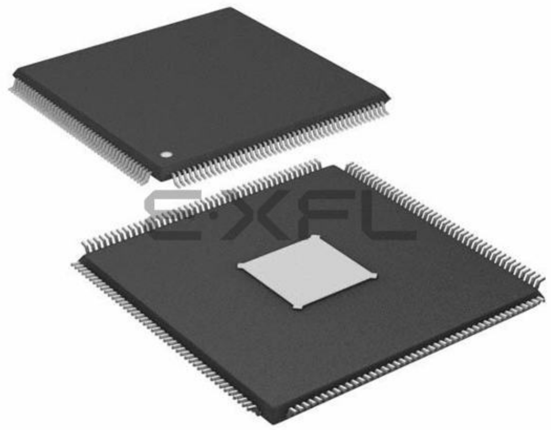

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	e200z2, e200z4, e200z4
Core Size	32-Bit Tri-Core
Speed	80MHz/160MHz
Connectivity	CANbus, Ethernet, I²C, LINbus, SAI, SPI, USB, USB OTG
Peripherals	DMA, LVD, POR, WDT
Number of I/O	129
Program Memory Size	4MB (4M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	768K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 80x10b, 64x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	176-LQFP Exposed Pad
Supplier Device Package	176-LQFP (24x24)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/spc5747gk1mku6r

Table of Contents

1 Block diagram

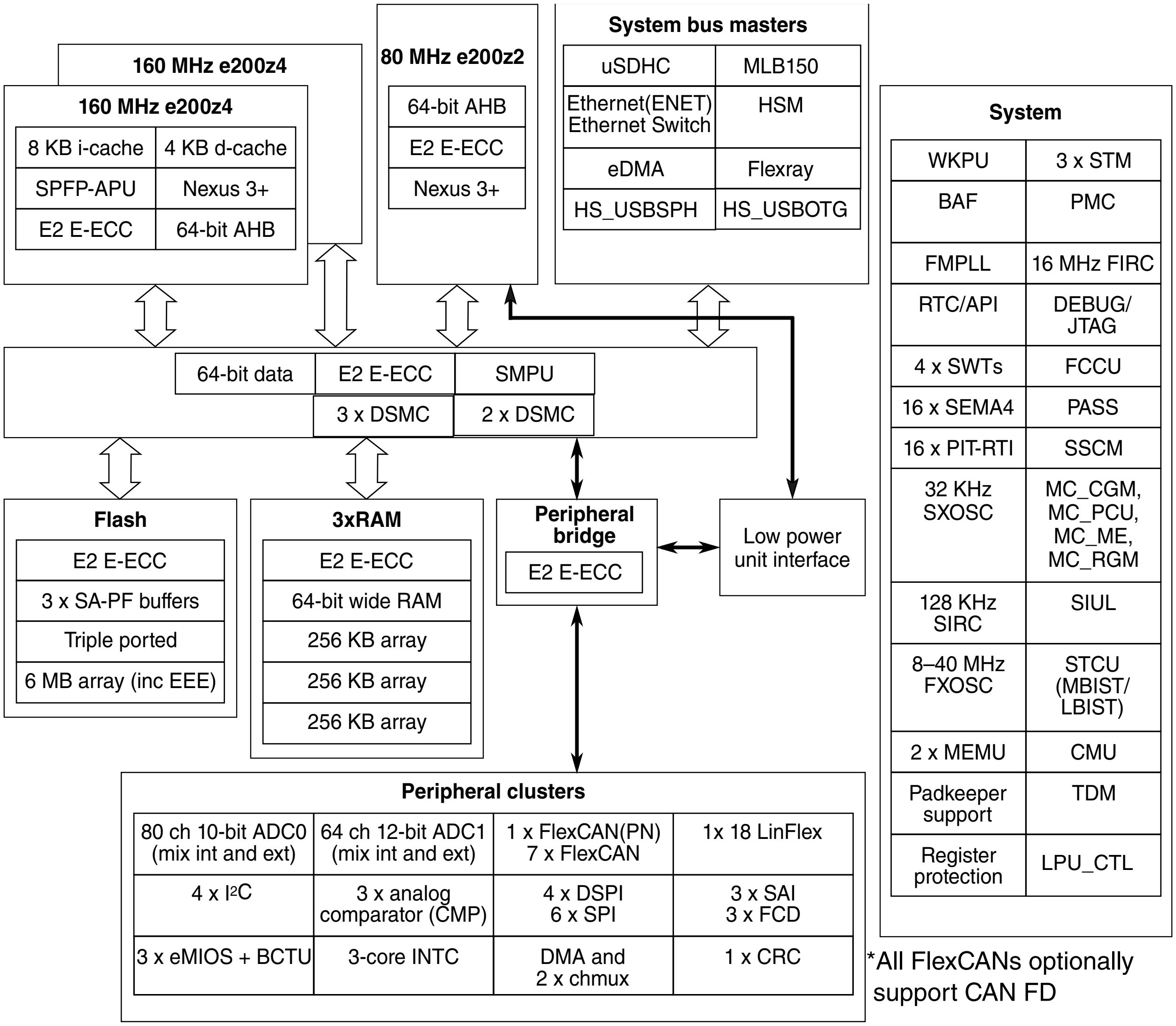


Figure 1. MPC5748G block diagram

2 Family comparison

The following table provides a summary of the different members of the MPC5748G family and their proposed features. This information is intended to provide an understanding of the range of functionality offered by this family. For full details of all of the family derivatives please contact your marketing representative.

Table 3. MPC5748G Family Comparison - NVM Memory Map 2

Start Address	End Address	Flash block	RWW	MPC5747C MPC5748C	MPC5746G MPC5747G MPC5748G
0x00F90000	0x00F93FFF	16 KB data Flash	2	available	available
0x00F94000	0x00F97FFF	16 KB data Flash	2	available	available
0x00F98000	0x00F9BFFF	16 KB data Flash	2	available	available
0x00F9C000	0x00F9FFFF	16 KB data Flash	2	available	available
0x00FA0000	0x00FA3FFF	16 KB data Flash	3	available	available
0x00FA4000	0x00FA7FFF	16 KB data Flash	3	available	available
0x00FA8000	0x00FABFFF	16 KB data Flash	3	available	available
0x00FAC000	0x00FAFFFF	16 KB data Flash	3	available	available
0x00FB0000	0x00FB7FFF	32 KB data Flash	2	not available	available
0x00FB8000	0x00FBFFFF	32 KB data flash	3	not available	available

Table 4. MPC5748G Family Comparison - RAM Memory Map

Start Address	End Address	Allocated size [KB]	MPC5747C	MPC5748C MPC5746G MPC5747G MPC5748G
0x40000000	0x40001FFF	8	available	available
0x40002000	0x4000FFFF	56	available	available
0x40010000	0x4001FFFF	64	available	available
0x40020000	0x4003FFFF	128	available	available
0x40040000	0x4007FFFF	256	available	available
0x40080000	0x400BFFFF	256	not available	available

3 Ordering parts

3.1 Determining valid orderable parts

To determine the orderable part numbers for this device, go to www.nxp.com and perform a part number search for the following device number: MPC5748G .

