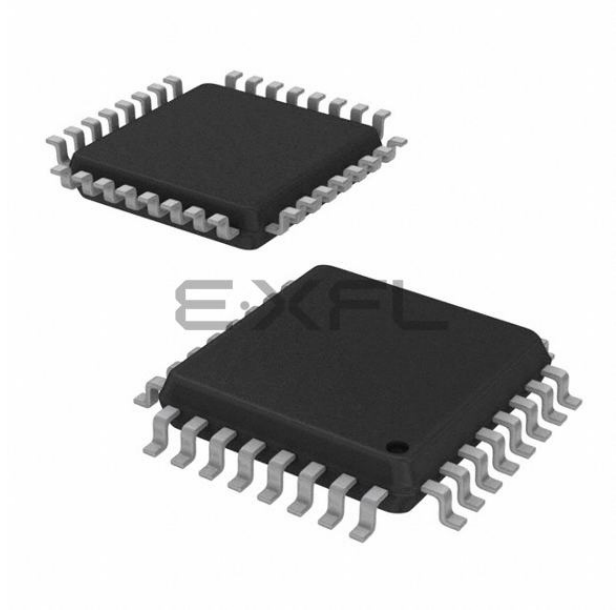


Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

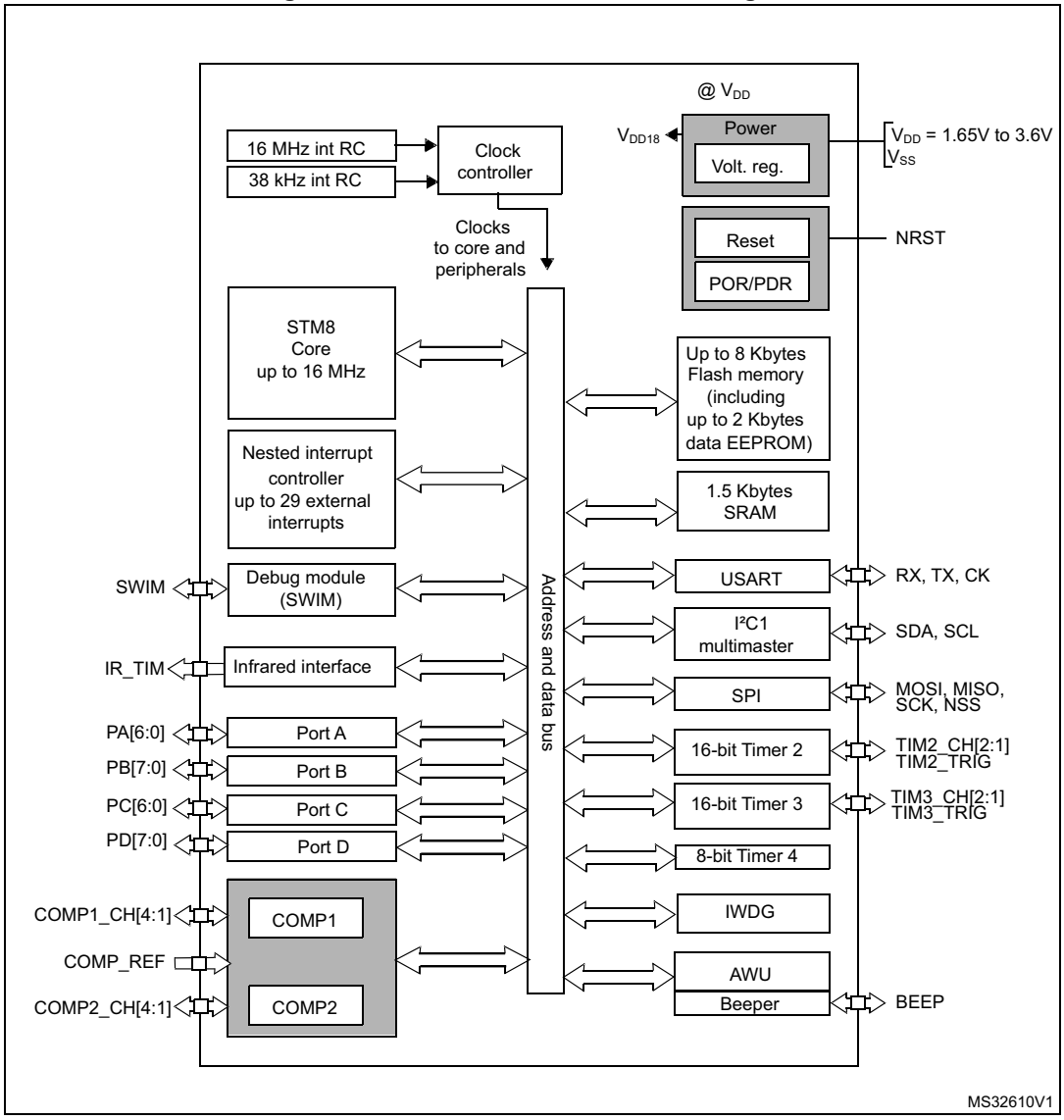
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	16MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Infrared, POR, PWM, WDT
Number of I/O	30
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8l101k3t3

List of figures

3 Product overview

Figure 1. STM8L101xx device block diagram



Legend:

AWU: Auto-wakeup unit
Int. RC: internal RC oscillator
I²C: Inter-integrated circuit multimaster interface
POR/PDR: Power on reset / power down reset
SPI: Serial peripheral interface
SWIM: Single wire interface module
USART: Universal synchronous / asynchronous receiver / transmitter
IWDG: Independent watchdog

3.5 Memory

The STM8L101xx devices have the following main features:

- 1.5 Kbytes of RAM
- The EEPROM is divided into two memory arrays (see the STM8L reference manual for details on the memory mapping):
  - Up to 8 Kbytes of low-density embedded Flash program including up to 2 Kbytes of data EEPROM. Data EEPROM and Flash program areas can be write protected independently by using the memory access security mechanism (MASS).
  - 64 option bytes (one block) of which 5 bytes are already used for the device.

