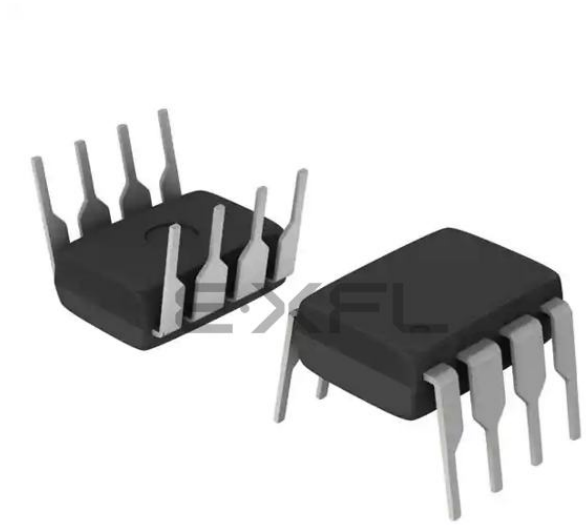

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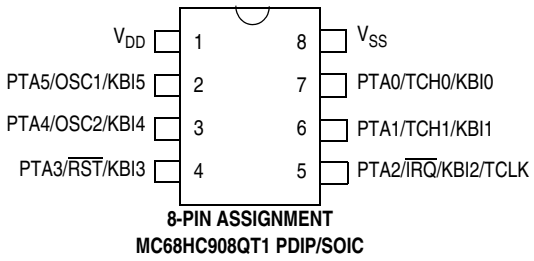
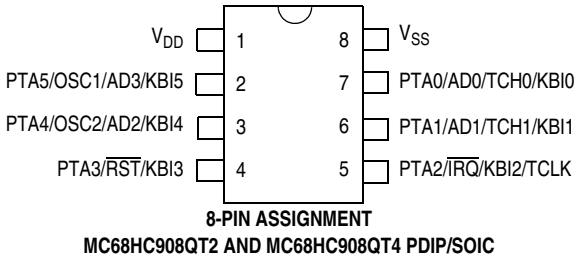
Applications of "Embedded - Microcontrollers"

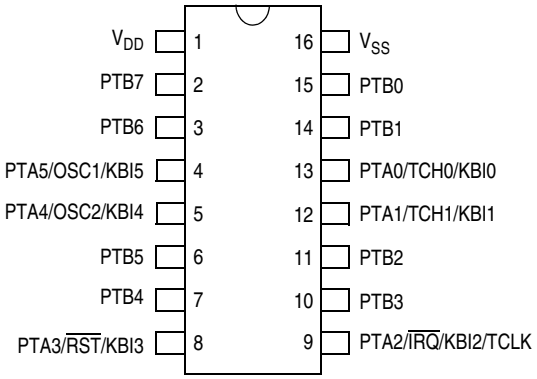
Details	
Product Status	Obsolete
Core Processor	HC08
Core Size	8-Bit
Speed	2MHz
Connectivity	-
Peripherals	LVD, POR, PWM
Number of I/O	5
Program Memory Size	1.5KB (1.5K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	8-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mchlc908qt1pe



8-PIN ASSIGNMENT
MC68HC908QT1 PDIP/SOIC



8-PIN ASSIGNMENT
MC68HC908QT2 AND MC68HC908QT4 PDIP/SOIC



16-PIN ASSIGNMENT
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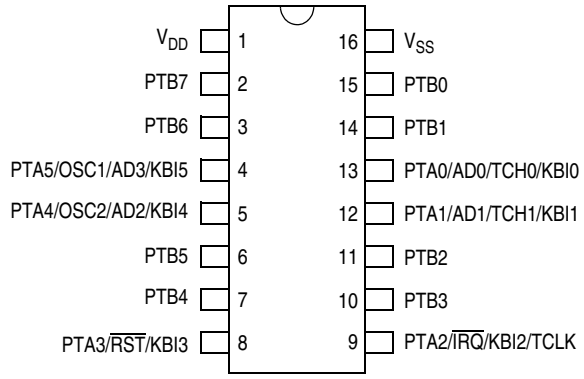
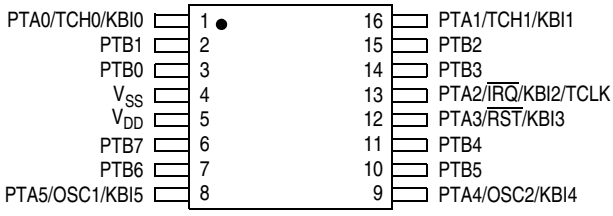
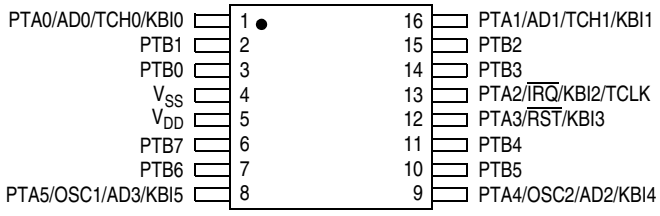


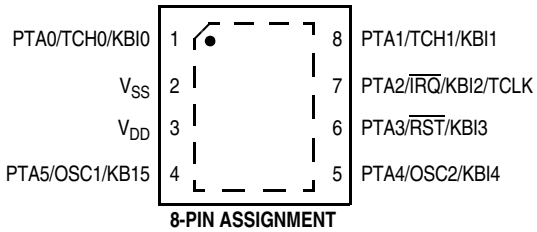
16-PIN ASSIGNMENT
MC68HC908QY2 AND MC68HC908QY4 PDIP/SOIC



