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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	6
Program Memory Size	3.5KB (2K x 14)
Program Memory Type	FLASH
EEPROM Size	224 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 5x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	8-PDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16lf15313-e-p">https://www.e-xfl.com/product-detail/microchip-technology/pic16lf15313-e-p</a>

## 4.0 MEMORY ORGANIZATION

These devices contain the following types of memory:

- Program Memory
  - Configuration Words
  - Device ID
  - User ID
  - Program Flash Memory
  - Device Information Area (DIA)
  - Device Configuration Information (DCI)
  - Revision ID
- Data Memory
  - Core Registers
  - Special Function Registers
  - General Purpose RAM
  - Common RAM

The following features are associated with access and control of program memory and data memory:

- PCL and PCLATH
- Stack
- Indirect Addressing
- NVMREG access

## 4.1 Program Memory Organization

The enhanced mid-range core has a 15-bit program counter capable of addressing 32K x 14 program memory space. Table 4-1 shows the memory sizes implemented. The Reset vector is at 0000h and the interrupt vector is at 0004h (see Figure 4-1).

**TABLE 4-1: DEVICE SIZES AND ADDRESSES**

Device	Program Memory Size (Words)	Last Program Memory Address
PIC16(L)F15313/23	2048	07FFh

## 5.2 Register Definitions: Configuration Words

### REGISTER 5-1: CONFIGURATION WORD 1: OSCILLATORS

R/P-1	U-1	R/P-1	U-1	U-1	R/P-1
FCMEN	—	CSWEN	—	—	CLKOUTEN
bit 13			bit 8		

U-1	R/P-1	R/P-1	R/P-1	U-1	R/P-1	R/P-1	R/P-1
—	RSTOSC2	RSTOSC1	RSTOSC0	—	FEXTOSC2	FEXTOSC1	FEXTOSC0
bit 7				bit 0			

#### Legend:

R = Readable bit

P = Programmable bit

x = Bit is unknown

U = Unimplemented bit, read as '1'

'0' = Bit is cleared

'1' = Bit is set

W = Writable bit

n = Value when blank or after Bulk Erase

- bit 13 **FCMEN:** Fail-Safe Clock Monitor Enable bit  
1 = FSCM timer enabled  
0 = FSCM timer disabled
- bit 12 **Unimplemented:** Read as '1'
- bit 11 **CSWEN:** Clock Switch Enable bit  
1 = Writing to NOSC and NDIV is allowed  
0 = The NOSC and NDIV bits cannot be changed by user software
- bit 10-9 **Unimplemented:** Read as '1'
- bit 8 **CLKOUTEN:** Clock Out Enable bit  
**If FEXTOSC = EC (high, mid or low) or Not Enabled:**  
1 = CLKOUT function is disabled; I/O or oscillator function on OSC2  
0 = CLKOUT function is enabled; FOSC/4 clock appears at OSC2  
**Otherwise:**  
This bit is ignored.
- bit 7 **Unimplemented:** Read as '1'
- bit 6-4 **RSTOSC<2:0>:** Power-up Default Value for COSC bits  
This value is the Reset-default value for COSC and selects the oscillator first used by user software.  
111 = EXTOSC operating per FEXTOSC bits (device manufacturing default)  
110 = HFINTOSC with HFFRQ = 3'b010  
101 = LFINTOSC  
100 = Reserved  
011 = Reserved  
010 = EXTOSC with 4x PLL, with EXTOSC operating per FEXTOSC bits  
001 = EXTOSC with 2x PLL, with EXTOSC operating per FEXTOSC bits  
000 = HFINTOSC with CDIV = 1:1 and HFFRQ = 3'b110
- bit 3 **Unimplemented:** Read as '1'
- bit 2-0 **FEXTOSC<2:0>:** FEXTOSC External Oscillator Mode Selection bits  
111 = EC (External Clock) above 8 MHz; PFM set to high power (device manufacturing default)  
110 = EC (External Clock) for 100 kHz to 8 MHz; PFM set to medium power  
101 = EC (External Clock) below 100 kHz  
100 = Oscillator not enabled  
011 = Reserved (do not use)  
010 = HS (Crystal oscillator) above 4 MHz; PFM set to high power  
001 = XT (Crystal oscillator) above 100 kHz, below 4 MHz; PFM set to medium power  
000 = LP (Crystal oscillator) optimized for 32.768 kHz; PFM set to low power

## 8.14 Power Control (PCONx) Registers

The Power Control (PCONx) registers contain flag bits to differentiate between a:

