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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT
Number of I/O	6
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	64 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z8f022asb020eg">https://www.e-xfl.com/product-detail/zilog/z8f022asb020eg</a>

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Table 15. Port Alternate Function Mapping (Non 8-Pin Parts) (Continued)

Port	Pin	Mnemonic	Alternate Function Description	Alternate Function Set Register AFS1
<b>Port B<sup>3</sup></b>	PB0	Reserved		AFS1[0]: 0
		ANA0/AMPOUT	ADC Analog Input/LPO Output	AFS1[0]: 1
	PB1	Reserved		AFS1[1]: 0
		ANA1/AMPINN	ADC Analog Input/LPO Input (N)	AFS1[1]: 1
	PB2	Reserved		AFS1[2]: 0
		ANA2/AMPINP	ADC Analog Input/LPO Input (P)	AFS1[2]: 1
	PB3	CLKIN	External Clock Input	AFS1[3]: 0
		ANA3	ADC Analog Input	AFS1[3]: 1
<b>Port C<sup>4</sup></b>	PB4	Reserved		AFS1[4]: 0
		ANA7	ADC Analog Input	AFS1[4]: 1
<b>Port D<sup>5</sup></b>	PB5	Reserved		AFS1[5]: 0
		V <sub>REF</sub> <sup>4</sup>	ADC Voltage Reference	AFS1[5]: 1
<b>Port E<sup>6</sup></b>	PB6	Reserved		AFS1[6]: 0
		Reserved		AFS1[6]: 1
<b>Port F<sup>7</sup></b>	PB7	Reserved		AFS1[7]: 0
		Reserved		AFS1[7]: 1

## Notes:

- Because there is only a single alternate function for each Port A pin, the Alternate Function Set registers are not implemented for Port A. Enabling alternate function selections automatically enables the associated alternate function. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
- Whether PA0/PA6 takes on the timer input or timer output complement function depends on the timer configuration. See the [Timer Pin Signal Operation](#) section on page 84 for details.
- Because there are at most two choices of alternate function for any pin of Port B, the Alternate Function Set Register AFS2 is not used to select the function. Alternate function selection must also be enabled. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
- V<sub>REF</sub> is available on PB5 in 28-pin products and on PC2 in 20-pin parts.
- Because there are at most two choices of alternate function for any pin of Port C, the Alternate Function Set Register AFS2 is not used to select the function. Alternate function selection must also be enabled. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.
- Because there is only a single alternate function for the Port PD0 pin, the Alternate Function Set registers are not implemented for Port D. Enabling alternate function selections automatically enables the associated alternate function. See the [Port A–D Alternate Function Subregisters \(PxAF\)](#) section on page 47 for details.

## Interrupt Control Register

The Interrupt Control (IRQCTL) Register, shown in Table 49, contains the master enable bit for all interrupts.

**Table 49. Interrupt Control Register (IRQCTL)**

Bit	7	6	5	4	3	2	1	0
Field	IRQE	Reserved						
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R	R	R	R	R	R	R
Address	FCFH							

Bit	Description
[7] IRQE	<b>Interrupt Request Enable</b> This bit is set to 1 by executing an EI (Enable Interrupts) or IRET (Interrupt Return) instruction, or by a direct register write of a 1 to this bit. It is reset to 0 by executing a DI instruction, eZ8 CPU acknowledgement of an interrupt request, Reset or by a direct register write of a 0 to this bit. 0 = Interrupts are disabled. 1 = Interrupts are enabled.
[6:0]	<b>Reserved</b> These bits are reserved and must be programmed to 0000000.

## Timers

These Z8 Encore! XP F082A Series products contain two 16-bit reloadable timers that can be used for timing, event counting, or generation of pulse-width modulated (PWM) signals. The timers' feature include:

- 16-bit reload counter
- Programmable prescaler with prescale values from 1 to 128
- PWM output generation
- Capture and compare capability
- External input pin for timer input, clock gating, or capture signal. External input pin signal frequency is limited to a maximum of one-fourth the system clock frequency
- Timer output pin
- Timer interrupt

In addition to the timers described in this chapter, the Baud Rate Generator of the UART (if unused) may also provide basic timing functionality. For information about using the Baud Rate Generator as an additional timer, see the [Universal Asynchronous Receiver/Transmitter chapter on page 99](#).

