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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product StatusActiveCore ProcessorARM® Cortex®-M4Core Size32-Bit Single-CoreSpeed72MHz	
Core Size 32-Bit Single-Core	
Speed 72MHz	
Connectivity CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART, USB	
Peripherals DMA, I <sup>2</sup> S, POR, PWM, WDT	
Number of I/O 51	
Program Memory Size 512KB (512K x 8)	
Program Memory Type FLASH	
EEPROM Size -	
RAM Size 64K x 8	
Voltage - Supply (Vcc/Vdd) 2V ~ 3.6V	
Data ConvertersA/D 16x12b; D/A 1x12b	
Oscillator Type Internal	
Operating Temperature -40°C ~ 105°C (TA)	
Mounting Type Surface Mount	
Package / Case 64-LQFP	
Supplier Device Package64-LQFP (10x10)	
Purchase URL https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f302ret7tr	

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# 3.8 General-purpose inputs/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain), as input (with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions. All GPIOs are high current capable except for analog inputs.

The I/Os alternate function configuration can be locked if needed following a specific sequence in order to avoid spurious writing to the I/Os registers.

Fast I/O handling allows I/O toggling up to 36 MHz.

# 3.9 Direct memory access (DMA)

The flexible general-purpose DMA is able to manage memory-to-memory, peripheral-tomemory and memory-to-peripheral transfers. The DMA controller supports circular buffer management, avoiding the generation of interrupts when the controller reaches the end of the buffer.

Each of the 7 DMA channels is connected to dedicated hardware DMA requests, with software trigger support for each channel. Configuration is done by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals: SPI, I<sup>2</sup>C, USART, timers, DAC and ADC.

# 3.10 Interrupts and events

### 3.10.1 Nested vectored interrupt controller (NVIC)

The STM32F302x6/8 devices embed a nested vectored interrupt controller (NVIC) able to handle up to 60 maskable interrupt channels and 16 priority levels.

The NVIC benefits are the following:

- Closely coupled NVIC gives low latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Closely coupled NVIC core interface
- Allows early processing of interrupts
- Processing of late arriving higher priority interrupts
- Support for tail chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

The NVIC hardware block provides flexible interrupt management features with minimal interrupt latency.



# 3.11 Fast analog-to-digital converter (ADC)

An analog-to-digital converter, with selectable resolution between 12 and 6 bit, is embedded in the STM32F302x6/8 family devices. The ADC has up to 15 external channels performing conversions in single-shot or scan modes. Channels can be configured to be either singleended input or differential input. In scan mode, automatic conversion is performed on a selected group of analog inputs.

Additional logic functions embedded in the ADC interface allow:

- Simultaneous sample and hold
- Single-shunt phase current reading techniques.

The ADC can be served by the DMA controller.

Three analog watchdogs are available. The analog watchdog feature allows very precise monitoring of the converted voltage of one, some or all selected channels. An interrupt is generated when the converted voltage is outside the programmed thresholds.

The events generated by the general-purpose timers (TIMx) and the advanced-control timer (TIM1) can be internally connected to the ADC start trigger and injection trigger, respectively, to allow the application to synchronize A/D conversion and timers.

### 3.11.1 Temperature sensor

The temperature sensor (TS) generates a voltage  $\mathsf{V}_{\mathsf{SENSE}}$  that varies linearly with temperature.

The temperature sensor is internally connected to the ADC1\_IN16 input channel which is used to convert the sensor output voltage into a digital value.

The sensor provides good linearity but it has to be calibrated to obtain good overall accuracy of the temperature measurement. As the offset of the temperature sensor varies from chip to chip due to process variation, the uncalibrated internal temperature sensor is suitable for applications that detect temperature changes only.

To improve the accuracy of the temperature sensor measurement, each device is individually factory-calibrated by ST. The temperature sensor factory calibration data are stored by ST in the system memory area, accessible in read-only mode.

# 3.11.2 Internal voltage reference (V<sub>REFINT</sub>)

The internal voltage reference ( $V_{REFINT}$ ) provides a stable (bandgap) voltage output for the ADC and Comparators.  $V_{REFINT}$  is internally connected to the ADC1\_IN18 input channel. The precise voltage of  $V_{REFINT}$  is individually measured for each part by ST during production test and stored in the system memory area. It is accessible in read-only mode.



