



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT
Number of I/O	6
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	64 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z8f022apb020eg">https://www.e-xfl.com/product-detail/zilog/z8f022apb020eg</a>

**Table 5. Z8 Encore! XP F082A Series Program Memory Maps (Continued)**

Program Memory Address (Hex)	Function
0002–0003	Reset Vector
0004–0005	WDT Interrupt Vector
0006–0007	Illegal Instruction Trap
0008–0037	Interrupt Vectors*
0038–0039	Reserved
003A–003D	Oscillator Fail Trap Vectors
003E–03FF	Program Memory

Note: \*See Table 32 on page 56 for a list of the interrupt vectors.

## Data Memory

The Z8 Encore! XP F082A Series does not use the eZ8 CPU's 64 KB Data Memory address space.

## Flash Information Area

Table 6 describes the Z8 Encore! XP F082A Series Flash Information Area. This 128B Information Area is accessed by setting bit 7 of the Flash Page Select Register to 1. When access is enabled, the Flash Information Area is mapped into the Program Memory and overlays the 128 bytes at addresses FE00H to FF7FH. When the Information Area access is enabled, all reads from these Program Memory addresses return the Information Area data rather than the Program Memory data. Access to the Flash Information Area is read-only.

**Table 6. Z8 Encore! XP F082A Series Flash Memory Information Area Map**

Program Memory Address (Hex)	Function
FE00–FE3F	Zilog Option Bits/Calibration Data
FE40–FE53	Part Number 20-character ASCII alphanumeric code Left-justified and filled with FFH
FE54–FE5F	Reserved
FE60–FE7F	Zilog Calibration Data
FE80–FFFF	Reserved

Table 15. Port Alternate Function Mapping (Non 8-Pin Parts)

Port	Pin	Mnemonic	Alternate Function Description	Alternate Function Set Register AFS1
Port A <sup>1,2</sup>	PA0	T0IN/T0OUT	Timer 0 Input/Timer 0 Output Complement	N/A
		Reserved		
	PA1	T0OUT	Timer 0 Output	
		Reserved		
	PA2	DE0	UART 0 Driver Enable	
		Reserved		
	PA3	CTS0	UART 0 Clear to Send	
		Reserved		
	PA4	RXD0/IRRX0	UART 0/IrDA 0 Receive Data	
		Reserved		
	PA5	TXD0/IRTX0	UART 0/IrDA 0 Transmit Data	
		Reserved		
	PA6	T1IN/T1OUT	Timer 1 Input/Timer 1 Output Complement	
		Reserved		
	PA7	T1OUT	Timer 1 Output	
		Reserved		

## Notes:

1. Because there is only a single alternate function for each Port A pin, the Alternate Function Set registers are not implemented for Port A. Enabling alternate function selections automatically enables the associated alternate function. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
2. Whether PA0/PA6 takes on the timer input or timer output complement function depends on the timer configuration. See the [Timer Pin Signal Operation](#) section on page 84 for details.
3. Because there are at most two choices of alternate function for any pin of Port B, the Alternate Function Set Register AFS2 is not used to select the function. Alternate function selection must also be enabled. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
4. V<sub>REF</sub> is available on PB5 in 28-pin products and on PC2 in 20-pin parts.
5. Because there are at most two choices of alternate function for any pin of Port C, the Alternate Function Set Register AFS2 is not used to select the function. Alternate function selection must also be enabled. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
6. Because there is only a single alternate function for the Port PD0 pin, the Alternate Function Set registers are not implemented for Port D. Enabling alternate function selections automatically enables the associated alternate function. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.

**Table 23. Port A–D Output Control Subregisters (PxOC)**

Bit	7	6	5	4	3	2	1	0
Field	POC7	POC6	POC5	POC4	POC3	POC2	POC1	POC0
RESET	00H (Ports A-C); 01H (Port D)							
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	If 03H in Port A–D Address Register, accessible through the Port A–D Control Register							

Bit	Description
[7:0] POCx	<b>Port Output Control</b> These bits function independently of the alternate function bit and always disable the drains if set to 1. 0 = The source current is enabled for any output mode unless overridden by the alternate function (push-pull output). 1 = The source current for the associated pin is disabled (open-drain mode).

