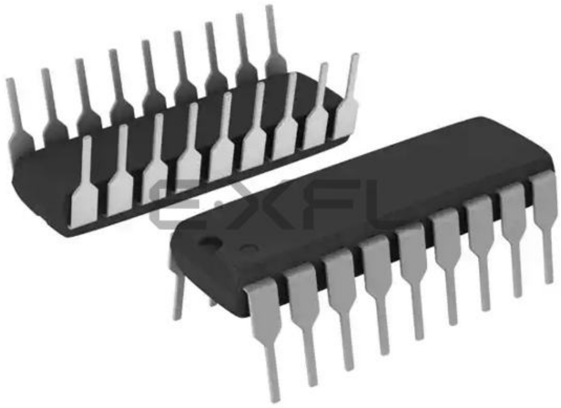

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Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	10MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	16
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	368 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	18-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf87-i-p

2.2.1 GENERAL PURPOSE REGISTER FILE

The register file can be accessed either directly, or indirectly, through the File Select Register (FSR).

FIGURE 2-2: PIC16F87 REGISTER FILE MAP

Bank 0	File Address	Bank 1	File Address	Bank 2	File Address	Bank 3	File Address
Indirect addr.(*)	00h	Indirect addr.(*)	80h	Indirect addr.(*)	100h	Indirect addr.(*)	180h
TMR0	01h	OPTION_REG	81h	TMR0	101h	OPTION_REG	181h
PCL	02h	PCL	82h	PCL	102h	PCL	182h
STATUS	03h	STATUS	83h	STATUS	103h	STATUS	183h
FSR	04h	FSR	84h	FSR	104h	FSR	184h
PORTA	05h	TRISA	85h	WDTCON	105h		185h
PORTB	06h	TRISB	86h	PORTB	106h	TRISB	186h
	07h		87h		107h		187h
	08h		88h		108h		188h
	09h		89h		109h		189h
PCLATH	0Ah	PCLATH	8Ah	PCLATH	10Ah	PCLATH	18Ah
INTCON	0Bh	INTCON	8Bh	INTCON	10Bh	INTCON	18Bh
PIR1	0Ch	PIE1	8Ch	EEDATA	10Ch	EECON1	18Ch
PIR2	0Dh	PIE2	8Dh	EEADR	10Dh	EECON2	18Dh
TMR1L	0Eh	PCON	8Eh	EEDATH	10Eh	Reserved(1)	18Eh
TMR1H	0Fh	OSCCON	8Fh	EEADRH	10Fh	Reserved(1)	18Fh
T1CON	10h	OSCTUNE	90h	General Purpose Register 16 Bytes	110h–11Fh	General Purpose Register 16 Bytes	190h–19Fh
TMR2	11h		91h				
T2CON	12h	PR2	92h				
SSPBUF	13h	SSPADD	93h				
SSPCON	14h	SSPSTAT	94h				
CCPR1L	15h		95h				
CCPR1H	16h		96h				
CCP1CON	17h		97h				
RCSTA	18h	TXSTA	98h				
TXREG	19h	SPBRG	99h				
RCREG	1Ah		9Ah				
	1Bh		9Bh				
	1Ch	CMCON	9Ch				
	1Dh	CVRCON	9Dh				
	1Eh		9Eh				
	1Fh		9Fh				
General Purpose Register 96 Bytes	20h–7Fh	General Purpose Register 80 Bytes	A0h–EFh	General Purpose Register 80 Bytes	120h–16Fh	General Purpose Register 80 Bytes	1A0h–1EFh
		accesses 70h-7Fh	F0h–FFh	accesses 70h-7Fh	170h–17Fh	accesses 70h-7Fh	1F0h–1FFh

[gray box] Unimplemented data memory locations, read as '0'.
* Not a physical register.

Note 1: This register is reserved, maintain this register clear.

2.2.2.2 OPTION_REG Register

The OPTION_REG register is a readable and writable register that contains various control bits to configure the TMR0 prescaler/WDT postscaler (single assignable register known also as the prescaler), the external INT interrupt, TMR0 and the weak pull-ups on PORTB.

> **Note:** To achieve a 1:1 prescaler assignment for the TMR0 register, assign the prescaler to the Watchdog Timer. Although the prescaler can be assigned to either the WDT or Timer0, but not both, a new divide counter is implemented in the WDT circuit to give multiple WDT time-out selections. This allows TMR0 and WDT to each have their own scaler. Refer to **Section 15.12 “Watchdog Timer (WDT)”** for further details.

REGISTER 2-2: OPTION_REG: OPTION CONTROL REGISTER (ADDRESS 81h, 181h)

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
$\overline{\text{RBPU}}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
bit 7							bit 0

bit 7 **$\overline{\text{RBPU}}$**: PORTB Pull-up Enable bit
1 = PORTB pull-ups are disabled
0 = PORTB pull-ups are enabled by individual port latch values

bit 6 **INTEDG:** Interrupt Edge Select bit
1 = Interrupt on rising edge of RB0/INT pin
0 = Interrupt on falling edge of RB0/INT pin

bit 5 **T0CS:** TMR0 Clock Source Select bit
1 = Transition on RA4/T0CKI/C2OUT pin
0 = Internal instruction cycle clock (CLKO)

bit 4 **T0SE:** TMR0 Source Edge Select bit
1 = Increment on high-to-low transition on RA4/T0CKI/C2OUT pin
0 = Increment on low-to-high transition on RA4/T0CKI/C2OUT pin

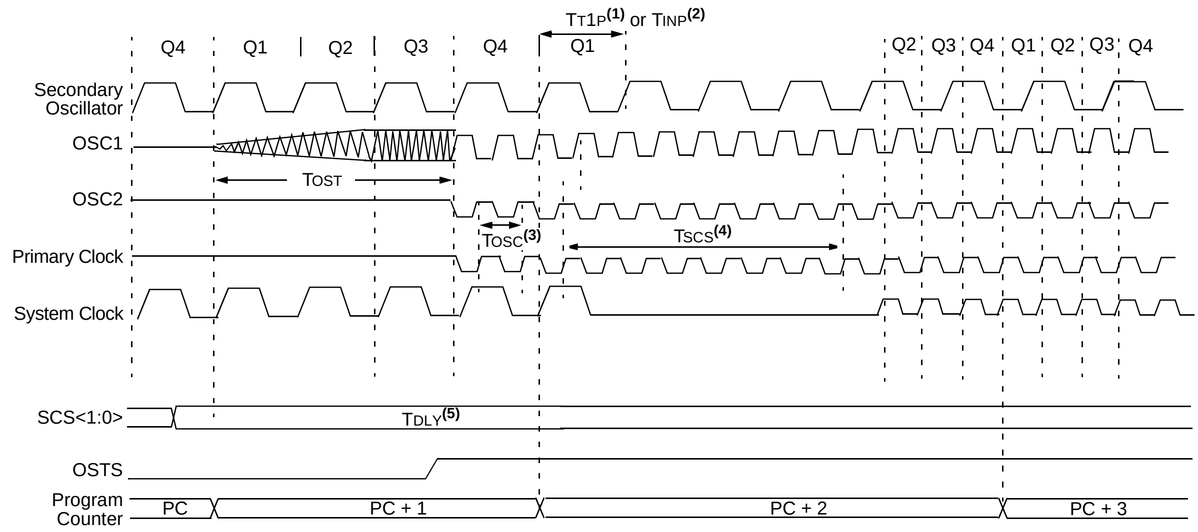
bit 3 **PSA:** Prescaler Assignment bit
1 = Prescaler is assigned to the WDT
0 = Prescaler is assigned to the Timer0 module

bit 2-0 **PS<2:0>:** Prescaler Rate Select bits

Bit Value	TMR0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

FIGURE 4-9: TIMING FOR TRANSITION BETWEEN SEC_RUN/RC_RUN AND PRIMARY CLOCK



Note 1: TT1P = 30.52 μs.
2: TINP = 32 μs typical.
3: TOSC = 50 ns minimum.
4: TSCS = 8 TINP OR 8 TT1P.
5: TDLY = 1 TINP OR 1 TT1P.