## Architecture

Figure 9 displays the architecture of the timers.

The timer input can be used as a selectable counting source. It shares the same pin as the complementary timer output. When selected by the GPIO Alternate Function registers, this pin functions as a timer input in all modes except for the DUAL PWM OUTPUT mode. For this mode, there is no timer input available.

## Timer Control Register Definitions

This section defines the features of the following Timer Control registers.

Timer 0–1 Control Registers: see page 85

Timer 0–1 High and Low Byte Registers: see page 89

Timer Reload High and Low Byte Registers: see page 91

Timer 0–1 PWM High and Low Byte Registers: see page 92

## Timer 0–1 Control Registers

The Timer Control registers are 8-bit read/write registers that control the operation of their associated counter/timers.

### Time 0–1 Control Register 0

The Timer Control Register 0 (TxCTL0) and Timer Control Register 1 (TxCTL1), shown in Table 50, determine the timer operating mode. These registers each include a programmable PWM deadband delay, two bits to configure timer interrupt definition and a status bit to identify if the most recent timer interrupt is caused by an input capture event.

**Table 50. Timer 0–1 Control Register 0 (TxCTL0)**

Bit	7	6	5	4	3	2	1	0
Field	TMODEHI	TICONFIG		Reserved	PWMD			INPCAP
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R
Address	F06H, F0EH							

Bit	Description
[7] TMODEHI	<b>Timer Mode High Bit</b> This bit, along with the TMODE field in the TxCTL1 Register, determines the operating mode of the timer. This bit is the most significant bit of the Timer mode selection value. See the description of the <u>Timer 0–1 Control Register 1 (TxCTL1)</u> for details about the full timer mode decoding.

into the Watchdog Timer Reload registers results in a one-second time-out at room temperature and 3.3V supply voltage. Time-outs other than one second may be obtained by scaling the calibration values up or down as required.

- 
- **Note:** The Watchdog Timer accuracy still degrades as temperature and supply voltage vary. See [Table 137](#) on page 235 for details.
- 

## Watchdog Timer Control Register Definitions

This section defines the features of the following Watchdog Timer Control registers.

[Watchdog Timer Control Register \(WDTCTL\)](#): see page 96

[Watchdog Timer Reload Upper Byte Register \(WDTU\)](#): see page 97

[Watchdog Timer Reload High Byte Register \(WDTH\)](#): see page 97

[Watchdog Timer Reload Low Byte Register \(WDTL\)](#): see page 98

### Watchdog Timer Control Register

The Watchdog Timer Control (WDTCTL) Register is a write-only control register. Writing the 55H, AAH unlock sequence to the WDTCTL Register address unlocks the three Watchdog Timer Reload Byte registers (WDTU, WDTH and WDTL) to allow changes to the time-out period. These write operations to the WDTCTL Register address produce no effect on the bits in the WDTCTL Register. The locking mechanism prevents spurious writes to the reload registers. This register address is shared with the read-only Reset Status Register.

**Table 59. Watchdog Timer Control Register (WDTCTL)**

Bit	7	6	5	4	3	2	1	0
Field	WDTUNLK							
RESET	X	X	X	X	X	X	X	X
R/W	W	W	W	W	W	W	W	W
Address	FF0H							
Note: X = Undefined.								

Bit	Description
[7:0]	<b>Watchdog Timer Unlock</b>
WDTUNLK	The software must write the correct unlocking sequence to this register before it is allowed to modify the contents of the Watchdog Timer reload registers.

**Table 105. Randomized Lot ID Locations (Continued)**

<b>Info Page</b>	<b>Memory Address</b>	<b>Usage</b>
6A	FE6A	Randomized Lot ID Byte 13.
6B	FE6B	Randomized Lot ID Byte 12.
6D	FE6D	Randomized Lot ID Byte 11.
6E	FE6E	Randomized Lot ID Byte 10.
70	FE70	Randomized Lot ID Byte 9.
71	FE71	Randomized Lot ID Byte 8.
73	FE73	Randomized Lot ID Byte 7.
74	FE74	Randomized Lot ID Byte 6.
76	FE76	Randomized Lot ID Byte 5.
77	FE77	Randomized Lot ID Byte 4.
79	FE79	Randomized Lot ID Byte 3.
7A	FE7A	Randomized Lot ID Byte 2.
7C	FE7C	Randomized Lot ID Byte 1.
7D	FE7D	Randomized Lot ID Byte 0 (least significant).