Note: x indicates the specific GPIO port pin number (7–0).

### Port A–D High Drive Enable Subregisters

The Port A–D High Drive Enable Subregister, shown in Table 24, is accessed through the port A–D Control Register by writing 04H to the Port A–D Address Register. Setting the bits in the Port A–D High Drive Enable subregisters to 1 configures the specified port pins for high current output drive operation. The Port A–D High Drive Enable subregister affects the pins directly and, as a result, alternate functions are also affected.

**Table 24. Port A–D High Drive Enable Subregisters (PxHDE)**

Bit	7	6	5	4	3	2	1	0
Field	PHDE7	PHDE6	PHDE5	PHDE4	PHDE3	PHDE2	PHDE1	PHDE0
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	If 04H in Port A–D Address Register, accessible through the Port A–D Control Register							

Bit	Description
[7:0] PHDEx	<b>Port High Drive Enabled</b> 0 = The port pin is configured for standard output current drive. 1 = The port pin is configured for high output current drive.

Note: x indicates the specific GPIO port pin number (7–0).

Table 34. Trap and Interrupt Vectors in Order of Priority

Priority	Program Memory Vector Address	Interrupt or Trap Source
Highest	0002H	Reset (not an interrupt)
	0004H	Watchdog Timer (see Watchdog Timer)
	003AH	Primary Oscillator Fail Trap (not an interrupt)
	003CH	Watchdog Oscillator Fail Trap (not an interrupt)
	0006H	Illegal Instruction Trap (not an interrupt)
	0008H	Reserved
	000AH	Timer 1
	000CH	Timer 0
	000EH	UART 0 receiver
	0010H	UART 0 transmitter
	0012H	Reserved
	0014H	Reserved
	0016H	ADC
	0018H	Port A Pin 7, selectable rising or falling input edge or LVD (see Reset, Stop Mode Recovery and Low Voltage Detection)
	001AH	Port A Pin 6, selectable rising or falling input edge or Comparator Output
	001CH	Port A Pin 5, selectable rising or falling input edge
	001EH	Port A Pin 4, selectable rising or falling input edge
	0020H	Port A Pin 3, selectable rising or falling input edge
	0022H	Port A Pin 2, selectable rising or falling input edge
	0024H	Port A Pin 1, selectable rising or falling input edge
	0026H	Port A Pin 0, selectable rising or falling input edge
	0028H	Reserved
	002AH	Reserved
	002CH	Reserved
	002EH	Reserved
	0030H	Port C Pin 3, both input edges
	0032H	Port C Pin 2, both input edges
	0034H	Port C Pin 1, both input edges
Lowest	0036H	Port C Pin 0, both input edges
	0038H	Reserved

**Table 42. IRQ1 Enable High Bit Register (IRQ1ENH)**

Bit	7	6	5	4	3	2	1	0
Field	PA7VENH	PA6CENH	PA5ENH	PA4ENH	PA3ENH	PA2ENH	PA1ENH	PA0ENH
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	FC4H							

Bit	Description
[7] PA7VENH	Port A Bit[7] or LVD Interrupt Request Enable High Bit
[6] PA6CENH	Port A Bit[7] or Comparator Interrupt Request Enable High Bit
[5:0] PAxENH	Port A Bit[x] Interrupt Request Enable High Bit

See the [Shared Interrupt Select Register \(IRQSS\) Register](#) on page 68 for selection of either the LVD or the comparator as the interrupt source.

**Table 43. IRQ1 Enable Low Bit Register (IRQ1ENL)**

Bit	7	6	5	4	3	2	1	0
Field	PA7VENL	PA6CENL	PA5ENL	PA4ENL	PA3ENL	PA2ENL	PA1ENL	PA0ENL
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	FC5H							

Bit	Description
[7] PA7VENL	Port A Bit[7] or LVD Interrupt Request Enable Low Bit
[6] PA6CENL	Port A Bit[6] or Comparator Interrupt Request Enable Low Bit
[5:0] PAxENL	Port A Bit[x] Interrupt Request Enable Low Bit

## IRQ2 Enable High and Low Bit Registers

Table 44 describes the priority control for IRQ2. The IRQ2 Enable High and Low Bit registers, shown in Tables 44 and 45, form a priority-encoded enabling for interrupts in the Interrupt Request 2 Register.