FIGURE 5-4: BLOCK DIAGRAM OF RA4/AN4/T0CKI/C2OUT PIN

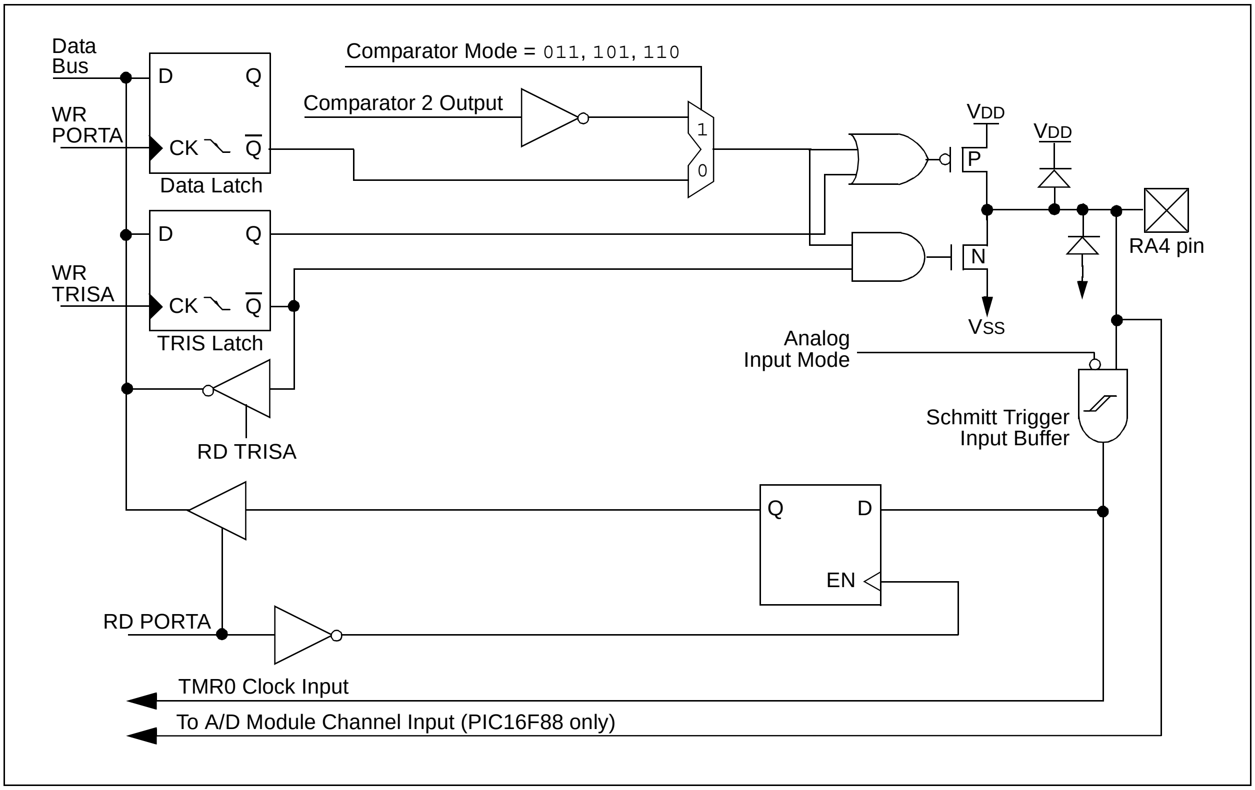


FIGURE 5-5: BLOCK DIAGRAM OF RA5/$\overline{MCLR}$/VPP PIN

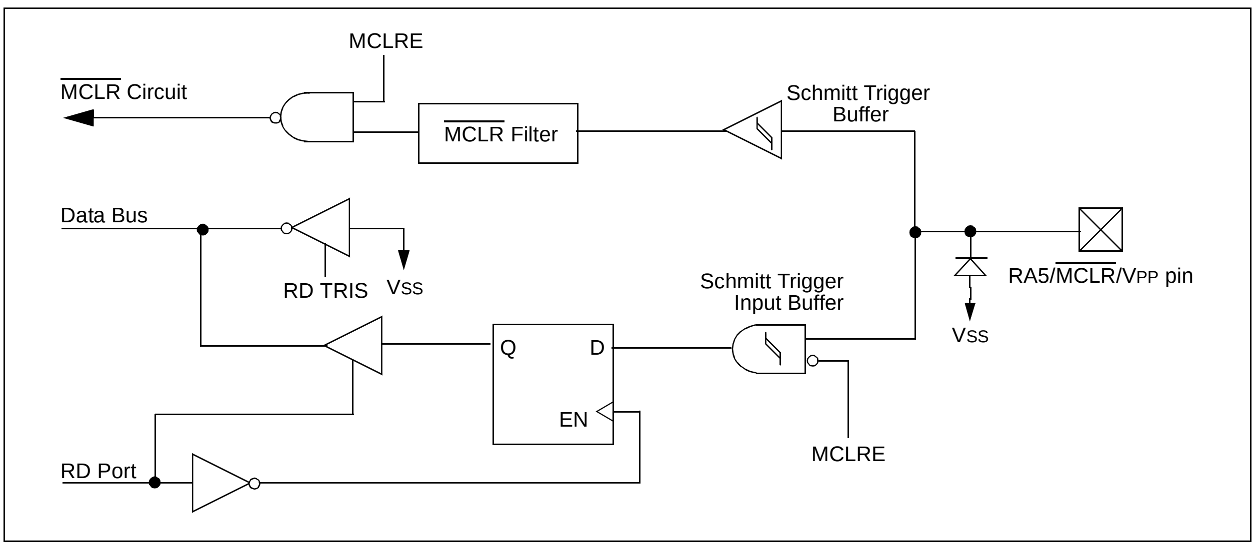
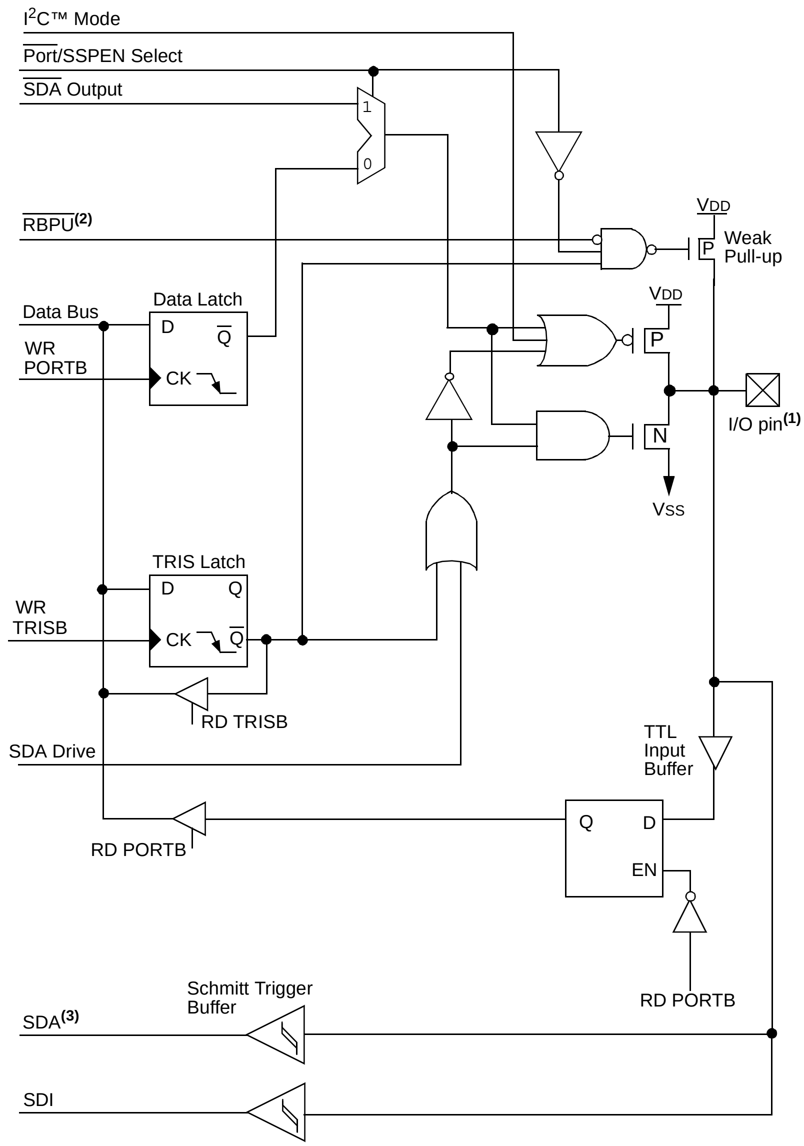


