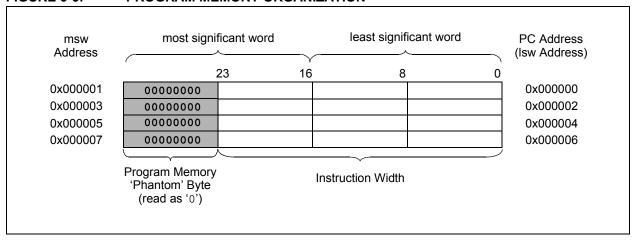
Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented, by two, during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

3.2.1.2 Interrupt and Trap Vectors

All dsPIC33CH128MP508 family devices reserve the addresses between 0x000000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user application at address, 0x000000, of Flash memory, with the actual address for the start of code at address, 0x000002, of Flash memory.

A more detailed discussion of the Interrupt Vector Tables (IVTs) is provided in **Section 3.5 "Master Interrupt Controller"**.

FIGURE 3-5: PROGRAM MEMORY ORGANIZATION



3.2.2 UNIQUE DEVICE IDENTIFIER (UDID)

All dsPIC33CH128MP508 family devices are individually encoded during final manufacturing with a Unique Device Identifier or UDID. The UDID cannot be erased by a bulk erase command or any other user-accessible means. This feature allows for manufacturing traceability of Microchip Technology devices in applications where this is a requirement. It may also be used by the application manufacturer for any number of things that may require unique identification, such as:

- · Tracking the device
- · Unique serial number
- · Unique security key

The UDID comprises five 24-bit program words. When taken together, these fields form a unique 120-bit identifier.

The UDID is stored in five read-only locations, located between 0x801200 and 0x801208 in the device configuration space. Table 3-3 lists the addresses of the identifier words and shows their contents

TABLE 3-3: UDID ADDRESSES

UDID	Address	Description		
UDID1	0x801200	UDID Word 1		
UDID2	0x801202	UDID Word 2		
UDID3	0x801204	UDID Word 3		
UDID4	0x801206	UDID Word 4		
UDID5	0x801208	UDID Word 5		

3.2.7 MODULO ADDRESSING

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either Data or Program Space (since the Data Pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into Program Space) and Y Data Spaces. Modulo Addressing can operate on any W Register Pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing since these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction, as there are certain restrictions on the buffer start address (for incrementing buffers) or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a Bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

3.2.7.1 Start and End Address

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT and YMODEND (see Table 3-4).

Note: Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

3.2.7.2 W Address Register Selection

The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags, as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 1111, X RAGU and X WAGU Modulo Addressing is disabled
- If YWM = 1111, Y AGU Modulo Addressing is disabled

The X Address Space Pointer W (XWM) register, to which Modulo Addressing is to be applied, is stored in MODCON<3:0> (see Table 3.2.1). Modulo Addressing is enabled for X Data Space when XWM is set to any value other than '1111' and the XMODEN bit is set (MODCON<15>).

The Y Address Space Pointer W (YWM) register, to which Modulo Addressing is to be applied, is stored in MODCON<7:4>. Modulo Addressing is enabled for Y Data Space when YWM is set to any value other than '1111' and the YMODEN bit (MODCON<14>) is set.

FIGURE 3-10: MODULO ADDRESSING OPERATION EXAMPLE

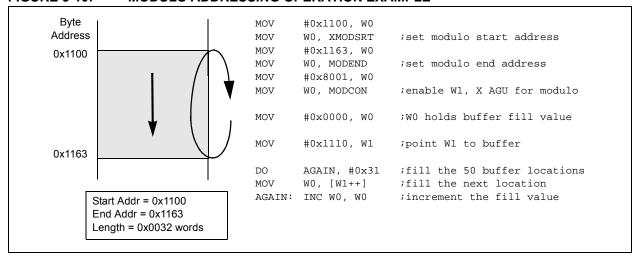


FIGURE 3-11: BIT-REVERSED ADDRESSING EXAMPLE

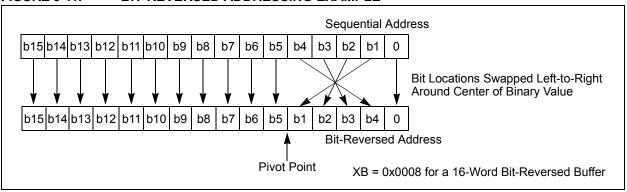


TABLE 3-21: BIT-REVERSED ADDRESSING SEQUENCE (16-ENTRY)

