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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Not For New Designs
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	SIO, UART/USART
Peripherals	LED, POR, Voltage Detect, WDT
Number of I/O	22
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21134fp-w4

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R8C/13 Group SINGLE-CHIP 16-BIT CMOS MICROCOMPUTER

REJ03B0069-0120 Rev.1.20 Jan 27, 2006

1. Overview

This MCU is built using the high-performance silicon gate CMOS process using a R8C/Tiny Series CPU core and is packaged in a 32-pin plastic molded LQFP. This MCU operates using sophisticated instructions featuring a high level of instruction efficiency. With 1M bytes of address space, it is capable of executing instructions at high speed.

The data flash ROM (2 KB X 2 blocks) is embedded.

1.1 Applications

Electric household appliance, office equipment, housing equipment (sensor, security), general industrial equipment, audio, etc.

R8C/13 Group 1. Overview

1.2 Performance Overview

Table 1.1. lists the performance outline of this MCU.

Table 1.1 Performance outline

	Item	Performance
CPU	Number of basic instructions	89 instructions
	Minimum instruction execution time	50 ns (f(XIN) = 20 MHz, VCC = 3.0 to 5.5 V)
		100 ns (f(XIN) = 10 MHz, Vcc = 2.7 to 5.5 V)
	Operating mode	Single-chip
	Address space	1M bytes
	Memory capacity	See Table 1.2.
Peripheral	Port	Input/Output: 22 (including LED drive port), Input: 2
function	LED drive port	I/O port: 8
	Timer	Timer X: 8 bits x 1 channel, Timer Y: 8 bits x 1 channel,
		Timer Z: 8 bits x 1 channel
		(Each timer equipped with 8-bit prescaler)
		Timer C: 16 bits x 1 channel
		(Circuits of input capture and output compare)
	Serial interface	•1 channel
		Clock synchronous, UART
		•1 channel
		UART
	A/D converter	10-bit A/D converter: 1 circuit, 12 channels
	Watchdog timer	15 bits x 1 (with prescaler)
		Reset start function selectable
,	Interrupt	Internal: 11 factors, External: 5 factors,
	·	Software: 4 factors, Priority level: 7 levels
	Clock generation circuit	2 circuits
	_	•Main clock generation circuit (Equipped with a built-in
		feedback resistor)
		On-chip oscillator (high-speed, low-speed)
		On high-speed on-chip oscillator the frequency adjust-
		ment function is usable.
	Oscillation stop detection function	Main clock oscillation stop detection function
	Voltage detection circuit	Included
	Power on reset circuit	Included
Electrical	Supply voltage	VCC = 3.0 to 5.5V (f(XIN) = 20MHz)
characteristics		VCC = 2.7 to 5.5V (f(XIN) = 10MHz)
	Power consumption	Typ.9 mA ($VCC = 5.0V$, ($f(XIN) = 20MHz$)
		Typ.5 mA ($VCC = 3.0V$, ($f(XIN) = 10MHz$)
		Typ.35 μA (Vcc = 3.0V, Wait mode, Peripheral clock stops)
		Typ.0.7 μA (Vcc = 3.0V, Stop mode)
Flash memory	Program/erase supply voltage	VCC = 2.7 to 5.5 V
	Program/erase endurance	10,000 times (Data flash)
		1,000 times (Program ROM)
Operating amb	pient temperature	-20 to 85°C
		-40 to 85°C (D-version)
Package		32-pin plastic mold LQFP

R8C/13 Group 1. Overview

1.4 Product Information

Table 1.2 lists the product information.

Table 1.2 Product Information

As of January 2006						
ре	Remarks					
В-А	Flash memory version					
B-A						
B-A						

Type No.	ROM capacity		RAM capacity	Dookogo typo	Remarks
Type No.	Program ROM	Data flash	KAIVI Capacity	Package type	Remarks
R5F21132FP	8K bytes	2K bytes x 2	512 bytes	PLQP0032GB-A	Flash memory version
R5F21133FP	12K bytes	2K bytes x 2	768 bytes	PLQP0032GB-A	
R5F21134FP	16K bytes	2K bytes x 2	1K bytes	PLQP0032GB-A	
R5F21132DFP	8K bytes	2K bytes x 2	512 bytes	PLQP0032GB-A	D version
R5F21133DFP	12K bytes	2K bytes x 2	768 bytes	PLQP0032GB-A	
R5F21134DFP	16K bytes	2K bytes x 2	1K bytes	PLQP0032GB-A	

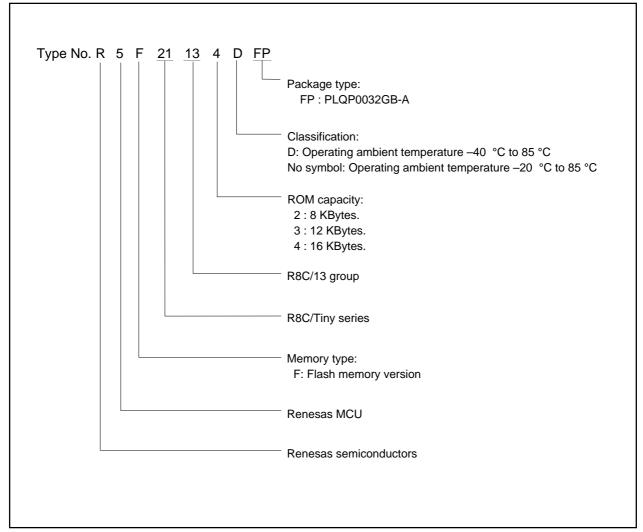


Figure 1.2 Type No., Memory Size, and Package

R8C/13 Group 1. Overview

1.5 Pin Assignments

Figure 1.3 shows the pin configuration (top view).