Error correction code is implemented on the EEPROM.

3.6 Low power modes

To minimize power consumption, the product features three low power modes:

- Wait mode: CPU clock stopped, selected peripherals at full clock speed.
- Active-halt mode: CPU and peripheral clocks are stopped. The programmable wakeup time is controlled by the AWU unit.
- Halt mode: CPU and peripheral clocks are stopped, the device remains powered on. The RAM content is preserved. Wakeup is triggered by an external interrupt.

3.7 Voltage regulators

The STM8L101xx embeds an internal voltage regulator for generating the 1.8 V power supply for the core and peripherals.

This regulator has two different modes: main voltage regulator mode (MVR) and low power voltage regulator mode (LPVR). When entering Halt or Active-halt modes, the system automatically switches from the MVR to the LPVR in order to reduce current consumption.

3.8 Clock control

The STM8L101xx embeds a robust clock controller. It is used to distribute the system clock to the core and the peripherals and to manage clock gating for low power modes. This system clock is a 16-MHz High Speed Internal RC oscillator (HSI RC), followed by a programmable prescaler.

In addition, a 38 kHz low speed internal RC oscillator is used by the independent watchdog (IWDG) and Auto-wakeup unit (AWU).

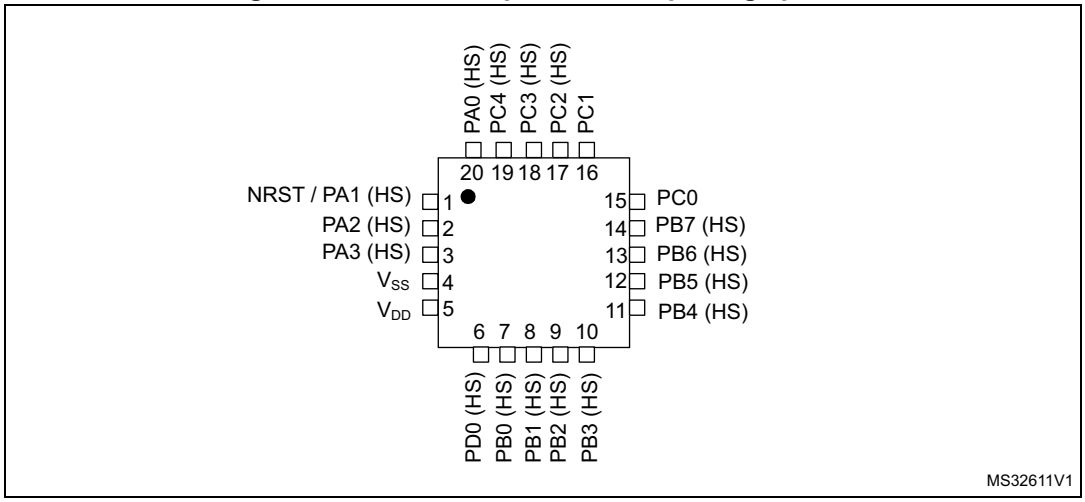
3.9 Independent watchdog

The independent watchdog (IWDG) peripheral can be used to resolve processor malfunctions due to hardware or software failures.

It is clocked by the 38 kHz LSI internal RC clock source, and thus stays active even in case of a CPU clock failure.

4 Pin description

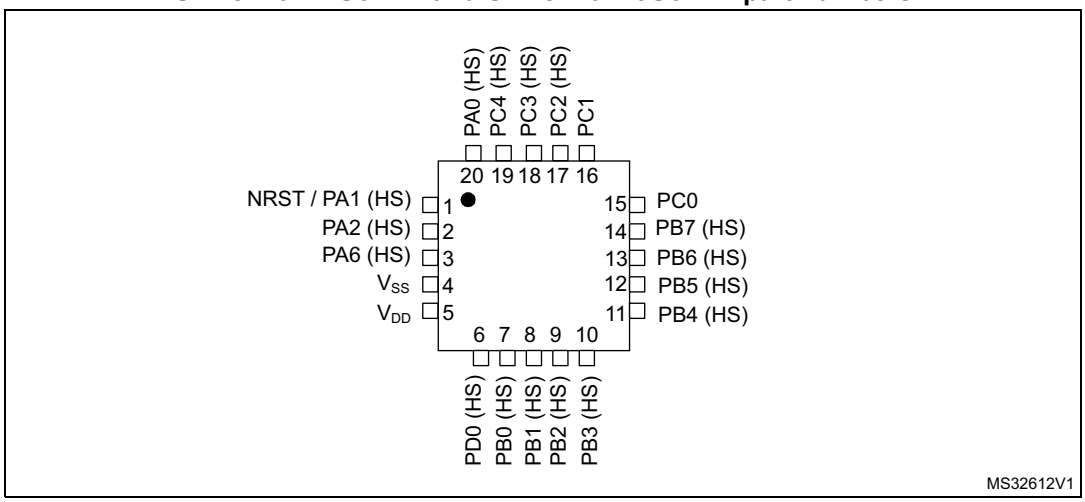
Figure 2. Standard 20-pin UFQFPN package pinout



1. HS corresponds to 20 mA high sink/source capability.
2. High sink LED driver capability available on PA0. Refer to the description of the IR_CR register in the STM8L reference manual (RM0013).

Note: The COMP_REF pin is not available in this standard 20-pin UFQFPN package. It is available on Port A6 in the Figure 3: 20-pin UFQFPN package pinout for STM8L101F1U6ATR, STM8L101F2U6ATR and STM8L101F3U6ATR part numbers.

Figure 3. 20-pin UFQFPN package pinout for STM8L101F1U6ATR, STM8L101F2U6ATR and STM8L101F3U6ATR part numbers



1. Please refer to the warning below.
2. HS corresponds to 20 mA high sink/source capability.
3. High sink LED driver capability available on PA0. Refer to the description of the IR_CR register in the STM8L reference manual (RM0013).