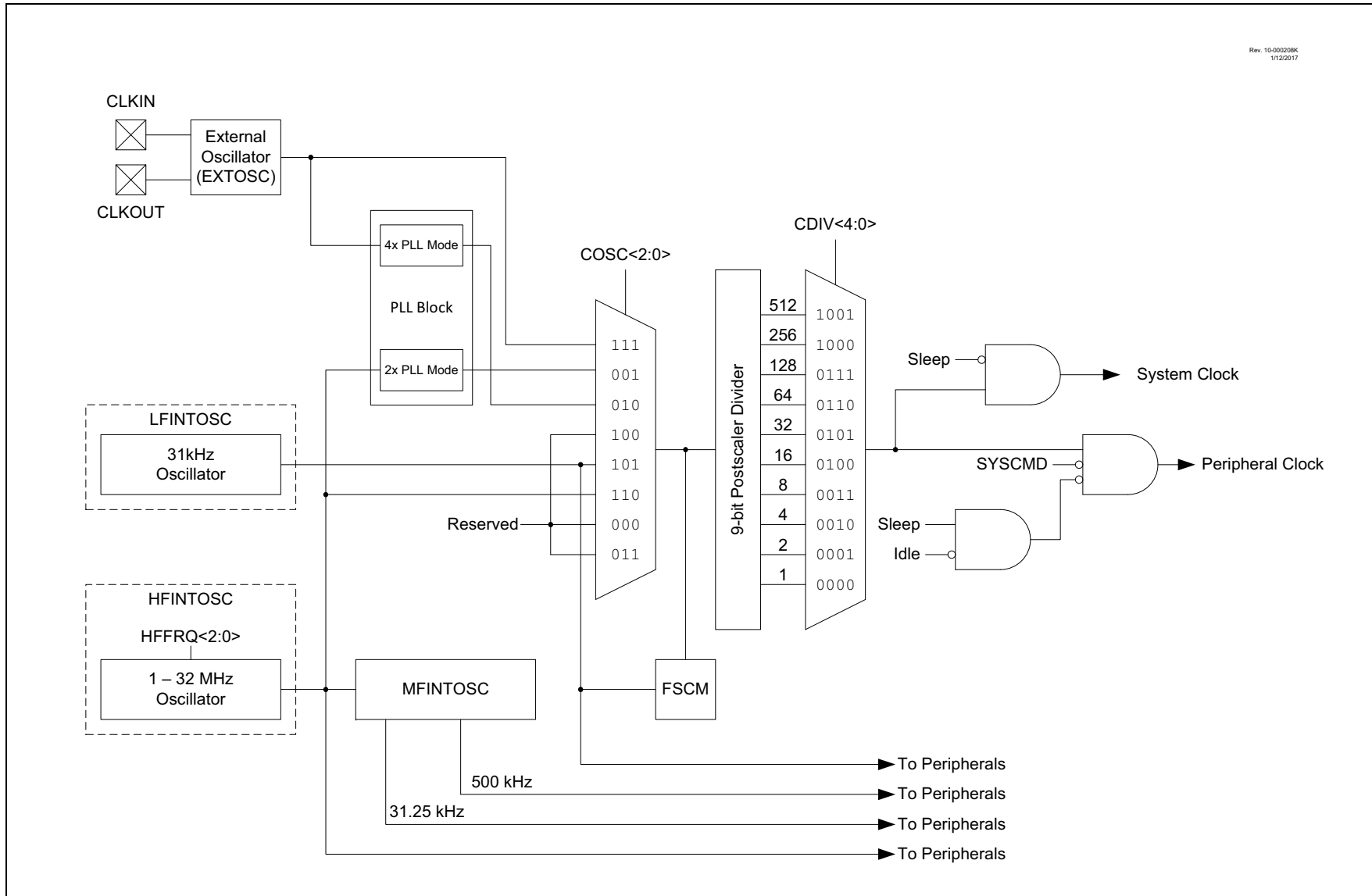
- Power-on Reset ( $\overline{\text{POR}}$ )
- Brown-out Reset ( $\overline{\text{BOR}}$ )
- Reset Instruction Reset ( $\overline{\text{RI}}$ )
- MCLR Reset ( $\overline{\text{RMCLR}}$ )
- Watchdog Timer Reset ( $\overline{\text{RWDT}}$ )
- Watchdog Timer Window Violation Reset ( $\overline{\text{WDTWV}}$ )
- Stack Underflow Reset (STKUNF)
- Stack Overflow Reset (STKOVF)
- Memory Violation Reset ( $\overline{\text{MEMV}}$ )

The PCON0 register bits are shown in Register 8-2.  
The PCON1 register bits are shown in Register 8-3.

Hardware will change the corresponding register bit during the Reset process; if the Reset was not caused by the condition, the bit remains unchanged (Table 8-4).

Software should reset the bit to the inactive state after the restart (hardware will not reset the bit).

Software may also set any PCON bit to the active state, so that user code may be tested, but no reset action will be generated.

**FIGURE 9-1: SIMPLIFIED PIC® MCU CLOCK SOURCE BLOCK DIAGRAM**

## REGISTER 12-2: WDTCON1: WATCHDOG TIMER CONTROL REGISTER 1

U-0	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	U-0	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>
—	WDTCS<2:0>			—	WINDOW<2:0>		
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **WDTCS<2:0>:** Watchdog Timer Clock Select bits

111 = Reserved

•  
•  
•

010 = Reserved

001 = MFINTOSC 31.25 kHz

000 = LFINTOSC 31 kHz

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **WINDOW<2:0>:** Watchdog Timer Window Select bits

WINDOW<2:0>	Window delay Percent of time	Window opening Percent of time
111	N/A	100
110	12.5	87.5
101	25	75
100	37.5	62.5
011	50	50
010	62.5	37.5
001	75	25
000	87.5	12.5

**Note 1:** If WDTCCS <2:0> in CONFIG3 = 111, the Reset value of WDTCS<2:0> is 000.

**2:** The Reset value of WINDOW<2:0> is determined by the value of WDTCCS<2:0> in the CONFIG3 register.

**3:** If WDTCCS<2:0> in CONFIG3 ≠ 111, these bits are read-only.

**4:** If WDTCCS<2:0> in CONFIG3 ≠ 111, these bits are read-only.

**TABLE 14-2: SUMMARY OF REGISTERS ASSOCIATED WITH PORTA**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	175
TRISA	—	—	TRISA5	TRISA4	—	TRISA2	TRISA1	TRISA0	175
LATA	—	—	LATA5	LATA4	—	LATA2	LATA1	LATA0	176
ANSELA	—	—	ANSA5	ANSA4	—	ANSA2	ANSA1	ANSA0	176
WPUA	—	—	WPUA5	WPUA4	WPUA3	WPUA2	WPUA1	WPUA0	177
ODCONA	—	—	ODCA5	ODCA4	—	ODCA2	ODCA1	ODCA0	177
SLRCONA	—	—	SLRA5	SLRA4	—	SLRA2	SLRA1	SLRA0	178
INLVLA	—	—	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0	178

**Legend:** x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by PORTA.

**REGISTER 16-2: PMD1: PMD CONTROL REGISTER 1**

R/W-0/0	U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
NCO1MD	—	—	—	—	TMR2MD	TMR1MD	TMR0MD
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

- bit 7      **NCO1MD:** Disable Numerically Control Oscillator bit  
1 = NCO1 module disabled  
0 = NCO1 module enabled
- bit 6-3    **Unimplemented:** Read as '0'
- bit 2      **TMR2MD:** Disable Timer TMR2 bit  
1 = Timer2 module disabled  
0 = Timer2 module enabled
- bit 1      **TMR1MD:** Disable Timer TMR1 bit  
1 = Timer1 module disabled  
0 = Timer1 module enabled
- bit 0      **TMR0MD:** Disable Timer TMR0 bit  
1 = Timer0 module disabled  
0 = Timer0 module enabled



