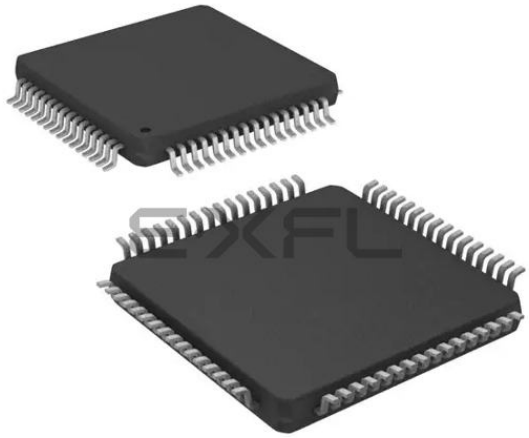

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	50
Program Memory Size	128KB (64K x 16)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atxmega128a3u-aur

6. AVR CPU

6.1 Features

- 8/16-bit, high-performance Atmel AVR RISC CPU
  - 142 instructions
  - Hardware multiplier
- 32x8-bit registers directly connected to the ALU
- Stack in RAM
- Stack pointer accessible in I/O memory space
- Direct addressing of up to 16MB of program memory and 16MB of data memory
- True 16/24-bit access to 16/24-bit I/O registers
- Efficient support for 8-, 16-, and 32-bit arithmetic
- Configuration change protection of system-critical features

6.2 Overview

All Atmel AVR XMEGA devices use the 8/16-bit AVR CPU. The main function of the CPU is to execute the code and perform all calculations. The CPU is able to access memories, perform calculations, control peripherals, and execute the program in the flash memory. Interrupt handling is described in a separate section, refer to “Interrupts and Programmable Multilevel Interrupt Controller” on page 30.

6.3 Architectural Overview

In order to maximize performance and parallelism, the AVR CPU uses a Harvard architecture with separate memories and buses for program and data. Instructions in the program memory are executed with single-level pipelining. While one instruction is being executed, the next instruction is pre-fetched from the program memory. This enables instructions to be executed on every clock cycle. For details of all AVR instructions, refer to http://www.atmel.com/avr.

36.1.5 I/O Pin Characteristics

The I/O pins comply with the JEDEC LVTTL and LVCMOS specification and the high- and low level input and output voltage limits reflect or exceed this specification.

Table 36-7. I/O pin characteristics.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
I_{OH} [1]/ I_{OL} [2]	I/O pin source/sink current			-20		20	mA
V_{IH}	High Level Input Voltage	V_{CC} = 2.7 - 3.6V		2		V_{CC}+0.3	V
		V_{CC} = 2.0 - 2.7V		0.7*V_{CC}		V_{CC}+0.3	
		V_{CC} = 1.6 - 2.0V		0.8*V_{CC}		V_{CC}+0.3	
V_{IL}	Low Level Input Voltage	V_{CC} = 2.7- 3.6V		-0.3		0.8	V
		V_{CC} = 2.0 - 2.7V		-0.3		0.3*V_{CC}	
		V_{CC} = 1.6 - 2.0V		-0.3		0.2*V_{CC}	
V_{OH}	High Level Output Voltage	V_{CC} = 3.0 - 3.6V	I_{OH} = -2mA	2.4	0.94*V_{CC}		V
		V_{CC} = 2.3 - 2.7V	I_{OH} = -1mA	2.0	0.96*V_{CC}		
			I_{OH} = -2mA	1.7	0.92*V_{CC}		
		V_{CC} = 3.3V	I_{OH} = -8mA	2.6	2.9		
		V_{CC} = 3.0V	I_{OH} = -6mA	2.1	2.6		
		V_{CC} = 1.8V	I_{OH} = -2mA	1.4	1.6		
V_{OL}	Low Level Output Voltage	V_{CC} = 3.0 - 3.6V	I_{OL} = 2mA		0.05*V_{CC}	0.4	V
		V_{CC} = 2.3 - 2.7V	I_{OL} = 1mA		0.03*V_{CC}	0.4	
			I_{OL} = 2mA		0.06*V_{CC}	0.7	
		V_{CC} = 3.3V	I_{OL} = 15mA		0.4	0.76	
		V_{CC} = 3.0V	I_{OL} = 10mA		0.3	0.64	
		V_{CC} = 1.8V	I_{OL} = 5mA		0.3	0.46	
I_{IN}	Input Leakage Current	T = 25°C			<0.01	0.1	µA
R_P	Pull/Buss keeper Resistor				27		kΩ
t_r	Rise time	No load			4		ns
			slew rate limitation		7		

Notes:
1. The sum of all I_{OH} for PORTA and PORTB must not exceed 100mA.
   The sum of all I_{OH} for PORTC, PORTD, PORTE must for each port not exceed 200mA.
   The sum of all I_{OH} for pins PF[0-5] on PORTF must not exceed 200mA.
   The sum of all I_{OL} for pins PF[6-7] on PORTF, PORTR and PDI must not exceed 100mA.
2. The sum of all I_{OL} for PORTA and PORTB must not exceed 100mA.
   The sum of all I_{OL} for PORTC, PORTD, PORTE must for each port not exceed 200mA.
   The sum of all I_{OL} for pins PF[0-5] on PORTF must not exceed 200mA.
   The sum of all I_{OL} for pins PF[6-7] on PORTF, PORTR and PDI must not exceed 100mA.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$t_{SU;STA}$	Set-up time for a repeated START condition	$f_{SCL} \leq 100kHz$	4.7			µs
		$f_{SCL} > 100kHz$	0.6			
$t_{HD;DAT}$	Data hold time	$f_{SCL} \leq 100kHz$	0		3.45	µs
		$f_{SCL} > 100kHz$	0		0.9	
$t_{SU;DAT}$	Data setup time	$f_{SCL} \leq 100kHz$	250			ns
		$f_{SCL} > 100kHz$	100			
$t_{SU;STO}$	Setup time for STOP condition	$f_{SCL} \leq 100kHz$	4.0			µs
		$f_{SCL} > 100kHz$	0.6			
t_{BUF}	Bus free time between a STOP and START condition	$f_{SCL} \leq 100kHz$	4.7			µs
		$f_{SCL} > 100kHz$	1.3			

Notes:
1. Required only for $f_{SCL} > 100kHz$.
2. C_b = Capacitance of one bus line in pF.
3. f_{PER} = Peripheral clock frequency.

Table 36-69. Current consumption for modules and peripherals.

