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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	10MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	16
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	368 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	A/D 7x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf88t-i-ss

PIC16F87/88

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TABLE 1-2: PIC16F87/88 PINOUT DESCRIPTION (CONTINUED)

Pin Name	PDIP/ SOIC Pin#	SSOP Pin#	QFN Pin#	I/O/P Type	Buffer Type	Description
RB0/INT/CCP1 ⁽⁵⁾ RB0 INT CCP1	6	7	7	I/O I I/O	TTL ST ⁽¹⁾ ST	PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-up on all inputs. Bidirectional I/O pin. External interrupt pin. Capture input, Compare output, PWM output.
RB1/SDI/SDA RB1 SDI SDA	7	8	8	I/O I I/O	TTL ST ST	Bidirectional I/O pin. SPI data in. I ² C™ data.
RB2/SDO/RX/DT RB2 SDO RX DT	8	9	9	I/O O I I/O	TTL ST ST ST	Bidirectional I/O pin. SPI data out. AUSART asynchronous receive. AUSART synchronous detect.
RB3/PGM/CCP1 ⁽⁵⁾ RB3 PGM CCP1	9	10	10	I/O I/O I	TTL ST ST	Bidirectional I/O pin. Low-Voltage ICSP™ Programming enable pin. Capture input, Compare output, PWM output.
RB4/SCK/SCL RB4 SCK SCL	10	11	12	I/O I/O I	TTL ST ST	Bidirectional I/O pin. Interrupt-on-change pin. Synchronous serial clock input/output for SPI. Synchronous serial clock Input for I ² C.
RB5/ \overline{SS} /TX/CK RB5 \overline{SS} TX CK	11	12	13	I/O I O I/O	TTL TTL ST ST	Bidirectional I/O pin. Interrupt-on-change pin. Slave select for SPI in Slave mode. AUSART asynchronous transmit. AUSART synchronous clock.
RB6/AN5/PGC/T1OSO/ T1CKI RB6 AN5 ⁽⁴⁾ PGC T1OSO T1CKI	12	13	15	I/O I I/O O I	TTL TTL ST ⁽²⁾ ST ST	Bidirectional I/O pin. Interrupt-on-change pin. Analog input channel 5. In-Circuit Debugger and programming clock pin. Timer1 oscillator output. Timer1 external clock input.
RB7/AN6/PGD/T1OSI RB7 AN6 ⁽⁴⁾ PGD T1OSI	13	14	16	I/O I I I	TTL TTL ST ⁽²⁾ ST	Bidirectional I/O pin. Interrupt-on-change pin. Analog input channel 6. In-Circuit Debugger and ICSP programming data pin. Timer1 oscillator input.
Vss	5	5, 6	3, 5	P	–	Ground reference for logic and I/O pins.
VDD	14	15, 16	17, 19	P	–	Positive supply for logic and I/O pins.

Legend: I = Input O = Output I/O = Input/Output P = Power
 – = Not used TTL = TTL Input ST = Schmitt Trigger Input

- Note 1:** This buffer is a Schmitt Trigger input when configured as the external interrupt.
2: This buffer is a Schmitt Trigger input when used in Serial Programming mode.
3: This buffer is a Schmitt Trigger input when configured in RC Oscillator mode and a CMOS input otherwise.
4: PIC16F88 devices only.
5: The CCP1 pin is determined by the CCPMX bit in Configuration Word 1 register.

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2.2.2.2 OPTION_REG Register

The OPTION_REG register is a readable and writable register that contains various control bits to configure the TMR0 prescaler/WDT postscaler (single assignable register known also as the prescaler), the external INT interrupt, TMR0 and the weak pull-ups on PORTB.

Note: To achieve a 1:1 prescaler assignment for the TMR0 register, assign the prescaler to the Watchdog Timer. Although the prescaler can be assigned to either the WDT or Timer0, but not both, a new divide counter is implemented in the WDT circuit to give multiple WDT time-out selections. This allows TMR0 and WDT to each have their own scaler. Refer to **Section 15.12 “Watchdog Timer (WDT)”** for further details.

REGISTER 2-2: OPTION_REG: OPTION CONTROL REGISTER (ADDRESS 81h, 181h)

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0

bit 7

bit 0

- bit 7 **RBPU:** PORTB Pull-up Enable bit
1 = PORTB pull-ups are disabled
0 = PORTB pull-ups are enabled by individual port latch values
- bit 6 **INTEDG:** Interrupt Edge Select bit
1 = Interrupt on rising edge of RB0/INT pin
0 = Interrupt on falling edge of RB0/INT pin
- bit 5 **T0CS:** TMR0 Clock Source Select bit
1 = Transition on RA4/T0CKI/C2OUT pin
0 = Internal instruction cycle clock (CLKO)
- bit 4 **T0SE:** TMR0 Source Edge Select bit
1 = Increment on high-to-low transition on RA4/T0CKI/C2OUT pin
0 = Increment on low-to-high transition on RA4/T0CKI/C2OUT pin
- bit 3 **PSA:** Prescaler Assignment bit
1 = Prescaler is assigned to the WDT
0 = Prescaler is assigned to the Timer0 module
- bit 2-0 **PS<2:0>:** Prescaler Rate Select bits

Bit Value	TMR0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

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4.6.3 CLOCK TRANSITION AND WDT

When clock switching is performed, the Watchdog Timer is disabled because the Watchdog ripple counter is used as the Oscillator Start-up Timer.

Note: The OST is only used when switching to XT, HS and LP Oscillator modes.

Once the clock transition is complete (i.e., new oscillator selection switch has occurred), the Watchdog counter is re-enabled with the counter reset. This allows the user to synchronize the Watchdog Timer to the start of execution at the new clock frequency.

REGISTER 4-2: OSCCON: OSCILLATOR CONTROL REGISTER (ADDRESS 8Fh)

U-0	R/W-0	R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0
—	IRCF2	IRCF1	IRCF0	OSTS ⁽¹⁾	IOFS	SCS1	SCS0
bit 7							bit 0

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IRCF<2:0>:** Internal RC Oscillator Frequency Select bits

- 000 = 31.25 kHz
- 001 = 125 kHz
- 010 = 250 kHz
- 011 = 500 kHz
- 100 = 1 MHz
- 101 = 2 MHz
- 110 = 4 MHz
- 111 = 8 MHz

bit 3 **OSTS:** Oscillator Start-up Time-out Status bit⁽¹⁾

- 1 = Device is running from the primary system clock
- 0 = Device is running from T1OSC or INTRC as a secondary system clock

Note 1: Bit resets to '0' with Two-Speed Start-up mode and LP, XT or HS selected as the oscillator mode.

bit 2 **IOFS:** INTOSC Frequency Stable bit

- 1 = Frequency is stable
- 0 = Frequency is not stable

bit 1-0 **SCS<1:0>:** Oscillator Mode Select bits

- 00 = Oscillator mode defined by FOSC<2:0>
- 01 = T1OSC is used for system clock
- 10 = Internal RC is used for system clock
- 11 = Reserved

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

EXAMPLE 6-1: CHANGING THE PRESCALER ASSIGNMENT FROM WDT TO TIMER0

```

CLRWDT          ; Clear WDT and prescaler
BANKSEL OPTION_REG ; Select Bank of OPTION_REG
MOVLW  b'xxxx0xxx' ; Select TMR0, new prescale
MOVWF  OPTION_REG ; value and clock source
    
```

TABLE 6-1: REGISTERS ASSOCIATED WITH TIMER0

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
01h,101h	TMR0	Timer0 Module Register								xxxx xxxx	uuuu uuuu
0Bh,8Bh, 10Bh,18Bh	INTCON	GIE	PEIE	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIF	0000 000x	0000 000u
81h,181h	OPTION_REG	RBP \bar{U}	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged. Shaded cells are not used by Timer0.