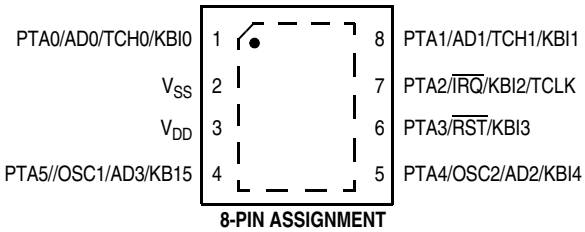
16-PIN ASSIGNMENT
MC68HC908QY1 TSSOP



16-PIN ASSIGNMENT
MC68HC908QY2 AND MC68HC908QY4 TSSOP



8-PIN ASSIGNMENT
MC68HC908QT1 DFN



8-PIN ASSIGNMENT
MC68HC908QT2 AND MC68HC908QT4 DFN

Figure 1-2. MCU Pin Assignments

Addr.	Register Name		Bit 7	6	5	4	3	2	1	Bit 0
$0005	Data Direction Register B (DDRB) See page 101.	Read:	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$0006 ↓ $000A	Unimplemented									
$000B	Port A Input Pullup Enable Register (PTAPUE) See page 99.	Read:	OSC2EN	0	PTAPUE5	PTAPUE4	PTAPUE3	PTAPUE2	PTAPUE1	PTAPUE0
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$000C	Port B Input Pullup Enable Register (PTBPUE) See page 102.	Read:	PTBPUE7	PTBPUE6	PTBPUE5	PTBPUE4	PTBPUE3	PTBPUE2	PTBPUE1	PTBPUE0
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$000D ↓ $0019	Unimplemented									
$001A	Keyboard Status and Control Register (KBSCR) See page 83.	Read:	0	0	0	0	KEYF	0	IMASKK	MODEK
		Write:						ACKK		
		Reset:	0	0	0	0	0	0	0	0
$001B	Keyboard Interrupt Enable Register (KBIER) See page 84.	Read:	0	AWUIE	KBIE5	KBIE4	KBIE3	KBIE2	KBIE1	KBIE0
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$001C	Unimplemented									
$001D	IRQ Status and Control Register (INTSCR) See page 77.	Read:	0	0	0	0	IRQF	0	IMASK	MODE
		Write:						ACK		
		Reset:	0	0	0	0	0	0	0	0
$001E	Configuration Register 2 (CONFIG2)(1) See page 53.	Read:	IRQPUD	IRQEN	R	OSCOPT1	OSCOPT0	R	R	RSTEN
		Write:								
		Reset:	0	0	0	0	0	0	0	0(2)

1. One-time writable register after each reset.
2. RSTEN reset to 0 by a power-on reset (POR) only.

= Unimplemented R = Reserved U = Unaffected

Figure 2-2. Control, Status, and Data Registers (Sheet 2 of 6)

Addr.	Register Name		Bit 7	6	5	4	3	2	1	Bit 0
$FE0B	Break Status and Control Register (BRKSCR) See page 138.	Read:	BRKE	BRKA	0	0	0	0	0	0
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$FE0C	LVI Status Register (LVISR) See page 87.	Read:	LVIOUT	0	0	0	0	0	0	R
		Write:								
		Reset:	0	0	0	0	0	0	0	0
$FE0D ↓ $FE0F	Reserved for FLASH Test		R	R	R	R	R	R	R	R
$FFBE	FLASH Block Protect Register (FLBPR) See page 37.	Read:	BPR7	BPR6	BPR5	BPR4	BPR3	BPR2	BPR1	BPR0
		Write:								
		Reset:	Unaffected by reset							
$FFBF	Reserved		R	R	R	R	R	R	R	R
$FFC0	Internal Oscillator Trim Value (Optional)	Read:	TRIM7	TRIM6	TRIM5	TRIM4	TRIM3	TRIM2	TRIM1	TRIM0
		Write:								
		Reset:	Unaffected by reset							
$FFC1	Reserved		R	R	R	R	R	R	R	R
$FFFF	COP Control Register (COPCTL) See page 59.	Read:	LOW BYTE OF RESET VECTOR							
		Write:	WRITING CLEARS COP COUNTER (ANY VALUE)							
		Reset:	Unaffected by reset							

= Unimplemented R = Reserved U = Unaffected

Figure 2-2. Control, Status, and Data Registers (Sheet 6 of 6)

MASS — Mass Erase Control Bit

This read/write bit configures the memory for mass erase operation.

1 = Mass Erase operation selected
0 = Mass Erase operation unselected

ERASE — Erase Control Bit

This read/write bit configures the memory for erase operation. ERASE is interlocked with the PGM bit such that both bits cannot be equal to 1 or set to 1 at the same time.

1 = Erase operation selected
0 = Erase operation unselected

PGM — Program Control Bit

This read/write bit configures the memory for program operation. PGM is interlocked with the ERASE bit such that both bits cannot be equal to 1 or set to 1 at the same time.

1 = Program operation selected
0 = Program operation unselected

2.6.2 FLASH Page Erase Operation

Use the following procedure to erase a page of FLASH memory. A page consists of 64 consecutive bytes starting from addresses $XX00, $XX40, $XX80, or $XXC0. The 48-byte user interrupt vectors area also forms a page. Any FLASH memory page can be erased alone.

1. Set the ERASE bit and clear the MASS bit in the FLASH control register.
2. Read the FLASH block protect register.
3. Write any data to any FLASH location within the address range of the block to be erased.
4. Wait for a time, t_{NVS} (minimum 10 µs).
5. Set the HVEN bit.
6. Wait for a time, t_{Erase} (minimum 1 ms or 4 ms).
7. Clear the ERASE bit.
8. Wait for a time, t_{NVH} (minimum 5 µs).
9. Clear the HVEN bit.
10. After time, t_{RCV} (typical 1 µs), the memory can be accessed in read mode again.

