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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	18
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 17x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SOIC (0.295", 7.50mm Width)
Supplier Device Package	20-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f18345t-i-so

- Up to 18 I/O Pins:
  - Individually programmable pull-ups
  - Slew rate control
  - Interrupt-on-change with edge-select
  - Input level selection control (ST or TTL)
  - Digital open-drain enable
- Peripheral Pin Select (PPS):
  - I/O pin remapping of digital peripherals
- Timer modules:
  - Timer0:
    - 8/16-bit timer/counter
    - Synchronous or asynchronous operation
    - Programmable prescaler/postscaler
    - Time base for capture/compare function
  - Timer1/3/5 with gate control:
    - 16-bit timer/counter
    - Programmable internal or external clock sources
    - Multiple gate sources
    - Multiple gate modes
    - Time base for capture/compare function
  - Timer2/4/6:
    - 8-bit timers
    - Programmable prescaler/postscaler
    - Time base for PWM function

Analog Peripherals

- 10-bit Analog-to-Digital Converter (ADC):
  - 17 external channels
  - Conversion available during Sleep
- Comparator:
  - Two comparators
  - Fixed Voltage Reference at non-inverting input(s)
  - Comparator outputs externally accessible
- 5-bit Digital-to-Analog Converter (DAC):
  - 5-bit resolution, rail-to-rail
  - Positive Reference Selection
  - Unbuffered I/O pin output
  - Internal connections to ADCs and comparators
- Voltage Reference:
  - Fixed Voltage Reference with 1.024V, 2.048V and 4.096V output levels

Flexible Oscillator Structure

- High-Precision Internal Oscillator:
  - Software-selectable frequency range up to 32 MHz
  - ±2% at nominal 4 MHz calibration point
- 4x PLL with External Sources
- Low-Power Internal 31 kHz Oscillator (LFINTOSC)
- External Low-Power 32 kHz Crystal Oscillator (SOSC)
- External Oscillator Block with:
  - Three Crystal/Resonator modes up to 20 MHz
  - Three External Clock modes up to 20 MHz
  - Fail-Safe Clock Monitor
    - Detects clock source failure
  - Oscillator Start-up Timer (OST)
    - Ensures stability of crystal oscillator sources

TABLE 1-1: DEVICE PERIPHERAL SUMMARY (CONTINUED)

Peripheral		PIC16(L)F18325	PIC16(L)F18345
Timers (TMR)			
	TMR0	•	•
	TMR1	•	•
	TMR2	•	•
	TMR3	•	•
	TMR4	•	•
	TMR5	•	•
	TMR6	•	•

4.1.1.2 Indirect Read with FSR

The program memory can be accessed as data by setting bit 7 of an FSRxH register and reading the matching INDFx register. The MOVIW instruction will place the lower eight bits of the addressed word in the W register. Writes to the program memory cannot be performed via the INDF registers. Instructions that read the program memory via the FSR require one extra instruction cycle to complete. Example 4-2 demonstrates reading the program memory via an FSR.

The HIGH directive will set bit 7 if a label points to a location in the program memory.

EXAMPLE 4-2: ACCESSING PROGRAM MEMORY VIA FSR

```
constants
    RETLW DATA0        ;Index0 data
    RETLW DATA1        ;Index1 data
    RETLW DATA2
    RETLW DATA3
my_function
    ;… LOTS OF CODE…
    MOVLW   LOW constants
    MOVWF   FSR1L
    MOVLW   HIGH constants
    MOVWF   FSR1H
    MOVIW   0[FSR1]
;THE PROGRAM MEMORY IS IN W
```

4.1.1.3 NVMREG Access

The NVMREG interface allows read/write access to all locations accessible by the FSRs, User ID locations, and EEPROM. The NVMREG interface also provides read-only access to Device ID, Revision ID, and Configuration data. See **Section 11.4 "NVMREG Access"** for more information.

4.2 Data Memory Organization

The data memory is partitioned into 32 memory banks with 128 bytes in each bank. Each bank consists of (Figure 4-2):

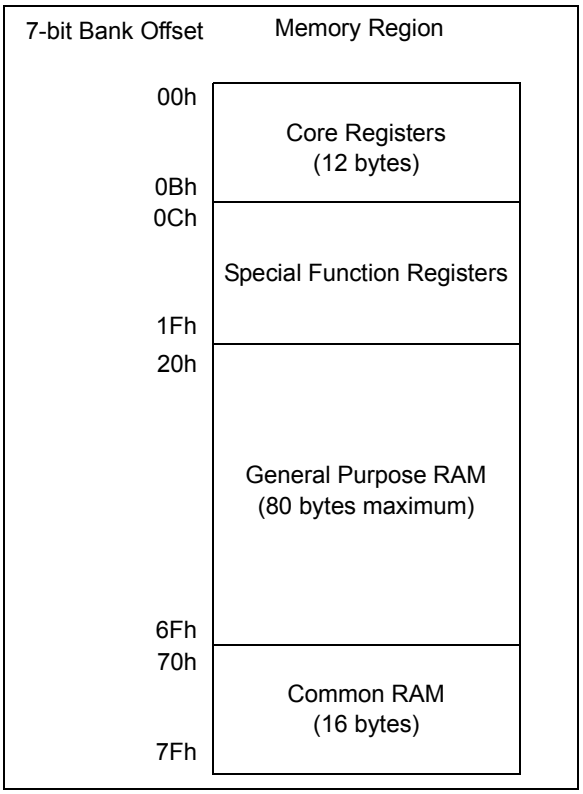
- 12 core registers
- Special Function Registers (SFR)
- Up to 80 bytes of General Purpose RAM (GPR)
- 16 bytes of common RAM

4.2.1 BANK SELECTION

The active bank is selected by writing the bank number into the Bank Select Register (BSR). Unimplemented memory will read as '0'. All data memory can be accessed either directly (via instructions that use the file registers) or indirectly via the two File Select Registers (FSR). See **Section 4.5 "Indirect Addressing""** for more information.

Data memory uses a 12-bit address. The upper five bits of the address define the Bank address and the lower seven bits select the registers/RAM in that bank.

