

Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, I ² C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, Motor Control PWM, PDR, POR, PVD, PWM, Temp Sensor, WDT
Number of I/O	51
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	20K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TFBGA
Supplier Device Package	64-TFBGA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f103rbh6

5	Electrical characteristics	32
5.1	Parameter conditions	32
5.1.1	Minimum and maximum values	32
5.1.2	Typical values	32
5.1.3	Typical curves	32
5.1.4	Loading capacitor	32
5.1.5	Pin input voltage	32
5.1.6	Power supply scheme	33
5.1.7	Current consumption measurement	34
5.2	Absolute maximum ratings	34
5.3	Operating conditions	35
5.3.1	General operating conditions	35
5.3.2	Operating conditions at power-up / power-down	36
5.3.3	Embedded reset and power control block characteristics	36
5.3.4	Embedded reference voltage	38
5.3.5	Supply current characteristics	38
5.3.6	External clock source characteristics	47
5.3.7	Internal clock source characteristics	50
5.3.8	PLL characteristics	52
5.3.9	Memory characteristics	52
5.3.10	EMC characteristics	53
5.3.11	Absolute maximum ratings (electrical sensitivity)	55
5.3.12	I/O port characteristics	56
5.3.13	NRST pin characteristics	59
5.3.14	TIM timer characteristics	60
5.3.15	Communications interfaces	61
5.3.16	CAN (controller area network) interface	66
5.3.17	12-bit ADC characteristics	67
5.3.18	Temperature sensor characteristics	71
6	Package characteristics	72
6.1	Package mechanical data	72
6.2	Thermal characteristics	81
6.2.1	Reference document	81
6.2.2	Selecting the product temperature range	82
7	Ordering information scheme	84

8 **Revision history** 85



Figure 44.	LQFP48, 48-pin low-profile quad flat package outline	80
Figure 45.	Recommended footprint ⁽¹⁾	80
Figure 46.	LQFP100 P_D max vs. T_A	83

1 Introduction

This datasheet provides the ordering information and mechanical device characteristics of the STM32F103x8 and STM32F103xB medium-density performance line microcontrollers. For more details on the whole STMicroelectronics STM32F103xx family, please refer to [Section 2.2: Full compatibility throughout the family](#).

The medium-density STM32F103xx datasheet should be read in conjunction with the low-, medium- and high-density STM32F10xxx reference manual.

The reference and Flash programming manuals are both available from the STMicroelectronics website www.st.com.

For information on the Cortex™-M3 core please refer to the Cortex™-M3 Technical Reference Manual, available from the www.arm.com website at the following address: <http://infocenter.arm.com/help/index.jsp?topic=/com.arm.doc.ddi0337e/>.

2 Description

The STM32F103x8 and STM32F103xB performance line family incorporates the high-performance ARM Cortex™-M3 32-bit RISC core operating at a 72 MHz frequency, high-speed embedded memories (Flash memory up to 128 Kbytes and SRAM up to 20 Kbytes), and an extensive range of enhanced I/Os and peripherals connected to two APB buses. All devices offer two 12-bit ADCs, three general purpose 16-bit timers plus one PWM timer, as well as standard and advanced communication interfaces: up to two I²Cs and SPIs, three USARTs, an USB and a CAN.

The STM32F103xx medium-density performance line family operates from a 2.0 to 3.6 V power supply. It is available in both the –40 to +85 °C temperature range and the –40 to +105 °C extended temperature range. A comprehensive set of power-saving mode allows the design of low-power applications.

The STM32F103xx medium-density performance line family includes devices in six different package types: from 36 pins to 100 pins. Depending on the device chosen, different sets of peripherals are included, the description below gives an overview of the complete range of peripherals proposed in this family.

These features make the STM32F103xx medium-density performance line microcontroller family suitable for a wide range of applications:

- Motor drive and application control
- Medical and handheld equipment
- PC peripherals gaming and GPS platforms
- Industrial applications: PLC, inverters, printers, and scanners
- Alarm systems, Video intercom, and HVAC

[Figure 1](#) shows the general block diagram of the device family.

2.3.13 DMA

The flexible 7-channel general-purpose DMA is able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers. The DMA controller supports circular buffer management avoiding the generation of interrupts when the controller reaches the end of the buffer.

Each channel is connected to dedicated hardware DMA requests, with support for software trigger on each channel. Configuration is made by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals: SPI, I²C, USART, general-purpose and advanced-control timers TIMx and ADC.

2.3.14 RTC (real-time clock) and backup registers

The RTC and the backup registers are supplied through a switch that takes power either on V_{DD} supply when present or through the V_{BAT} pin. The backup registers are ten 16-bit registers used to store 20 bytes of user application data when V_{DD} power is not present.

The real-time clock provides a set of continuously running counters which can be used with suitable software to provide a clock calendar function, and provides an alarm interrupt and a periodic interrupt. It is clocked by a 32.768 kHz external crystal, resonator or oscillator, the internal low-power RC oscillator or the high-speed external clock divided by 128. The internal low-power RC has a typical frequency of 40 kHz. The RTC can be calibrated using an external 512 Hz output to compensate for any natural crystal deviation. The RTC features a 32-bit programmable counter for long-term measurement using the Compare register to generate an alarm. A 20-bit prescaler is used for the time base clock and is by default configured to generate a time base of 1 second from a clock at 32.768 kHz.