FIGURE 5-9: BLOCK DIAGRAM OF RB1/SDI/SDA PIN



Note 1: I/O pins have diode protection to VDD and VSS.

2: To enable weak pull-ups, set the appropriate TRIS bit(s) and clear the RBPU bit.

3: The SDA Schmitt conforms to the I2C specification.

10.3.1 SLAVE MODE

In Slave mode, the SCL and SDA pins must be configured as inputs (TRISB<4,1> set). The SSP module will override the input state with the output data when required (slave-transmitter).

When an address is matched, or the data transfer after an address match is received, the hardware automatically will generate the Acknowledge ($\overline{\text{ACK}}$) pulse and then load the SSPBUF register with the received value currently in the SSPSR register.

Either or both of the following conditions will cause the SSP module not to give this $\overline{\text{ACK}}$ pulse:

a) The Buffer Full bit, BF (SSPSTAT<0>), was set before the transfer was received.

b) The Overflow bit, SSPOV (SSPCON<6>), was set before the transfer was received.

In this case, the SSPSR register value is not loaded into the SSPBUF, but bit SSPIF (PIR1<3>) is set. Table 10-2 shows what happens when a data transfer byte is received, given the status of bits BF and SSPOV. The shaded cells show the condition where user software did not properly clear the overflow condition. Flag bit, BF, is cleared by reading the SSPBUF register while bit, SSPOV, is cleared through software.

The SCL clock input must have a minimum high and low for proper operation. The high and low times of the I^{2}C specification, as well as the requirement of the SSP module, are shown in timing parameter #100 and parameter #101.

10.3.1.1 Addressing

Once the SSP module has been enabled, it waits for a Start condition to occur. Following the Start condition, the eight bits are shifted into the SSPSR register. All incoming bits are sampled with the rising edge of the clock (SCL) line. The value of register SSPSR<7:1> is compared to the value of the SSPADD register. The address is compared on the falling edge of the eighth clock (SCL) pulse. If the addresses match and the BF and SSPOV bits are clear, the following events occur:

a) The SSPSR register value is loaded into the SSPBUF register.

b) The Buffer Full bit, BF, is set.

c) An $\overline{\text{ACK}}$ pulse is generated.

d) SSP Interrupt Flag bit, SSPIF (PIR1<3>), is set (interrupt is generated if enabled) – on the falling edge of the ninth SCL pulse.

In 10-bit Address mode, two address bytes need to be received by the slave device. The five Most Significant bits (MSbs) of the first address byte specify if this is a 10-bit address. Bit R/$\overline{\text{W}}$ (SSPSTAT<2>) must specify a write so the slave device will receive the second address byte. For a 10-bit address, the first byte would equal '`1111 0 A9 A8 0`', where `A9` and `A8` are the two MSbs of the address.

The sequence of events for 10-bit Address mode is as follows, with steps 7-9 for slave transmitter:

1. Receive first (high) byte of address (bits SSPIF, BF and UA (SSPSTAT<1>) are set).
2. Update the SSPADD register with second (low) byte of address (clears bit UA and releases the SCL line).
3. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.
4. Receive second (low) byte of address (bits SSPIF, BF and UA are set).
5. Update the SSPADD register with the first (high) byte of address; if match releases SCL line, this will clear bit UA.
6. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.
7. Receive Repeated Start condition.
8. Receive first (high) byte of address (bits SSPIF and BF are set).
9. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.

10.3.1.2 Reception

When the R/$\overline{\text{W}}$ bit of the address byte is clear and an address match occurs, the R/$\overline{\text{W}}$ bit of the SSPSTAT register is cleared. The received address is loaded into the SSPBUF register.

When the address byte overflow condition exists, then a no Acknowledge ($\overline{\text{ACK}}$) pulse is given. An overflow condition is indicated if either bit, BF (SSPSTAT<0>), is set or bit, SSPOV (SSPCON<6>), is set.

An SSP interrupt is generated for each data transfer byte. Flag bit, SSPIF (PIR1<3>), must be cleared in software. The SSPSTAT register is used to determine the status of the byte.

10.3.1.3 Transmission

When the R/$\overline{\text{W}}$ bit of the incoming address byte is set and an address match occurs, the R/$\overline{\text{W}}$ bit of the SSPSTAT register is set. The received address is loaded into the SSPBUF register. The $\overline{\text{ACK}}$ pulse will be sent on the ninth bit and pin RB4/SCK/SCL is held low. The transmit data must be loaded into the SSPBUF register which also loads the SSPSR register. Then, pin RB4/SCK/SCL should be enabled by setting bit CKP (SSPCON<4>). The master device must monitor the SCL pin prior to asserting another clock pulse. The slave devices may be holding off the master device by stretching the clock. The eight data bits are shifted out on the falling edge of the SCL input. This ensures that the SDA signal is valid during the SCL high time (Figure 10-7).