Symbol	Parameter	Condition[1]		Min.	Typ.	Max.	Units
I_{CC}	ULP oscillator				1.0		µA
	32.768kHz int. oscillator				27		µA
	2MHz int. oscillator				85		µA
		DFLL enabled with 32.768kHz int. osc. as reference			115		
	32MHz int. oscillator				270		µA
		DFLL enabled with 32.768kHz int. osc. as reference			460		
	PLL	20x multiplication factor, 32MHz int. osc. DIV4 as reference			220		µA
	Watchdog Timer				1		µA
	BOD	Continuous mode			138		µA
		Sampled mode, includes ULP oscillator			1.2		
	Internal 1.0V reference				100		µA
	Temperature sensor				95		µA
	ADC	250ksps V_{REF} = Ext ref			3.0		mA
			CURRLIMIT = LOW		2.6		
			CURRLIMIT = MEDIUM		2.1		
			CURRLIMIT = HIGH		1.6		
	DAC	250ksps V_{REF} = Ext ref No load	Normal mode		1.9		mA
			Low Power mode		1.1		
	AC	High Speed Mode			330		µA
		Low Power Mode			130		
	DMA	615KBps between I/O registers and SRAM			115		µA
	Timer/Counter				16		µA
	USART	Rx and Tx enabled, 9600 BAUD			2.5		µA
	Flash memory and EEPROM programming				4		mA

Note: 1. All parameters measured as the difference in current consumption between module enabled and disabled. All data at V_{CC} = 3.0V, Clk_{SYS} = 1MHz external clock without prescaling, T = 25°C unless other conditions are givenAll parameters measured as the difference in current consumption between module enabled and disabled. All data at V_{CC} = 3.0V, Clk_{SYS} = 1MHz external clock without prescaling, T = 25°C unless other conditions are given.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
	Offset Error, input referred	1x gain, normal mode			-2		mV
		8x gain, normal mode			-5		
		64x gain, normal mode			-4		
	Noise	1x gain, normal mode	V_{CC} = 3.6V Ext. V_{REF}		0.5		mV rms
		8x gain, normal mode			1.5		
		64x gain, normal mode			11		

Note: 1. Maximum numbers are based on characterisation and not tested in production, and valid for 5% to 95% input voltage range.

36.3.7 DAC Characteristics

Table 36-76. Power supply, reference and output range.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
AV_{CC}	Analog supply voltage		V_{CC}- 0.3		V_{CC}+ 0.3	
AV_{REF}	External reference voltage		1.0		V_{CC}- 0.6	V
$R_{channel}$	DC output impedance				50	Ω
	Linear output voltage range		0.15		AV_{CC}-0.15	V
R_{AREF}	Reference input resistance			>10		MΩ
CAREF	Reference input capacitance	Static load		7		pF
	Minimum Resistance load		1			kΩ
	Maximum capacitance load				100	pF
		1000Ω serial resistance			1	nF
	Output sink/source	Operating within accuracy specification			AV_{CC}/1000	mA
		Safe operation			10	

Table 36-77. Clock and timing.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
f_{DAC}	Conversion rate	C_{load}=100pF, maximum step size	Normal mode	0		1000	ksps
			Low power mode	0		500	

36.3.11 External Reset Characteristics

Table 36-82. External reset characteristics.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
t_{EXT}	Minimum reset pulse width			95	1000	ns
V_{RST}	Reset threshold voltage (V_{IH})	V_{CC} = 2.7 - 3.6V		0.60*V_{CC}		V
		V_{CC} = 1.6 - 2.7V		0.70*V_{CC}		
	Reset threshold voltage (V_{IL})	V_{CC} = 2.7 - 3.6V		0.40*V_{CC}		
		V_{CC} = 1.6 - 2.7V		0.30*V_{CC}		
R_{RST}	Reset pin Pull-up Resistor			25		kΩ

36.3.12 Power-on Reset Characteristics

Table 36-83. Power-on reset characteristics.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V_{POT-} [1]	POR threshold voltage falling V_{CC}	V_{CC} falls faster than 1V/ms	0.4	1.0		V
		V_{CC} falls at 1V/ms or slower	0.8	1.0		
V_{POT+}	POR threshold voltage rising V_{CC}			1.3	1.59	V

Note: 1. V_{POT-} values are only valid when BOD is disabled. When BOD is enabled V_{POT-} = V_{POT+}.

36.3.13 Flash and EEPROM Memory Characteristics

Table 36-84. Endurance and data retention.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
	Flash	Write/Erase cycles	25°C	10K			Cycle
			85°C	10K			
			105°C	2K			
		Data retention	25°C	100			Year
			85°C	25			
			105°C	10			
	EEPROM	Write/Erase cycles	25°C	100K			Cycle
			85°C	100K			
			105°C	30K			
		Data retention	25°C	100			Year
			85°C	25			
			105°C	10			

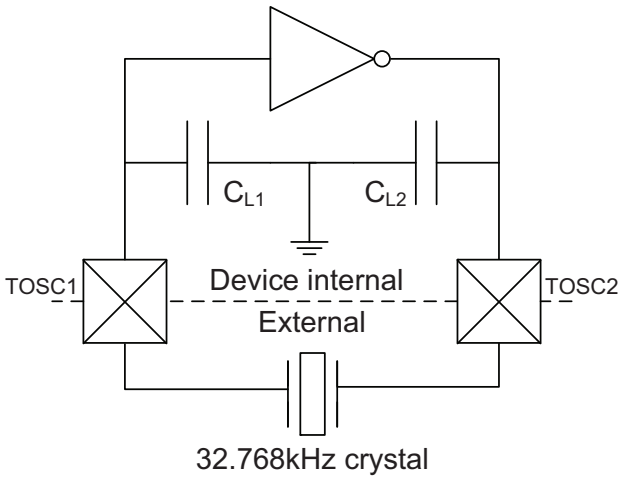
36.3.14.8 External 32.768kHz crystal oscillator and TOSC characteristics

Table 36-94. External 32.768kHz crystal oscillator and TOSC characteristics.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
ESR/R1	Recommended crystal equivalent series resistance (ESR)	Crystal load capacitance 6.5pF			60	kΩ
		Crystal load capacitance 9.0pF			35	
C_{TOSC1}	Parasitic capacitance TOSC1 pin			4.2		pF
C_{TOSC2}	Parasitic capacitance TOSC2 pin			4.3		pF
	Recommended safety factor	capacitance load matched to crystal specification	3			

Note: 1. See Figure 36-4 for definition.

Figure 36-18. TOSC input capacitance.