FIGURE 4-2: BANKED MEMORY PARTITIONING



4.2.2 CORE REGISTERS

The core registers contain the registers that directly affect basic operation. The core registers occupy the first 12 addresses of every data memory bank (addresses x00h/x80h through x0Bh/x8Bh). These registers are listed below in Table 4-2. For detailed information, see Table 4-4.

TABLE 4-2: CORE REGISTERS

Addresses	BANKx
x00h or x80h	INDF0
x01h or x81h	INDF1
x02h or x82h	PCL
x03h or x83h	STATUS
x04h or x84h	FSR0L
x05h or x85h	FSR0H
x06h or x86h	FSR1L
x07h or x87h	FSR1H
x08h or x88h	BSR
x09h or x89h	WREG
x0Ah or x8Ah	PCLATH
x0Bh or x8Bh	INTCON

4.4 Stack

All devices have a 16-level x 15-bit wide hardware stack (refer to Figure 4-4 through Figure 4-7). The stack space is not part of either program or data space. The PC is PUSHed onto the stack when CALL or CALLW instructions are executed or an interrupt causes a branch. The stack is POPed in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer and does not cause a Reset when either a Stack Overflow or Underflow occur if the STVREN bit is programmed to '0' (Configuration Words). This means that after the stack has been PUSHed sixteen times, the seventeenth PUSH overwrites the value that was stored from the first PUSH. The eighteenth PUSH overwrites the second PUSH (and so on). The STKOVF and STKUNF flag bits will be set on an Overflow/Underflow, regardless of whether the Reset is enabled.

If the STVREN bit in Configuration Words is programmed to '1', the device will be Reset if the stack is PUSHed beyond the sixteenth level or POPed beyond the first level, setting the appropriate bits (STKOVF or STKUNF, respectively) in the PCON register.

Note 1:	There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the CALL, CALLW, RETURN, RETLW and RETFIE instructions or the vectoring to an interrupt address.

4.4.1 ACCESSING THE STACK

The stack is accessible through the TOSH, TOSL and STKPTR registers. STKPTR is the current value of the Stack Pointer. TOSH:TOSL register pair points to the TOP of the stack. Both registers are read/writable. TOS is split into TOSH and TOSL due to the 15-bit size of the PC. To access the stack, adjust the value of STKPTR, which will position TOSH:TOSL, then read/write to TOSH:TOSL. STKPTR is five bits to allow detection of overflow and underflow.

Note:	Care should be taken when modifying the STKPTR while interrupts are enabled.

During normal program operation, CALL, CALLW and Interrupts will increment STKPTR while RETLW, RETURN, and RETFIE will decrement STKPTR. At any time, STKPTR can be read to see how many levels remain available on the stack. The STKPTR always points at the currently used place on the stack. Therefore, a CALL or CALLW will increment the STKPTR and then write the PC, and a return will write the PC and then decrement the STKPTR.

Reference Figure 4-4 through Figure 4-7 for examples of accessing the stack.

5.3 Code Protection

Code protection allows the device to be protected from unauthorized access. Program memory protection and data memory are controlled independently. Internal access to the program memory is unaffected by any code protection setting.

5.3.1 PROGRAM MEMORY PROTECTION

The entire program memory space is protected from external reads and writes by the $\overline{CP}$ bit in Configuration Words. When $\overline{CP}$ = 0, external reads and writes of program memory are inhibited and a read will return all '0's. The CPU can continue to read program memory, regardless of the protection bit settings. Self-write writing the program memory is dependent upon the write protection setting. See **Section 5.4 "Write Protection"** for more information.

5.3.2 DATA MEMORY PROTECTION

The entire data EEPROM is protected from external reads and writes by the $\overline{CPD}$ bit in the Configuration Words. When $\overline{CPD}$ = 0, external reads and writes of EEPROM memory are inhibited and a read will return all '0's. The CPU can continue to read and write EEPROM memory, regardless of the protection bit settings.

5.4 Write Protection

Write protection allows the device to be protected from unintended self-writes. Applications, such as boot loader software, can be protected while allowing other regions of the program memory to be modified.

The WRT<1:0> bits in Configuration Words define the size of the program memory block that is protected.

5.5 User ID

Four memory locations (8000h-8003h) are designated as ID locations where the user can store checksum or other code identification numbers. These locations are readable and writable during normal execution. See **Section 11.4.7 "NVMREG EEPROM, User ID, Device ID and Configuration Word Access"** for more information on accessing these memory locations. For more information on checksum calculation, see the *"PIC16(L)F183XX Memory Programming Specification"* (DS40001738).

5.6 Device ID and Revision ID

The 14-bit device ID word is located at 8006h and the 14-bit revision ID is located at 8005h. These locations are read-only and cannot be erased or modified. See **Section 11.4.7 "NVMREG EEPROM, User ID, Device ID and Configuration Word Access"** for more information on accessing these memory locations.

Development tools, such as device programmers and debuggers, may be used to read the Device ID and Revision ID.

10.6 Register Definitions: Watchdog Control

REGISTER 10-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

U-0	U-0	R/W-0/0	R/W-1/1	R/W-0/0	R/W-1/1	R/W-1/1	R/W-0/0
—	—	WDTPS<4:0>(1)					SWDTEN
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-m/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **Unimplemented:** Read as '0'

bit 5-1 **WDTPS<4:0>:** Watchdog Timer Period Select bits(1)

Bit Value = Prescale Rate

11111 = Reserved. Results in minimum interval (1:32)
•
•
•
10011 = Reserved. Results in minimum interval (1:32)

10010 = 1:8388608 (2^{23}) (Interval 256s nominal)
10001 = 1:4194304 (2^{22}) (Interval 128s nominal)
10000 = 1:2097152 (2^{21}) (Interval 64s nominal)
01111 = 1:1048576 (2^{20}) (Interval 32s nominal)
01110 = 1:524288 (2^{19}) (Interval 16s nominal)
01101 = 1:262144 (2^{18}) (Interval 8s nominal)
01100 = 1:131072 (2^{17}) (Interval 4s nominal)
01011 = 1:65536 (Interval 2s nominal) (Reset value)
01010 = 1:32768 (Interval 1s nominal)
01001 = 1:16384 (Interval 512 ms nominal)
01000 = 1:8192 (Interval 256 ms nominal)
00111 = 1:4096 (Interval 128 ms nominal)
00110 = 1:2048 (Interval 64 ms nominal)
00101 = 1:1024 (Interval 32 ms nominal)
00100 = 1:512 (Interval 16 ms nominal)
00011 = 1:256 (Interval 8 ms nominal)
00010 = 1:128 (Interval 4 ms nominal)
00001 = 1:64 (Interval 2 ms nominal)
00000 = 1:32 (Interval 1 ms nominal)

bit 0 **SWDTEN:** Software Enable/Disable for Watchdog Timer bit

If WDTE<1:0> = 1x:
This bit is ignored.
If WDTE<1:0> = 01:
1 = WDT is turned on
0 = WDT is turned off
If WDTE<1:0> = 00:
This bit is ignored.