- If the PA2/RESET pin is held Low while a 32-bit key sequence is issued to the PA0/DBG pin, the DBG feature is unlocked. After releasing PA2/RESET, it is pulled High. At this point, the PA0/DBG pin may be used to autobaud and cause the device to enter DEBUG Mode. See the [OCD Unlock Sequence \(8-Pin Devices Only\) section on page 185](#).

### Exiting DEBUG Mode

The device exits DEBUG Mode following any of these operations:

- Clearing the DBGMODE bit in the OCD Control Register to 0
- Power-On Reset
- Voltage Brown-Out reset
- Watchdog Timer reset
- Asserting the RESET pin Low to initiate a Reset
- Driving the DBG pin Low while the device is in STOP Mode initiates a System Reset

### OCD Data Format

The OCD interface uses the asynchronous data format defined for RS-232. Each character transmitted and received by the OCD consists of 1 Start bit, 8 data bits (least-significant bit first) and 1 Stop bit as displayed in Figure 26.



Figure 26. OCD Data Format

- 
- **Note:** When responding to a request for data, the OCD may commence transmitting immediately after receiving the stop bit of an incoming frame. Therefore, when sending the stop bit, the host must not actively drive the DBG pin High for more than 0.5 bit times. Zilog recommends that, if possible, the host drives the DBG pin using an open drain output to avoid this issue.
- 

### OCD Auto-Baud Detector/Generator

To run over a range of baud rates (data bits per second) with various system clock frequencies, the On-Chip Debugger contains an Auto-Baud Detector/Generator. After a reset, the OCD is idle until it receives data. The OCD requires that the first character sent from the

host is the character 80H. The character 80H has eight continuous bits Low (one Start bit plus 7 data bits), framed between High bits. The Auto-Baud Detector measures this period and sets the OCD Baud Rate Generator accordingly.

The Auto-Baud Detector/Generator is clocked by the system clock. The minimum baud rate is the system clock frequency divided by 512. For optimal operation with asynchronous datastreams, the maximum recommended baud rate is the system clock frequency divided by 8. The maximum possible baud rate for asynchronous datastreams is the system clock frequency divided by 4, but this theoretical maximum is possible only for low noise designs with clean signals. Table 108 lists minimum and recommended maximum baud rates for sample crystal frequencies.

**Table 108. OCD Baud-Rate Limits**

System Clock Frequency (MHz)	Recommended Maximum Baud Rate (Kbps)	Recommended Standard PC Baud Rate (bps)	Minimum Baud Rate (Kbps)
20.0	2500.0	1,843,200	39
1.0	125.0	115,200	1.95
0.032768 (32kHz)	4.096	2,400	0.064

If the OCD receives a Serial Break (nine or more continuous bits Low) the Auto-Baud Detector/Generator resets. Reconfigure the Auto-Baud Detector/Generator by sending 80H.

## OCD Serial Errors

The On-Chip Debugger can detect any of the following error conditions on the DBG pin:

- Serial Break (a minimum of nine continuous bits Low)
- Framing Error (received Stop bit is Low)
- Transmit Collision (OCD and host simultaneous transmission detected by the OCD)

When the OCD detects one of these errors, it aborts any command currently in progress, transmits a four character long Serial Break back to the host and resets the Auto-Baud Detector/Generator. A Framing Error or Transmit Collision may be caused by the host sending a Serial Break to the OCD. Because of the open-drain nature of the interface, returning a Serial Break back to the host only extends the length of the Serial Break if the host releases the Serial Break early.

