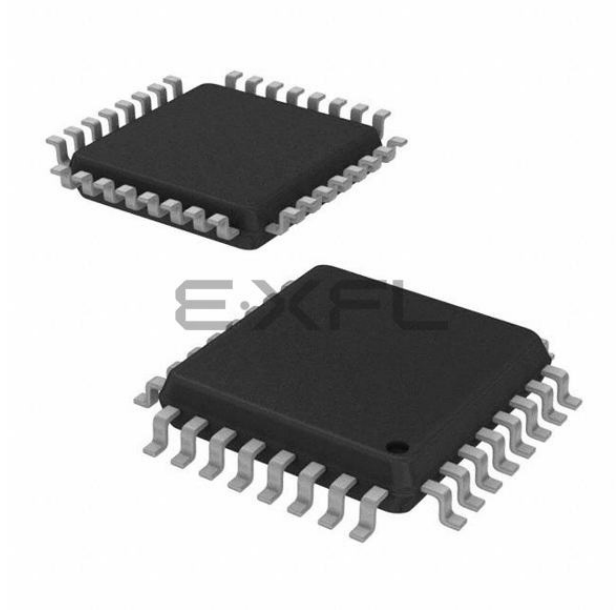

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

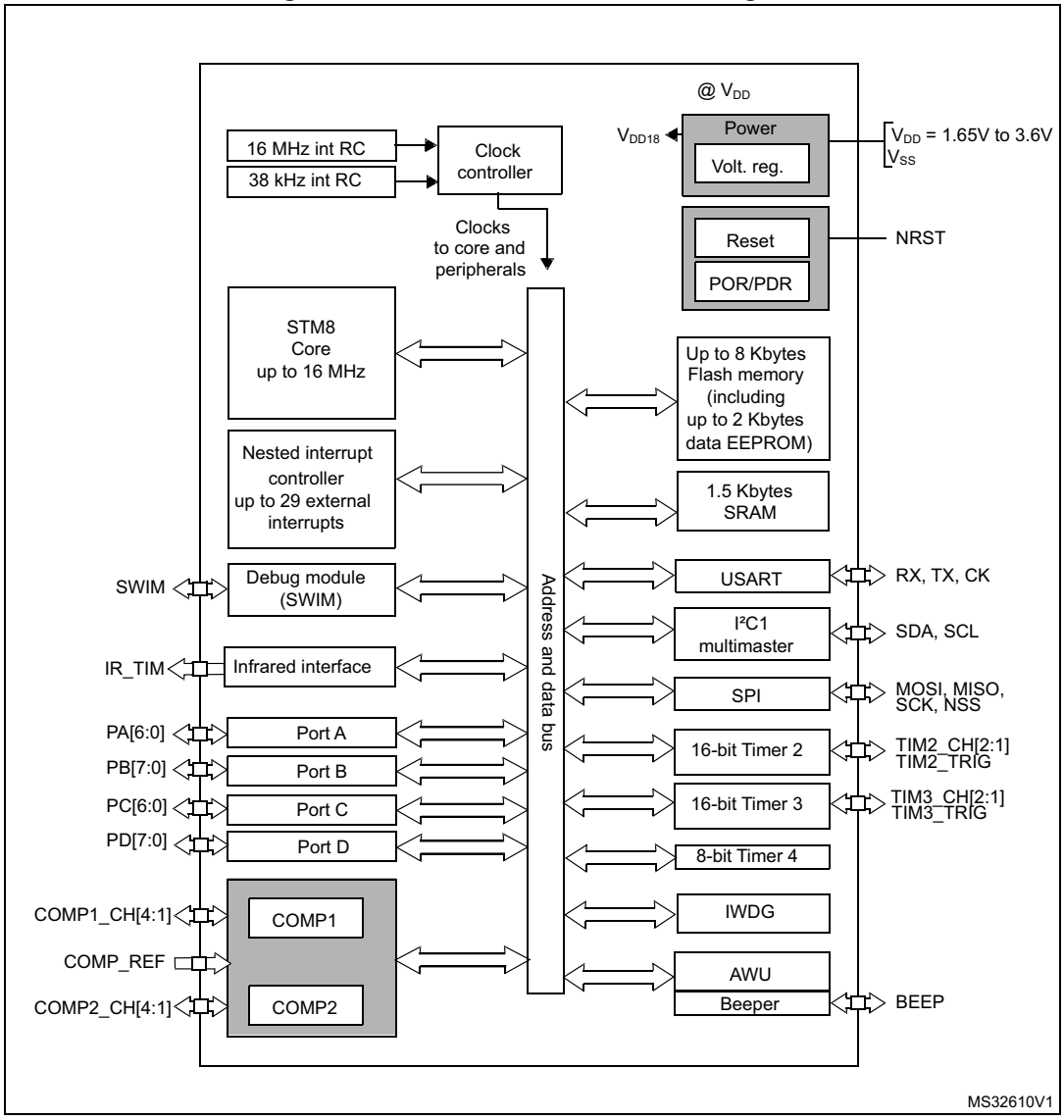
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	16MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Infrared, POR, PWM, WDT
Number of I/O	30
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8l101k3t6

List of tables

3 Product overview

Figure 1. STM8L101xx device block diagram



Legend:

AWU: Auto-wakeup unit
Int. RC: internal RC oscillator
I²C: Inter-integrated circuit multimaster interface
POR/PDR: Power on reset / power down reset
SPI: Serial peripheral interface
SWIM: Single wire interface module
USART: Universal synchronous / asynchronous receiver / transmitter
IWDG: Independent watchdog

3.1 Central processing unit STM8

The 8-bit STM8 core is designed for code efficiency and performance.