## 3.11.3 V<sub>BAT</sub> battery voltage monitoring

This embedded hardware feature allows the application to measure the V<sub>BAT</sub> battery voltage using the internal ADC channel ADC1\_IN17. As the V<sub>BAT</sub> voltage may be higher than V<sub>DDA</sub>, and thus outside the ADC input range, the V<sub>BAT</sub> pin is internally connected to a bridge divider by 2. As a consequence, the converted digital value is half the V<sub>BAT</sub> voltage.

# 3.12 Digital-to-analog converter (DAC)

One 12-bit buffered DAC channel (DAC1\_OUT1) can be used to convert digital signals into analog voltage signal outputs. The chosen design structure is composed of integrated resistor strings and an amplifier in inverting configuration.

This digital interface supports the following features:

- One DAC output channel
- 8-bit or 12-bit monotonic output
- Left or right data alignment in 12-bit mode
- Synchronized update capability
- Noise-wave generation
- Triangular-wave generation
- DMA capability
- External triggers for conversion

# 3.13 Operational amplifier (OPAMP)

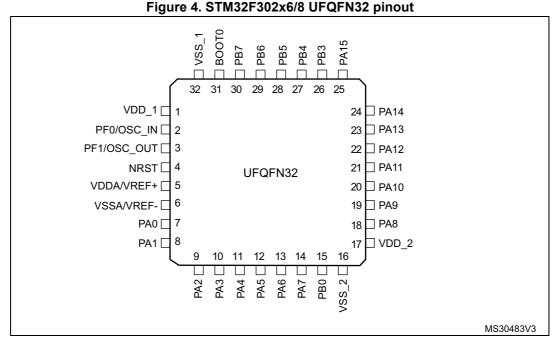
The STM32F302x6/8 devices embed one operational amplifier with external or internal follower routing and PGA capability (or even amplifier and filter capability with external components). When the operational amplifier is selected, an external ADC channel is used to enable output measurement.

The operational amplifier features:

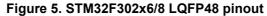
- 8.2 MHz bandwidth
- 0.5 mA output capability
- Rail-to-rail input/output
- In PGA mode, the gain can be programmed to be 2, 4, 8 or 16.

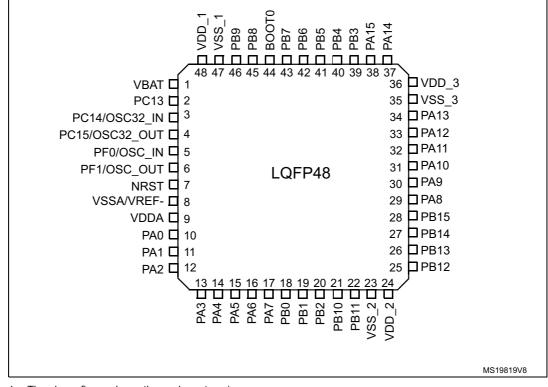


# 4 Pinouts and pin description



1. The above figure shows the package top view.





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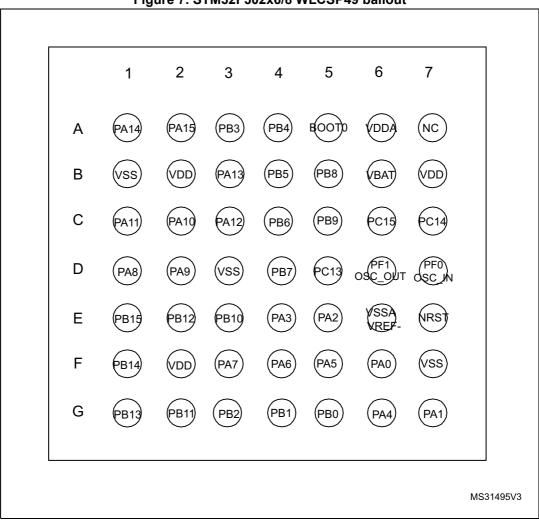


