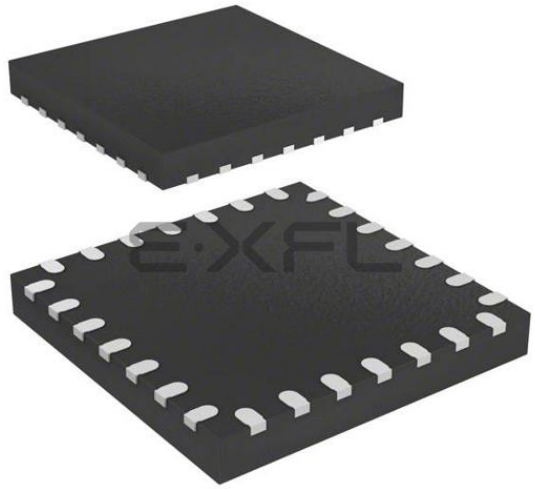

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	16MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Infrared, POR, PWM, WDT
Number of I/O	26
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UFQFN
Supplier Device Package	28-UFQFPN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8l101g3u6tr

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2 Description

The STM8L101x1 STM8L101x2 STM8L101x3 low-power family features the enhanced STM8 CPU core providing increased processing power (up to 16 MIPS at 16 MHz) while maintaining the advantages of a CISC architecture with improved code density, a 24-bit linear addressing space and an optimized architecture for low power operations.

The family includes an integrated debug module with a hardware interface (SWIM) which allows non-intrusive in-application debugging and ultrafast Flash programming.

All STM8L101xx microcontrollers feature low power low-voltage single-supply program Flash memory. The 8-Kbyte devices embed data EEPROM.

The STM8L101xx low power family is based on a generic set of state-of-the-art peripherals. The modular design of the peripheral set allows the same peripherals to be found in different ST microcontroller families including 32-bit families. This makes any transition to a different family very easy, and simplified even more by the use of a common set of development tools.

All STM8L low power products are based on the same architecture with the same memory mapping and a coherent pinout.

Table 2. STM8L101xx device feature summary

Features	STM8L101xx		
Flash	2 Kbytes of Flash program memory	4 Kbytes of Flash program memory	8 Kbytes of Flash program memory including up to 2 Kbytes of Data EEPROM
RAM	1.5 Kbytes		
Peripheral functions	Independent watchdog (IWDG), Auto-wakeup unit (AWU), Beep, Serial peripheral interface (SPI), Inter-integrated circuit (I²C), Universal synchronous / asynchronous receiver / transmitter (USART), 2 comparators, Infrared (IR) interface		
Timers	Two 16-bit timers, one 8-bit timer		
Operating voltage	1.65 to 3.6 V		
Operating temperature	-40 to +85 °C		-40 to +85 °C or -40 to +125 °C
Packages	UFQFPN20 3x3	UFQFPN28 4x 4 UFQFPN20 3x3 TSSOP20 4.4 x 6.4	UFQFPN28 4x4 UFQFPN20 3x3 UFQFPN32 LQFP32

3.5 Memory

The STM8L101xx devices have the following main features:

- 1.5 Kbytes of RAM
- The EEPROM is divided into two memory arrays (see the STM8L reference manual for details on the memory mapping):
  - Up to 8 Kbytes of low-density embedded Flash program including up to 2 Kbytes of data EEPROM. Data EEPROM and Flash program areas can be write protected independently by using the memory access security mechanism (MASS).
  - 64 option bytes (one block) of which 5 bytes are already used for the device.

Error correction code is implemented on the EEPROM.

3.6 Low power modes

To minimize power consumption, the product features three low power modes:

- Wait mode: CPU clock stopped, selected peripherals at full clock speed.
- Active-halt mode: CPU and peripheral clocks are stopped. The programmable wakeup time is controlled by the AWU unit.
- Halt mode: CPU and peripheral clocks are stopped, the device remains powered on. The RAM content is preserved. Wakeup is triggered by an external interrupt.

3.7 Voltage regulators

The STM8L101xx embeds an internal voltage regulator for generating the 1.8 V power supply for the core and peripherals.

This regulator has two different modes: main voltage regulator mode (MVR) and low power voltage regulator mode (LPVR). When entering Halt or Active-halt modes, the system automatically switches from the MVR to the LPVR in order to reduce current consumption.

3.8 Clock control

The STM8L101xx embeds a robust clock controller. It is used to distribute the system clock to the core and the peripherals and to manage clock gating for low power modes. This system clock is a 16-MHz High Speed Internal RC oscillator (HSI RC), followed by a programmable prescaler.

In addition, a 38 kHz low speed internal RC oscillator is used by the independent watchdog (IWDG) and Auto-wakeup unit (AWU).

3.9 Independent watchdog

The independent watchdog (IWDG) peripheral can be used to resolve processor malfunctions due to hardware or software failures.

It is clocked by the 38 kHz LSI internal RC clock source, and thus stays active even in case of a CPU clock failure.

3.15 USART

The USART interface (USART) allows full duplex, asynchronous communications with external devices requiring an industry standard NRZ asynchronous serial data format. It offers a very wide range of baud rates.

3.16 SPI

The serial peripheral interface (SPI) provides half/ full duplex synchronous serial communication with external devices. It can be configured as the master and in this case it provides the communication clock (SCK) to the external slave device. The interface can also operate in multi-master configuration.

3.17 I²C

The inter-integrated circuit (I2C) bus interface is designed to serve as an interface between the microcontroller and the serial I^2C bus. It provides multi-master capability, and controls all I²C bus-specific sequencing, protocol, arbitration and timing. It manages standard and fast speed modes.