2.3.15 Timers and watchdogs

The medium-density STM32F103xx performance line devices include an advanced-control timer, three general-purpose timers, two watchdog timers and a SysTick timer.

[Table 4](#) compares the features of the advanced-control and general-purpose timers.

Table 4. Timer feature comparison

Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary outputs
TIM1	16-bit	Up, down, up/down	Any integer between 1 and 65536	Yes	4	Yes
TIM2, TIM3, TIM4	16-bit	Up, down, up/down	Any integer between 1 and 65536	Yes	4	No

Advanced-control timer (TIM1)

The advanced-control timer (TIM1) can be seen as a three-phase PWM multiplexed on 6 channels. It has complementary PWM outputs with programmable inserted dead-times. It

can also be seen as a complete general-purpose timer. The 4 independent channels can be used for

- Input capture
- Output compare
- PWM generation (edge- or center-aligned modes)
- One-pulse mode output

If configured as a general-purpose 16-bit timer, it has the same features as the TIMx timer. If configured as the 16-bit PWM generator, it has full modulation capability (0-100%).

In debug mode, the advanced-control timer counter can be frozen and the PWM outputs disabled to turn off any power switch driven by these outputs.

Many features are shared with those of the general-purpose TIM timers which have the same architecture. The advanced-control timer can therefore work together with the TIM timers via the Timer Link feature for synchronization or event chaining.

General-purpose timers (TIMx)

There are up to three synchronizable general-purpose timers embedded in the STM32F103xx performance line devices. These timers are based on a 16-bit auto-reload up/down counter, a 16-bit prescaler and feature 4 independent channels each for input capture/output compare, PWM or one-pulse mode output. This gives up to 12 input captures/output compares/PWMs on the largest packages.

The general-purpose timers can work together with the advanced-control timer via the Timer Link feature for synchronization or event chaining. Their counter can be frozen in debug mode. Any of the general-purpose timers can be used to generate PWM outputs. They all have independent DMA request generation.

These timers are capable of handling quadrature (incremental) encoder signals and the digital outputs from 1 to 3 hall-effect sensors.

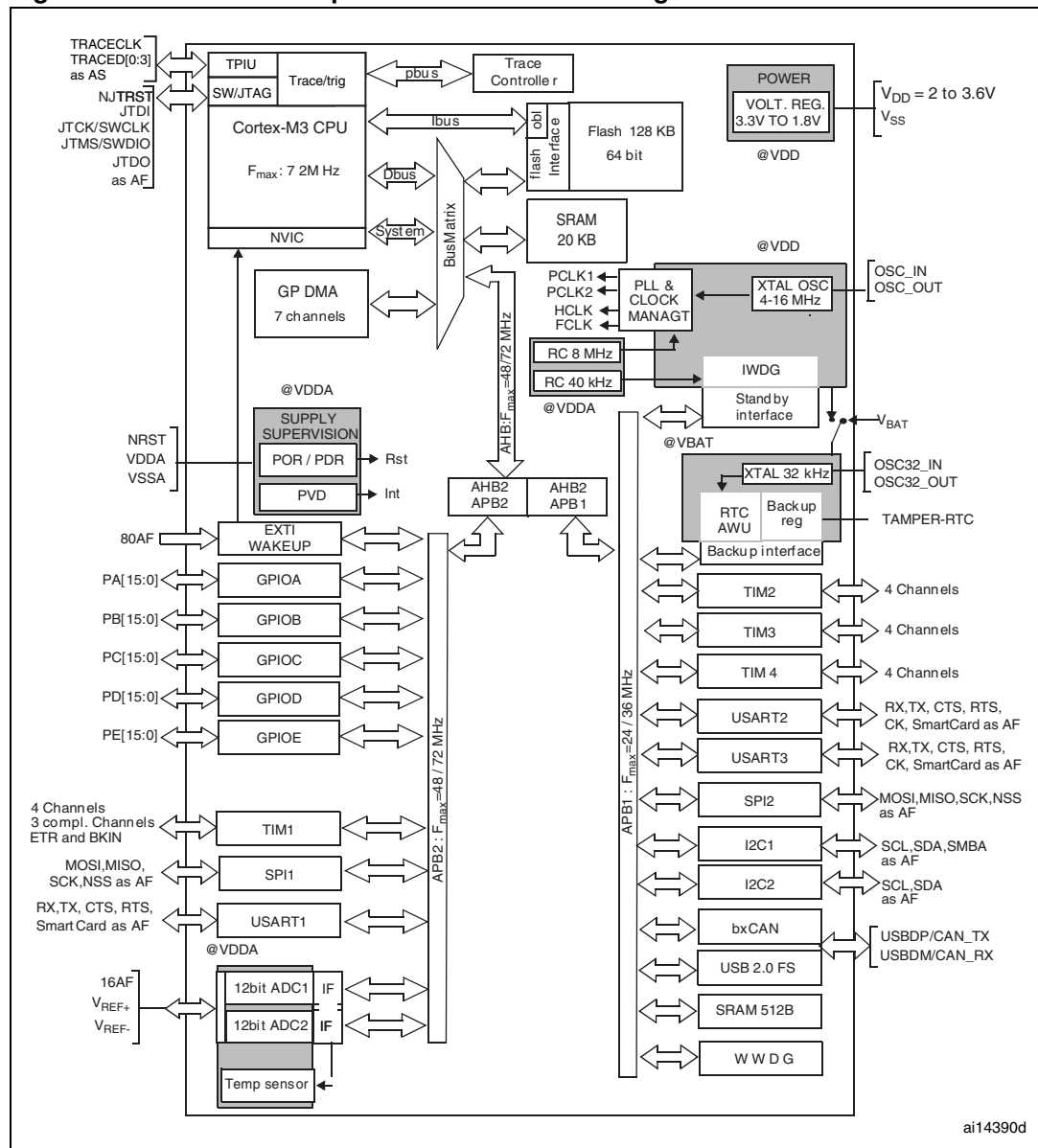
Independent watchdog

The independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 40 kHz internal RC and as it operates independently of the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free-running timer for application timeout management. It is hardware- or software-configurable through the option bytes. The counter can be frozen in debug mode.