Figure 7. STM32F302x6/8 WLCSP49 ballout

1. The above figure shows the package top view.

2. NC: Not connected.



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	Table 12. STM32F302x6/8 pin definitions (continued)         Pin Number												
UQFN32	WLCSP49	LQFP48	LQFP64	Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions				
-	-	-	24	PC4	I/O	TT	-	EVENTOUT, TIM1_ETR, USART1_TX					
-	-	-	25	PC5	I/O	TTa	-	EVENTOUT, TIM15_BKIN, TSC_G3_IO1, USART1_RX	OPAMP2_VINM				
15	G5	18	26	PB0	I/O	TTa	-	TSC_G3_IO2, TIM1_CH2N, EVENTOUT	ADC1_IN11, COMP4_INP, OPAMP2_VINP				
-	G4	19	27	PB1	I/O	TTa	-	TSC_G3_IO3, TIM1_CH3N, COMP4_OUT, EVENTOUT	ADC1_IN12				
-	G3	20	28	PB2	I/O	TTa	-	TSC_G3_IO4, EVENTOUT	COMP4_INM				
-	E3	21	29	PB10	I/O	TT	-	TIM2_CH3, TSC_SYNC, USART3_TX, EVENTOUT					
-	G2	22	30	PB11	I/O	TTa	-	TIM2_CH4, TSC_G6_IO1, USART3_RX, EVENTOUT	ADC1_IN14, COMP6_INP				
16	D3	23	31	VSS_2	S	-	-	Digital	ground				
17	B2	24	32	VDD_2	S	-	-	Digital pov	wer supply				
-	E2	25	33	PB12	I/O	TT	-	TSC_G6_IO2, I2C2_SMBAL, SPI2_NSS/I2S2_WS, TIM1_BKIN, USART3_CK, EVENTOUT					
-	G1	26	34	PB13	I/O	ТТа	-	TSC_G6_IO3, SPI2_SCK/I2S2_CK, TIM1_CH1N, USART3_CTS, EVENTOUT	ADC1_IN13				

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r	1				Та	ble 14. A	Alternate	functior	ns for Po	rt B	-					
	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
Port & pin name	SYS_AF	TIM2/TIM15/TIM16 /TIM17/EVENT	I2C3/TIM1/TIM2/TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3/Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/Infrared	USART1/USART2/USART3/ CAN/GPCOMP6	I2C3/GPCOMP2 /GPCOMP4/GPCOMP6	CAN/TIM1/TIM15	TIM2/TIM17	TIM1	TIM1		1	EVENT
PB0	-	-	-	TSC _G3_IO2	-	-	TIM1 _CH2N	-	-	-	-	-	-	-	-	EVENT OUT
PB1	-	-	-	TSC _G3_IO3	-	-	TIM1 _CH3N	-	COMP4_ OUT	-	-	-	-	-	-	EVENT OUT
PB2				TSC _G3_IO4	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
PB3	JTDO- TRACE SWO	TIM2 _CH2	-	TSC _G5_IO1	-	-	SPI3_SC K/I2S3_ CK	USART2 _TX	-	-	-	-	-	-	-	EVENT OUT
PB4	JTRST	TIM16 _CH1	-	TSC _G5_IO2	-	-	SPI3_MI SO/I2S3 _SD	USART2 _RX	-	-	TIM17 _BKIN	-	-	-	-	EVENT OUT
PB5	-	TIM16 _BKIN	-	-	I2C1 _SMBAI	-	SPI3 _MOSI/ I2S3ext_ SD	USART2 _CK	I2C3 _SDA	-	TIM17 _CH1	-	-	-	-	EVENT OUT
PB6	-	TIM16 _CH1N	-	TSC _G5_IO3	I2C1 _SCL	-	-	USART1 _TX	-	-	-	-	-	-	-	EVENT OUT
PB7	-	TIM17 _CH1N	-	TSC _G5_IO4	l2C1 _SDA	-	-	USART1 _RX	-	-	-	-	-	-	-	EVENT OUT
PB8	-	TIM16 _CH1	-	TSC _SYNC	I2C1 _SCL	-	-	USART3 _RX	-	CAN _RX	-	-	TIM1 _BKIN	-	-	EVENT OUT