Note 1: Times are approximate. WDT time is based on 31 kHz LFINTOSC.

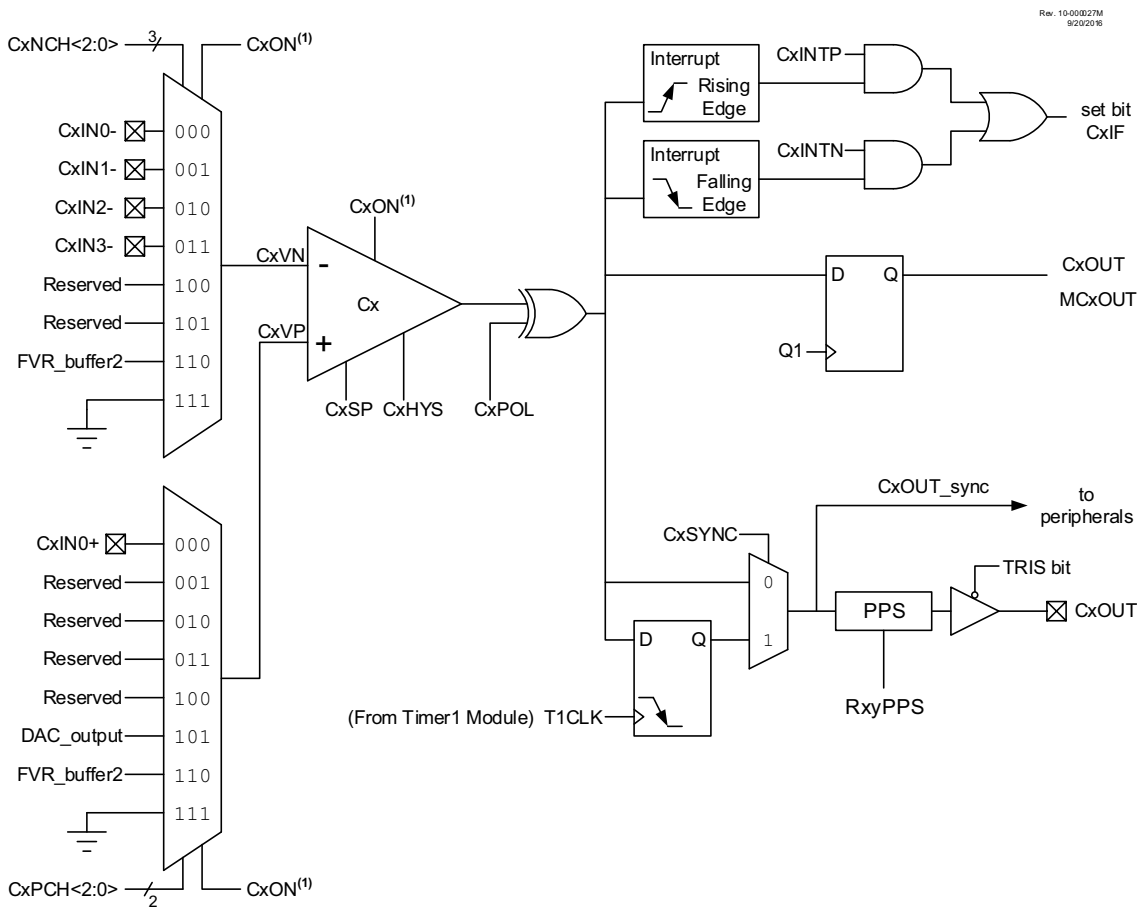
TABLE 13-1: SUMMARY OF REGISTERS ASSOCIATED WITH THE PPS MODULE (CONTINUED)

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
RXPPS	—	—	—	RXPPS<4:0>					162
CLCIN0PPS	—	—	—	CLCIN0PPS<4:0>					162
CLCIN1PPS	—	—	—	CLCIN1PPS<4:0>					162
CLCIN2PPS	—	—	—	CLCIN2PPS<4:0>					162
CLCIN3PPS	—	—	—	CLCIN3PPS<4:0>					162
RA0PPS	—	—	—	RA0PPS<4:0>					163
RA1PPS	—	—	—	RA1PPS<4:0>					163
RA2PPS	—	—	—	RA2PPS<4:0>					163
RA4PPS	—	—	—	RA4PPS<4:0>					163
RA5PPS	—	—	—	RA5PPS<4:0>					163
RB4PPS(1)	—	—	—	RB4PPS<4:0>					163
RB5PPS(1)	—	—	—	RB5PPS<4:0>					163
RB6PPS(1)	—	—	—	RB6PPS<4:0>					163
RB7PPS(1)	—	—	—	RB7PPS<4:0>					163
RC0PPS	—	—	—	RC0PPS<4:0>					163
RC1PPS	—	—	—	RC1PPS<4:0>					163
RC2PPS	—	—	—	RC2PPS<4:0>					163
RC3PPS	—	—	—	RC3PPS<4:0>					163
RC4PPS	—	—	—	RC4PPS<4:0>					163
RC5PPS	—	—	—	RC5PPS<4:0>					163
RC6PPS(1)	—	—	—	RC6PPS<4:0>					163
RC7PPS(1)	—	—	—	RC7PPS<4:0>					163

Legend: — = unimplemented, read as '0'. Shaded cells are unused by the PPS module.

Note 1: PIC16(L)F18345 only.

