

Welcome to **E-XFL.COM**

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	16MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	3
Program Memory Size	448B (256 x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 3x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-VFDFN Exposed Pad
Supplier Device Package	8-DFN (2x3)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic10lf320t-i-mc

Table of Contents

1.0	Device Overview	6
2.0	Memory Organization	9
3.0	Device Configuration	19
4.0	Oscillator Module	24
5.0	Resets	28
6.0	Interrupts	35
7.0	Power-Down Mode (Sleep)	44
8.0	Watchdog Timer	46
9.0	Flash Program Memory Control	50
10.0	I/O Port	67
11.0	Interrupt-On-Change	73
12.0	Fixed Voltage Reference (FVR)	77
13.0	Internal Voltage Regulator (IVR)	79
14.0	Temperature Indicator Module	81
15.0	Analog-to-Digital Converter (ADC) Module	83
	Timero Module	
17.0	Timer2 Module	96
18.0	Pulse-Width Modulation (PWM) Module	98
19.0	Configurable Logic Cell (CLC)	. 104
20.0	Numerically Controlled Oscillator (NCO) Module	. 119
21.0	Complementary Waveform Generator (CWG) Module	. 129
22.0	In-Circuit Serial Programming™ (ICSP™)	. 144
23.0	Instruction Set Summary	. 147
24.0	Electrical Specifications	. 156
25.0	DC and AC Characteristics Graphs and Charts	. 176
26.0	Development Support	. 177
27.0	Packaging Information	. 181
Appe	ndix A: Data Sheet Revision History	. 189

2.0 MEMORY ORGANIZATION

These devices contain the following types of memory:

- · Program Memory
 - Configuration Word
 - Device ID
 - User ID
 - Flash Program Memory
- · Data Memory
 - Core Registers
 - Special Function Registers
 - General Purpose RAM
 - Common RAM

The following features are associated with access and control of program memory and data memory:

- PCL and PCLATH
- Stack
- · Indirect Addressing

2.1 Program Memory Organization

The mid-range core has a 13-bit program counter capable of addressing $8K \times 14$ program memory space. This device family only implements up to 512 words of the 8K program memory space. Table 2-1 shows the memory sizes implemented for the PIC10(L)F320/322 family. Accessing a location above these boundaries will cause a wrap-around within the implemented memory space. The Reset vector is at 0000h and the interrupt vector is at 0004h (see Figures 2-1, and 2-2).

TABLE 2-1: DEVICE SIZES AND ADDRESSES

Device	Device Program Memory Space (Words)		High-Endurance Flash Memory Address Range ⁽¹⁾
PIC10(L)F320	256	00FFh	0080h-00FFh
PIC10(L)F322	512	01FFh	0180h-01FFh

Note 1: High-endurance Flash applies to low byte of each address in the range.

FIGURE 2-1: PROGRAM MEMORY MAP AND STACK FOR PIC10(L)F320

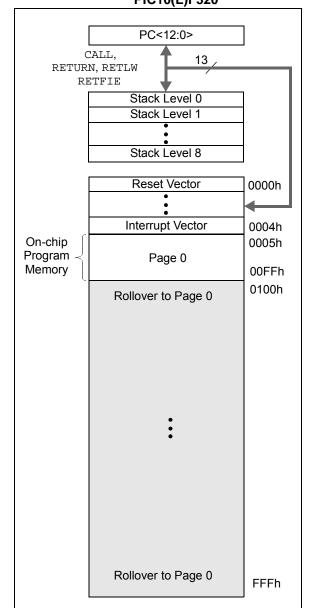
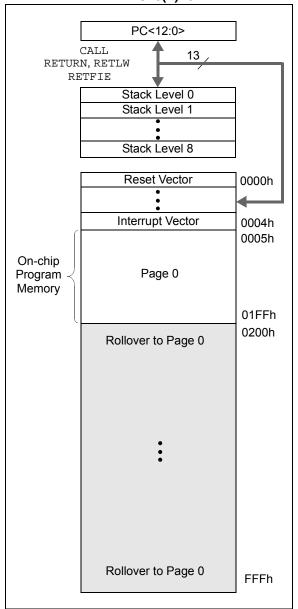