## REGISTER 17-4: IOCCP: INTERRUPT-ON-CHANGE PORTC POSITIVE EDGE REGISTER<sup>(1)</sup>

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IOCCP5	IOCCP4	IOCCP3	IOCCP2	IOCCP1	IOCCP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-6 **Unimplemented:** read as '0'

bit 5-0 **IOCCP<5:0>:** Interrupt-on-Change PORTC Positive Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a positive-going edge. IOCCFx bit and IOCIF flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin

**Note 1:** Present only in PIC16(L)F15323.

## REGISTER 17-5: IOCCN: INTERRUPT-ON-CHANGE PORTC NEGATIVE EDGE REGISTER<sup>(1)</sup>

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IOCCN5	IOCCN4	IOCCN3	IOCCN2	IOCCN1	IOCCN0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-6 **Unimplemented:** read as '0'

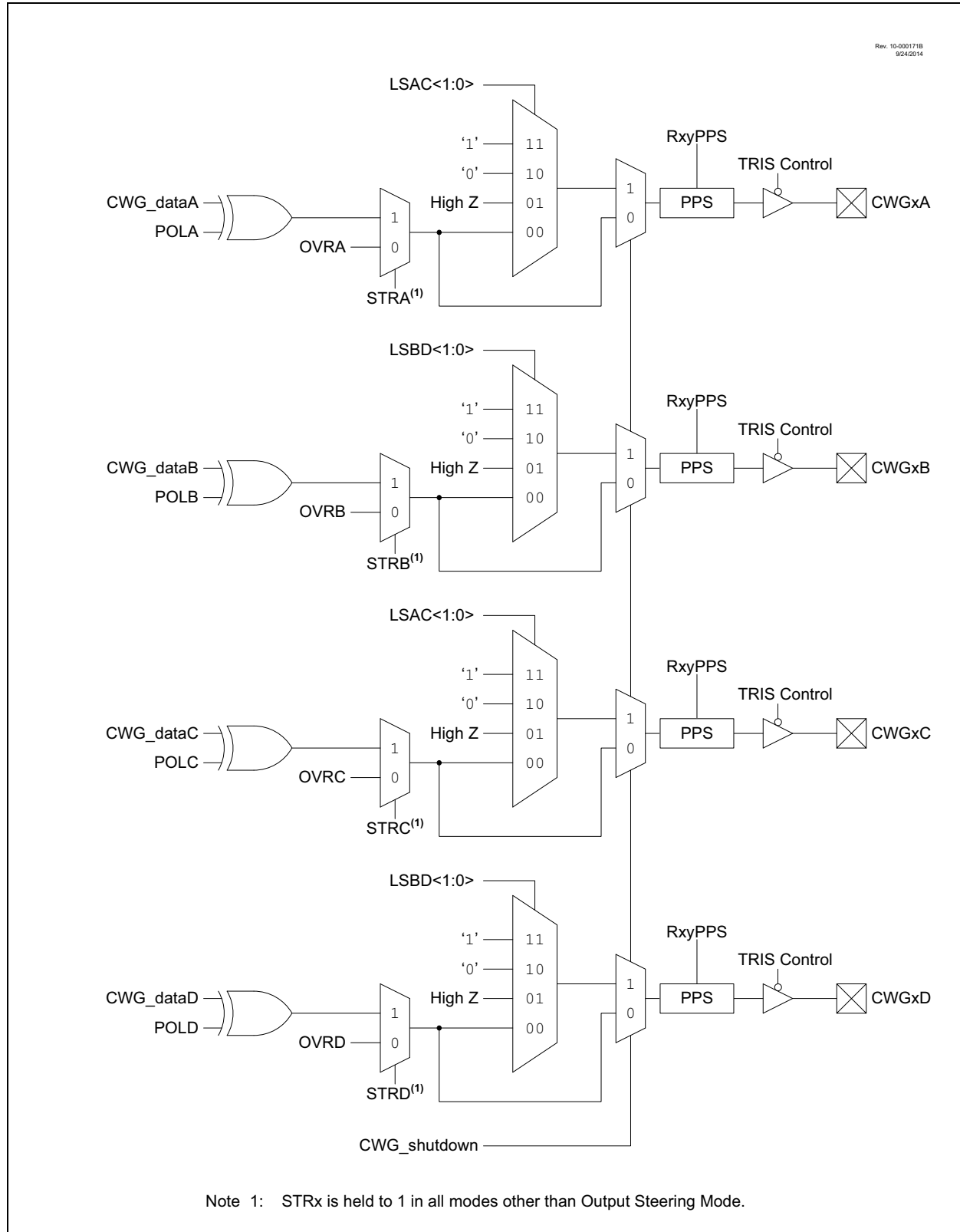
bit 5-0 **IOCCN<5:0>:** Interrupt-on-Change PORTC Negative Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a negative-going edge. IOCCFx bit and IOCIF flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin

**Note 1:** Present only in PIC16(L)F15323.

**FIGURE 30-5: CWG OUTPUT BLOCK DIAGRAM**



## REGISTER 30-5: CWG1AS0: CWG1 AUTO-SHUTDOWN CONTROL REGISTER 0

R/W/HS-0/0	R/W-0/0	R/W-0/0	R/W-1/1	R/W-0/0	R/W-1/1	U-0	U-0
SHUTDOWN <sup>(1,2)</sup>	REN	LSBD<1:0>		LSAC<1:0>		—	—
bit 7							bit 0

### Legend:

HC = Bit is cleared by hardware

HS = Bit is set by hardware

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Value depends on condition

bit 7 **SHUTDOWN:** Auto-Shutdown Event Status bit<sup>(1,2)</sup>

1 = An Auto-Shutdown state is in effect

0 = No Auto-shutdown event has occurred

bit 6 **REN:** Auto-Restart Enable bit

1 = Auto-restart enabled

0 = Auto-restart disabled

bit 5-4 **LSBD<1:0>:** CWG1B and CWG1D Auto-Shutdown State Control bits

11 =A logic '1' is placed on CWG1B/D when an auto-shutdown event is present

10 =A logic '0' is placed on CWG1B/D when an auto-shutdown event is present

01 =Pin is tri-stated on CWG1B/D when an auto-shutdown event is present

00 =The inactive state of the pin, including polarity, is placed on CWG1B/D after the required dead-band interval

