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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DMA, POR, WDT
Connectivity	EBI/EMI, Ethernet, I ² C, SPI, UART/USART
Speed	80MHz
Primary Attributes	ProASIC®3 FPGA, 500K Gates, 11520 D-Flip-Flops
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	288-TFBGA, CSPBGA
Supplier Device Package	288-CSP (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a2f500m3g-cs288i

Datasheet Categories 6-14
Microsemi SoC Products Group Safety Critic

VCCxxxIOBx Trip Point:

Ramping up: $0.6\text{ V} < \text{trip_point_up} < 1.2\text{ V}$

Ramping down: $0.5\text{ V} < \text{trip_point_down} < 1.1\text{ V}$

VCC Trip Point:

Ramping up: $0.6\text{ V} < \text{trip_point_up} < 1.1\text{ V}$

Ramping down: $0.5\text{ V} < \text{trip_point_down} < 1\text{ V}$

VCC and VCCxxxIOBx ramp-up trip points are about 100 mV higher than ramp-down trip points. This specifically built-in hysteresis prevents undesirable power-up osc

Standby Mode and Time Keeping Mode

$$P_{NET} = 0 \text{ W}$$

I/O Input Buffer Dynamic Contribution— P_{INPUTS}
SoC Mode

$$P_{INPUTS} = N_{INPUTS} * (\alpha_2 / 2) * P_{AC9} * F_{CLK}$$

Where:

N_{INPUTS} is the number of I/O input buffers used in the design.

α_2 is the I/O buffer toggle rate—guidelines are provided in [Table 2-17 on page 2-18](#).

F_{CLK} is the global clock signal frequency.

Standby Mode and Time Keeping Mode

$$P_{INPUTS} = 0 \text{ W}$$

I/O Output Buffer Dynamic Contribution— $P_{OUTPUTS}$
SoC Mode

$$P_{OUTPUTS} = N_{OUTPUTS} * (\alpha_2 / 2) * \beta_1 * P_{AC10} * F_{CLK}$$

Where:

$N_{OUTPUTS}$ is the number of I/O output buffers used in the design.

α_2 is the I/O buffer toggle rate—guidelines are provided in [Table 2-17 on page 2-18](#).

β_1 is the I/O buffer enable rate—guidelines are provided in [Table 2-18 on page 2-18](#).

F_{CLK} is the global clock signal frequency.

Standby Mode and Time Keeping Mode

$$P_{OUTPUTS} = 0 \text{ W}$$

FPGA Fabric SRAM Dynamic Contribution— P_{MEMORY}
SoC Mode

$$P_{MEMORY} = (N_{BLOCKS} * P_{AC11} * \beta_2 * F_{READ-CLOCK}) + (N_{BLOCKS} * P_{AC12} * \beta_3 * F_{WRITE-CLOCK})$$

Where:

N_{BLOCKS} is the number of RAM blocks used in the design.

$F_{READ-CLOCK}$ is the memory read clock frequency.

β_2 is the RAM enable rate for read operations—guidelines are provided in [Table 2-18 on page 2-18](#).

β_3 the RAM enable rate for write operations—guidelines are provided in [Table 2-18 on page 2-18](#).

$F_{WRITE-CLOCK}$ is the memory write clock frequency.

Standby Mode and Time Keeping Mode

$$P_{MEMORY} = 0 \text{ W}$$

PLL/CCC Dynamic Contribution— P_{PLL}
SoC Mode

$$P_{PLL} = P_{AC13} * F_{CLKOUT}$$

F_{CLKIN} is the input clock frequency.

F_{CLKOUT} is the output clock frequency.¹

Standby Mode and Time Keeping Mode

1. The PLL dynamic contribution depends on the input clock frequency, the number of output clock signals generated by the PLL, and the frequency of each output clock. If a PLL is used to generate more than one output clock, include each output clock in the formula output clock by adding its corresponding contribution ($P_{AC14} * F_{CLKOUT}$ product) to the total PLL contribution.

Summary of I/O Timing Characteristics – Default I/O Software Settings

Fully Registered I/O Buffers with Synchronous Enable and Asynchronous Clear

Pin No.	CS288		
	A2F060 Function	A2F200 Function	A2F500 Function
K17	GNDLPXTAL	GNDLPXTAL	GNDLPXTAL
K19	GNDMAINXTAL	GNDMAINXTAL	GNDMAINXTAL
K21	MAINXIN	MAINXIN	MAINXIN
L1	GNDRCOSC	GNDRCOSC	GNDRCOSC
L3	VCCFPGAIOB5	VCCFPGAIOB5	VCCFPGAIOB5
L5	EMC_DB[2]/IO37NPB5VO	EMC_DB[2]/IO60NPB5VO	EMC_DB[2]/IO77NPB5VO
L6	NC	GNDQ	GNDQ
L8	VCC	VCC	VCC
L9	GND	GND	GND
L10	VCC	VCC	VCC
L12	VCC	VCC	VCC
L13	GND	GND	GND
L14	VCC	VCC	VCC
L16	VCCLPXTAL	VCCLPXTAL	VCCLPXTAL
L17	VDDBAT	VDDBAT	VDDBAT
L19	LPXIN	LPXIN	LPXIN
L21	MAINXOUT	MAINXOUT	MAINXOUT
M1	VCCRCOSC	VCCRCOSC	VCCRCOSC
M3	MSS_RESET_N	MSS_R ESET_N	MSS_RESET_N
M5	GPIO_5/IO28RSB4VO	GPIO_5/IO42RSB4VO	GPIO_5/IO51RSB4VO
M6	GND	GND	GND
M8	GND	GND	GND
M9	VCC	VCC	VCC
M10	GND	GND	GND
M11	VCC	VCC	VCC
M12	GND	GND	GND
M13	VCC	VCC	VCC
M14	GND	GND	GND
M16	TMS	TMS	TMS
M17	VJTAG	VJTAG	VJTAG
M19	TDO	TDO	TDO

Notes:

1. Shading denotes pins that do not have completely identical functions from density to density. For example, the bank assignment can be different for an I/O, or the function might be available only on a larger density device.
2. *: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the Glitchless MUX section in [SmartFusion Microcontroller Subsystem User's Guide](#) for more details.