NOTE

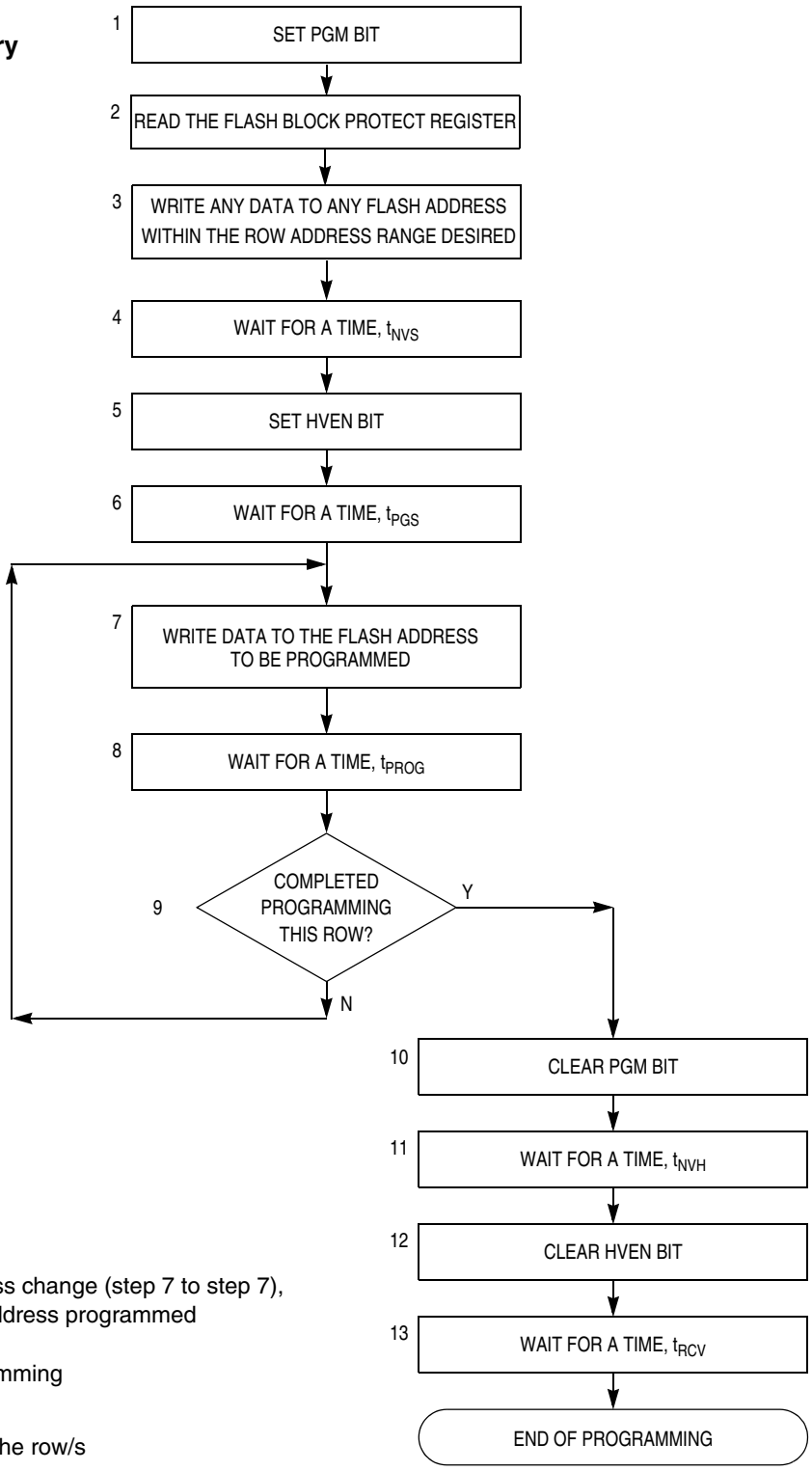
Programming and erasing of FLASH locations cannot be performed by code being executed from the FLASH memory. While these operations must be performed in the order as shown, but other unrelated operations may occur between the steps.

CAUTION

A page erase of the vector page will erase the internal oscillator trim value at $FFC0.

In applications that require more than 1000 program/erase cycles, use the 4 ms page erase specification to get improved long-term reliability. Any application can use this 4 ms page erase specification. However, in applications where a FLASH location will be erased and reprogrammed less than 1000 times, and speed is important, use the 1 ms page erase specification to get a shorter cycle time.

Algorithm for Programming a Row (32 Bytes) of FLASH Memory



NOTES:

The time between each FLASH address change (step 7 to step 7), or the time between the last FLASH address programmed to clearing PGM bit (step 7 to step 10) must not exceed the maximum programming time, t_{PROG} max.

This row program algorithm assumes the row/s to be programmed are initially erased.

Figure 2-4. FLASH Programming Flowchart

Chapter 6
Computer Operating Properly (COP)

6.1 Introduction

The computer operating properly (COP) module contains a free-running counter that generates a reset if allowed to overflow. The COP module helps software recover from runaway code. Prevent a COP reset by clearing the COP counter periodically. The COP module can be disabled through the COPD bit in the configuration 1 (CONFIG1) register.