Warning: **For the STM8L101F1U6ATR, STM8L101F2U6ATR and STM8L101F3U6ATR part numbers (devices with COMP_REF pin), all ports available on 32-pin packages must be considered as active ports. To avoid spurious effects, the user has to configure them as input pull-up. A small increase in consumption (typ. < 300 µA) may occur during the power up and reset phase until these ports are properly configured.**

Table 4. STM8L101xx pin description (continued)

Pin number						Pin name	Type	Input			Output			Main function (after reset)	Alternate function
standard UFQFPN20	UFQFPN20 with COMP_REF(1)	TSSOP20	standard UFQFPN28	UFQFPN28 with COMP_REF(1)	UFQFPN32 or LQFP32			floating	wpu	Ext. interrupt	High sink/source	OD	PP		
-	-	-	26	26	30	PC5	I/O	**X**	X	X	HS	X	X	**Port C5**	-
-	-	-	27	27	31	PC6	I/O	**X**	X	X	HS	X	X	**Port C6**	-
20	20	3	28	28	32	PA0(5)/SWIM/ BEEP/IR_TIM (6)	I/O	X	**X**(5)	X	HS(6)	X	X	**Port A0**	SWIM input and output /Beep output/Timer Infrared output

1. Please refer to the warning below.
2. At power-up, the PA1/NRST pin is a reset input pin with pull-up. To be used as a general purpose pin (PA1), it can be configured only as a general purpose pin (PA1), it can be configured only as output push-pull, not neither as output open-drain nor as a general purpose input. Refer to Section *Configuring NRST/PA1 pin as general purpose output* in the STM8L reference manual (RM0013).
3. A pull-up is applied to PB0 and PB4 during the reset phase. These two pins are input floating after reset release.
4. In the open-drain output column, 'T' defines a true open-drain I/O (P-buffer, weak pull-up and protection diode to V_{DD} are not implemented).
5. The PA0 pin is in input pull-up during the reset phase and after reset release.
6. High sink LED driver capability available on PA0.

Slope control of all GPIO pins can be programmed except true open drain pins and by default is limited to 2 MHz.

Warning: For the STM8L101F1U6ATR, STM8L101F2U6ATR, STM8L101F3U6ATR, STM8L101G2U6ATR and STM8L101G3U6ATR part numbers (devices with COMP_REF pin), all ports available on 32-pin packages must be considered as active ports. To avoid spurious effects, the user has to configure them as input pull-up. A small increase in consumption (typ. < 300 µA) may occur during the power up and reset phase until these ports are properly configured.

Table 5. Flash and RAM boundary addresses

Memory area	Size	Start address	End address
RAM	1.5 Kbytes	0x00 0000	0x00 05FF
Flash program memory	2 Kbytes	0x00 8000	0x00 87FF
	4 Kbytes	0x00 8000	0x00 8FFF
	8 Kbytes	0x00 8000	0x00 9FFF

Note: 2 Kbytes of Data EEPROM is only available on devices with 8 Kbytes flash program memory.

Table 6. I/O Port hardware register map

Address	Block	Register label	Register name	Reset status
0x00 5000	Port A	PA_ODR	Port A data output latch register	0x00
0x00 5001		PA_IDR	Port A input pin value register	0xxx
0x00 5002		PA_DDR	Port A data direction register	0x00
0x00 5003		PA_CR1	Port A control register 1	0x00
0x00 5004		PA_CR2	Port A control register 2	0x00
0x00 5005	Port B	PB_ODR	Port B data output latch register	0x00
0x00 5006		PB_IDR	Port B input pin value register	0xxx
0x00 5007		PB_DDR	Port B data direction register	0x00
0x00 5008		PB_CR1	Port B control register 1	0x00
0x00 5009		PB_CR2	Port B control register 2	0x00
0x00 500A	Port C	PC_ODR	Port C data output latch register	0x00
0x00 500B		PC_IDR	Port C input pin value register	0xxx
0x00 500C		PC_DDR	Port C data direction register	0x00
0x00 500D		PC_CR1	Port C control register 1	0x00
0x00 500E		PC_CR2	Port C control register 2	0x00
0x00 500F	Port D	PD_ODR	Port D data output latch register	0x00
0x00 5010		PD_IDR	Port D input pin value register	0xxx
0x00 5011		PD_DDR	Port D data direction register	0x00
0x00 5012		PD_CR1	Port D control register 1	0x00
0x00 5013		PD_CR2	Port D control register 2	0x00

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 521E to 0x00 522F	Reserved area (18 bytes)			
0x00 5230	USART	USART_SR	USART status register	0xC0
0x00 5231		USART_DR	USART data register	0xXX
0x00 5232		USART_BRR1	USART baud rate register 1	0x00
0x00 5233		USART_BRR2	USART baud rate register 2	0x00
0x00 5234		USART_CR1	USART control register 1	0x00
0x00 5235		USART_CR2	USART control register 2	0x00
0x00 5236		USART_CR3	USART control register 3	0x00
0x00 5237		USART_CR4	USART control register 4	0x00
0x00 5238 to 0x00 524F	Reserved area (18 bytes)			