Window watchdog

The window watchdog is based on a 7-bit downcounter that can be set as free-running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in debug mode.

Figure 1. STM32F103xx performance line block diagram



ai14390d

1. $T_A = -40\text{ }^{\circ}\text{C}$ to $+105\text{ }^{\circ}\text{C}$ (junction temperature up to $125\text{ }^{\circ}\text{C}$).
2. AF = alternate function on I/O port pin.

Table 5. Medium-density STM32F103xx pin definitions

Pins						Pin name	Type ⁽¹⁾	I / O Level ⁽²⁾	Main function ⁽³⁾ (after reset)	Alternate functions	
LFBGA100	LQFP48	TFBGA64	LQFP64	LQFP100	VFQFPN36					Default	Remap
A3	-		-	1	-	PE2	I/O	FT	PE2	TRACECK	
B3	-		-	2	-	PE3	I/O	FT	PE3	TRACED0	
C3	-		-	3	-	PE4	I/O	FT	PE4	TRACED1	
D3	-		-	4	-	PE5	I/O	FT	PE5	TRACED2	
E3	-		-	5	-	PE6	I/O	FT	PE6	TRACED3	
B2	1	B2	1	6	-	V _{BAT}	S		V _{BAT}		
A2	2	A2	2	7	-	PC13-TAMPER-RTC ⁽⁴⁾	I/O		PC13 ⁽⁵⁾	TAMPER-RTC	
A1	3	A1	3	8	-	PC14-OSC32_IN ⁽⁴⁾	I/O		PC14 ⁽⁵⁾	OSC32_IN	
B1	4	B1	4	9	-	PC15-OSC32_OUT ⁽⁴⁾	I/O		PC15 ⁽⁵⁾	OSC32_OUT	
C2	-	-	-	10	-	V _{SS_5}	S		V _{SS_5}		
D2	-	-	-	11	-	V _{DD_5}	S		V _{DD_5}		
C1	5	C1	5	12	2	OSC_IN	I		OSC_IN		
D1	6	D1	6	13	3	OSC_OUT	O		OSC_OUT		
E1	7	E1	7	14	4	NRST	I/O		NRST		
F1	-	E3	8	15	-	PC0	I/O		PC0	ADC12_IN10	
F2	-	E2	9	16	-	PC1	I/O		PC1	ADC12_IN11	
E2	-	F2	10	17	-	PC2	I/O		PC2	ADC12_IN12	
F3	-	_(6)	11	18	-	PC3	I/O		PC3	ADC12_IN13	
G1	8	F1	12	19	5	V _{SSA}	S		V _{SSA}		
H1	-	-	-	20	-	V _{REF-}	S		V _{REF-}		
J1	-	G1 ⁽⁶⁾	-	21	-	V _{REF+}	S		V _{REF+}		
K1	9	H1	13	22	6	V _{DDA}	S		V _{DDA}		
G2	10	G2	14	23	7	PA0-WKUP	I/O		PA0	WKUP/ USART2_CTS ⁽⁷⁾ / ADC12_IN0/ TIM2_CH1_ETR ⁽⁷⁾	
H2	11	H2	15	24	8	PA1	I/O		PA1	USART2_RTS ⁽⁷⁾ / ADC12_IN1/ TIM2_CH2 ⁽⁷⁾	
J2	12	F3	16	25	9	PA2	I/O		PA2	USART2_TX ⁽⁷⁾ / ADC12_IN2/ TIM2_CH3 ⁽⁷⁾	

Table 5. Medium-density STM32F103xx pin definitions (continued)