REGISTER 12-3: ADCON1: A/D CONTROL REGISTER 1 (ADDRESS 9Fh) PIC16F88 DEVICES ONLY

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
ADFM	ADCS2	VCFG1	VCFG0	—	—	—	—
bit 7							bit 0

bit 7 **ADFM:** A/D Result Format Select bit

1 = Right justified. Six Most Significant bits of ADRESH are read as '0'.
0 = Left justified. Six Least Significant bits of ADRESL are read as '0'.

bit 6 **ADCS2:** A/D Clock Divide by 2 Select bit

1 = A/D clock source is divided by 2 when system clock is used
0 = Disabled

bit 5-4 **VCFG<1:0>:** A/D Voltage Reference Configuration bits

Logic State	VREF+	VREF-
00	AVDD	AVSS
01	AVDD	VREF-
10	VREF+	AVSS
11	VREF+	VREF-

Note: The ANSEL bits for AN3 and AN2 inputs must be configured as analog inputs for the VREF+ and VREF- external pins to be used.

bit 3-0 **Unimplemented:** Read as '0'

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

12.4 Configuring Analog Port Pins

The ADCON1, ANSEL, TRISA and TRISB registers control the operation of the A/D port pins. The port pins that are desired as analog inputs must have their corresponding TRIS bits set (input). If the TRIS bit is cleared (output), the digital output level (V_{OH} or V_{OL}) will be converted.

The A/D operation is independent of the state of the CHS<2:0> bits and the TRIS bits.

Note 1:	When reading the Port register, all pins configured as analog input channels will read as cleared (a low level). Pins configured as digital inputs will convert an analog input. Analog levels on a digitally configured input will not affect the conversion accuracy.
2:	Analog levels on any pin that is defined as a digital input (including the RA4:RA0 and RB7:RB6 pins), may cause the input buffer to consume current out of the device specification.

12.5 A/D Conversions

Clearing the GO/$\overline{\text{DONE}}$ bit during a conversion will abort the current conversion. The A/D Result register pair will NOT be updated with the partially completed A/D conversion sample. That is, the ADRESH:ADRESL registers will continue to contain the value of the last completed conversion (or the last value written to the ADRESH:ADRESL registers). After the A/D conversion is aborted, a 2 T_{AD} wait is required before the next acquisition is started. After this 2 T_{AD} wait, acquisition on the selected channel is automatically started. The GO/$\overline{\text{DONE}}$ bit can then be set to start the conversion.

In Figure 12-3, after the GO/$\overline{\text{DONE}}$ bit is set, the first time segment has a minimum of T_{CY} and a maximum of T_{AD}.

Note:	The GO/$\overline{\text{DONE}}$ bit should **NOT** be set in the same instruction that turns on the A/D.

12.5.1 A/D RESULT REGISTERS

The ADRESH:ADRESL register pair is the location where the 10-bit A/D result is loaded at the completion of the A/D conversion. This register pair is 16 bits wide. The A/D module gives the flexibility to left or right justify the 10-bit result in the 16-bit result register. The A/D Format Select bit (ADFM) controls this justification. Figure 12-4 shows the operation of the A/D result justification. The extra bits are loaded with ‘0’s. When an A/D result will not overwrite these locations (A/D disable), these registers may be used as two general purpose 8-bit registers.

FIGURE 12-3: A/D CONVERSION T_{AD} CYCLES

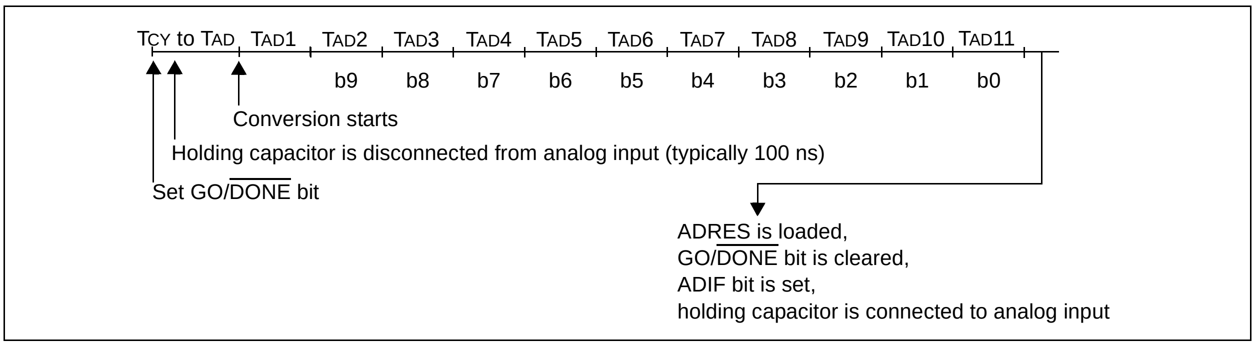


FIGURE 12-4: A/D RESULT JUSTIFICATION

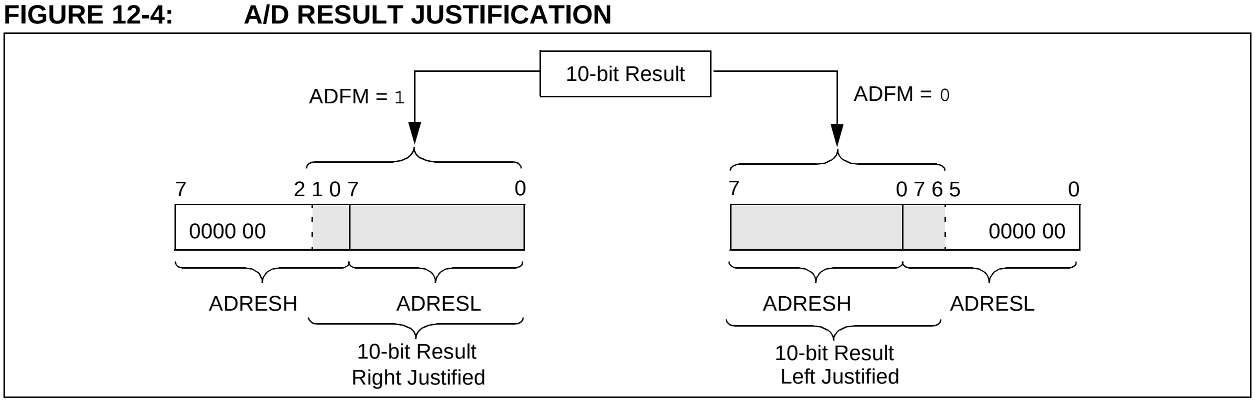


TABLE 15-3: RESET CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	STATUS Register	PCON Register
Power-on Reset	000h	`0001 1xxx`	`---- --0x`
$\overline{\text{MCLR}}$ Reset during normal operation	000h	`000u uuuu`	`---- --uu`
$\overline{\text{MCLR}}$ Reset during Sleep	000h	`0001 0uuu`	`---- --uu`
WDT Reset	000h	`0000 1uuu`	`---- --uu`
WDT Wake-up	PC + 1	`uuu0 0uuu`	`---- --uu`
Brown-out Reset	000h	`0001 1uuu`	`---- --u0`
Interrupt Wake-up from Sleep	PC + 1(1)	`uuu1 0uuu`	`---- --uu`

Legend: `u` = unchanged, `x` = unknown, - = unimplemented bit, read as '`0`'