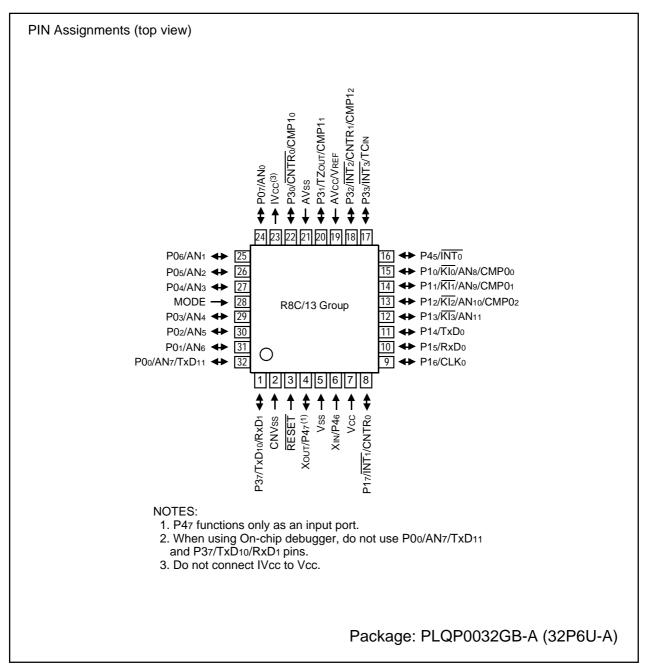


Figure 1.3 Pin Assignments (Top View)

R8C/13 Group 1. Overview

1.6 Pin Description

Table 1.3 shows the pin description

Table 1.3 Pin description

Signal name	Pin name	I/O type	Function
Power supply	Vcc,	I	Apply 2.7 V to 5.5 V to the Vcc pin. Apply 0 V to the
input	Vss		Vss pin.
IVcc	IVcc	0	This pin is to stabilize internal power supply.
			Connect this pin to Vss via a capacitor (0.1 µF).
			Do not connect to Vcc.
Analog power	AVcc, AVss	I	Power supply input pins for A/D converter. Connect the
supply input			AVcc pin to Vcc. Connect the AVss pin to Vss. Connect a
			capacitor between pins AVcc and AVss.
Reset input	RESET	I	Input "L" on this pin resets the MCU.
CNVss	CNVss	I	Connect this pin to Vss via a resistor.
MODE	MODE	I	Connect this pin to Vcc via a resistor.
Main clock input	XIN	I	These pins are provided for the main clock generat-
·			ing circuit I/O. Connect a ceramic resonator or a crys-
Main clock output	Xout	0	tal oscillator between the XIN and XOUT pins. To use
·			an externally derived clock, input it to the XIN pin and
			leave the XOUT pin open.
INT interrupt input	INTo to INT3	I	INT interrupt input pins.
Key input interrupt		I	Key input interrupt pins.
input			
Timer X	CNTR ₀	I/O	Timer X I/O pin
	CNTR ₀	0	Timer X output pin
Timer Y	CNTR ₁	I/O	Timer Y I/O pin
Timer Z	TZout	0	Timer Z output pin
Timer C	TCIN	I	Timer C input pin
	CMP00 to CMP02,	0	The timer C output pins
	CMP10 to CMP12		
Serial interface	CLK ₀	I/O	Transfer clock I/O pin.
	RxD0, RxD1	I	Serial data input pins.
	TxD0, TxD10,	0	Serial data output pins.
	TxD11		
Reference voltage	VREF	I	Reference voltage input pin for A/D converter. Con-
input			nect the VREF pin to Vcc.
A/D converter	ANo to AN11	I	Analog input pins for A/D converter
I/O port	P00 to P07,	I/O	These are 8-bit CMOS I/O ports. Each port has an I/O
	P10 to P17,		select direction register, allowing each pin in that port
	P30 to P33, P37,		to be directed for input or output individually.
	P45		Any port set to input can select whether to use a pull-
			up resistor or not by program.
			P10 to P17 also function as LED drive ports.
			· ·
Input port	P46, P47	I	Port for input-only