Table 44. IRQ2 Enable and Priority Encoding

IRQ2ENH[x]	IRQ2ENL[x]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Medium
1	1	Level 3	High

Note: x indicates register bits 0–7.

Table 45. IRQ2 Enable High Bit Register (IRQ2ENH)

Bit	7	6	5	4	3	2	1	0
Field	Reserved				C3ENH	C2ENH	C1ENH	C0ENH
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	FC7H							

Bit	Description
[7:4]	<b>Reserved</b> These bits are reserved and must be programmed to 0000.
[3] C3ENH	<b>Port C3 Interrupt Request Enable High Bit</b>
[2] C2ENH	<b>Port C2 Interrupt Request Enable High Bit</b>
[1] C1ENH	<b>Port C1 Interrupt Request Enable High Bit</b>
[0] C0ENH	<b>Port C0 Interrupt Request Enable High Bit</b>

The timer input can be used as a selectable counting source. It shares the same pin as the complementary timer output. When selected by the GPIO Alternate Function registers, this pin functions as a timer input in all modes except for the DUAL PWM OUTPUT mode. For this mode, there is no timer input available.

## Timer Control Register Definitions

This section defines the features of the following Timer Control registers.

Timer 0–1 Control Registers: see page 85

Timer 0–1 High and Low Byte Registers: see page 89

Timer Reload High and Low Byte Registers: see page 91

Timer 0–1 PWM High and Low Byte Registers: see page 92

### Timer 0–1 Control Registers

The Timer Control registers are 8-bit read/write registers that control the operation of their associated counter/timers.

#### Time 0–1 Control Register 0

The Timer Control Register 0 (TxCTL0) and Timer Control Register 1 (TxCTL1), shown in Table 50, determine the timer operating mode. These registers each include a programmable PWM deadband delay, two bits to configure timer interrupt definition and a status bit to identify if the most recent timer interrupt is caused by an input capture event.

**Table 50. Timer 0–1 Control Register 0 (TxCTL0)**

Bit	7	6	5	4	3	2	1	0
Field	TMODEHI	TICONFIG		Reserved	PWMD			INPCAP
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R
Address	F06H, F0EH							

Bit	Description
[7] TMODEHI	<b>Timer Mode High Bit</b> This bit, along with the TMODE field in the TxCTL1 Register, determines the operating mode of the timer. This bit is the most significant bit of the Timer mode selection value. See the description of the <u>Timer 0–1 Control Register 1 (TxCTL1)</u> for details about the full timer mode decoding.



Table 67. UART Transmit Data Register (U0TXD)

Bit	7	6	5	4	3	2	1	0
Field	TXD							
RESET	X	X	X	X	X	X	X	X
R/W	W	W	W	W	W	W	W	W
Address	F40H							
Note: X = Undefined.								

Bit	Description
[7:0]	<b>Transmit Data</b>
TXD	UART transmitter data byte to be shifted out through the TXDx pin.

## UART Receive Data Register

Data bytes received through the RXDx pin are stored in the UART Receive Data (UxRXD) Register, shown in Table 68. The read-only UART Receive Data Register shares a Register File address with the Write-only UART Transmit Data Register.

Table 68. UART Receive Data Register (U0RXD)

Bit	7	6	5	4	3	2	1	0
Field	RXD							
RESET	X	X	X	X	X	X	X	X
R/W	R	R	R	R	R	R	R	R
Address	F40H							
Note: X = Undefined.								

Bit	Description
[7:0]	<b>Receive Data</b>
RXD	UART receiver data byte from the RXDx pin.

## UART Address Compare Register

The UART Address Compare (UxADDR) Register stores the multi-node network address of the UART (see Table 69). When the MPMD[1] bit of UART Control Register 0 is set, all incoming address bytes are compared to the value stored in the Address Compare Register. Receive interrupts and RDA assertions only occur in the event of a match.

## ADC Control Register 0

The ADC Control Register 0 (ADCCTL0) selects the analog input channel and initiates the analog-to-digital conversion. It also selects the voltage reference configuration.