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				Table 1	6. Alternate fund	ctions for Port D	)		
Ĩ		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
	Port & pin name	SYS_AF	TIM2/TIM15/ TIM16/TIM17/ EVENT	I2C3/TIM1/TIM2/ TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3/ Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/ Infrared	USART1/ USART2/ USART3/CAN/ GPCOMP6
	PD2	-	EVENTOUT	-	-	-	_	-	-

Table 17. Alternate functions for Port F

Dout 9	AF0 AF1		AF2	AF3	AF4	AF5	AF6	AF7	
Port & pin name	SYS_AF	TIM2/TIM15/ TIM16/TIM17/ EVENT	I2C3/TIM1/TIM2/ TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3/ Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/ Infrared	USART1/USAR T2/USART3/ CAN/GPCOMP6	
PF0	-	-	-	-	I2C2_SDA	SPI2_NSS/ I2S2_WS	TIM1_CH3N	-	
PF1	-	-	-	-	I2C2_SCL	SPI2_SCK/ I2S2_CK	-	-	

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Pinouts and pin description

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# 6.2 Absolute maximum ratings

Stresses above the absolute maximum ratings listed in *Table 19: Voltage characteristics*, *Table 20: Current characteristics*, and *Table 21: Thermal characteristics* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Symbol	Ratings	Min	Max	Unit
V <sub>DD</sub> -V <sub>SS</sub>	External main supply voltage (including $V_{DDA,}$ $V_{BAT}$ and $V_{DD})$	-0.3	4.0	V
V <sub>DD</sub> –V <sub>DDA</sub>	Allowed voltage difference for $V_{DD} > V_{DDA}$	-	0.4	V
	Input voltage on FT and FTf pins	V <sub>SS</sub> –0.3	V <sub>DD</sub> + 4.0	
	Input voltage on TTa and TT pins	V <sub>SS</sub> –0.3		
V <sub>IN</sub> <sup>(2)</sup>	Input voltage on any other pin	V <sub>SS</sub> -0.3	4.0	V
	Input voltage on Boot0 pin	0	9	
$ \Delta V_{DDx} $	Variations between different V <sub>DD</sub> power pins	-	50	mV
V <sub>SSX</sub> –V <sub>SS</sub>	Variations between all the different ground pins <sup>(3)</sup>	-	50	111V
V <sub>ESD(HBM)</sub>	Electrostatic discharge voltage (human body model)	see Section 6.3. sensitivity charac		V

Table 19. Voltag	ge characteristics <sup>(1)</sup>
------------------	-----------------------------------

All main power (V<sub>DD</sub>, V<sub>DDA</sub>) and ground (V<sub>SS</sub>, V<sub>SSA</sub>) pins must always be connected to the external power supply, in the permitted range. The following relationship must be respected between V<sub>DDA</sub> and V<sub>DD</sub>: V<sub>DDA</sub> must power on before or at the same time as V<sub>DD</sub> in the power up sequence. V<sub>DDA</sub> must be greater than or equal to V<sub>DD</sub>.

2. V<sub>IN</sub> maximum must always be respected. Refer to *Table 20: Current characteristics* for the maximum allowed injected current values.

3. Include V<sub>REF-</sub> pin.



					V <sub>DDA</sub>	= 2.4 V			V <sub>DDA</sub>	= 3.6 \	/				
Symbol	Parameter	Conditions (1)	f <sub>HCLK</sub>	Тур	М	ax @ T <sub>A</sub>	(2)	Тур	м	Unit					
				тур	25 °C	85 °C	105 °C	קני	25 °C	85 °C	105 °C				
			72 MHz	231	254 <sup>(3)</sup>	266	271 <sup>(3)</sup>	251	274 <sup>(3)</sup>	294	300 <sup>(3)</sup>				
		64 MHz	203	226	239	243	222	245	261	266					
	Supply current in	in	48 MHz	153	174	182	186	165	185	198	203	- - - μΑ			
			32 MHz	105	124	131	133	114	132	141	143				
			24 MHz	82	98	104	105	89	106	111	113				
	Run mode, code		8 MHz	3.1	4.1	4.1	5.1	3.6	4.7	5.2	5.5				
I <sub>DDA</sub>	executing		1 MHz	3.1	4.1	4.1	5.1	3.6	4.7	5.2	5.5				
	from Flash or RAM		64 MHz	270	294	307	312	296	322	338	343				
	UI RAIVI		48 MHz	219	242	253	257	240	263	276	281				
		HSI clock	32 MHz	171	192	201	203	188	209	219	222	1			
			24 MHz	148	169	175	177	163	182	190	193				
							8 MHz	69	84	87	87	79	92	94	96