7.2 Timer1 Operation in Timer Mode

Timer mode is selected by clearing the TMR1CS (T1CON<1>) bit. In this mode, the input clock to the timer is $F_{osc}/4$. The synchronize control bit, T1SYNC (T1CON<2>), has no effect since the internal clock is always in sync.

7.3 Timer1 Counter Operation

Timer1 may operate in Asynchronous or Synchronous mode, depending on the setting of the TMR1CS bit.

When Timer1 is being incremented via an external source, increments occur on a rising edge. After Timer1 is enabled in Counter mode, the module must first have a falling edge before the counter begins to increment.

7.4 Timer1 Operation in Synchronized Counter Mode

Counter mode is selected by setting bit TMR1CS. In this mode, the timer increments on every rising edge of clock input on pin RB7/PGD/T1OSI when bit T1OSCEN is set, or on pin RB6/PGC/T1OSO/T1CKI when bit T1OSCEN is cleared.

If T1SYNC is cleared, then the external clock input is synchronized with internal phase clocks. The synchronization is done after the prescaler stage. The prescaler stage is an asynchronous ripple counter.

In this configuration, during Sleep mode, Timer1 will not increment even if the external clock is present since the synchronization circuit is shut off. The prescaler, however, will continue to increment.

FIGURE 7-1: TIMER1 INCREMENTING EDGE

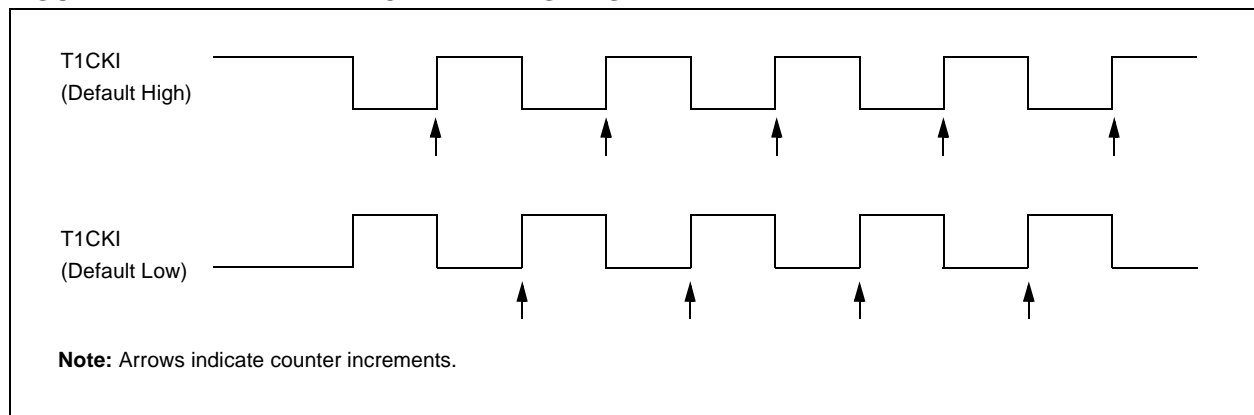
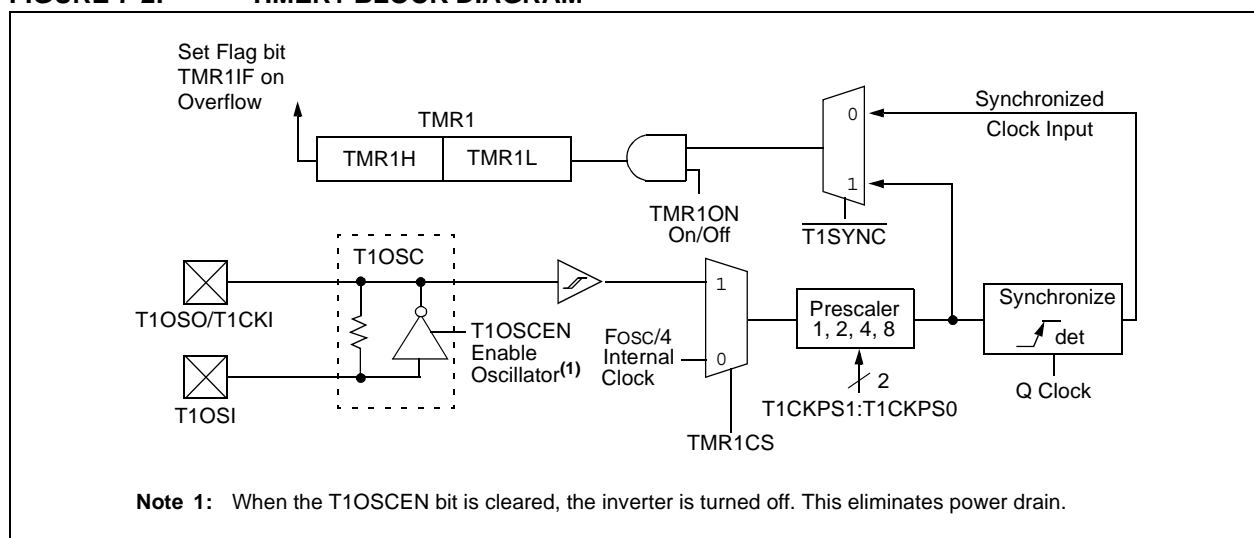


FIGURE 7-2: TIMER1 BLOCK DIAGRAM



When setting up an asynchronous reception, follow these steps:

1. Initialize the SPBRG register for the appropriate baud rate. If a high-speed baud rate is desired, set bit BRGH (Section 11.1 “AUSART Baud Rate Generator (BRG)”).
2. Enable the asynchronous serial port by clearing bit SYNC and setting bit SPEN.
3. If interrupts are desired, then set enable bit RCIE.
4. If 9-bit reception is desired, then set bit RX9.
5. Enable the reception by setting bit CREN.
6. Flag bit RCIF will be set when reception is complete and an interrupt will be generated if enable bit RCIE is set.
7. Read the RCSTA register to get the ninth bit (if enabled) and determine if any error occurred during reception.
8. Read the 8-bit received data by reading the RCREG register.
9. If any error occurred, clear the error by clearing enable bit CREN.
10. If using interrupts, ensure that GIE and PEIE (bits 7 and 6) of the INTCON register are set.