**Table 73. ADC Control Register 0 (ADCCTL0)**

Bit	7	6	5	4	3	2	1	0
Field	CEN	REFSELL	REFOUT	CONT	ANAIN[3:0]			
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	F70H							

Bit	Description
[7] CEN	<b>Conversion Enable</b> 0 = Conversion is complete. Writing a 0 produces no effect. The ADC automatically clears this bit to 0 when a conversion is complete. 1 = Begin conversion. Writing a 1 to this bit starts a conversion. If a conversion is already in progress, the conversion restarts. This bit remains 1 until the conversion is complete.
[6] REFSELL	<b>Voltage Reference Level Select Low Bit</b> In conjunction with the High bit (REFSELH) in ADC Control/Status Register 1, this determines the level of the internal voltage reference; the following details the effects of {REFSELH, REFSELL}; note that this reference is independent of the Comparator reference. 00 = Internal Reference Disabled, reference comes from external pin. 01 = Internal Reference set to 1.0 V. 10 = Internal Reference set to 2.0 V (default). 11 = Reserved.
[5] REFOUT	<b>Internal Reference Output Enable</b> 0 = Reference buffer is disabled; Vref pin is available for GPIO or analog functions. 1 = The internal ADC reference is buffered and driven out to the V <sub>REF</sub> pin. <b>Caution:</b> When the ADC is used with an external reference ({REFSELH,REFSELL}=00), the REFOUT bit must be set to 0.
[4] CONT	<b>Conversion</b> 0 = Single-shot conversion. ADC data is output once at completion of the 5129 system clock cycles (measurements of the internal temperature sensor take twice as long). 1 = Continuous conversion. ADC data updated every 256 system clock cycles after an initial 5129 clock conversion (measurements of the internal temperature sensor take twice as long).
[3:0] ANAIN[3:0]	<b>Analog Input Select</b> These bits select the analog input for conversion. Not all Port pins in this list are available in all packages for the Z8 Encore! XP F082A Series. For information about port pins available with each package style, see the <a href="#">Pin Description</a> chapter on page 8. Do not enable unavailable analog inputs. Usage of these bits changes depending on the buffer mode selected in ADC Control/Status Register 1.

# Comparator

The Z8 Encore! XP F082A Series devices feature a general purpose comparator that compares two analog input signals. These analog signals may be external stimulus from a pin (CINP and/or CINN) or internally generated signals. Both a programmable voltage reference and the temperature sensor output voltage are available internally. The output is available as an interrupt source or can be routed to an external pin.

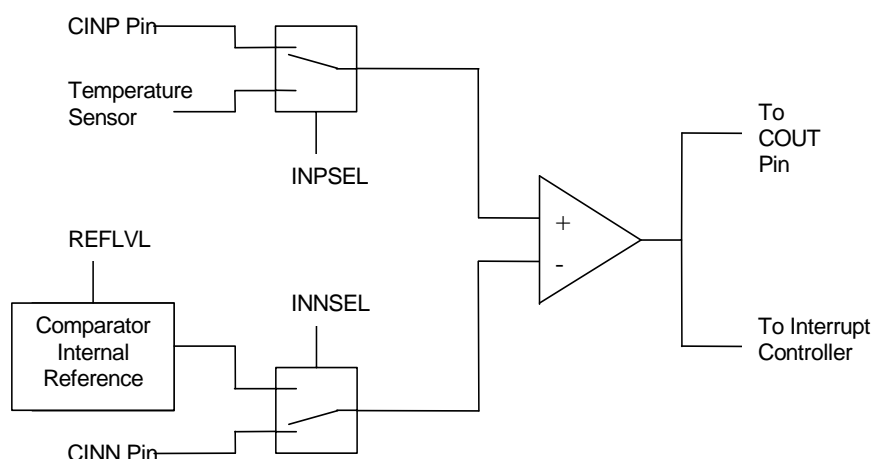


Figure 20. Comparator Block Diagram

## Operation

When the positive comparator input exceeds the negative input by more than the specified hysteresis, the output is a logic High. When the negative input exceeds the positive by more than the hysteresis, the output is a logic Low. Otherwise, the comparator output retains its present value. See [Table 141](#) on page 238 for details.

The comparator may be powered down to reduce supply current. See the [Power Control Register 0](#) section on page 33 for details.