Table 29. Typical and maximum current consumption from the  $V_{\text{DDA}}$  supply

1. Current consumption from the  $V_{DDA}$  supply is independent of whether the peripherals are on or off. Furthermore when the PLL is off,  $I_{DDA}$  is independent from the frequency.

2. Guaranteed by characterization results.

3. Data based on characterization results and tested in production with code executing from RAM.

		Conditions		Тур (	@V <sub>DD</sub> (	(V <sub>DD</sub> =\							
Symbol	Parameter		2.0 V	2.4 V	2.7 V	3.0 V	3.3 V	3.6 V	T <sub>A</sub> = 25 °C	T <sub>A</sub> = 85 °C	T <sub>A</sub> = 105 °C	Unit	
	Supply current in Stop mode	Regulator in run mode, all oscillators OFF	16.92	17.09	17.16	17.27	17.39	17.50	29.7	359.1	564.5	_	
		Regulator in low-power mode, all oscillators OFF	5.29	5.46	5.55	5.70	5.73	5.95	16.40	267.1	407.4		
I <sub>DD</sub>	Supply	LSI ON and IWDG ON	0.80	0.93	1.11	1.19	1.31	1.41	-	-	-	. I	
c S	current in Standby mode	LSI OFF and IWDG OFF	0.63	0.76	0.84	0.95	1.02	1.10	5.00	6.30	12.60		

### Table 30. Typical and maximum $V_{\text{DD}}$ consumption in Stop and Standby modes

1. Guaranteed by characterization results.



### **On-chip peripheral current consumption**

The MCU is placed under the following conditions:

- all I/O pins are in analog input configuration
- all peripherals are disabled unless otherwise mentioned
- the given value is calculated by measuring the current consumption
  - with all peripherals clocked off
  - with only one peripheral clocked on
- ambient operating temperature at 25°C and  $V_{DD} = V_{DDA} = 3.3$  V.



Davishand	Typical consumption <sup>(1)</sup>	
Peripheral	I <sub>DD</sub>	
BusMatrix <sup>(2)</sup>	11.3	
DMA1	6.7	
CRC	2.0	
GPIOA	8.5	
GPIOB	8.3	
GPIOC	8.6	
GPIOD	1.5	
GPIOF	1.0	
TSC	4.7	
ADC1	15.9	
APB2-Bridge <sup>(3)</sup>	2.7	
SYSCFG	3.2	
TIM1	27.6	
USART1	21.0	
TIM15	14.3	
TIM16	10.1	
TIM17	10.4	μA/MHz
APB1-Bridge <sup>(3)</sup>	5.8	
TIM2	40.7	
TIM6	7.4	
WWDG	4.6	
SPI2	35.2	
SPI3	34.2	
USART2	13.9	
USART3	13.1	
I2C1	9.4	
I2C2	9.4	
USB	17.4	
CAN	28.8	
PWR	4.5	
DAC	8.3	
I2C3	10.5	

### Table 36. Peripheral current consumption

 The power consumption of the analog part (I<sub>DDA</sub>) of peripherals such as ADC, DAC, Comparators, OpAmp etc. is not included. Refer to the tables of characteristics in the subsequent sections.