4.3 Voltage regulator electrical characteristics

The voltage regulator is composed of the following blocks:

- Choice of generating supply voltage for the core area.
  - Control of external NPN ballast transistor
  - Connecting an external 1.25 V (nominal) supply directly without the NPN ballast
- Internal generation of the 3.3 V flash supply when device connected in 5V applications
- External bypass of the 3.3 V flash regulator when device connected in 3.3V applications
- Low voltage detector - low threshold (LVD_IO_A_LO) for $V_{DD\_HV\_IO\_A\ supply}$
- Low voltage detector - high threshold (LVD_IO_A_Hi) for $V_{DD\_HV\_IO\_A\ supply}$
- Various low voltage detectors (LVD_LV_x)
- High voltage detector (HVD_LV_cold) for 1.2 V digital core supply (VDD_LV)
- Power on Reset (POR_LV) for 1.25 V digital core supply (VDD_LV)
- Power on Reset (POR_HV) for 3.3 V to 5 V supply (VDD_HV_A)

The following bipolar transistors[1] are supported, depending on the device performance requirements. As a minimum the following must be considered when determining the most appropriate solution to maintain the device under its maximum power dissipation capability: current, ambient temperature, mounting pad area, duty cycle and frequency for Idd, collector voltage, etc

1. BCP56, MCP68 and MJD31are guaranteed ballasts.

4.5 Supply current characteristics

Current consumption data is given in the following table. These specifications are design targets and are subject to change per device characterization.

NOTE

The ballast must be chosen in accordance with the ballast transistor supplier operating conditions and recommendations.

Table 10. Current consumption characteristics

Symbol	Parameter	Conditions[1]	Min	Typ	Max	Unit
I_{DD_FULL} [2, 3]	RUN Full Mode Operating current	LV supply + HV supply + HV Flash supply + 2 x HV ADC supplies T_a = 85°C V_{DD_LV} = 1.25 V VDD_HV_A = 5.5V SYS_CLK = 160MHz	—	219	292	mA
		T_a = 105°C	—	230	328	mA
		T_a = 125 °C	—	249	400	mA
I_{DD_GWY} [5, 6]	RUN Gateway Mode Operating current	LV supply + HV supply + HV Flash supply + 2 x HV ADC supplies T_a = 85°C V_{DD_LV} = 1.25 V VDD_HV_A = 5.5V SYS_CLK = 160MHz	—	183	260	mA
		T_a = 105°C	—	196	294	mA
		T_a = 125°C[4]	—	215	348	mA
$I_{DD\_BODY\_1}$ [7, 8]	RUN Body Mode Profile Operating current	LV supply + HV supply + HV Flash supply + 2 x HV ADC supplies T_a = 85 °C V_{DD_LV} = 1.25 V VDD_HV_A = 5.5V SYS_CLK = 120MHz	—	149	223	mA
		T_a = 105 °C	—	158	270	mA
		T_a = 125°C [4]	—	175	310	mA
IDD_BODY_2[9, 10]	RUN Body Mode Profile Operating current	LV supply + HV supply + HV Flash supply + 2 x HV ADC supplies T_a = 85 °C V_{DD_LV} = 1.25 V VDD_HV_A = 5.5V SYS_CLK = 80MHz	—	105	174	mA

Table continues on the next page...

x FlexCAN state machines clocked(other FLEXCAN clock gated), 4 x LINFlexD transmitting (Other clock gated), 1x eMIOS clocked(used OPWFMB mode) (Others clock gated), FIRC, SIRC, FXOSC, SXOSC, PLL running, BCTU, DMAMUX, ACMP clock gated. All others modules clock gated if not specifically mentioned. I/O supply current excluded

6. Recommended Transistors:MJD31@85°C, 105°C and 125°C.
7. Enabled Modules in Body mode enabled at maximum frequency: 2 x e200Z4 @120Mhz(Instruction and Data cache enabled),Platform@120MHz, SRAMs accessed in parallel, Flash access(prefetch is disabled while buffers are enabled), HSM reading from flash at regular intervals(500 pll clock cycles), DMA (SRAM to SRAM), ADC0 converting using BCTU triggers which are triggered through PIT(ADC1 clocked), RTC clocked, 3 x STM clocked, 2 x DSPI transmitting(others DSPIs clocked), 2 x SPI transmitting(others clocked), 4 x FlexCAN state machines working(others clocked), 9xLINFlexD transmitting (others clocked), 1xeMIOS operational (used OPWFMB mode) (others clocked), FIRC, SIRC, FXOSC, SXOSC, PLL running, MEMU, FCCU, SIUL, SDHC,CMP clocked, e200Z2, ENET, MLB, SAI, I2C, FlexRay, USB clock gated. All others modules clock gated if not specifically mentioned I/O supply current excluded
8. Recommended Transistors:BCP56, BCP68 or MJD31@85°C, BCP56, BCP68 or MJD31@105°C and MJD31@125°C.
9. Enabled Modules in Body mode enabled at maximum frequency:2 x e200Z4 @80Mhz(Instruction and Data cache enabled),Platform@80MHz, SRAMs accessed in parallel, Flash access(prefetch is disabled while buffers are enabled), HSM reading from flash at regular intervals(500 pll clock cycles), DMA (SRAM to SRAM), ADC0 converting using BCTU triggers which are triggered through PIT(ADC1 clocked), RTC clocked, 3 x STM clocked, 2 x DSPI transmitting(others DSPIs clocked), 2 x SPI transmitting(others clocked), 4 x FlexCAN state machines working(others clocked), 9xLINFlexD transmitting (others clocked), 1xeMIOS operational (used OPWFMB mode) (others clocked), FIRC, SIRC, FXOSC, SXOSC, PLL running, MEMU, FCCU, SIUL, SDHC,CMP clocked, e200Z2, ENET, MLB, SAI, I2C, FlexRay, USB clock gated. All others modules clock gated if not specifically mentioned I/O supply current excluded
10. Recommended Transistors:BCP56, BCP68 or MJD31@85°C, 105°C and 125°C
11. Internal structures hold the input voltage less than $V_{DD\_HV\_ADC\_REF}$ + 1.0 V on all pads powered by V_{DDA} supplies, if the maximum injection current specification is met (3 mA for all pins) and V_{DDA} is within the operating voltage specifications.
12. This value is the total current for two ADCs.Each ADC might consume upto 2mA at max.