		Norma	al Addres	ss			Bit-Rev	ersed Ac	Idress
А3	A2	A 1	Α0	Decimal	А3	A2	A 1	A0	Decimal
0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	8
0	0	1	0	2	0	1	0	0	4
0	0	1	1	3	1	1	0	0	12
0	1	0	0	4	0	0	1	0	2
0	1	0	1	5	1	0	1	0	10
0	1	1	0	6	0	1	1	0	6
0	1	1	1	7	1	1	1	0	14
1	0	0	0	8	0	0	0	1	1
1	0	0	1	9	1	0	0	1	9
1	0	1	0	10	0	1	0	1	5
1	0	1	1	11	1	1	0	1	13
1	1	0	0	12	0	0	1	1	3
1	1	0	1	13	1	0	1	1	11
1	1	1	0	14	0	1	1	1	7
1	1	1	1	15	1	1	1	1	15

REGISTER 3-134: C1FIFOCONLx: CAN FIFO CONTROL REGISTER x (x = 1 TO 7) LOW (CONTINUED)

bit 2 TFERFFIE: Transmit/Receive FIFO Empty/Full Interrupt Enable bit

TXEN = 1 (FIFO configured as a transmit FIFO):

Transmit FIFO Empty Interrupt Enable
1 = Interrupt is enabled for FIFO empty
0 = Interrupt is disabled for FIFO empty

TXEN = 0 (FIFO configured as a receive FIFO):

Receive FIFO Full Interrupt Enable

1 = Interrupt is enabled for FIFO full

0 = Interrupt is disabled for FIFO full

bit 1 TFHRFHIE: Transmit/Receive FIFO Half Empty/Half Full Interrupt Enable bit

TXEN = 1 (FIFO configured as a transmit FIFO):
Transmit FIFO Half Empty Interrupt Enable
1 = Interrupt is enabled for FIFO half empty
0 = Interrupt is disabled for FIFO half empty
TXEN = 0 (FIFO configured as a receive FIFO):

Receive FIFO Half Full Interrupt Enable 1 = Interrupt is enabled for FIFO half full 0 = Interrupt is disabled for FIFO half full

bit 0 TFNRFNIE: Transmit/Receive FIFO Not Full/Not Empty Interrupt Enable bit

TXEN = 1 (FIFO configured as a transmit FIFO):

Transmit FIFO Not Full Interrupt Enable
1 = Interrupt is enabled for FIFO not full
0 = Interrupt is disabled for FIFO not full

TXEN = 0 (FIFO configured as a receive FIFO):
Receive FIFO Not Empty Interrupt Enable

1 = Interrupt is enabled for FIFO not empty0 = Interrupt is disabled for FIFO not empty

Note 1: This bit can only be modified in Configuration mode (OPMOD<2:0> = 100).

REGISTER 3-174: ADIEL: ADC INTERRUPT ENABLE REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
IE<15:8>										
bit 15							bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
IE<7:0>										
bit 7							bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-0 **IE<15:0>:** Common Interrupt Enable bits

1 = Common and individual interrupts are enabled for the corresponding channel

0 = Common and individual interrupts are disabled for the corresponding channel

REGISTER 3-175: ADIEH: ADC INTERRUPT ENABLE REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	_	_			IE<20:16>		
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4-0 **IE<20:16>:** Common Interrupt Enable bits

1 = Common and individual interrupts are enabled for the corresponding channel

0 = Common and individual interrupts are disabled for the corresponding channel

REGISTER 3-183: PTGCST: PTG CONTROL/STATUS LOW REGISTER (CONTINUED)

- bit 1-0 **PTGITM<1:0>:** PTG Input Trigger Operation Selection bit⁽¹⁾
 - 11 = Single-level detect with Step delay not executed on exit of command (regardless of the PTGCTRL command) (Mode 3)
 - 10 = Single-level detect with Step delay executed on exit of command (Mode 2)
 - 01 = Continuous edge detect with Step delay not executed on exit of command (regardless of the PTGCTRL command) (Mode 1)
 - 00 = Continuous edge detect with Step delay executed on exit of command (Mode 0)
- Note 1: These bits apply to the PTGWHI and PTGWLO commands only.
 - 2: This bit is only used with the PTGCTRL Step command software trigger option.
 - 3: The PTGSSEN bit may only be written when in Debug mode.