2. BusMatrix is automatically active when at least one master is ON (CPU or DMA1).

3. The APBx bridge is automatically active when at least one peripheral is ON on the same bus.



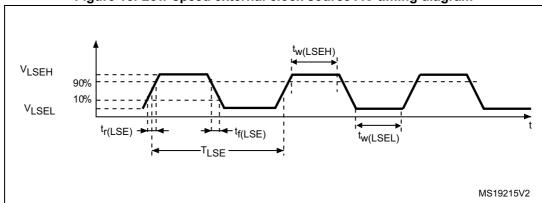
### Low-speed external user clock generated from an external source

In bypass mode the LSE oscillator is switched off and the input pin is a standard GPIO. The external clock signal has to respect the I/O characteristics in *Section 6.3.14*. However, the recommended clock input waveform is shown in *Figure 15* 

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
f <sub>LSE_ext</sub>	User External clock source frequency <sup>(1)</sup>		-	32.768	1000	kHz
V <sub>LSEH</sub>	OSC32_IN input pin high level voltage		0.7V <sub>DD</sub>	-	V <sub>DD</sub>	V
V <sub>LSEL</sub>	OSC32_IN input pin low level voltage			-	0.3V <sub>DD</sub>	v
t <sub>w(LSEH)</sub> t <sub>w(LSEL)</sub>	OSC32_IN high or low time <sup>(1)</sup>		450	-	-	ns
t <sub>r(LSE)</sub> t <sub>f(LSE)</sub>	OSC32_IN rise or fall time <sup>(1)</sup>		-	-	50	10

 Table 40. Low-speed external user clock characteristics

1. Guaranteed by design.

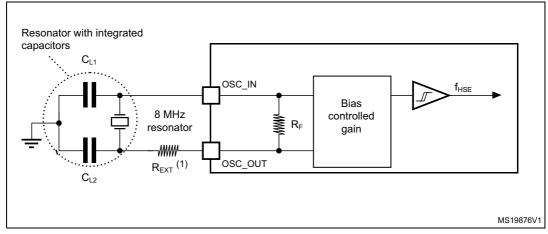


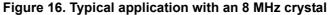




For C<sub>L1</sub> and C<sub>L2</sub>, it is recommended to use high-quality external ceramic capacitors in the 5 pF to 25 pF range (Typ.), designed for high-frequency applications, and selected to match the requirements of the crystal or resonator (see *Figure 16*). C<sub>L1</sub> and C<sub>L2</sub> are usually the same size. The crystal manufacturer typically specifies a load capacitance which is the series combination of C<sub>L1</sub> and C<sub>L2</sub>. PCB and MCU pin capacitance must be included (10 pF can be used as a rough estimate of the combined pin and board capacitance) when sizing C<sub>L1</sub> and C<sub>L2</sub>.

*Note:* For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.





1. R<sub>EXT</sub> value depends on the crystal characteristics.



### Low-speed external clock generated from a crystal/ceramic resonator

The low-speed external (LSE) clock can be supplied with a 32.768 kHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in *Table 42*. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Symbol	Parameter	Conditions <sup>(1)</sup>	Min <sup>(2)</sup>	Тур	Max <sup>(2)</sup>	Unit	
I <sub>DD</sub>	LSE current consumption	LSEDRV[1:0]=00 lower driving capability	-	0.5	0.9	.9	
		LSEDRV[1:0]=10 medium low driving capability	-	-	1		
		LSEDRV[1:0]=01 medium high driving capability	-	-	1.3	μA	
		LSEDRV[1:0]=11 higher driving capability	-	-	1.6		
9 <sub>m</sub>	Oscillator transconductance	LSEDRV[1:0]=00 lower driving capability	5	;			
		LSEDRV[1:0]=10 8 -		-	-	μA/V	
		LSEDRV[1:0]=01 medium high driving capability	15	-	-	- µAV	
		LSEDRV[1:0]=11 higher driving capability	25	-	-		
$t_{SU(LSE)}^{(3)}$	Startup time	V <sub>DD</sub> is stabilized	-	2	-	S	

### Table 42. LSE oscillator characteristics (f<sub>LSE</sub> = 32.768 kHz)

1. Refer to the note and caution paragraphs below the table, and to the application note AN2867 "Oscillator design guide for ST microcontrollers".

2. Guaranteed by design.

3. t<sub>SU(LSE)</sub> is the startup time measured from the moment it is enabled (by software) to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal and it can vary significantly with the crystal manufacturer.

*Note:* For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website <u>www.st.com</u>.