It features 21 internal registers, 20 addressing modes including indexed, indirect and relative addressing, and 80 instructions.

3.2 Development tools

Development tools for the STM8 microcontrollers include:

- The STice emulation system offering tracing and code profiling
- The STVD high-level language debugger including C compiler, assembler and integrated development environment
- The STVP Flash programming software

The STM8 also comes with starter kits, evaluation boards and low-cost in-circuit debugging/programming tools.

3.3 Single wire data interface (SWIM) and debug module

The debug module with its single wire data interface (SWIM) permits non-intrusive real-time in-circuit debugging and fast memory programming.

The Single wire interface is used for direct access to the debugging module and memory programming. The interface can be activated in all device operation modes.

The non-intrusive debugging module features a performance close to a full-featured emulator. Beside memory and peripherals, also CPU operation can be monitored in real-time by means of shadow registers.

3.4 Interrupt controller

The STM8L101xx features a nested vectored interrupt controller:

- Nested interrupts with 3 software priority levels
- 26 interrupt vectors with hardware priority
- Up to 29 external interrupt sources on 10 vectors
- Trap and reset interrupts.

3.5 Memory

The STM8L101xx devices have the following main features:

- 1.5 Kbytes of RAM
- The EEPROM is divided into two memory arrays (see the STM8L reference manual for details on the memory mapping):
  - Up to 8 Kbytes of low-density embedded Flash program including up to 2 Kbytes of data EEPROM. Data EEPROM and Flash program areas can be write protected independently by using the memory access security mechanism (MASS).
  - 64 option bytes (one block) of which 5 bytes are already used for the device.

Error correction code is implemented on the EEPROM.

3.6 Low power modes

To minimize power consumption, the product features three low power modes:

- Wait mode: CPU clock stopped, selected peripherals at full clock speed.
- Active-halt mode: CPU and peripheral clocks are stopped. The programmable wakeup time is controlled by the AWU unit.
- Halt mode: CPU and peripheral clocks are stopped, the device remains powered on. The RAM content is preserved. Wakeup is triggered by an external interrupt.

3.7 Voltage regulators

The STM8L101xx embeds an internal voltage regulator for generating the 1.8 V power supply for the core and peripherals.

This regulator has two different modes: main voltage regulator mode (MVR) and low power voltage regulator mode (LPVR). When entering Halt or Active-halt modes, the system automatically switches from the MVR to the LPVR in order to reduce current consumption.

3.8 Clock control

The STM8L101xx embeds a robust clock controller. It is used to distribute the system clock to the core and the peripherals and to manage clock gating for low power modes. This system clock is a 16-MHz High Speed Internal RC oscillator (HSI RC), followed by a programmable prescaler.

In addition, a 38 kHz low speed internal RC oscillator is used by the independent watchdog (IWDG) and Auto-wakeup unit (AWU).

3.9 Independent watchdog

The independent watchdog (IWDG) peripheral can be used to resolve processor malfunctions due to hardware or software failures.

It is clocked by the 38 kHz LSI internal RC clock source, and thus stays active even in case of a CPU clock failure.

3.10 Auto-wakeup counter

The auto-wakeup (AWU) counter is used to wakeup the device from Active-halt mode.

3.11 General purpose and basic timers

STM8L101xx devices contain two 16-bit general purpose timers (TIM2 and TIM3) and one 8-bit basic timer (TIM4).

16-bit general purpose timers

The 16-bit timers consist of 16-bit up/down auto-reload counters driven by a programmable prescaler. They perform a wide range of functions, including:

- Time base generation
- Measuring the pulse lengths of input signals (input capture)
- Generating output waveforms (output compare, PWM and One pulse mode)
- Interrupt capability on various events (capture, compare, overflow, break, trigger)

8-bit basic timer

The 8-bit timer consists of an 8-bit up auto-reload counter driven by a programmable prescaler. It can be used for timebase generation with interrupt generation on timer overflow.

3.12 Beeper

The STM8L101xx devices include a beeper function used to generate a beep signal in the range of 1, 2 or 4 kHz when the LSI clock is operating at a frequency of 38 kHz.

3.13 Infrared (IR) interface

The STM8L101xx devices contain an infrared interface which can be used with an IR LED for remote control functions. Two timer output compare channels are used to generate the infrared remote control signals.

3.14 Comparators

The STM8L101xx features two zero-crossing comparators (COMP1 and COMP2) sharing the same current bias and voltage reference. The voltage reference can be internal (comparison with ground) or external (comparison to a reference pin voltage).

Each comparator is connected to 4 channels, which can be used to generate interrupt, timer input capture or timer break. Their polarity can be inverted.