TABLE 11-8: REGISTERS ASSOCIATED WITH ASYNCHRONOUS RECEPTION

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
0Bh, 8Bh, 10Bh, 18Bh	INTCON	GIE	PEIE	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIG	0000 000x	0000 000u
0Ch	PIR1	—	ADIF ⁽¹⁾	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
18h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
1Ah	RCREG	AUSART Receive Data Register								0000 0000	0000 0000
8Ch	PIE1	—	ADIE ⁽¹⁾	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
99h	SPBRG	Baud Rate Generator Register								0000 0000	0000 0000

Legend: x = unknown, - = unimplemented locations read as '0'. Shaded cells are not used for asynchronous reception.

Note 1: This bit is only implemented on the PIC16F88. The bit will read '0' on the PIC16F87.

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11.3.2 AUSART SYNCHRONOUS MASTER RECEPTION

Once Synchronous mode is selected, reception is enabled by setting either enable bit SREN (RCSTA<5>), or enable bit CREN (RCSTA<4>). Data is sampled on the RB2/SDO/RX/DT pin on the falling edge of the clock. If enable bit SREN is set, then only a single word is received. If enable bit CREN is set, the reception is continuous until CREN is cleared. If both bits are set, CREN takes precedence.

After clocking the last bit, the received data in the Receive Shift Register (RSR) is transferred to the RCREG register (if it is empty). When the transfer is complete, interrupt flag bit, RCIF (PIR1<5>), is set. The actual interrupt can be enabled/disabled by setting/clearing enable bit RCIE (PIE1<5>).

Flag bit RCIF is a read-only bit which is reset by the hardware. In this case, it is reset when the RCREG register has been read and is empty. The RCREG is a double-buffered register (i.e., it is a two-deep FIFO). It is possible for two bytes of data to be received and transferred to the RCREG FIFO and a third byte to begin shifting into the RSR register. On the clocking of the last bit of the third byte, if the RCREG register is still full, then Overrun Error bit, OERR (RCSTA<1>), is set. The word in the RSR will be lost. The RCREG register can be read twice to retrieve the two bytes in the FIFO. Bit OERR has to be cleared in software (by clearing bit CREN). If bit OERR is set, transfers from the RSR to the RCREG are inhibited, so it is essential to clear bit OERR if it is set. The ninth receive bit is buffered the same way as the

receive data. Reading the RCREG register will load bit RX9D with a new value, therefore, it is essential for the user to read the RCSTA register, before reading RCREG, in order not to lose the old RX9D information.

When setting up a synchronous master reception:

1. Initialize the SPBRG register for the appropriate baud rate (**Section 11.1 “AUSART Baud Rate Generator (BRG)”**).
2. Enable the synchronous master serial port by setting bits SYNC, SPEN and CSRC.
3. Ensure bits CREN and SREN are clear.
4. If interrupts are desired, then set enable bit RCIE.
5. If 9-bit reception is desired, then set bit RX9.
6. If a single reception is required, set bit SREN. For continuous reception, set bit CREN.
7. Interrupt flag bit, RCIF, will be set when reception is complete and an interrupt will be generated if enable bit, RCIE, was set.
8. Read the RCSTA register to get the ninth bit (if enabled) and determine if any error occurred during reception.
9. Read the 8-bit received data by reading the RCREG register.
10. If any error occurred, clear the error by clearing bit CREN.
11. If using interrupts, ensure that GIE and PEIE (bits 7 and 6) of the INTCON register are set.

TABLE 11-11: REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
0Bh, 8Bh, 10Bh, 18Bh	INTCON	GIE	PEIE	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIF	0000 000x	0000 000u
0Ch	PIR1	—	ADIF ⁽¹⁾	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
18h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
1Ah	RCREG	AUSART Receive Data Register								0000 0000	0000 0000
8Ch	PIE1	—	ADIE ⁽¹⁾	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
99h	SPBRG	Baud Rate Generator Register								0000 0000	0000 0000

Legend: x = unknown, - = unimplemented, read as '0'. Shaded cells are not used for synchronous master reception.

Note 1: This bit is only implemented on the PIC16F88. The bit will read '0' on the PIC16F87.

FIGURE 15-3: TIME-OUT SEQUENCE ON POWER-UP ($\overline{\text{MCLR}}$ TIED TO V_{DD} THROUGH PULL-UP RESISTOR)