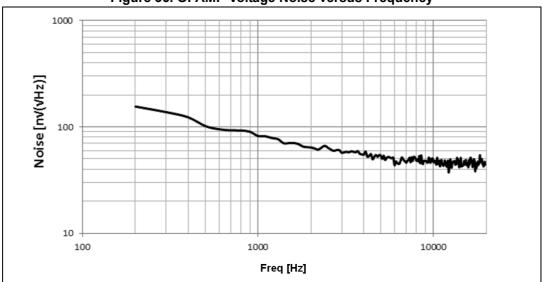
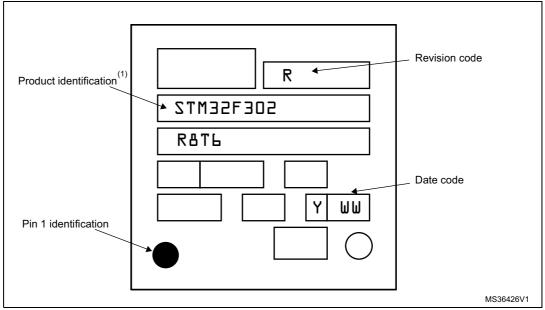


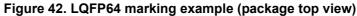
Figure 36. OPAMP Voltage Noise versus Frequency



### **Device marking**

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

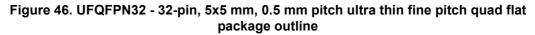


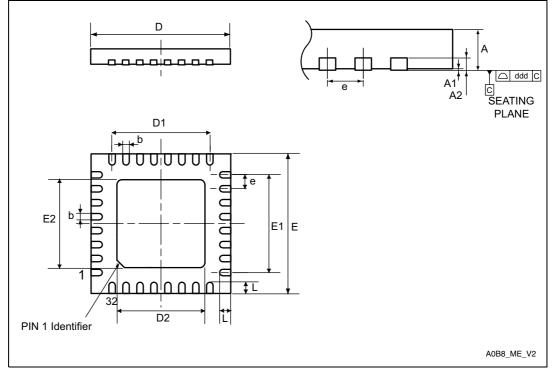


 Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.



# 7.4 UFQFPN32 package information





1. Drawing is not to scale.

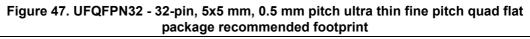
- 2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
- 3. There is an exposed die pad on the underside of the UFQFPN package. This pad is used for the device ground and must be connected. It is referred to as pin 0 in Table: Pin definitions.

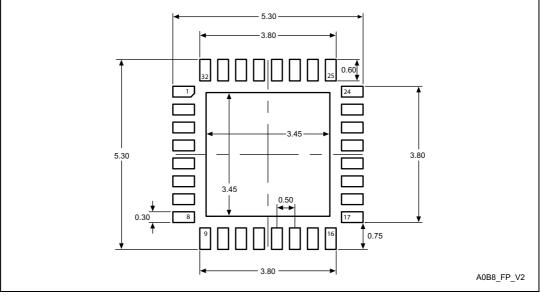


	millimeters			inches <sup>(1)</sup>			
Symbol	111111111111111111111111111111111111111						
	Min	Тур	Мах	Min	Тур	Max	
A	0.500	0.550	0.600	0.0197	0.0217	0.0236	
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020	
A3	-	0.152	-	-	0.0060	-	
b	0.180	0.230	0.280	0.0071	0.0091	0.0110	
D	4.900	5.000	5.100	0.1929	0.1969	0.2008	
D1	3.400	3.500	3.600	0.1339	0.1378	0.1417	
D2	3.400	3.500	3.600	0.1339	0.1378	0.1417	
E	4.900	5.000	5.100	0.1929	0.1969	0.2008	
E1	3.400	3.500	3.600	0.1339	0.1378	0.1417	
E2	3.400	3.500	3.600	0.1339	0.1378	0.1417	
е	-	0.500	-	-	0.0197	-	
L	0.300	0.400	0.500	0.0118	0.0157	0.0197	
ddd	-	-	0.080	-	-	0.0031	

# Table 81. UFQFPN32 - 32-pin, 5x5 mm, 0.5 mm pitch ultra thin fine pitch quad flatpackage mechanical data

1. Values in inches are converted from mm and rounded to 4 decimal digits.





1. Dimensions are expressed in millimeters.



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