---

**! Caution:** Because of the propagation delay of the comparator, Zilog does not recommend enabling or reconfiguring the comparator without first disabling the interrupts and waiting for the comparator output to settle. Doing so can result in spurious interrupts.

---

The following code example illustrates how to safely enable the comparator:

```
di
ld cmp0, r0 ; load some new configuration
nop
nop          ; wait for output to settle
clr irq0 ; clear any spurious interrupts pending
ei
```

## Comparator Control Register Definition

The Comparator Control Register (CMP0) configures the comparator inputs and sets the value of the internal voltage reference.

**Table 77. Comparator Control Register (CMP0)**

Bit	7	6	5	4	3	2	1	0
Field	INPSEL	INNSEL	REFLVL				Reserved (20-/28-pin) REFLVL (8-pin)	
RESET	0	0	0	1	0	1	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	F90H							

Bit	Description
[7] INPSEL	<b>Signal Select for Positive Input</b> 0 = GPIO pin used as positive comparator input. 1 = Temperature sensor used as positive comparator input.
[6] INNSEL	<b>Signal Select for Negative Input</b> 0 = Internal reference disabled, GPIO pin used as negative comparator input. 1 = Internal reference enabled as negative comparator input.

Bit	Description (Continued)
[1:0]	For 8-pin devices, the following voltages can be configured; for 20- and 28-pin devices, these bits are reserved. 000000 = 0.00 V 000001 = 0.05 V 000010 = 0.10 V 000011 = 0.15 V 000100 = 0.20 V 000101 = 0.25 V 000110 = 0.30 V 000111 = 0.35 V 001000 = 0.40 V 001001 = 0.45 V 001010 = 0.50 V 001011 = 0.55 V 001100 = 0.60 V 001101 = 0.65 V 001110 = 0.70 V 001111 = 0.75 V 010000 = 0.80 V 010001 = 0.85 V 010010 = 0.90 V 010011 = 0.95 V 010100 = 1.00 V (Default) 010101 = 1.05 V 010110 = 1.10 V 010111 = 1.15 V 011000 = 1.20 V 011001 = 1.25 V 011010 = 1.30 V 011011 = 1.35 V 011100 = 1.40 V 011101 = 1.45 V 011110 = 1.50 V 011111 = 1.55 V 100000 = 1.60 V 100001 = 1.65 V 100010 = 1.70 V 100011 = 1.75 V 100100 = 1.80 V

# Temperature Sensor

The on-chip Temperature Sensor allows you to measure temperature on the die with either the on-board ADC or on-board comparator. This block is factory calibrated for in-circuit software correction. Uncalibrated accuracy is significantly worse, therefore the temperature sensor is not recommended for uncalibrated use.

## Temperature Sensor Operation

The on-chip temperature sensor is a Proportional to Absolute Temperature (PTAT) topology. A pair of Flash option bytes contain the calibration data. The temperature sensor can be disabled by a bit in the Power Control Register 0 section on page 33 to reduce power consumption.

The temperature sensor can be directly read by the ADC to determine the absolute value of its output. The temperature sensor output is also available as an input to the comparator for threshold type measurement determination. The accuracy of the sensor when used with the comparator is substantially less than when measured by the ADC.

If the temperature sensor is routed to the ADC, the ADC must be configured in unity-gain buffered mode (for details, see the Input Buffer Stage section on page 133). The value read back from the ADC is a signed number, although it is always positive.

The sensor is factory-trimmed through the ADC using the external 2.0 V reference. Unless the sensor is retrimmed for use with a different reference, it is most accurate when used with the external 2.0 V reference.

Because this sensor is an on-chip sensor, Zilog recommends that the user account for the difference between ambient and die temperature when inferring ambient temperature conditions.

During normal operation, the die undergoes heating that causes a mismatch between the ambient temperature and that measured by the sensor. For best results, the Z8 Encore! XP device must be placed into STOP Mode for sufficient time such that the die and ambient temperatures converge (this time is dependent on the thermal design of the system). The temperature sensor measurement must then be made immediately after recovery from STOP Mode.

The following equation defines the transfer function between the temperature sensor output voltage and the die temperature. This is needed for comparator threshold measurements.

$$V = 0.01 \times T + 0.65$$

**!** **Caution:** The Flash Frequency High and Low Byte registers must be loaded with the correct value to ensure proper operation of the device. Also, Flash programming and erasure is not supported for system clock frequencies below 20kHz or above 20MHz.