Pins						Pin name	Type ⁽¹⁾	I / O Level ⁽²⁾	Main function ⁽³⁾ (after reset)	Alternate functions	
LFBGA100	LQFP48	TFBGA64	LQFP64	LQFP100	VFQFPN36					Default	Remap
K2	13	G3	17	26	10	PA3	I/O		PA3	USART2_RX ⁽⁷⁾ / ADC12_IN3/ TIM2_CH4 ⁽⁷⁾	
E4	-	C2	18	27	-	V _{SS_4}	S		V _{SS_4}		
F4	-	D2	19	28	-	V _{DD_4}	S		V _{DD_4}		
G3	14	H3	20	29	11	PA4	I/O		PA4	SPI1_NSS ⁽⁷⁾ / USART2_CK ⁽⁷⁾ / ADC12_IN4	
H3	15	F4	21	30	12	PA5	I/O		PA5	SPI1_SCK ⁽⁷⁾ / ADC12_IN5	
J3	16	G4	22	31	13	PA6	I/O		PA6	SPI1_MISO ⁽⁷⁾ / ADC12_IN6/ TIM3_CH1 ⁽⁷⁾	TIM1_BKIN
K3	17	H4	23	32	14	PA7	I/O		PA7	SPI1_MOSI ⁽⁷⁾ / ADC12_IN7/ TIM3_CH2 ⁽⁷⁾	TIM1_CH1N
G4	-	H5	24	33		PC4	I/O		PC4	ADC12_IN14	
H4	-	H6	25	34		PC5	I/O		PC5	ADC12_IN15	
J4	18	F5	26	35	15	PB0	I/O		PB0	ADC12_IN8/ TIM3_CH3 ⁽⁷⁾	TIM1_CH2N
K4	19	G5	27	36	16	PB1	I/O		PB1	ADC12_IN9/ TIM3_CH4 ⁽⁷⁾	TIM1_CH3N
G5	20	G6	28	37	17	PB2	I/O	FT	PB2/BOOT1		
H5	-	-	-	38	-	PE7	I/O	FT	PE7		TIM1_ETR
J5	-	-	-	39	-	PE8	I/O	FT	PE8		TIM1_CH1N
K5	-	-	-	40	-	PE9	I/O	FT	PE9		TIM1_CH1
G6	-	-	-	41	-	PE10	I/O	FT	PE10		TIM1_CH2N
H6	-	-	-	42	-	PE11	I/O	FT	PE11		TIM1_CH2
J6	-	-	-	43	-	PE12	I/O	FT	PE12		TIM1_CH3N
K6	-	-	-	44	-	PE13	I/O	FT	PE13		TIM1_CH3
G7	-	-	-	45	-	PE14	I/O	FT	PE14		TIM1_CH4
H7	-	-	-	46	-	PE15	I/O	FT	PE15		TIM1_BKIN
J7	21	G7	29	47	-	PB10	I/O	FT	PB10	I2C2_SCL/ USART3_TX ⁽⁷⁾	TIM2_CH3
K7	22	H7	30	48	-	PB11	I/O	FT	PB11	I2C2_SDA/ USART3_RX ⁽⁷⁾	TIM2_CH4
E7	23	D6	31	49	18	V _{SS_1}	S		V _{SS_1}		

Table 5. Medium-density STM32F103xx pin definitions (continued)

Pins						Pin name	Type ⁽¹⁾	I / O Level ⁽²⁾	Main function ⁽³⁾ (after reset)	Alternate functions	
LFBGA100	LQFP48	TFBGA64	LQFP64	LQFP100	VFQFPN36					Default	Remap
F7	24	E6	32	50	19	V _{DD_1}	S		V _{DD_1}		
K8	25	H8	33	51	-	PB12	I/O	FT	PB12	SPI2_NSS/ I2C2_SMBAL/ USART3_CK ⁽⁷⁾ / TIM1_BKIN ⁽⁷⁾	
J8	26	G8	34	52	-	PB13	I/O	FT	PB13	SPI2_SCK/ USART3_CTS ⁽⁷⁾ / TIM1_CH1N ⁽⁷⁾	
H8	27	F8	35	53	-	PB14	I/O	FT	PB14	SPI2_MISO/ USART3_RTS ⁽⁷⁾ / TIM1_CH2N ⁽⁷⁾	
G8	28	F7	36	54	-	PB15	I/O	FT	PB15	SPI2_MOSI/ TIM1_CH3N ⁽⁷⁾	
K9	-	-	-	55	-	PD8	I/O	FT	PD8		USART3_TX
J9	-	-	-	56	-	PD9	I/O	FT	PD9		USART3_RX
H9	-	-	-	57	-	PD10	I/O	FT	PD10		USART3_CK
G9	-	-	-	58	-	PD11	I/O	FT	PD11		USART3_CTS
K10	-	-	-	59	-	PD12	I/O	FT	PD12		TIM4_CH1 / USART3_RTS
J10	-	-	-	60	-	PD13	I/O	FT	PD13		TIM4_CH2
H10	-	-	-	61	-	PD14	I/O	FT	PD14		TIM4_CH3
G10	-	-	-	62	-	PD15	I/O	FT	PD15		TIM4_CH4
F10	-	F6	37	63	-	PC6	I/O	FT	PC6		TIM3_CH1
E10	-	E7	38	64	-	PC7	I/O	FT	PC7		TIM3_CH2
F9	-	E8	39	65	-	PC8	I/O	FT	PC8		TIM3_CH3
E9	-	D8	40	66	-	PC9	I/O	FT	PC9		TIM3_CH4
D9	29	D7	41	67	20	PA8	I/O	FT	PA8	USART1_CK/ TIM1_CH1 ⁽⁷⁾ /MCO	
C9	30	C7	42	68	21	PA9	I/O	FT	PA9	USART1_TX ⁽⁷⁾ / TIM1_CH2 ⁽⁷⁾	
D10	31	C6	43	69	22	PA10	I/O	FT	PA10	USART1_RX ⁽⁷⁾ / TIM1_CH3 ⁽⁷⁾	
C10	32	C8	44	70	23	PA11	I/O	FT	PA11	USART1_CTS/ CANRX ⁽⁷⁾ /USBDP TIM1_CH4 ⁽⁷⁾	
B10	33	B8	45	71	24	PA12	I/O	FT	PA12	USART1_RTS/ CANTX ⁽⁷⁾ //USBDP TIM1_ETR ⁽⁷⁾	