6.2 Functional Description

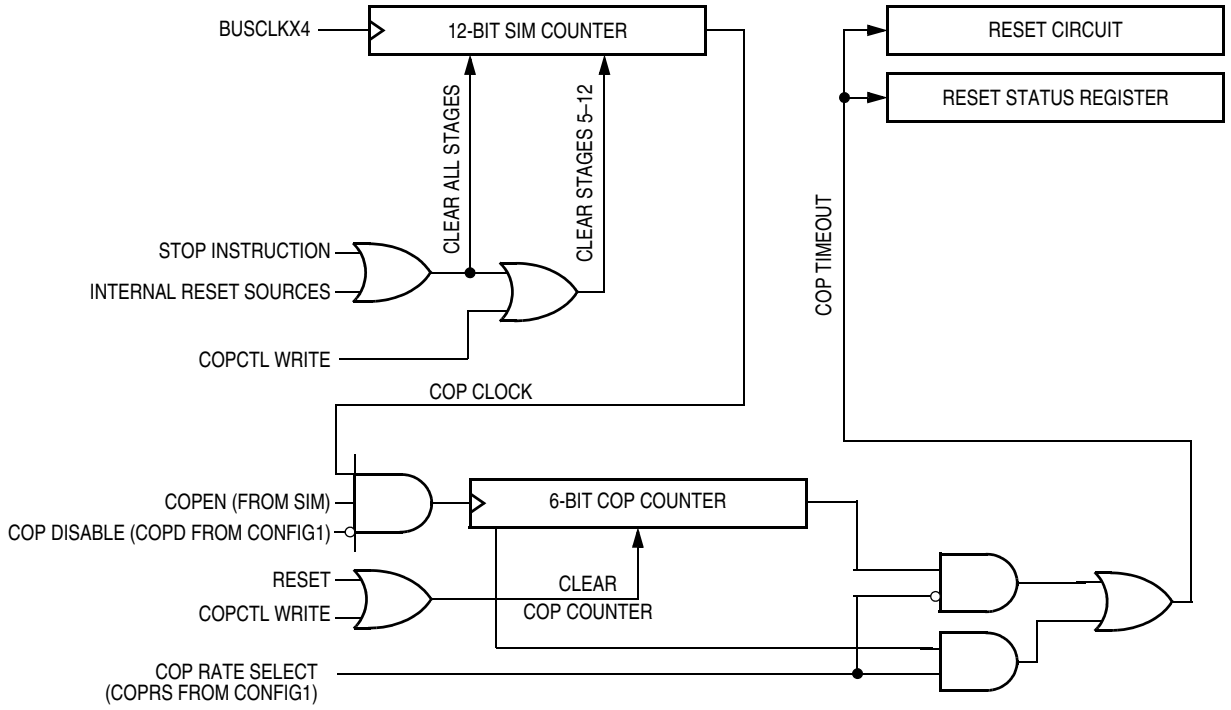


Figure 6-1. COP Block Diagram

Polling and forced reset operation modes can be combined to take full advantage of LVD and LVR trip voltages selection. LVD (LVDLVR = 1) in polling mode (LVIRSTD = 1) can be used as a low voltage warning in a slowly and continuously falling V_{DD} application (for example, battery applications). Once LVD has been identified, the part can be set to LVR (LVDLVR = 0) and reset enabled (LVIRSTD = 0). So, as V_{DD} continues to fall the part will reset when LVR trip voltage is reached. Unlike other bits in CONFIG registers, LVIRSTD and LVDLVR bits are allowed to be written multiple times after reset.

NOTE

The microcontroller is guaranteed to operate at a minimum supply voltage. The trip point (V_{TRIPF} [LVD] or V_{TRIPF} [LVR]) may be lower than this. See 16.5 DC Electrical Characteristics for the actual trip point voltages.

10.4 LVI Status Register

The LVI status register (LVISR) indicates if the V_{DD} voltage was detected below the V_{TRIPF} level while LVI resets have been disabled.

Address: $FE0C

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	LVIOUT	0	0	0	0	0	0	R
Write:								
Reset:	0	0	0	0	0	0	0	0

= Unimplemented R = Reserved

Figure 10-2. LVI Status Register (LVISR)

LVIOUT — LVI Output Bit

This read-only flag becomes set when the V_{DD} voltage falls below the V_{TRIPF} trip voltage and is cleared when V_{DD} voltage rises above V_{TRIPR}. The difference in these threshold levels results in a hysteresis that prevents oscillation into and out of reset (see Table 10-1). Reset clears the LVIOUT bit.

Table 10-1. LVIOUT Bit Indication

V_{DD}	LVIOUT
$V_{DD} > V_{TRIPR}$	0
$V_{DD} < V_{TRIPF}$	1
$V_{TRIPF} < V_{DD} < V_{TRIPR}$	Previous value

10.5 LVI Interrupts

The LVI module does not generate interrupt requests.

11.6 Oscillator During Break Mode

The oscillator continues to drive BUSCLKX2 and BUSCLKX4 when the device enters the break state.

11.7 CONFIG2 Options

Two CONFIG2 register options affect the operation of the oscillator module: OSCOPT1 and OSCOPT0. All CONFIG2 register bits will have a default configuration. Refer to Chapter 5 Configuration Register (CONFIG) for more information on how the CONFIG2 register is used.

Table 11-2 shows how the OSCOPT bits are used to select the oscillator clock source.

Table 11-2. Oscillator Modes

OSCOPT1	OSCOPT0	Oscillator Modes
0	0	Internal Oscillator
0	1	External Oscillator
1	0	External RC
1	1	External Crystal

11.8 Input/Output (I/O) Registers

The oscillator module contains these two registers:

1. Oscillator status register (OSCSTAT)
2. Oscillator trim register (OSCTRIM)

11.8.1 Oscillator Status Register

The oscillator status register (OSCSTAT) contains the bits for switching from internal to external clock sources.

Address: $0036

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	R	R	R	R	R	R	ECGON	ECGST
Write:								
Reset:	0	0	0	0	0	0	0	0

R = Reserved = Unimplemented

Figure 11-4. Oscillator Status Register (OSCSTAT)

ECGON — External Clock Generator On Bit

This read/write bit enables external clock generator, so that the switching process can be initiated. This bit is forced low during reset. This bit is ignored in monitor mode with the internal oscillator bypassed.

1 = External clock generator enabled
0 = External clock generator disabled

ECGST — External Clock Status Bit

This read-only bit indicates whether or not an external clock source is engaged to drive the system clock.

1 = An external clock source engaged
0 = An external clock source disengaged

12.2.1 Port A Data Register

The port A data register (PTA) contains a data latch for each of the six port A pins.