FIGURE 2-2: PROGRAM MEMORY MAP AND STACK FOR PIC10(L)F322



REGISTER 2-1: STATUS: STATUS REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R-1/q	R-1/q	R/W-x/u	R/W-x/u	R/W-x/u
IRP	RP1	RP0	TO	PD	Z	DC	С
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7	IRP: Reserved ⁽²⁾
bit 6-5	RP<1:0>: Reserved ⁽²⁾
bit 4	TO: Time-out bit
	1 = After power-up, CLRWDT instruction or SLEEP instruction0 = A WDT time-out occurred
bit 3	PD: Power-Down bit
	1 = After power-up or by the CLRWDT instruction0 = By execution of the SLEEP instruction
bit 2	Z: Zero bit
	1 = The result of an arithmetic or logic operation is zero
	0 = The result of an arithmetic or logic operation is not zero
bit 1	DC: Digit Carry/Borrow bit (ADDWF, ADDLW, SUBLW, SUBWF instructions)(1)
	1 = A carry-out from the 4th low-order bit of the result occurred
	0 = No carry-out from the 4th low-order bit of the result
bit 0	C: Carry/Borrow bit (ADDWF, ADDLW, SUBLW, SUBWF instructions)(1)
	1 = A carry-out from the Most Significant bit of the result occurred
	0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (RRF, RLF) instructions, this bit is loaded with either the high or low-order bit of the source register.

2: Maintain as '0'.

4.6 External Clock Mode

4.6.1 EC MODE

The External Clock (EC) mode allows an externally generated logic level as the system clock source. When operating in this mode, an external clock source is connected to the CLKIN input.

TABLE 4-1: SUMMARY OF REGISTERS ASSOCIATED WITH CLOCK SOURCES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CLKRCON	_	CLKROE	_	_	_	_	_	_	26
OSCCON	_		IRCF<2:0>		HFIOFR	_	LFIOFR	HFIOFS	26

Legend: x = unknown, u = unchanged, - = unimplemented locations read as '0'. Shaded cells are not used by ECWG.

TABLE 4-2: SUMMARY OF CONFIGURATION WORD WITH CLOCK SOURCES

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIC	13:8	_	_	_	WRT	WRT<1:0>		LPBOR	LVP	20
CONFIG	7:0	CP	MCLRE	PWRTE	WDTE	<1:0>	BOREI	N<1:0>	FOSC	20

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by clock sources.

5.0 RESETS

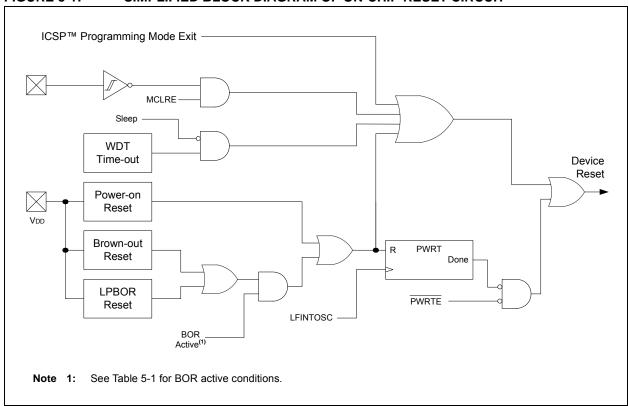
There are multiple ways to reset this device:

- Power-On Reset (POR)
- Brown-Out Reset (BOR)
- Low-Power Brown-Out Reset (LPBOR)
- MCLR Reset
- WDT Reset
- · Programming mode exit

To allow VDD to stabilize, an optional Power-up Timer can be enabled to extend the Reset time after a BOR or POR event.

A simplified block diagram of the On-Chip Reset Circuit is shown in Figure 5-1.

FIGURE 5-1: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT



8.6 Watchdog Control Register

Legend:

R = Readable bit

u = Bit is unchanged

REGISTER 8-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

W = Writable bit

x = Bit is unknown

U-0	U-0	R/W-0/0	R/W-1/1	R/W-0/0	R/W-1/1	R/W-1/1	R/W-0/0			
_	_		WDTPS<4:0>							
bit 7							bit 0			

U = Unimplemented bit, read as '0'