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 50E0	IWDG	IWDG_KR	IWDG key register	0xXX
0x00 50E1		IWDG_PR	IWDG prescaler register	0x00
0x00 50E2		IWDG_RLR	IWDG reload register	0xFF
0x00 50E3 to 0x00 50EF	Reserved area (13 bytes)			
0x00 50F0	AWU	AWU_CSR	AWU control/status register	0x00
0x00 50F1		AWU_APR	AWU asynchronous prescaler buffer register	0x3F
0x00 50F2		AWU_TBR	AWU timebase selection register	0x00
0x00 50F3	BEEP	BEEP_CSR	BEEP control/status register	0x1F
0x00 50F4 to 0x00 51FF	Reserved area (268 bytes)			
0x00 5200	SPI	SPI_CR1	SPI control register 1	0x00
0x00 5201		SPI_CR2	SPI control register 2	0x00
0x00 5202		SPI_ICR	SPI interrupt control register	0x00
0x00 5203		SPI_SR	SPI status register	0x02
0x00 5204		SPI_DR	SPI data register	0x00
0x00 5205 to 0x00 520F	Reserved area (11 bytes)			
0x00 5210	I2C	I2C_CR1	I2C control register 1	0x00
0x00 5211		I2C_CR2	I2C control register 2	0x00
0x00 5212		I2C_FREQR	I2C frequency register	0x00
0x00 5213		I2C_OARL	I2C own address register low	0x00
0x00 5214		I2C_OARH	I2C own address register high	0x00
0x00 5215		Reserved area (1 byte)		
0x00 5216		I2C_DR	I2C data register	0x00
0x00 5217		I2C_SR1	I2C status register 1	0x00
0x00 5218		I2C_SR2	I2C status register 2	0x00
0x00 5219		I2C_SR3	I2C status register 3	0x00
0x00 521A		I2C_ITR	I2C interrupt control register	0x00
0x00 521B		I2C_CCRL	I2C Clock control register low	0x00
0x00 521C		I2C_CCRH	I2C Clock control register high	0x00
0x00 521D		I2C_TRISER	I2C TRISE register	0x02

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 521E to 0x00 522F	Reserved area (18 bytes)			
0x00 5230	USART	USART_SR	USART status register	0xC0
0x00 5231		USART_DR	USART data register	0xXX
0x00 5232		USART_BRR1	USART baud rate register 1	0x00
0x00 5233		USART_BRR2	USART baud rate register 2	0x00
0x00 5234		USART_CR1	USART control register 1	0x00
0x00 5235		USART_CR2	USART control register 2	0x00
0x00 5236		USART_CR3	USART control register 3	0x00
0x00 5237		USART_CR4	USART control register 4	0x00
0x00 5238 to 0x00 524F	Reserved area (18 bytes)			

Table 7. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5280	TIM3	TIM3_CR1	TIM3 control register 1	0x00
0x00 5281		TIM3_CR2	TIM3 control register 2	0x00
0x00 5282		TIM3_SMCR	TIM3 slave mode control register	0x00
0x00 5283		TIM3_ETR	TIM3 external trigger register	0x00
0x00 5284		TIM3_IER	TIM3 interrupt enable register	0x00
0x00 5285		TIM3_SR1	TIM3 status register 1	0x00
0x00 5286		TIM3_SR2	TIM3 status register 2	0x00
0x00 5287		TIM3_EGR	TIM3 event generation register	0x00
0x00 5288		TIM3_CCMR1	TIM3 capture/compare mode register 1	0x00
0x00 5289		TIM3_CCMR2	TIM3 capture/compare mode register 2	0x00
0x00 528A		TIM3_CCER1	TIM3 capture/compare enable register 1	0x00
0x00 528B		TIM3_CNTRH	TIM3 counter high	0x00
0x00 528C		TIM3_CNTRL	TIM3 counter low	0x00
0x00 528D		TIM3_PSCR	TIM3 prescaler register	0x00
0x00 528E		TIM3_ARRH	TIM3 auto-reload register high	0xFF
0x00 528F		TIM3_ARRL	TIM3 auto-reload register low	0xFF
0x00 5290		TIM3_CCR1H	TIM3 capture/compare register 1 high	0x00
0x00 5291		TIM3_CCR1L	TIM3 capture/compare register 1 low	0x00
0x00 5292		TIM3_CCR2H	TIM3 capture/compare register 2 high	0x00
0x00 5293		TIM3_CCR2L	TIM3 capture/compare register 2 low	0x00
0x00 5294		TIM3_BKR	TIM3 break register	0x00
0x00 5295		TIM3_OISR	TIM3 output idle state register	0x00
0x00 5296 to 0x00 52DF	Reserved area (74 bytes)			
0x00 52E0	TIM4	TIM4_CR1	TIM4 control register 1	0x00
0x00 52E1		TIM4_CR2	TIM4 control register 2	0x00
0x00 52E2		TIM4_SMCR	TIM4 Slave mode control register	0x00
0x00 52E3		TIM4_IER	TIM4 interrupt enable register	0x00
0x00 52E4		TIM4_SR1	TIM4 Status register 1	0x00
0x00 52E5		TIM4_EGR	TIM4 event generation register	0x00
0x00 52E6		TIM4_CNTR	TIM4 counter	0x00
0x00 52E7		TIM4_PSCR	TIM4 prescaler register	0x00
0x00 52E8		TIM4_ARR	TIM4 auto-reload register low	0xFF

Table 8. CPU/SWIM/debug module/interrupt controller registers (continued)