The parasitic capacitance between the TOSC pins is C_{L1} + C_{L2} in series as seen from the crystal when oscillating without external capacitors.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
R_Q	Negative impedance (1)	XOSCPWR=0, FRQRANGE=0	0.4MHz resonator, CL=100pF	2.4k			Ω
			1MHz crystal, CL=20pF	8.7k			
			2MHz crystal, CL=20pF	2.1k			
		XOSCPWR=0, FRQRANGE=1, CL=20pF	2MHz crystal	4.2k			
			8MHz crystal	250			
			9MHz crystal	195			
		XOSCPWR=0, FRQRANGE=2, CL=20pF	8MHz crystal	360			
			9MHz crystal	285			
			12MHz crystal	155			
		XOSCPWR=0, FRQRANGE=3, CL=20pF	9MHz crystal	365			
			12MHz crystal	200			
			16MHz crystal	105			
		XOSCPWR=1, FRQRANGE=0, CL=20pF	9MHz crystal	435			
			12MHz crystal	235			
			16MHz crystal	125			
		XOSCPWR=1, FRQRANGE=1, CL=20pF	9MHz crystal	495			
			12MHz crystal	270			
			16MHz crystal	145			
		XOSCPWR=1, FRQRANGE=2, CL=20pF	12MHz crystal	305			
			16MHz crystal	160			
		XOSCPWR=1, FRQRANGE=3, CL=20pF	12MHz crystal	380			
			16MHz crystal	205			
	ESR	SF = Safety factor				$\min(R_Q)/SF$	kΩ
C_{XTAL1}	Parasitic capacitance XTAL1 pin				5.2		pF
C_{XTAL2}	Parasitic capacitance XTAL2 pin				6.8		pF
C_{LOAD}	Parasitic capacitance load				2.95		pF

Note: 1. Numbers for negative impedance are not tested in production but guaranteed from design and characterization.

Figure 37-65. Reset pin input threshold voltage vs. V_{CC}.

V_{IH} - Reset pin read as "1".

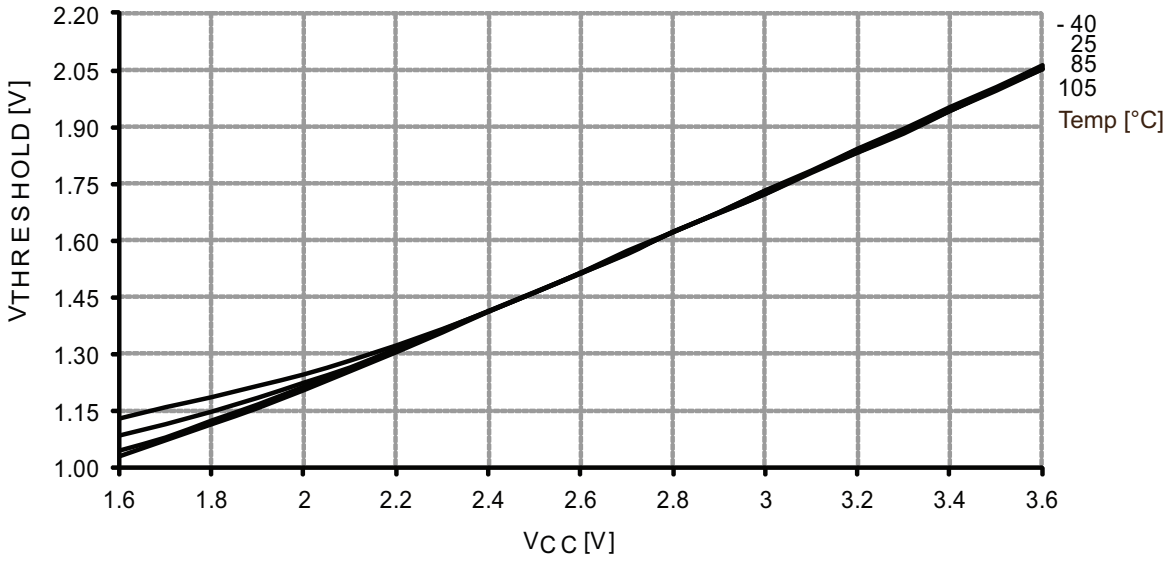


Figure 37-66. Reset pin input threshold voltage vs. V_{CC}.

V_{IL} - Reset pin read as "0".

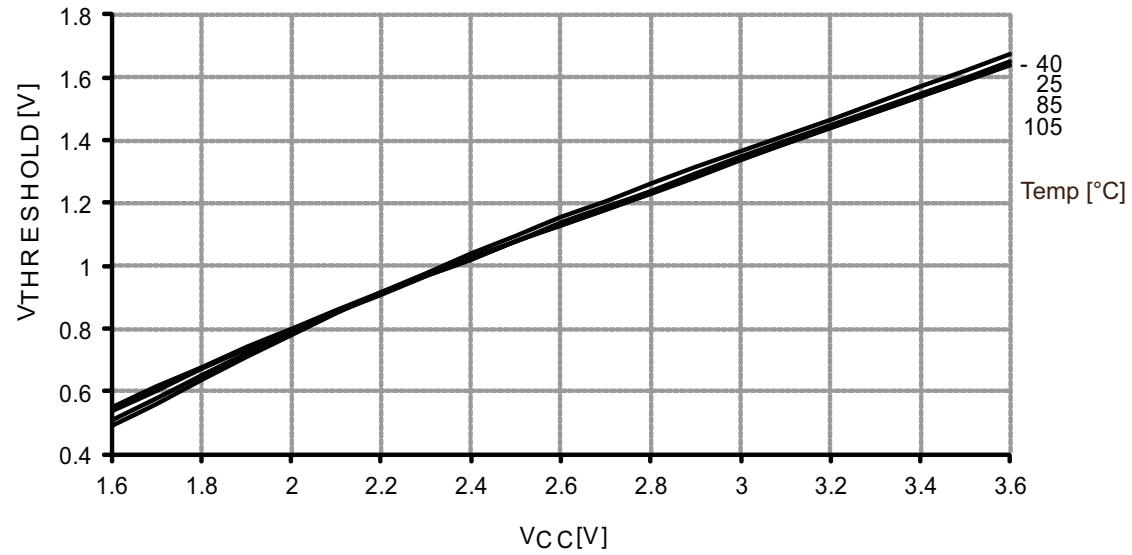


Figure 37-72. 2MHz internal oscillator frequency vs. temperature.

DFLL enabled, from the 32.768kHz internal oscillator.