Note 1: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

TABLE 15-4: INITIALIZATION CONDITIONS FOR ALL REGISTERS

Register	Power-on Reset, Brown-out Reset	$\overline{\text{MCLR}}$ Reset, WDT Reset	Wake-up via WDT or Interrupt
W	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
INDF	N/A	N/A	N/A
TMR0	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
PCL	`0000h`	`0000h`	PC + 1(2)
STATUS	`0001 1xxx`	`000q quuu`(3)	`uuuq quuu`(3)
FSR	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
PORTA (PIC16F87) PORTA (PIC16F88)	`xxxx 0000` `xxx0 0000`	`uuuu 0000` `uuu0 0000`	`uuuu uuuu` `uuuu uuuu`
PORTB (PIC16F87) PORTB (PIC16F87)	`xxxx xxxx` `00xx xxxx`	`uuuu uuuu` `00uu uuuu`	`uuuu uuuu` `uuuu uuuu`
PCLATH	`---0 0000`	`---0 0000`	`---u uuuu`
INTCON	`0000 000x`	`0000 000u`	`uuuu uuuu`(1)
PIR1	`-000 0000`	`-000 0000`	`-uuu uuuu`(1)
PIR2	`00-0 ----`	`00-0 ----`	`uu-u ----`(1)
TMR1L	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
TMR1H	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
T1CON	`-000 0000`	`-uuu uuuu`	`-uuu uuuu`
TMR2	`0000 0000`	`0000 0000`	`uuuu uuuu`
T2CON	`-000 0000`	`-000 0000`	`-uuu uuuu`
SSPBUF	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
SSPCON	`0000 0000`	`0000 0000`	`uuuu uuuu`
CCPR1L	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
CCPR1H	`xxxx xxxx`	`uuuu uuuu`	`uuuu uuuu`
CCP1CON	`--00 0000`	`--00 0000`	`--uu uuuu`
RCSTA	`0000 000x`	`0000 000x`	`uuuu uuuu`

Legend: `u` = unchanged, `x` = unknown, - = unimplemented bit, read as '`0`', `q` = value depends on condition

Note 1: One or more bits in INTCON, PIR1 and PR2 will be affected (to cause wake-up).

2: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

3: See Table 15-3 for Reset value for specific condition.

REGISTER 15-3: WDTCON: WATCHDOG CONTROL REGISTER (ADDRESS 105h)

U-0	U-0	U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	SWDTEN(1)
bit 7							bit 0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-1 **WDTPS<3:0>:** Watchdog Timer Period Select bits

Bit Value		Prescale Rate
0000	=	1:32
0001	=	1:64
0010	=	1:128
0011	=	1:256
0100	=	1:512
0101	=	1:1024
0110	=	1:2048
0111	=	1:4096
1000	=	1:8192
1001	=	1:16394
1010	=	1:32768
1011	=	1:65536

bit 0 **SWDTEN:** Software Enable/Disable for Watchdog Timer bit(1)

1 = WDT is turned on
0 = WDT is turned off

Note 1: If WDTEN configuration bit = 1, then WDT is always enabled, irrespective of this control bit. If WDTEN configuration bit = 0, then it is possible to turn WDT on/off with this control bit.

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

TABLE 15-6: SUMMARY OF WATCHDOG TIMER REGISTERS

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
81h,181h	OPTION_REG	$\overline{\text{RBPU}}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
2007h	Configuration bits	LVP	BOREN	MCLRE	FOSC2	$\overline{\text{PWRTEN}}$	WDTEN	FOSC1	FOSC0
105h	WDTCON	—	—	—	WDTPS3	$\overline{\text{WDTPS2}}$	WSTPS1	WDTPS0	SWDTEN

Legend: Shaded cells are not used by the Watchdog Timer.
Note 1: See Register 15-1 for operation of these bits.

15.12.4.2 FSCM and the Watchdog Timer

When a clock failure is detected, SCS<1:0> will be forced to '10' which will reset the WDT (if enabled).

15.12.4.3 POR or Wake From Sleep

The FSCM is designed to detect oscillator failure at any point after the device has exited Power-on Reset (POR) or low-power Sleep mode. When the primary system clock is EC, RC or INTRC modes, monitoring can begin immediately following these events.

For Oscillator modes involving a crystal or resonator (HS, LP or XT), the situation is somewhat different. Since the oscillator may require a start-up time considerably longer than the FSCM sample clock time, a false clock failure may be detected. To prevent this, the internal oscillator block is automatically configured as the system clock and functions until the primary clock is stable (the OST timer has timed out). This is identical to Two-Speed Start-up mode. Once the primary clock is stable, the INTRC returns to its role as the FSCM source.

Note:	The same logic that prevents false oscillator failure interrupts on port or wake from Sleep, will also prevent the detection of the oscillator's failure to start at all following these events. This can be avoided by monitoring the OSTS bit and using a timing routine to determine if the oscillator is taking too long to start. Even so, no oscillator failure interrupt will be flagged.

15.12.4.4 Example Fail-Safe Conditions

1. CONDITIONS:

   The device is clocked from a crystal, crystal operation fails and then Sleep mode is entered.

   OSTS = 0

   SCS = 00

   OSFIF = 1

   USER ACTION:

   Sleep mode will exit the fail-safe condition. Therefore, if the user code did not handle the detected fail-safe prior to the SLEEP command, then upon wake-up, the device will try to start the crystal that failed and a fail-safe condition will not be detected. Monitoring the OSTS bit will determine if the crystal is operating. The user should not enter Sleep mode without handling the fail-safe condition first.

2. CONDITIONS:

   After a POR (Power-on Reset), the device is running in Two-Speed Start-up mode. The crystal fails before the OST has expired. If a crystal fails during the OST period, a fail-safe condition will not be detected (OSFIF will not get set).

   OSTS = 0

   SCS = 00

   OSFIF = 0

   USER ACTION:

   Check the OSTS bit. If it's clear and the OST should have expired at this point, then the user can assume the crystal has failed. The user should change the SCS bit to cause a clock switch which will also release the 10-bit ripple counter for WDT operation (if enabled).

3. CONDITIONS:

   The device is clocked from a crystal during normal operation and it fails.

   OSTS = 0

   SCS = 00

   OSFIF = 1

   USER ACTION:

   Clear the OSFIF bit. Configure the SCS bits for a clock switch and the fail-safe condition will be cleared. Later, if the user decides to, the crystal can be retried for operation. If this is done, the OSTS bit should be monitored to determine if the crystal operates.

15.13 Power-Down Mode (Sleep)

Power-Down mode is entered by executing a SLEEP instruction.

If enabled, the Watchdog Timer will be cleared but keeps running, the $\overline{PD}$ bit (STATUS<3>) is cleared, the $\overline{TO}$ (STATUS<4>) bit is set and the oscillator driver is turned off. The I/O ports maintain the status they had before the SLEEP instruction was executed (driving high, low or high-impedance).

For lowest current consumption in this mode, place all I/O pins at either V_{DD} or V_{SS}, ensure no external circuitry is drawing current from the I/O pin, power-down the A/D and disable external clocks. Pull all I/O pins that are high-impedance inputs, high or low externally, to avoid switching currents caused by floating inputs. The T0CKI input should also be at V_{DD} or V_{SS} for lowest current consumption. The contribution from on-chip pull-ups on PORTB should also be considered.

The $\overline{MCLR}$ pin must be at a logic high level (V_{IHMC}).

16.2 Instruction Descriptions

ADDLW	**Add Literal and W**
Syntax:	[*label*] ADDLW k
Operands:	$0 \le k \le 255$
Operation:	(W) + k → (W)
Status Affected:	C, DC, Z
Description:	The contents of the W register are added to the eight-bit literal 'k' and the result is placed in the W register.