FIGURE 18-2: COMPARATOR MODULE SIMPLIFIED BLOCK DIAGRAM



Note 1: When CxON = 0, all multiplexer inputs are disconnected and the Comparator will produce a '0' at the output.

18.5 Comparator Interrupt

An interrupt can be generated when either the rising edge or falling edge detector detects a change in the output value of each comparator.

When either edge detector is triggered and its associated enable bit is set (CxINTP and/or CxINTN bits of the CMxCON1 register), the Corresponding Interrupt Flag bit (CxIF bit of the PIR2 register) will be set.

To enable the interrupt, you must set the following bits:

- CxON bit of the CMxCON0 register
- CxIE bit of the PIE2 register
- CxINTP bit of the CMxCON1 register (for a rising edge detection)
- CxINTN bit of the CMxCON1 register (for a falling edge detection)
- PEIE and GIE bits of the INTCON register

The associated interrupt flag bit, CxIF bit of the PIR2 register, must be cleared in software. If another edge is detected while this flag is being cleared, the flag will still be set at the end of the sequence.

Note:	Although a comparator is disabled, an interrupt can be generated by changing the output polarity with the CxPOL bit of the CMxCON0 register, or by switching the comparator on or off with the CxON bit of the CMxCON0 register.

18.6 Comparator Positive Input Selection

Configuring the CxPCH<2:0> bits of the CMxCON1 register directs an internal voltage reference or an analog pin to the non-inverting input of the comparator:

- CxIN0+ analog pin
- DAC output
- FVR (Fixed Voltage Reference)
- VSS (Ground)

See **Section 16.0 “Fixed Voltage Reference (FVR)”** for more information on the Fixed Voltage Reference module.

See **Section 24.0 “5-bit Digital-to-Analog Converter (DAC1) Module”** for more information on the DAC input signal.

Any time the comparator is disabled (CxON = 0), all comparator inputs are disabled.

18.7 Comparator Negative Input Selection

The CxNCH<2:0> bits of the CMxCON1 register direct an analog input pin and internal reference voltage or analog ground to the inverting input of the comparator:

- CxIN- pin
- FVR (Fixed Voltage Reference)
- Analog Ground

Note:	To use CxINy+ and CxINy- pins as analog input, the appropriate bits must be set in the ANSEL register and the corresponding TRIS bits must also be set to disable the output drivers.

18.8 Comparator Response Time

The comparator output is indeterminate for a period of time after the change of an input source or the selection of a new reference voltage. This period is referred to as the response time. The response time of the comparator differs from the settling time of the voltage reference. Therefore, both of these times must be considered when determining the total response time to a comparator input change. See the Comparator and Voltage Reference Specifications in Table 35-14 for more details.

21.0 CONFIGURABLE LOGIC CELL (CLC)

The Configurable Logic Cell (CLCx) provides programmable logic that operates outside the speed limitations of software execution. The logic cell takes up to 36 input signals and, through the use of configurable gates, reduces the 36 inputs to four logic lines that drive one of eight selectable single-output logic functions.

Input sources are a combination of the following:

- I/O pins
- Internal clocks
- Peripherals
- Register bits

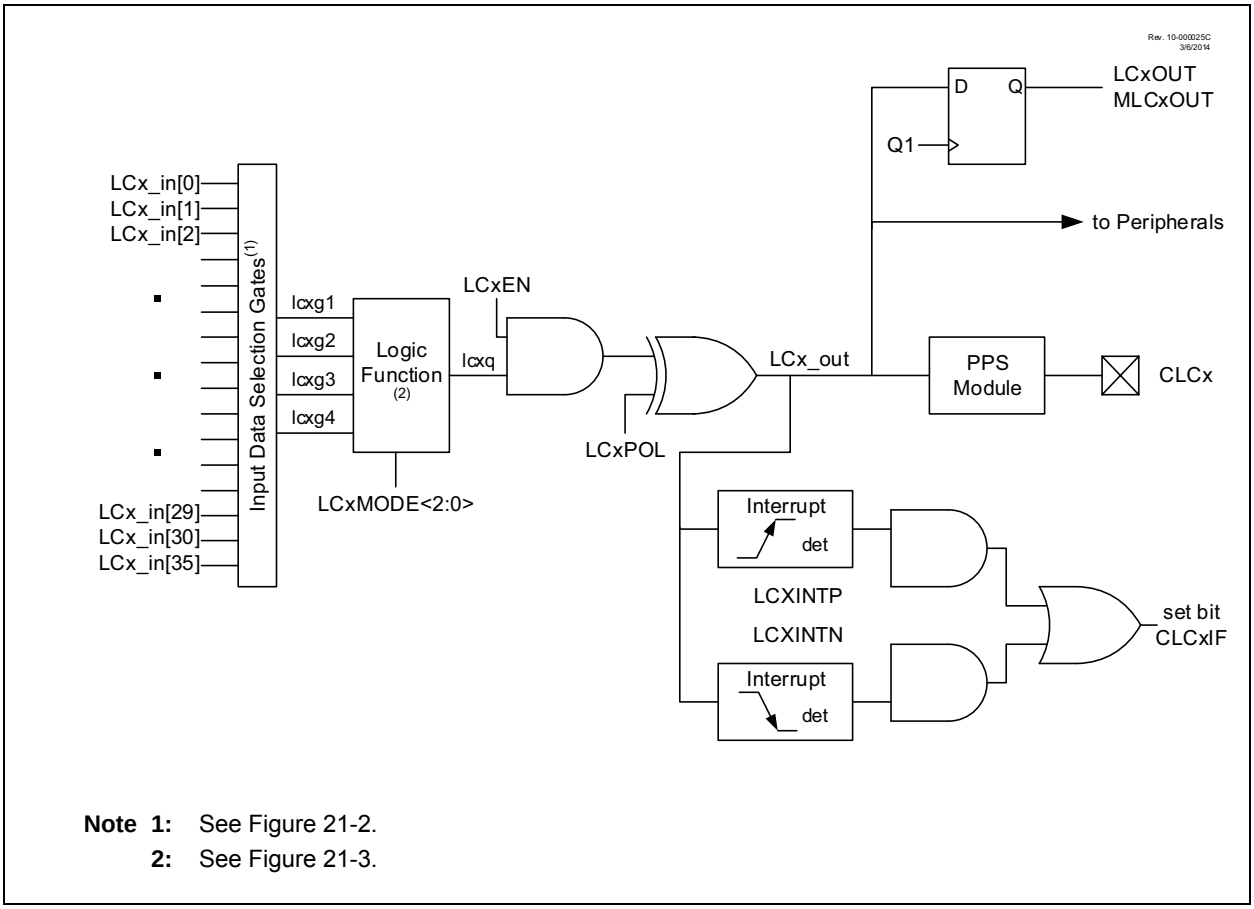
The output can be directed internally to peripherals and to an output pin.