Table 4. STM8L101xx pin description (continued)

Pin number						Pin name	Type	Input			Output			Main function (after reset)	Alternate function
standard UFQFPN20	UFQFPN20 with COMP_REF(1)	TSSOP20	standard UFQFPN28	UFQFPN28 with COMP_REF(1)	UFQFPN32 or LQFP32			floating	wpu	Ext. interrupt	High sink/source	OD	PP		
-	-	-	26	26	30	PC5	I/O	**X**	X	X	HS	X	X	**Port C5**	-
-	-	-	27	27	31	PC6	I/O	**X**	X	X	HS	X	X	**Port C6**	-
20	20	3	28	28	32	PA0(5)/SWIM/ BEEP/IR_TIM (6)	I/O	X	**X**(5)	X	HS(6)	X	X	**Port A0**	SWIM input and output /Beep output/Timer Infrared output

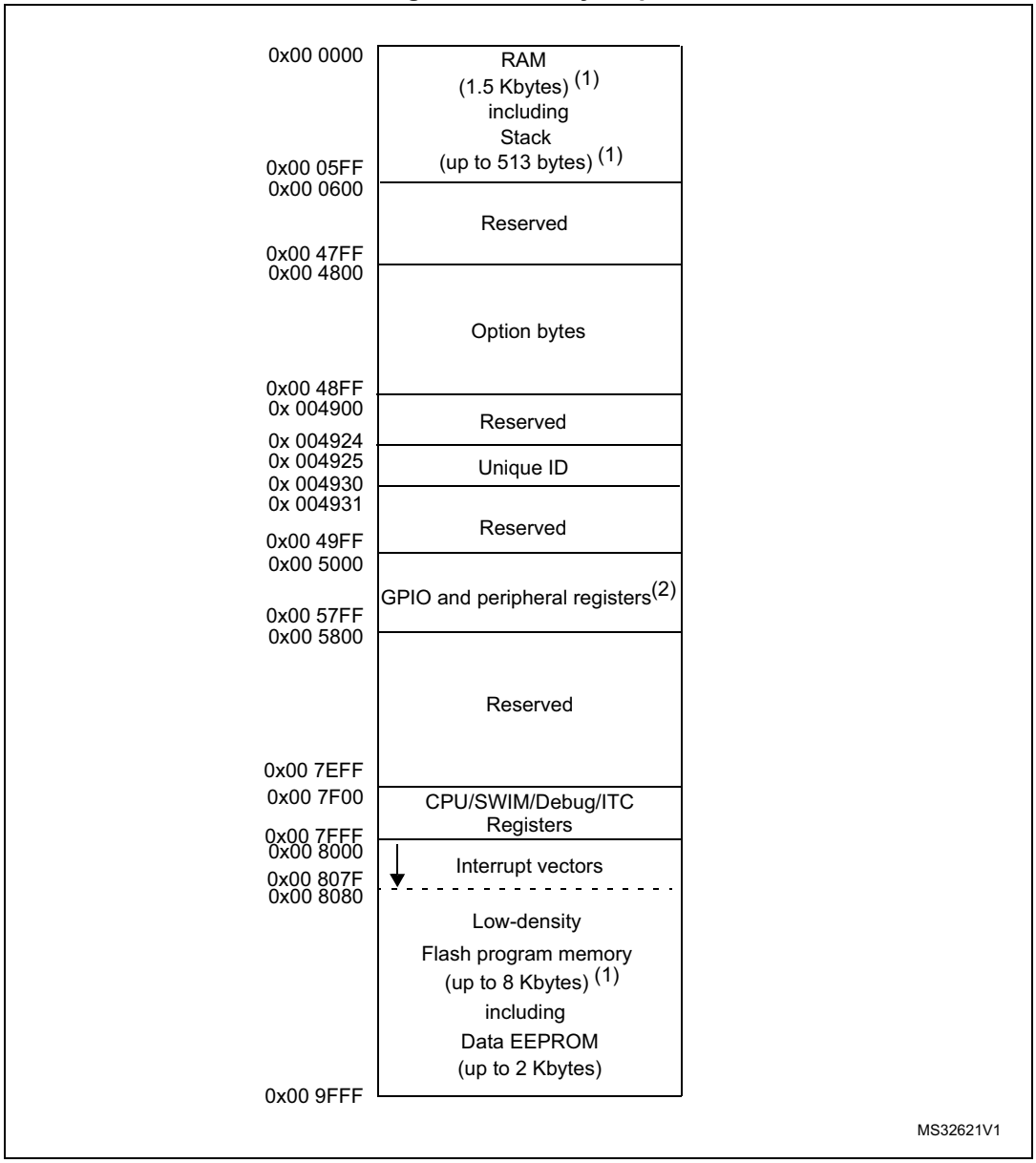
1. Please refer to the warning below.
2. At power-up, the PA1/NRST pin is a reset input pin with pull-up. To be used as a general purpose pin (PA1), it can be configured only as a general purpose pin (PA1), it can be configured only as output push-pull, not neither as output open-drain nor as a general purpose input. Refer to Section *Configuring NRST/PA1 pin as general purpose output* in the STM8L reference manual (RM0013).
3. A pull-up is applied to PB0 and PB4 during the reset phase. These two pins are input floating after reset release.
4. In the open-drain output column, 'T' defines a true open-drain I/O (P-buffer, weak pull-up and protection diode to V_{DD} are not implemented).
5. The PA0 pin is in input pull-up during the reset phase and after reset release.
6. High sink LED driver capability available on PA0.

Slope control of all GPIO pins can be programmed except true open drain pins and by default is limited to 2 MHz.

Warning: For the STM8L101F1U6ATR, STM8L101F2U6ATR, STM8L101F3U6ATR, STM8L101G2U6ATR and STM8L101G3U6ATR part numbers (devices with COMP_REF pin), all ports available on 32-pin packages must be considered as active ports. To avoid spurious effects, the user has to configure them as input pull-up. A small increase in consumption (typ. < 300 µA) may occur during the power up and reset phase until these ports are properly configured.