bit 3-2 **LSAC<1:0>:** CWG1A and CWG1C Auto-Shutdown State Control bits

11 =A logic '1' is placed on CWG1A/C when an auto-shutdown event is present

10 =A logic '0' is placed on CWG1A/C when an auto-shutdown event is present

01 =Pin is tri-stated on CWG1A/C when an auto-shutdown event is present

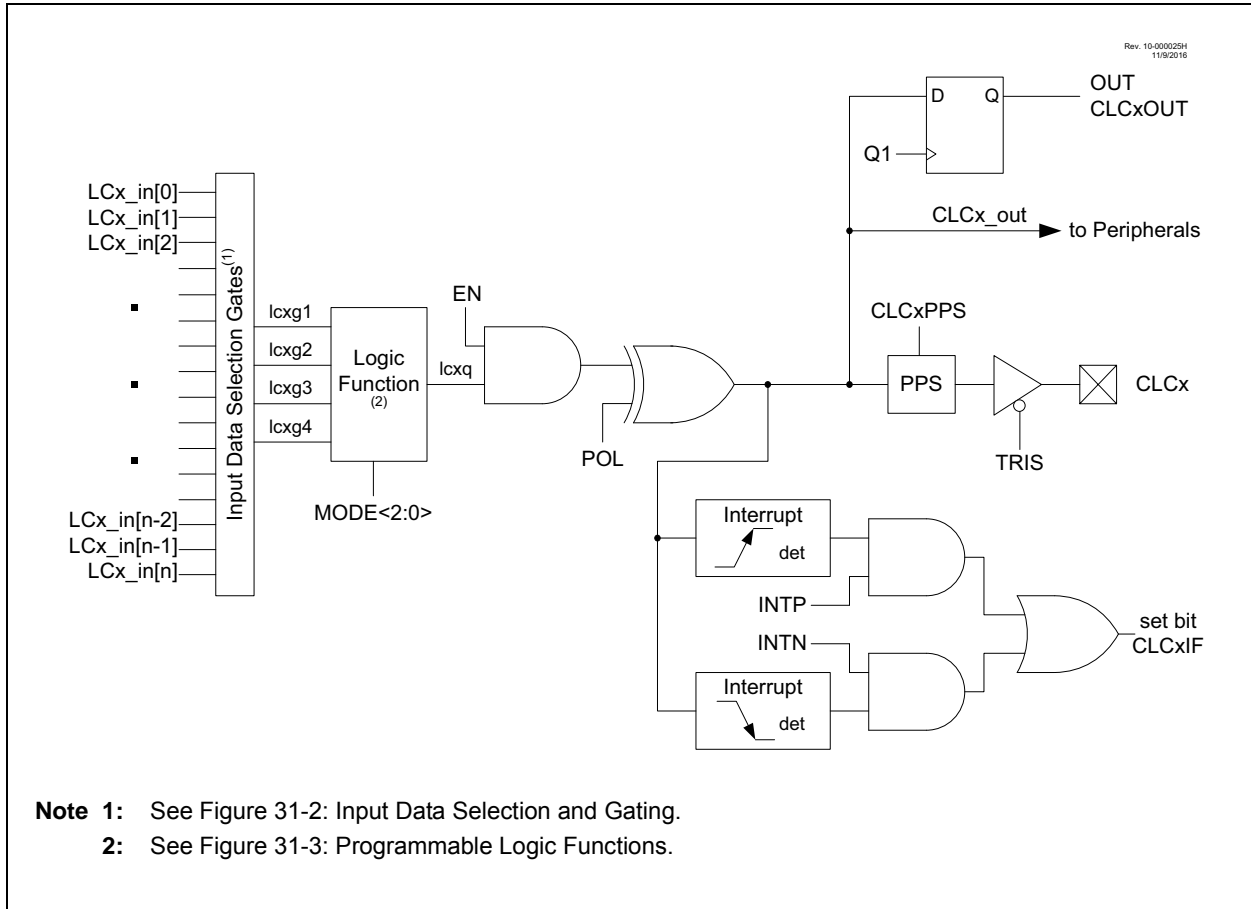
00 =The inactive state of the pin, including polarity, is placed on CWG1A/C after the required dead-band interval

bit 1-0 **Unimplemented:** Read as '0'

**Note 1:** This bit may be written while EN = 0 (CWG1CON0 register) to place the outputs into the shutdown configuration.

**2:** The outputs will remain in auto-shutdown state until the next rising edge of the input signal after this bit is cleared.

**FIGURE 31-1: CLCx SIMPLIFIED BLOCK DIAGRAM**



## REGISTER 31-10: CLCxGLS3: GATE 3 LOGIC SELECT REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
LCxG4D4T	LCxG4D4N	LCxG4D3T	LCxG4D3N	LCxG4D2T	LCxG4D2N	LCxG4D1T	LCxG4D1N
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7 **LCxG4D4T:** Gate 3 Data 4 True (non-inverted) bit  
 1 = CLCIN3 (true) is gated into CLCx Gate 3  
 0 = CLCIN3 (true) is not gated into CLCx Gate 3
- bit 6 **LCxG4D4N:** Gate 3 Data 4 Negated (inverted) bit  
 1 = CLCIN3 (inverted) is gated into CLCx Gate 3  
 0 = CLCIN3 (inverted) is not gated into CLCx Gate 3
- bit 5 **LCxG4D3T:** Gate 3 Data 3 True (non-inverted) bit  
 1 = CLCIN2 (true) is gated into CLCx Gate 3  
 0 = CLCIN2 (true) is not gated into CLCx Gate 3
- bit 4 **LCxG4D3N:** Gate 3 Data 3 Negated (inverted) bit  
 1 = CLCIN2 (inverted) is gated into CLCx Gate 3  
 0 = CLCIN2 (inverted) is not gated into CLCx Gate 3
- bit 3 **LCxG4D2T:** Gate 3 Data 2 True (non-inverted) bit  
 1 = CLCIN1 (true) is gated into CLCx Gate 3  
 0 = CLCIN1 (true) is not gated into CLCx Gate 3
- bit 2 **LCxG4D2N:** Gate 3 Data 2 Negated (inverted) bit  
 1 = CLCIN1 (inverted) is gated into CLCx Gate 3  
 0 = CLCIN1 (inverted) is not gated into CLCx Gate 3
- bit 1 **LCxG4D1T:** Gate 4 Data 1 True (non-inverted) bit  
 1 = CLCIN0 (true) is gated into CLCx Gate 3  
 0 = CLCIN0 (true) is not gated into CLCx Gate 3
- bit 0 **LCxG4D1N:** Gate 3 Data 1 Negated (inverted) bit  
 1 = CLCIN0 (inverted) is gated into CLCx Gate 3  
 0 = CLCIN0 (inverted) is not gated into CLCx Gate 3

## 32.2.3 SPI MASTER MODE

The master can initiate the data transfer at any time because it controls the SCK line. The master determines when the slave (Processor 2, Figure 32-5) is to broadcast data by the software protocol.