ADDWF	**Add W and f**
Syntax:	[*label*] ADDWF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(W) + (f) → (destination)
Status Affected:	C, DC, Z
Description:	Add the contents of the W register with register 'f'. If 'd' = `0`, the result is stored in the W register. If 'd' = `1`, the result is stored back in register 'f'.

ANDLW	**AND Literal with W**
Syntax:	[*label*] ANDLW k
Operands:	$0 \le k \le 255$
Operation:	(W) .AND. (k) → (W)
Status Affected:	Z
Description:	The contents of W register are AND'ed with the eight-bit literal 'k'. The result is placed in the W register.

ANDWF	**AND W with f**
Syntax:	[*label*] ANDWF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(W) .AND. (f) → (destination)
Status Affected:	Z
Description:	AND the W register with register 'f'. If 'd' = `0`, the result is stored in the W register. If 'd' = `1`, the result is stored back in register 'f'.

BCF	**Bit Clear f**
Syntax:	[*label*] BCF f,b
Operands:	$0 \le f \le 127$ $0 \le b \le 7$
Operation:	0 → (f<b>)
Status Affected:	None
Description:	Bit 'b' in register 'f' is cleared.

BSF	**Bit Set f**
Syntax:	[*label*] BSF f,b
Operands:	$0 \le f \le 127$ $0 \le b \le 7$
Operation:	1 → (f<b>)
Status Affected:	None
Description:	Bit 'b' in register 'f' is set.

BTFSS	**Bit Test f, Skip if Set**
Syntax:	[*label*] BTFSS f,b
Operands:	0 ≤ f ≤ 127 0 ≤ b < 7
Operation:	skip if (f<b>) = `1`
Status Affected:	None
Description:	If bit 'b' in register 'f' = `0`, the next instruction is executed. If bit 'b' = `1`, then the next instruction is discarded and a `NOP` is executed instead, making this a 2 TCY instruction.

BTFSC	**Bit Test, Skip if Clear**
Syntax:	[*label*] BTFSC f,b
Operands:	0 ≤ f ≤ 127 0 ≤ b ≤ 7
Operation:	skip if (f<b>) = `0`
Status Affected:	None
Description:	If bit 'b' in register 'f' = `1`, the next instruction is executed. If bit 'b', in register 'f', = `0`, the next instruction is discarded and a `NOP` is executed instead, making this a 2 TCY instruction.

CALL	**Call Subroutine**
Syntax:	[*label*] CALL k
Operands:	0 ≤ k ≤ 2047
Operation:	(PC) + 1 → TOS, k → PC<10:0>, (PCLATH<4:3>) → PC<12:11>
Status Affected:	None
Description:	Call subroutine. First, return address (PC + 1) is pushed onto the stack. The eleven-bit immediate address is loaded into PC bits <10:0>. The upper bits of the PC are loaded from PCLATH. `CALL` is a two-cycle instruction.

CLRF	**Clear f**
Syntax:	[*label*] CLRF f
Operands:	0 ≤ f ≤ 127
Operation:	00h → (f), 1 → Z
Status Affected:	Z
Description:	The contents of register 'f' are cleared and the Z bit is set.

CLRW	**Clear W**
Syntax:	[*label*] CLRW
Operands:	None
Operation:	00h → (W), 1 → Z
Status Affected:	Z
Description:	W register is cleared. Zero bit (Z) is set.

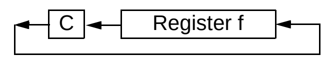
CLRWDT	**Clear Watchdog Timer**
Syntax:	[*label*] CLRWDT
Operands:	None
Operation:	00h → WDT, 0 → WDT prescaler, 1 → $\overline{TO}$, 1 → $\overline{PD}$
Status Affected:	$\overline{TO}$, $\overline{PD}$
Description:	`CLRWDT` instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits $\overline{TO}$ and $\overline{PD}$ are set.

RETFIE	Return from Interrupt
Syntax:	[*label*] RETFIE
Operands:	None
Operation:	TOS → PC, 1 → GIE
Status Affected:	None

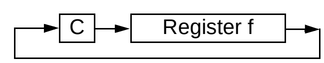
RETLW	Return with Literal in W
Syntax:	[*label*] RETLW k
Operands:	0 ≤ k ≤ 255
Operation:	k → (W); TOS → PC
Status Affected:	None
Description:	The W register is loaded with the eight-bit literal ‘k’. The program counter is loaded from the top of the stack (the return address). This is a two-cycle instruction.

RETURN	Return from Subroutine
Syntax:	[*label*] RETURN
Operands:	None
Operation:	TOS → PC
Status Affected:	None
Description:	Return from subroutine. The stack is POPed and the top of the stack (TOS) is loaded into the program counter. This is a two-cycle instruction.

RLF	Rotate Left f through Carry
Syntax:	[*label*] RLF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	See description below
Status Affected:	C
Description:	The contents of register ‘f’ are rotated one bit to the left through the Carry flag. If ‘d’ = `0`, the result is placed in the W register. If ‘d’ = `1`, the result is stored back in register ‘f’.

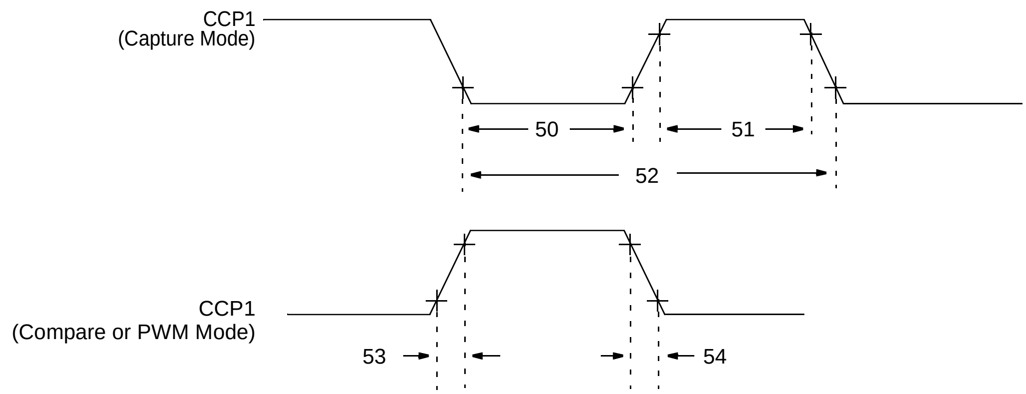


RRF	Rotate Right f through Carry
Syntax:	[*label*] RRF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	See description below
Status Affected:	C
Description:	The contents of register ‘f’ are rotated one bit to the right through the Carry flag. If ‘d’ = `0`, the result is placed in the W register. If ‘d’ = `1`, the result is placed back in register ‘f’.



SLEEP	Sleep
Syntax:	[*label*] SLEEP
Operands:	None
Operation:	00h → WDT, 0 → WDT prescaler, 1 → $\overline{TO}$, 0 → $\overline{PD}$
Status Affected:	$\overline{TO}$, $\overline{PD}$
Description:	The Power-Down status bit, $\overline{PD}$, is cleared. Time-out status bit, $\overline{TO}$, is set. Watchdog Timer and its prescaler are cleared. The processor is put into Sleep mode with the oscillator stopped.

FIGURE 18-9: CAPTURE/COMPARE/PWM TIMINGS (CCP1)



Note: Refer to Figure 18-3 for load conditions.