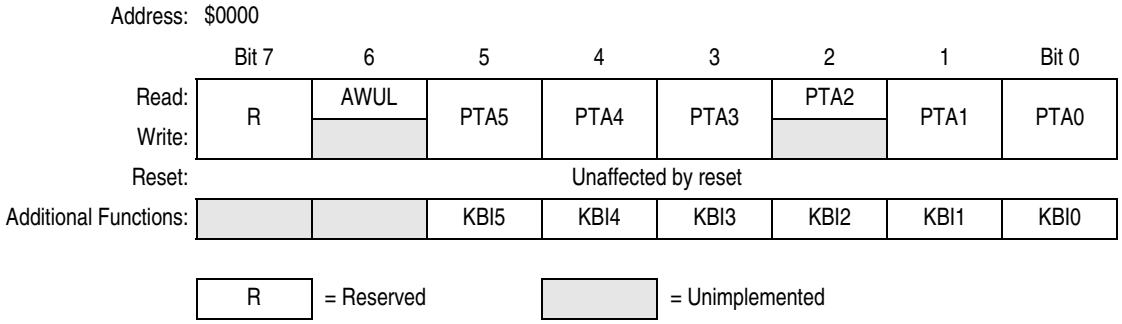


Figure 12-1. Port A Data Register (PTA)

PTA[5:0] — Port A Data Bits

These read/write bits are software programmable. Data direction of each port A pin is under the control of the corresponding bit in data direction register A. Reset has no effect on port A data.

AWUL — Auto Wakeup Latch Data Bit

This is a read-only bit which has the value of the auto wakeup interrupt request latch. The wakeup request signal is generated internally (see Chapter 4 Auto Wakeup Module (AWU)). There is no PTA6 port nor any of the associated bits such as PTA6 data register, pullup enable or direction.

KBI[5:0] — Port A Keyboard Interrupts

The keyboard interrupt enable bits, KBIE5–KBIE0, in the keyboard interrupt control enable register (KBIER) enable the port A pins as external interrupt pins (see Chapter 9 Keyboard Interrupt Module (KBI)).

12.2.2 Data Direction Register A

Data direction register A (DDRA) determines whether each port A pin is an input or an output. Writing a 1 to a DDRA bit enables the output buffer for the corresponding port A pin; a 0 disables the output buffer.

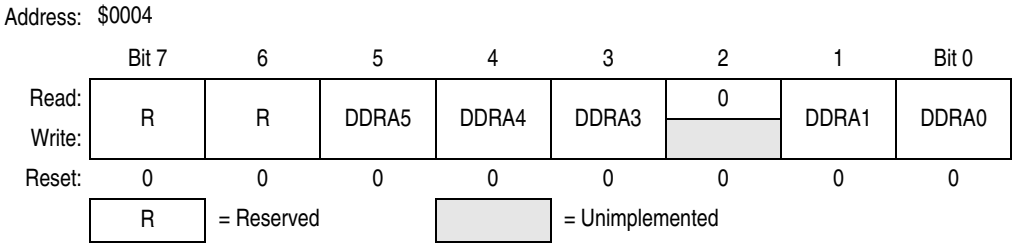


Figure 12-2. Data Direction Register A (DDRA)

DDRA[5:0] — Data Direction Register A Bits

These read/write bits control port A data direction. Reset clears DDRA[5:0], configuring all port A pins as inputs.

1 = Corresponding port A pin configured as output
0 = Corresponding port A pin configured as input

NOTE

Avoid glitches on port A pins by writing to the port A data register before changing data direction register A bits from 0 to 1.

13.5.3 SIM Counter and Reset States

External reset has no effect on the SIM counter (see 13.7.2 Stop Mode for details.) The SIM counter is free-running after all reset states. See 13.4.2 Active Resets from Internal Sources for counter control and internal reset recovery sequences.

13.6 Exception Control

Normal sequential program execution can be changed in three different ways:

1. Interrupts
   a. Maskable hardware CPU interrupts
   b. Non-maskable software interrupt instruction (SWI)
2. Reset
3. Break interrupts

13.6.1 Interrupts

An interrupt temporarily changes the sequence of program execution to respond to a particular event. Figure 13-7 flow charts the handling of system interrupts.

Interrupts are latched, and arbitration is performed in the SIM at the start of interrupt processing. The arbitration result is a constant that the CPU uses to determine which vector to fetch. Once an interrupt is latched by the SIM, no other interrupt can take precedence, regardless of priority, until the latched interrupt is serviced (or the I bit is cleared).

At the beginning of an interrupt, the CPU saves the CPU register contents on the stack and sets the interrupt mask (I bit) to prevent additional interrupts. At the end of an interrupt, the RTI instruction recovers the CPU register contents from the stack so that normal processing can resume. Figure 13-8 shows interrupt entry timing. Figure 13-9 shows interrupt recovery timing.

13.6.1.1 Hardware Interrupts

A hardware interrupt does not stop the current instruction. Processing of a hardware interrupt begins after completion of the current instruction. When the current instruction is complete, the SIM checks all pending hardware interrupts. If interrupts are not masked (I bit clear in the condition code register), and if the corresponding interrupt enable bit is set, the SIM proceeds with interrupt processing; otherwise, the next instruction is fetched and executed.

If more than one interrupt is pending at the end of an instruction execution, the highest priority interrupt is serviced first. Figure 13-10 demonstrates what happens when two interrupts are pending. If an interrupt is pending upon exit from the original interrupt service routine, the pending interrupt is serviced before the LDA instruction is executed.

The LDA opcode is prefetched by both the INT1 and INT2 return-from-interrupt (RTI) instructions. However, in the case of the INT1 RTI prefetch, this is a redundant operation.

NOTE

To maintain compatibility with the M6805 Family, the H register is not pushed on the stack during interrupt entry. If the interrupt service routine modifies the H register or uses the indexed addressing mode, software should save the H register and then restore it prior to exiting the routine.

13.6.1.2 SWI Instruction

The SWI instruction is a non-maskable instruction that causes an interrupt regardless of the state of the interrupt mask (I bit) in the condition code register.

NOTE

A software interrupt pushes PC onto the stack. A software interrupt does ***not*** *push PC – 1, as a hardware interrupt does.*

13.6.2 Interrupt Status Registers

The flags in the interrupt status registers identify maskable interrupt sources. Table 13-3 summarizes the interrupt sources and the interrupt status register flags that they set. The interrupt status registers can be useful for debugging.