5 Memory and register map

Figure 8. Memory map



1. *Table 5* lists the boundary addresses for each memory size. The top of the stack is at the RAM end address.
2. Refer to *Table 7* for an overview of hardware register mapping, to *Table 6* for details on I/O port hardware registers, and to *Table 8* for information on CPU/SWIM/debug module controller registers.

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5280	TIM3	TIM3_CR1	TIM3 control register 1	0x00
0x00 5281		TIM3_CR2	TIM3 control register 2	0x00
0x00 5282		TIM3_SMCR	TIM3 slave mode control register	0x00
0x00 5283		TIM3_ETR	TIM3 external trigger register	0x00
0x00 5284		TIM3_IER	TIM3 interrupt enable register	0x00
0x00 5285		TIM3_SR1	TIM3 status register 1	0x00
0x00 5286		TIM3_SR2	TIM3 status register 2	0x00
0x00 5287		TIM3_EGR	TIM3 event generation register	0x00
0x00 5288		TIM3_CCMR1	TIM3 capture/compare mode register 1	0x00
0x00 5289		TIM3_CCMR2	TIM3 capture/compare mode register 2	0x00
0x00 528A		TIM3_CCER1	TIM3 capture/compare enable register 1	0x00
0x00 528B		TIM3_CNTRH	TIM3 counter high	0x00
0x00 528C		TIM3_CNTRL	TIM3 counter low	0x00
0x00 528D		TIM3_PSCR	TIM3 prescaler register	0x00
0x00 528E		TIM3_ARRH	TIM3 auto-reload register high	0xFF
0x00 528F		TIM3_ARRL	TIM3 auto-reload register low	0xFF
0x00 5290		TIM3_CCR1H	TIM3 capture/compare register 1 high	0x00
0x00 5291		TIM3_CCR1L	TIM3 capture/compare register 1 low	0x00
0x00 5292		TIM3_CCR2H	TIM3 capture/compare register 2 high	0x00
0x00 5293		TIM3_CCR2L	TIM3 capture/compare register 2 low	0x00
0x00 5294		TIM3_BKR	TIM3 break register	0x00
0x00 5295		TIM3_OISR	TIM3 output idle state register	0x00
0x00 5296 to 0x00 52DF	Reserved area (74 bytes)			
0x00 52E0	TIM4	TIM4_CR1	TIM4 control register 1	0x00
0x00 52E1		TIM4_CR2	TIM4 control register 2	0x00
0x00 52E2		TIM4_SMCR	TIM4 Slave mode control register	0x00
0x00 52E3		TIM4_IER	TIM4 interrupt enable register	0x00
0x00 52E4		TIM4_SR1	TIM4 Status register 1	0x00
0x00 52E5		TIM4_EGR	TIM4 event generation register	0x00
0x00 52E6		TIM4_CNTR	TIM4 counter	0x00
0x00 52E7		TIM4_PSCR	TIM4 prescaler register	0x00
0x00 52E8		TIM4_ARR	TIM4 auto-reload register low	0xFF

Table 8. CPU/SWIM/debug module/interrupt controller registers (continued)

Address	Block	Register label	Register name	Reset status
0x00 7F78 to 0x00 7F79	Reserved area (2 bytes)			
0x00 7F80	SWIM	SWIM_CSR	SWIM control status register	0x00
0x00 7F81 to 0x00 7F8F	Reserved area (15 bytes)			
0x00 7F90	DM	DM_BK1RE	Breakpoint 1 register extended byte	0xFF
0x00 7F91		DM_BK1RH	Breakpoint 1 register high byte	0xFF
0x00 7F92		DM_BK1RL	Breakpoint 1 register low byte	0xFF
0x00 7F93		DM_BK2RE	Breakpoint 2 register extended byte	0xFF
0x00 7F94		DM_BK2RH	Breakpoint 2 register high byte	0xFF
0x00 7F95		DM_BK2RL	Breakpoint 2 register low byte	0xFF
0x00 7F96		DM_CR1	Debug module control register 1	0x00
0x00 7F97		DM_CR2	Debug module control register 2	0x00
0x00 7F98		DM_CSR1	Debug module control/status register 1	0x10
0x00 7F99		DM_CSR2	Debug module control/status register 2	0x00
0x00 7F9A		DM_ENFCTR	Enable function register	0xFF

1. Refer to *Table 7: General hardware register map on page 25* (addresses 0x00 50A0 to 0x00 50A5) for a list of external interrupt registers.

7 Option bytes

Option bytes contain configurations for device hardware features as well as the memory protection of the device. They are stored in a dedicated row of the memory.

All option bytes can be modified only in ICP mode (with SWIM) by accessing the EEPROM address. See *Table 10* for details on option byte addresses.

Refer to the STM8L Flash programming manual (PM0054) and STM8 SWIM and Debug Manual (UM0470) for information on SWIM programming procedures.

Table 10. Option bytes

Addr.	Option name	Option byte No.	Option bits								Factory default setting
			7	6	5	4	3	2	1	0	
0x4800	Read-out protection (ROP)	OPT1	ROP[7:0]								0x00
0x4807	-	-	Must be programmed to 0x00								0x00
0x4802	UBC (User Boot code size)	OPT2	UBC[7:0]								0x00
0x4803	DATASIZE	OPT3	DATASIZE[7:0]								0x00
0x4808	Independent watchdog option	OPT4 [1:0]	Reserved						IWDG _HALT	IWDG _HW	0x00

Table 11. Option byte description

OPT1	**ROP[7:0]** *Memory readout protection (ROP)* 0xAA: Enable readout protection (write access via SWIM protocol) Refer to *Read-out protection* section in the STM8L reference manual (RM0013) for details.
OPT2	**UBC[7:0]** *Size of the user boot code area* 0x00: no UBC 0x01-0x02: UBC contains only the interrupt vectors. 0x03: Page 0 and 1 reserved for the interrupt vectors. Page 2 is available to store user boot code. Memory is write protected ... 0x7F - Page 0 to 126 reserved for UBC, memory is write protected Refer to *User boot area (UBC)* section in the STM8L reference manual (RM0013) for more details. UBC[7] is forced to 0 internally by HW.