Refer to Figure 21-1 for a simplified diagram showing signal flow through the CLCx.

Possible configurations include:

- Combinatorial Logic
  - AND
  - NAND
  - AND-OR
  - AND-OR-INVERT
  - OR-XOR
  - OR-XNOR
- Latches
  - S-R
  - Clocked D with Set and Reset
  - Transparent D with Set and Reset
  - Clocked J-K with Reset

FIGURE 21-1: CLCx SIMPLIFIED BLOCK DIAGRAM



Note 1: See Figure 21-2.
2: See Figure 21-3.

22.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- Port configuration
- Channel selection
- ADC voltage reference selection
- ADC conversion clock source
- Interrupt control
- Result formatting

22.1.1 PORT CONFIGURATION

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin should be configured for analog by setting the associated TRIS and ANSEL bits. Refer to **Section 12.0 "I/O Ports"** for more information.

Note:	Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

22.1.2 CHANNEL SELECTION

There are several channel selections available:

- Five PORTA pins (RA0-RA2, RA4-RA5)
- Four PORTB pins (RB4-RB7, PIC16(L)F18345 only)
- Six PORTC pins (RC0-RC5, PIC16(L)F18325)
- Eight PORTC pins (RC0-RC7, PIC16(L)F18345 only)
- Temperature Indicator
- DAC output
- Fixed Voltage Reference (FVR)
- VSS (ground)

The CHS<5:0> bits of the ADCON0 register (Register 22-1) determine which channel is connected to the sample and hold circuit.

When changing channels, a delay is required before starting the next conversion. Refer to **Section 22.2 "ADC Operation"** for more information.

Note:	It is recommended that when switching from an ADC channel of a higher voltage to a channel of a lower voltage, the software selects the VSS channel before switching to the channel of the lower voltage. If the ADC does not have a dedicated VSS input channel, the VSS selection (DAC1R<4:0> = b'00000') through the DAC output channel can be used. If the DAC is in use, a free input channel can be connected to VSS, and can be used in place of the DAC.

22.1.3 ADC VOLTAGE REFERENCE

The ADPREF<1:0> bits of the ADCON1 register provides control of the positive voltage reference. The positive voltage reference can be:

- VREF+ pin
- VDD
- FVR 2.048V
- FVR 4.096V (Not available on LF devices)

The ADNREF bit of the ADCON1 register provides control of the negative voltage reference. The negative voltage reference can be:

- VREF- pin
- VSS

See **Section 16.0 "Fixed Voltage Reference (FVR)"** for more details on the Fixed Voltage Reference.

22.1.4 CONVERSION CLOCK

The source of the conversion clock is software selectable via the ADCS<2:0> bits of the ADCON1 register. There are seven possible clock options:

- FOSC/2
- FOSC/4
- FOSC/8
- FOSC/16
- FOSC/32
- FOSC/64
- ADCRC (dedicated RC oscillator)

The time to complete one bit conversion is defined as TAD. One full 10-bit conversion requires 12 TAD periods as shown in Figure 22-2.

For correct conversion, the appropriate TAD specification must be met. Refer to Table 35-13 for more information. Table 22-1 gives examples of appropriate ADC clock selections.

Note:	Unless using the ADCRC, any changes in the system clock frequency will change the ADC clock frequency, which may adversely affect the ADC result.

TABLE 26-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER0

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
TRISA	—	—	TRISA5	TRISA4	—(2)	TRISA2	TRISA1	TRISA0	143
ANSELA	—	—	ANSA5	ANSA4	—	ANSA2	ANSA1	ANSA0	144
TRISB(1)	TRISB7	TRISB6	TRISB5	TRISB4	—	—	—	—	149
ANSELB(1)	ANSB7	ANSB6	ANSB5	ANSB4	—	—	—	—	150
TRISC	TRISC7(1)	TRISC6(1)	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	156
ANSELC	ANSC7(1)	ANSC6(1)	ANSC5	ANSC4	ANSC3	ANSC2	ANSC1	ANSC0	157
TMR0L	TMR0L<7:0>								279
TMR0H	TMR0H<7:0> or TMR0<15:8>								279
T0CON0	T0EN	—	T0OUT	T016BIT	T0OUTPS<3:0>				280
T0CON1	T0CS<2:0>			T0ASYNC	T0CKPS<3:0>				281
T0CKIPPS	—	—	—	T0CKIPPS<4:0>					162
TMR0PPS	—	—	—	TMR0PPS<4:0>					162
ADACT	—	—	—	ADACT<4:0>					246
CLCxSELy	—	—	LCxDyS<5:0>						229
T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/$\overline{\text{DONE}}$	T1GVAL	T1GSS<1:0>		293
INTCON	GIE	PEIE	—	—	—	—	—	INTEDG	101
PIR0	—	—	TMR0IF	IOCIF	—	—	—	INTF	107
PIE0	—	—	TMR0IE	IOCIE	—	—	—	INTE	102

Legend: — = Unimplemented location, read as '0'. Shaded cells are not used by the Timer0 module.

Note 1: PIC16(L)F18345 only.

2: Unimplemented, read as '1'.