Table 13-3. Interrupt Sources

Priority	Source	Flag	Mask[1]	INT Register Flag	Vector Address
Highest	Reset	—	—	—	$FFFE–$FFFF
↑	SWI instruction	—	—	—	$FFFC–$FFFD
↑	$\overline{\text{IRQ}}$ pin	IRQF	IMASK	IF1	$FFFA–$FFFB
↑	Timer channel 0 interrupt	CH0F	CH0IE	IF3	$FFF6–$FFF7
↑	Timer channel 1 interrupt	CH1F	CH1IE	IF4	$FFF4–$FFF5
↑	Timer overflow interrupt	TOF	TOIE	IF5	$FFF2–$FFF3
↑	Keyboard interrupt	KEYF	IMASKK	IF14	$FFE0–$FFE1
Lowest	ADC conversion complete interrupt	COCO	AIEN	IF15	$FFDE–$FFDF

1. The I bit in the condition code register is a global mask for all interrupt sources except the SWI instruction.

13.6.2.1 Interrupt Status Register 1

Address: $FE04

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	0	IF5	IF4	IF3	0	IF1	0	0
Write:	R	R	R	R	R	R	R	R
Reset:	0	0	0	0	0	0	0	0

R = Reserved

Figure 13-11. Interrupt Status Register 1 (INT1)

IF1 and IF3–IF5 — Interrupt Flags

These flags indicate the presence of interrupt requests from the sources shown in Table 13-3.

1 = Interrupt request present
0 = No interrupt request present

Bit 0, 1, 3, and 7 — Always read 0

13.6.2.2 Interrupt Status Register 2

Address: $FE05

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	IF14	0	0	0	0	0	0	0
Write:	R	R	R	R	R	R	R	R
Reset:	0	0	0	0	0	0	0	0

R = Reserved

Figure 13-12. Interrupt Status Register 2 (INT2)

IF14 — Interrupt Flags

This flag indicates the presence of interrupt requests from the sources shown in Table 13-3.

1 = Interrupt request present
0 = No interrupt request present

Bit 0–6 — Always read 0

13.6.2.3 Interrupt Status Register 3

Address: $FE06

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	0	0	0	0	0	0	0	IF15
Write:	R	R	R	R	R	R	R	R
Reset:	0	0	0	0	0	0	0	0

R = Reserved

Figure 13-13. Interrupt Status Register 3 (INT3)

IF15 — Interrupt Flags

These flags indicate the presence of interrupt requests from the sources shown in Table 13-3.

1 = Interrupt request present
0 = No interrupt request present

Bit 1–7 — Always read 0

13.6.3 Reset

All reset sources always have equal and highest priority and cannot be arbitrated.

13.6.4 Break Interrupts

The break module can stop normal program flow at a software programmable break point by asserting its break interrupt output. (See Chapter 15 Development Support.) The SIM puts the CPU into the break

13.8.2 Break Flag Control Register

The break control register (BFCR) contains a bit that enables software to clear status bits while the MCU is in a break state.

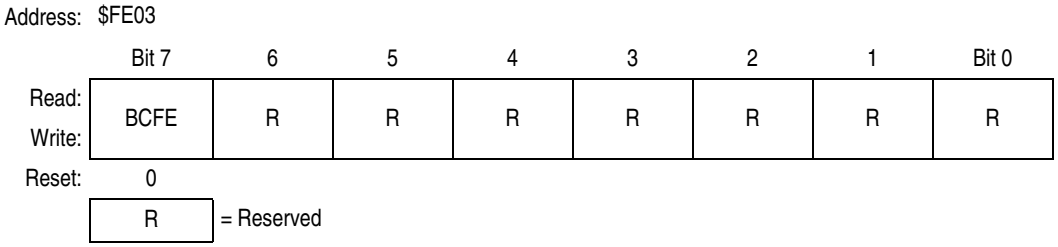


Figure 13-20. Break Flag Control Register (BFCR)

BCFE — Break Clear Flag Enable Bit

This read/write bit enables software to clear status bits by accessing status registers while the MCU is in a break state. To clear status bits during the break state, the BCFE bit must be set.

1 = Status bits clearable during break
0 = Status bits not clearable during break

Chapter 14
Timer Interface Module (TIM)

14.1 Introduction

This section describes the timer interface module (TIM). The TIM is a two-channel timer that provides a timing reference with input capture, output compare, and pulse-width-modulation functions. Figure 14-2 is a block diagram of the TIM.

14.2 Features

Features of the TIM include the following:

- Two input capture/output compare channels
  - Rising-edge, falling-edge, or any-edge input capture trigger
  - Set, clear, or toggle output compare action
- Buffered and unbuffered pulse width modulation (PWM) signal generation
- Programmable TIM clock input
  - 7-frequency internal bus clock prescaler selection
  - External TIM clock input
- Free-running or modulo up-count operation
- Toggle any channel pin on overflow
- TIM counter stop and reset bits

14.3 Pin Name Conventions

The TIM shares two input/output (I/O) pins with two port A I/O pins. The full names of the TIM I/O pins are listed in Table 14-1. The generic pin name appear in the text that follows.

Table 14-1. Pin Name Conventions

TIM Generic Pin Names:	TCH0	TCH1	TCLK
Full TIM Pin Names:	PTA0/TCH0	PTA1/TCH1	PTA2/TCLK

14.9.4 TIM Channel Status and Control Registers

Each of the TIM channel status and control registers does the following:

- Flags input captures and output compares
- Enables input capture and output compare interrupts
- Selects input capture, output compare, or PWM operation
- Selects high, low, or toggling output on output compare
- Selects rising edge, falling edge, or any edge as the active input capture trigger
- Selects output toggling on TIM overflow
- Selects 0% and 100% PWM duty cycle
- Selects buffered or unbuffered output compare/PWM operation

Address: $0025 TSC0

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	CH0F	CH0IE	MS0B	MS0A	ELS0B	ELS0A	TOV0	CH0MAX
Write:	0							
Reset:	0	0	0	0	0	0	0	0

Address: $0028 TSC1

	Bit 7	6	5	4	3	2	1	Bit 0
Read:	CH1F	CH1IE	0	MS1A	ELS1B	ELS1A	TOV1	CH1MAX
Write:	0							
Reset:	0	0	0	0	0	0	0	0

= Unimplemented

Figure 14-7. TIM Channel Status and Control Registers (TSC0:TSC1)

CHxF — Channel x Flag Bit

When channel x is an input capture channel, this read/write bit is set when an active edge occurs on the channel x pin. When channel x is an output compare channel, CHxF is set when the value in the TIM counter registers matches the value in the TIM channel x registers.