TABLE 4-9: SLAVE SFR BLOCK 900h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
ССР			CCP2STATL	980	000xx0000	CCP3RAL	9B0	00000000000000000
CCP1CON1L	950	0-00000000000000	CCP2STATH	982	00000	CCP3RBL	9B4	00000000000000000
CCP1CON1H	952	00000000000000	CCP2TMRL	984	00000000000000000	CCP3BUFL	9B8	00000000000000000
CCP1CON2L	954	00-000000000	CCP2TMRH	986	00000000000000000	CCP3BUFH	9BA	00000000000000000
CCP1CON2H	956	0100-00000	CCP2PRL	988	11111111111111111	CCP4CON1L	9BC	0-00000000000000
CCP1CON3H	95A	00000-00	CCP2PRH	98A	11111111111111111	CCP4CON1H	9BE	00000000000000
CCP1STATL	95C	000xx0000	CCP2RAL	98C	00000000000000000	CCP4CON2L	9C0	00-000000000
CCP1STATH	95E	00000	CCP2RBL	990	00000000000000000	CCP4CON2H	9C2	0100-00000
CCP1TMRL	960	00000000000000000	CCP2BUFL	994	00000000000000000	CCP4CON3H	9C6	00000-00
CCP1TMRH	962	00000000000000000	CCP2BUFH	996	00000000000000000	CCP4STATL	9C8	000xx0000
CCP1PRL	964	1111111111111111	CCP3CON1L	998	0-00000000000000	CCP4STATH	9CA	00000
CCP1PRH	966	1111111111111111	CCP3CON1H	99A	00000000000000	CCP4TMRL	9CC	00000000000000000
CCP1RAL	968	00000000000000000	CCP3CON2L	99C	00-000000000	CCP4TMRH	9CE	00000000000000000
CCP1RBL	96C	00000000000000000	CCP3CON2H	99E	0100-00000	CCP4PRL	9D0	1111111111111111
CCP1BUFL	970	00000000000000000	CCP3CON3H	9A2	00000-00	CCP4PRH	9D2	11111111111111111
CCP1BUFH	972	00000000000000000	CCP3STATL	9A4	000xx0000	CCP4RAL	9D4	00000000000000000
CCP2CON1L	974	0-00000000000000	CCP3STATH	9A6	00000	CCP4RBL	9D8	00000000000000000
CCP2CON1H	976	00000000000000	CCP3TMRL	9A8	00000000000000000	CCP4BUFL	9DC	00000000000000000
CCP2CON2L	978	00-000000000	CCP3TMRH	9AA	00000000000000000	CCP4BUFH	9DE	00000000000000000
CCP2CON2H	97A	0100-00000	CCP3PRL	9AC	1111111111111111			
CCP2CON3H	97E	00000-00	CCP3PRH	9AE	1111111111111111			

Legend: x = unknown or indeterminate value; "-" = unimplemented bits. Address and Reset values are in hexadecimal and binary, respectively.

TABLE 4-10: SLAVE SFR BLOCK A00h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
DMA	DMA			AC4	0-00000000000	DMACH1	ACE	0-00000000000
DMACON	ABC	0-00	DMAINT0	AC6	00000000000000	DMAINT1	AD0	000000000000000
DMABUF	ABE	00000000000000000	DMASRC0	AC8	00000000000000000	DMASRC1	AD2	00000000000000000
DMAL	AC0	00010000000000000	DMADST0	ACA	00000000000000000	DMADST1	AD4	00000000000000000
DMAH	AC2	00010000000000000	DMACNT0	ACC	0000000000000001	DMACNT1	AD6	0000000000000001

Legend: x = unknown or indeterminate value; "-" = unimplemented bits. Address and Reset values are in hexadecimal and binary, respectively.

4.2.4.2 Extended X Data Space

The lower portion of the base address space range, between 0x0000 and 0x7FFF, is always accessible, regardless of the contents of the Data Space Read Page register. It is indirectly addressable through the register indirect instructions. It can be regarded as being located in the default EDS Page 0 (i.e., EDS address range of 0x0000000 to 0x007FFF with the base address bit, EA<15> = 0, for this address range). However, Page 0 cannot be accessed through the upper 32 Kbytes, 0x8000 to 0xFFFF, of base Data Space in combination with DSRPAG = 0x00. Consequently, DSRPAG is initialized to 0x001 at Reset.

- Note 1: DSRPAG should not be used to access Page 0. An EDS access with DSRPAG set to 0x000 will generate an address error trap.
 - 2: Clearing the DSRPAG in software has no effect.

The remaining PSV pages are only accessible using the DSRPAG register in combination with the upper 32 Kbytes, 0x8000 to 0xFFFF, of the base address, where base address bit, EA<15>=1.