The host transmits a Serial Break on the DBG pin when first connecting to the Z8 Encore! XP F082A Series devices or when recovering from an error. A Serial Break from the host resets the Auto-Baud Generator/Detector but does not reset the OCD Control Register. A

```
DBG ← Size[15:8]
DBG ← Size[7:0]
DBG ← 1-65536 data bytes
```

**Read Data Memory (0DH).** The Read Data Memory command reads from Data Memory. This command is equivalent to the LDE and LDEI instructions. Data can be read 1 to 65536 bytes at a time (65536 bytes can be read by setting size to 0). If the device is not in DEBUG Mode, this command returns FFH for the data.

```
DBG ← 0DH
DBG ← Data Memory Address[15:8]
DBG ← Data Memory Address[7:0]
DBG ← Size[15:8]
DBG ← Size[7:0]
DBG → 1-65536 data bytes
```

**Read Program Memory CRC (0EH).** The Read Program Memory CRC command computes and returns the Cyclic Redundancy Check (CRC) of Program Memory using the 16-bit CRC-CCITT polynomial. If the device is not in DEBUG Mode, this command returns FFFFH for the CRC value. Unlike most other OCD Read commands, there is a delay from issuing of the command until the OCD returns the data. The OCD reads the Program Memory, calculates the CRC value and returns the result. The delay is a function of the Program Memory size and is approximately equal to the system clock period multiplied by the number of bytes in the Program Memory.

```
DBG ← 0EH
DBG → CRC[15:8]
DBG → CRC[7:0]
```

**Step Instruction (10H).** The Step Instruction command steps one assembly instruction at the current Program Counter (PC) location. If the device is not in DEBUG Mode or the Flash Read Protect Option bit is enabled, the OCD ignores this command.

```
DBG ← 10H
```

**Stuff Instruction (11H).** The Stuff Instruction command steps one assembly instruction and allows specification of the first byte of the instruction. The remaining 0-4 bytes of the instruction are read from Program Memory. This command is useful for stepping over instructions where the first byte of the instruction has been overwritten by a Breakpoint. If the device is not in DEBUG Mode or the Flash Read Protect Option bit is enabled, the OCD ignores this command.

```
DBG ← 11H
DBG ← opcode[7:0]
```

**Execute Instruction (12H).** The Execute Instruction command allows sending an entire instruction to be executed to the eZ8 CPU. This command can also step over Breakpoints. The number of bytes to send for the instruction depends on the opcode. If the device is not

**Table 114. Recommended Crystal Oscillator Specifications**

Parameter	Value	Units	Comments
Frequency	20	MHz	
Resonance	Parallel		
Mode	Fundamental		
Series Resistance ( $R_S$ )	60	W	Maximum
Load Capacitance ( $C_L$ )	30	pF	Maximum
Shunt Capacitance ( $C_0$ )	7	pF	Maximum
Drive Level	1	mW	Maximum

**Table 115. Transconductance Values for Low, Medium and High Gain Operating Modes**

Mode	Crystal Frequency Range	Function	Transconductance (mA/V) (Use this range for calculations)		
Low Gain*	32kHz–1MHz	Low Power/Frequency Applications	0.02	0.04	0.09
Medium Gain*	0.5MHz–10MHz	Medium Power/Frequency Applications	0.84	1.7	3.1
High Gain*	8MHz–20MHz	High Power/Frequency Applications	1.1	2.3	4.2

Note: \*Printed circuit board layouts must not add more than 4pF of stray capacitance to either the  $X_{IN}$  or  $X_{OUT}$  pins. If no oscillation occurs, reduce the values of the capacitors C1 and C2 to decrease the loading.

Table 128. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode		Opcode(s) (Hex)	Flags					Fetch Cycle s	Instr. Cycle s
		dst	src		C	Z	S	V	D		
CALL dst	SP ← SP -2	IRR		D4	—	—	—	—	—	2	6
	@SP ← PC			DA	D6						
CCF	C ← ~C			EF	*	—	—	—	—	1	2
CLR dst	dst ← 00H	R		B0	—	—	—	—	—	2	2
				IR	B1						
COM dst	dst ← ~dst	R		60	—	*	*	0	—	2	2
				IR	61						
CP dst, src	dst - src	r	r	A2	*	*	*	*	—	2	3
		r	Ir	A3							
		R	R	A4						3	3
		R	IR	A5							
		R	IM	A6						3	3
		IR	IM	A7							
CPC dst, src	dst - src - C	r	r	1FA2	*	*	*	*	—	3	3
		r	Ir	1FA3							
		R	R	1FA4						4	3
		R	IR	1FA5							
		R	IM	1FA6						4	3
		IR	IM	1FA7							
CPCX dst, src	dst - src - C	ER	ER	1FA8	*	*	*	*	—	5	3
		ER	IM	1FA9							
CPX dst, src	dst - src	ER	ER	A8	*	*	*	*	—	4	3
		ER	IM	A9							

Note: Flags Notation:

\* = Value is a function of the result of the operation.