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared bit 7-6 Unimplemented: Read as '0' bit 5-1 WDTPS<4:0>: Watchdog Timer Period Select bits(1) Bit Value = Prescale Rate 11111 = Reserved. Results in minimum interval (1:32) 10011 = Reserved. Results in minimum interval (1:32) $10010 = 1:8388608 (2^{23}) (Interval 256s nominal)$ $10001 = 1:4194304 (2^{22}) (Interval 128s nominal)$ $10000 = 1:2097152 (2^{21})$ (Interval 64s nominal) $01111 = 1:1048576 (2^{20}) (Interval 32s nominal)$ $01110 = 1.524288 (2^{19}) (Interval 16s nominal)$ $01101 = 1:262144 (2^{18})$ (Interval 8s nominal) $01100 = 1:131072 (2^{17}) (Interval 4s nominal)$ 01011 = 1:65536 (Interval 2s nominal) (Reset value) 01010 = 1:32768 (Interval 1s nominal) 01001 = 1:16384 (Interval 512 ms nominal) 01000 = 1:8192 (Interval 256 ms nominal) 00111 = 1:4096 (Interval 128 ms nominal) 00110 = 1:2048 (Interval 64 ms nominal) 00101 = 1:1024 (Interval 32 ms nominal) 00100 = 1:512 (Interval 16 ms nominal) 00011 = 1:256 (Interval 8 ms nominal) 00010 = 1:128 (Interval 4 ms nominal) 00001 = 1:64 (Interval 2 ms nominal) 00000 = 1:32 (Interval 1 ms nominal) bit 0 SWDTEN: Software Enable/Disable for Watchdog Timer bit <u>If WDTE<1:0> = 00:</u> This bit is ignored. If WDTE<1:0> = 01: 1 = WDT is turned on

Note 1: Times are approximate. WDT time is based on 31 kHz LFINTOSC.

0 = WDT is turned off If WDTE<1:0> = 1x: This bit is ignored.

TABLE 8-3: SUMMARY OF REGISTERS ASSOCIATED WITH WATCHDOG TIMER

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
OSCCON	_		IRCF<2:0>			_	LFIOFR	HFIOFS	26
STATUS	IRP	RP1	RP0	TO	PD	Z	DC	С	13
WDTCON	_	_		\		SWDTEN	48		

Legend: x = unknown, u = unchanged, – = unimplemented locations read as '0'. Shaded cells are not used by Watchdog Timer.

TABLE 8-4: SUMMARY OF CONFIGURATION WORD WITH WATCHDOG TIMER

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIC	13:8			_	WRT	WRT<1:0>		LPBOR	LVP	20
CONFIG	7:0	CP	MCLRE	PWRTE	WDTE	WDTE<1:0>		N<1:0>	FOSC	20

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Watchdog Timer.

9.2.3 ERASING FLASH PROGRAM MEMORY

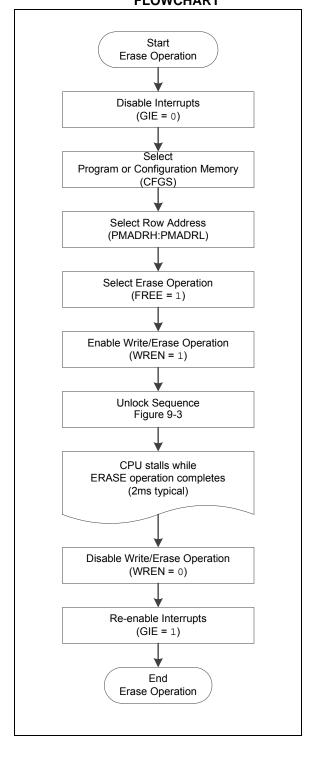
While executing code, program memory can only be erased by rows. To erase a row:

- 1. Load the PMADRH:PMADRL register pair with any address within the row to be erased.
- 2. Clear the CFGS bit of the PMCON1 register.
- Set the FREE and WREN bits of the PMCON1 register.
- 4. Write 55h, then AAh, to PMCON2 (Flash programming unlock sequence).
- 5. Set control bit WR of the PMCON1 register to begin the erase operation.

See Example 9-2.

After the "BSF PMCON1, WR" instruction, the processor requires two cycles to set up the erase operation. The user must place two NOP instructions after the WR bit is set. The processor will halt internal operations for the typical 2 ms erase time. This is not Sleep mode as the clocks and peripherals will continue to run. After the erase cycle, the processor will resume operation with the third instruction after the PMCON1 write instruction.