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5250	TIM2	TIM2_CR1	TIM2 control register 1	0x00
0x00 5251		TIM2_CR2	TIM2 control register 2	0x00
0x00 5252		TIM2_SMCR	TIM2 slave mode control register	0x00
0x00 5253		TIM2_ETR	TIM2 external trigger register	0x00
0x00 5254		TIM2_IER	TIM2 interrupt enable register	0x00
0x00 5255		TIM2_SR1	TIM2 status register 1	0x00
0x00 5256		TIM2_SR2	TIM2 status register 2	0x00
0x00 5257		TIM2_EGR	TIM2 event generation register	0x00
0x00 5258		TIM2_CCMR1	TIM2 capture/compare mode register 1	0x00
0x00 5259		TIM2_CCMR2	TIM2 capture/compare mode register 2	0x00
0x00 525A		TIM2_CCER1	TIM2 capture/compare enable register 1	0x00
0x00 525B		TIM2_CNTRH	TIM2 counter high	0x00
0x00 525C		TIM2_CNTRL	TIM2 counter low	0x00
0x00 525D		TIM2_PSCR	TIM2 prescaler register	0x00
0x00 525E		TIM2_ARRH	TIM2 auto-reload register high	0xFF
0x00 525F		TIM2_ARRL	TIM2 auto-reload register low	0xFF
0x00 5260		TIM2_CCR1H	TIM2 capture/compare register 1 high	0x00
0x00 5261		TIM2_CCR1L	TIM2 capture/compare register 1 low	0x00
0x00 5262		TIM2_CCR2H	TIM2 capture/compare register 2 high	0x00
0x00 5263		TIM2_CCR2L	TIM2 capture/compare register 2 low	0x00
0x00 5264		TIM2_BKR	TIM2 break register	0x00
0x00 5265		TIM2_OISR	TIM2 output idle state register	0x00
0x00 5266 to 0x00 527F	Reserved area (26 bytes)			

Table 9. Interrupt mapping (continued)

IRQ No.	Source block	Description	Wakeup from Halt mode	Wakeup from Active-halt mode	Wakeup from Wait (WFI mode)	Wakeup from Wait (WFE mode)	Vector address
27	USART	Transmission complete/transmit data register empty	-	-	Yes	Yes(1)	0x00 8074
28	USART	Receive Register DATA FULL/overrun/idle line detected/parity error	-	-	Yes	Yes(1)	0x00 8078
29	I2C	I2C interrupt(2)	Yes	Yes	Yes	Yes(1)	0x00 807C

1. In WFE mode, this interrupt is served if it has been previously enabled. After processing the interrupt, the processor goes back to WFE mode. Refer to Section *Wait for event (WFE) mode* in the RM0013 reference manual.
2. The device is woken up from Halt or Active-halt mode only when the address received matches the interface address.

8 Unique ID

STM8L101xx devices feature a 96-bit unique device identifier which provides a reference number that is unique for any device and in any context. The 96 bits of the identifier can never be altered by the user.

The unique device identifier can be read in single bytes and may then be concatenated using a custom algorithm.

The unique device identifier is ideally suited:

- For use as serial numbers
- For use as security keys to increase the code security in the program memory while using and combining this unique ID with software cryptographic primitives and protocols before programming the internal memory
- To activate secure boot processes.

Table 12. Unique ID registers (96 bits)

Address	Content description	Unique ID bits							
		7	6	5	4	3	2	1	0
0x4925	X co-ordinate on the wafer	U_ID[7:0]							
0x4926		U_ID[15:8]							
0x4927	Y co-ordinate on the wafer	U_ID[23:16]							
0x4928		U_ID[31:24]							
0x4929	Wafer number	U_ID[39:32]							
0x492A	Lot number	U_ID[47:40]							
0x492B		U_ID[55:48]							
0x492C		U_ID[63:56]							
0x492D		U_ID[71:64]							
0x492E		U_ID[79:72]							
0x492F		U_ID[87:80]							
0x4930		U_ID[95:88]							

9 Electrical parameters

9.1 Parameter conditions

Unless otherwise specified, all voltages are referred to V_{SS}.

9.1.1 Minimum and maximum values

Unless otherwise specified the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at T_A= 25 °C and T_A = T_A max (given by the selected temperature range).

Note: The values given at 85 °C <T_A ≤ 125 °C are only valid for suffix 3 versions.

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean±3Σ).

9.1.2 Typical values

Unless otherwise specified, typical data are based on T_A = 25 °C, V_{DD} = 3 V. They are given only as design guidelines and are not tested.

9.1.3 Typical curves

Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

9.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in *Figure 9*.

Figure 9. Pin loading conditions

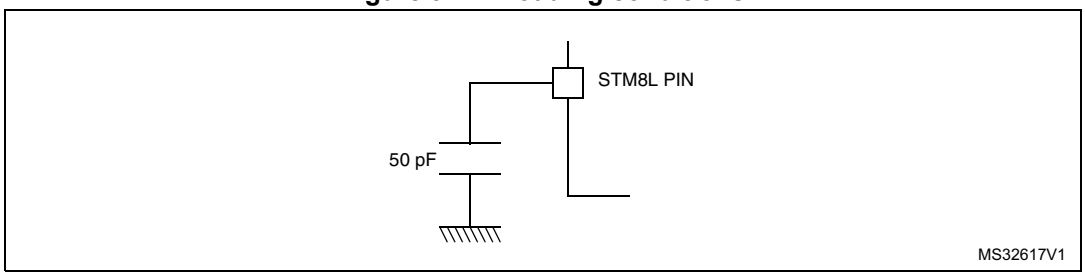


Table 18. Total current consumption in Run mode (1)

Symbol	Parameter	Conditions(2)		Typ	Max(3)	Unit
$I_{DD\ (Run)}$	Supply current in Run mode(4) (5)	Code executed from RAM	f_{MASTER} = 2 MHz	0.39	0.60	mA
			f_{MASTER} = 4 MHz	0.55	0.70	
			f_{MASTER} = 8 MHz	0.90	1.20	
			f_{MASTER} = 16 MHz	1.60	2.10(6)	
		Code executed from Flash	f_{MASTER} = 2 MHz	0.55	0.70	
			f_{MASTER} = 4 MHz	0.88	1.80	
			f_{MASTER} = 8 MHz	1.50	2.50	
			f_{MASTER} = 16 MHz	2.70	3.50	

1. Based on characterization results, unless otherwise specified.
2. All peripherals off, V_{DD} from 1.65 V to 3.6 V, HSI internal RC osc., $f_{CPU}=f_{MASTER}$
3. Maximum values are given for T_A = –40 to 125 °C.
4. CPU executing typical data processing.
5. An approximate value of $I_{DD(Run)}$ can be given by the following formula: $I_{DD(Run)} = f_{MASTER}$ x 150 µA/MHz +215 µA.
6. Tested in production.