**Table 84. Flash Frequency High Byte Register (FFREQH)**

Bit	7	6	5	4	3	2	1	0
Field	FFREQH							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	FFAH							

Bit	Description
-----	-------------

[7:0]	<b>Flash Frequency High Byte</b>
-------	----------------------------------

FFREQH	High byte of the 16-bit Flash Frequency value.
--------	--

**Table 85. Flash Frequency Low Byte Register (FFREQL)**

Bit	7	6	5	4	3	2	1	0
Field	FFREQL							
RESET	0							
R/W	R/W							
Address	FFBH							

Bit	Description
-----	-------------

[7:0]	<b>Flash Frequency Low Byte</b>
-------	---------------------------------

FFREQL	Low byte of the 16-bit Flash Frequency value.
--------	---

## Temperature Sensor Calibration Data

**Table 98. Temperature Sensor Calibration High Byte at 003A (TSCALH)**

Bit	7	6	5	4	3	2	1	0
Field	TSCALH							
RESET	U	U	U	U	U	U	U	U
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	Information Page Memory 003A							
Note: U = Unchanged by Reset. R/W = Read/Write.								

Bit	Description
[7:0]	<b>Temperature Sensor Calibration High Byte</b>
TSCALH	The TSCALH and TSCALL bytes combine to form the 12-bit temperature sensor offset calibration value. For more details, see Temperature Sensor Operation on page 139.

**Table 99. Temperature Sensor Calibration Low Byte at 003B (TSCALL)**

Bit	7	6	5	4	3	2	1	0
Field	TSCALL							
RESET	U	U	U	U	U	U	U	U
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	Information Page Memory 003B							
Note: U = Unchanged by Reset. R/W = Read/Write.								

Bit	Description
[7:0]	<b>Temperature Sensor Calibration Low Byte</b>
TSCALL	The TSCALH and TSCALL bytes combine to form the 12-bit temperature sensor offset calibration value. For usage details, see the <a href="#">Temperature Sensor Operation</a> section on page 144.



## Watchdog Timer Calibration Data

Table 100. Watchdog Calibration High Byte at 007EH (WDTCALH)

Bit	7	6	5	4	3	2	1	0
Field	WDTCALH							
RESET	U	U	U	U	U	U	U	U
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	Information Page Memory 007EH							
Note: U = Unchanged by Reset. R/W = Read/Write.								

Bit	Description
[7:0]	<b>Watchdog Timer Calibration High Byte</b>
WDTCALH	The WDTCALH and WDTCALL bytes, when loaded into the Watchdog Timer reload registers result in a one second time-out at room temperature and 3.3V supply voltage. To use the Watchdog Timer calibration, user code must load WDTU with 0x00, WDTL with WDT-CALH and WDTL with WDTCALL.

**Table 135. Power-On Reset and Voltage Brown-Out Electrical Characteristics and Timing**

Symbol	Parameter	$T_A = -40^{\circ}\text{C to } +105^{\circ}\text{C}$			Units	Conditions
		Minimum	Typical <sup>1</sup>	Maximum		
$T_{\text{RAMP}}$	Time for $V_{\text{DD}}$ to transition from $V_{\text{SS}}$ to $V_{\text{POR}}$ to ensure valid Reset	0.10	–	100	ms	
$T_{\text{SMP}}$	Stop Mode Recovery pin pulse rejection period		20		ns	For any SMR pin or for the Reset pin when it is asserted in STOP Mode.

Note: Data in the typical column is from characterization at 3.3V and 30°C. These values are provided for design guidance only and are not tested in production.