Pin No.	FG256		
	A2F060 Function	A2F200 Function	A2F500 Function
M11	ADC6	TM2	TM2
M12	ADC5	CM2	CM2
M13	SPI_O_SS/GPIO_19	SPI_O_SS/GPIO_19	SPI_O_SS/GPIO_19
M14	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
M15	SPI_O_CLK/GPIO_18	SPI_O_CLK/GPIO_18	SPI_O_CLK/GPIO_18
M16	SPI_O_DI/GPIO_17	SPI_O_DI/GPIO_17	SPI_O_DI/GPIO_17
N1	GPIO_8/IO25RSB4VO	MAC_RXD[1]/IO53RSB4VO	MAC_RXD[1]/IO62RSB4VO
N2	VCCMSSIOB4	VCCMSSIOB4	VCCMSSIOB4
N3	VCC15A	VCC15A	VCC15A
N4	VCC33AP	VCC33AP	VCC33AP
N5	NC	ABPS3	ABPS3
N6	ADC4	TM1	TM1
N7	NC	GND33ADCO	GND33ADCO
N8	VCC33ADCO	VCC33ADC1	VCC33ADC1
N9	ADC8	ADC5	ADC5
N10	CMO	CM3	CM3
N11	GNDAQ	GNDAQ	GNDAQ
N12	VAREFOUT	VAREFOUT	VAREFOUT
N13	NC	GNDSD1	GNDSD1
N14	NC	VCC33SD1	VCC33SD1
N15	GND	GND	GND
N16	SPI_O_DO/GPIO_16	SPI_O_DO/GPIO_16	SPI_O_DO/GPIO_16
P1	GNDSD0	GNDSD0	GNDSD0
P2	VCC33SD0	VCC33SD0	VCC33SD0
P3	VCC33N	VCC33N	VCC33N
P4	GND	GND	GND
P5	GNDAQ	GNDAQ	GNDAQ
P6	NC	CM1	CM1
P7	NC	ADC2	ADC2
P8	NC	VCC15ADCO	VCC15ADCO
P9	ADC9	ADC6	ADC6

Notes:

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2. *: Indicates that the signal assigned to the pins CLKBUF/CLKBUF_LVPECL /CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the Glitchless MUX section in [SmartFusion Microcontroller Subsystem User's Guide](#) for more details.

Pin Number	FG484	
	A2F200 Function	A2F500 Function
H7	GND	GND
H8	VCC	VCC
H9	GND	GND
H10	VCC	VCC
H11	GND	GND
H12	VCC	VCC
H13	GND	GND
H14	VCC	VCC
H15	GND	GND
H16	VCCFPGAIOB1	VCCFPGAIOB1
H17	IO25NDB1VO	IO29NDB1VO
H18	GCC2/IO25PDB1VO	GCC2/IO29PDB1VO
H19	GND	GND
H20	GCC0/IO26NPB1VO	GCC0/IO35NPB1VO
H21	VCCFPGAIOB1	VCCFPGAIOB1
H22	GCB0/IO27NDB1VO	GCB0/IO34NDB1VO
J1	EMC_DB[6]/GEBO/IO62NDB5VO	EMC_DB[6]/GEBO/IO79NDB5VO
J2	EMC_DB[5]/GEA1/IO61PDB5VO	EMC_DB[5]/GEA1/IO78PDB5VO
J3	EMC_DB[4]/GEAO/IO61NDB5VO	EMC_DB[4]/GEAO/IO78NDB5VO
J4	EMC_DB[3]/GEC2/IO60PPB5VO	EMC_DB[3]/GEC2/IO77PPB5VO
J5	VCCFPGAIOB5	VCCFPGAIOB5
J6	GFA0/IO64NDB5VO	GFA0/IO81NDB5VO
J7	VCCFPGAIOB5	VCCFPGAIOB5
J8	GND	GND
J9	VCC	VCC
J10	GND	GND
J11	VCC	VCC
J12	GND	GND
J13	VCC	VCC
J14	GND	GND
J15	VCC	VCC
J16	GND	GND
J17	NC	IO37PDB1VO
J18	VCCFPGAIOB1	VCCFPGAIOB1

Notes:

1. Shading denotes pins that do not have completely identical functions from density to density. For example, the bank assignment can be different for an I/O, or the function might be available only on a larger density device.
2. *: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the Glitchless MUX section in [SmartFusion Microcontroller Subsystem User's Guide](#) for more details.

Datasheet Categories

Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device, as highlighted in the "[SmartFusion cSoC Device Status](#)" table on page III, is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

Product Brief

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

Production

This version contains information that is considered to be final.

Export Administration Regulations (EAR)

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Microsemi SoC Products Group Safety Critical, Life Support, and High-Reliability Applications Policy

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