Figure 11. $I_{DD(RUN)}$ vs. V_{DD}, f_{CPU} = 2 MHz

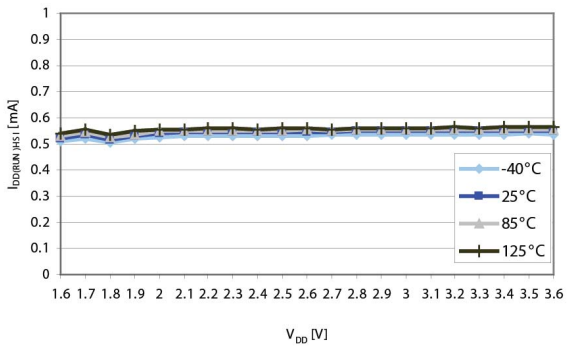
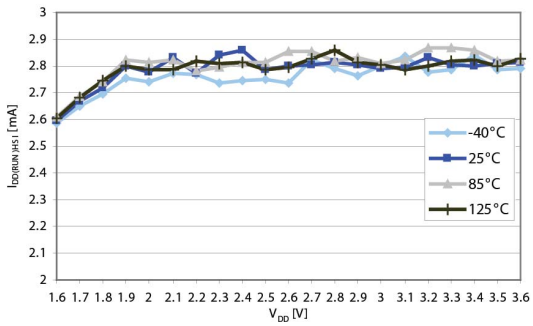


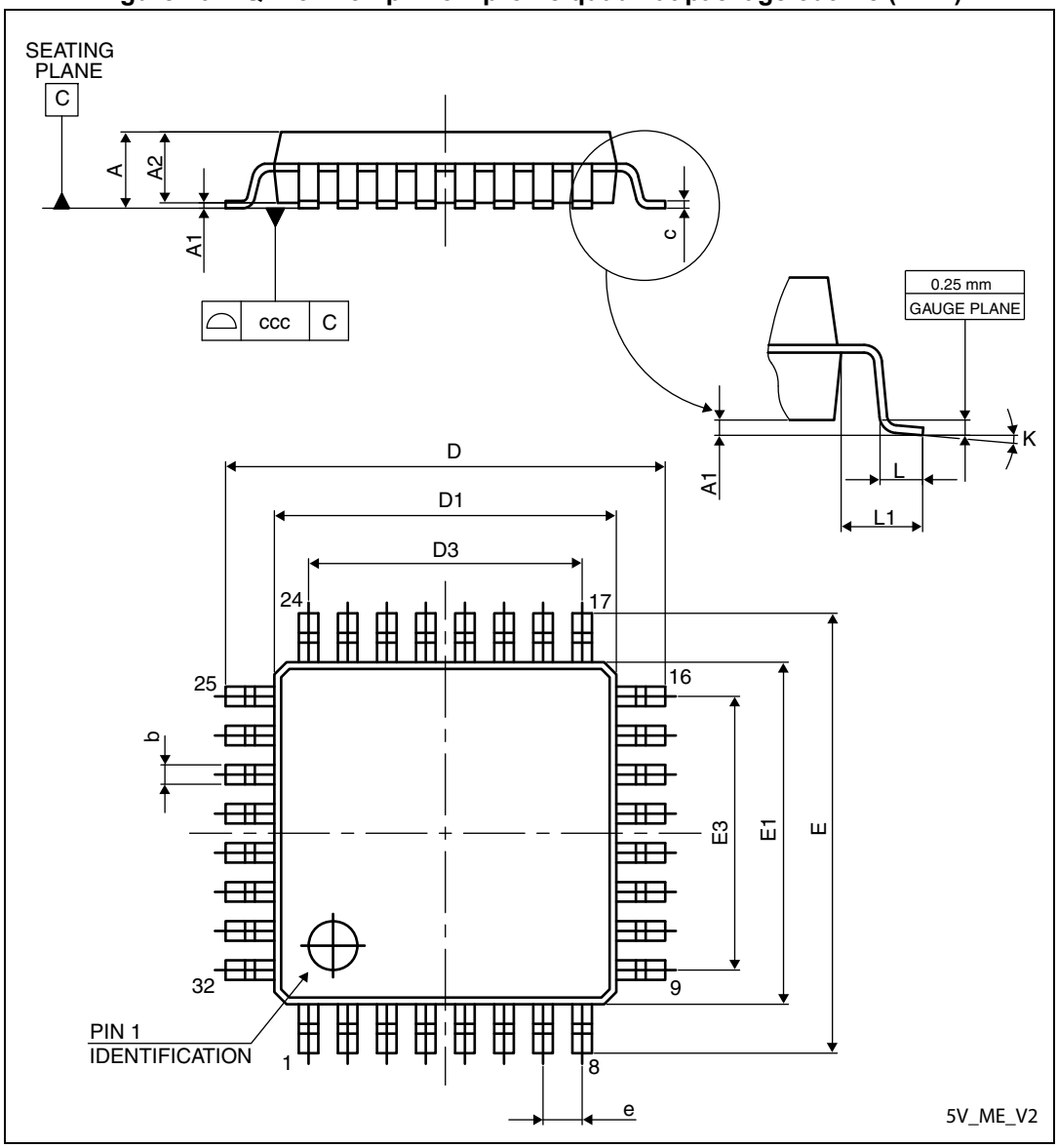
Figure 12. $I_{DD(RUN)}$ vs. V_{DD}, f_{CPU} = 16 MHz



1. Typical current consumption measured with code executed from Flash.

10.2 LQFP32 package information

Figure 40. LQFP32 - 32-pin low profile quad flat package outline (7 x 7)