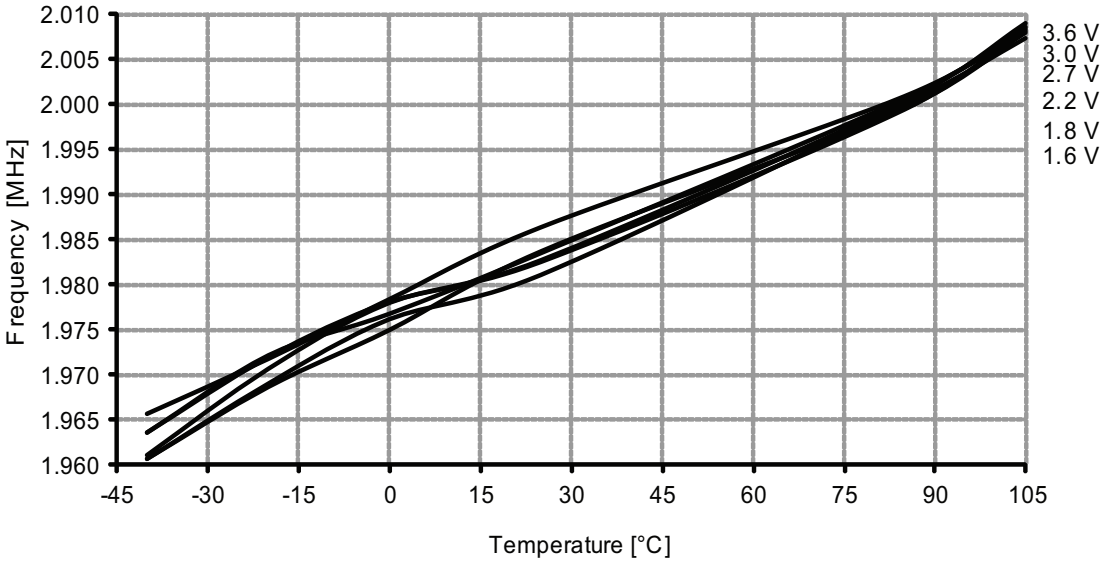
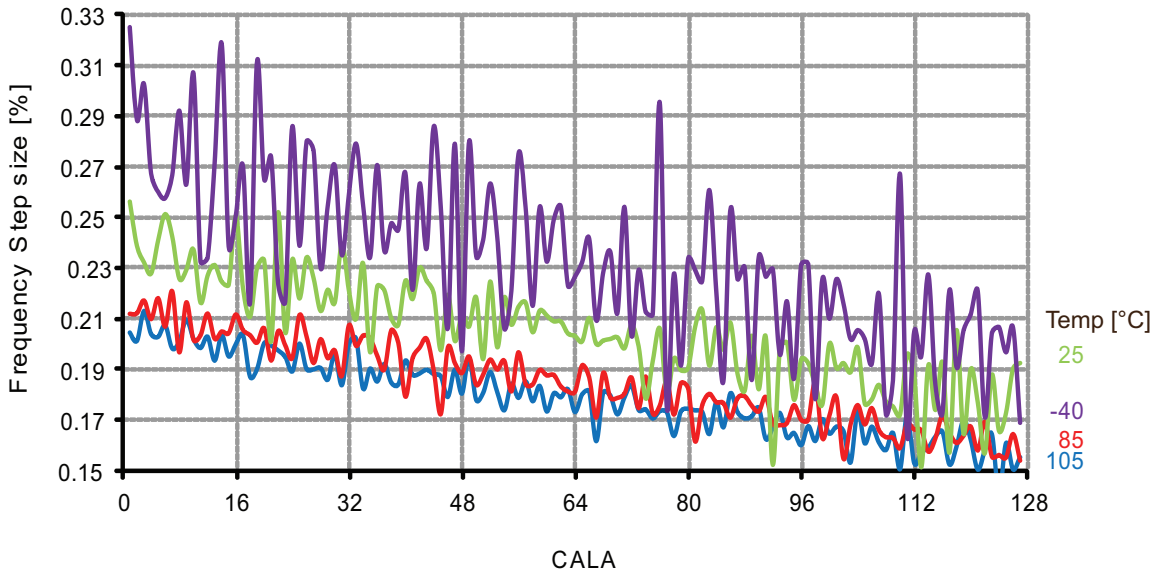


Figure 37-73. 2MHz internal oscillator CALA calibration step size.

V_{CC} = 3V.



37.1.10.4 32MHz Internal Oscillator

Figure 37-74. 32MHz internal oscillator frequency vs. temperature.
DFLL disabled.

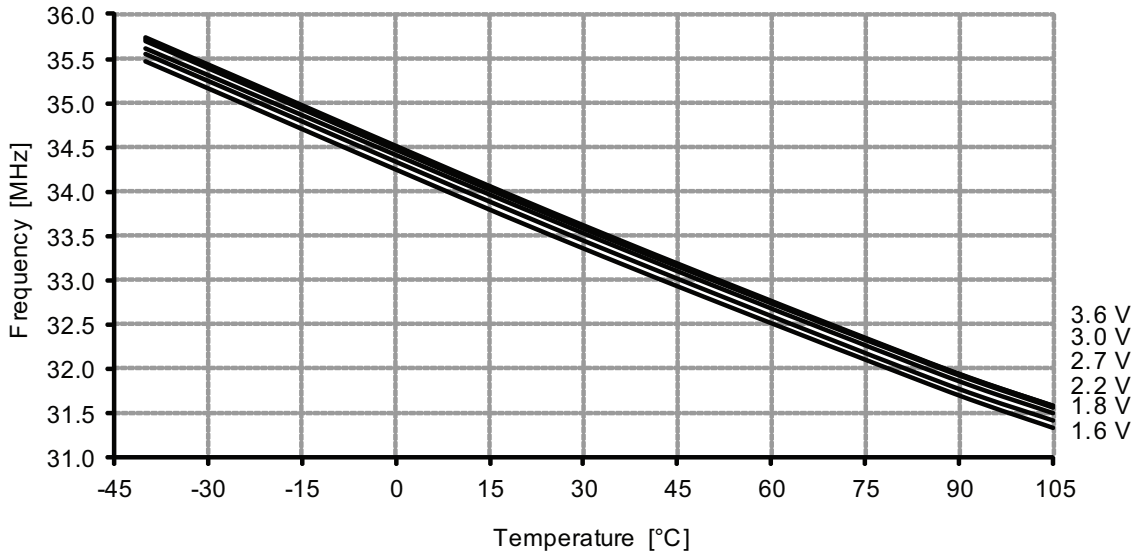
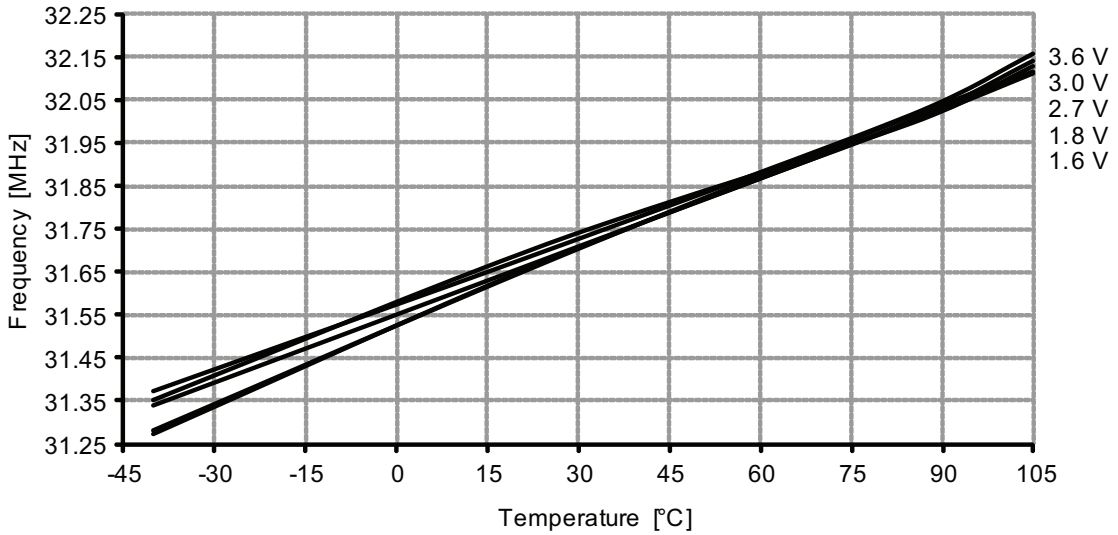