In Master mode, the data is transmitted/received as soon as the SSP1BUF register is written to. If the SPI is only going to receive, the SDO output could be disabled (programmed as an input). The SSP1SR register will continue to shift in the signal present on the SDI pin at the programmed clock rate. As each byte is received, it will be loaded into the SSP1BUF register as if a normal received byte (interrupts and Status bits appropriately set).

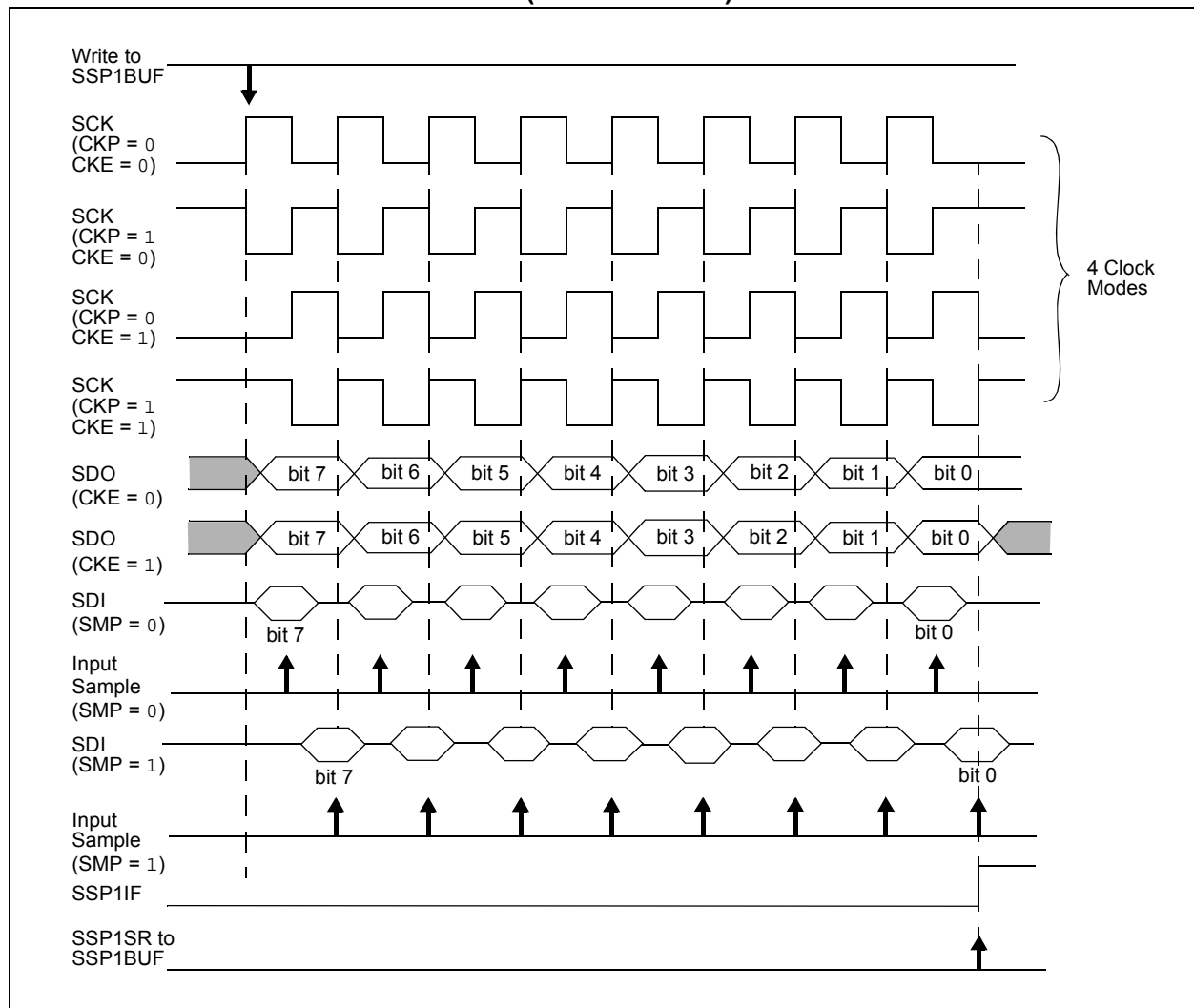
The clock polarity is selected by appropriately programming the CKP bit of the SSP1CON1 register and the CKE bit of the SSP1STAT register. This then, would give waveforms for SPI communication as shown in Figure 32-6, Figure 32-8, Figure 32-9 and Figure 32-10, where the MSB is transmitted first. In Master mode, the SPI clock rate (bit rate) is user programmable to be one of the following:

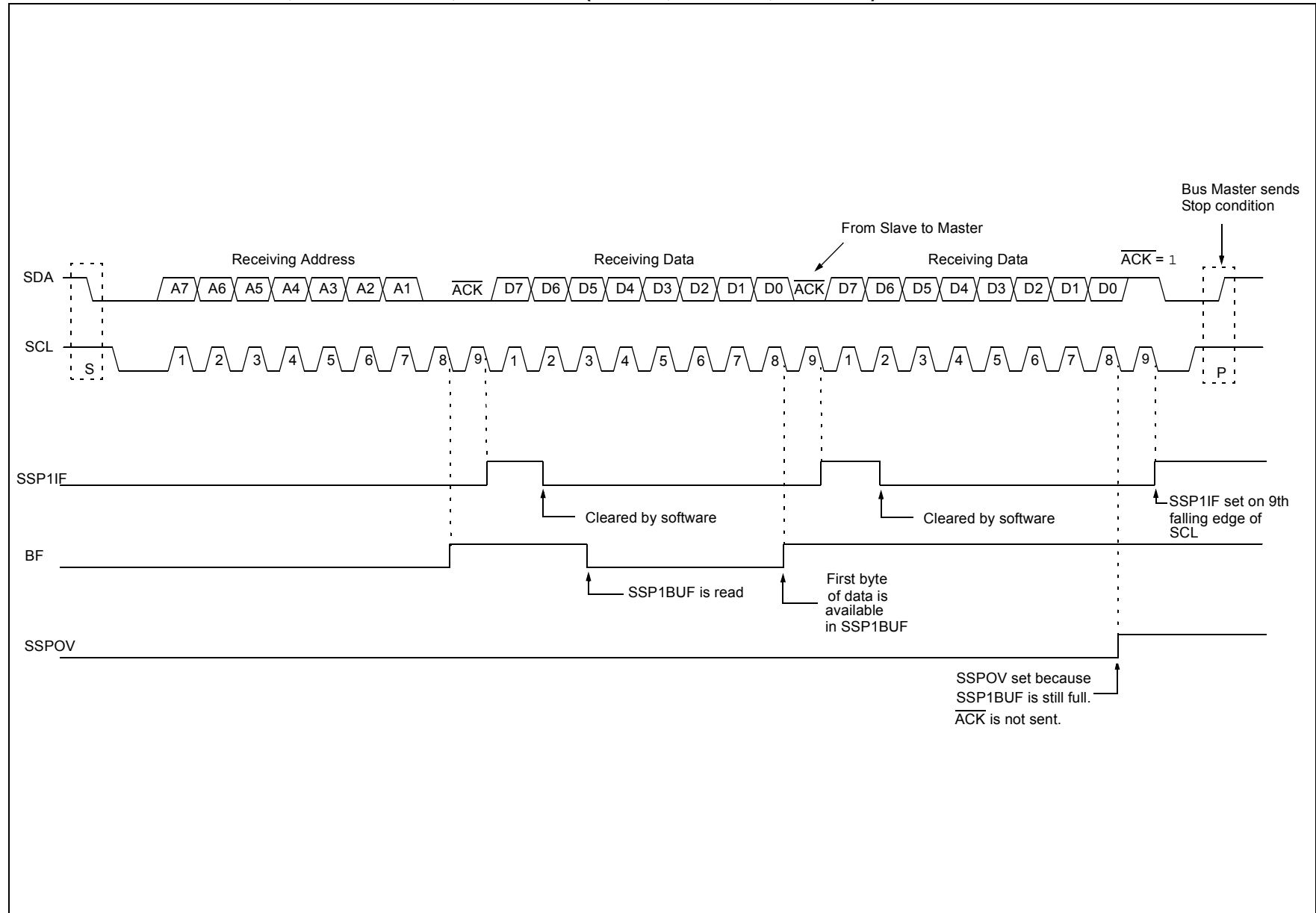
- $F_{osc}/4$  (or  $T_{CY}$ )
- $F_{osc}/16$  (or  $4 * T_{CY}$ )
- $F_{osc}/64$  (or  $16 * T_{CY}$ )
- Timer2 output/2
- $F_{osc}/(4 * (SSP1ADD + 1))$

Figure 32-6 shows the waveforms for Master mode.

When the CKE bit is set, the SDO data is valid before there is a clock edge on SCK. The change of the input sample is shown based on the state of the SMP bit. The time when the SSP1BUF is loaded with the received data is shown.

**FIGURE 32-6: SPI MODE WAVEFORM (MASTER MODE)**



**FIGURE 32-14: I<sup>2</sup>C SLAVE, 7-BIT ADDRESS, RECEPTION (SEN = 0, AHEN = 0, DHEN = 0)**

## 32.5.3.3 7-bit Transmission with Address Hold Enabled

Setting the AHEN bit of the SSP1CON3 register enables additional clock stretching and interrupt generation after the eighth falling edge of a received matching address. Once a matching address has been clocked in, CKP is cleared and the SSP1IF interrupt is set.

Figure 32-19 displays a standard waveform of a 7-bit address slave transmission with AHEN enabled.

1. Bus starts Idle.
2. Master sends Start condition; the S bit of SSP1STAT is set; SSP1IF is set if interrupt on Start detect is enabled.
3. Master sends matching address with  $\overline{R/W}$  bit set. After the eighth falling edge of the SCL line the CKP bit is cleared and SSP1IF interrupt is generated.
4. Slave software clears SSP1IF.
5. Slave software reads ACKTIM bit of SSP1CON3 register, and  $\overline{R/W}$  and D/A of the SSP1STAT register to determine the source of the interrupt.
6. Slave reads the address value from the SSP1BUF register clearing the BF bit.
7. Slave software decides from this information if it wishes to ACK or not ACK and sets the ACKDT bit of the SSP1CON2 register accordingly.
8. Slave sets the CKP bit releasing SCL.
9. Master clocks in the  $\overline{ACK}$  value from the slave.
10. Slave hardware automatically clears the CKP bit and sets SSP1IF after the ACK if the  $\overline{R/W}$  bit is set.
11. Slave software clears SSP1IF.
12. Slave loads value to transmit to the master into SSP1BUF setting the BF bit.

**Note:** SSP1BUF cannot be loaded until after the  $\overline{ACK}$ .

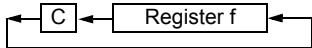
13. Slave sets the CKP bit releasing the clock.
14. Master clocks out the data from the slave and sends an  $\overline{ACK}$  value on the ninth SCL pulse.
15. Slave hardware copies the  $\overline{ACK}$  value into the ACKSTAT bit of the SSP1CON2 register.
16. Steps 10-15 are repeated for each byte transmitted to the master from the slave.
17. If the master sends a not  $\overline{ACK}$  the slave releases the bus allowing the master to send a Stop and end the communication.

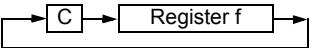
**Note:** Master must send a not  $\overline{ACK}$  on the last byte to ensure that the slave releases the SCL line to receive a Stop.