8 Unique ID

STM8L101xx devices feature a 96-bit unique device identifier which provides a reference number that is unique for any device and in any context. The 96 bits of the identifier can never be altered by the user.

The unique device identifier can be read in single bytes and may then be concatenated using a custom algorithm.

The unique device identifier is ideally suited:

- For use as serial numbers
- For use as security keys to increase the code security in the program memory while using and combining this unique ID with software cryptographic primitives and protocols before programming the internal memory
- To activate secure boot processes.

Table 12. Unique ID registers (96 bits)

Address	Content description	Unique ID bits							
		7	6	5	4	3	2	1	0
0x4925	X co-ordinate on the wafer	U_ID[7:0]							
0x4926		U_ID[15:8]							
0x4927	Y co-ordinate on the wafer	U_ID[23:16]							
0x4928		U_ID[31:24]							
0x4929	Wafer number	U_ID[39:32]							
0x492A	Lot number	U_ID[47:40]							
0x492B		U_ID[55:48]							
0x492C		U_ID[63:56]							
0x492D		U_ID[71:64]							
0x492E		U_ID[79:72]							
0x492F		U_ID[87:80]							
0x4930		U_ID[95:88]							

9 Electrical parameters

9.1 Parameter conditions

Unless otherwise specified, all voltages are referred to V_{SS}.

9.1.1 Minimum and maximum values

Unless otherwise specified the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at T_A= 25 °C and T_A = T_A max (given by the selected temperature range).

Note: The values given at 85 °C <T_A ≤ 125 °C are only valid for suffix 3 versions.

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean±3Σ).

9.1.2 Typical values

Unless otherwise specified, typical data are based on T_A = 25 °C, V_{DD} = 3 V. They are given only as design guidelines and are not tested.

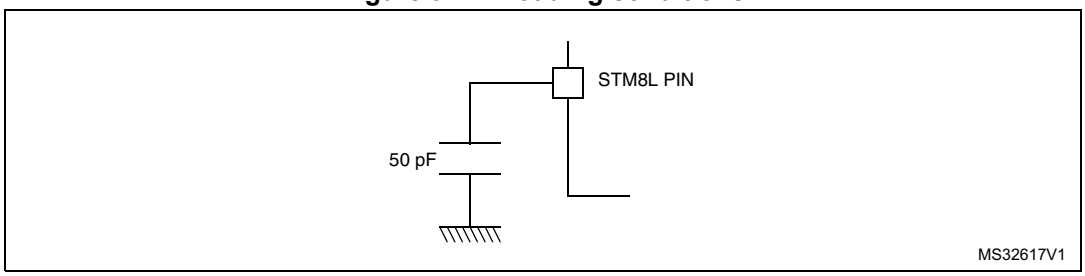
9.1.3 Typical curves

Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

9.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in *Figure 9*.

Figure 9. Pin loading conditions



Current consumption of on-chip peripherals

Measurement made for f_{MASTER} = from 2 MHz to 16 MHz

Table 21. Peripheral current consumption

Symbol	Parameter	Typ. V_{DD} = 3.0 V	Unit
$I_{DD(TIM2)}$	TIM2 supply current (1)	9	µA/MHz
$I_{DD(TIM3)}$	TIM3 supply current (1)	9	
$I_{DD(TIM4)}$	TIM4 timer supply current (1)	4	
$I_{DD(USART)}$	USART supply current (2)	7	
$I_{DD(SPI)}$	SPI supply current (2)	4	
$I_{DD(I^2C1)}$	I2C supply current (2)	4	
$I_{DD(COMP)}$	Comparator supply current (2)	20	µA

1. Data based on a differential I_{DD} measurement between all peripherals off and a timer counter running at 16 MHz. The CPU is in Wait mode in both cases. No IC/OC programmed, no I/O pin toggling. Not tested in production.
2. Data based on a differential I_{DD} measurement between the on-chip peripheral when kept under reset and not clocked and the on-chip peripheral when clocked and not kept under reset. The CPU is in Wait mode in both cases. No I/O pin toggling. Not tested in production.

9.3.4 Clock and timing characteristics

Internal clock sources

Subject to general operating conditions for V_{DD} and T_A.

High speed internal RC oscillator (HSI)

Table 22. HSI oscillator characteristics (1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI}	Frequency	V_{DD} = 3.0 V	-	16	-	MHz
ACC_{HSI}	Accuracy of HSI oscillator (factory calibrated)	V_{DD} = 3.0 V, T_A = 25 °C	-1	-	1	%
		V_{DD} = 3.0 V, -10 °C ≤T_A ≤ 85 °C	-2.5(2)	-	2(2)	%
		V_{DD} = 3.0 V, -10 °C ≤T_A ≤ 125 °C	-4.5(2)	-	2(2)	%
		V_{DD} = 3.0 V, 0 °C ≤T_A ≤ 55 °C	-1.5(2)	-	1.5(2)	%
		V_{DD} = 3.0 V, -10 °C ≤T_A ≤ 70 °C	-2(2)	-	2(2)	%
		1.65 V ≤ V_{DD} ≤ 3.6 V, -40 °C ≤ T_A ≤125 °C	-4.5(2)	-	3(2)	%
$I_{DD(HSI)}$	HSI oscillator power consumption	-	-	70	100(2)	µA

1. V_{DD} = 3.0 V, T_A = -40 to 125 °C unless otherwise specified.
2. Data based on characterization results, not tested in production.