Figure 10. Pin loading conditions

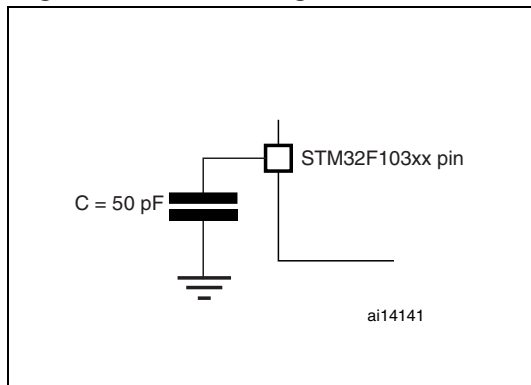
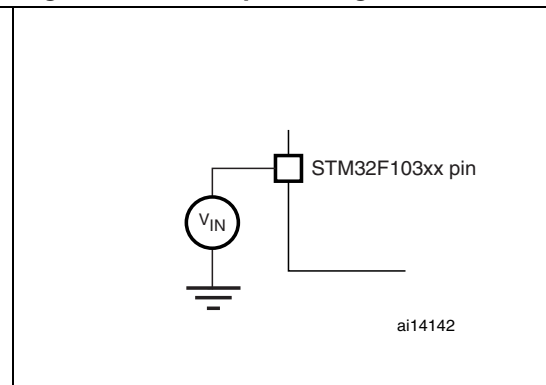
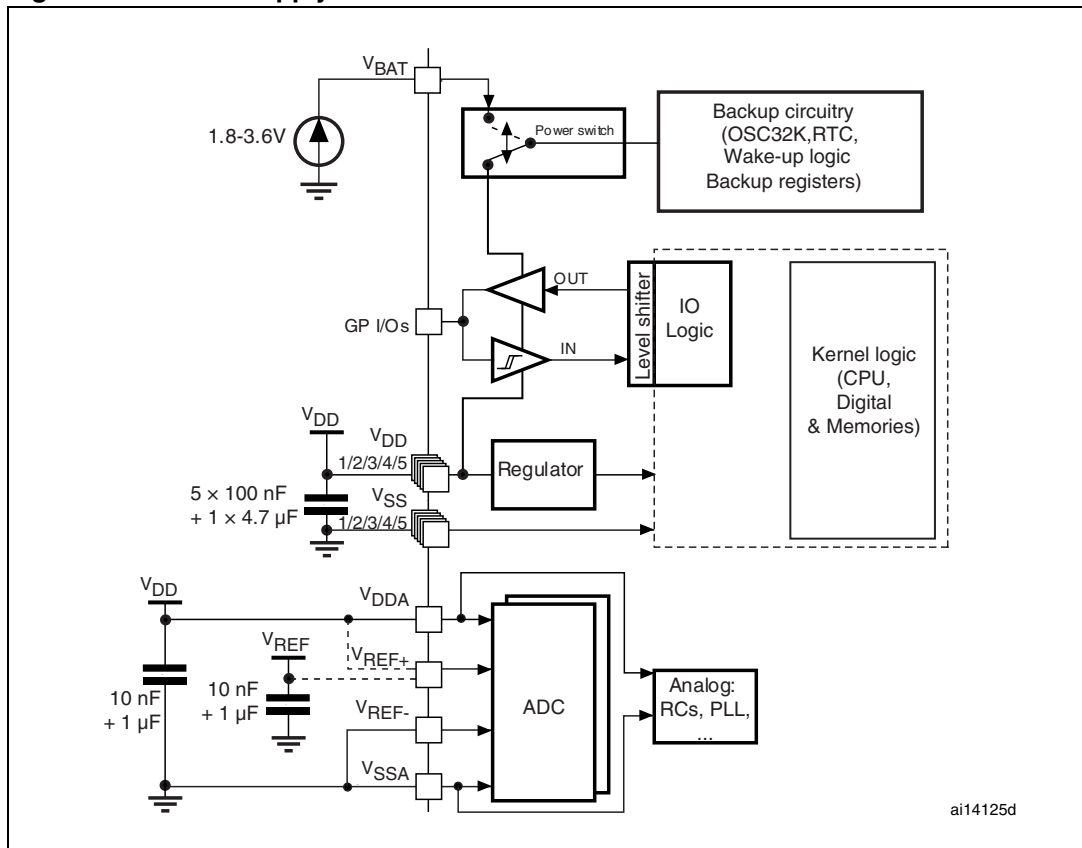


Figure 11. Pin input voltage



5.1.6 Power supply scheme

Figure 12. Power supply scheme



Caution: In [Figure 12](#), the $4.7 \mu\text{F}$ capacitor must be connected to V_{DD3} .