FIGURE 9-4: FLASH PROGRAM MEMORY ERASE FLOWCHART



10.0 I/O PORT

Depending on which peripherals are enabled, some or all of the pins may not be available as general purpose I/O. In general, when a peripheral is enabled on a port pin, that pin cannot be used as a general purpose output. However, the pin can still be read.

PORTA has three standard registers for its operation. These registers are:

- TRISA register (data direction)
- PORTA register (reads the levels on the pins of the device)
- LATA register (output latch)

Some ports may have one or more of the following additional registers. These registers are:

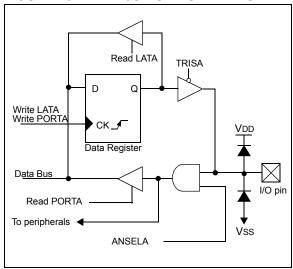
- · ANSELA (analog select)
- WPUA (weak pull-up)

The Data Latch (LATA register) is useful for read-modify-write operations on the value that the I/O pins are driving.

A write operation to the LATA register has the same effect as a write to the corresponding PORTA register. A read of the LATA register reads of the values held in the I/O PORT latches, while a read of the PORTA register reads the actual I/O pin value.

Ports that support analog inputs have an associated ANSELA register. When an ANSEL bit is set, the digital input buffer associated with that bit is disabled. Disabling the input buffer prevents analog signal levels on the pin between a logic high and low from causing excessive current in the logic input circuitry. A simplified model of a generic I/O port, without the interfaces to other peripherals, is shown in Figure 10-1.

FIGURE 10-1: I/O PORT OPERATION



EXAMPLE 10-1: INITIALIZING PORTA

```
; This code example illustrates
; initializing the PORTA register. The
; other ports are initialized in the same
; manner.
BANKSEL
          PORTA
                          ;not required on devices with 1 Bank of SFRs
CLRF
          PORTA
                          ;Init PORTA
BANKSEL
          LATA
                          ;not required on devices with 1 Bank of SFRs
CLRF
          LATA
BANKSEL
          ANSELA
                          ;not required on devices with 1 Bank of SFRs
CLRF
          ANSELA
                          ;digital I/O
BANKSEL
          TRISA
                          ;not required on devices with 1 Bank of SFRs
MOVLW
          B'00000011'
                          ;Set RA<1:0> as inputs
MOVWF
          TRISA
                          ;and set RA<2:3> as
                          ;outputs
```

11.0 INTERRUPT-ON-CHANGE

The PORTA pins can be configured to operate as Interrupt-On-Change (IOC) pins. An interrupt can be generated by detecting a signal that has either a rising edge or a falling edge. Any individual PORTA pin, or combination of PORTA pins, can be configured to generate an interrupt. The Interrupt-on-change module has the following features:

- Interrupt-on-Change enable (Master Switch)
- Individual pin configuration
- · Rising and falling edge detection
- · Individual pin interrupt flags

Figure 11-1 is a block diagram of the IOC module.

11.1 Enabling the Module

To allow individual PORTA pins to generate an interrupt, the IOCIE bit of the INTCON register must be set. If the IOCIE bit is disabled, the edge detection on the pin will still occur, but an interrupt will not be generated.

11.2 Individual Pin Configuration

For each PORTA pin, a rising edge detector and a falling edge detector are present. To enable a pin to detect a rising edge, the associated IOCAPx bit of the IOCAP register is set. To enable a pin to detect a falling edge, the associated IOCANx bit of the IOCAN register is set.

A pin can be configured to detect rising and falling edges simultaneously by setting both the IOCAPx bit and the IOCANx bit of the IOCAP and IOCAN registers, respectively.

11.3 Interrupt Flags

The IOCAFx bits located in the IOCAF register are status flags that correspond to the interrupt-on-change pins of PORTA. If an expected edge is detected on an appropriately enabled pin, then the status flag for that pin will be set, and an interrupt will be generated if the IOCIE bit is set. The IOCIF bit of the INTCON register reflects the status of all IOCAFx bits.

11.4 Clearing Interrupt Flags

The individual status flags, (IOCAFx bits), can be cleared by resetting them to zero. If another edge is detected during this clearing operation, the associated status flag will be set at the end of the sequence, regardless of the value actually being written.