4.2.4.3 Software Stack

The W15 register serves as a dedicated Software Stack Pointer (SSP), and is automatically modified by exception processing, subroutine calls and returns; however, W15 can be referenced by any instruction in the same manner as all other W registers. This simplifies reading, writing and manipulating the Stack Pointer (for example, creating stack frames).

Note: To protect against misaligned stack accesses, W15<0> is fixed to '0' by the hardware.

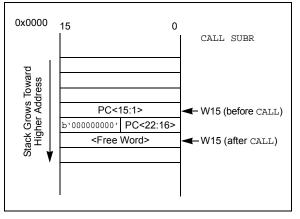
W15 is initialized to 0x1000 during all Resets. This address ensures that the SSP points to valid RAM in all dsPIC33CH128MP508S1 devices and permits stack availability for non-maskable trap exceptions. These can occur before the SSP is initialized by the user software. You can reprogram the SSP during initialization to any location within Data Space.

The Software Stack Pointer always points to the first available free word and fills the software stack, working from lower toward higher addresses. Figure 4-8 illustrates how it pre-decrements for a stack pop (read) and post-increments for a stack push (writes).

When the PC is pushed onto the stack, PC<15:0> are pushed onto the first available stack word, then PC<22:16> are pushed into the second available stack location. For a PC push during any CALL instruction, the MSB of the PC is zero-extended before the push, as shown in Figure 4-8. During exception processing, the MSB of the PC is concatenated with the lower 8 bits of the CPU STATUS Register, SR. This allows the contents of SRL to be preserved automatically during interrupt processing.

- Note 1: To maintain system Stack Pointer (W15) coherency, W15 is never subject to (EDS) paging, and is therefore, restricted to an address range of 0x0000 to 0xFFFF. The same applies to W14 when used as a Stack Frame Pointer (SFA = 1).
 - 2: As the stack can be placed in, and can access X and Y spaces, care must be taken regarding its use, particularly with regard to local automatic variables in a C development environment

FIGURE 4-8: CALL STACK FRAME



4.6.5.5 Virtual Connections

The dsPIC33CH128MP508S1 family devices support six virtual S1RPn pins (S1RP170-S1RP175), which are identical in functionality to all other S1RPn pins, with the exception of pinouts. These six pins are internal to the devices and are not connected to a physical device pin.

These pins provide a simple way for inter-peripheral connection without utilizing a physical pin. For example, the output of the analog comparator can be connected to S1RP170 and the PWM control input can be configured for S1RP170 as well. This configuration allows the analog comparator to trigger PWM Faults without the use of an actual physical pin on the device.

4.6.5.6 Slave PPS Inputs to Master Core PPS

The dsPIC33CH128MP508S1 Slave core subsystem PPS has connections to the Master core subsystem virtual PPS (S1RPV5-S1RPV0) output blocks. These inputs are mapped as S1RP175, S1RP174, S1RP173, S1RP172, S1RP171 and S1RP170.

The S1RPn inputs, S1RP1-S1RP13, are connected to internal signals from both the Master and Slave core subsystems. Additionally, the Master core virtual PPS output blocks (RPV5-RPV0) are connected to the Slave core PPS circuitry.

There are virtual pins in PPS to share between Master and Slave:

- RP181 is for Master input (RPV5)
- · RP180 is for Master input (RPV4)
- RP179 is for Master input (RPV3)
- RP178 is for Master input (RPV2)
- RP177 is for Master input (RPV1)
- RP176 is for Master input (RPV0)
- S1RP175 is for Slave input (S1RPV5)
- S1RP174 is for Slave input (S1RPV4)
- S1RP173 is for Slave input (S1RPV3)
- S1RP172 is for Slave input (S1RPV2)
- · S1RP171 is for Slave input (S1RPV1)
- S1RP170 is for Slave input (S1RPV0)

The idea of the S1RPVn (Remappable Pin Virtual) is to interconnect between Master and Slave without an I/O pin. For example, the Master UART receiver can be connected to the Slave UART transmit using S1RPVn and data communication can happen from Slave to Master without using any physical pin.

6.4 Master Special Function Registers

These Special Function Registers provide run-time control and status of the Master core's oscillator system.