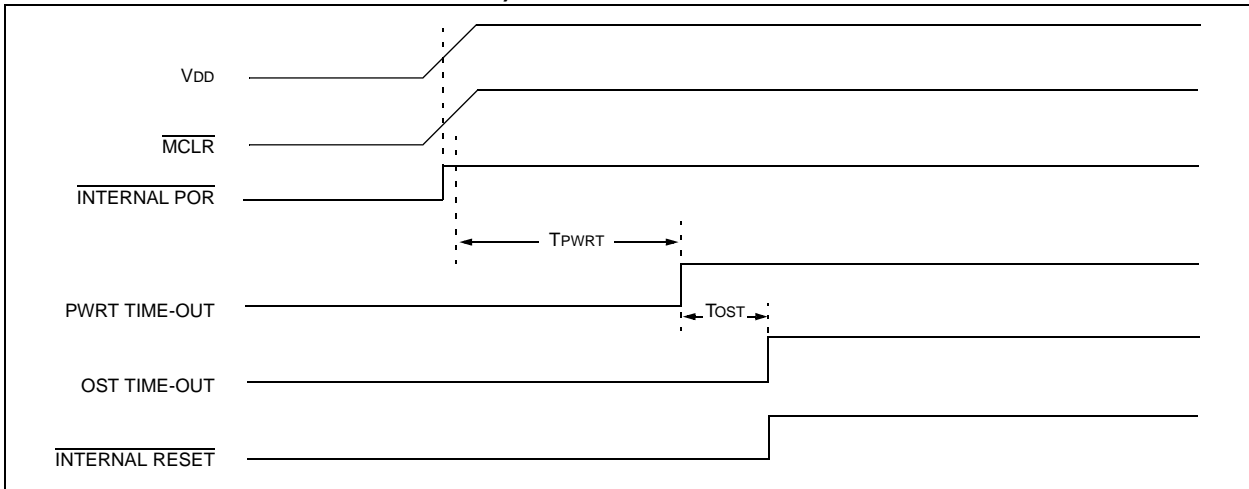


FIGURE 15-4: TIME-OUT SEQUENCE ON POWER-UP ($\overline{\text{MCLR}}$ TIED TO V_{DD} THROUGH RC NETWORK): CASE 1

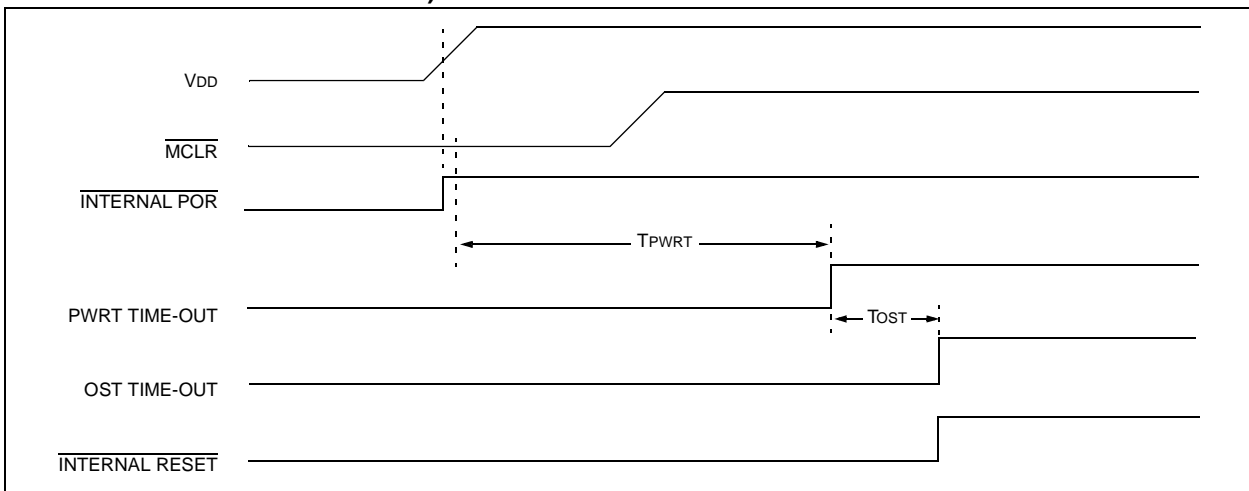
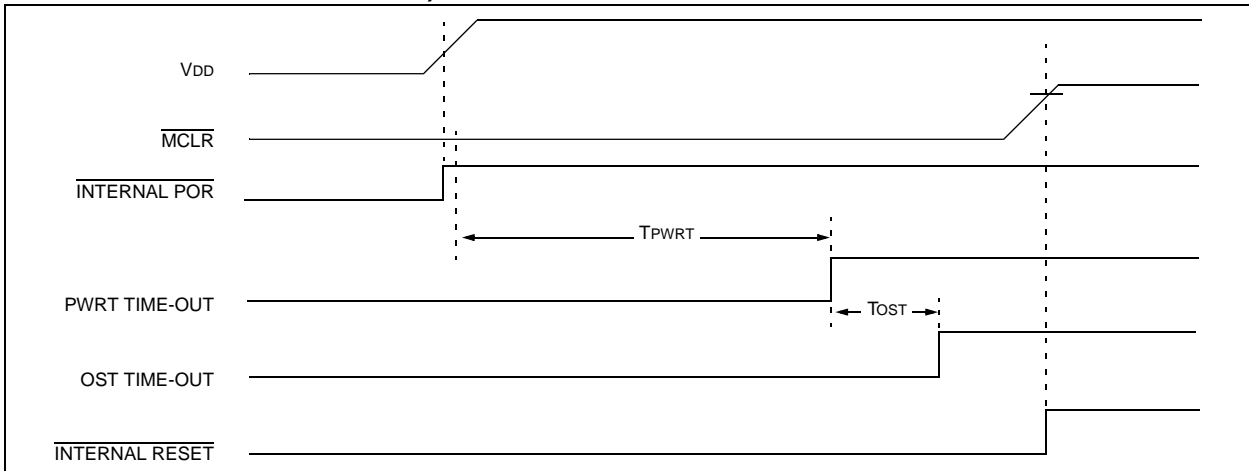


FIGURE 15-5: TIME-OUT SEQUENCE ON POWER-UP ($\overline{\text{MCLR}}$ TIED TO V_{DD} THROUGH RC NETWORK): CASE 2

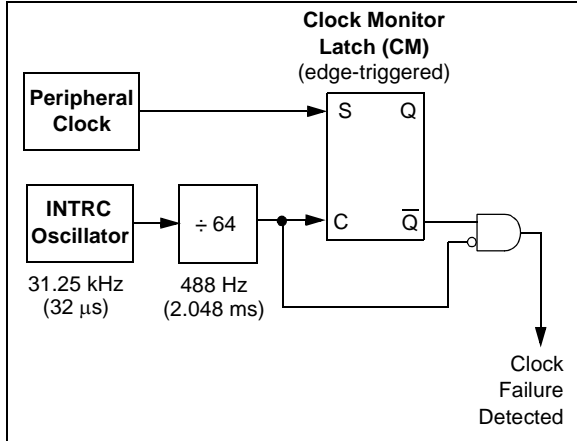


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15.12.4 FAIL-SAFE OPTION

The Fail-Safe Clock Monitor (FSCM) is designed to allow the device to continue to operate even in the event of an oscillator failure.

FIGURE 15-10: FSCM BLOCK DIAGRAM



The FSCM function is enabled by setting the FCMEN bit in Configuration Word 2.

In the event of an oscillator failure, the FSCM will generate an oscillator fail interrupt and will switch the system clock over to the internal oscillator. The system will continue to come from the internal oscillator until the fail-safe condition is exited. The fail-safe condition is exited with either a Reset, the execution of a SLEEP instruction or a write to the OSCCON register.

The frequency of the internal oscillator will depend upon the value contained in the IRCF bits. Another clock source can be selected via the IRCF and the SCS bits of the OSCCON register.

The FSCM sample clock is generated by dividing the INTRC clock by 64. This will allow enough time between FSCM sample clocks for a system clock edge to occur.

On the rising edge of the postscaled clock, the monitoring latch (CM = 0) will be cleared. On a falling edge of the primary or secondary system clock, the monitoring latch will be set (CM = 1). In the event that a falling edge of the postscaled clock occurs and the monitoring latch is not set, a clock failure has been detected.

While in Fail-Safe mode, a Reset will exit the fail-safe condition. If the primary clock source is configured for a crystal, the OST timer will wait for the 1024 clock cycles for the OST time-out and the device will continue running from the internal oscillator until the OST is complete. A SLEEP instruction, or a write to the SCS bits (where SCS bits do not = 00), can be performed to put the device into a low-power mode.