Table 11. Low Power Unit (LPU) Current consumption characteristics

Symbol	Parameter	Conditions[1]	Min	Typ	Max	Unit
LPU_RUN	with 256K RAM, but only one RAM being accessed	T_a = 25 °C SYS_CLK = 16MHz ADC0 = OFF, SPI0 = OFF, LIN0 = OFF, CAN0 = OFF	—	8.9		mA
		T_a = 25 °C SYS_CLK = 16MHz ADC0 = ON, SPI0 = ON, LIN0 = ON, CAN0 = ON		10.2		
		T_a = 85 °C	—	12.5	22	
		T_a = 105 °C	—	14.5	24	
		T_a = 125 °C , [2] SYS_CLK = 16MHz ADC0 = ON, SPI0 = ON, LIN0 = ON, CAN0 = ON	—	16	26	
LPU_STOP	with 256K RAM	T_a = 25 °C	—	0.535		mA
		T_a = 85 °C	—	0.72	6	
		T_a = 105 °C	—	1	8	
		T_a = 125 °C [2]	—	1.6	10.6	

1. The content of the Conditions column identifies the components that draw the specific current.
2. Assuming Ta=Tj, as the device is in static (fully clock gated) mode. Assumes maximum θJA of 2s2p board. See Thermal attributes

Table 13. ESD ratings (continued)

Symbol	Parameter	Conditions[1]	Class	Max value[2]	Unit
		conforming to AEC-Q100-002			
$V_{ESD(CDM)}$	Electrostatic discharge (Charged Device Model)	T_A = 25 °C conforming to AEC-Q100-011	C3A	500 750 (corners)	V

1. All ESD testing is in conformity with CDF-AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits.
2. Data based on characterization results, not tested in production.

4.7 Electromagnetic Compatibility (EMC) specifications

EMC measurements to IC-level IEC standards are available from NXP on request.

5 I/O parameters

5.1 AC specifications @ 3.3 V Range

Table 14. Functional Pad AC Specifications @ 3.3 V Range

Symbol	Prop. Delay (ns)[1] L>H/H>L		Rise/Fall Edge (ns)		Drive Load (pF)	SIUL2_MSCRn[SRC 1:0]
	Min	Max	Min	Max		MSB,LSB
pad_sr_hv (output)		6/6		1.9/1.5	25	11
	2.5/2.5	8.25/7.5	0.8/0.6	3.25/3	50	
	6.4/5	19.5/19.5	3.5/2.5	12/12	200	
	2.2/2.5	8/8	0.55/0.5	3.9/3.5	25	10
	0.090	1.1	0.035	1.1	asymmetry[2]	
	2.9/3.5	12.5/11	1/1	7/6	50	
	11/8	35/31	7.7/5	25/21	200	
	8.3/9.6	45/45	4/3.5	25/25	50	01
	13.5/15	65/65	6.3/6.2	30/30	200	
	13/13	75/75	6.8/6	40/40	50	00[3]
	21/22	100/100	11/11	51/51	200	
pad_i_hv/ pad_sr_hv (input)[4]		2/2		0.5/0.5	0.5	NA

1. As measured from 50% of core side input to Voh/Vol of the output
2. This row specifies the min and max asymmetry between both the prop delay and the edge rates for a given PVT and 25pF load. Required for the Flexray spec.

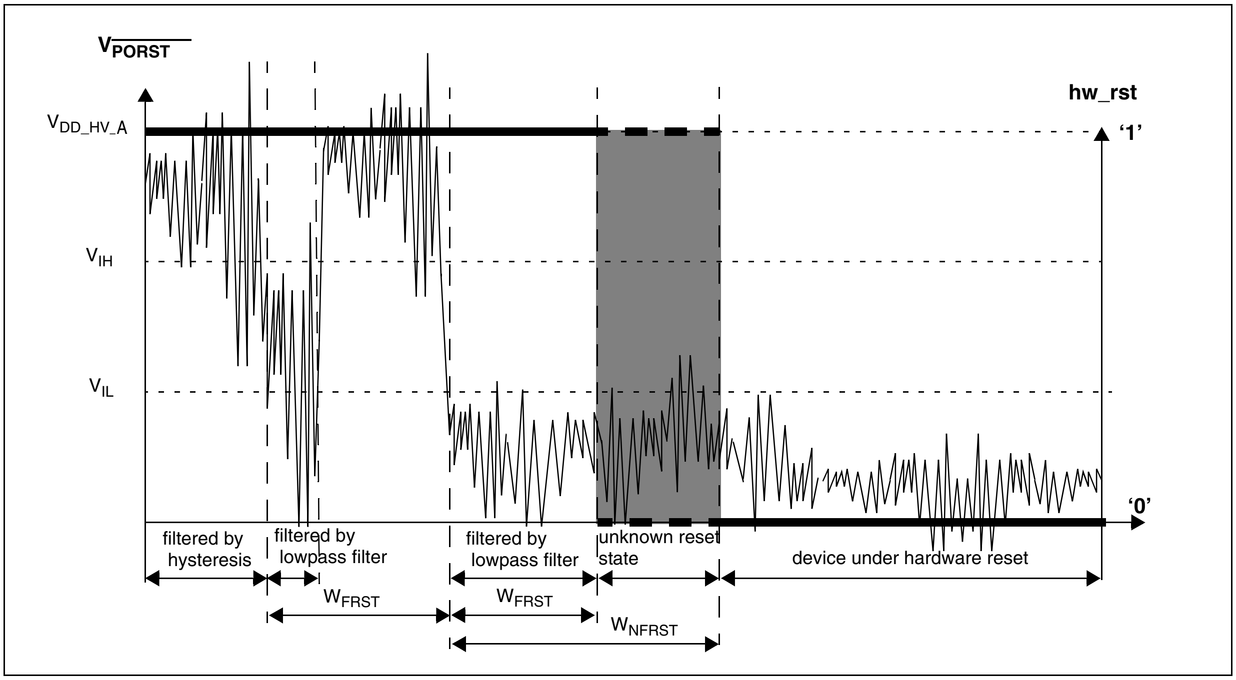


Figure 4. Noise filtering on reset signal

Table 18. Functional reset pad electrical specifications

Symbol	Parameter	Conditions	Value			Unit
			Min	Typ	Max	
V_{IH}	Input high level TTL (Schmitt Trigger)	—	2.0	—	$V_{DD\_HV\_A}$ +0.4	V
V_{IL}	Input low level TTL (Schmitt Trigger)	—	–0.4	—	0.8	V
V_{HYS}	Input hysteresis TTL (Schmitt Trigger)	—	300	—	—	mV
V_{DD_POR}	Minimum supply for strong pull-down activation	—	—	—	1.2	V
I_{OL_R}	Strong pull-down current [1]	Device under power-on reset $V_{DD\_HV\_A}= V_{DD\_POR}$ $V_{OL} = 0.35*V_{DD\_HV\_A}$	0.2	—	—	mA
		Device under power-on reset $V_{DD\_HV\_A}= V_{DD\_POR}$ $V_{OL} = 0.35*V_{DD\_HV\_IO}$	11	—	—	mA
W_{FRST}	$\overline{\text{RESET}}$ input filtered pulse	—	—	—	500	ns
W_{NFRST}	$\overline{\text{RESET}}$ input not filtered pulse	—	2000	—	—	ns
$\|I_{WPU}\|$	Weak pull-up current absolute value	RESET pin $V_{IN} = V_{DD}$	23	—	82	μA