In order to ensure that no detected edge is lost while clearing flags, only AND operations masking out known changed bits should be performed. The following sequence is an example of what should be performed.

EXAMPLE 11-1: CLEARING INTERRUPT FLAGS

11.5 Operation in Sleep

The interrupt-on-change interrupt sequence will wake the device from Sleep mode, if the IOCIE bit is set.

If an edge is detected while in Sleep mode, the IOCAF register will be updated prior to the first instruction executed out of Sleep.

11.6 Interrupt-On-Change Registers

REGISTER 11-1: IOCAP: INTERRUPT-ON-CHANGE PORTA POSITIVE EDGE REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
_	_	_	_	IOCAP3	IOCAP2	IOCAP1	IOCAP0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7-4 **Unimplemented**: Read as '0'.

bit 3-0 IOCAP<3:0>: Interrupt-on-Change PORTA Positive Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a positive going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. (1)

0 = Interrupt-on-Change disabled for the associated pin.

Note 1: Interrupt-on-change also requires that the IOCIE bit of the INTCON register be set (Register 6-1).

REGISTER 11-2: IOCAN: INTERRUPT-ON-CHANGE PORTA NEGATIVE EDGE REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
_	_	_	_	IOCAN3	IOCAN2	IOCAN1	IOCAN0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7-4 **Unimplemented**: Read as '0'.

bit 3-0 IOCAN<3:0>: Interrupt-on-Change PORTA Negative Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a negative going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. (1)

0 = Interrupt-on-Change disabled for the associated pin.

Note 1: Interrupt-on-change also requires that the IOCIE bit of the INTCON register be set (Register 6-1).

REGISTER 11-3: IOCAF: INTERRUPT-ON-CHANGE PORTA FLAG REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
_	_	_	_	IOCAF3	IOCAF2	IOCAF1	IOCAF0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared HS - Bit is set in hardware

bit 7-4 Unimplemented: Read as '0'.

bit 3-0 IOCAF<3:0>: Interrupt-on-Change PORTA Flag bits

1 = An enable change was detected on the associated pin.
Set when IOCAPx = 1 and a rising edge was detected on RAx, or when IOCANx = 1 and a falling edge was detected on RAx. (1)

0 = No change was detected, or the user cleared the detected change.

Note 1: Interrupt-on-change also requires that the IOCIE bit of the INTCON register be set (Register 6-1).

TABLE 11-1: SUMMARY OF REGISTERS ASSOCIATED WITH INTERRUPT-ON-CHANGE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	40
IOCAF	_	_	_	_	IOCAF3	IOCAF2	IOCAF1	IOCAF0	76
IOCAN	_	_	_	_	IOCAN3	IOCAN2	IOCAN1	IOCAN0	75
IOCAP	_	_	_	_	IOCAP3	IOCAP2	IOCAP1	IOCAP0	75
TRISA	_	_	_	_	(1)	TRISA2	TRISA1	TRISA0	69

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Interrupt-on-Change.

Note 1: Unimplemented, read as '1'.

12.0 FIXED VOLTAGE REFERENCE (FVR)

The Fixed Voltage Reference, or FVR, is a stable voltage reference, independent of VDD, with 1.024V, 2.048V or 4.096V selectable output levels. The output of the FVR can be configured to supply a reference voltage to the following:

· ADC input channel

The FVR can be enabled by setting the FVREN bit of the FVRCON register.

12.1 Independent Gain Amplifiers

The output of the FVR supplied to the ADC is routed through an independent programmable gain amplifier. The amplifier can be configured to amplify the reference voltage by 1x, 2x or 4x, to produce the three possible voltage levels.

The ADFVR<1:0> bits of the FVRCON register are used to enable and configure the gain amplifier settings for the reference supplied to the ADC module. Reference Section 15.0 "Analog-to-Digital Converter (ADC) Module" for additional information.

To minimize current consumption when the FVR is disabled, the FVR buffers should be turned off by clearing the ADFVR<1:0> bits.

12.2 FVR Stabilization Period

When the Fixed Voltage Reference module is enabled, it requires time for the reference and amplifier circuits to stabilize. Once the circuits stabilize and are ready for use, the FVRRDY bit of the FVRCON register will be set. See Section 24.0 "Electrical Specifications" for the minimum delay requirement.