Table 9. General operating conditions (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
P_D	Power dissipation at $T_A = 85\text{ }^{\circ}\text{C}$ for suffix 6 or $T_A = 105\text{ }^{\circ}\text{C}$ for suffix 7 ⁽³⁾	LFBGA100		454	mW
		LQFP100		434	
		TFBGA64		308	
		LQFP64		444	
		LQFP48		363	
		VFQFPN36		1110	
T_A	Ambient temperature for 6 suffix version	Maximum power dissipation	-40	85	$^{\circ}\text{C}$
		Low power dissipation ⁽⁴⁾	-40	105	
	Ambient temperature for 7 suffix version	Maximum power dissipation	-40	105	$^{\circ}\text{C}$
		Low power dissipation ⁽⁴⁾	-40	125	
T_J	Junction temperature range	6 suffix version	-40	105	$^{\circ}\text{C}$
		7 suffix version	-40	125	

- When the ADC is used, refer to [Table 45: ADC characteristics](#).
- It is recommended to power V_{DD} and V_{DDA} from the same source. A maximum difference of 300 mV between V_{DD} and V_{DDA} can be tolerated during power-up and operation.
- If T_A is lower, higher P_D values are allowed as long as T_J does not exceed T_{Jmax} (see [Table 6.2: Thermal characteristics on page 81](#)).
- In low power dissipation state, T_A can be extended to this range as long as T_J does not exceed T_{Jmax} (see [Table 6.2: Thermal characteristics on page 81](#)).

5.3.2 Operating conditions at power-up / power-down

Subject to general operating conditions for T_A .

Table 10. Operating conditions at power-up / power-down

Symbol	Parameter	Conditions	Min	Max	Unit
t_{VDD}	V_{DD} rise time rate		0	∞	$\mu\text{s/V}$
	V_{DD} fall time rate		20	∞	

5.3.3 Embedded reset and power control block characteristics

The parameters given in [Table 11](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 9](#).

5.3.4 Embedded reference voltage

The parameters given in [Table 12](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 9](#).

Table 12. Embedded internal reference voltage

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{REFINT}	Internal reference voltage	$-40\text{ }^{\circ}\text{C} < T_A < +105\text{ }^{\circ}\text{C}$	1.16	1.20	1.26	V
		$-40\text{ }^{\circ}\text{C} < T_A < +85\text{ }^{\circ}\text{C}$	1.16	1.20	1.24	V
$T_{S_vrefint}^{(1)}$	ADC sampling time when reading the internal reference voltage			5.1	17.1 ⁽²⁾	μs

1. Shortest sampling time can be determined in the application by multiple iterations.

2. Guaranteed by design, not tested in production.

5.3.5 Supply current characteristics

The current consumption is a function of several parameters and factors such as the operating voltage, ambient temperature, I/O pin loading, device software configuration, operating frequencies, I/O pin switching rate, program location in memory and executed binary code.

The current consumption is measured as described in [Figure 13: Current consumption measurement scheme](#).

All Run-mode current consumption measurements given in this section are performed with a reduced code that gives a consumption equivalent to Dhrystone 2.1 code.

Maximum current consumption

The MCU is placed under the following conditions:

- All I/O pins are in input mode with a static value at V_{DD} or V_{SS} (no load)
- All peripherals are disabled except when explicitly mentioned
- The Flash memory access time is adjusted to the f_{HCLK} frequency (0 wait state from 0 to 24 MHz, 1 wait state from 24 to 48 MHz and 2 wait states above)
- Prefetch in ON (reminder: this bit must be set before clock setting and bus prescaling)
- When the peripherals are enabled $f_{PCLK1} = f_{HCLK}/2$, $f_{PCLK2} = f_{HCLK}$

The parameters given in [Table 13](#), [Table 14](#) and [Table 15](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 9](#).

Table 15. Maximum current consumption in Sleep mode, code running from Flash or RAM

Symbol	Parameter	Conditions	f_{HCLK}	Max ⁽¹⁾		Unit
				$T_A = 85\text{ }^{\circ}\text{C}$	$T_A = 105\text{ }^{\circ}\text{C}$	
I_{DD}	Supply current in Sleep mode	External clock ⁽²⁾ , all peripherals enabled	72 MHz	30	32	mA
			48 MHz	20	20.5	
			36 MHz	15.5	16	
			24 MHz	11.5	12	
			16 MHz	8.5	9	
			8 MHz	5.5	6	
		External clock ⁽²⁾ , all peripherals disabled	72 MHz	7.5	8	
			48 MHz	6	6.5	
			36 MHz	5	5.5	
			24 MHz	4.5	5	
			16 MHz	4	4.5	
			8 MHz	3	4	

1. based on characterization, tested in production at $V_{DD\text{ max}}$, $f_{HCLK\text{ max}}$ with peripherals enabled.

2. External clock is 8 MHz and PLL is on when $f_{HCLK} > 8\text{ MHz}$.

Table 18. Typical current consumption in Sleep mode, code running from Flash or RAM

Symbol	Parameter	Conditions	f _{HCLK}	Typ ⁽¹⁾		Unit
				All peripherals enabled ⁽²⁾	All peripherals disabled	
I _{DD}	Supply current in Sleep mode	External clock ⁽³⁾	72 MHz	14.4	5.5	mA
			48 MHz	9.9	3.9	
			36 MHz	7.6	3.1	
			24 MHz	5.3	2.3	
			16 MHz	3.8	1.8	
			8 MHz	2.1	1.2	
			4 MHz	1.6	1.1	
			2 MHz	1.3	1	
			1 MHz	1.11	0.98	
			500 kHz	1.04	0.96	
			125 kHz	0.98	0.95	
		Running on high speed internal RC (HSI), AHB prescaler used to reduce the frequency	64 MHz	12.3	4.4	
			48 MHz	9.3	3.3	
			36 MHz	7	2.5	
			24 MHz	4.8	1.8	
			16 MHz	3.2	1.2	
			8 MHz	1.6	0.6	
			4 MHz	1	0.5	
			2 MHz	0.72	0.47	
			1 MHz	0.56	0.44	
			500 kHz	0.49	0.42	
			125 kHz	0.43	0.41	

1. Typical values are measures at T_A = 25 °C, V_{DD} = 3.3 V.
2. Add an additional power consumption of 0.8 mA per ADC for the analog part. In applications, this consumption occurs only while the ADC is on (ADON bit is set in the ADC_CR2 register).
3. External clock is 8 MHz and PLL is on when f_{HCLK} > 8 MHz.