1. Strong pull-down is active on PHASE0, PHASE1, PHASE2, and the beginning of PHASE3 for RESET.

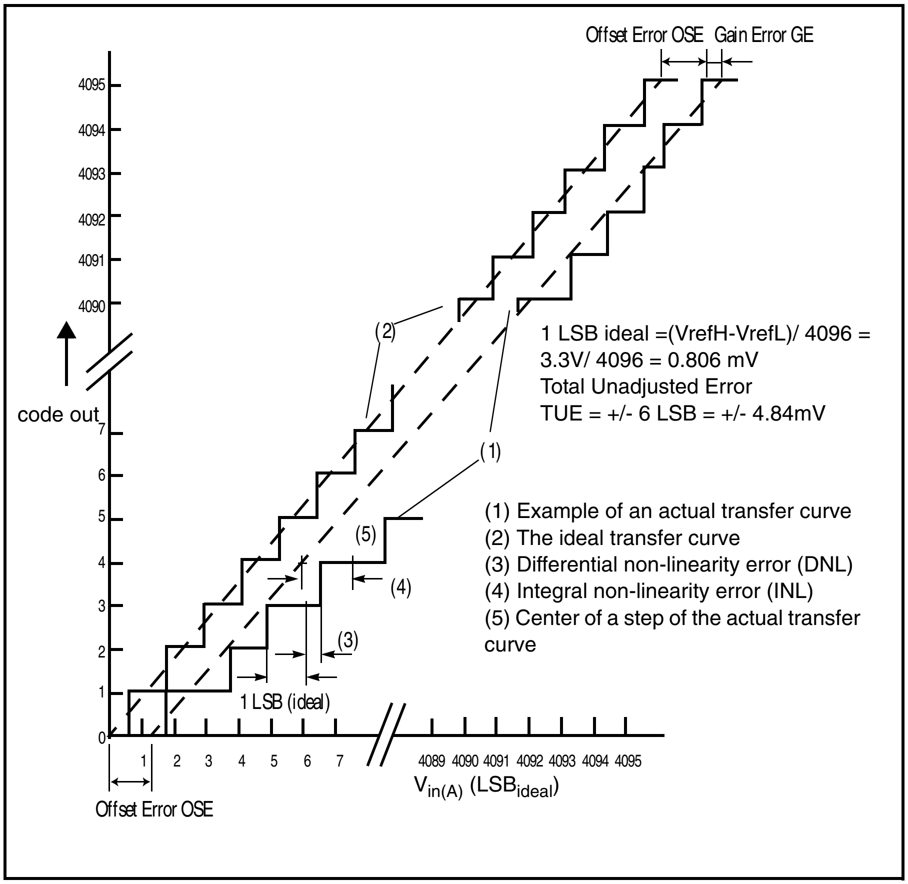


Figure 5. ADC characteristics and error definitions

Table 20. ADC conversion characteristics (for 12-bit) (continued)

Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
R_{AD}[6]	Internal resistance of analog source	—	—	—	825	Ω
INL	Integral non-linearity (precise channel)	—	–2	—	2	LSB
INL	Integral non-linearity (standard channel)	—	–3	—	3	LSB
DNL	Differential non-linearity	—	–1	—	1	LSB
OFS	Offset error	—	–6	—	6	LSB
GNE	Gain error	—	–4	—	4	LSB
ADC Analog Pad (pad going to one ADC)	Max leakage (precision channel)	150 °C	—	—	250	nA
	Max leakage (standard channel)	150 °C	—	—	2500	nA
	Max leakage (standard channel)	105 °C $_{TA}$	—	5	250	nA
	Max positive/negative injection		–5	—	5	mA
$TUE_{precision\ channels}$	Total unadjusted error for precision channels	Without current injection	–6	+/-4	6	LSB
		With current injection		+/-5		LSB
$TUE_{standard/extended\ channels}$	Total unadjusted error for standard/ extended channels	Without current injection	–8	+/-6	8	LSB
		With current injection[7]		+/-8		LSB
$t_{recovery}$	STOP mode to Run mode recovery time				< 1	μs

1. Active ADC input, VinA < [min(ADC_VrefH, ADC_ADV, VDD_HV_IOx)]. VDD_HV_IOx refers to I/O segment supply voltage. Violation of this condition would lead to degradation of ADC performance. Please refer to Table: 'Absolute maximum ratings' to avoid damage. Refer to Table: 'Recommended operating conditions (VDD_HV_x = 3.3 V)' for required relation between IO_supply_A,B,C and ADC_Supply.
2. The internally generated clock (known as AD_clk or ADCK) could be same as the peripheral clock or half of the peripheral clock based on register configuration in the ADC.
3. During the sample time the input capacitance C_S can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t_{sample}. After the end of the sample time t_{sample}, changes of the analog input voltage have no effect on the conversion result. Values for the sample clock t_{sample} depend on programming.
4. This parameter does not include the sample time t_{sample}, but only the time for determining the digital result and the time to load the result register with the conversion result.
5. Apart from tsample and tconv, few cycles are used up in ADC digital interface and hence the overall throughput from the ADC is lower.
6. See Figure 2.
7. Current injection condition for ADC channels is defined for an inactive ADC channel (on which conversion is NOT being performed), and this occurs when voltage on the ADC pin exceeds the I/O supply or ground. However, absolute maximum voltage spec on pad input (VINA, see Table: Absolute maximum ratings) must be honored to meet TUE spec quoted here

Table 21. ADC conversion characteristics (for 10-bit)

Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
f_{CK}	ADC Clock frequency (depends on ADC configuration) (The duty cycle depends on AD_CK[2] frequency.)	—	15.2	80	80	MHz
f_s	Sampling frequency	—	—	—	1.00	MHz
t_{sample}	Sample time[3]	80 MHz@ 100 ohm source impedance	275	—	—	ns

Table continues on the next page...