FIGURE 12-1: VOLTAGE REFERENCE BLOCK DIAGRAM

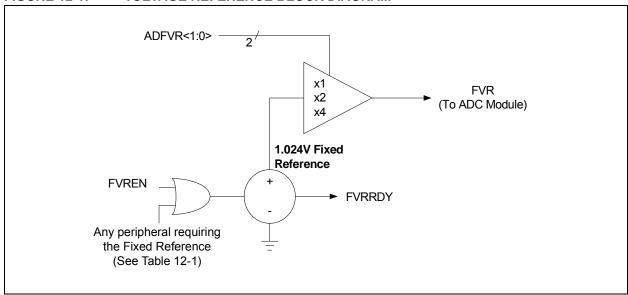


TABLE 12-1: PERIPHERALS REQUIRING THE FIXED VOLTAGE REFERENCE (FVR)

Peripheral	Conditions	Description
HFINTOSC	FOSC = 1	EC on CLKIN pin.
	BOREN<1:0> = 11	BOR always enabled.
BOR	BOREN<1:0> = 10 and BORFS = 1	BOR disabled in Sleep mode, BOR Fast Start enabled.
	BOREN<1:0> = 01 and BORFS = 1	BOR under software control, BOR Fast Start enabled.
IVR	All PIC10F320/322 devices, when VREGPM1 = 1 and not in Sleep	The device runs off of the Power-Save mode regulator when in Sleep mode.

14.0 TEMPERATURE INDICATOR MODULE

This family of devices is equipped with a temperature circuit designed to measure the operating temperature of the silicon die. The circuit's range of operating temperature falls between of -40°C and +85°C. The output is a voltage that is proportional to the device temperature. The output of the temperature indicator is internally connected to the device ADC.

The circuit may be used as a temperature threshold detector or a more accurate temperature indicator, depending on the level of calibration performed. A one-point calibration allows the circuit to indicate a temperature closely surrounding that point. A two-point calibration allows the circuit to sense the entire range of temperature more accurately. Reference Application Note AN1333, "Use and Calibration of the Internal Temperature Indicator" (DS01333) for more details regarding the calibration process.

14.1 Circuit Operation

Figure 14-1 shows a simplified block diagram of the temperature circuit. The proportional voltage output is achieved by measuring the forward voltage drop across multiple silicon junctions.

Equation 14-1 describes the output characteristics of the temperature indicator.

EQUATION 14-1: VOUT RANGES

High Range: VOUT = VDD - 4VT

Low Range: VOUT = VDD - 2VT

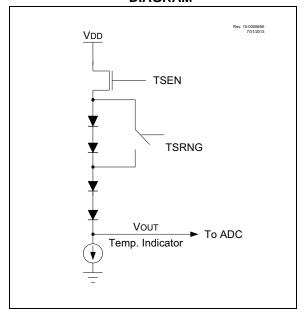
The temperature sense circuit is integrated with the Fixed Voltage Reference (FVR) module. See Section 12.0 "Fixed Voltage Reference (FVR)" for more information.

The circuit is enabled by setting the TSEN bit of the FVRCON register. When disabled, the circuit draws no current.

The circuit operates in either high or low range. The high range, selected by setting the TSRNG bit of the FVRCON register, provides a wider output voltage. This provides more resolution over the temperature range, but may be less consistent from part to part. This range requires a higher bias voltage to operate and thus, a higher VDD is needed.

The low range is selected by clearing the TSRNG bit of the FVRCON0 register. The low range generates a lower voltage drop and thus, a lower bias voltage is needed to operate the circuit. The low range is provided for low voltage operation.

FIGURE 14-1: TEMPERATURE CIRCUIT DIAGRAM



14.2 Minimum Operating VDD vs. Minimum Sensing Temperature

When the temperature circuit is operated in low range, the device may be operated at any operating voltage that is within specifications.

When the temperature circuit is operated in high range, the device operating voltage, VDD, must be high enough to ensure that the temperature circuit is correctly biased.

Table 14-1 shows the recommended minimum VDD vs. range setting.

TABLE 14-1: RECOMMENDED VDD VS. RANGE

Min. VDD, TSRNG = 1	Min. VDD, TSRNG = 0
3.6V	1.8V

14.3 Temperature Output

The output of the circuit is measured using the internal Analog-to-Digital Converter. A channel is reserved for the temperature circuit output. Refer to **Section 15.0** "Analog-to-Digital Converter (ADC) Module" for detailed information.