6.4.1 MASTER OSCILLATOR CONTROL REGISTERS

REGISTER 6-1: OSCCON: OSCILLATOR CONTROL REGISTER (MASTER)(1)

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
_	COSC2	COSC1	COSC0	_	NOSC2 ⁽²⁾	NOSC1 ⁽²⁾	NOSCO ⁽²⁾
bit 15							bit 8

R/W-0	U-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0			
CLKLOCK	_	LOCK	_	CF ⁽³⁾	_	_	OSWEN			
bit 7 bit 0										

Legend:y = Value set from Configuration bits on PORR = Readable bitW = Writable bitU = Unimplemented bit, read as '0'-n = Value at POR'1' = Bit is set'0' = Bit is clearedx = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits (read-only)

111 = Fast RC Oscillator (FRC) with Divide-by-n (FRCDIVN)

110 = Backup FRC (BFRC)

101 = Low-Power RC Oscillator (LPRC)

100 = Reserved – default to FRC

011 = Primary Oscillator (XT, HS, EC) with PLL (XTPLL, HSPLL, ECPLL)

010 = Primary Oscillator (XT, HS, EC)

001 = Fast RC Oscillator (FRC) with PLL (FRCPLL)

000 = Fast RC Oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits⁽²⁾

111 = Fast RC Oscillator (FRC) with Divide-by-n (FRCDIVN)

110 = Backup FRC (BFRC)

101 = Low-Power RC Oscillator (LPRC)

100 = Reserved – default to FRC

011 = Primary Oscillator (XT, HS, EC) with PLL (XTPLL, HSPLL, ECPLL)

010 = Primary Oscillator (XT, HS, EC)

001 = Fast RC Oscillator (FRC) with PLL (FRCPLL)

000 = Fast RC Oscillator (FRC)

bit 7 CLKLOCK: Clock Lock Enable bit

1 = If (FCKSM0 = 1), then clock and PLL configurations are locked; if (FCKSM0 = 0), then clock and PLL configurations may be modified

0 = Clock and PLL selections are not locked, configurations may be modified

bit 6 **Unimplemented:** Read as '0'

Note 1: Writes to this register require an unlock sequence.

2: Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.

3: This bit should only be cleared in software. Setting the bit in software (= 1) will have the same effect as an actual oscillator failure and will trigger an oscillator failure trap.

REGISTER 7-3: PMD2: MASTER PERIPHERAL MODULE DISABLE 2 CONTROL REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0					
_	_	_	_	_	_	_	_					
bit 15	bit 15 bit 8											

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| CCP8MD | CCP7MD | CCP6MD | CCP5MD | CCP4MD | CCP3MD | CCP2MD | CCP1MD |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 CCP8MD: SCCP8 Module Disable bit

1 = SCCP8 module is disabled 0 = SCCP8 module is enabled

bit 6 CCP7MD: SCCP7 Module Disable bit

1 = SCCP7 module is disabled 0 = SCCP7 module is enabled

bit 5 CCP6MD: SCCP6 Module Disable bit

1 = SCCP6 module is disabled 0 = SCCP6 module is enabled

bit 4 CCP5MD: SCCP5 Module Disable bit

1 = SCCP5 module is disabled 0 = SCCP5 module is enabled

bit 3 CCP4MD: SCCP4 Module Disable bit

1 = SCCP4 module is disabled 0 = SCCP4 module is enabled

bit 2 CCP3MD: SCCP3 Module Disable bit

1 = SCCP3 module is disabled 0 = SCCP3 module is enabled

bit 1 CCP2MD: SCCP2 Module Disable bit

1 = SCCP2 module is disabled 0 = SCCP2 module is enabled

bit 0 CCP1MD: SCCP1 Module Disable bit

1 = SCCP1 module is disabled0 = SCCP1 module is enabled

REGISTER 10-3: CCPxCON2L: CCPx CONTROL 2 LOW REGISTERS

R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	
PWMRSEN	ASDGM	_	SSDG	_	_	_	_	
bit 15								

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| ASDG7 | ASDG6 | ASDG5 | ASDG4 | ASDG3 | ASDG2 | ASDG1 | ASDG0 |
| bit 7 | | | | | | | bit 0 |

Legend:				
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15 **PWMRSEN:** CCPx PWM Restart Enable bit

1 = ASEVT bit clears automatically at the beginning of the next PWM period, after the shutdown input has ended

0 = ASEVT bit must be cleared in software to resume PWM activity on output pins

bit 14 ASDGM: CCPx Auto-Shutdown Gate Mode Enable bit

1 = Waits until the next Time Base Reset or rollover for shutdown to occur

0 = Shutdown event occurs immediately

bit 13 **Unimplemented:** Read as '0'

bit 12 SSDG: CCPx Software Shutdown/Gate Control bit

1 = Manually forces auto-shutdown, timer clock gate or input capture signal gate event (setting of ASDGM bit still applies)