**Table 136. Flash Memory Electrical Characteristics and Timing**

Parameter	$V_{\text{DD}} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40^{\circ}\text{C to } +105^{\circ}\text{C}$ (unless otherwise stated)			Units	Notes
	Minimum	Typical	Maximum		
Flash Byte Read Time	100	–	–	ns	
Flash Byte Program Time	20	–	40	$\mu\text{s}$	
Flash Page Erase Time	10	–	–	ms	
Flash Mass Erase Time	200	–	–	ms	
Writes to Single Address Before Next Erase	–	–	2		
Flash Row Program Time	–	–	8	ms	Cumulative program time for single row cannot exceed limit before next erase. This parameter is only an issue when bypassing the Flash Controller.
Data Retention	100	–	–	years	25°C
Endurance	10,000	–	–	cycles	Program/erase cycles

Table 137. Watchdog Timer Electrical Characteristics and Timing

$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ $T_A = -40^{\circ}\text{C to }+105^{\circ}\text{C}$ (unless otherwise stated)						
Symbol	Parameter	Minimum	Typical	Maximum	Units	Conditions
$F_{WDT}$	WDT Oscillator Frequency		10		kHz	
$F_{WDT}$	WDT Oscillator Error			$\pm 50$	%	
$T_{WDT\text{CAL}}$	WDT Calibrated Time-out	0.98	1	1.02	s	$V_{DD} = 3.3\text{ V};$ $T_A = 30^{\circ}\text{C}$
		0.70	1	1.30	s	$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ $T_A = 0^{\circ}\text{C to }70^{\circ}\text{C}$
		0.50	1	1.50	s	$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ $T_A = -40^{\circ}\text{C to }+105^{\circ}\text{C}$

Table 138. Non-Volatile Data Storage

$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ $T_A = -40^{\circ}\text{C to }+105^{\circ}\text{C}$					
Parameter	Minimum	Typical	Maximum	Units	Notes
NVDS Byte Read Time	34	–	519	$\mu\text{s}$	With system clock at 20MHz
NVDS Byte Program Time	0.171	–	39.7	ms	With system clock at 20MHz
Data Retention	100	–	–	years	25°C
Endurance	160,000	–	–	cycles	Cumulative write cycles for entire memory

**Table 148. Z8 Encore! XP F082A Series Ordering Matrix**

Part Number	Flash	RAM	NVDS	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Comparator	Temperature Sensor	Description
<b>Z8 Encore! XP F082A Series with 1 KB Flash, 10-Bit Analog-to-Digital Converter</b>											
<b>Standard Temperature: 0°C to 70°C</b>											
Z8F012APB020SG	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020SG	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020SG	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020SG	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020SG	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020SG	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020SG	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020SG	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020SG	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package
<b>Extended Temperature: –40°C to 105°C</b>											
Z8F012APB020EG	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020EG	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020EG	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020EG	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020EG	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020EG	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020EG	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020EG	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020EG	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package

LD 210  
LDC 210  
LDCI 209, 210  
LDE 210  
LDEI 209  
LDX 210  
LEA 210  
logical 210  
MULT 208  
NOP 209  
OR 210  
ORX 210  
POP 210  
POPX 210  
program control 211  
PUSH 210  
PUSHX 210  
RCF 209, 210  
RET 211  
RL 211  
RLC 211  
rotate and shift 211  
RR 211  
RRC 211  
SBC 208  
SCF 209, 210  
SRA 211  
SRL 211  
SRP 210  
STOP 210  
SUB 208  
SUBX 208  
SWAP 211  
TCM 209  
TCMX 209  
TM 209  
TMX 209  
TRAP 211  
Watchdog Timer refresh 210  
XOR 210  
XORX 210  
instructions, eZ8 classes of 207  
interrupt control register 69  
interrupt controller 55

architecture 55  
interrupt assertion types 58  
interrupt vectors and priority 58  
operation 57  
register definitions 60  
software interrupt assertion 59  
interrupt edge select register 67  
interrupt request 0 register 60  
interrupt request 1 register 61  
interrupt request 2 register 62  
interrupt return 211  
interrupt vector listing 55  
interrupts  
    UART 108  
IR 206  
Ir 206  
IrDA  
    architecture 120  
    block diagram 120  
    control register definitions 123  
    operation 120  
    receiving data 122  
    transmitting data 121  
IRET 211  
IRQ0 enable high and low bit registers 62  
IRQ1 enable high and low bit registers 64  
IRQ2 enable high and low bit registers 65  
IRR 206  
Irr 206

## **J**

JP 211  
jump, conditional, relative, and relative conditional  
211

## **L**

LD 210  
LDC 210  
LDCI 209, 210  
LDE 210  
LDEI 209, 210  
LDX 210