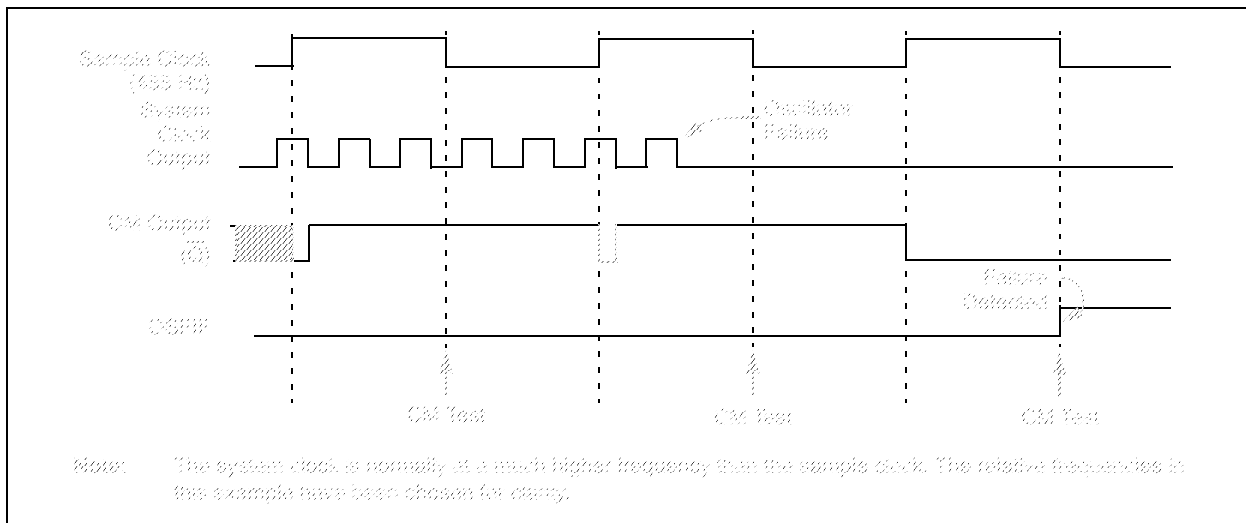
Note: Two-Speed Start-up mode is automatically enabled when the fail-safe option is enabled.

If Reset occurs while in Fail-Safe mode and the primary clock source is EC or RC, then the device will immediately switch back to EC or RC mode.

15.12.4.1 Fail-Safe in Low-Power Mode

A write to the OSCCON register, or SLEEP instruction, will end the fail-safe condition. The system clock will default to the source selected by the SCS bits, which is either T1OSC, INTRC or none (Sleep mode). However, the FSCM will continue to monitor the system clock. If the secondary clock fails, the device will immediately switch to the internal oscillator clock. If OSFIE is set, an interrupt will be generated.

FIGURE 15-11: FSCM TIMING DIAGRAM



15.12.4.2 FSCM and the Watchdog Timer

When a clock failure is detected, SCS<1:0> will be forced to '10' which will reset the WDT (if enabled).

15.12.4.3 POR or Wake From Sleep

The FSCM is designed to detect oscillator failure at any point after the device has exited Power-on Reset (POR) or low-power Sleep mode. When the primary system clock is EC, RC or INTRC modes, monitoring can begin immediately following these events.

For Oscillator modes involving a crystal or resonator (HS, LP or XT), the situation is somewhat different. Since the oscillator may require a start-up time considerably longer than the FSCM sample clock time, a false clock failure may be detected. To prevent this, the internal oscillator block is automatically configured as the system clock and functions until the primary clock is stable (the OST timer has timed out). This is identical to Two-Speed Start-up mode. Once the primary clock is stable, the INTRC returns to its role as the FSCM source.

Note: The same logic that prevents false oscillator failure interrupts on port or wake from Sleep, will also prevent the detection of the oscillator's failure to start at all following these events. This can be avoided by monitoring the OSTS bit and using a timing routine to determine if the oscillator is taking too long to start. Even so, no oscillator failure interrupt will be flagged.

15.12.4.4 Example Fail-Safe Conditions

1. CONDITIONS:

The device is clocked from a crystal, crystal operation fails and then Sleep mode is entered.

OSTS = 0

SCS = 00

OSFIF = 1

USER ACTION:

Sleep mode will exit the fail-safe condition. Therefore, if the user code did not handle the detected fail-safe prior to the SLEEP command, then upon wake-up, the device will try to start the crystal that failed and a fail-safe condition will not be detected. Monitoring the OSTS bit will determine if the crystal is operating. The user should not enter Sleep mode without handling the fail-safe condition first.

2. CONDITIONS:

After a POR (Power-on Reset), the device is running in Two-Speed Start-up mode. The crystal fails before the OST has expired. If a crystal fails during the OST period, a fail-safe condition will not be detected (OSFIF will not get set).

OSTS = 0

SCS = 00

OSFIF = 0

USER ACTION:

Check the OSTS bit. If it's clear and the OST should have expired at this point, then the user can assume the crystal has failed. The user should change the SCS bit to cause a clock switch which will also release the 10-bit ripple counter for WDT operation (if enabled).

3. CONDITIONS:

The device is clocked from a crystal during normal operation and it fails.

OSTS = 0

SCS = 00

OSFIF = 1

USER ACTION:

Clear the OSFIF bit. Configure the SCS bits for a clock switch and the fail-safe condition will be cleared. Later, if the user decides to, the crystal can be retried for operation. If this is done, the OSTS bit should be monitored to determine if the crystal operates.

15.13 Power-Down Mode (Sleep)

Power-Down mode is entered by executing a SLEEP instruction.

If enabled, the Watchdog Timer will be cleared but keeps running, the \overline{PD} bit (STATUS<3>) is cleared, the \overline{TO} (STATUS<4>) bit is set and the oscillator driver is turned off. The I/O ports maintain the status they had before the SLEEP instruction was executed (driving high, low or high-impedance).

For lowest current consumption in this mode, place all I/O pins at either VDD or VSS, ensure no external circuitry is drawing current from the I/O pin, power-down the A/D and disable external clocks. Pull all I/O pins that are high-impedance inputs, high or low externally, to avoid switching currents caused by floating inputs. The T0CKI input should also be at VDD or VSS for lowest current consumption. The contribution from on-chip pull-ups on PORTB should also be considered.

The \overline{MCLR} pin must be at a logic high level (VIHMC).

18.2 DC Characteristics: Power-Down and Supply Current PIC16F87/88 (Industrial, Extended) PIC16LF87/88 (Industrial) (Continued)

PIC16LF87/88 (Industrial)		Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial				
PIC16F87/88 (Industrial, Extended)		Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended				
Param No.	Device	Typ	Max	Units	Conditions	
D022 (ΔI_{WDT})	Watchdog Timer	1.5	3.8	μA	-40°C	V _{DD} = 2.0V
		2.2	3.8	μA	+25°C	
		2.7	4.0	μA	+85°C	
		2.3	4.6	μA	-40°C	V _{DD} = 3.0V
		2.7	4.6	μA	+25°C	
		3.1	4.8	μA	+85°C	
		3.0	10.0	μA	-40°C	V _{DD} = 5.0V
		3.3	10.0	μA	+25°C	
		3.9	13.0	μA	+85°C	
		Extended devices		5.0	21.0	μA
D022A (ΔI_{BOR})	Brown-out Reset	40	60	μA	-40°C to +85°C	V _{DD} = 5.0V
D025 (ΔI_{OSCB})	Timer1 Oscillator	1.7	2.3	μA	-40°C	V _{DD} = 2.0V
		1.8	2.3	μA	+25°C	
		2.0	2.3	μA	+85°C	
		2.2	3.8	μA	-40°C	V _{DD} = 3.0V
		2.6	3.8	μA	+25°C	
		2.9	3.8	μA	+85°C	
		3.0	6.0	μA	-40°C	V _{DD} = 5.0V
		3.2	6.0	μA	+25°C	
		3.4	7.0	μA	+85°C	
D026 (ΔI_{AD})	A/D Converter	0.001	2.0	μA	-40°C to +85°C	V _{DD} = 2.0V
		0.001	2.0	μA	-40°C to +85°C	V _{DD} = 3.0V
		0.003	2.0	μA	-40°C to +85°C	V _{DD} = 5.0V
	Extended devices		4.0	8.0	μA	-40°C to +125°C

Legend: Shading of rows is to assist in readability of the table.