Table 4.4 SFR Information(4)⁽¹⁾

Address	Register	Symbol	After reset
00C016	AD register	AD	XX16
00C116			XX16
00C216			
00C316 00C416			
00C416			
00C616			
00C716			
00C816			
00C916			
00CA16			
00CB16			
00CC16			
00CD16 00CE16			
00CE16			
00D016			
00D116			
00D216			
00D316			
00D416	AD control register 2	ADCON2	0016
00D516		4000:::	000000////
00D616	AD control register 0	ADCON0	00000XXX2
00D716	AD control register 1	ADCON1	0016
00D816 00D916			
00D916 00DA16			
00DA16			
00DC16			
00DD16			
00DE16			
00DF16			
00E016	Port P0 register	P0	XX16
00E116	Port P1 register	P1	XX16
00E216	Port P0 direction register	PD0	0016
00E316 00E416	Port P1 direction register	PD1	0016
00E416	Port P3 register	P3	XX16
00E616	1 or 1 o register	13	XXIII
00E716	Port P3 direction register	PD3	0016
00E816	Port P4 register	P4	XX16
00E916	-		
00EA16	Port P4 direction register	PD4	0016
00EB16			
00EC16			
00ED16			
00EE16			
00F016			
00F116			
00F216			
00F316			
00F416			
00F516			
00F616			
00F716			
00F816			
00F916			
03FA ₁₆ 00FB ₁₆			
00FB16 00FC16	Pull-up control register 0	PUR0	00XX00002
00FC16	Pull-up control register 1	PUR1	XXXXXX0X2
00FE16	Port P1 drive capacity control register	DRR	0016
00FF16	Timer C output control register	TCOUT	0016
	·	•	<u> </u>
₹			
01B316	Flash memory control register 4	FMR4	010000002
01B416		EMB (40000001/
01B516	Flash memory control register 1	FMR1	1000000X2
01B616	Floob moment control register 0	EMBO	000000040
01B716	Flash memory control register 0	FMR0	00000012
0FFFF16	Option function select register ⁽²⁾	OFS	(Note 2)
0111116	- Spring Control College Logistics	5.5	(50 2)

X: Undefined NOTES:

1. Blank columns, 010016 to 01B216 and 01B816 to 02FF16 are all reserved. No access is allowed.

2. The watchdog timer control bit is assigned. Refer to "Figure11.2 OFS, WDC, WDTR and WDTS registers" of Hardware Manual for details

5. Electrical Characteristics

Table 5.1 Absolute Maximum Ratings

Symbol	Parameter	Condition	Rated value	Unit
Vcc	Supply voltage	Vcc=AVcc	-0.3 to 6.5	V
AVcc	Analog supply voltage	Vcc=AVcc	-0.3 to 6.5	V
Vı	Input voltage		-0.3 to Vcc+0.3	V
Vo	Output voltage		-0.3 to Vcc+0.3	V
Pd	Power dissipation	Topr=25 °C	300	mW
Topr	Operating ambient temperature		-20 to 85 / -40 to 85 (D version)	°C
Tstg	Storage temperature		-65 to 150	°C

Table 5.2 Recommended Operating Conditions

Constant	Parameter		Conditions		Standard			
Symbol	Parame	ter	Conditions	Min.	Тур.	Max.	Unit	
Vcc	Supply voltage			2.7		5.5	V	
AVcc	Analog supply v	oltage			Vcc(3)		V	
Vss	Supply voltage				0		V	
AVss	Analog supply v	oltage			0		V	
VIH	"H" input voltage	е		0.8Vcc		Vcc	V	
VIL	"L" input voltage	е		0		0.2Vcc	V	
I _{OH (sum)}	"H" peak all output currents	Sum of all pins' IOH (peak)			_	-60.0	mA	
I _{OH} (peak)	"H" peak output current					-10.0	mA	
I _{OH (avg)}	"H" average out	put current				-5.0	mA	
I _{OL (sum)}	"L" peak all output currents	Sum of all pins' IOL (peak)				60	mA	
I _{OL (peak)}	"L" peak output	Except P10 to P17				10	mA	
. ,	current	P10 to P17	Drive ability HIGH			30	mA	
			Drive ability LOW			10	mA	
I _{OL (avg)}	"L" average	Except P10 to P17				5	mA	
·OL (avg)	output current	P10 to P17	Drive ability HIGH			15	mA	
			Drive ability LOW			5	mA	
f (XIN)	Main clock inpu	t oscillation frequency	3.0V ≤ Vcc ≤ 5.5V	0		20	MHz	
	<u> </u>		2.7V ≤ Vcc < 3.0V	0		10	MHz	

^{1.} Vcc = AVcc = 2.7 to 5.5V at Topr = -20 to 85 °C / -40 to 85 °C, unless otherwise specified.
2. The typical values when average output current is 100ms.
3. Hold Vcc=AVcc.