— = Unaffected.

X = Undefined.

0 = Reset to 0.

1 = Set to 1.

Table 128. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode		Opcode(s) (Hex)	Flags					Fetch Cycle s	Instr. Cycle s
		dst	src		C	Z	S	V	D		
JR dst	PC ← PC + X	DA		8B	—	—	—	—	—	2	2
JR cc, dst	if cc is true PC ← PC + X	DA		0B-FB	—	—	—	—	—	2	2
LD dst, rc	dst ← src	r	IM	0C-FC	—	—	—	—	—	2	2
		r	X(r)	C7						3	3
		X(r)	r	D7						3	4
		r	Ir	E3						2	3
		R	R	E4						3	2
		R	IR	E5						3	4
		R	IM	E6						3	2
		IR	IM	E7						3	3
		Ir	r	F3						2	3
		IR	R	F5						3	3
LDC dst, src	dst ← src	r	Irr	C2	—	—	—	—	—	2	5
		Ir	Irr	C5						2	9
		Irr	r	D2						2	5
LDCI dst, src	dst ← src r ← r + 1 rr ← rr + 1	Ir	Irr	C3	—	—	—	—	—	2	9
		Irr	Ir	D3						2	9
LDE dst, src	dst ← src	r	Irr	82	—	—	—	—	—	2	5
		Irr	r	92						2	5
LDEI dst, src	dst ← src r ← r + 1 rr ← rr + 1	Ir	Irr	83	—	—	—	—	—	2	9
		Irr	Ir	93						2	9
LDWX dst, src	dst ← src	ER	ER	1FE8	—	—	—	—	—	5	4

Note: Flags Notation:

\* = Value is a function of the result of the operation.

— = Unaffected.

X = Undefined.

0 = Reset to 0.

1 = Set to 1.

## On-Chip Peripheral AC and DC Electrical Characteristics

Table 135 tabulates the electrical characteristics of the POR and VBO blocks.

**Table 135. Power-On Reset and Voltage Brown-Out Electrical Characteristics and Timing**

$T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$						
Symbol	Parameter	Minimum	Typical <sup>1</sup>	Maximum	Units	Conditions
$V_{\text{POR}}$	Power-On Reset Voltage Threshold	2.20	2.45	2.70	V	$V_{\text{DD}} = V_{\text{POR}}$
$V_{\text{VBO}}$	Voltage Brown-Out Reset Voltage Threshold	2.15	2.40	2.65	V	$V_{\text{DD}} = V_{\text{VBO}}$
	$V_{\text{POR}}$ to $V_{\text{VBO}}$ hysteresis		50	75	mV	
	Starting $V_{\text{DD}}$ voltage to ensure valid Power-On Reset.	–	$V_{\text{SS}}$	–	V	
$T_{\text{ANA}}$	Power-On Reset Analog Delay	–	70	–	μs	$V_{\text{DD}} > V_{\text{POR}}$ ; $T_{\text{POR}}$ Digital Reset delay follows $T_{\text{ANA}}$
$T_{\text{POR}}$	Power-On Reset Digital Delay		16		μs	66 Internal Precision Oscillator cycles + IPO startup time ( $T_{\text{IPOST}}$ )
$T_{\text{POR}}$	Power-On Reset Digital Delay		1		ms	5000 Internal Precision Oscillator cycles
$T_{\text{SMR}}$	Stop Mode Recovery with crystal oscillator disabled		16		μs	66 Internal Precision Oscillator cycles
$T_{\text{SMR}}$	Stop Mode Recovery with crystal oscillator enabled		1		ms	5000 Internal Precision Oscillator cycles
$T_{\text{VBO}}$	Voltage Brown-Out Pulse Rejection Period	–	10	–	μs	Period of time in which $V_{\text{DD}} < V_{\text{VBO}}$ without generating a Reset.

Note: Data in the typical column is from characterization at 3.3V and 30°C. These values are provided for design guidance only and are not tested in production.