0 = Normal module operation

bit 11-8 Unimplemented: Read as '0'

bit 7-0 ASDG<7:0>: CCPx Auto-Shutdown/Gating Source Enable bits

1 = ASDGx Source n is enabled (see Table 10-8 and Table 10-9 for auto-shutdown/gating sources)

0 = ASDGx Source n is disabled

16.4 SENT Control/Status Registers

REGISTER 16-1: SENTxCON1: SENTx CONTROL REGISTER 1

R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
SNTEN	_	SNTSIDL	_	RCVEN	TXM ⁽¹⁾	TXPOL ⁽¹⁾	CRCEN
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	
PPP	SPCEN ⁽²⁾	_	PS	_	NIBCNT2	NIBCNT1	NIBCNT0	
bit 7 b								

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 SNTEN: SENTx Enable bit

1 = SENTx is enabled 0 = SENTx is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 SNTSIDL: SENTx Stop in Idle Mode bit

1 = Discontinues module operation when the device enters Idle mode

0 = Continues module operation in Idle mode

bit 12 **Unimplemented:** Read as '0'

bit 11 RCVEN: SENTx Receive Enable bit

1 = SENTx operates as a receiver

0 = SENTx operates as a transmitter (sensor)

bit 10 **TXM:** SENTx Transmit Mode bit⁽¹⁾

1 = SENTx transmits data frame only when triggered using the SYNCTXEN status bit

0 = SENTx transmits data frames continuously while SNTEN = 1

bit 9 **TXPOL:** SENTx Transmit Polarity bit⁽¹⁾

1 = SENTx data output pin is low in the Idle state

0 = SENTx data output pin is high in the Idle state

bit 8 CRCEN: CRC Enable bit

Module in Receive Mode (RCVEN = 1):

1 = SENTx performs CRC verification on received data using the preferred J2716 method

0 = SENTx does not perform CRC verification on received data

Module in Transmit Mode (RCVEN = 1):

1 = SENTx automatically calculates CRC using the preferred J2716 method

0 = SENTx does not calculate CRC

bit 7 **PPP:** Pause Pulse Present bit

1 = SENTx is configured to transmit/receive SENT messages with pause pulse

0 = SENTx is configured to transmit/receive SENT messages without pause pulse

bit 6 SPCEN: Short PWM Code Enable bit⁽²⁾

1 = SPC control from external source is enabled

0 = SPC control from external source is disabled

bit 5 **Unimplemented:** Read as '0'

Note 1: This bit has no function in Receive mode (RCVEN = 1).

2: This bit has no function in Transmit mode (RCVEN = 0).

19.0 32-BIT PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

Note 1: This data sheet summarizes the features of the dsPIC33CH128MP508 family of devices. It is not intended to be a comprehensive reference source. For more information, refer to "32-Bit Programmable Cyclic Redundancy Check (CRC)" (DS30009729) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip web site (www.microchip.com).

2: The CRC module is available only on the Master.

The 32-bit programmable CRC generator provides a hardware implemented method of quickly generating checksums for various networking and security applications. It offers the following features:

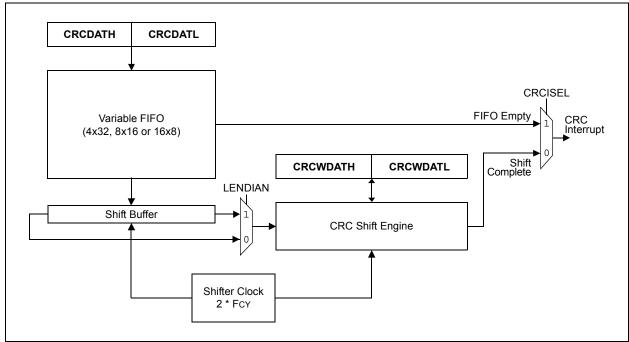
- User-Programmable CRC Polynomial Equation, up to 32 Bits
- Programmable Shift Direction (little or big-endian)
- Independent Data and Polynomial Lengths
- · Configurable Interrupt Output
- Data FIFO

A simple version of the CRC shift engine is displayed in Figure 19-1. Table 19-1 displays a simplified block diagram of the CRC generator.