- Note 1:** The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to V_{DD} or V_{SS} and all features that add delta current disabled (such as WDT, Timer1 Oscillator, BOR, etc.).
- 2:** The supply current is mainly a function of operating voltage, frequency and mode. Other factors, such as I/O pin loading and switching rate, oscillator type and circuit, internal code execution pattern and temperature, also have an impact on the current consumption.
The test conditions for all I_{DD} measurements in active operation mode are:
OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to V_{DD};
MCLR = V_{DD}; WDT enabled/disabled as specified.
- 3:** For RC oscillator configurations, current through R_{EXT} is not included. The current through the resistor can be estimated by the formula $I_r = V_{DD}/2R_{EXT}$ (mA) with R_{EXT} in k Ω .

FIGURE 18-6: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING

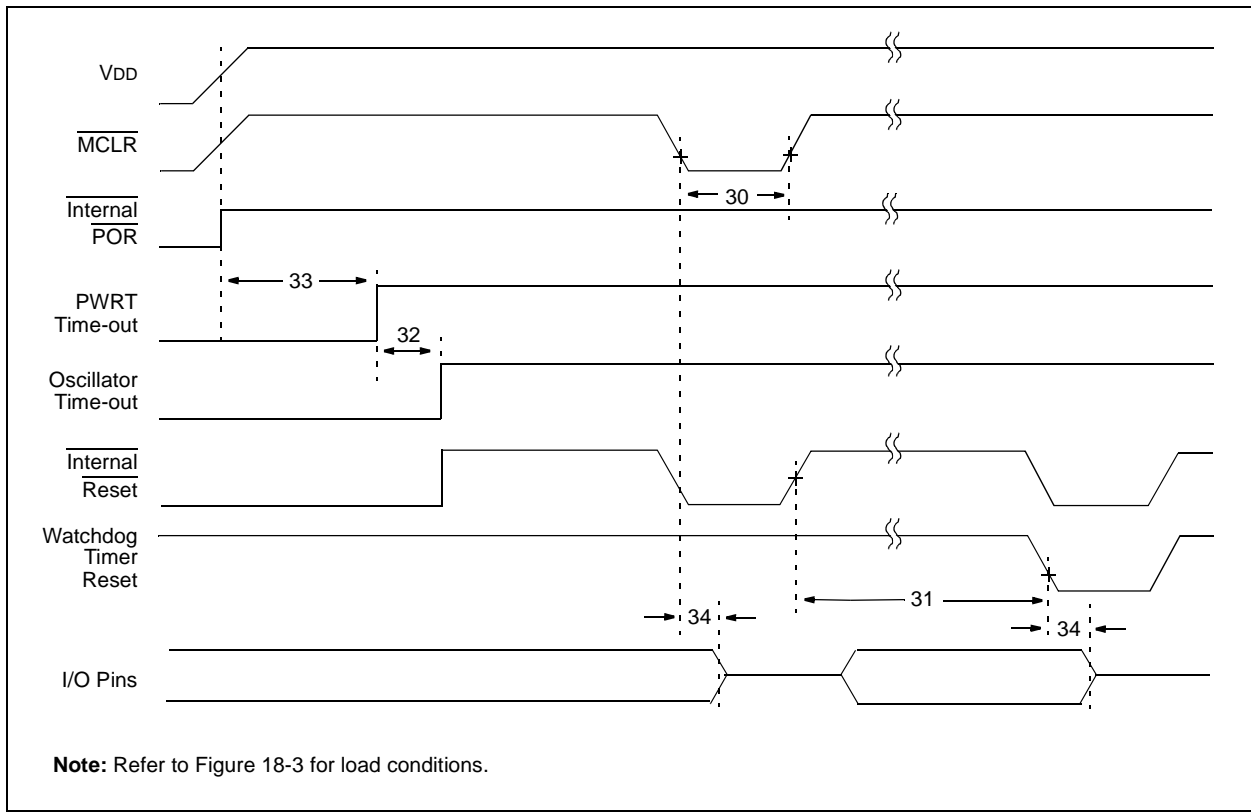


FIGURE 18-7: BROWN-OUT RESET TIMING

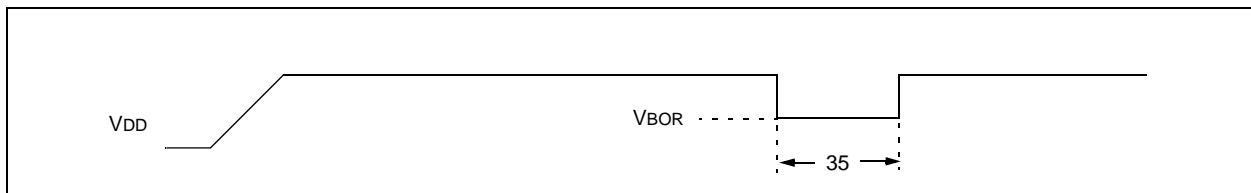


TABLE 18-5: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER AND BROWN-OUT RESET REQUIREMENTS

Parameter No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
30	TmCL	MCLR Pulse Width (Low)	2	—	—	μs	VDD = 5V, -40°C to +85°C
31*	TWDT	Watchdog Timer Time-out Period (16-bit prescaler = 0100 and no postscaler)	13.6	16	18.4	ms	VDD = 5V, -40°C to +85°C
32	TOST	Oscillation Start-up Timer Period	—	1024 TOSC	—	—	TOSC = OSC1 period
33*	TPWRT	Power-up Timer Period	61.2	72	82.8	ms	VDD = 5V, -40°C to +85°C
34	TIOZ	I/O High-impedance from MCLR Low or Watchdog Timer Reset	—	—	2.1	μs	
35	TBOR	Brown-out Reset Pulse Width	100	—	—	μs	VDD ≤ VBOR (D005)

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 19-13: AVERAGE F_{osc} vs. V_{DD} FOR VARIOUS VALUES OF R (RC MODE, C = 300 pF, +25°C)