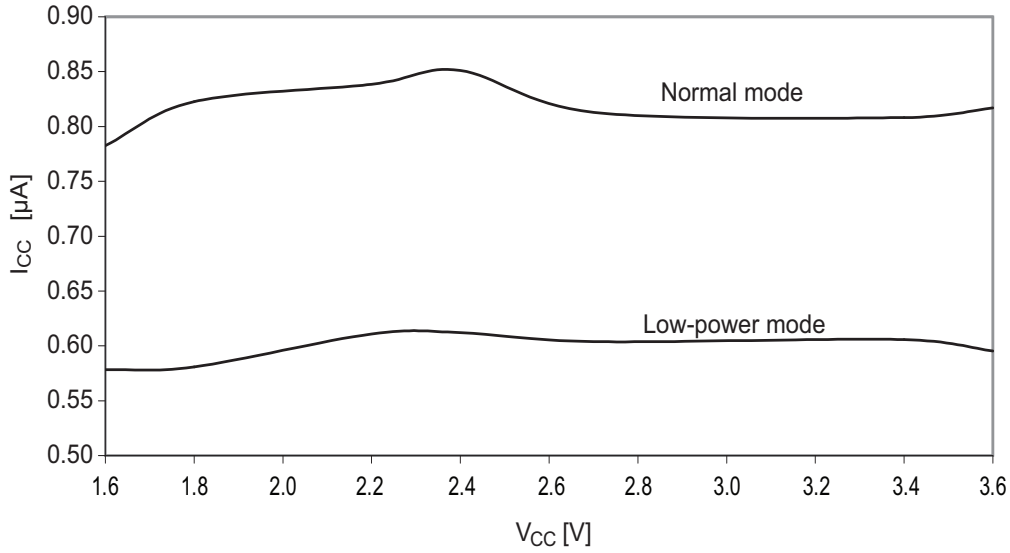
Figure 37-75. 32MHz internal oscillator frequency vs. temperature.
DFLL enabled, from the 32.768kHz internal oscillator.



37.2.1.4 Power-save mode supply current

Figure 37-100. Power-save mode supply current vs. V_{CC}.

Real Time Counter enabled and running from 1.024kHz output of 32.768kHz TOSC.



37.2.1.5 Standby mode supply current

Figure 37-101. Standby supply current vs. V_{CC}.

Standby, f_{SYS} = 1MHz.

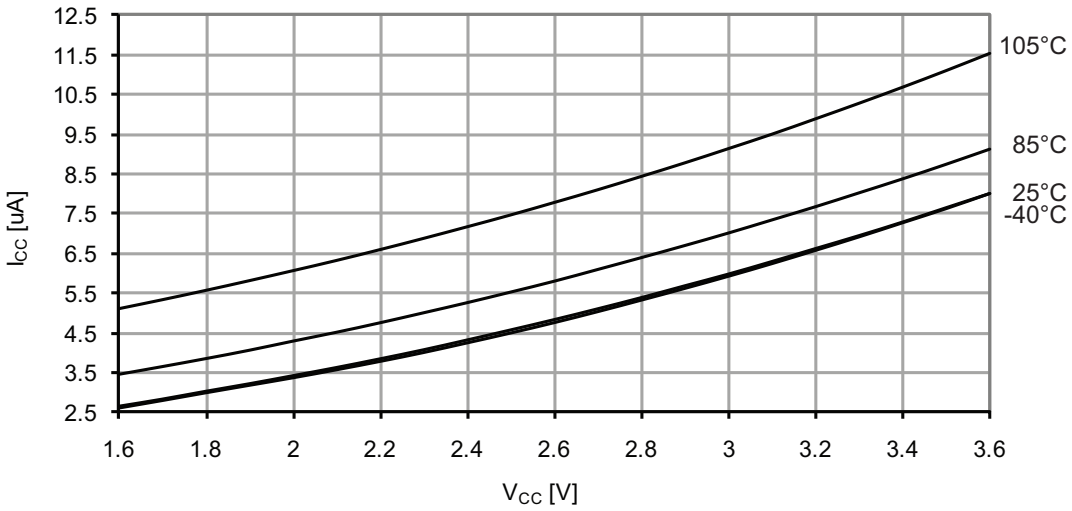


Figure 37-171. Active mode supply current vs. V_{CC}.

f_{SYS} = 2MHz internal oscillator.