TABLE 19-1: CRC MODULE OVERVIEW

	Number of CRC Modules	Identical (Modules)		
Master Core	1	Yes		
Slave Core	None	NA		





REGISTER 21-4: FOSCSEL CONFIGURATION REGISTER

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1	
_	_	_	_	_	_	_	_	
bit 23								

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1		
_	_	_	_	_	_	_	_		
bit 15 bit									

R/PO-1	U-1	U-1	U-1	U-1	R/PO-1	R/PO-1	R/PO-1
IESO	_	_	_	_	FNOSC2	FNOSC1	FNOSC0
bit 7							bit 0

Legend: PO = Program Once bit

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 23-8 **Unimplemented:** Read as '1'

bit 7 **IESO:** Internal External Switchover bit

1 = Internal External Switchover mode is enabled (Two-Speed Start-up is enabled)

0 = Internal External Switchover mode is disabled (Two-Speed Start-up is disabled)

bit 6-3 **Unimplemented:** Read as '1'

bit 2-0 FNOSC<2:0>: Initial Oscillator Source Selection bits

111 = Internal Fast RC (FRC) Oscillator with Postscaler

110 = Backup Fast RC (BFRC)

101 = LPRC Oscillator

100 = Reserved

011 = Primary Oscillator with PLL (XTPLL, HSPLL, ECPLL)

010 = Primary (XT, HS, EC) Oscillator

001 = Internal Fast RC Oscillator with PLL (FRCPLL)

000 = Fast RC (FRC) Oscillator

TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
40	DIV2.U	DIV2.U	Wm,Wn	Unsigned 16/16-bit Integer Divide (W1:W0 preserved)	1	6	N,Z,C,OV
		DIV2.UD	Wm,Wn	Unsigned 32/16-bit Integer Divide (W1:W0 preserved)	1	6	N,Z,C,OV
41	DO	DO	#lit15,Expr	Do Code to PC + Expr, lit15 + 1 Times	2	2	None
		DO	Wn,Expr	Do code to PC + Expr, (Wn) + 1 Times		2	None
42	ED	ED	Wm*Wm,Acc,Wx,Wy,Wxd	Euclidean Distance (no accumulate)	1	1	OA,OB,OAB, SA,SB,SAB
43	EDAC	EDAC	Wm*Wm,Acc,Wx,Wy,Wxd	Euclidean Distance	1	1	OA,OB,OAB, SA,SB,SAB
44	EXCH	EXCH	Wns, Wnd	Swap Wns with Wnd	1	1	None
46	FBCL	FBCL	Ws,Wnd	Find Bit Change from Left (MSb) Side	1	1	С
47	FF1L	FF1L	Ws, Wnd	Find First One from Left (MSb) Side	1	1	С
48	FF1R	FF1R	Ws, Wnd	Find First One from Right (LSb) Side	1	1	С
49	FLIM	FLIM	Wb, Ws	Force Data (Upper and Lower) Range Limit without Limit Excess Result	1	1	N,Z,OV
		FLIM.V	Wb, Ws, Wd	Force Data (Upper and Lower) Range Limit with Limit Excess Result	1	1	N,Z,OV
50	GOTO	GOTO	Expr	Go to Address	2	4/2 ⁽²⁾	None
		GOTO	Wn	Go to Indirect	1	4/2 ⁽²⁾	None
		GOTO.L	Wn	Go to Indirect (long address)	1	4/2 ⁽²⁾	None
51	INC	INC	f	f = f + 1	1	1	C,DC,N,OV,Z
		INC	f,WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		INC	Ws,Wd	Wd = Ws + 1	1	1	C,DC,N,OV,Z
52	INC2	INC2	f	f=f+2	1	1	C,DC,N,OV,Z
		INC2	f,WREG	WREG = f + 2	1	1	C,DC,N,OV,Z
		INC2	Ws,Wd	Wd = Ws + 2	1	1	C,DC,N,OV,Z
53	IOR	IOR	f	f = f .IOR. WREG	1	1	N,Z
		IOR	f,WREG	WREG = f.IOR. WREG	1	1	N,Z
		IOR	#lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N,Z
		IOR	Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N,Z
		IOR	Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N,Z
54	LAC	LAC	Wso,#Slit4,Acc	Load Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		LAC.D	Wso, #Slit4, Acc	Load Accumulator Double	1	2	OA,SA,OB,SB
55	LDSLV	LDSLV	Wso,Wdo,lit2	Move a Single Instruction Word from Master to Slave PRAM	1	1	None
56	LNK	LNK	#lit14	Link Frame Pointer	1	1	SFA
57	LSR	LSR	f	f = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	f,WREG	WREG = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	Ws,Wd	Wd = Logical Right Shift Ws	1	1	C,N,OV,Z
		LSR	Wb, Wns, Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N,Z
		LSR	Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N,Z
58	MAC	MAC	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd, AWB	Multiply and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB
		MAC	Wm*Wm,Acc,Wx,Wxd,Wy,Wyd	Square and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB
59	MAX	MAX	Acc	Force Data Maximum Range Limit	1	1	N,OV,Z
		MAX.V	Acc, Wnd	Force Data Maximum Range Limit with Result	1	1	N,OV,Z

Note 1: Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

^{2:} Cycle times for Slave core are different for Master core, as shown in 2.