Table 5.5 Flash Memory (Data flash Block A, Block B) Electrical Characteristics⁽⁴⁾

Symbol	Parameter	Measuring condition	S				
Cymbol	Parameter	Measuring condition	Min.	Тур.	Max	Unit	
_	Program/Erase endurance ⁽²⁾		10000(3)	_	_	times	
-	Byte program time(program/erase endurance ≤1000 times)		_	50	400	μs	
-	Byte program time(program/erase endurance >1000 times)		_	65		μs	
-	Block erase time(program/erase endurance ≤1000 times)		_	0.2	9	S	
-	Block erase time(program/erase endurance >1000 times)		_	0.3		s	
td(SR-ES)	Time delay from Suspend Request until E	rase Suspend	_		8	ms	
-	Erase Suspend Request Interval		10	_		ms	
_	Program, Erase Voltage		2.7	_	5.5	V	
-	Read Voltage		2.7	_	5.5	V	
_	Program/Erase Temperature		-20(-40)(8)		85	°C	
-	Data hold time ⁽⁹⁾	Ambient temperature = 55 °C	20	_		year	

- 1. Referenced to Vcc=AVcc=2.7 to 5.5V at Topr = -20°C to 85°C / -40°C to 85°C unless otherwise specified.
- 2. Definition of Program/Erase
 - The endurance of Program/Erase shows a time for each block.
 - If the program/erase number is "n" (n = 1000, 10000), "n" times erase can be performed for each block.
 - For example, if performing one-byte write to the distinct addresses on Block A of 2K-byte block 2048 times and then erasing that block, the number of Program/Erase cycles is one time.
 - However, performing multiple writes to the same address before an erase operation is prohibited (overwriting prohibited).
- 3. Numbers of Program/Erase cycles for which all electrical characteristics is guaranteed.
- 4. Table 5.5 applies for Block A or B when the Program/Erase cycles are more than 1000. The byte program time up to 1000 cycles are the same as that of the program area (see Table 5.4).
- 5. To reduce the number of Program/Erase cycles, a block erase should ideally be performed after writing in series as many distinct addresses (only one time each) as possible. If programming a set of 16 bytes, write up to 128 sets and then erase them one time. This will result in ideally reducing the number of Program/Erase cycles. Additionally, averaging the number of Program/Erase cycles for Block A and B will be more effective. It is important to track the total number of block erases and restrict the number.
- 6. If error occurs during block erase, attempt to execute the clear status register command, then the block erase command at least three times until the erase error disappears.
- Customers desiring Program/Erase failure rate information should contact their Renesas technical support representative.
- 8. -40 °C for D version.
- 9. The data hold time includes time that the power supply is off or the clock is not supplied.

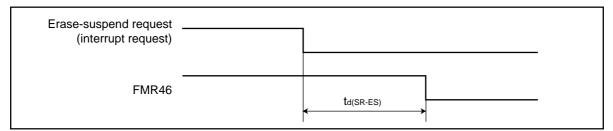


Figure 5.2 Time delay from Suspend Request until Erase Suspend

Table 5.6 Voltage Detection Circuit Electrical Characteristics

Symbol	Parameter	Measuring condition				
Cyllibol	i didiffetei	Wedsuring condition	Min.	Тур.	Max.	Unit
Vdet	Voltage detection level		3.3	3.8	4.3	V
	Voltage detection interrupt request generating time ⁽²⁾			40		μs
	Voltage detection circuit self consumption current	VC27=1, VCC=5.0V		600		nA
td(E-A)	Waiting time until voltage detection circuit operation starts(3)				20	μs
Vccmin	Microcomputer operation voltage minimum value		2.7			V

NOTES:

- 1. The measuring condition is Vcc=AVcc=2.7V to 5.5V and Topr=-40°C to 85°C.
- 2. This shows the time until the voltage detection interrupt request is generated since the voltage passes Vdet.
- 3. This shows the required time until the voltage detection circuit operates when setting to "1" again after setting the VC27 bit in the VCR2 register to "0".

Table 5.7 Reset Circuit Electrical Characteristics (When Using Hardware Reset 2^(1, 3))

Symbol	Parameter	Measuring condition	Standard			Llmit
Cymbol	ramotor	Wiededinig dentalien	Min.	Тур.	Max.	Unit
Vpor2	Power-on reset valid voltage	-20°C ≤ Topr < 85°C	_	_	Vdet	V
tw(Vpor2- Vdet)	Supply voltage rising time when power-on reset is canceled ⁽²⁾	-20 °C \leq Topr $<$ 85°C, tw(por2) \geq 0s ⁽⁴⁾	_		100	ms

NOTES:

- 1. The voltage detection circuit which is embedded in a microcomputer is a factor to generate the hardware reset 2. Refer to 5.1.2 Hardware Reset 2 of Hardware Manual for details.
- 2. This condition is not applicable when using Vcc ≥ 1.0V.
- 3. When turning power on after the external power has been held below the valid voltage (Vpor1) for greater than 10 seconds, refer to Table 5.8 Reset Circuit Electrical Characteristics (When Not Using Hardware Reset 2).
- 4. tw(por2) is time to hold the external power below effective voltage (Vpor2).