Address	Block	Register label	Register name	Reset status
0x00 7F78 to 0x00 7F79	Reserved area (2 bytes)			
0x00 7F80	SWIM	SWIM_CSR	SWIM control status register	0x00
0x00 7F81 to 0x00 7F8F	Reserved area (15 bytes)			
0x00 7F90	DM	DM_BK1RE	Breakpoint 1 register extended byte	0xFF
0x00 7F91		DM_BK1RH	Breakpoint 1 register high byte	0xFF
0x00 7F92		DM_BK1RL	Breakpoint 1 register low byte	0xFF
0x00 7F93		DM_BK2RE	Breakpoint 2 register extended byte	0xFF
0x00 7F94		DM_BK2RH	Breakpoint 2 register high byte	0xFF
0x00 7F95		DM_BK2RL	Breakpoint 2 register low byte	0xFF
0x00 7F96		DM_CR1	Debug module control register 1	0x00
0x00 7F97		DM_CR2	Debug module control register 2	0x00
0x00 7F98		DM_CSR1	Debug module control/status register 1	0x10
0x00 7F99		DM_CSR2	Debug module control/status register 2	0x00
0x00 7F9A		DM_ENFCTR	Enable function register	0xFF

1. Refer to *Table 7: General hardware register map on page 25* (addresses 0x00 50A0 to 0x00 50A5) for a list of external interrupt registers.

6 Interrupt vector mapping

Table 9. Interrupt mapping

IRQ No.	Source block	Description	Wakeup from Halt mode	Wakeup from Active-halt mode	Wakeup from Wait (WFI mode)	Wakeup from Wait (WFE mode)	Vector address
-	RESET	Reset	Yes	Yes	Yes	Yes	0x00 8000
-	TRAP	Software interrupt	-	-	-	-	0x00 8004
0	-	Reserved	-	-	-	-	0x00 8008
1	FLASH	EOP/WR_PG_DIS	-	-	Yes	Yes(1)	0x00 800C
2-3	-	Reserved	-	-	-	-	0x00 8010 -0x00 8017
4	AWU	Auto wakeup from Halt	-	Yes	Yes	Yes(1)	0x00 8018
5	-	Reserved	-	-	-	-	0x00 801C
6	EXTIB	External interrupt port B	Yes	Yes	Yes	Yes	0x00 8020
7	EXTID	External interrupt port D	Yes	Yes	Yes	Yes	0x00 8024
8	EXTI0	External interrupt 0	Yes	Yes	Yes	Yes	0x00 8028
9	EXTI1	External interrupt 1	Yes	Yes	Yes	Yes	0x00 802C
10	EXTI2	External interrupt 2	Yes	Yes	Yes	Yes	0x00 8030
11	EXTI3	External interrupt 3	Yes	Yes	Yes	Yes	0x00 8034
12	EXTI4	External interrupt 4	Yes	Yes	Yes	Yes	0x00 8038
13	EXTI5	External interrupt 5	Yes	Yes	Yes	Yes	0x00 803C
14	EXTI6	External interrupt 6	Yes	Yes	Yes	Yes	0x00 8040
15	EXTI7	External interrupt 7	Yes	Yes	Yes	Yes	0x00 8044
16	-	Reserved	-	-	-	-	0x00 8048
17	-	Reserved	-	-	-	-	0x00 804C -0x00 804F
18	COMP	Comparators	-	-	Yes	Yes(1)	0x00 8050
19	TIM2	Update /Overflow/Trigger/Break	-	-	Yes	Yes	0x00 8054
20	TIM2	Capture/Compare	-	-	Yes	Yes	0x00 8058
21	TIM3	Update /Overflow/Break	-	-	Yes	Yes(1)	0x00 805C
22	TIM3	Capture/Compare	-	-	Yes	Yes(1)	0x00 8060
23-24	-	Reserved	-	-	-	-	0x00 8064-0x00 806B
25	TIM4	Update /Trigger	-	-	Yes	Yes(1)	0x00 806C
26	SPI	End of Transfer	Yes	Yes	Yes	Yes(1)	0x00 8070

7 Option bytes

Option bytes contain configurations for device hardware features as well as the memory protection of the device. They are stored in a dedicated row of the memory.

All option bytes can be modified only in ICP mode (with SWIM) by accessing the EEPROM address. See *Table 10* for details on option byte addresses.

Refer to the STM8L Flash programming manual (PM0054) and STM8 SWIM and Debug Manual (UM0470) for information on SWIM programming procedures.

Table 10. Option bytes

Addr.	Option name	Option byte No.	Option bits								Factory default setting
			7	6	5	4	3	2	1	0	
0x4800	Read-out protection (ROP)	OPT1	ROP[7:0]								0x00
0x4807	-	-	Must be programmed to 0x00								0x00
0x4802	UBC (User Boot code size)	OPT2	UBC[7:0]								0x00
0x4803	DATASIZE	OPT3	DATASIZE[7:0]								0x00
0x4808	Independent watchdog option	OPT4 [1:0]	Reserved						IWDG _HALT	IWDG _HW	0x00

Table 11. Option byte description

OPT1	**ROP[7:0]** *Memory readout protection (ROP)* 0xAA: Enable readout protection (write access via SWIM protocol) Refer to *Read-out protection* section in the STM8L reference manual (RM0013) for details.
OPT2	**UBC[7:0]** *Size of the user boot code area* 0x00: no UBC 0x01-0x02: UBC contains only the interrupt vectors. 0x03: Page 0 and 1 reserved for the interrupt vectors. Page 2 is available to store user boot code. Memory is write protected ... 0x7F - Page 0 to 126 reserved for UBC, memory is write protected Refer to *User boot area (UBC)* section in the STM8L reference manual (RM0013) for more details. UBC[7] is forced to 0 internally by HW.