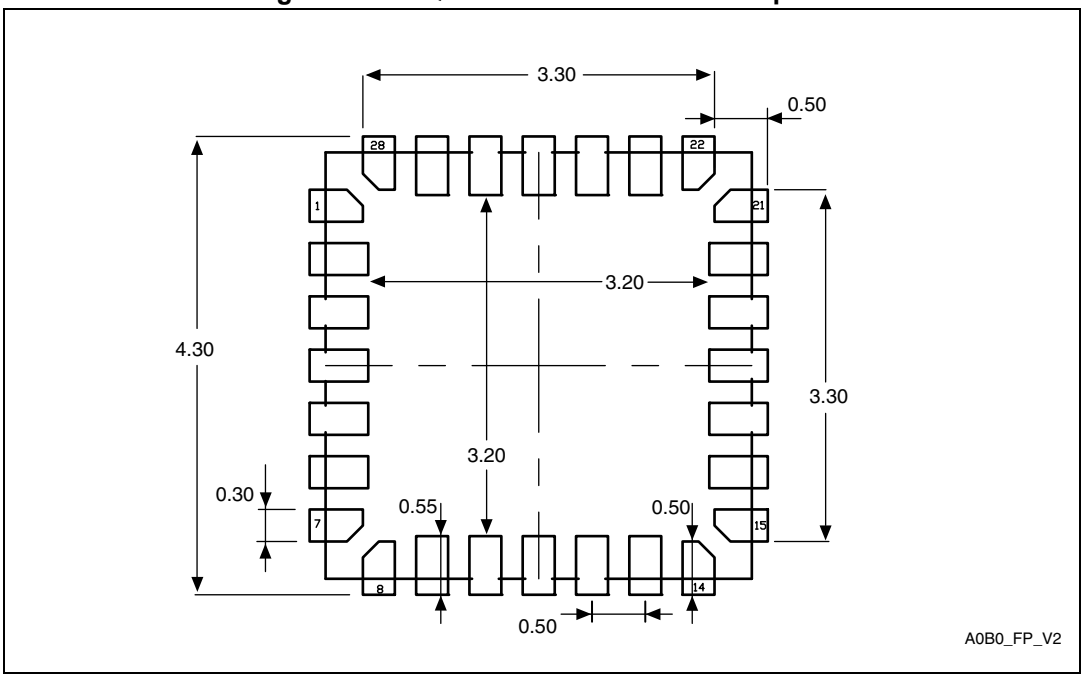
1. Drawing is not to scale.

Table 41. UFQFPN28 - 28-lead ultra thin fine pitch quad flat no-lead package (4 x 4), package mechanical data

Dim.	mm			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	0	0.020	0.050	0	0.0008	0.002
A3	-	0.152	-	-	0.0060	-
b	0.180	0.250	0.300	0.0071	0.0098	0.0118
D	-	4.000	-	-	0.1575	-
E	-	4.000	-	-	0.1575	-
e	-	0.500	-	-	0.0197	-
L1	0.250	0.350	0.450	0.0098	0.0138	0.0177
L2	0.300	0.400	0.500	0.0118	0.0157	0.0197
ddd	-	0.080	-	-	0.0031	-
-	Number of pins					
N	28					

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 44. UFQFPN28 recommended footprint



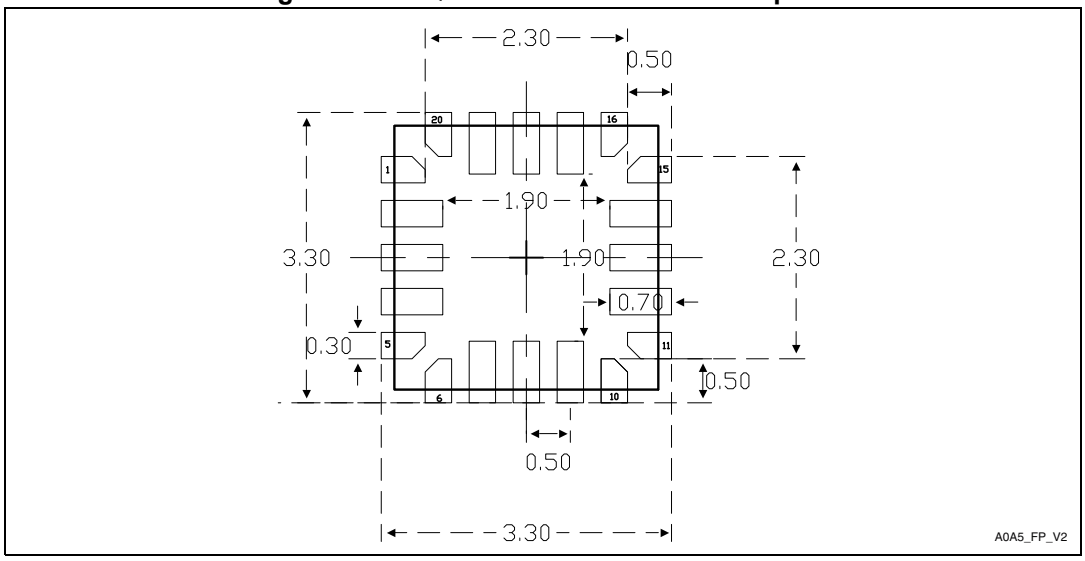
1. Dimensions are expressed in millimeters.

Table 42. UFQFPN20 - 20-lead ultra thin fine pitch quad flat package (3 x 3 mm) mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
D	-	3.000	-	-	0.1181	-
E	-	3.000	-	-	0.1181	-
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020
A3	-	0.152	-	-	0.0060	-
e	-	0.500	-	-	0.0197	-
L1	0.500	0.550	0.600	0.0197	0.0217	0.0236
L2	0.300	0.350	0.400	0.0118	0.0138	0.0157
L3	-	0.375	-	-	0.0148	-
L4	-	0.200	-	-	0.0079	-
L5	-	0.150	-	-	0.0059	-
b	0.180	0.250	0.300	0.0071	0.0098	0.0118
ddd	-	0.050	-	-	0.0020	-