REGISTER 27-2: TxGCON(1): TIMERx GATE CONTROL REGISTER

R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W/HC-0/u	R-x/x	R/W-0/u	R/W-0/u
TMRxGE	TxGPOL	TxGTM	TxGSPM	TxGGO/$\overline{\text{DONE}}$	TxGVAL	TxGSS<1:0>	
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HC = Bit is cleared by hardware

bit 7 **TMRxGE:** Timer1 Gate Enable bit

If TMRxON = 0:
This bit is ignored
If TMRxON = 1:
1 = Timerx counting is controlled by the Timer1 gate function
0 = Timerx is always counting

bit 6 **TxGPOL:** Timerx Gate Polarity bit

1 = Timerx gate is active-high (Timerx counts when gate is high)
0 = Timerx gate is active-low (Timerx counts when gate is low)

bit 5 **TxGTM:** Timerx Gate Toggle Mode bit

1 = Timerx Gate Toggle mode is enabled
0 = Timerx Gate Toggle mode is disabled and toggle flip-flop is cleared
Timerx gate flip-flop toggles on every rising edge.

bit 4 **TxGSPM:** Timerx Gate Single-Pulse Mode bit

1 = Timerx Gate Single-Pulse mode is enabled and is controlling Timerx gate
0 = Timerx Gate Single-Pulse mode is disabled

bit 3 **TxGGO/$\overline{\text{DONE}}$:** Timerx Gate Single-Pulse Acquisition Status bit

1 = Timerx gate single-pulse acquisition is ready, waiting for an edge
0 = Timerx gate single-pulse acquisition has completed or has not been started
This bit is automatically cleared when TxGSPM is cleared

bit 2 **TxGVAL:** Timerx Gate Value Status bit

Indicates the current state of the Timerx gate, latched at Q1, provided to TMRxH:TMRxL
Unaffected by Timerx Gate Enable (TMRxGE)

bit 1-0 **TxGSS<1:0>:** Timerx Gate Source Select bits

11 = Comparator 2 optionally synchronized output
10 = Comparator 1 optionally synchronized output
01 = Timer0 overflow output
00 = Timerx gate pin

Note 1: 'x' refers to either '1', '3' or '5' for the respective Timer1/3/5 registers.

29.3 Compare Mode

Compare mode makes use of the 16-bit Timer1/3/5 resource. The 16-bit value of the CCPRxH:CCPRxL register pair is constantly compared against the 16-bit value of the TMR1/3/5H:TMR1/3/5L register pair. When a match occurs, one of the following events can occur:

- Toggle the CCPx output
- Set the CCPx output
- Clear the CCPx output
- Generate an Auto-conversion Trigger
- Generate a Software Interrupt

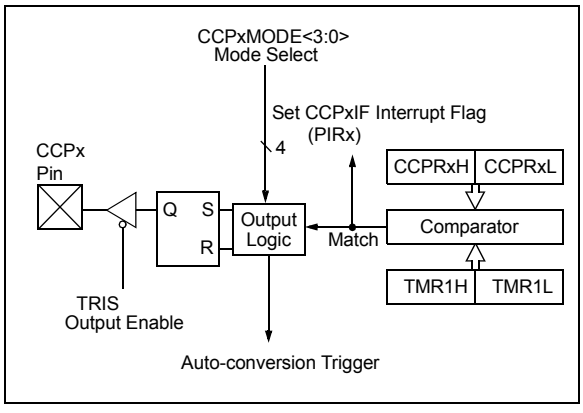
The action on the pin is based on the value of the CCPxMODE<3:0> control bits of the CCPxCON register. At the same time, the interrupt flag CCPxIF bit is set, and an ADC conversion can be triggered, if selected.

All Compare modes can generate an interrupt and trigger an ADC conversion.

Figure 29-2 shows a simplified diagram of the compare operation.

Note:	When the CCP is configured in Compare mode using the 'toggle output on match' setting (CCPxMODE<3:0> bits = 0010) and the reference timer is set for an input clock prescale other than 1:1, the output of the CCP will toggle multiple times until finally settling a '0' logic level. To avoid this, the timer input clock prescale select bits must be set to a 1:1 ratio (TxCKPS = 00).

FIGURE 29-2: COMPARE MODE OPERATION BLOCK DIAGRAM



29.3.1 CCPX PIN CONFIGURATION

The user must configure the CCPx pin as an output by clearing the associated TRIS bit and defining the appropriate output pin through the RxyPPS registers. See **Section 13.0 "Peripheral Pin Select (PPS) Module"** for more details.

Note:	Clearing the CCPxCON register will force the CCPx compare output latch to the default low level. This is not the PORT I/O data latch.

29.3.2 TIMER1/3/5 MODE RESOURCE

In Compare mode, Timer1/3/5 must be running in either Timer mode or Synchronized mode. The compare operation may not work in Asynchronous mode.

See **Section 27.0 "Timer1/3/5 Module with Gate Control"** for more information on configuring Timer1/3/5.

Note:	Clocking Timer1/3/5 from the system clock (FOSC) should not be used in Compare mode. In order for Compare mode to recognize the trigger event on the CCPx pin, Timer1/3/5 must be clocked from the instruction clock (FOSC/4) or from an external clock source.

29.3.3 AUTO-CONVERSION TRIGGER

All CCPx modes set the CCP interrupt flag (CCPxIF). When this flag is set as a match occurs, an auto-conversion trigger can occur if the CCP module is selected as the conversion trigger source.

Refer to **Section 22.2.5 "Auto-Conversion Trigger"** for more information.

Note:	Removing the Match condition by changing the contents of the CCPRxH and CCPRxL register pair, between the clock edge that generates the Auto-conversion Trigger and the clock edge that generates the Timer Reset, will preclude the Reset from occurring.

29.3.4 COMPARE DURING SLEEP

Since FOSC is shut down during Sleep mode, the Compare mode will not function properly during Sleep, unless the timer is running. The device will wake on interrupt (if enabled).

29.3.5 COMPARE INTERRUPTS

The CCPxIF interrupt flag will be set when a match between the CCPRxH:CCPRxL register pair and the TMR1/3/5H:TMR1/3/5L register pair occurs. If the device is in Sleep and interrupts are enabled (CCPxIE = 1), the device will wake up, assuming Timer1 is operating during Sleep.

TABLE 30-2: MSSP CLOCK RATE W/BRG

FOSC	FCY	BRG Value	FCLOCK (2 Rollovers of BRG)
32 MHz	8 MHz	13h	400 kHz
32 MHz	8 MHz	19h	308 kHz
32 MHz	8 MHz	4Fh	100 kHz
16 MHz	4 MHz	09h	400 kHz
16 MHz	4 MHz	0Ch	308 kHz
16 MHz	4 MHz	27h	100 kHz
4 MHz	1 MHz	09h	100 kHz

Note: Refer to the I/O port electrical specifications in Table 35-4 to ensure the system is designed to support IOL requirements.