Table 5.8 Reset Circuit Electrical Characteristics (When Not Using Hardware Reset 2)

Symbol	Parameter	Measuring condition		Unit		
Cymbol	ramotor	Wisdodining Schlamon	Min.	Тур.	Max.	Unit
Vpor1	Power-on reset valid voltage	–20°C ≤ Topr < 85°C		_	0.1	V
tW(Vpor1- Vdet)	Supply voltage rising time when power-on reset is canceled	$0^{\circ}C \le Topr \le 85^{\circ}C$, tw(por1) $\ge 10s^{(2)}$	1	_	100	ms
tW(Vpor1- Vdet)	Supply voltage rising time when power-on reset is canceled	$-20^{\circ}\text{C} \le \text{Topr} < 0^{\circ}\text{C}, \text{ tw(por1)} \ge 30\text{s}^{(2)}$	-	_	100	ms
tW(Vpor1- Vdet)	Supply voltage rising time when power-on reset is canceled	$-20^{\circ}\text{C} \le \text{Topr} < 0^{\circ}\text{C}, \text{ tw(por1)} \ge 10\text{s}^{(2)}$	1	_	1	ms
tW(Vpor1- Vdet)	Supply voltage rising time when power-on reset is canceled	$0^{\circ}C \le Topr \le 85^{\circ}C$, $tw(por1) \ge 1s^{(2)}$	1	_	0.5	ms

- 1. When not using hardware reset 2, use with $Vcc \ge 2.7V$.
- 2. tw(por1) is time to hold the external power below effective voltage (Vpor1).

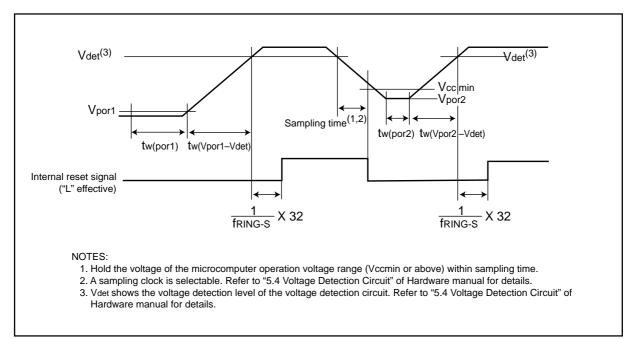


Figure 5.3 Reset Circuit Electrical Characteristics

Table 5.9 High-speed On-Chip Oscillator Circuit Electrical Characteristics

Symbol	Parameter	Measuring condition	Standard			Unit
Cymbol	randicio	Modedling condition	Min.	Тур.	Max.	Unit
_	High-speed on-chip oscillator frequency 1 / {td(HRoffset)+td(HR)} when the reset is released	VCC=5.0V, Topr=25 °C Set "4016" in the HR1 register	_	8	=	MHz
td(HRoffset)	Settable high-speed on-chip oscillator minimum period	VCC=5.0V, Topr=25 °C Set "0016" in the HR1 register		61	_	ns
td(HR)	High-speed on-chip oscillator period adjusted unit	Differences when setting "0116" and "0016" in the HR register	-	1	_	ns
_	High-speed on-chip oscillator frequency temperature dependence(1)	Frequency fluctuation in temperature range of -10 °C to 50 °C	_	±5	_	%
_	High-speed on-chip oscillator frequency temperature dependence(2)	Frequency fluctuation in temperature range of -40 °C to 85 °C	_	±10	_	%

NOTES:

Table 5.10 Power Circuit Timing Characteristics

Symbol Parameter		Measuring condition	Standard			
Cymbol	i didiffetei	Wicasaring condition	Min.	Тур.	Max.	Unit
td(P-R)	Time for internal power supply stabilization during powering-on(2)		1		2000	μs
td(R-S)	STOP release time ⁽ 3)				150	μs

NOTES:

- 1. The measuring condition is Vcc=AVcc=2.7 to 5.5 V and Topr=25 °C.
- 2. This shows the wait time until the internal power supply generating circuit is stabilized during power-on.
- 3. This shows the time until BCLK starts from the interrupt acknowledgement to cancel stop mode.

Table 5.11 Electrical Characteristics (1) [Vcc=5V]

Symbol	D.	arameter	Measuring	condition		Standard	Í	Unit
Symbol	F	arameter	Wicasainig	goonanion	Min.	Тур.	Max.	Unit
	"H" output voltage	Except Xouт	IOH=-5mA		Vcc-2.0	_	Vcc	V
Vон			Іон=-200μА		Vcc-0.3	_	Vcc	V
		Хоит	Drive capacity HIGH	IOH=-1 mA	Vcc-2.0	_	Vcc	V
			Drive capacity LOW	Іон=-500μА	Vcc-2.0	_	Vcc	V
	"L" output voltage	Except P10 to P17, Xout	IoL= 5 mA		_	_	2.0	V
Vol			IoL= 200 μA		_	_	0.45	V
		P10 to P17	Drive capacity HIGH	IoL= 15 mA	_	_	2.0	V
			Drive capacity LOW	IoL= 5 mA	_	-	2.0	V
			Drive capacity LOW	IoL= 200 μA	_	_	0.45	V
		Хоит	Drive capacity HIGH	IoL= 1 mA	_	_	2.0	V
			Drive capacity LOW	IoL=500 μA	_	_	2.0	V
VT+-VT-	Hysteresis	INT0, INT1, INT2, INT3, KI0, KI1, KI2, KI3, CNTR0, CNTR1, TCIN, RxD0, RxD1, P45			0.2	_	1.0	V
		RESET			0.2	_	2.2	٧
liн	"H" input current		Vi=5V		_	_	5.0	μA
lıL	"L" input current		VI=0V		_	_	-5.0	μA
RPULLUP	Pull-up resistance		VI=0V		30	50	167	kΩ
RfXIN	Feedback resistance	XIN			_	1.0	_	Ω M
fring-s	Low-speed on-chip oscillator frequ	ency			40	125	250	kHz
VRAM	RAM retention voltage		At stop mode		2.0	_	_	V

^{1.} The measuring condition is Vcc=AVcc=5.0 V and Topr=25 °C.