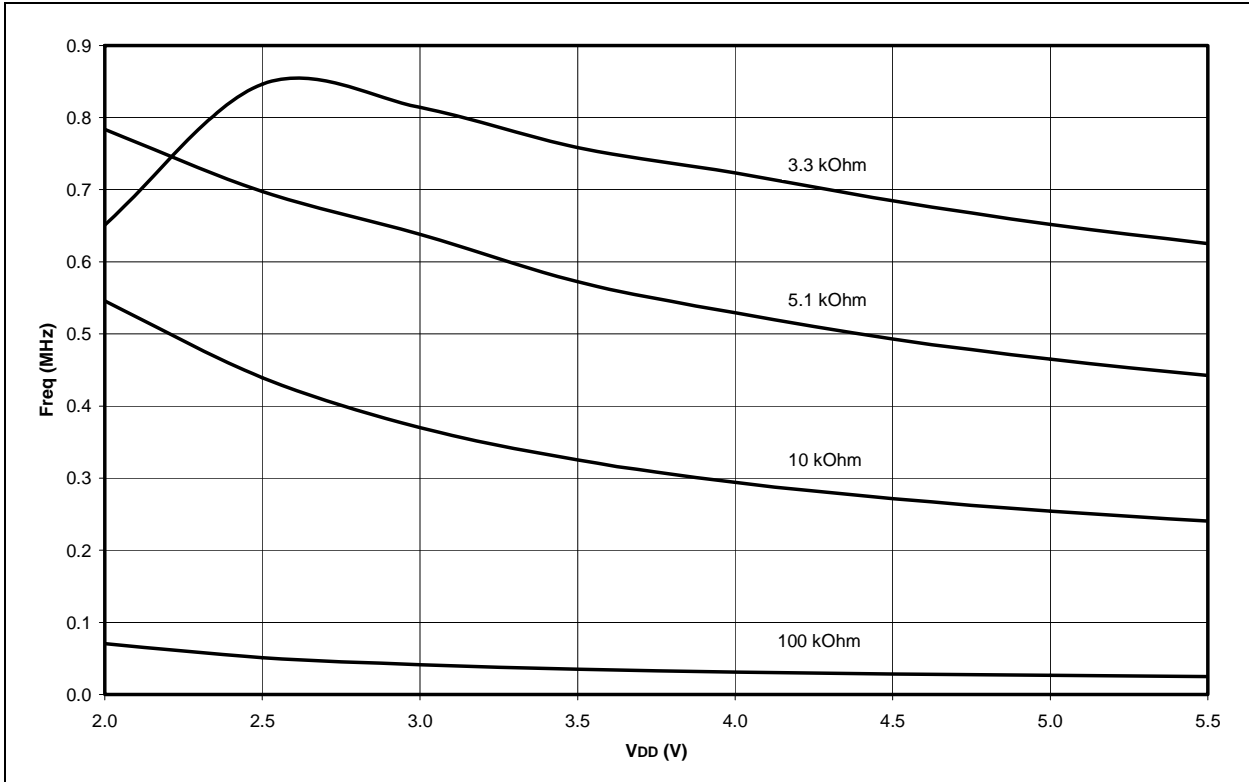


FIGURE 19-14: ΔI_{PD} TIMER1 OSCILLATOR, -10°C TO +70°C (SLEEP MODE, TMR1 COUNTER DISABLED)

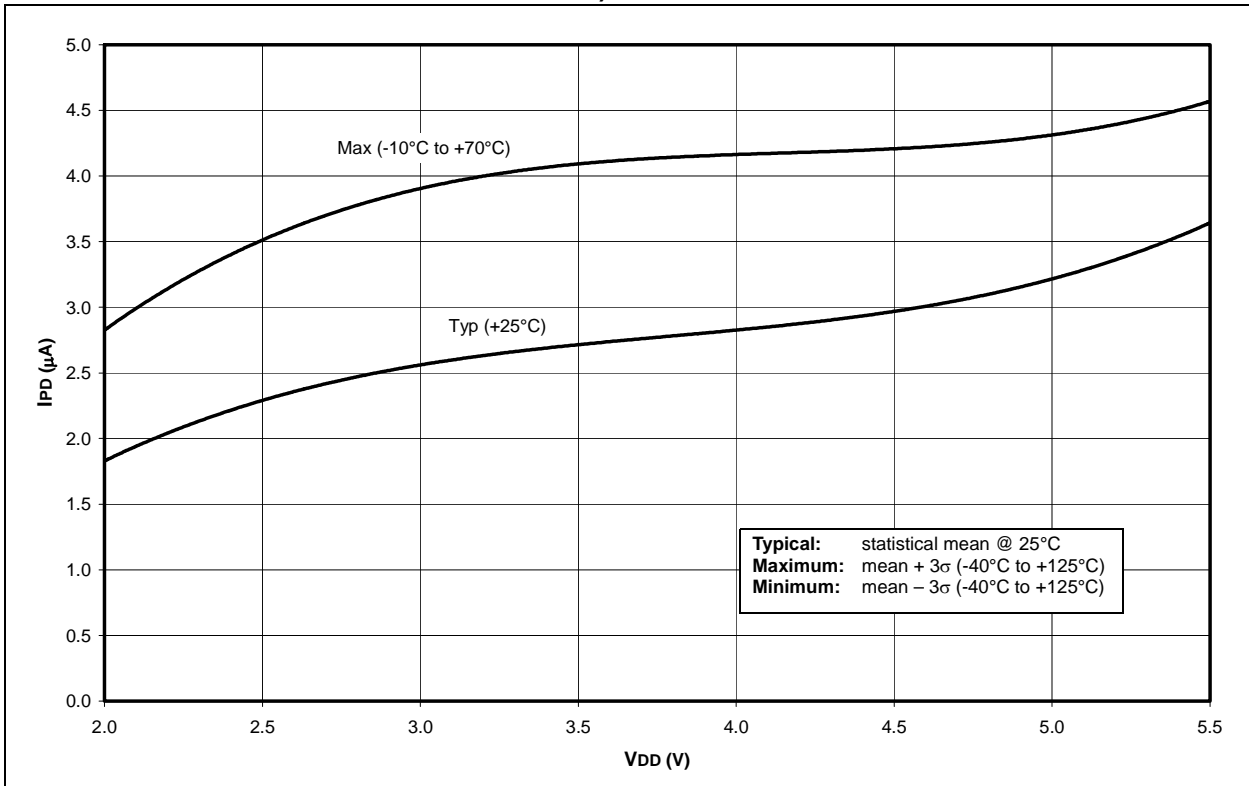


FIGURE 19-25: A/D NONLINEARITY vs. VREFH (VDD = VREFH, -40°C TO +125°C)