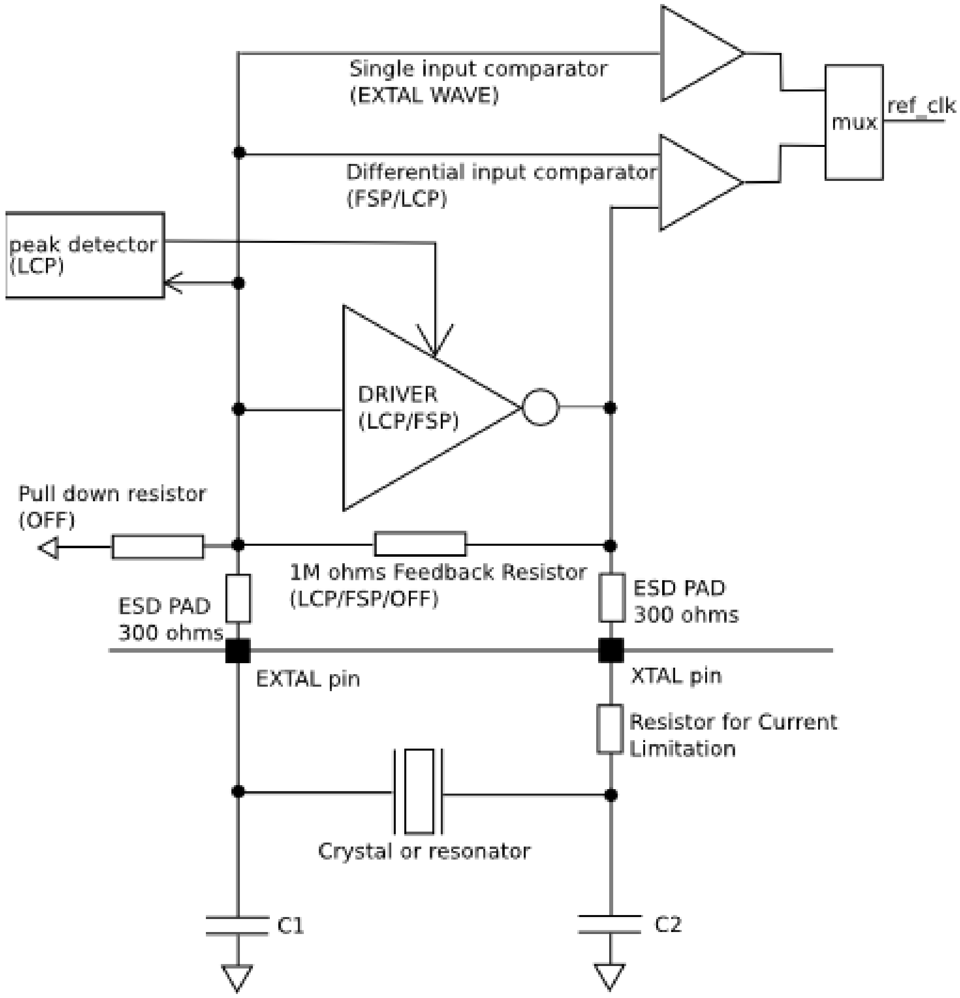


Figure 7. Oscillator connections scheme

Table 23. Main oscillator electrical characteristics

Symbol	Parameter	Mode	Conditions	Min	Typ	Max	Unit
f_{XOSCHS}	Oscillator frequency	FSP/LCP		8		40	MHz
$g_{mXOSCHS}$	Driver Transconductance	LCP			23		mA/V
		FSP			33		
V_{XOSCHS}	Oscillation Amplitude	LCP	8 MHz		1.0		V_{PP}
			16 MHz		1.0		
			40 MHz		0.8		
$T_{XOSCHSSU}$	Startup time	FSP/LCP	8 MHz		2		ms
			16 MHz		1		
			40 MHz		0.5		
	Oscillator Analog Circuit supply current	FSP	8 MHz		2.2		mA
			16 MHz		2.2		
			40 MHz		3.2		

Table continues on the next page...

Table 30. Flash memory program and erase specifications (continued)

Symbol	Characteristic[1]	Typ[2]	Factory Programming[3, 4]		Field Update			Unit
			Initial Max	Initial Max, Full Temp	Typical End of Life[5]	Lifetime Max[6]		
			20°C ≤T_A ≤30°C	-40°C ≤T_J ≤150°C	-40°C ≤T_J ≤150°C	≤ 1,000 cycles	≤ 250,000 cycles	
t_{32kers}	32 KB Block erase time	217	360	390	310	1,200		ms
t_{32kpgm}	32 KB Block program time	69	100	110	90	1,200		ms
t_{64kers}	64 KB Block erase time	315	490	590	420	1,600		ms
t_{64kpgm}	64 KB Block program time	138	180	210	170	1,600		ms
$t_{256kers}$	256 KB Block erase time	884	1,520	2,030	1,080	4,000	—	ms
$t_{256kpgm}$	256 KB Block program time	552	720	880	650	4,000	—	ms

1. Program times are actual hardware programming times and do not include software overhead. Block program times assume quad-page programming.
2. Typical program and erase times represent the median performance and assume nominal supply values and operation at 25 °C. Typical program and erase times may be used for throughput calculations.
3. Conditions: ≤ 150 cycles, nominal voltage.
4. Plant Programing times provide guidance for timeout limits used in the factory.
5. Typical End of Life program and erase times represent the median performance and assume nominal supply values. Typical End of Life program and erase values may be used for throughput calculations.
6. Conditions: -40°C ≤ T_J ≤ 150°C, full spec voltage.

6.3.2 Flash memory Array Integrity and Margin Read specifications

Table 31. Flash memory Array Integrity and Margin Read specifications

Symbol	Characteristic	Min	Typical	Max	Units
$t_{ai16kseq}$	Array Integrity time for sequential sequence on 16 KB block.	—	—	512 x Tperiod x Nread	—
$t_{ai32kseq}$	Array Integrity time for sequential sequence on 32 KB block.	—	—	1024 x Tperiod x Nread	—
$t_{ai64kseq}$	Array Integrity time for sequential sequence on 64 KB block.	—	—	2048 x Tperiod x Nread	—
tai256kseq	Array Integrity time for sequential sequence on 256 KB block.	—	—	8192 x Tperiod x Nread	—
$t_{mr16kseq}$	Margin Read time for sequential sequence on 16 KB block.	73.81	—	110.7	μs
$t_{mr32kseq}$	Margin Read time for sequential sequence on 32 KB block.	128.43	—	192.6	μs
$t_{mr64kseq}$	Margin Read time for sequential sequence on 64 KB block.	237.65	—	356.5	μs
$t_{mr256kseq}$	Margin Read time for sequential sequence on 256 KB block.	893.01	—	1,339.5	μs