Figure 24. Typ. V_{OL} at V_{DD} = 3.0 V (High sink ports)

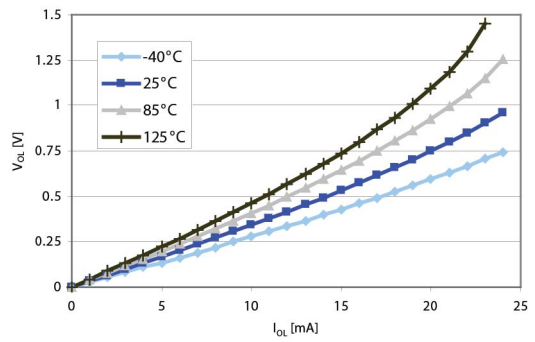


Figure 25. Typ. V_{OL} at V_{DD} = 1.8 V (High sink ports)

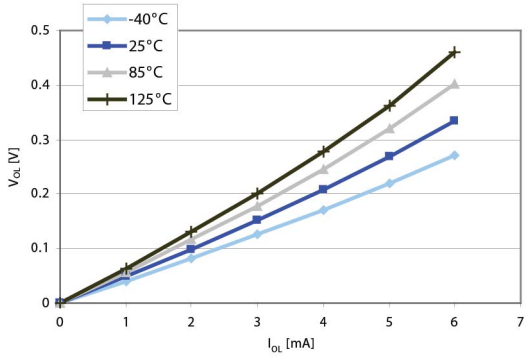


Figure 26. Typ. V_{OL} at V_{DD} = 3.0 V (true open drain ports)

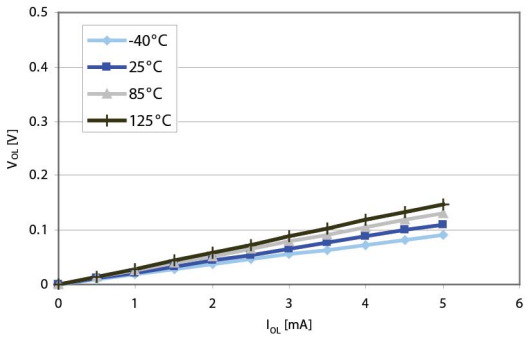


Figure 27. Typ. V_{OL} at V_{DD} = 1.8 V (true open drain ports)

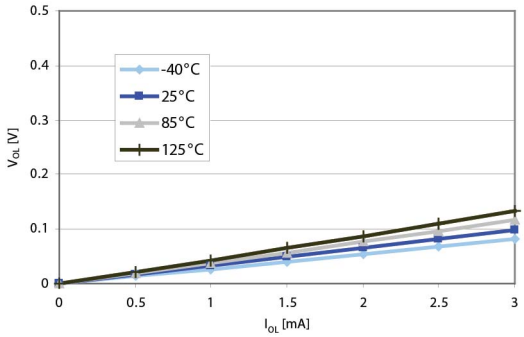


Figure 28. Typ. V_{DD} - V_{OH} at V_{DD} = 3.0 V (High sink ports)

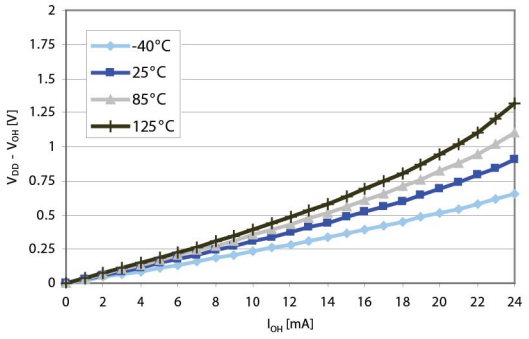
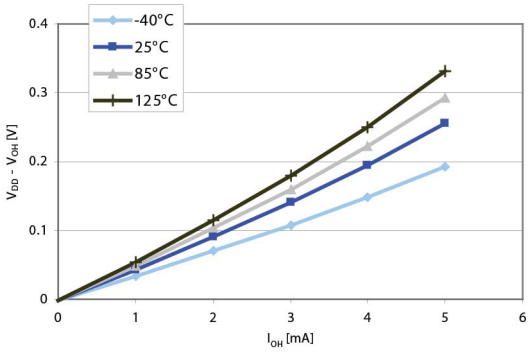


Figure 29. Typ. V_{DD} - V_{OH} at V_{DD} = 1.8 V (High sink ports)



NRST pin

The NRST pin input driver is CMOS. A permanent pull-up is present.
$R_{PU(NRST)}$ has the same value as R_{PU} (see *Table 26 on page 48*).

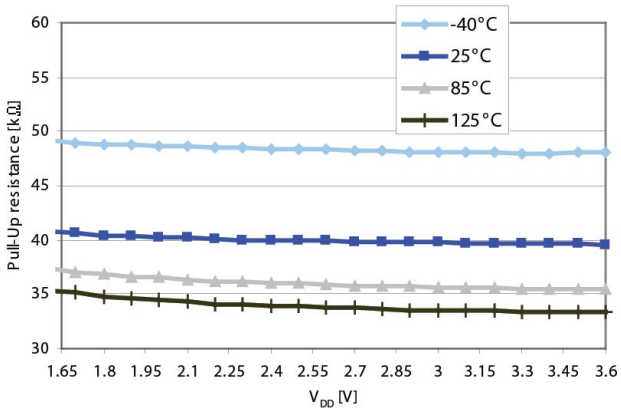
Subject to general operating conditions for V_{DD} and T_A unless otherwise specified.