34.0 INSTRUCTION SET SUMMARY

Each instruction is a 14-bit word containing the operation code (opcode) and all required operands. The opcodes are broken into three broad categories.

- Byte Oriented
- Bit Oriented
- Literal and Control

The literal and control category contains the most varied instruction word format.

Table 34-3 lists the instructions recognized by the MPASM™ assembler.

All instructions are executed within a single instruction cycle, with the following exceptions, which may take two or three cycles:

- Subroutine entry takes two cycles (CALL, CALLW)
- Returns from interrupts or subroutines take two cycles (RETURN, RETLW, RETFIE)
- Program branching takes two cycles (GOTO, BRA, BRW, BTFSS, BTFSC, DECFSZ, INCSFZ)
- One additional instruction cycle will be used when any instruction references an indirect file register and the file select register is pointing to program memory.

One instruction cycle consists of 4 oscillator cycles; for an oscillator frequency of 4 MHz, this gives a nominal instruction execution rate of 1 MHz.

All instruction examples use the format '0xhh' to represent a hexadecimal number, where 'h' signifies a hexadecimal digit.

34.1 Read-Modify-Write Operations

Any write instruction that specifies a file register as part of the instruction performs a Read-Modify-Write (R-M-W) operation. The register is read, the data is modified, and the result is stored according to either the working (W) register, or the originating file register, depending on the state of the destination designator 'd' (see Table 34-1 for more information). A read operation is performed on a register even if the instruction writes to that register.

TABLE 34-1: OPCODE FIELD DESCRIPTIONS

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f.
n	FSR or INDF number. (0-1)
mm	Pre-post increment-decrement mode selection

TABLE 34-2: ABBREVIATION DESCRIPTIONS

Field	Description
PC	Program Counter
$\overline{TO}$	Time-Out bit
C	Carry bit
DC	Digit Carry bit
Z	Zero bit
$\overline{PD}$	Power-Down bit

34.2 Instruction Descriptions

ADDFSR — Add Literal to FSRn

Syntax:	[*label*] ADDFSR FSRn, k
Operands:	-32 ≤ k ≤ 31 n ∈ [0, 1]
Operation:	FSR(n) + k → FSR(n)
Status Affected:	None
Description:	The signed 6-bit literal 'k' is added to the contents of the FSRnH:FSRnL register pair. FSRn is limited to the range 0000h-FFFFh. Moving beyond these bounds will cause the FSR to wrap-around.

ADDLW — Add literal and W

Syntax:	[*label*] ADDLW k
Operands:	0 ≤ k ≤ 255
Operation:	(W) + k → (W)
Status Affected:	C, DC, Z
Description:	The contents of the W register are added to the 8-bit literal 'k' and the result is placed in the W register.

ADDWF — Add W and f

Syntax:	[*label*] ADDWF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) + (f) → (destination)
Status Affected:	C, DC, Z
Description:	Add the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

ADDWFC — ADD W and CARRY bit to f

Syntax:	[*label*] ADDWFC f {,d}
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) + (f) + (C) → dest
Status Affected:	C, DC, Z
Description:	Add W, the Carry flag and data memory location 'f'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed in data memory location 'f'.

ANDLW — AND literal with W

Syntax:	[*label*] ANDLW k
Operands:	0 ≤ k ≤ 255
Operation:	(W) .AND. (k) → (W)
Status Affected:	Z
Description:	The contents of W register are AND'ed with the 8-bit literal 'k'. The result is placed in the W register.

ANDWF — AND W with f

Syntax:	[*label*] ANDWF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) .AND. (f) → (destination)
Status Affected:	Z
Description:	AND the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

ASRF — Arithmetic Right Shift

Syntax:	[*label*] ASRF f {,d}
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(f<7>)→ dest<7> (f<7:1>) → dest<6:0>, (f<0>) → C,
Status Affected:	C, Z
Description:	The contents of register 'f' are shifted one bit to the right through the Carry flag. The MSb remains unchanged. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f'.

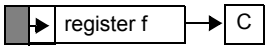
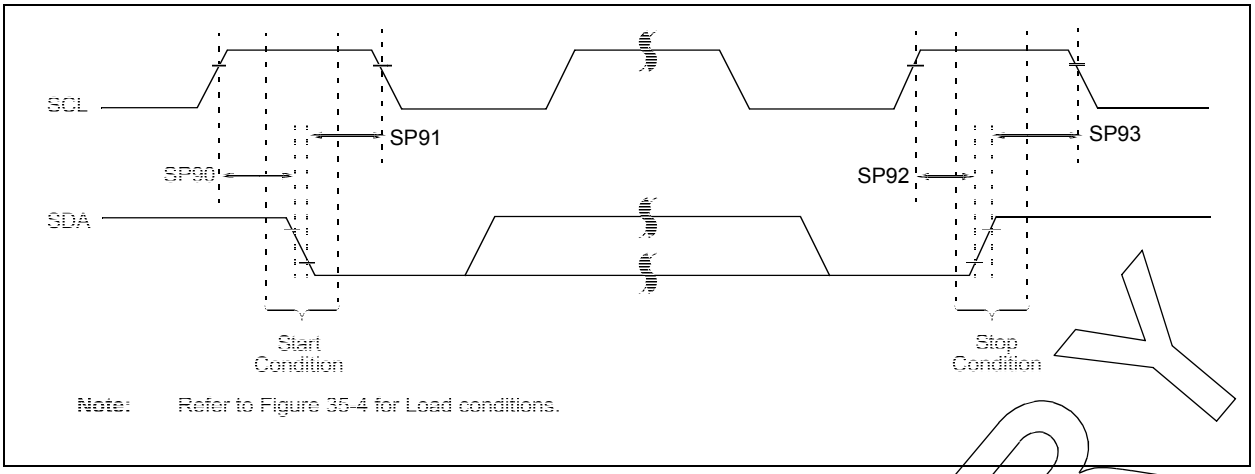