^{1.} Referenced to Vcc = AVcc = 4.2 to 5.5V at Topr = -20 to 85 °C / -40 to 85 °C, f(XIN)=20MHz unless otherwise specified.

Timing requirements [Vcc=5V] (Unless otherwise noted: Vcc = 5V, Vss = 0V at Topr = 25 °C)

Table 5.13 XIN input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tc(XIN)	XIN input cycle time	50	_	ns
twh(XIN)	XIN input HIGH pulse width	25	_	ns
twL(XIN)	XIN input LOW pulse width	25	_	ns

Table 5.14 CNTR0 input, CNTR1 input, INT2 input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tC(CNTR0)	CNTR0 input cycle time	100	-	ns
tWH(CNTR0)	CNTR0 input HIGH pulse width	40	_	ns
tWL(CNTR0)	CNTR0 input LOW pulse width	40	_	ns

Table 5.15 TCIN input, INT3 input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tc(TCIN)	TCIN input cycle time	400 ⁽¹⁾	_	ns
tWH(TCIN)	TCIN input HIGH pulse width	200 ⁽²⁾	_	ns
tWL(TCIN)	TCIN input LOW pulse width	200 ⁽²⁾	_	ns

NOTES:

- 1. When using the Timer C input capture mode, adjust the cycle time above (1/ Timer C count source frequency x 3).
- 2. When using the Timer C input capture mode, adjust the pulse width above (1/Timer C count source frequency x 1.5).

Table 5.5 Serial Interface

Symbol	Parameter	Star	ndard	Unit
		Min.	Max.	
tc(ck)	CLKi input cycle time	200	_	ns
tw(ckH)	CLKi input HIGH pulse width	100	_	ns
tw(ckl)	CLKi input LOW pulse width	100	_	ns
td(C-Q)	TxDi output delay time	_	80	ns
th(C-Q)	TxDi hold time	0	_	ns
tsu(D-C)	RxDi input setup time	35	_	ns
th(C-D)	RxDi input hold time	90	_	ns

Table 5.17 External interrupt INTO input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tw(INH)	INTO input HIGH pulse width	250 ⁽¹⁾	_	ns
tw(INL)	INTO input LOW pulse width	250 ⁽²⁾	_	ns

- 1. When selecting the digital filter by the $\overline{\text{INT0}}$ input filter select bit, use the $\overline{\text{INT0}}$ input HIGH pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.
- 2. When selecting the digital filter by the $\overline{\text{INT0}}$ input filter select bit, use the $\overline{\text{INT0}}$ input LOW pusle width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.

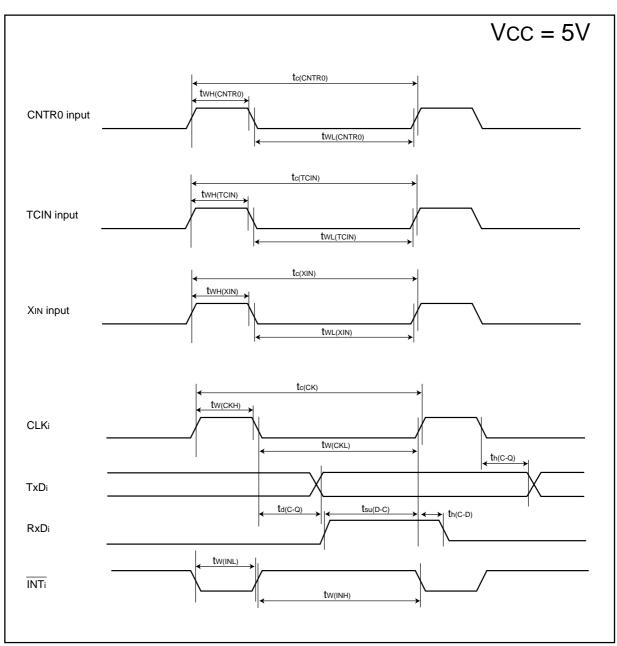


Figure 5.4 Vcc=5V timing diagram

Table 5.18 Electrical Characteristics (3) [Vcc=3V]