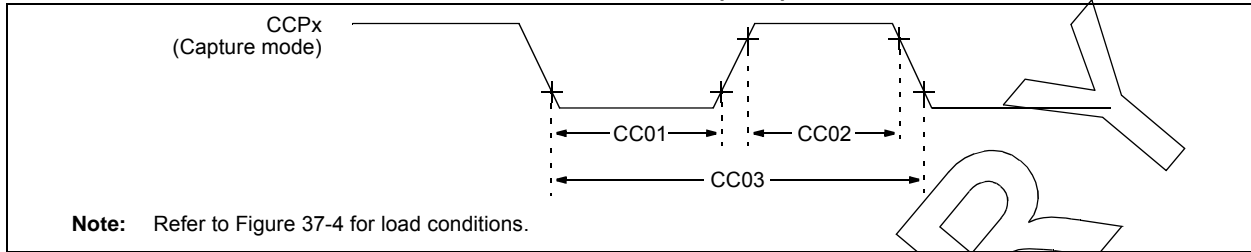
<b>RETLW</b>	<b>Return with literal in W</b>
Syntax:	[ <i>label</i> ] RETLW <i>k</i>
Operands:	$0 \leq k \leq 255$
Operation:	$k \rightarrow (W)$ ; $TOS \rightarrow PC$
Status Affected:	None
Description:	The W register is loaded with the 8-bit literal 'k'. The program counter is loaded from the top of the stack (the return address). This is a 2-cycle instruction.
Words:	1
Cycles:	2
<u>Example:</u>	CALL TABLE;W contains table ;offset value • ;W now has table value • • ADDWF PC ;W = offset RETLW k1 ;Begin table RETLW k2 ; • • • RETLW kn ; End of table
TABLE	
	Before Instruction W = 0x07 After Instruction W = value of k8

<b>RETURN</b>	<b>Return from Subroutine</b>
Syntax:	[ <i>label</i> ] RETURN
Operands:	None
Operation:	$TOS \rightarrow PC$
Status Affected:	None
Description:	Return from subroutine. The stack is POPed and the top of the stack (TOS) is loaded into the program counter. This is a 2-cycle instruction.

<b>RLF</b>	<b>Rotate Left f through Carry</b>
Syntax:	[ <i>label</i> ] RLF <i>f,d</i>
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	See description below
Status Affected:	C
Description:	The contents of register 'f' are rotated one bit to the left through the Carry flag. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is stored back in register 'f'.
	
Words:	1
Cycles:	1
<u>Example:</u>	RLF REG1,0 Before Instruction REG1 = 1110 0110 C = 0 After Instruction REG1 = 1110 0110 W = 1100 1100 C = 1

<b>RRF</b>	<b>Rotate Right f through Carry</b>
Syntax:	[ <i>label</i> ] RRF <i>f,d</i>
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	See description below
Status Affected:	C
Description:	The contents of register 'f' are rotated one bit to the right through the Carry flag. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.
	

**FIGURE 37-13: CAPTURE/COMPARE/PWM TIMINGS (CCP)**



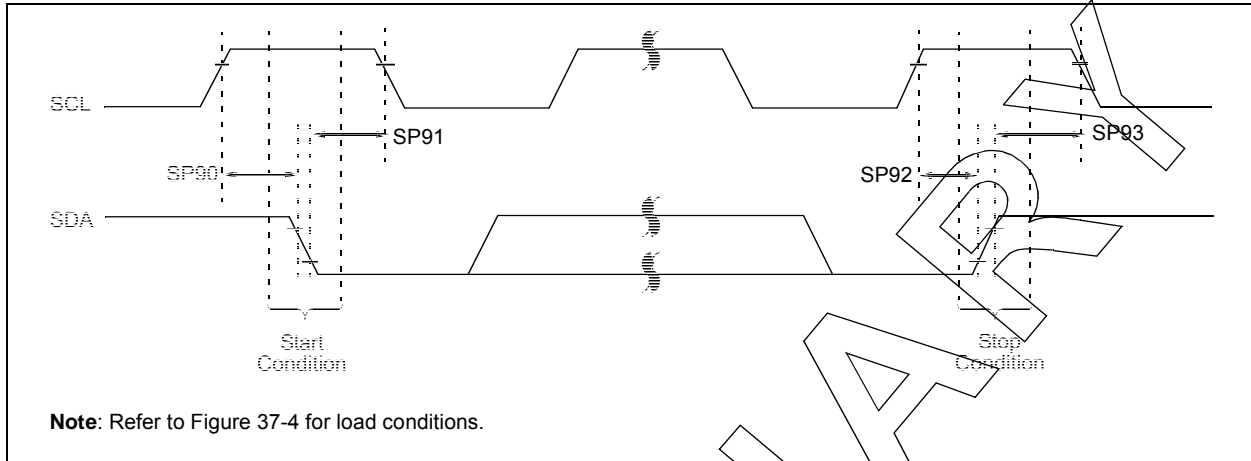
**TABLE 37-19: CAPTURE/COMPARE/PWM REQUIREMENTS (CCP)**

Standard Operating Conditions (unless otherwise stated)							
Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$							
Param. No.	Sym.	Characteristic		Min.	Typ†	Max.	Units
CC01*	TccL	CCPx Input Low Time	No Prescaler	$0.5T_{CY} + 20$	—	—	ns
			With Prescaler	20	—	—	ns
CC02*	TccH	CCPx Input High Time	No Prescaler	$0.5T_{CY} + 20$	—	—	ns
			With Prescaler	20	—	—	ns
CC03*	TccP	CCPx Input Period		$\frac{3T_{CY} + 40}{N}$	—	—	ns