Table 30. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ (1)	Max	Unit
$V_{IL(NRST)}$	NRST input low level voltage (1)	-	V_{SS}	-	0.8	V
$V_{IH(NRST)}$	NRST input high level voltage (1)	-	1.4	-	V_{DD}	
$V_{OL(NRST)}$	NRST output low level voltage	I_{OL} = 2 mA	-	-	V_{DD}-0.8	
$R_{PU(NRST)}$	NRST pull-up equivalent resistor (2)	-	30	45	60	kΩ
$V_{F(NRST)}$	NRST input filtered pulse (3)	-	-	-	50	ns
$t_{OP(NRST)}$	NRST output pulse width	-	20	-	-	ns
$V_{NF(NRST)}$	NRST input not filtered pulse (3)	-	300	-	-	ns

1. Data based on characterization results, not tested in production.
2. The R_{PU} pull-up equivalent resistor is based on a resistive transistor (*Figure 30*). Corresponding I_{PU} current characteristics are described in *Figure 31*.
3. Data guaranteed by design, not tested in production.

Figure 30. Typical NRST pull-up resistance R_{PU} vs. V_{DD}



Static latch-up

- **LU**: 2 complementary static tests are required on 10 parts to assess the latch-up performance. A supply overvoltage (applied to each power supply pin) and a current injection (applied to each input, output and configurable I/O pin) are performed on each sample. This test conforms to the EIA/JESD 78 IC latch-up standard. For more details, refer to the application note AN1181.

Table 37. Electrical sensitivities

Symbol	Parameter	Class
LU	Static latch-up class	II

9.4 Thermal characteristics

The maximum chip junction temperature (T_{Jmax}) must never exceed the values given in *Table 16: General operating conditions on page 40*.

The maximum chip-junction temperature, T_{Jmax}, in degrees Celsius, may be calculated using the following equation:

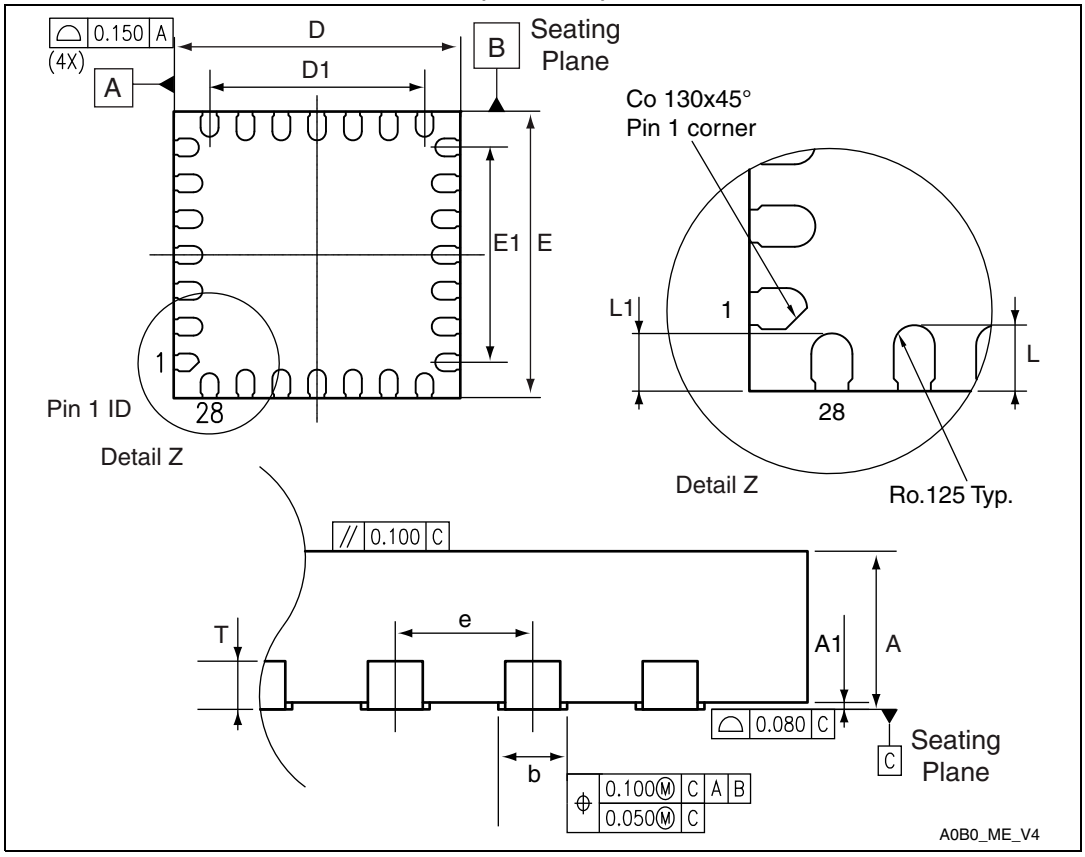
$T_{Jmax} = T_{Amax} + (P_{Dmax} \times \Theta_{JA})$

Where:

- T_{Amax} is the maximum ambient temperature in °C
- Θ_{JA} is the package junction-to-ambient thermal resistance in °C/W
- P_{Dmax} is the sum of P_{INTmax} and $P_{I/Omax}$ ($P_{Dmax} = P_{INTmax} + P_{I/Omax}$)
- P_{INTmax} is the product of I_{DD} and V_{DD}, expressed in watts. This is the maximum chip internal power.
- $P_{I/Omax}$ represents the maximum power dissipation on output pins
  where:
  $P_{I/Omax} = \Sigma (V_{OL}*I_{OL}) + \Sigma((V_{DD}-V_{OH})*I_{OH})$,
  taking into account the actual V_{OL}/I_{OL} and V_{OH}/I_{OH} of the I/Os at low and high level in the application.