1. Values in inches are rounded to 4 decimal digits

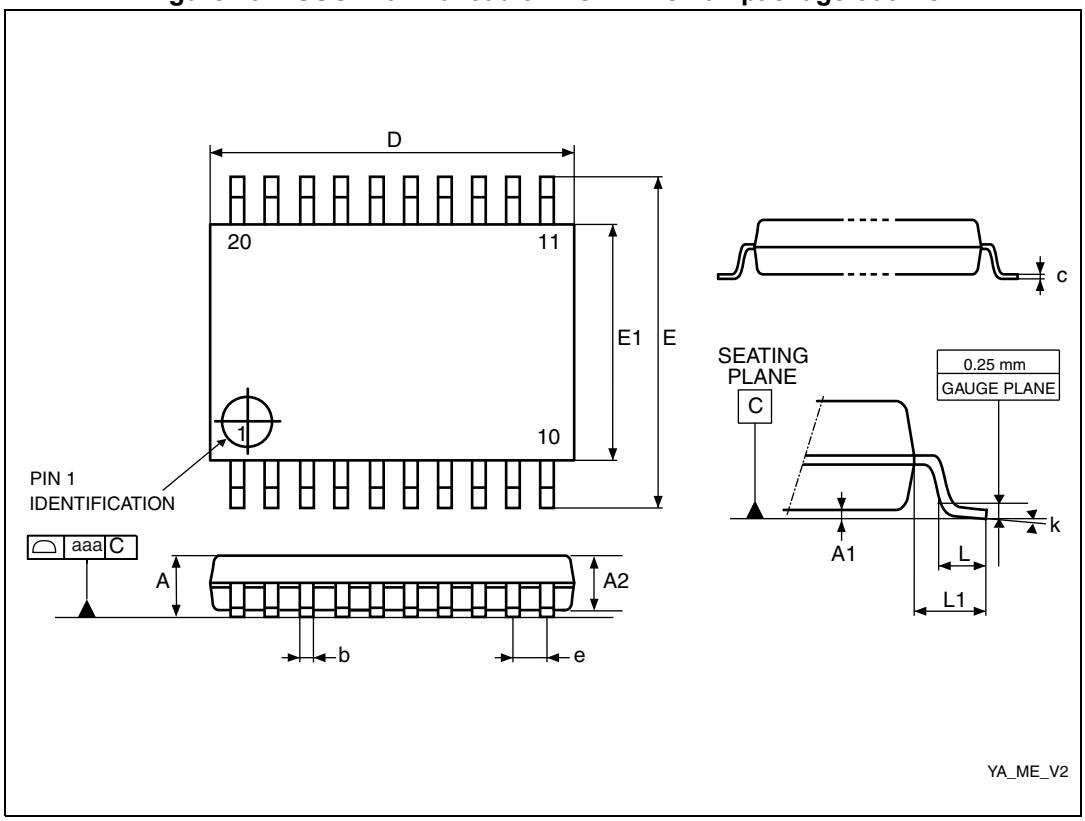
Figure 47. UFQFPN20 recommended footprint



1. Dimensions are in millimeters.

10.5 TSSOP20 package information

Figure 49. TSSOP20 - 20-lead thin shrink small package outline



1. Drawing is not to scale.

Table 43. TSSOP20 - 20-lead thin shrink small package mechanical data

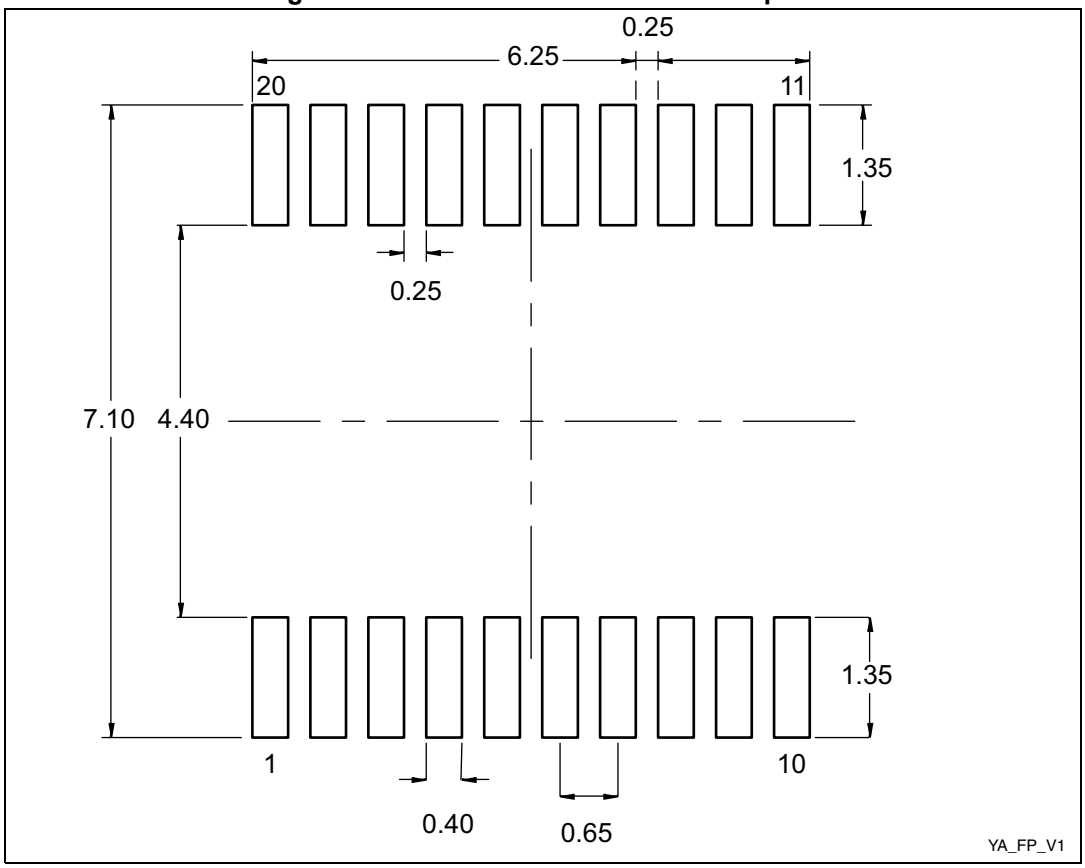
Dim.	mm				inches(1)	
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.200	-	-	0.0472
A1	0.050	-	0.150	0.0020	-	0.0059
A2	0.800	1.000	1.050	0.0315	0.0394	0.0413
b	0.190	-	0.300	0.0075	-	0.0118
CP	-	-	0.100	-	-	0.0039
c	0.090	-	0.200	0.0035	-	0.0079
D(2)	6.400	6.500	6.600	0.2520	0.2559	0.2598
E	6.200	6.400	6.600	0.2441	0.2520	0.2598
E1(3)	4.300	4.400	4.500	0.1693	0.1732	0.1772
e	-	0.650	-	0.1693	0.0256	-
L	0.450	0.600	0.750	0.1693	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-