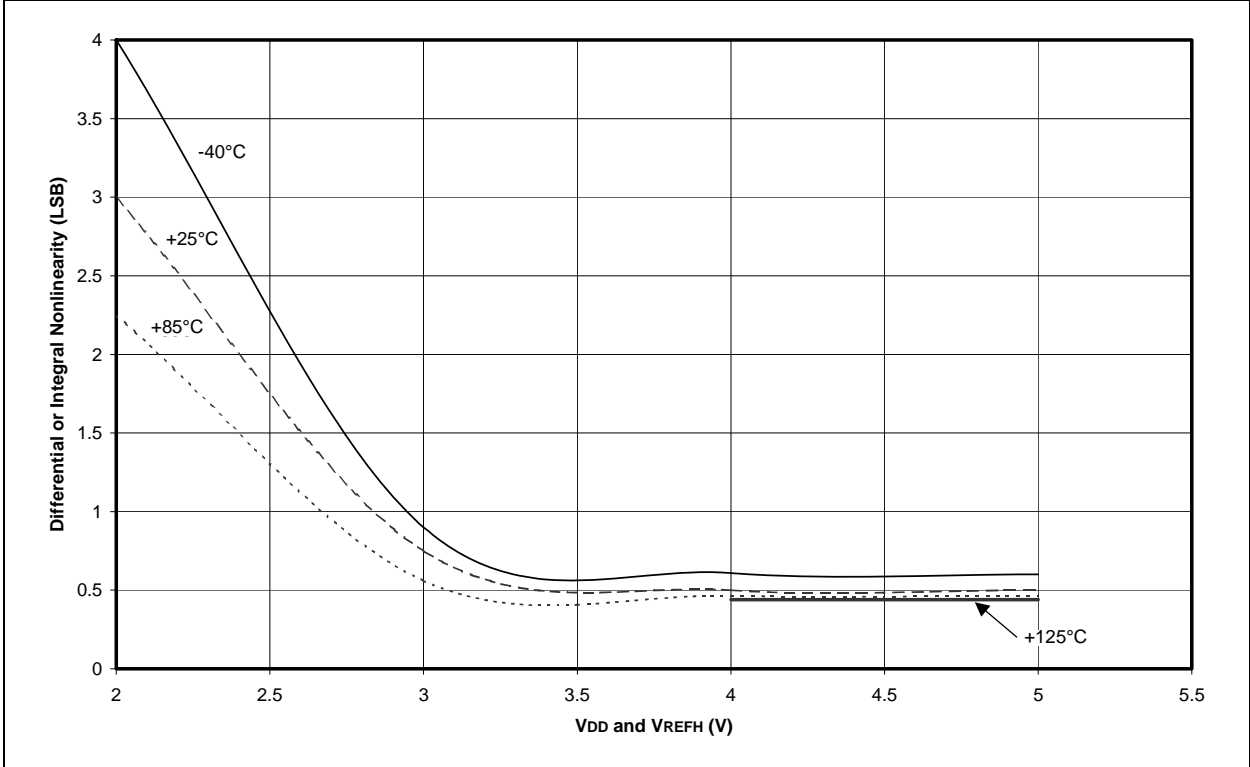
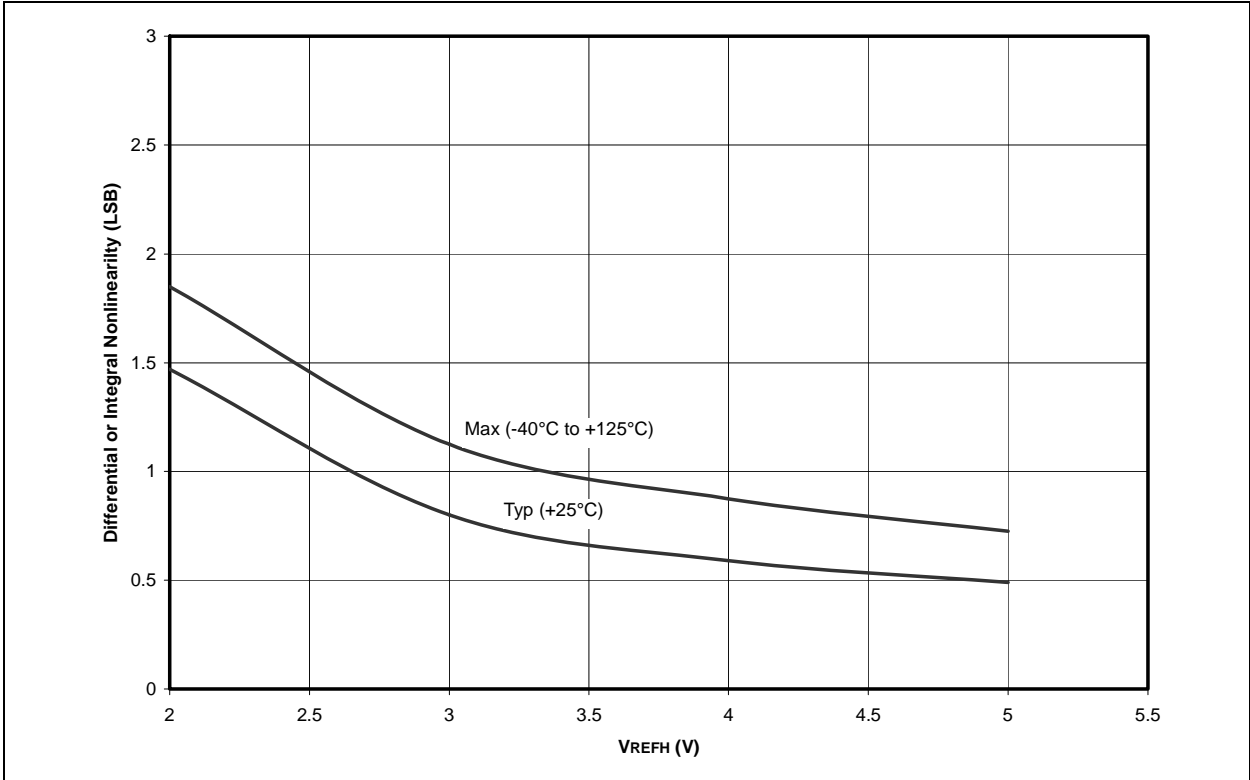


FIGURE 19-26: A/D NONLINEARITY vs. VREFH (VDD = 5V, -40°C TO +125°C)



PIC16F87/88

NOTES:

APPENDIX A: REVISION HISTORY

Revision A (November 2003)

Original data sheet for PIC16F87/88 devices.

Revision B (August 2003)

The specifications in **Section 18.0 “Electrical Characteristics”** have been updated to include the addition of maximum specifications to the DC Characteristics tables, text clarification has been made to **Section 4.6.2 “Clock Switching”** and there have been minor updates to the data sheet text.

Revision C (January 2005)

This revision includes the DC and AC Characteristics Graphs and Tables. The Electrical Specifications in **Section 18.0 “Electrical Characteristics”** have been updated and there have been minor corrections to the data sheet text.

Revision D (October 2011)

This revision updated the package marking and package outline drawings in **Section 20.0 “Packaging Information”**.

APPENDIX B: DEVICE DIFFERENCES

The differences between the devices in this data sheet are listed in Table B-1.

TABLE B-1: DIFFERENCES BETWEEN THE PIC16F87 AND PIC16F88

Features	PIC16F87	PIC16F88
Analog-to-Digital Converter	N/A	10-bit, 7-channel

PIC16F87/88

NOTES:

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