TABLE 18-7: CAPTURE/COMPARE/PWM REQUIREMENTS (CCP1)

Param No.	Symbol	Characteristic			Min	Typ†	Max	Units	Conditions
50*	TccL	CCP1 Input Low Time	No Prescaler		0.5 TCY + 20	—	—	ns	
			With Prescaler	PIC16**F**87/88	10	—	—	ns	
				PIC16**LF**87/88	20	—	—	ns	
51*	TccH	CCP1 Input High Time	No Prescaler		0.5 TCY + 20	—	—	ns	
			With Prescaler	PIC16**F**87/88	10	—	—	ns	
				PIC16**LF**87/88	20	—	—	ns	
52*	TccP	CCP1 Input Period			$\frac{3 T_{CY} + 40}{N}$	—	—	ns	N = prescale value (1, 4 or 16)
53*	TccR	CCP1 Output Rise Time		PIC16**F**87/88	—	10	25	ns	
				PIC16**LF**87/88	—	25	50	ns	
54*	TccF	CCP1 Output Fall Time		PIC16**F**87/88	—	10	25	ns	
				PIC16**LF**87/88	—	25	45	ns	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 19-3: TYPICAL IDD vs. FOSC OVER VDD (XT MODE)

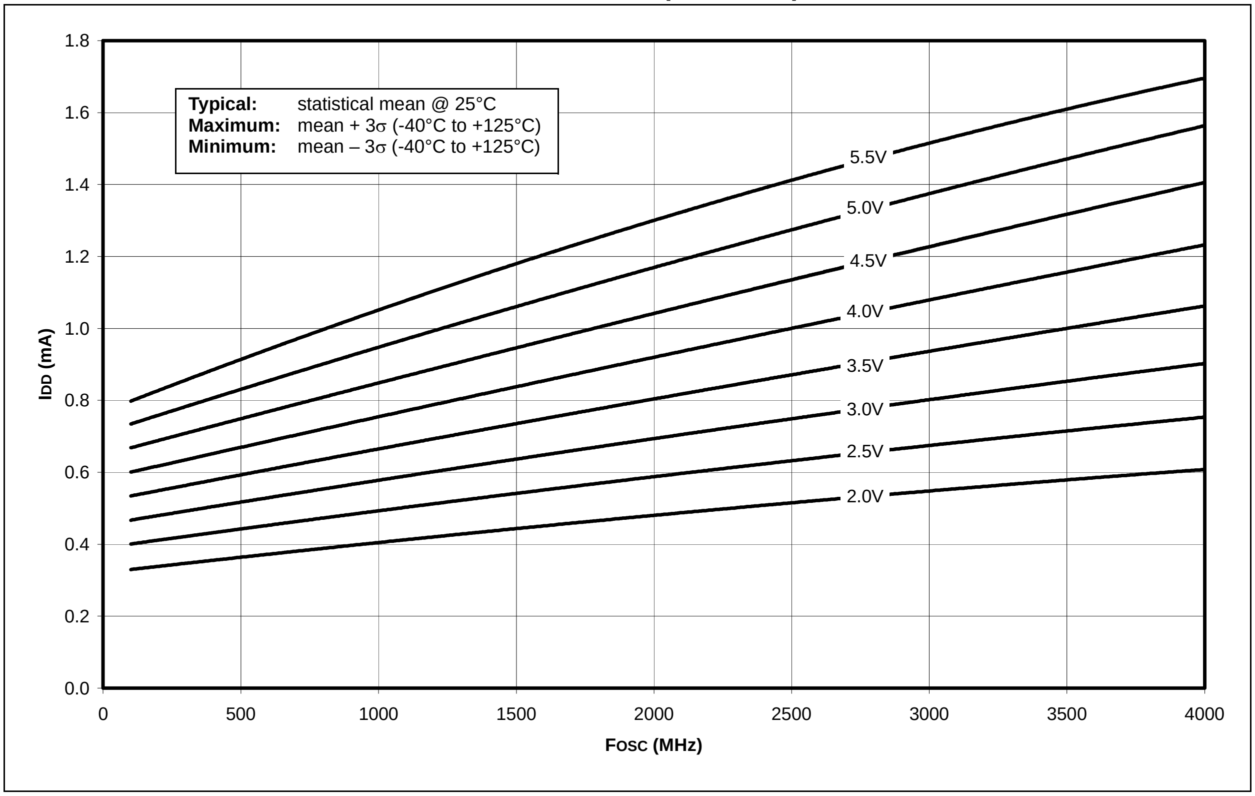


FIGURE 19-4: MAXIMUM IDD vs. FOSC OVER VDD (XT MODE)

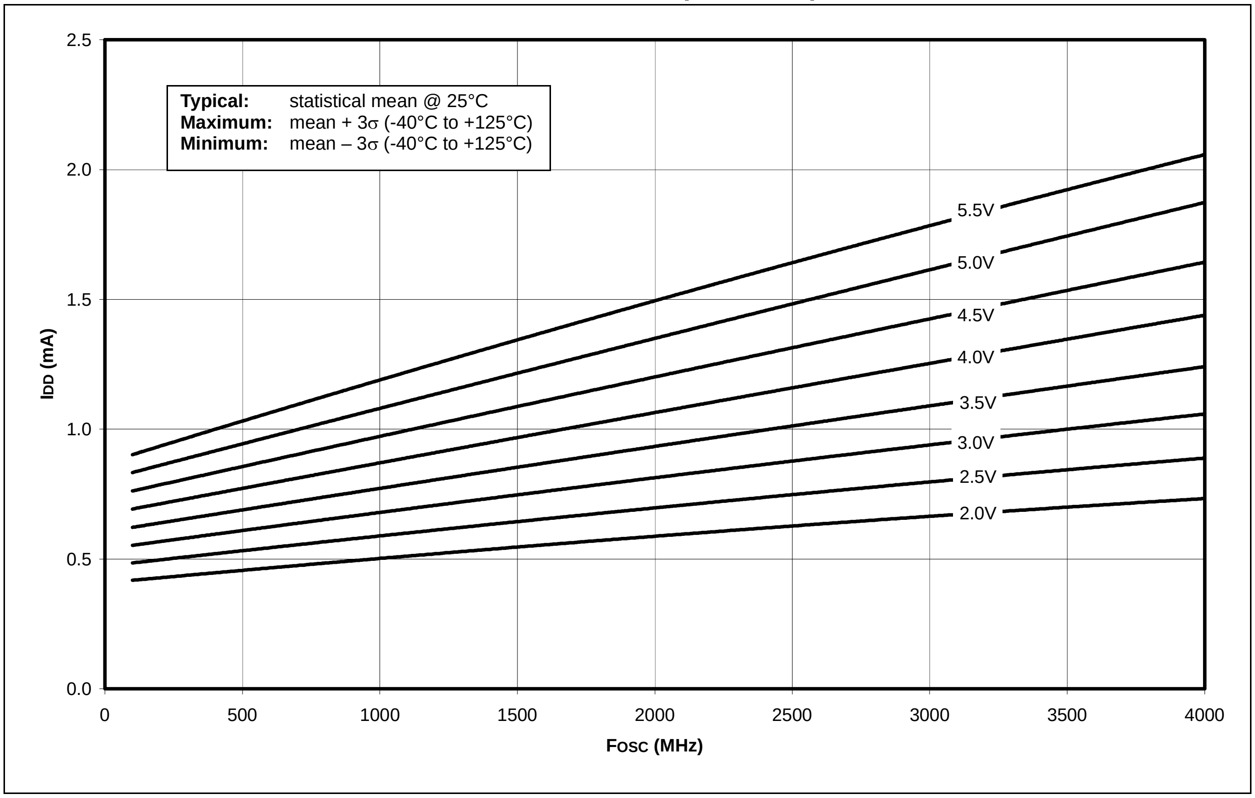


FIGURE 19-21: TYPICAL, MINIMUM AND MAXIMUM VOL vs. IOL (VDD = 3V, -40°C TO +125°C)