Symbol		Parameter		r condition		Standard		
Syllibol				Measuring condition		Тур.	Max.	Unit
	"H" output voltage	Except Xout	IOH=-1mA		Vcc-0.5	_	Vcc	V
Vон		Хоит	Drive capacity HIGH	Iон=-0.1 mA	Vcc-0.5	_	Vcc	V
			Drive capacity LOW	Іон=-50 μА	Vcc-0.5	_	Vcc	V
	"L" output voltage	Except P10 to P17, XouT	IoL= 1 mA		_	_	0.5	V
Vol		P10 to P17	Drive capacity HIGH	IoL= 2 mA		_	0.5	V
			Drive capacity LOW	IoL= 1 mA		_	0.5	V
		Хоит	Drive capacity HIGH	IoL= 0.1 mA	_	-	0.5	V
			Drive capacity LOW	IoL=50 μA	_	_	0.5	V
VT+-VT-	Hysteresis	into, into, into, into, kio, kio, kio, kio, cntro, cntro, tcin, rxdo, rxdo, p45			0.2	_	0.8	V
		RESET			0.2	_	1.8	٧
liн	"H" input current		VI=3V			_	4.0	μA
lıL	"L" input current		Vi=0V		_	_	-4.0	μΑ
RPULLUP	Pull-up resistance		Vi=0V		66	160	500	kΩ
RfXIN	Feedback resistance	XIN			_	3.0	_	МΩ
fring-s	Low-speed on-chip oscillator for	requency			40	125	250	kHz
VRAM	RAM retention voltage		At stop mode		2.0	_	_	V



NOTES:

1. Referenced to Vcc = AVcc = 2.7 to 3.3V at Topr = -20 to 85 °C / -40 to 85 °C, f(XIN)=10MHz unless otherwise specified.

5. Electrical Characteristics

Table 5.19 Electrical Characteristics (4) [Vcc=3V]

Symbol	Para	meter	Mea	asuring condition		Standard		Unit
Cymbol	i dic		11101	acuming containen	Min.	Тур.	Max.	Unit
			High-speed mode	Xm=20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division	_	8	13	mA
				XIN=16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division	_	7	12	mA
				X _{IN} =10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division		5		mA
			Medium-speed mode	XIN=20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8		3	_	mA
Icc	Power supply current			X _{IN} =16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	_	2.5	_	mA
	(Vcc=2.7 to 3.3V) In single-chip mode, the output pins are open and other pins are Vss			X _{IN} =10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	_	1.6	_	mA
	are vos		High-speed on-chip oscillator mode	Main clock off High-speed on-chip oscillator on=8 MHz Low-speed on-chip oscillator on=125 kHz No division	_	3.5	7.5	mA
				Main clock off High-speed on-chip oscillator on=8 MHz Low-speed on-chip oscillator on=125 kHz Division by 8	_	1.5	_	mA
			Low-speed on-chip oscillator mode	Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8		420	800	μА
			Wait mode	Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz When a WAIT instruction is executed ⁽¹⁾ Peripheral clock operation VC27='0'		37	74	μА
			Wait mode	Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz When a WAIT instruction is executed ⁽¹⁾ Peripheral clock off VC27=0''	_	35	70	μА
			Stop mode	Main clock off, Topr=-25 °C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10="1" Peripheral clock off VC27="0"	_	0.7	3.0	μА



NOTES:
1. Timer Y is operated with timer mode.
2. Referenced to Vcc = AVcc = 2.7 to 3.3V at Topr = -20 to 85 °C / -40 to 85 °C, f(XIN)=10MHz unless otherwise specified.

Timing requirements [Vcc=3V] (Unless otherwise noted: Vcc = 3V, Vss = 0V at Topr = 25 °C)

Table 5.20 XIN input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tc(XIN)	XIN input cycle time	100	_	ns
twh(XIN)	XIN input HIGH pulse width	40	_	ns
twL(XIN)	XIN input LOW pulse width	40	_	ns

Table 5.21 CNTR0 input, CNTR1 input, INT2 input

Symbol	Parameter	Stan	dard	Unit
		Min.	Max.	
tC(CNTR0)	CNTR0 input cycle time	300	_	ns
tWH(CNTR0)	CNTR0 input HIGH pulse width	120	_	ns
tWL(CNTR0)	CNTR0 input LOW pulse width	120	_	ns

Table 5.22 TCIN input, INT3 input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
tC(TCIN)	TCIN input cycle time	1200 ⁽¹⁾	ı	ns
twh(TCIN)	TCIN input HIGH pulse width	600 ⁽²⁾	-	ns
twL(TCIN)	TCIN input LOW pulse width	600 ⁽²⁾	ı	ns

NOTES:

- 1. When using the Timer C input capture mode, adjust the cycle time above (1/ Timer C count source frequency x 3).
- 2. When using the Timer C input capture mode, adjust the pulse width above (1/ Timer C count source frequency x 1.5).