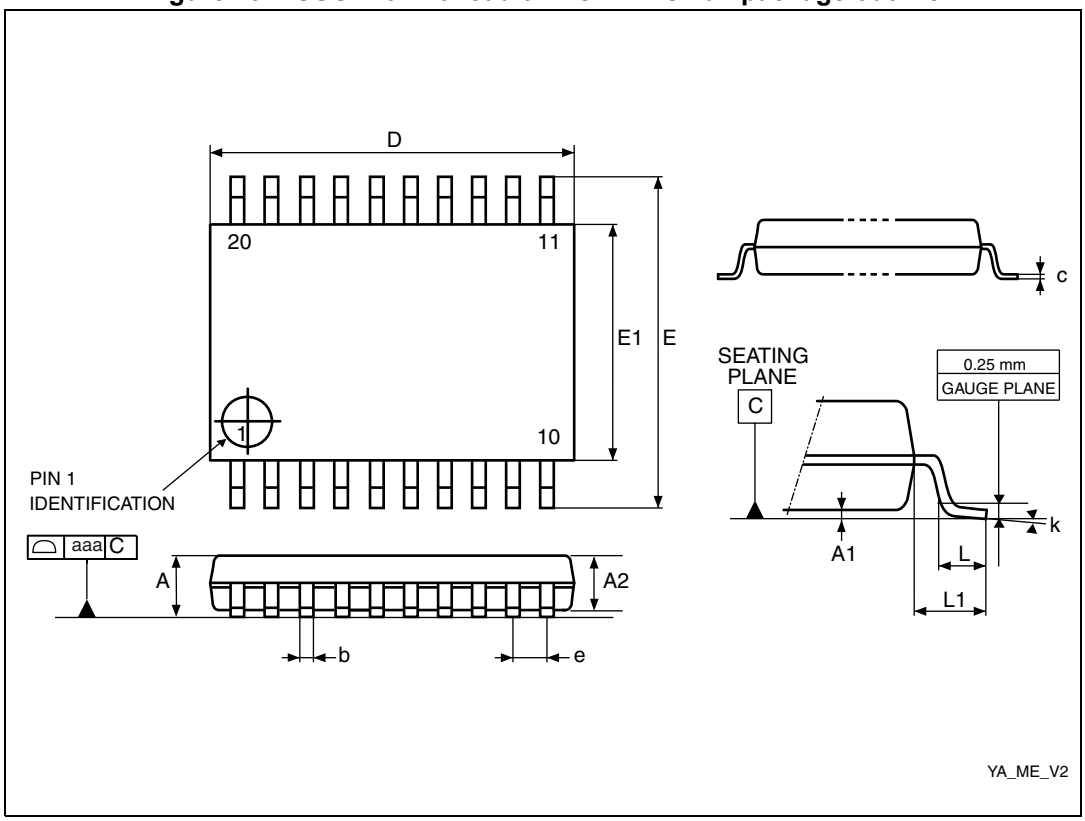
10.3 UFQFPN28 package information

Figure 43. UFQFPN28 - 28-lead ultra thin fine pitch quad flat no-lead package outline (4 x 4 mm)



10.5 TSSOP20 package information

Figure 49. TSSOP20 - 20-lead thin shrink small package outline



1. Drawing is not to scale.

Table 43. TSSOP20 - 20-lead thin shrink small package mechanical data

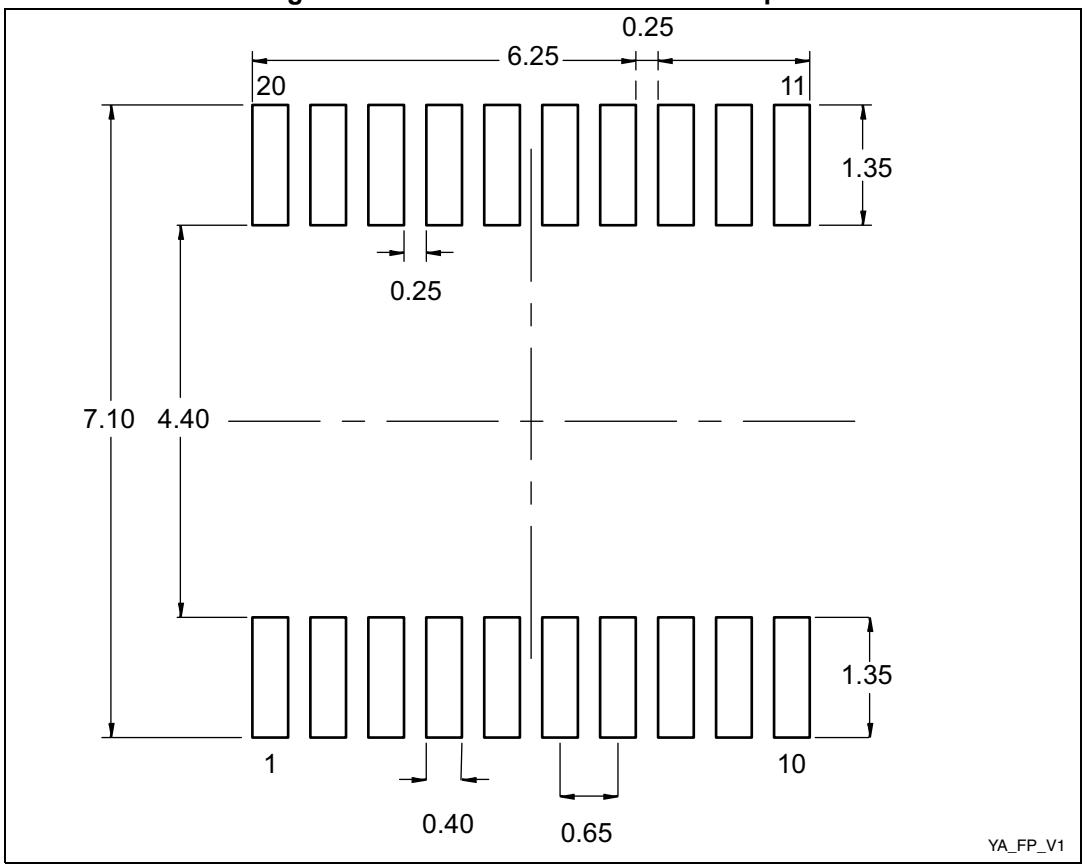
Dim.	mm				inches(1)	
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.200	-	-	0.0472
A1	0.050	-	0.150	0.0020	-	0.0059
A2	0.800	1.000	1.050	0.0315	0.0394	0.0413
b	0.190	-	0.300	0.0075	-	0.0118
CP	-	-	0.100	-	-	0.0039
c	0.090	-	0.200	0.0035	-	0.0079
D(2)	6.400	6.500	6.600	0.2520	0.2559	0.2598
E	6.200	6.400	6.600	0.2441	0.2520	0.2598
E1(3)	4.300	4.400	4.500	0.1693	0.1732	0.1772
e	-	0.650	-	0.1693	0.0256	-
L	0.450	0.600	0.750	0.1693	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-