14.4 ADC Acquisition Time

To ensure accurate temperature measurements, the user must wait at least 200 μs after the ADC input multiplexer is connected to the temperature indicator output before the conversion is performed. In addition, the user must wait 200 μs between sequential conversions of the temperature indicator output.

15.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- · Port configuration
- · Channel selection
- · ADC conversion clock source
- · Interrupt control

15.1.1 PORT CONFIGURATION

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin should be configured for analog by setting the associated TRIS and ANSEL bits. Refer to **Section 10.0 "I/O Port"** for more information.

Note: Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

15.1.2 CHANNEL SELECTION

There are up to five channel selections available:

- AN<2:0> pins
- · Temperature Indicator
- · FVR (Fixed Voltage Reference) Output

Refer to Section 12.0 "Fixed Voltage Reference (FVR)" and Section 14.0 "Temperature Indicator Module" for more information on these channel selections.

The CHS bits of the ADCON register determine which channel is connected to the sample and hold circuit.

When changing channels, a delay is required before starting the next conversion. Refer to **Section 15.2** "**ADC Operation**" for more information.

15.1.3 ADC VOLTAGE REFERENCE

There is no external voltage reference connections to the ADC. Only VDD can be used as a reference source. The FVR is only available as an input channel and not a VREF+ input to the ADC.

15.1.4 CONVERSION CLOCK

The source of the conversion clock is software selectable via the ADCS bits of the ADCON register (Register 15-1). There are seven possible clock options:

- Fosc/2
- Fosc/4
- Fosc/8
- Fosc/16
- Fosc/32
- Fosc/64
- FRC (dedicated internal RC oscillator)

The time to complete one bit conversion is defined as TAD. One full 8-bit conversion requires 9.5 TAD periods as shown in Figure 15-2.

For correct conversion, the appropriate TAD specification must be met. Refer to the A/D conversion requirements in **Section 24.0** "**Electrical Specifications**" for more information. Table 15-1 gives examples of appropriate ADC clock selections.

Unless using the FRC, any changes in the system clock frequency will change the ADC clock frequency, which may adversely affect the ADC result.

19.0 CONFIGURABLE LOGIC CELL (CLC)

The Configurable Logic Cell (CLCx) provides programmable logic that operates outside the speed limitations of software execution. The logic cell selects any combination of the eight input signals and through the use of configurable gates reduces the selected inputs to four logic lines that drive one of eight selectable single-output logic functions.

Input sources are a combination of the following:

- Two I/O pins
- · Internal clocks
- · Peripherals
- · Register bits

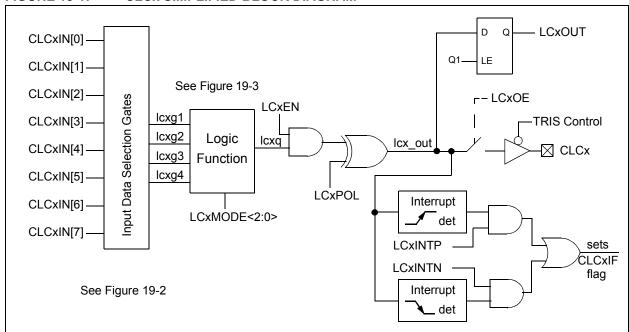
The output can be directed internally to peripherals and to an output pin.

Refer to Figure 19-1 for a simplified diagram showing signal flow through the CLCx.

Possible configurations include:

- · Combinatorial Logic
 - AND
 - NAND
 - AND-OR
 - AND-OR-INVERT
 - OR-XOR
 - OR-XNOR
- · Latches
 - S-R
 - Clocked D with Set and Reset
 - Transparent D with Set and Reset
 - Clocked J-K with Reset

FIGURE 19-1: CLCx SIMPLIFIED BLOCK DIAGRAM



REGISTER 19-7: CLCxGLS2: GATE 3 LOGIC SELECT REGISTER

| R/W-x/u |
|----------|----------|----------|----------|----------|----------|----------|----------|
| LCxG3D4T | LCxG3D4N | LCxG3D3T | LCxG3D3N | LCxG3D2T | LCxG3D2N | LCxG3D1T | LCxG3D1N |
| bit 7 | | | | | | | bit 0 |