Table 43. TSSOP20 - 20-lead thin shrink small package mechanical data (continued)

Dim.	mm				inches[1]	
	Min	Typ	Max	Min	Typ	Max
k	0°	-	8°	0°	-	8°
aaa	-	-	0.100	-	-	0.0039
Number of pins	20					

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. Dimension “D” does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15mm per side.
3. Dimension “E1” does not include interlead flash or protrusions. Interlead flash or protrusions shall not exceed 0.25mm per side.

Figure 50. TSSOP20 recommended footprint



1. Dimensions are in millimeters.

12.2 Software tools

STM8 development tools are supported by a complete, free software package from STMicroelectronics that includes ST Visual Develop (STVD) IDE and the ST Visual Programmer (STVP) software interface. STVD provides seamless integration of the Cosmic and Raisonance C compilers for STM8. A free version that outputs up to 32 Kbytes of code is available.

12.2.1 STM8 toolset

STM8 toolset with STVD integrated development environment and STVP programming software is available for free download at *www.st.com*. This package includes:

ST Visual Develop – Full-featured integrated development environment from ST, featuring

- Seamless integration of C and ASM toolsets
- Full-featured debugger
- Project management
- Syntax highlighting editor
- Integrated programming interface
- Support of advanced emulation features for STice such as code profiling and coverage

ST Visual Programmer (STVP) – Easy-to-use, unlimited graphical interface allowing read, write and verify of the STM8 microcontroller Flash program memory, data EEPROM and option bytes. STVP also offers project mode for saving programming configurations and automating programming sequences.

12.2.2 C and assembly toolchains

Control of C and assembly toolchains is seamlessly integrated into the STVD integrated development environment, making it possible to configure and control the building of user application directly from an easy-to-use graphical interface.

Available toolchains include:

- ***Cosmic C compiler for STM8*** – One free version that outputs up to 32 Kbytes of code is available. For more information, see www.cosmic-software.com.
- ***Raisonance C compiler for STM8*** – One free version that outputs up to 32 Kbytes of code. For more information, see www.raisonance.com.
- ***STM8 assembler linker*** – Free assembly toolchain included in the STVD toolset, which allows the user to assemble and link their application source code.

12.3 Programming tools

During the development cycle, STice provides in-circuit programming of the STM8 Flash microcontroller on the user's application board via the SWIM protocol. Additional tools are to include a low-cost in-circuit programmer as well as ST socket boards, which provide dedicated programming platforms with sockets for programming the STM8.

For production environments, programmers will include a complete range of gang and automated programming solutions from third-party tool developers already supplying programmers for the STM8 family.

Table 44. Document revision history (continued)

Date	Revision	Changes
14-Oct-2010	11	Added STM8L101F1 devices: Modified *Table 1: Device summary on page 1*, *Table 2: STM8L101xx device feature summary on page 9* and *Table 5: Flash and RAM boundary addresses on page 24* Modified warning below *Figure 3 on page 16* and below*Table 4: STM8L101xx pin description on page 20* Modified *Figure 52: STM8L101xx ordering information scheme on page 79* Modified text above *Figure 32: Recommended NRST pin configuration on page 54* Modified *Figure 32 on page 54*
02-Aug-2013	12	Added “The RAM content is preserved” in halt mode *Section 3.6: Low power modes* Reformatted *Figure 2: Standard 20-pin UFQFPN package pinout*, *Figure 3: 20-pin UFQFPN package pinout for STM8L101F1U6ATR, STM8L101F2U6ATR and STM8L101F3U6ATR part numbers*, *Figure 4: 20-pin TSSOP package pinout*, *Figure 4: 20-pin TSSOP package pinout*, *Figure 5: Standard 28-pin UFQFPN package pinout*, *Figure 6: 28-pin UFQFPN package pinout for STM8L101G3U6ATR and STM8L101G2U6ATR part numbers* and *Figure 7: 32-pin package pinout* Corrected NRST/PA1 pin OD output capability in *Table 4: STM8L101xx pin description* and corrected note *2.* and *4.* Added note “Slope control of all GPIO can be programmed except...” in *Table 4: STM8L101xx pin description* Added note under *Table 5: Flash and RAM boundary addresses* Replaced UM0320 with UM0470 in *Section 7: Option bytes* Updated OPT2 and OPT3 in *Table 10: Option bytes* Added additional note *2.* references in *Table 22: HSI oscillator characteristics* Added note *2.* under *Table 17: Operating conditions at power-up / power-down* and under *Figure 32: Recommended NRST pin configuration* Corrected ‘SCK output’ in *Figure 35: SPI timing diagram - master mode(1)* Added top view in *Figure 43: UFQFPN20 3 x 3 mm 0.6 mm package outline* Repositioned the package layout and footprint for all packages. Replaced “Standard ports” with “High sink ports” Replaced “TIMx_TRIG” with “TIMx_ETR” Replaced all ‘"Data guaranteed, each individual device tested in production” notes with “Tested in production”
31-Mar-2014	13	Updated L3 value on *Table 42*, added note 2) and 3) on *Table 43*