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

**FIGURE 37-21: I<sup>2</sup>C BUS START/STOP BITS TIMING**

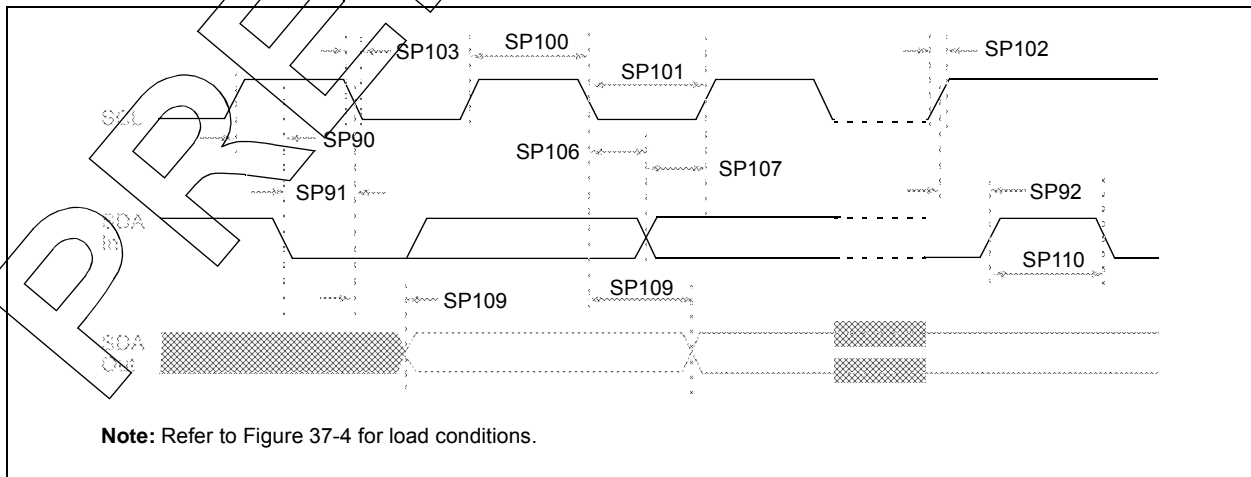


**TABLE 37-24: I<sup>2</sup>C BUS START/STOP BITS REQUIREMENTS**

Standard Operating Conditions (unless otherwise stated)								
Param. No.	Symbol	Characteristic		Min.	Typ	Max.	Units	Conditions
SP90*	TSU:STA	Start condition	100 kHz mode	4700	—	—	ns	Only relevant for Repeated Start condition
		Setup time	400 kHz mode	600	—	—		
SP91*	THD:STA	Start condition	100 kHz mode	4000	—	—	ns	After this period, the first clock pulse is generated
		Hold time	400 kHz mode	600	—	—		
SP92*	TSU:STO	Stop condition	100 kHz mode	4700	—	—	ns	
		Setup time	400 kHz mode	600	—	—		
SP93	THD:STO	Stop condition	100 kHz mode	4000	—	—	ns	
		Hold time	400 kHz mode	600	—	—		

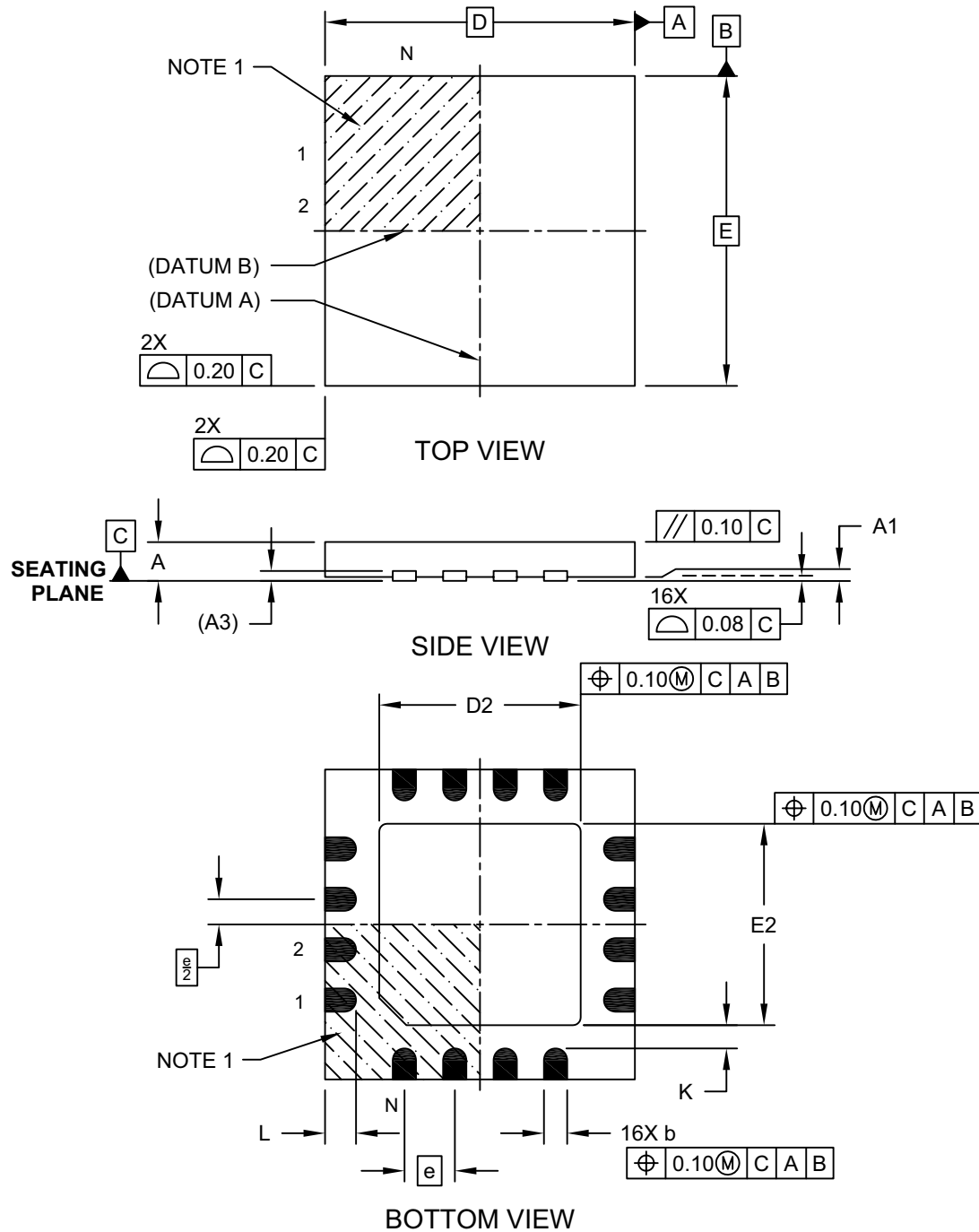
\* These parameters are characterized but not tested.

**FIGURE 37-22: I<sup>2</sup>C BUS DATA TIMING**



## 16-Lead Ultra Thin Plastic Quad Flat, No Lead Package (JQ) - 4x4x0.5 mm Body [UQFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-257A Sheet 1 of 2

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