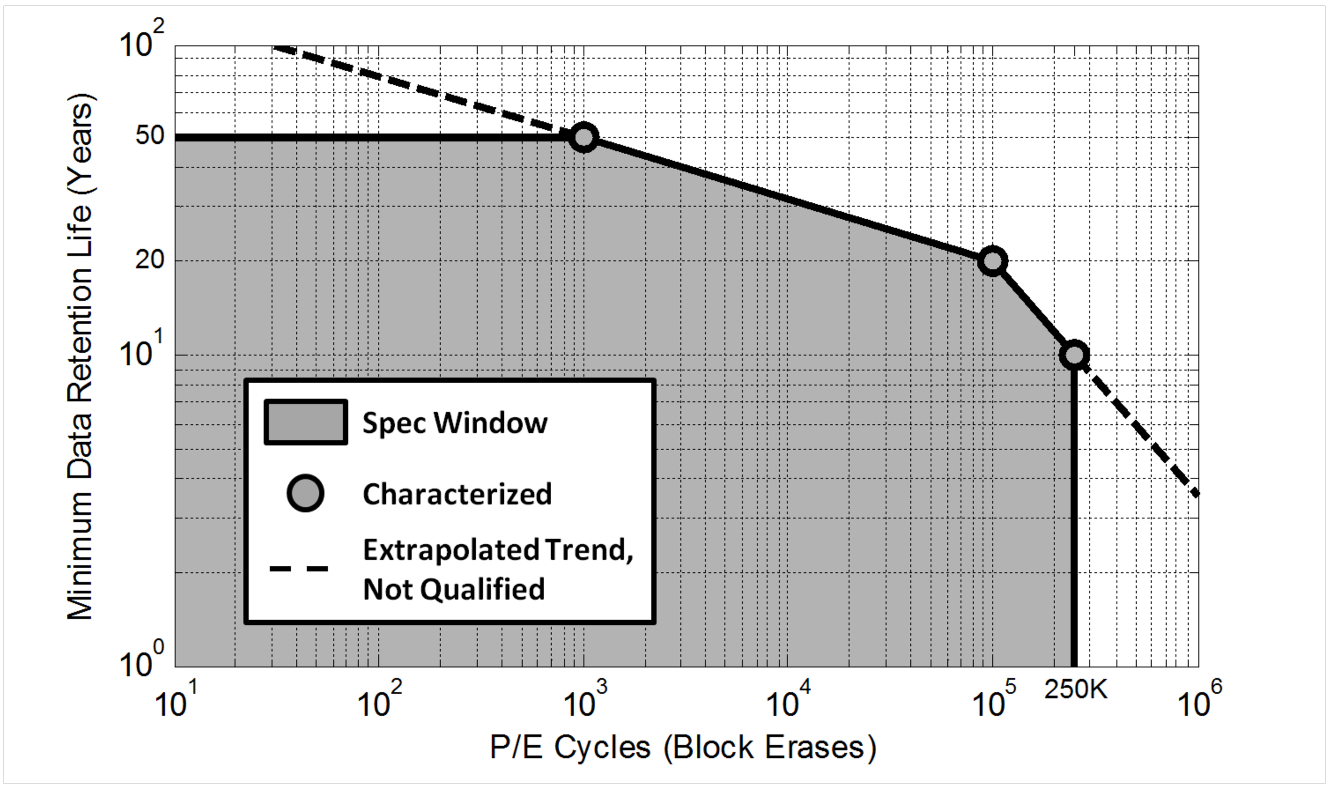
6.3.3 Flash memory module life specifications

Table 32. Flash memory module life specifications

Symbol	Characteristic	Conditions	Min	Typical	Units
Array P/E cycles	Number of program/erase cycles per block for 16 KB, 32 KB and 64 KB blocks.	—	250,000	—	P/E cycles
	Number of program/erase cycles per block for 256 KB blocks.	—	1,000	250,000	P/E cycles
Data retention	Minimum data retention.	Blocks with 0 - 1,000 P/E cycles.	50	—	Years
		Blocks with 100,000 P/E cycles.	20	—	Years
		Blocks with 250,000 P/E cycles.	10	—	Years

6.3.4 Data retention vs program/erase cycles

Graphically, Data Retention versus Program/Erase Cycles can be represented by the following figure. The spec window represents qualified limits. The extrapolated dotted line demonstrates technology capability, however is beyond the qualification limits.



6.3.6 Flash read wait state and address pipeline control settings

The following table describes the recommended RWSC and APC settings at various operating frequencies based on specified intrinsic flash access times of the flash module controller array at 125 °C.

Table 34. Flash Read Wait State and Address Pipeline Control Combinations

Flash frequency	RWSC setting	APC setting
0 MHz < fFlash <= 33 MHz	0	0
33 MHz < fFlash <= 100 MHz	2	1
100 MHz < fFlash <= 133 MHz	3	1
133 MHz < fFlash <= 160 MHz	4	1

6.4 Communication interfaces

6.4.1 DSPI timing

Table 35. DSPI electrical specifications

No	Symbol	Parameter	Conditions	High Speed Mode		low Speed mode		Unit
				Min	Max	Min	Max	
1	t_{SCK}	DSPI cycle time	Master (MTFE = 0)	25	—	50	—	ns
			Slave (MTFE = 0)	40	—	60	—	
2	t_{CSC}	PCS to SCK delay	—	16	—	—	—	ns
3	t_{ASC}	After SCK delay	—	16	—	—	—	ns
4	t_{SDC}	SCK duty cycle	—	$t_{SCK}/2 - 10$	$t_{SCK}/2 + 10$	—	—	ns
5	t_A	Slave access time	$\overline{SS}$ active to SOUT valid	—	40	—	—	ns
6	t_{DIS}	Slave SOUT disable time	SS inactive to SOUT High-Z or invalid	—	10	—	—	ns
7	t_{PCSC}	PCSx to $\overline{PCSS}$ time	—	13	—	—	—	ns
8	t_{PASC}	$\overline{PCSS}$ to PCSx time	—	13	—	—	—	ns
9	t_{SUI}	Data setup time for inputs	Master (MTFE = 0)	NA	—	20	—	ns
			Slave	2	—	2	—	
			Master (MTFE = 1, CPHA = 0)	15	—	8[1]	—	

Table continues on the next page...