Table 11. Option byte description (continued)

OPT3	**DATASIZE[7:0]** Size of the data EEPROM area 0x00: no data EEPROM area (1) 0x01: 1 page reserved for data storage from 0x9FC0 to 0x9FFF(1) 0x02: 2 pages reserved for data storage from 0x9F80 to 0x9FFF(1) ... (1) 0x20: 32 pages reserved for data storage from 0x9800 to 0x9FFF(1) Refer to *Data EEPROM (DATA)* section in the STM8L reference manual (RM0013) for more details. DATASIZE[7:6] are forced to 0 internal by HW.
OPT4	**IWDG_HW:** *Independent watchdog* 0: Independent watchdog activated by software 1: Independent watchdog activated by hardware
	IWDG_HALT: *Independent window watchdog reset on Halt/Active-halt* 0: Independent watchdog continues running in Halt/Active-halt mode 1: Independent watchdog stopped in Halt/Active-halt mode

1. 0x00 is the only allowed value for 4 Kbyte STM8L101xx devices.

Caution: After a device reset, read access to the program memory is not guaranteed if address 0x4807 is not programmed to 0x00.

9.3 Operating conditions

Subject to general operating conditions for V_{DD} and T_A.

9.3.1 General operating conditions

Table 16. General operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MASTER} (1)	Master clock frequency	1.65 V ≤V_{DD} < 3.6 V	2	16	MHz
V_{DD}	Standard operating voltage	-	1.65	3.6	V
P_D (2)	Power dissipation at T_A= 85 °C for suffix 6 devices	LQFP32	-	288	mW
		UFQFPN32	-	288	
		UFQFPN28	-	250	
		TSSOP20	-	181	
		UFQFPN20	-	196	
	Power dissipation at T_A= 125 °C for suffix 3 devices	LQFP32	-	83	
		UFQFPN32	-	185	
		UFQFPN28	-	62	
		TSSOP20	-	45	
		UFQFPN20	-	49	
T_A	Temperature range	1.65 V ≤V_{DD} < 3.6 V (6 suffix version)	–40	85	°C
		1.65 V ≤V_{DD} < 3.6 V (3 suffix version)	–40	125	
T_J	Junction temperature range	-40 °C ≤T_A ≤85 °C (6 suffix version)	- 40	105	°C
		-40 °C ≤T_A ≤125 °C (3 suffix version)	–40	130	°C

1. f_{MASTER} = f_{CPU}
2. To calculate $P_{Dmax}(T_A)$ use the formula given in thermal characteristics $P_{Dmax}=(T_{Jmax} - T_A)/\Theta_{JA}$ with T_{Jmax} in this table and Θ_{JA} in table “Thermal characteristics”

Output driving current

Subject to general operating conditions for V_{DD} and T_A unless otherwise specified.

Table 27. Output driving current (High sink ports)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
Standard	V_{OL} (1)	Output low level voltage for an I/O pin	I_{IO} = +2 mA, V_{DD} = 3.0 V	-	0.45	V
			I_{IO} = +2 mA, V_{DD} = 1.8 V	-	0.45	V
			I_{IO} = +10 mA, V_{DD} = 3.0 V	-	1.2	V
	V_{OH} (2)	Output high level voltage for an I/O pin	I_{IO} = -2 mA, V_{DD} = 3.0 V	V_{DD}-0.45	-	V
			I_{IO} = -1 mA, V_{DD} = 1.8 V	V_{DD}-0.45	-	V
			I_{IO} = -10 mA, V_{DD} = 3.0 V	V_{DD}-1.2	-	V

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 14* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.
2. The I_{IO} current sourced must always respect the absolute maximum rating specified in *Table 14* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VDD}.

Table 28. Output driving current (true open drain ports)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
Open drain	V_{OL} (1)	Output low level voltage for an I/O pin	I_{IO} = +3 mA, V_{DD} = 3.0 V	-	0.45	V
			I_{IO} = +1 mA, V_{DD} = 1.8 V	-	0.45	V

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 14* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.

Table 29. Output driving current (PA0 with high sink LED driver capability)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
IR	V_{OL} (1)	Output low level voltage for an I/O pin	I_{IO} = +20 mA, V_{DD} = 2.0 V	-	0.9	V

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 14* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.

NRST pin

The NRST pin input driver is CMOS. A permanent pull-up is present.
$R_{PU(NRST)}$ has the same value as R_{PU} (see *Table 26 on page 48*).

Subject to general operating conditions for V_{DD} and T_A unless otherwise specified.

Table 30. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ (1)	Max	Unit
$V_{IL(NRST)}$	NRST input low level voltage (1)	-	V_{SS}	-	0.8	V
$V_{IH(NRST)}$	NRST input high level voltage (1)	-	1.4	-	V_{DD}	
$V_{OL(NRST)}$	NRST output low level voltage	I_{OL} = 2 mA	-	-	V_{DD}-0.8	
$R_{PU(NRST)}$	NRST pull-up equivalent resistor (2)	-	30	45	60	kΩ
$V_{F(NRST)}$	NRST input filtered pulse (3)	-	-	-	50	ns
$t_{OP(NRST)}$	NRST output pulse width	-	20	-	-	ns
$V_{NF(NRST)}$	NRST input not filtered pulse (3)	-	300	-	-	ns

1. Data based on characterization results, not tested in production.
2. The R_{PU} pull-up equivalent resistor is based on a resistive transistor (*Figure 30*). Corresponding I_{PU} current characteristics are described in *Figure 31*.
3. Data guaranteed by design, not tested in production.