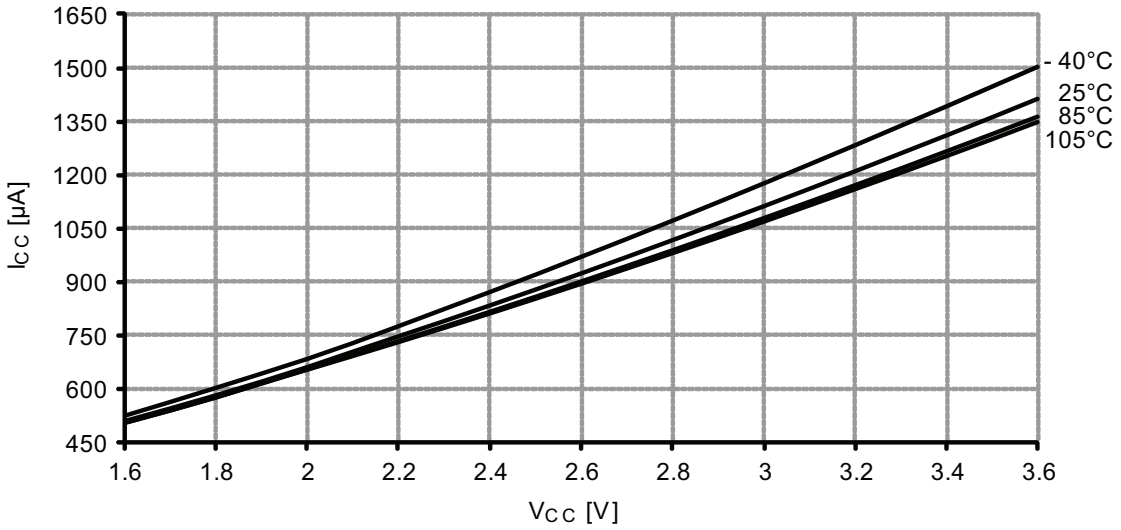
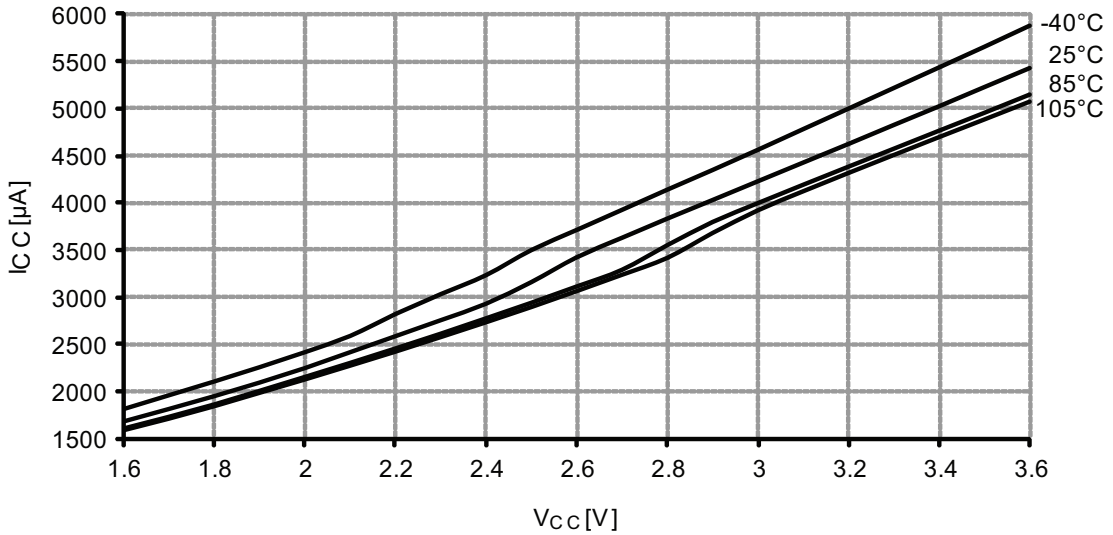


Figure 37-172. Active mode supply current vs. V_{CC}.

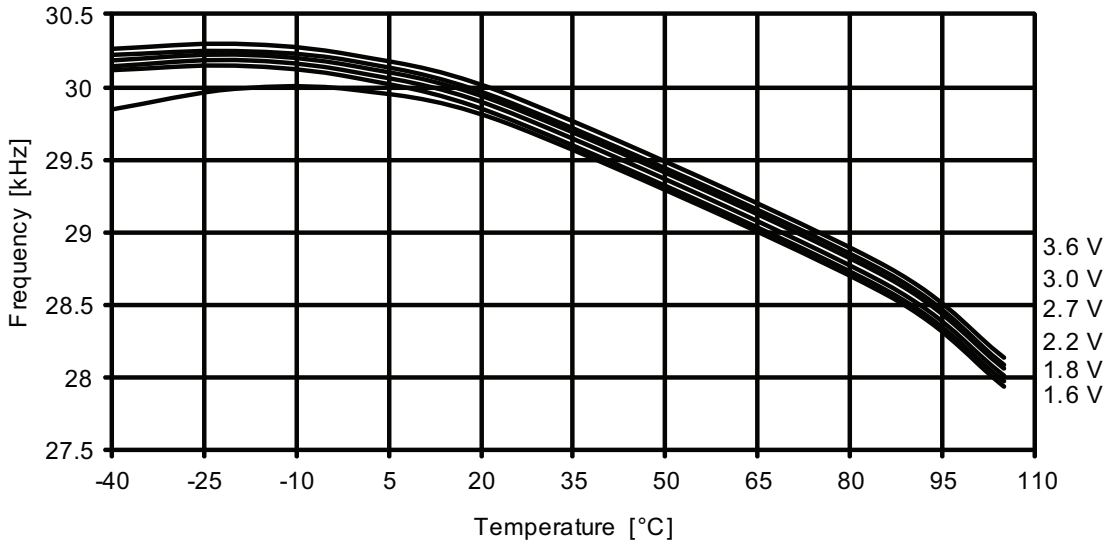
f_{SYS} = 32MHz internal oscillator prescaled to 8MHz.



37.3.10 Oscillator Characteristics

37.3.10.1 Ultra Low-Power internal oscillator

Figure 37-234. Ultra Low-Power internal oscillator frequency vs. temperature.



37.3.10.2 32.768kHz Internal Oscillator

Figure 37-235. 32.768kHz internal oscillator frequency vs. temperature.

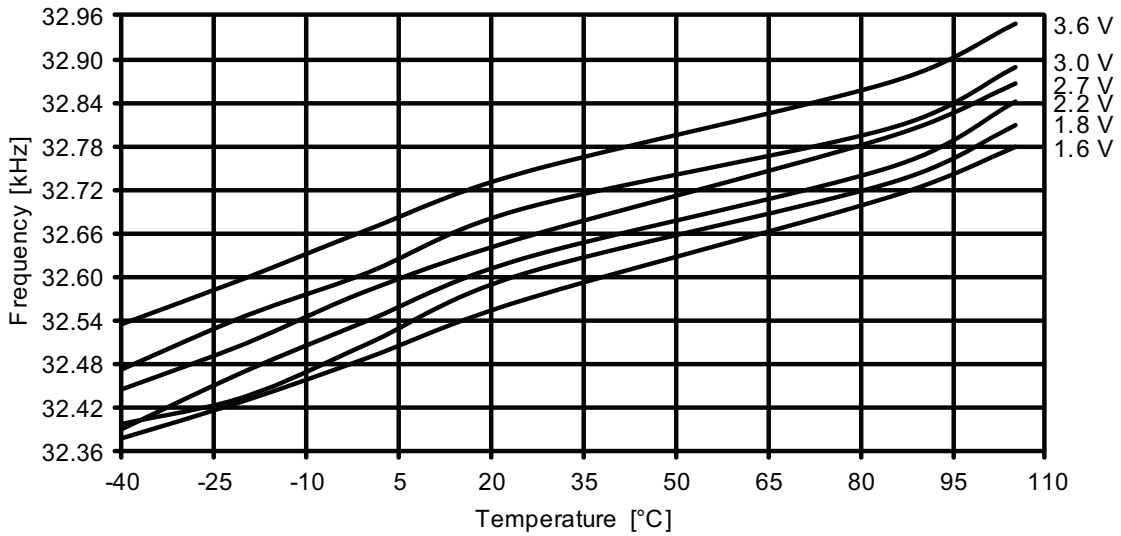


Figure 37-258. Idle mode supply current vs. frequency.

f_{SYS} = 1 - 32MHz external clock, T = 25°C.