**Table 139. Analog-to-Digital Converter Electrical Characteristics and Timing (Continued)**

$V_{DD} = 3.0 \text{ V to } 3.6 \text{ V}$ $T_A = 0^\circ\text{C to } +70^\circ\text{C}$ (unless otherwise stated)						
Symbol	Parameter	Minimum	Typical	Maximum	Units	Conditions
Continuous Conversion Time	—	256	—	—	System clock cycles	All measurements but temperature sensor
	—	512	—	—	—	Temperature sensor measurement
Signal Input Bandwidth	—	10	—	—	kHz	As defined by -3 dB point
$R_S$	Analog Source Impedance <sup>4</sup>	—	—	10	kΩ	In unbuffered mode
	—	—	—	500	kΩ	In buffered modes
Zin	Input Impedance	—	150	—	kΩ	In unbuffered mode at 20MHz <sup>5</sup>
	—	10	—	—	MΩ	In buffered modes
Vin	Input Voltage Range	0	—	$V_{DD}$	V	Unbuffered Mode
	—	0.3	—	$V_{DD}-1.1$	V	Buffered Modes These values define the range over which the ADC performs within spec; exceeding these values does not cause damage or instability; see DC Characteristics for absolute pin voltage limits.

## Notes:

1. Analog source impedance affects the ADC offset voltage (because of pin leakage) and input settling time.
2. Devices are factory calibrated at  $V_{DD} = 3.3\text{V}$  and  $T_A = +30^\circ\text{C}$ , so the ADC is maximally accurate under these conditions.
3. LSBs are defined assuming 10-bit resolution.
4. This is the maximum recommended resistance seen by the ADC input pin.
5. The input impedance is inversely proportional to the system clock frequency.

**Table 140. Low Power Operational Amplifier Electrical Characteristics**

$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40^\circ\text{C to } +105^\circ\text{C}$						
<b>Symbol</b>	<b>Parameter</b>	<b>Minimum</b>	<b>Typical</b>	<b>Maximum</b>	<b>Units</b>	<b>Conditions</b>
Av	Open loop voltage gain	80			dB	
GBW	Gain/Bandwidth product	500			kHz	
PM	Phase Margin	50			deg	Assuming 13pF load capacitance.
$V_{osLPO}$	Input Offset Voltage	$\pm 1$	$\pm 4$		mV	
$V_{osLPO}$	Input Offset Voltage (Temperature Drift)	1	10		$\mu\text{V/C}$	
$V_{IN}$	Input Voltage Range	0.3		$V_{DD}-1$	V	
$V_{OUT}$	Output Voltage Range	0.3		$V_{DD}-1$	V	$I_{OUT} = 45\mu\text{A}$ .

**Table 141. Comparator Electrical Characteristics**

$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40^\circ\text{C to } +105^\circ\text{C}$						
<b>Symbol</b>	<b>Parameter</b>	<b>Minimum</b>	<b>Typical</b>	<b>Maximum</b>	<b>Units</b>	<b>Conditions</b>
$V_{OS}$	Input DC Offset		5		mV	
$V_{CREF}$	Programmable Internal Reference Voltage		$\pm 5$		%	20- and 28-pin devices.
			$\pm 3$		%	8-pin devices.
$T_{PROP}$	Propagation Delay	200			ns	
$V_{HYS}$	Input Hysteresis		4		mV	
$V_{IN}$	Input Voltage Range	$V_{SS}$		$V_{DD}-1$	V	

## On-Chip Debugger Timing

Figure 36 and Table 145 provide timing information for the DBG pin. The DBG pin timing specifications assume a 4 ns maximum rise and fall time.