FIGURE 35-21: I²C BUS START/STOP BITS TIMING



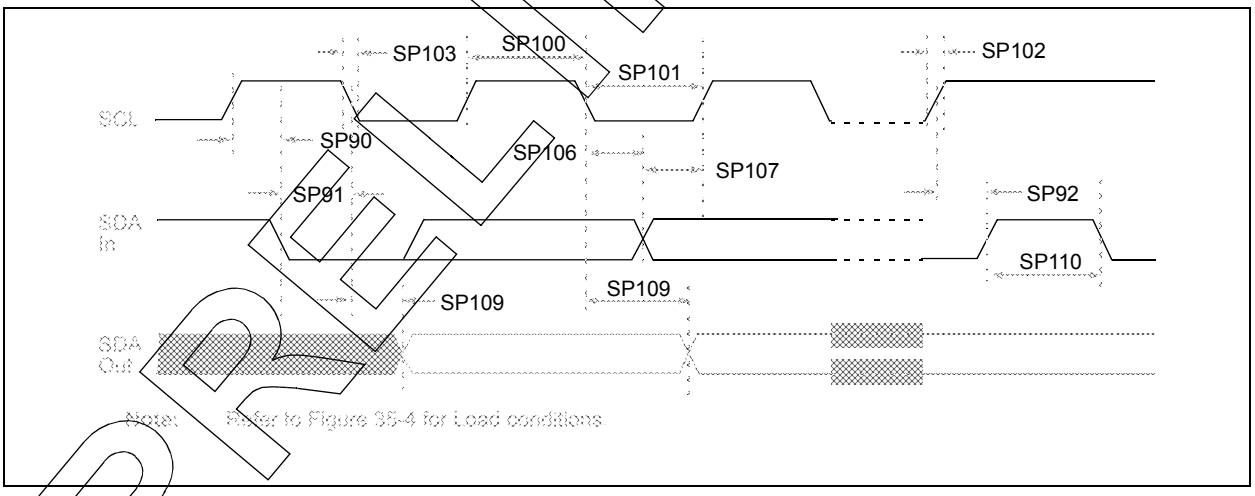
Note: Refer to Figure 35-4 for Load conditions.

TABLE 35-23: I²C BUS START/STOP BITS CHARACTERISTICS

Standard Operating Conditions (unless otherwise stated)								
Param. No.	**Symbol**	**Characteristic**		**Min.**	**Typ.**	**Max.**	**Units**	**Conditions**
SP90*	TSU:STA	Start condition Setup time	100 kHz mode	4700	—	—	ns	Only relevant for Repeated Start condition
			400 kHz mode	600	—	—		
SP91*	THD:STA	Start condition Hold time	100 kHz mode	4000	—	—	ns	After this period, the first clock pulse is generated
			400 kHz mode	600	—	—		
SP92*	TSU:STO	Stop condition Setup time	100 kHz mode	4700	—	—	ns	
			400 kHz mode	600	—	—		
SP93	THD:STO	Stop condition Hold time	100 kHz mode	4000	—	—	ns	
			400 kHz mode	600	—	—		

* These parameters are characterized but not tested.

FIGURE 35-22: I²C BUS DATA TIMING



Note: Refer to Figure 35-4 for Load conditions.

37.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
  - MPLAB Xpress IDE Software
  - Microchip Code Configurator (MCC)
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/ MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICkit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits
- Third-party development tools

37.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

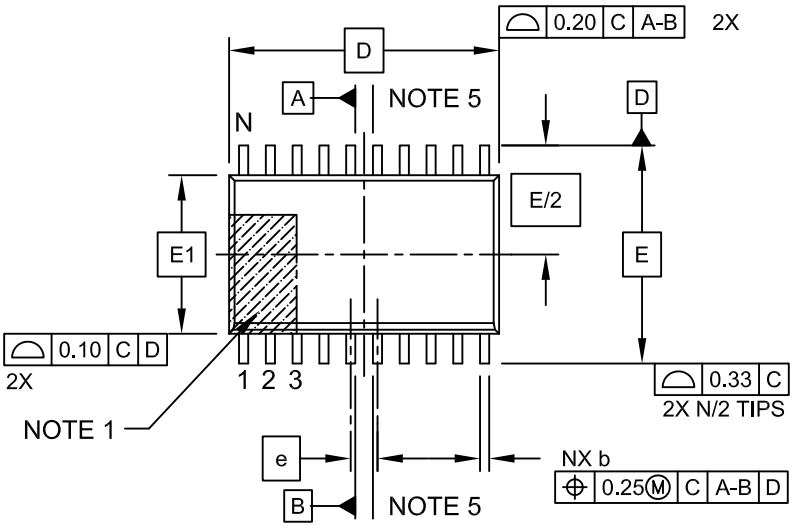
- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

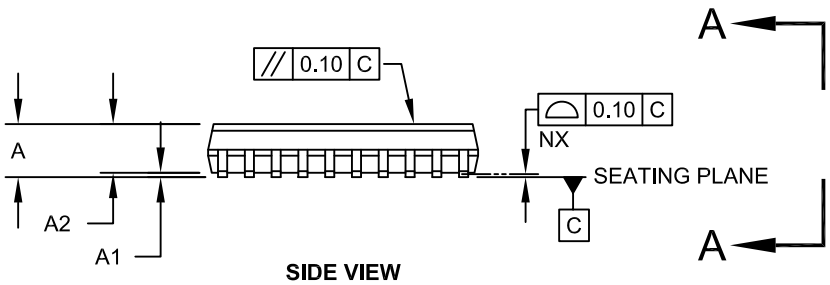
- Local file history feature
- Built-in support for Bugzilla issue tracker

20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

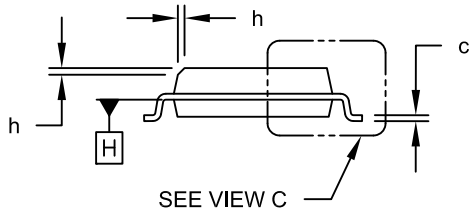
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



TOP VIEW



SIDE VIEW



VIEW A-A

Microchip Technology Drawing C04-094C Sheet 1 of 2