Figure 30. Typical NRST pull-up resistance R_{PU} vs. V_{DD}

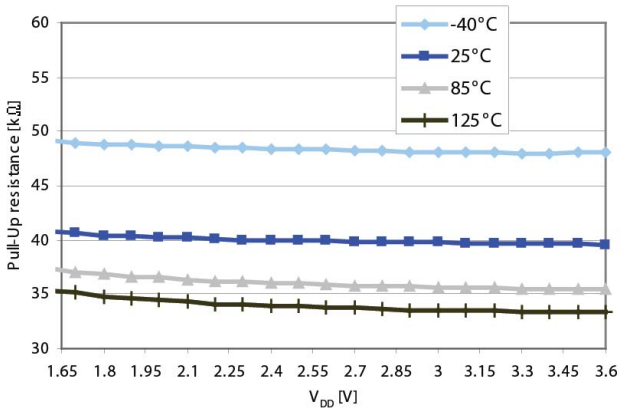
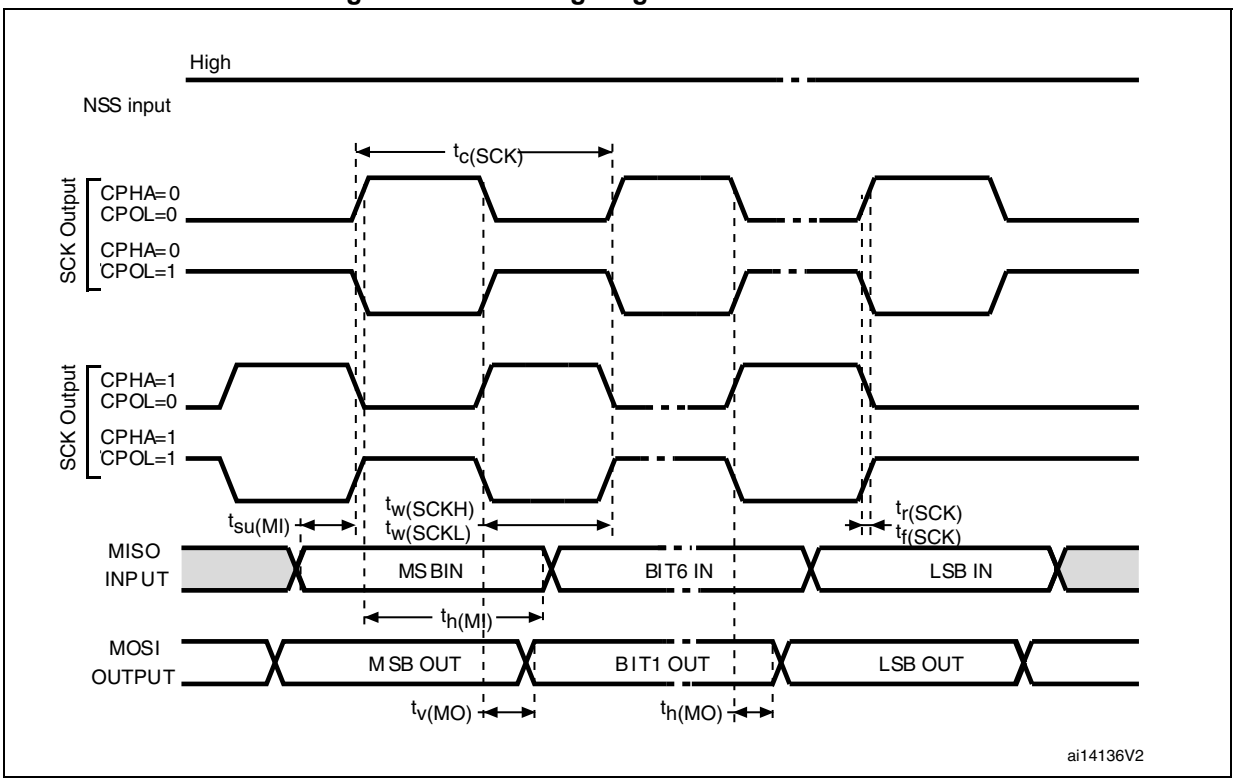


Figure 35. SPI timing diagram - master mode(1)