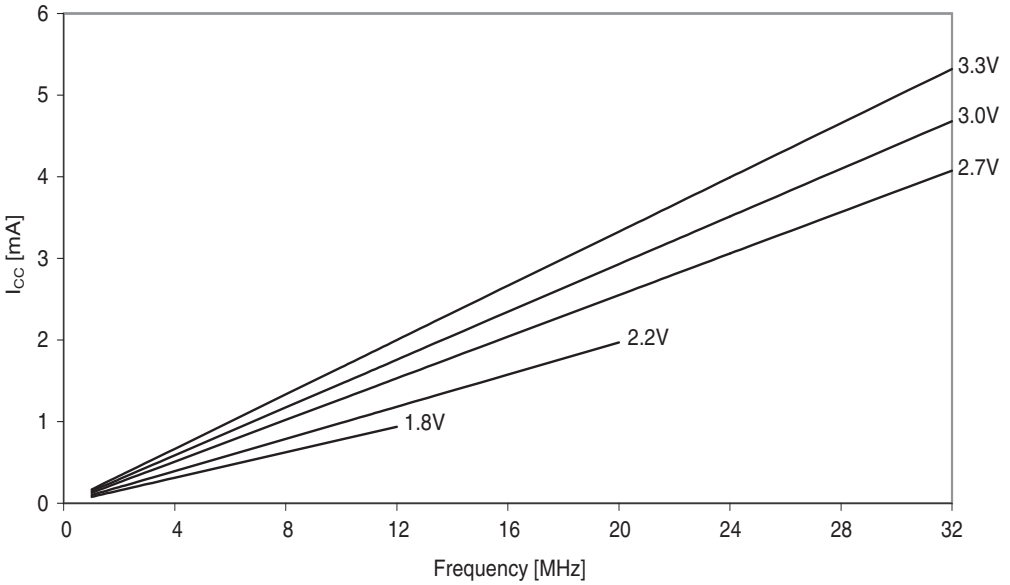


Figure 37-259. Idle mode supply current vs. V_{CC}.

f_{SYS} = 32.768kHz internal oscillator.

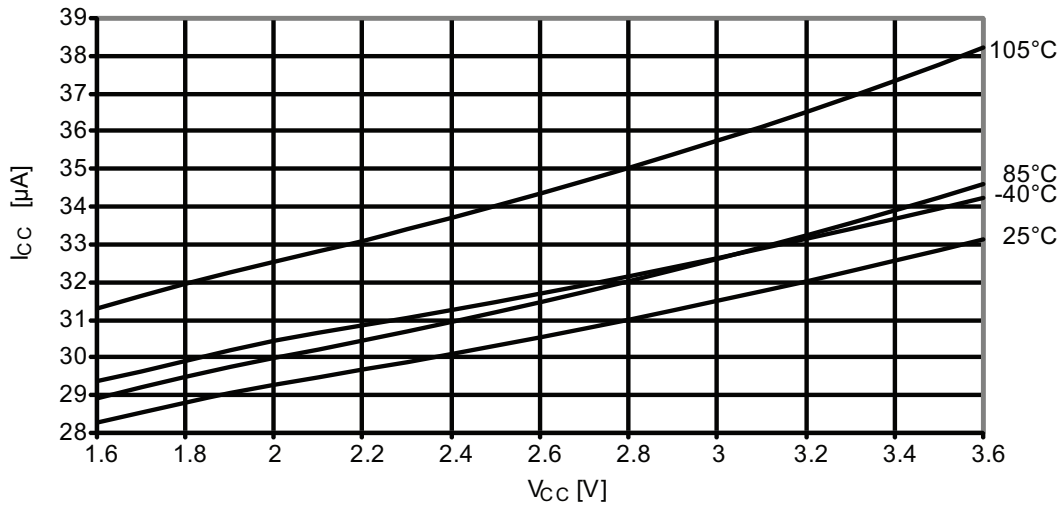


Figure 37-278. I/O pin output voltage vs. sink current.

V_{CC} = 3.3V.

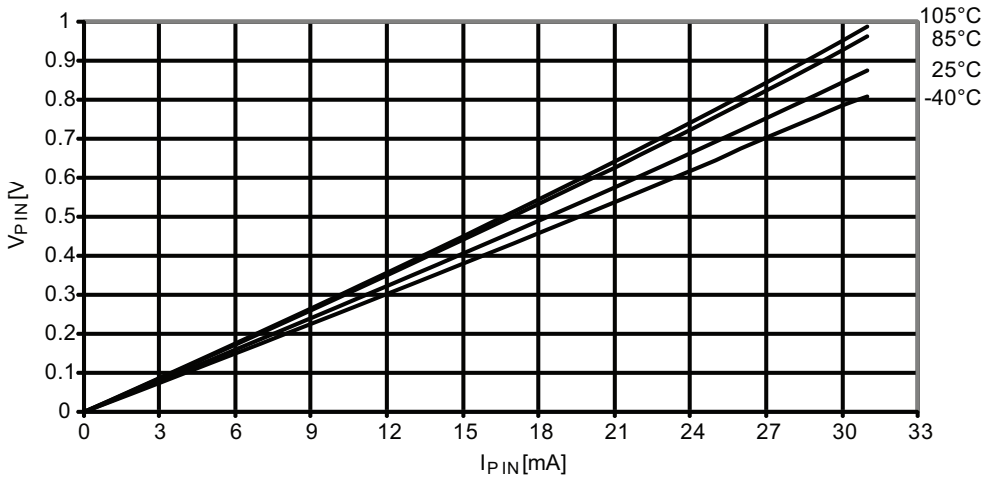
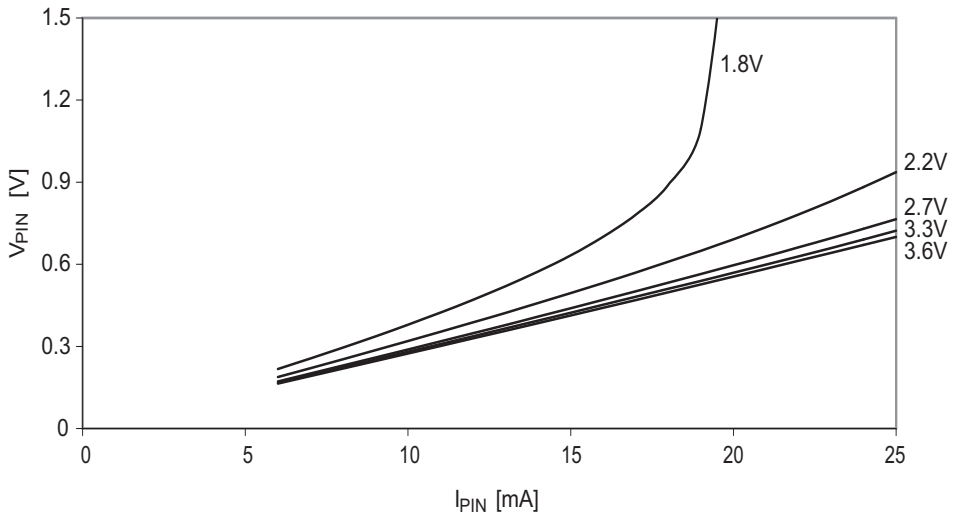