5.3.6 External clock source characteristics

High-speed external user clock generated from an external source

The characteristics given in [Table 20](#) result from tests performed using an high-speed external clock source, and under ambient temperature and supply voltage conditions summarized in [Table 9](#).

Table 20. High-speed external user clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency ⁽¹⁾		0	8	25	MHz
V_{HSEH}	OSC_IN input pin high level voltage		$0.7V_{DD}$		V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}		$0.3V_{DD}$	
$t_{w(HSE)}$ $t_{w(HSE)}$	OSC_IN high or low time ⁽¹⁾		16			ns
$t_{r(HSE)}$ $t_{f(HSE)}$	OSC_IN rise or fall time ⁽¹⁾				20	
$C_{in(HSE)}$	OSC_IN input capacitance ⁽¹⁾			5		pF
$DuCy_{(HSE)}$	Duty cycle		45		55	%
I_L	OSC_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_D$			± 1	μA

1. Guaranteed by design, not tested in production.

Low-speed external user clock generated from an external source

The characteristics given in [Table 21](#) result from tests performed using an low-speed external clock source, and under ambient temperature and supply voltage conditions summarized in [Table 9](#).

Table 21. Low-speed external user clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{LSE_ext}	User External clock source frequency ⁽¹⁾			32.768	1000	kHz
V_{LSEH}	OSC32_IN input pin high level voltage		$0.7V_{DD}$		V_{DD}	V
V_{LSEL}	OSC32_IN input pin low level voltage		V_{SS}		$0.3V_{DD}$	
$t_{w(LSE)}$ $t_{w(LSE)}$	OSC32_IN high or low time ⁽¹⁾		450			ns
$t_{r(LSE)}$ $t_{f(LSE)}$	OSC32_IN rise or fall time ⁽¹⁾				50	
$C_{in(LSE)}$	OSC32_IN input capacitance ⁽¹⁾			5		pF
$DuCy_{(LSE)}$	Duty cycle		30		70	%
I_L	OSC32_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_D$			± 1	μA

Table 28. Flash memory characteristics (continued)

Symbol	Parameter	Conditions	Min ⁽¹⁾	Typ	Max ⁽¹⁾	Unit
I _{DD}	Supply current	Read mode f _{HCLK} = 72 MHz with 2 wait states, V _{DD} = 3.3 V			20	mA
		Write / Erase modes f _{HCLK} = 72 MHz, V _{DD} = 3.3 V			5	mA
		Power-down mode / Halt, V _{DD} = 3.0 to 3.6 V			50	μA
V _{prog}	Programming voltage		2		3.6	V

1. Guaranteed by design, not tested in production.

Table 29. Flash memory endurance and data retention

Symbol	Parameter	Conditions	Value			Unit
			Min ⁽¹⁾	Typ	Max	
N _{END}	Endurance	T _A = -40 to +85 °C (6 suffix versions) T _A = -40 to +105 °C (7 suffix versions)	10			kcycles
t _{RET}	Data retention	1 kcycle ⁽²⁾ at T _A = 85 °C	30			Years
		1 kcycle ⁽²⁾ at T _A = 105 °C	10			
		10 kcycles ⁽²⁾ at T _A = 55 °C	20			

1. Based on characterization, not tested in production.

2. Cycling performed over the whole temperature range.

5.3.10 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

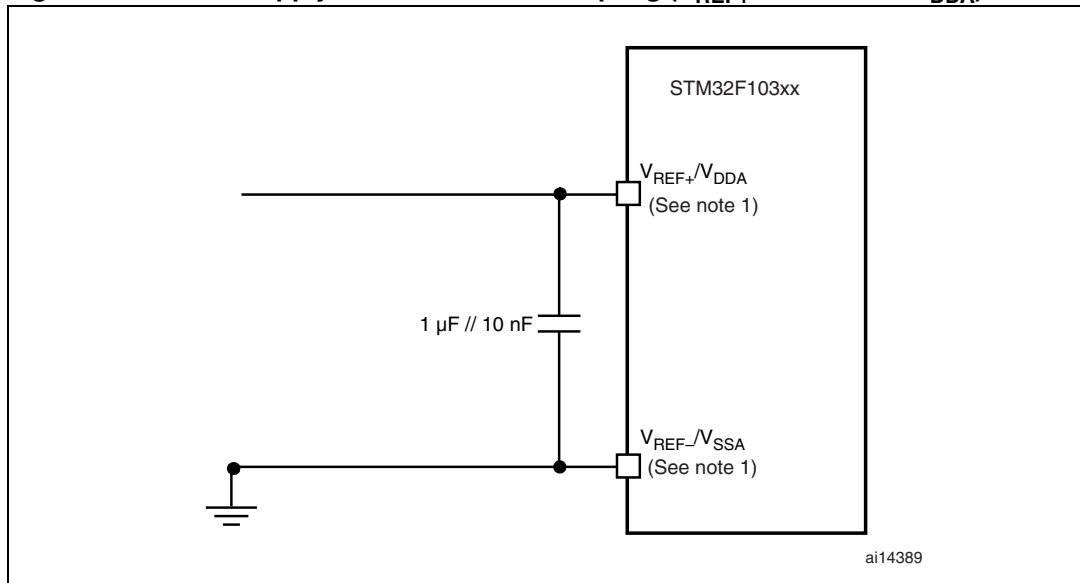
Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports), the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- **Electrostatic discharge (ESD)** (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 1000-4-2 standard.
- **FTB**: A Burst of Fast Transient voltage (positive and negative) is applied to V_{DD} and V_{SS} through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 1000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in [Table 30](#). They are based on the EMS levels and classes defined in application note AN1709.