Table 35. DSPI electrical specifications (continued)

No	Symbol	Parameter	Conditions	High Speed Mode		low Speed mode		Unit
				Min	Max	Min	Max	
			Master (MTFE = 1, CPHA = 1)	15	—	20	—	
10	t_{HI}	Data hold time for inputs	Master (MTFE = 0)	NA	—	–5	—	ns
			Slave	4	—	4	—	
			Master (MTFE = 1, CPHA = 0)	0	—	11[1]	—	
			Master (MTFE = 1, CPHA = 1)	0	—	-5	—	
11	t_{SUO}	Data valid (after SCK edge)	Master (MTFE = 0)	—	NA	—	4	ns
			Slave	—	15	—	23	
			Master (MTFE = 1, CPHA = 0)	—	4	—	16[1]	
			Master (MTFE = 1, CPHA = 1)	—	4	—	4	
12	t_{HO}	Data hold time for outputs	Master (MTFE = 0)	NA	—	–2	—	ns
			Slave	4	—	6	—	
			Master (MTFE = 1, CPHA = 0)	-2	—	10[1]	—	
			Master (MTFE = 1, CPHA = 1)	–2	—	–2	—	

1. SMPL_PTR should be set to 1

NOTE

Restriction For High Speed modes

- DSPI2, DSPI3, SPI1 and SPI2 will support 40MHz Master mode SCK
- DSPI2, DSPI3, SPI1 and SPI2 will support 25MHz Slave SCK frequency
- Only one {SIN,SOUT and SCK} group per DSPI/SPI will support high frequency mode
- For Master mode MTFE will be 1 for high speed mode
- For high speed slaves, their master have to be in MTFE=1 mode or should be able to support 15ns tSUO delay

NOTE

For numbers shown in the following figures, see Table 35

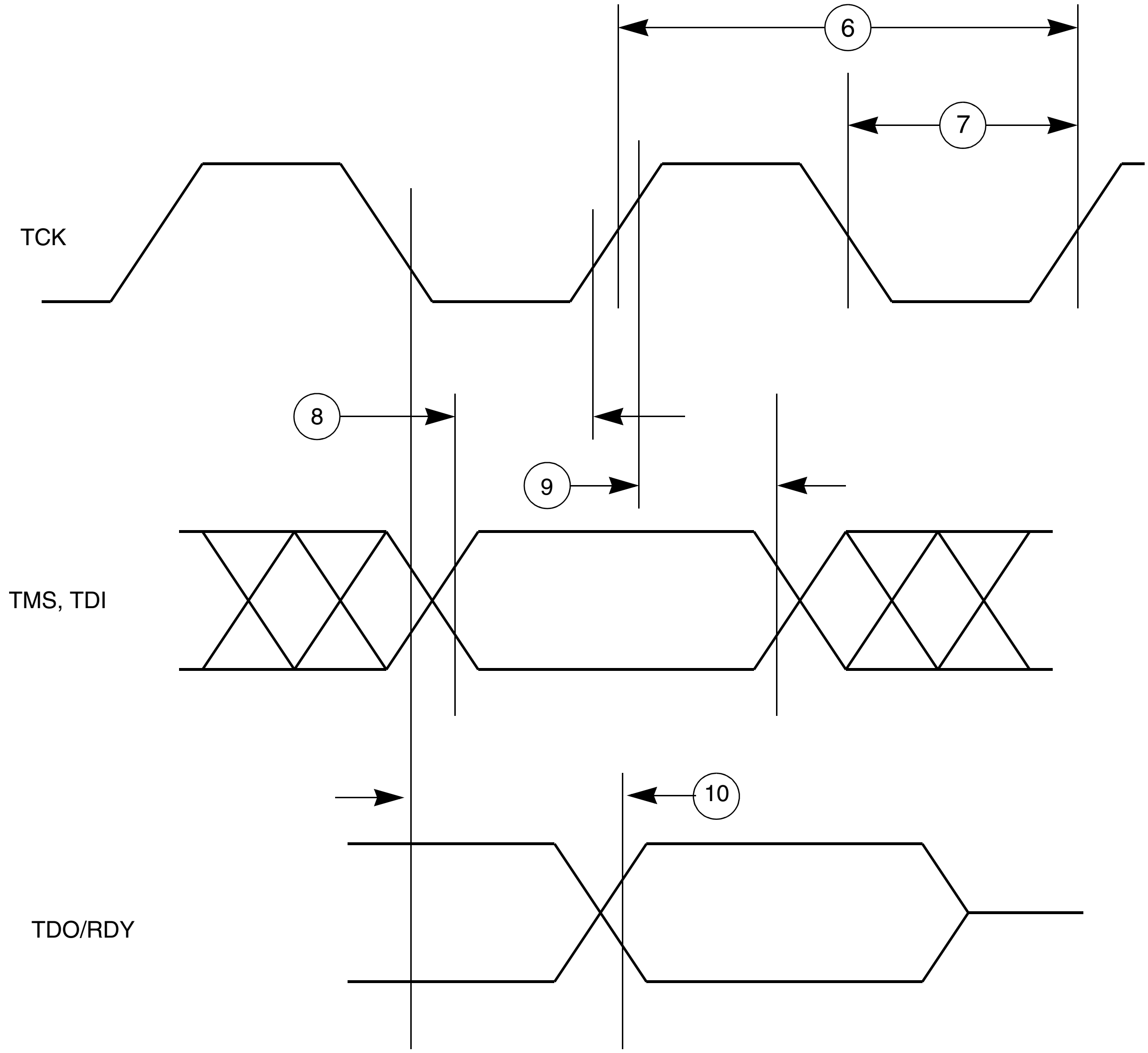


Figure 33. Nexus TDI, TMS, TDO timing

6.5.3 WKPU/NMI timing

Table 52. WKPU/NMI glitch filter

No.	Symbol	Parameter	Min	Typ	Max	Unit
1	W_{FNMI}	NMI pulse width that is rejected	—	—	20	ns
2	$W_{NFNMI}D$	NMI pulse width that is passed	400	—	—	ns

9 Pinouts

9.1 Package pinouts and signal descriptions

For package pinouts and signal descriptions, refer to the Reference Manual.

10 Reset sequence

This section describes different reset sequences and details the duration for which the device remains in reset condition in each of those conditions.

10.1 Reset sequence duration

Table 54 specifies the minimum and the maximum reset sequence duration for the five different reset sequences described in Reset sequence description.

Table 54. RESET sequences

No.	Symbol	Parameter	T_{Reset}			Unit
			Min	Typ [1]	Max	
1	T_{DRB}	Destructive Reset Sequence, BIST enabled	5.730	7.796		ms
2	T_{DR}	Destructive Reset Sequence, BIST disabled	0.111	0.182		ms
3	T_{ERLB}	External Reset Sequence Long, Unsecure Boot	5.729	7.793		ms
4	T_{FRL}	Functional Reset Sequence Long, Unsecure Boot	0.110	0.179		ms
5	T_{FRS}	Functional Reset Sequence Short, Unsecure Boot	0.007	0.009		ms

1. The Typ value is applicable only if the reset sequence duration is not prolonged by an extended assertion of RESET_B by an external reset generator.