Table 5.23 Serial Interface

Symbol	Parameter Standard		ndard	Unit
		Min.	Max.	
tc(ck)	CLKi input cycle time		_	ns
tw(ckH)	CLKi input HIGH pulse width	150	_	ns
tW(CKL)	CLKi input LOW pulse width		_	ns
td(C-Q)	TxDi output delay time	_	160	ns
th(C-Q)	TxDi hold time	0	_	ns
tsu(D-C)	RxDi input setup time	55	_	ns
th(C-D)	RxDi input hold time	90	_	ns

Table 5.24 External interrupt INTO input

Symbol	Parameter		Standard	
		Min.	Max.	
tw(INH)	INTO input HIGH pulse width	380 ⁽¹⁾	ı	ns
tW(INL)	INTO input LOW pulse width	380 ⁽²⁾	1	ns

- 1. When selecting the digital filter by the $\overline{\text{INT0}}$ input filter select bit, use the $\overline{\text{INT0}}$ input HIGH pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.
- 2. When selecting the digital filter by the $\overline{\text{INT0}}$ input filter select bit, use the $\overline{\text{INT0}}$ input LOW pusle width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.

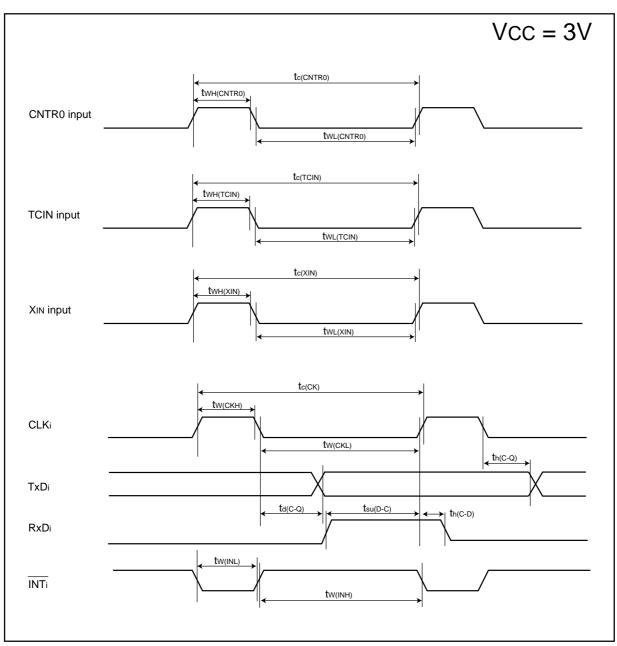
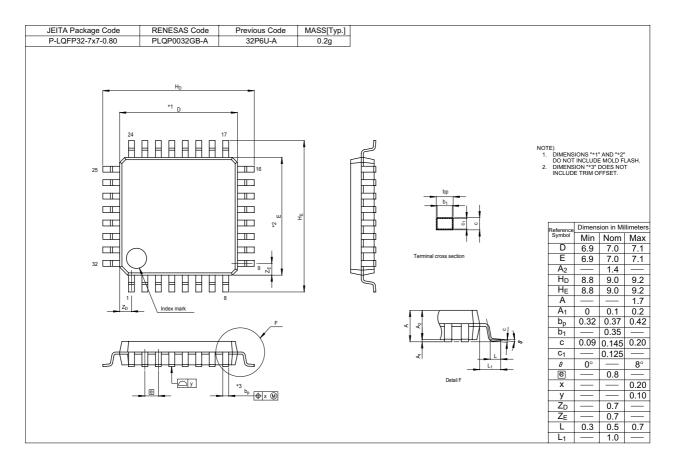


Figure 5.5 Vcc=3V timing diagram

R8C/13 Group Package Dimensions

Package Dimensions



REVISION HISTORY

R8C/13 Group Datasheet

Rev.	Date		Description		
		Page	Summary		
0.10	Oct 28, 2003		First edition issued		
0.20	Dec05, 2003	5	Figure 1.3 revised		
		10	Chapter 4, NOTES revised		
		16	Table 5.4 revised Table 5.5 revised		
		17	Table 5.6 revised Figure 5.3 added		
		18	Table 5.8 revised Table 5.10 revised		
		21	Figure 5.3 revised to Figure 5.4		
		22	Table 5.17 revised		
		25	Figure 5.4 revised to Figure 5.5		
1.00	Sep 30, 2004	All pages	Words standardized (on-chip oscillator, serial interface, A/D)		
		2	Table 1.1 revised		
		5	Figure 1.3, NOTES 3 added		
		6	Table 1.3 revised		
		9	Figure 3.1, NOTES added		
		10-13	One body sentence in chapter 4 added ; Titles of Table 4.1 to 4.4 added		
		12	Table 4.3 revised ; Table 4.4 revised		
		14	Table 5.2 revised		
		15	Table 5.3 revised		
		16	Table 5.4 and Table 5.5 revised		
		17	Table 5.6, 5.7 and 5.8 revised ; Figure 5.3 revised		
		18	Table 5.9 and 5.11 revised		
		19	Table 5.12 revised		
		20	Table 5.13 revised		
		22	Table 5.18 revised		
		23	Table 5.19 revised		
		24	Table 5.20 and Table 5.24 revised		
1.10	Apr.27.2005	4	Table 1.2, Figure 1.2 package name revised		
		5	Figure 1.3 package name revised		
		10	Table 4.1 revised		
		12	Table 4.3 revised		
		15	Table 5.3 partly revised		
		16	Table 5.4, Table 5.5 partly added		

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