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	LCxG3D4T: Gate 3 Data 4 True (non-inverted) bit
	1 = Icxd4T is gated into lcxg3
	0 = Icxd4T is not gated into Icxg3
bit 6	LCxG3D4N: Gate 3 Data 4 Negated (inverted) bit
	1 = lcxd4N is gated into lcxg3
	0 = Icxd4N is not gated into Icxg3
bit 5	LCxG3D3T: Gate 3 Data 3 True (non-inverted) bit
	1 = lcxd3T is gated into lcxg3
	0 = lcxd3T is not gated into lcxg3
bit 4	LCxG3D3N: Gate 3 Data 3 Negated (inverted) bit
	1 = lcxd3N is gated into lcxg3
	0 = lcxd3N is not gated into lcxg3
bit 3	LCxG3D2T: Gate 3 Data 2 True (non-inverted) bit
	1 = lcxd2T is gated into lcxg3
	0 = lcxd2T is not gated into lcxg3
bit 2	LCxG3D2N: Gate 3 Data 2 Negated (inverted) bit
	1 = lcxd2N is gated into lcxg3
	0 = lcxd2N is not gated into lcxg3
bit 1	LCxG3D1T: Gate 3 Data 1 True (non-inverted) bit
	1 = Icxd1T is gated into lcxg3
	0 = lcxd1T is not gated into lcxg3
bit 0	LCxG3D1N: Gate 3 Data 1 Negated (inverted) bit
	1 = lcxd1N is gated into lcxg3
	0 = lcxd1N is not gated into lcxg3

EQUATION 21-1: DEAD-BAND DELAY TIME UNCERTAINTY

$$TDEADBAND_UNCERTAINTY = \frac{1}{Fcwg_clock}$$

EXAMPLE 21-1: DEAD-BAND DELAY TIME UNCERTAINTY

$$Fcwg_clock = 16 MHz$$

Therefore:

$$TDEADBAND_UNCERTAINTY = \frac{1}{Fcwg_clock}$$
$$= \frac{1}{16 MHz}$$
$$= 625 ns$$

BTFSS	Bit Test f, Skip if Set
Syntax:	[label] BTFSS f,b
Operands:	$0 \le f \le 127$ $0 \le b < 7$
Operation:	skip if (f) = 1
Status Affected:	None
Description:	If bit 'b' in register 'f' is '0', the next instruction is executed. If bit 'b' is '1', then the next instruction is discarded and a NOP is executed instead, making this a 2-cycle instruction.

CLRWDT	Clear Watchdog Timer
Syntax:	[label] CLRWDT
Operands:	None
Operation:	00h → WDT 0 → WDT prescaler, 1 → $\overline{10}$ 1 → \overline{PD}
Status Affected:	TO, PD
Description:	CLRWDT instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits TO and PD are set.

CALL	Call Subroutine
Syntax:	[label] CALL k
Operands:	$0 \leq k \leq 2047$
Operation:	(PC)+ 1 \rightarrow TOS, k \rightarrow PC<10:0>, (PCLATH<4:3>) \rightarrow PC<12:11>
Status Affected:	None
Description:	Call Subroutine. First, return address (PC + 1) is pushed onto the stack. The 11-bit immediate address is loaded into PC bits <10:0>. The upper bits of the PC are loaded from PCLATH. CALL is a 2-cycle instruction.

COMF	Complement f
Syntax:	[label] COMF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	$(\bar{f}) \rightarrow (destination)$
Status Affected:	Z
Description:	The contents of register 'f' are complemented. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f'.

CLRF	Clear f
Syntax:	[label] CLRF f
Operands:	$0 \leq f \leq 127$
Operation:	$00h \to (f)$ $1 \to Z$
Status Affected:	Z
Description:	The contents of register 'f' are cleared and the Z bit is set.

DECF	Decrement f
Syntax:	[label] DECF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(f) - 1 \rightarrow (destination)
Status Affected:	Z
Description:	Decrement register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

CLRW	Clear W
Syntax:	[label] CLRW
Operands:	None
Operation:	$00h \rightarrow (W)$ $1 \rightarrow Z$
Status Affected:	Z
Description:	W register is cleared. Zero bit (Z) is set.