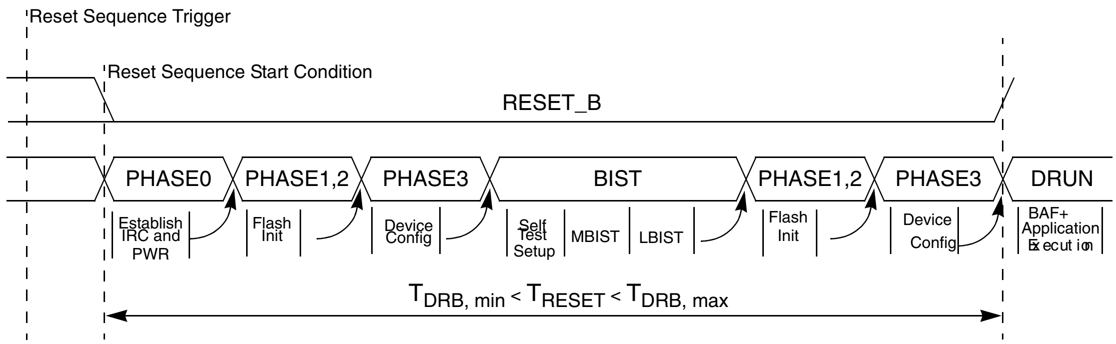


Figure 35. Destructive reset sequence, BIST enabled

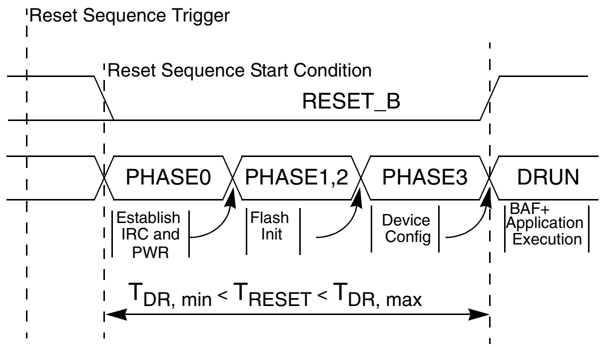


Figure 36. Destructive reset sequence, BIST disabled

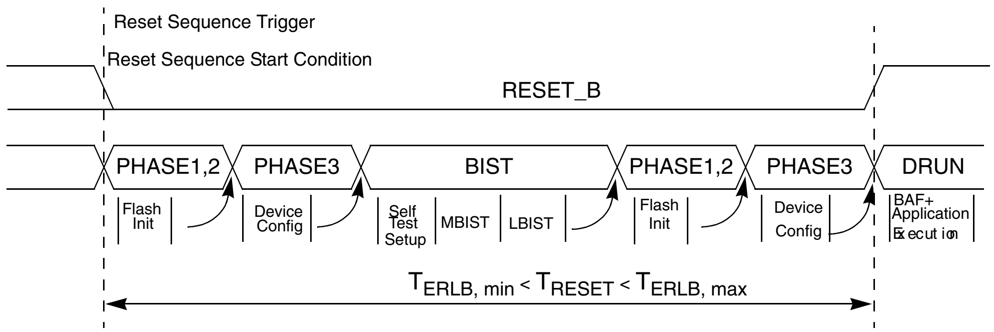


Figure 37. External reset sequence long, BIST enabled

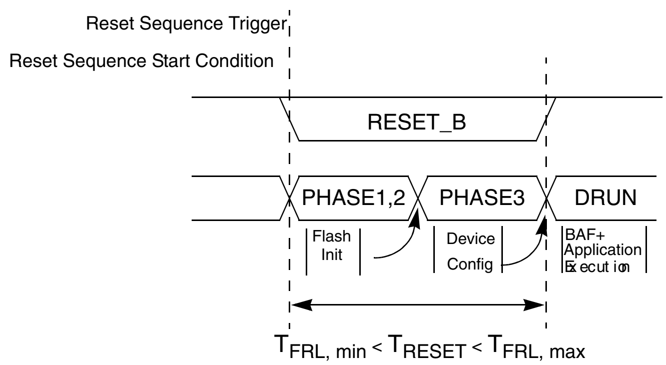


Figure 38. Functional reset sequence long

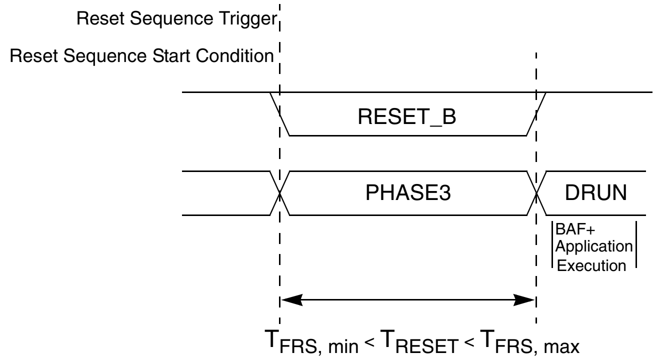


Figure 39. Functional reset sequence short

The reset sequences shown in Figure 38 and Figure 39 are triggered by functional reset events. RESET_B is driven low during these two reset sequences only if the corresponding functional reset source (which triggered the reset sequence) was enabled to drive RESET_B low for the duration of the internal reset sequence. See the RGM_FBRE register in the device reference manual for more information.

11 Revision History

The following table provides a revision history for this document.

Table 56. Revision History

Rev. No.	Date	Substantial Changes
1	14 March 2013	Initial Release
1.1	16 May 2013	Updated Pinouts section

2	22 May 2014	• Removed Category (SR, CC, P, T, D, B) column from all the table of the Datasheet
		• Revised the feature list.
		• Revised Introduction section to remove classification information.
		• Updated optional information in the ordering information figure.
		• Revised Absolute maximum rating section:
		  • Removed category column from table
		  • Added footnote at Ta
		• Revised Recommended operating conditions section
		  • Added notes
		  • Updated table: Recommended operating conditions (VDD_HV_x = 3.3 V)
		  • Updated table: Recommended operating conditions (VDD_HV_x = 5 V)
		• Revised Voltage regulator electrical characteristics
		  • Updated text describing bipolar transistors
		  • Updated figure: Voltage regulator capacitance connection
		  • Updated table: Voltage regulator electrical specifications
		  • Removed Brownout information
		• Revised Voltage monitor electrical characteristics table

		• Revised Supply current characteristics section
		  • Updated table: Current consumption characteristics
		  • Updated table: Low Power Unit (LPU) Current consumption characteristics
		  • STANDBY Current consumption characteristics

Table continues on the next page...

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