Clear CHxF by reading the TIM channel x status and control register with CHxF set and then writing a 0 to CHxF. If another interrupt request occurs before the clearing sequence is complete, then writing a 0 to CHxF has no effect. Therefore, an interrupt request cannot be lost due to inadvertent clearing of CHxF.

Reset clears the CHxF bit. Writing a 1 to CHxF has no effect.

1 = Input capture or output compare on channel x
0 = No input capture or output compare on channel x

CHxIE — Channel x Interrupt Enable Bit

This read/write bit enables TIM CPU interrupt service requests on channel x. Reset clears the CHxIE bit.

1 = Channel x CPU interrupt requests enabled
0 = Channel x CPU interrupt requests disabled

MSxB — Mode Select Bit B

This read/write bit selects buffered output compare/PWM operation. MSxB exists only in the TIM channel 0 status and control register.

Chapter 16
Electrical Specifications

16.1 Introduction

This section contains electrical and timing specifications.

16.2 Absolute Maximum Ratings

Maximum ratings are the extreme limits to which the microcontroller unit (MCU) can be exposed without permanently damaging it.

NOTE

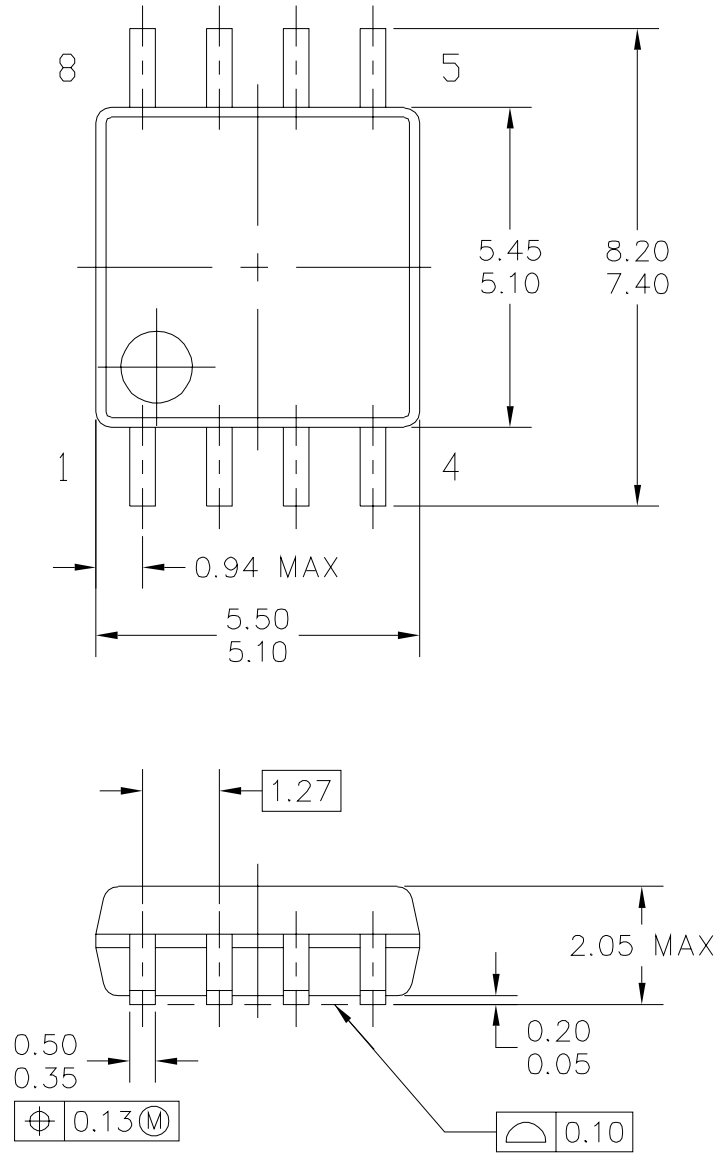
This device is not guaranteed to operate properly at the maximum ratings. Refer to 16.5 DC Electrical Characteristics for guaranteed operating conditions.

Characteristic[1]	Symbol	Value	Unit
Supply voltage	V_{DD}	−0.3 to +6.0	V
Input voltage	V_{IN}	V_{SS} −0.3 to V_{DD} +0.3	V
Mode entry voltage, $\overline{IRQ}$ pin	V_{TST}	V_{SS} −0.3 to +9.1	V
Maximum current per pin excluding PTA0–PTA5, V_{DD}, and V_{SS}	I	±15	mA
Maximum current for pins PTA0–PTA5	I_{PTA0}—I_{PTA5}	±25	mA
Storage temperature	T_{STG}	−55 to +150	°C
Maximum current out of V_{SS}	I_{MVSS}	100	mA
Maximum current into V_{DD}	I_{MVDD}	100	mA

1. Voltages references to V_{SS}.

NOTE

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum-rated voltages to this high-impedance circuit. For proper operation, it is recommended that V_{IN} and V_{OUT} be constrained to the range $V_{SS} \le (V_{IN}$ or $V_{OUT}) \le V_{DD}$. Reliability of operation is enhanced if unused inputs are connected to an appropriate logic voltage level (for example, either V_{SS} or V_{DD}.)