^{3:} For dsPIC33CH128MP508 devices, the divide instructions must be preceded with a "REPEAT #5" instruction, such that they are executed six consecutive times

FIGURE 24-13: I2Cx BUS START/STOP BITS TIMING CHARACTERISTICS (MASTER MODE)

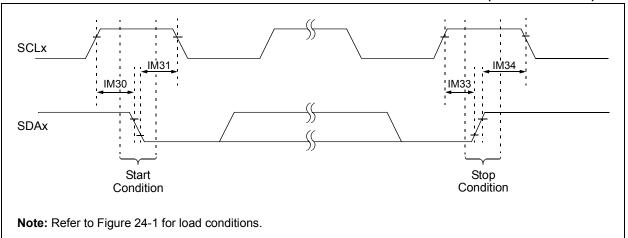
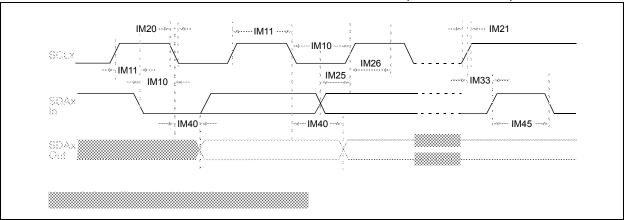
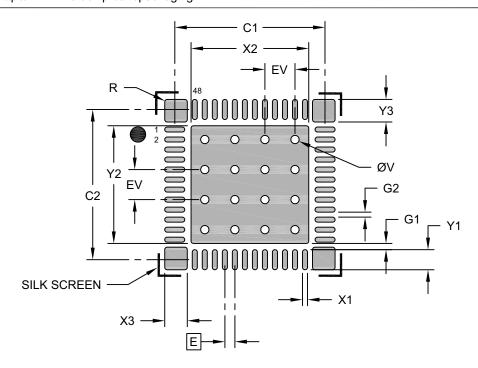


FIGURE 24-14: I2Cx BUS DATA TIMING CHARACTERISTICS (MASTER MODE)



48-Lead Ultra Thin Plastic Quad Flat, No Lead Package (M4) - 6x6 mm Body [UQFN] With Corner Anchors and 4.6x4.6 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	Units			
Dimension	MIN	NOM	MAX	
Contact Pitch	E		0.40 BSC	
Center Pad Width	X2			4.70
Center Pad Length	Y2			4.70
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X48)	X1			0.20
Contact Pad Length (X48)	Y1			0.80
Corner Anchor Pad Width (X4)	Х3			0.90
Corner Anchor Pad Length (X4)	Y3			0.90
Pad Corner Radius (X 20)	R			0.10
Contact Pad to Center Pad (X48)	G1	0.25		
Contact Pad to Contact Pad	G2	0.20		
Thermal Via Diameter	V		0.33	
Thermal Via Pitch	EV		1.20	

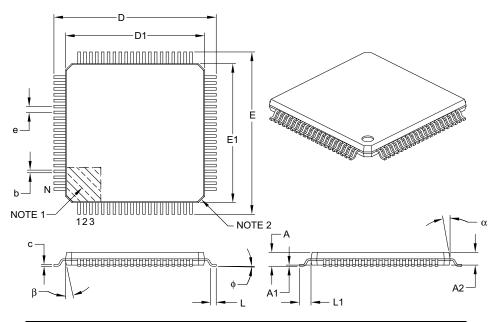
Notes:

- Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- 2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2442A-M4

80-Lead Plastic Thin Quad Flatpack (PT) - 12x12x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS		
	Dimension Limits	MIN	NOM	MAX
Number of Leads	N	80		
Lead Pitch	е	0.50 BSC		
Overall Height	Α	1	_	1.20
Molded Package Thickness	A2	0.95	1.00	1.05
Standoff	A1	0.05	_	0.15
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	ф	0°	3.5°	7°
Overall Width	E	14.00 BSC		
Overall Length	D	14.00 BSC		
Molded Package Width	E1	12.00 BSC		
Molded Package Length	D1	12.00 BSC		
Lead Thickness	С	0.09	_	0.20
Lead Width	b	0.17	0.22	0.27
Mold Draft Angle Top	α	11°	12°	13°
Mold Draft Angle Bottom	β	11°	12°	13°

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Chamfers at corners are optional; size may vary.
- 3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-092B