Figure 33. Power supply and reference decoupling (V_{REF+} connected to V_{DDA})

1. V_{REF+} and V_{REF-} inputs are available only on 100-pin packages.

5.3.18 Temperature sensor characteristics

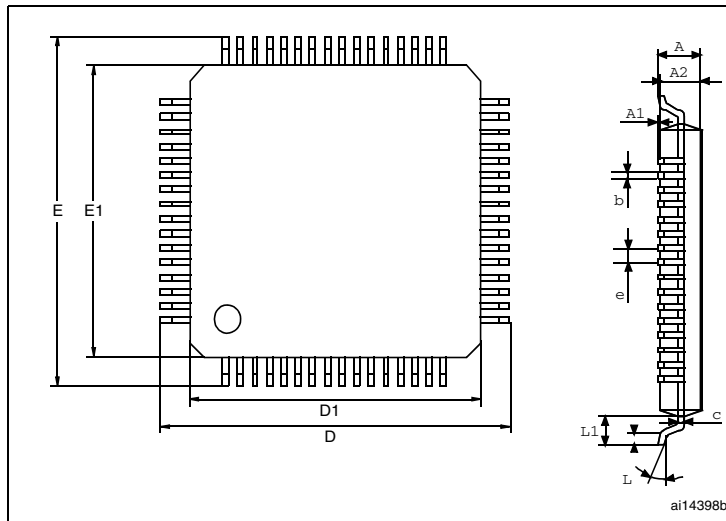
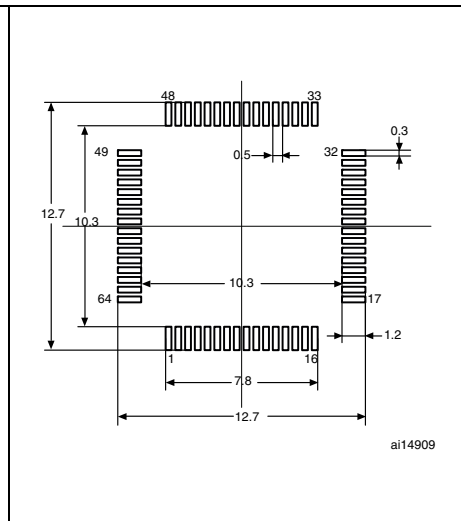
Table 49. TS characteristics

Symbol	Parameter	Min	Typ	Max	Unit
$T_L^{(1)}$	V_{SENSE} linearity with temperature		± 1	± 2	$^{\circ}\text{C}$
$\text{Avg_Slope}^{(1)}$	Average slope	4.0	4.3	4.6	$\text{mV}/^{\circ}\text{C}$
$V_{25}^{(1)}$	Voltage at 25 $^{\circ}\text{C}$	1.34	1.43	1.52	V
$t_{\text{START}}^{(2)}$	Startup time	4		10	μs
$T_{\text{S_temp}}^{(3)(2)}$	ADC sampling time when reading the temperature			17.1	μs

1. Based on characterization, not tested in production.

2. Guaranteed by design, not tested in production.

3. Shortest sampling time can be determined in the application by multiple iterations.

Figure 40. LQFP64, 64-pin low-profile quad flat package outline⁽¹⁾**Figure 41. Recommended footprint⁽¹⁾⁽²⁾**

1. Drawing is not to scale.

2. Dimensions are in millimeters.

Table 53. LQFP64, 64-pin low-profile quad flat package mechanical data

Dim.	mm			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A			1.60			0.0630
A1	0.05		0.15	0.0020		0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0571
b	0.17	0.22	0.27	0.0067	0.0087	0.0106
c	0.09		0.20	0.0035		0.0079
D		12.00			0.4724	
D1		10.00			0.3937	
E		12.00			0.4724	
E1		10.00			0.3937	
e		0.50			0.0197	
θ	0°	3.5°	7°	0°	3.5°	7°
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1		1.00			0.0394	
N	Number of pins					
	64					

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Using the values obtained in [Table 56](#) T_{Jmax} is calculated as follows:

– For LQFP100, 46 °C/W

$$T_{Jmax} = 115\text{ °C} + (46\text{ °C/W} \times 134\text{ mW}) = 115\text{ °C} + 6.2\text{ °C} = 121.2\text{ °C}$$

This is within the range of the suffix 7 version parts ($-40 < T_J < 125\text{ °C}$).

In this case, parts must be ordered at least with the temperature range suffix 7 (see [Table 57: Ordering information scheme](#)).

Figure 46. LQFP100 P_D max vs. T_A