Table 43. TSSOP20 - 20-lead thin shrink small package mechanical data (continued)

Dim.	mm				inches[1]	
	Min	Typ	Max	Min	Typ	Max
k	0°	-	8°	0°	-	8°
aaa	-	-	0.100	-	-	0.0039
Number of pins	20					

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. Dimension “D” does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15mm per side.
3. Dimension “E1” does not include interlead flash or protrusions. Interlead flash or protrusions shall not exceed 0.25mm per side.

Figure 50. TSSOP20 recommended footprint

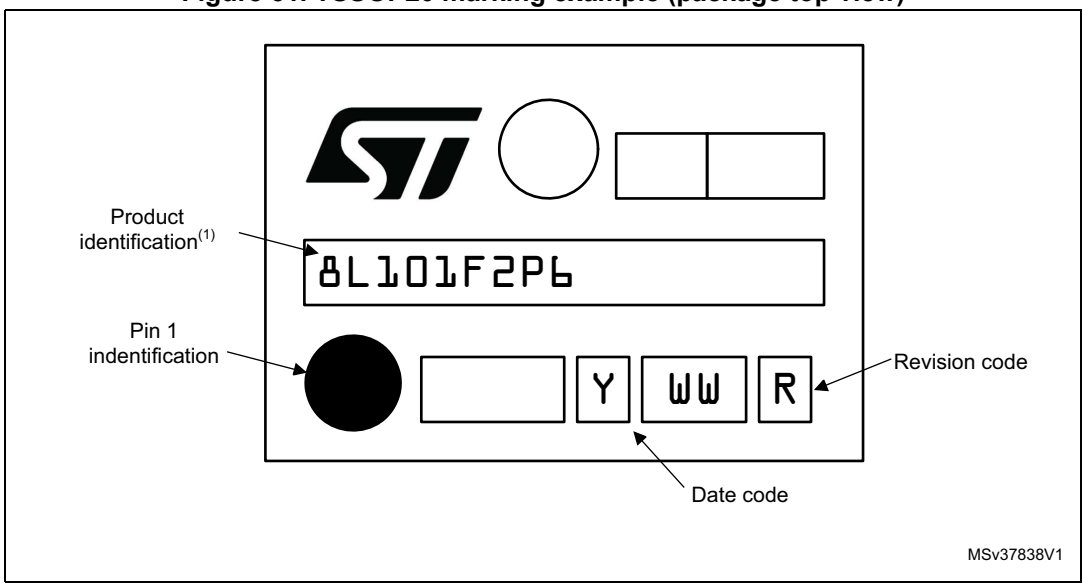


1. Dimensions are in millimeters.

Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Figure 51. TSSOP20 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

13 Revision history

Table 44. Document revision history

Date	Revision	Changes
19-Dec-2008	1	Initial release.
22-Apr-2009	2	Added TSSOP28 package Modified packages on first page COMPx_OUT pins removed Added *Figure 6: 28-pin TSSOP package pinout on page 17* Modified *Section 9: Electrical parameters on page 37*. Updated UBC[7:0] description in *Section 7: Option bytes*. Updated low power current consumption on cover page. Updated *Table 13: Voltage characteristics*, *Table 20: Total current consumption and timing in Halt and Active-halt mode at VDD = 1.65 V to 3.6 V*, *Table 26: I/O static characteristics*, *Table 30: NRST pin characteristics*, and *Section 9.3.9: EMC characteristics*. Updated PA1/NRST, PC0 and PC1 in *Table 4: STM8L101xx pin description*. Added ECC feature. Changed internal RC frequency to 38 kHz. Updated electrical characteristics in *Table 16*, *Table 18*, *Table 19*, *Table 20*, *Table 22*, *Table 23*, and *Table 26*.
24-Apr-2009	3	Corrected title on cover page. Changed VFQFPN32 to WFQFPN32 and updated *Table 39: UFQFPN32 - 32-lead ultra thin fine pitch quad flat no-lead package (5 x 5), package mechanical data*. Updated *Table 13*, *Table 26*, and *Table 33*.
14-May-2009	4	Replaced WFQFPN20 3 x 3 mm 0.8 mm package by UFQFPN20 3 x 3 mm 0.6 mm package (first page, *Table 16: General operating conditions on page 40*, *Table 38: Thermal characteristics on page 63*, *Section 10.2: Package mechanical data on page 67*) Added one UFQFPN20 version with COMP_REF Modified *Figure 40: LQFP32 recommended footprint(1) on page 69* Added I_{PROG} values in *Table 25: Flash program memory on page 47* Updated *Table 31: SPI characteristics on page 55*
15-May-2009	5	Added STM8L101F3U6ATR part number in *Section 4: Pin description on page 15* and in *Figure 47: STM8L101xx ordering information scheme on page 74*