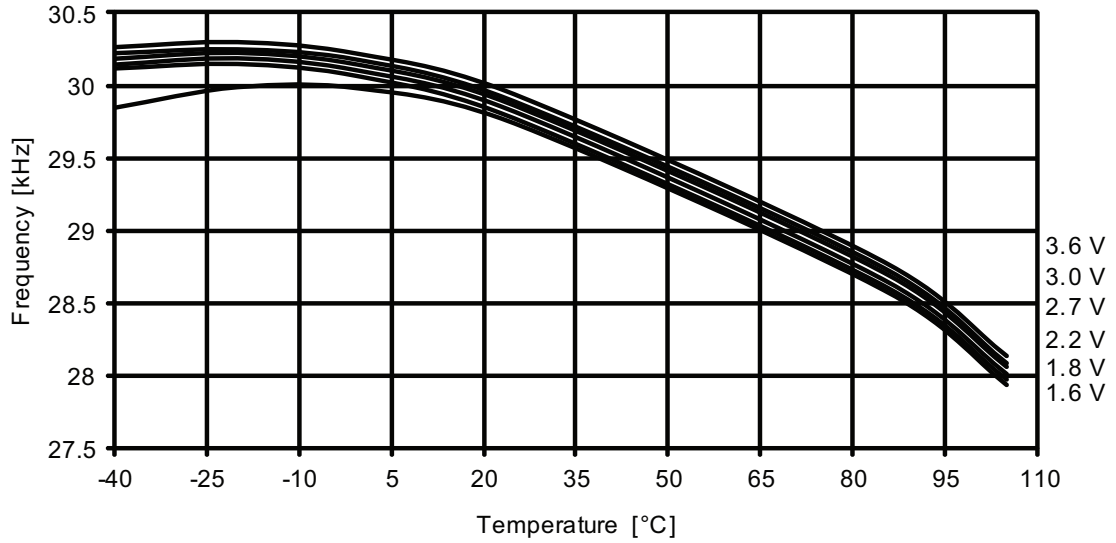
Figure 37-279. I/O pin output voltage vs. sink current.



37.4.10 Oscillator Characteristics

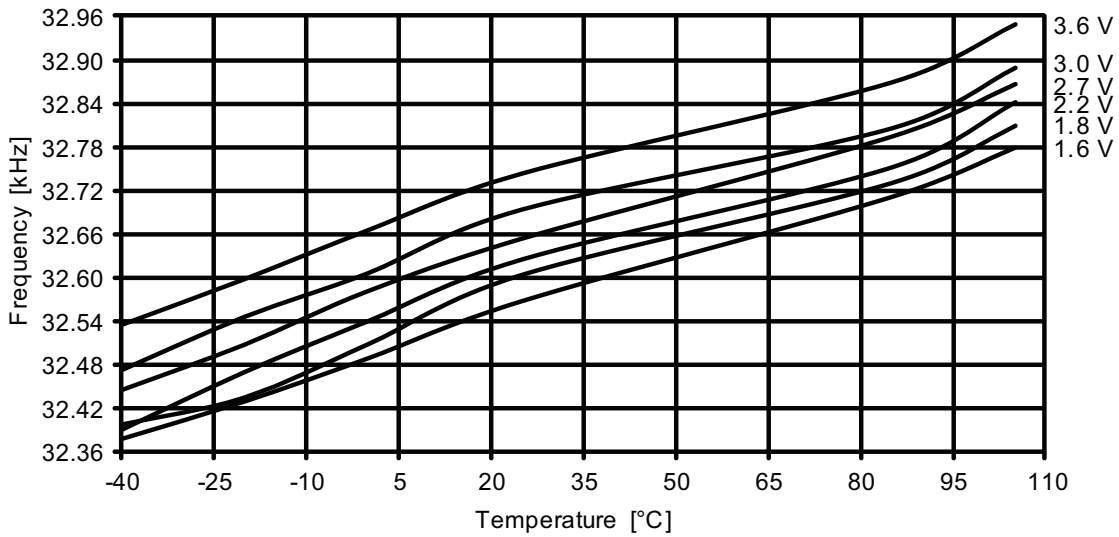
37.4.10.1 Ultra Low-Power internal oscillator

Figure 37-317. Ultra Low-Power internal oscillator frequency vs. temperature.



37.4.10.2 32.768kHz Internal Oscillator

Figure 37-318. 32.768kHz internal oscillator frequency vs. temperature.



38. Errata

38.1 ATxmega64A3U, ATxmega128A3U, ATxmega192A3U, ATxmega256A3U

38.1.1 Rev. G

- The DAC Channel 1 has not been calibrated in the Xmega devices released prior to April 2012.
- AWeX fault protection restore is not done correct in Pattern Generation Mode.

1. **AWeX fault protection restore is not done correct in Pattern Generation Mode**
   When a fault is detected the OUTOVEN register is cleared, and when fault condition is cleared, OUTOVEN is restored according to the corresponding enabled DTI channels. For Common Waveform Channel Mode (CWCM), this has no effect as the OUTOVEN is correct after restoring from fault. For Pattern Generation Mode (PGM), OUTOVEN should instead have been restored according to the DTLSBUF register.

   Problem fix/Workaround
   Problem fix/Workaround

   For CWCM no workaround is required.

   For PGM in latched mode, disable the DTI channels before returning from the fault condition. Then, set correct OUTOVEN value and enable the DTI channels, before the direction (DIR) register is written to enable the correct outputs again.

   For PGM in cycle-by-cycle mode there is no workaround.

38.1.2 Rev. A-F

Not sampled.