TITLE:

8 LEAD MFP

CASE NUMBER: 968-02

STANDARD: EIAJ

PACKAGE CODE: 6003

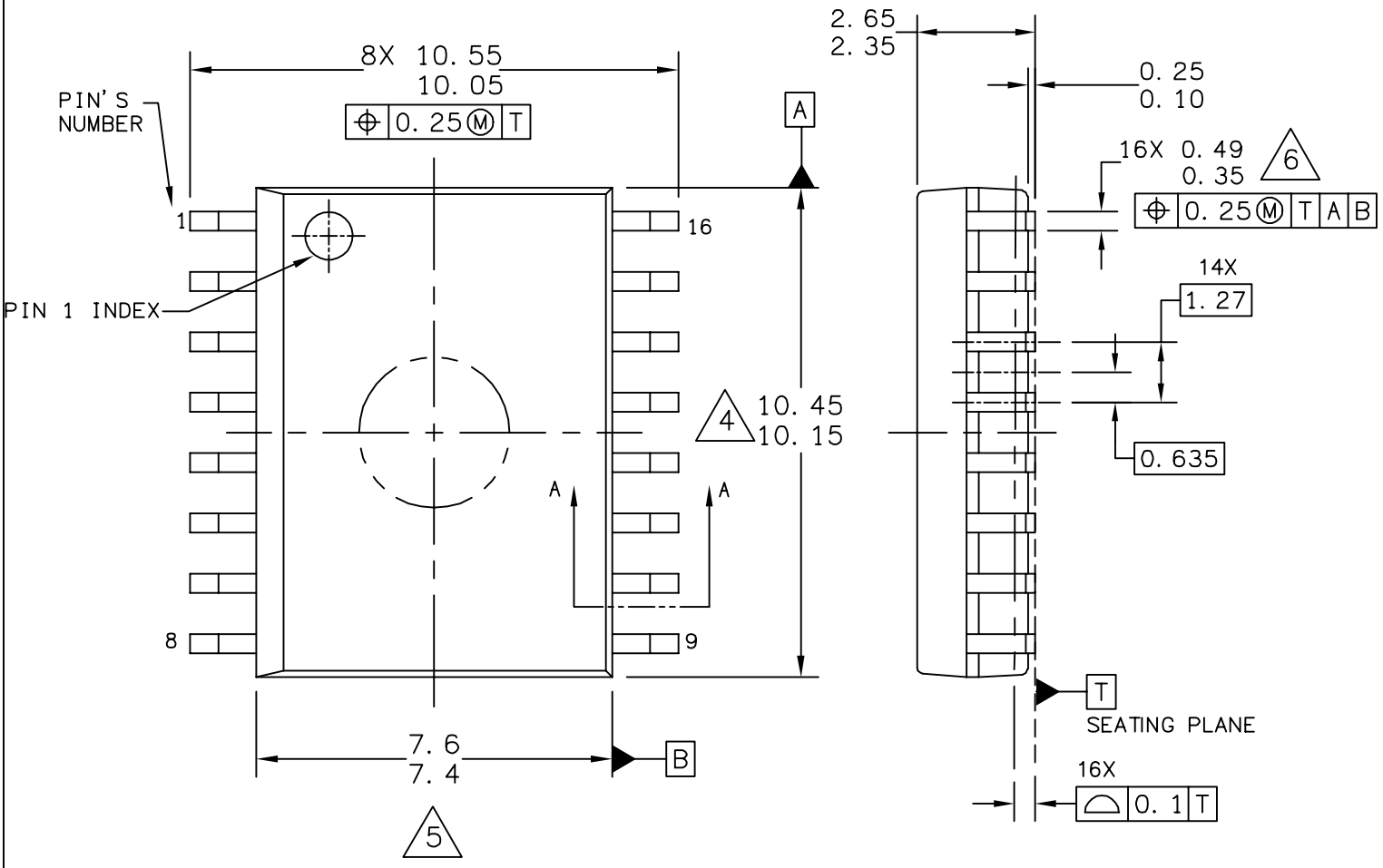
SHEET: 1 OF 4

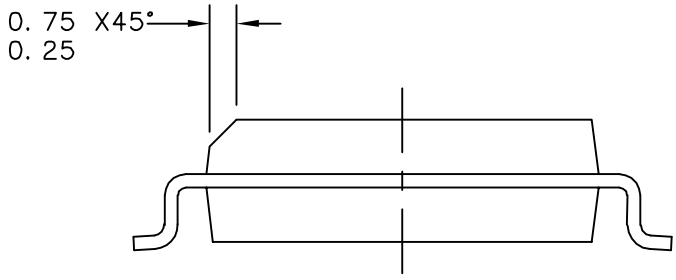
NOTES:

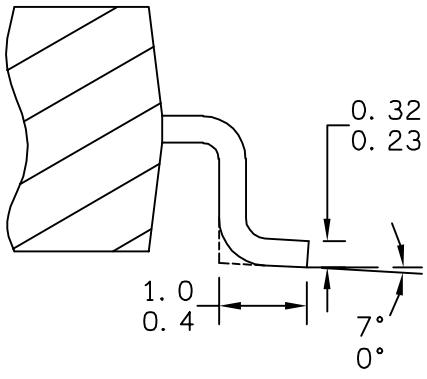
1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M–1994.
3. THE COMPLETE JEDEC DESIGNATOR FOR THIS PACKAGE IS: HP–VFDFP–N.
4. COPLANARITY APPLIES TO LEADS AND DIE ATTACH PAD.

MECHANICAL OUTLINES DICTIONARY

DOCUMENT NO: 98ASB42567B
PAGE: 751G
DO NOT SCALE THIS DRAWING
REV: E







SECTION A–A

TITLE:
16LD SOIC W/B, 1.27 PITCH
CASE-OUTLINE

CASE NUMBER: 751G-05
STANDARD: JEDEC MS-013AA
PACKAGE CODE: 2003
SHEET: 1 OF 3