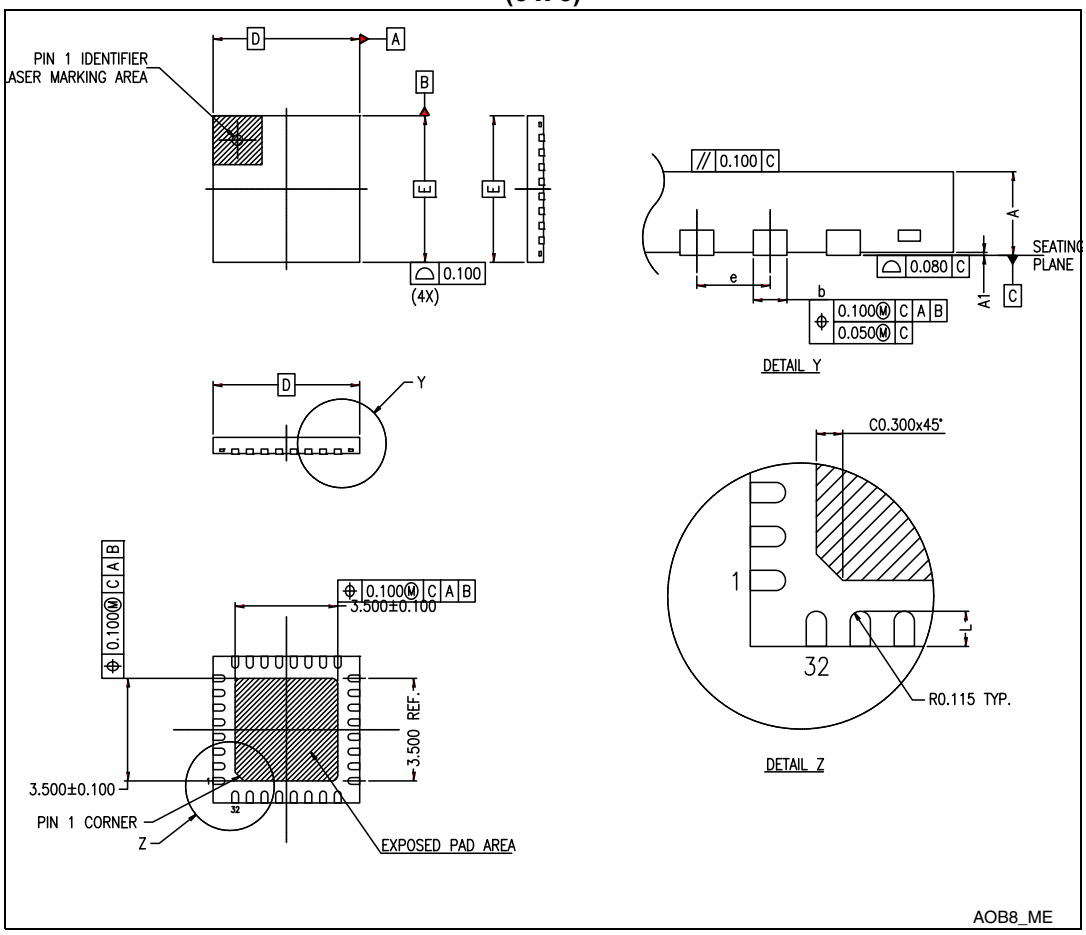
1. Measurement points are done at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.

10 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK® is an ST trademark.

10.1 UFQFPN32 package information

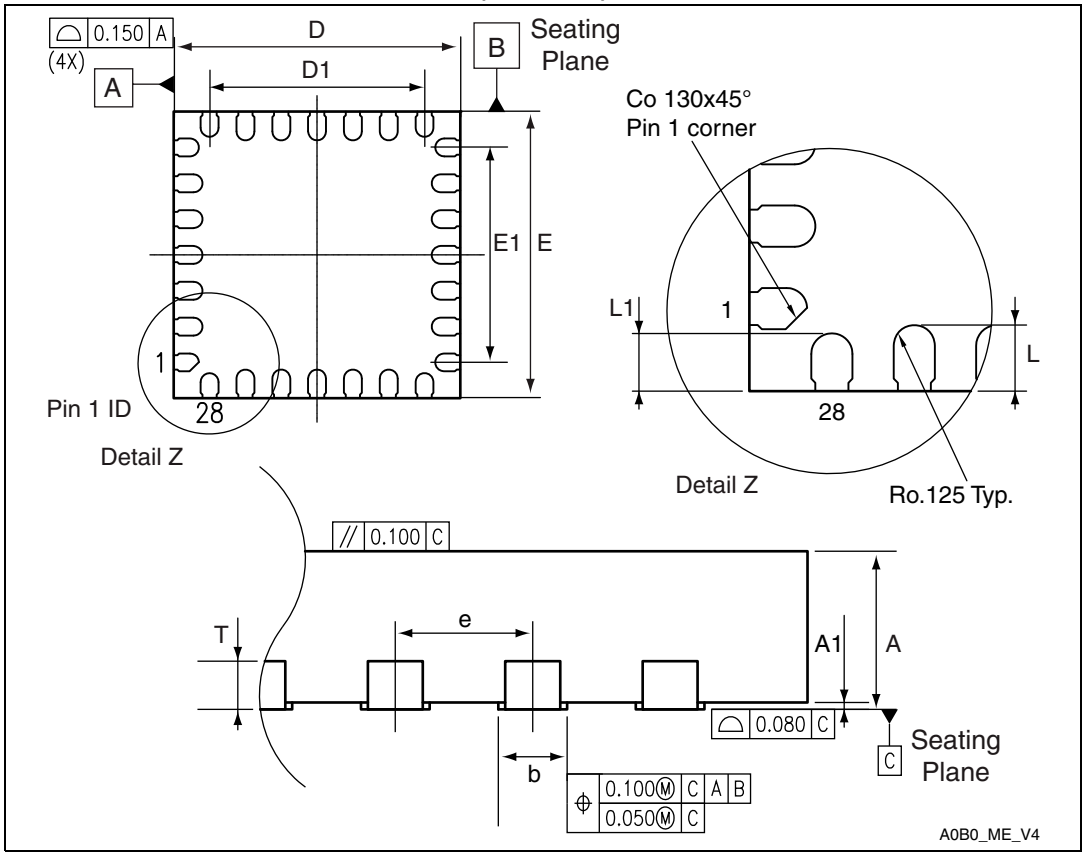
Figure 37. UFQFPN32 - 32-lead ultra thin fine pitch quad flat no-lead package outline (5 x 5)