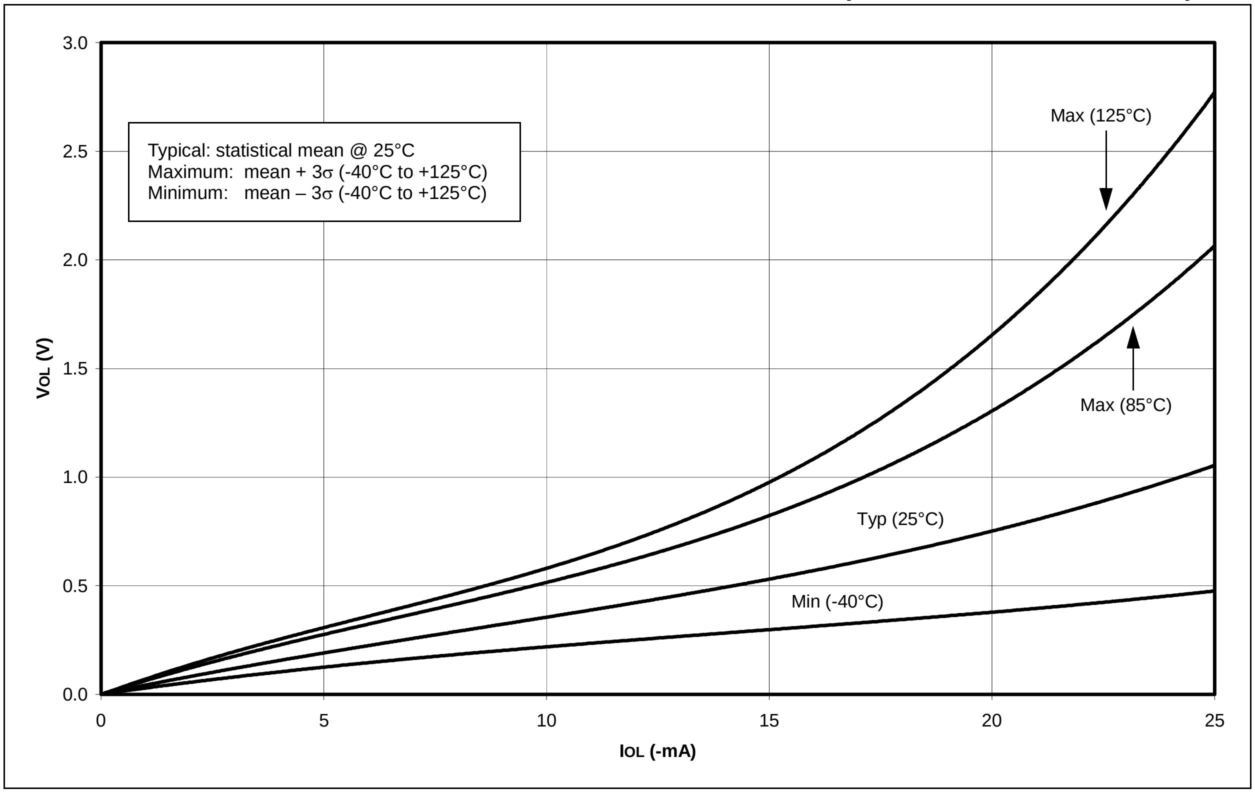
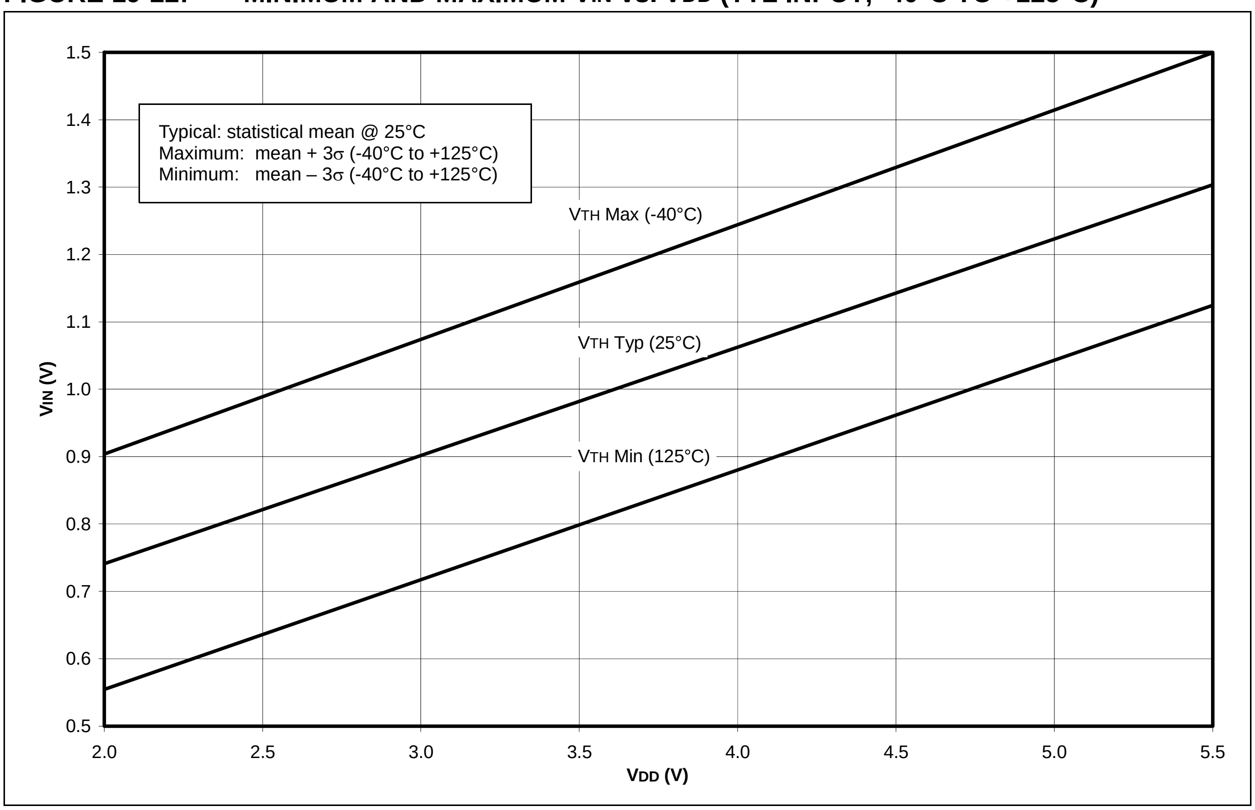


FIGURE 19-22: MINIMUM AND MAXIMUM VIN vs. VDD (TTL INPUT, -40°C TO +125°C)



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