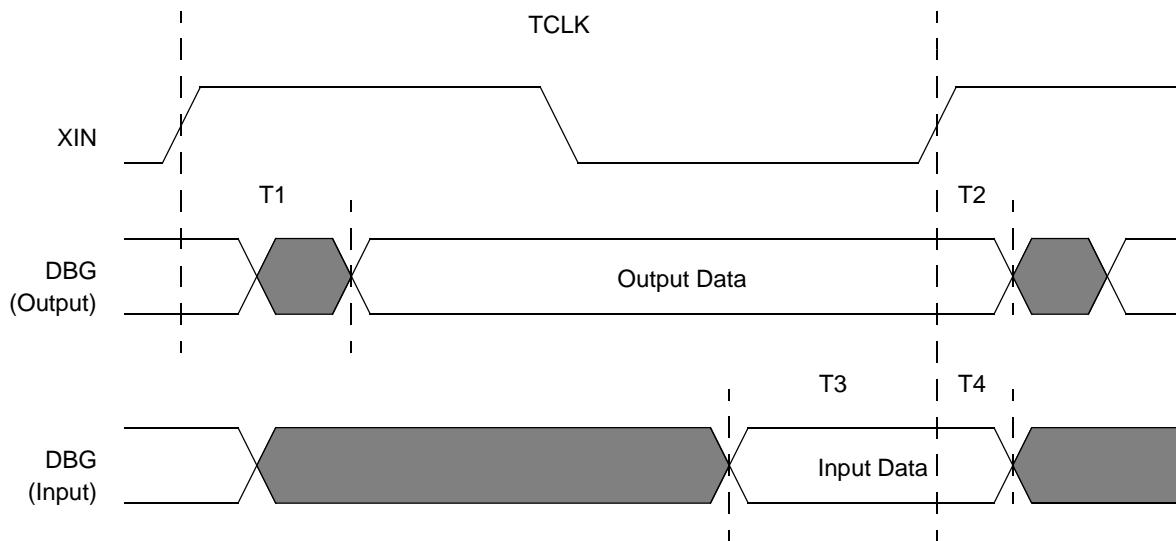


Figure 36. On-Chip Debugger Timing

Table 145. On-Chip Debugger Timing

Parameter	Abbreviation	Delay (ns)	
		Minimum	Maximum
<b>DBG</b>			
$T_1$	$X_{IN}$ Rise to DBG Valid Delay	—	15
$T_2$	$X_{IN}$ Rise to DBG Output Hold Time	2	—
$T_3$	DBG to $X_{IN}$ Rise Input Setup Time	5	—
$T_4$	DBG to $X_{IN}$ Rise Input Hold Time	5	—

Table 148. Z8 Encore! XP F082A Series Ordering Matrix

Part Number	Flash	RAM	NVDS	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Comparator	Temperature Sensor	Description
<b>Z8 Encore! XP F082A Series with 8KB Flash</b>											
<b>Standard Temperature: 0°C to 70°C</b>											
Z8F081APB020SG	8KB	1KB	0	6	13	2	0	1	1	0	PDIP 8-pin package
Z8F081AQB020SG	8KB	1KB	0	6	13	2	0	1	1	0	QFN 8-pin package
Z8F081ASB020SG	8KB	1KB	0	6	13	2	0	1	1	0	SOIC 8-pin package
Z8F081ASH020SG	8KB	1KB	0	17	19	2	0	1	1	0	SOIC 20-pin package
Z8F081AHH020SG	8KB	1KB	0	17	19	2	0	1	1	0	SSOP 20-pin package
Z8F081APH020SG	8KB	1KB	0	17	19	2	0	1	1	0	PDIP 20-pin package
Z8F081ASJ020SG	8KB	1KB	0	25	19	2	0	1	1	0	SOIC 28-pin package
Z8F081AHJ020SG	8KB	1KB	0	25	19	2	0	1	1	0	SSOP 28-pin package
Z8F081APJ020SG	8KB	1KB	0	25	19	2	0	1	1	0	PDIP 28-pin package
<b>Extended Temperature: -40°C to 105°C</b>											
Z8F081APB020EG	8KB	1KB	0	6	13	2	0	1	1	0	PDIP 8-pin package
Z8F081AQB020EG	8KB	1KB	0	6	13	2	0	1	1	0	QFN 8-pin package
Z8F081ASB020EG	8KB	1KB	0	6	13	2	0	1	1	0	SOIC 8-pin package
Z8F081ASH020EG	8KB	1KB	0	17	19	2	0	1	1	0	SOIC 20-pin package
Z8F081AHH020EG	8KB	1KB	0	17	19	2	0	1	1	0	SSOP 20-pin package
Z8F081APH020EG	8KB	1KB	0	17	19	2	0	1	1	0	PDIP 20-pin package
Z8F081ASJ020EG	8KB	1KB	0	25	19	2	0	1	1	0	SOIC 28-pin package
Z8F081AHJ020EG	8KB	1KB	0	25	19	2	0	1	1	0	SSOP 28-pin package
Z8F081APJ020EG	8KB	1KB	0	25	19	2	0	1	1	0	PDIP 28-pin package

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