1. Drawing is not to scale.
2. All leads/pads should be soldered to the PCB to improve the lead/pad solder joint life.
3. There is an exposed die pad on the underside of the UFQFPN package. It is recommended to connect and solder this back-side pad to PCB ground.

10.3 UFQFPN28 package information

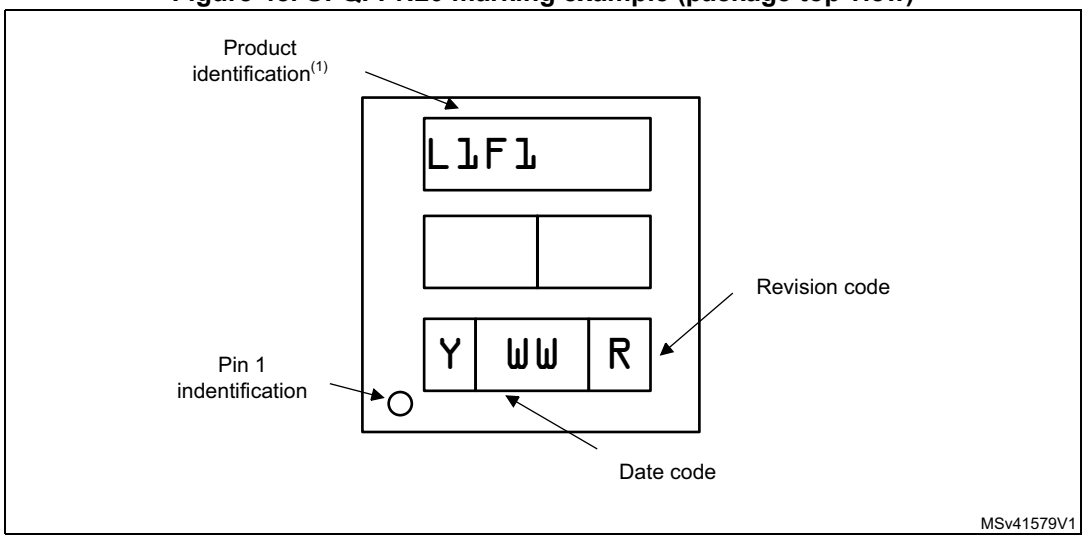
Figure 43. UFQFPN28 - 28-lead ultra thin fine pitch quad flat no-lead package outline (4 x 4 mm)



Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Figure 48. UFQFPN20 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

Table 44. Document revision history (continued)

Date	Revision	Changes
29-Nov-2009	8	Modified status of the document (datasheet instead of preliminary data) Replaced WFQFPN32 with UFQFPN32 and WFQFPN28 with UFQFPN28. Modified title of the reference manual mentioned in *Section 2: Description on page 9* Added references to “low-density” in *Section 2: Description on page 9*, *Section 3.5: Memory on page 12* and in *Figure 8: Memory map on page 23* Modified *Figure 8: Memory map on page 23* (unique ID are added) *Table 7: General hardware register map on page 25*: Modified reserved areas and IR block replaced with IRTIM block Modified t_{TEMP} in *Table 17: Operating conditions at power-up / power-down on page 41* Modified *Table 23: LSI oscillator characteristics on page 47* Modified *Table 25: Flash program memory on page 47* (t_{PROG}) Modified *Table 16: General operating conditions on page 40* and *Table 38: Thermal characteristics on page 63* Modified *Section 13: Revision history on page 82*
18-Jun-2010	9	Modified *Introduction* and *Description* Modified one reserved area (0x00 5055 to 0x00 509F) in *Table 7: General hardware register map* Modified*Table 4: STM8L101xx pin description*: modified note 2 and removed “wpu” for PC0 and PC1 Removed one note to *Table 22: HSI oscillator characteristics on page 45* Modified first paragraph in *Section : NRST pin* Modified OPT3 description in *Table 11: Option byte description* Added note 5 to *Table 18: Total current consumption in Run mode* Modified $V_{ESD(CDM)}$ in *Table 36: ESD absolute maximum ratings on page 61* Modified *Figure 36: Typical application with I2C bus and timing diagram 1) on page 59* Modified COMP_REF availability information in *Figure 52: STM8L101xx ordering information scheme on page 79* Modified *Section 12.2: Software tools on page 78*
21-Jul-2010	10	Modified *Table 3: Legend/abbreviation for table 4 on page 20* and *Table 4: STM8L101xx pin description on page 20* (for PA0, PA1, PB0 and PB4) Modified *Table 13: Voltage characteristics on page 38* and *Table 14: Current characteristics on page 39* Modified V_{IH} in *Table 26: I/O static characteristics on page 48* Added notes below UFQFPN32 package