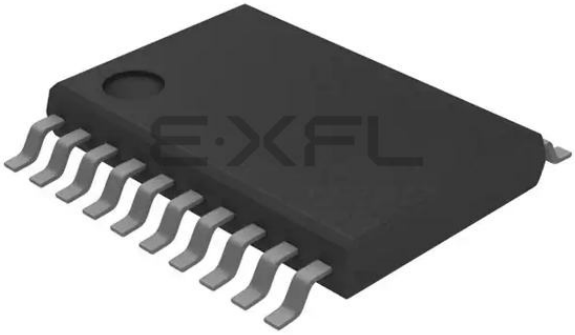

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	16
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	20-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	20-TSSOP
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s08rn16w2vtjr

- Peripherals
  - ACMP - one analog comparator with both positive and negative inputs; separately selectable interrupt on rising and falling comparator output; filtering
  - ADC - 12-channel, 12-bit resolution for 48-, 32-pin packages; 10-channel, 10-bit resolution for 20-pin package; 8-channel, 10-bit for 16-pin package; 2.5 µs conversion time; data buffers with optional watermark; automatic compare function; internal bandgap reference channel; operation in stop mode; optional hardware trigger
  - CRC - programmable cyclic redundancy check module
  - FTM - two flex timer modulators modules including one 6-channel and one 2-channel ones; 16-bit counter; each channel can be configured for input capture, output compare, edge- or center-aligned PWM mode
  - IIC - One inter-integrated circuit module; up to 400 kbps; multi-master operation; programmable slave address; supporting broadcast mode and 10-bit addressing
  - MTIM - One modulo timer with 8-bit prescaler and overflow interrupt
  - RTC - 16-bit real time counter (RTC)
  - SCI - two serial communication interface (SCI/UART) modules optional 13-bit break; full duplex non-return to zero (NRZ); LIN extension support
  - SPI - one 8-bit serial peripheral interface (SPI) modules; full-duplex or single-wire bidirectional; master or slave mode
  - TSI - supporting up to 16 external electrodes; configurable software or hardware scan trigger; fully support freescale touch sensing software library; capability to wake MCU from stop3 mode
- Input/Output
  - Up to 35 GPIOs including one output-only pin
  - One 8-bit keyboard interrupt module (KBI)
  - Two true open-drain output pins
  - Four, ultra-high current sink pins supporting 20 mA source/sink current
- Package options
  - 48-pin LQFP
  - 32-pin LQFP
  - 20-pin TSSOP
  - 16-pin TSSOP

Table of Contents

Field	Description	Values
		• LC = 32-LQFP • TJ = 20-TSSOP • TG = 16-TSSOP

2.4 Example

This is an example part number:

S9S08RN16W2MLF

3 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 1. Parameter Classifications

P	Those parameters are guaranteed during production testing on each individual device.
C	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
T	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

4 Ratings

4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T_{STG}	Storage temperature	–55	150	°C	1
T_{SDR}	Solder temperature, lead-free	—	260	°C	2

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.

Symbol	Description	Min.	Max.	Unit
V_{DD}	Supply voltage	–0.3	5.8	V
I_{DD}	Maximum current into V_{DD}	—	120	mA
V_{DIO}	Digital input voltage (except $\overline{\text{RESET}}$, EXTAL, XTAL, or true open drain pin PTA2 and PTA3)	–0.3	V_{DD} + 0.3	V
	Digital input voltage (true open drain pin PTA2 and PTA3)	-0.3	6	V
V_{AIO}	Analog[1], $\overline{\text{RESET}}$, EXTAL, and XTAL input voltage	–0.3	V_{DD} + 0.3	V
I_D	Instantaneous maximum current single pin limit (applies to all port pins)	–25	25	mA
V_{DDA}	Analog supply voltage	V_{DD} – 0.3	V_{DD} + 0.3	V

1. All digital I/O pins, except open-drain pin PTA2 and PTA3, are internally clamped to V_{SS} and V_{DD}. PTA2 and PTA3 is only clamped to V_{SS}.

5 General

5.1 Nonswitching electrical specifications

5.1.1 DC characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 2. DC characteristics

Symbol	C	Descriptions			Min	Typical[1]	Max	Unit
—	—	Operating voltage		—	2.7	—	5.5	V
V_{OH}	C	Output high voltage	All I/O pins, standard-drive strength	5 V, I_{load} = -5 mA	V_{DD} - 0.8	—	—	V
	C			3 V, I_{load} = -2.5 mA	V_{DD} - 0.8	—	—	V
	C		High current drive pins, high-drive strength[2]	5 V, I_{load} = -20 mA	V_{DD} - 0.8	—	—	V
	C			3 V, I_{load} = -10 mA	V_{DD} - 0.8	—	—	V
I_{OHT}	D	Output high current	Max total I_{OH} for all ports	5 V	—	—	-100	mA
				3 V	—	—	-50	
V_{OL}	C	Output low voltage	All I/O pins, standard-drive strength	5 V, I_{load} = 5 mA	—	—	0.8	V
	C			3 V, I_{load} = 2.5 mA	—	—	0.8	V

Table continues on the next page...

Table 2. DC characteristics (continued)

Symbol	C	Descriptions			Min	Typical[1]	Max	Unit
	C		High current drive pins, high-drive strength[2]	5 V, I_{load} =20 mA	—	—	0.8	V
	C			3 V, I_{load} = 10 mA	—	—	0.8	V
I_{OLT}	D	Output low current	Max total I_{OL} for all ports	5 V	—	—	100	mA
				3 V	—	—	50	
V_{IH}	P	Input high voltage	All digital inputs	V_{DD}>4.5V	0.70 × V_{DD}	—	—	V
	C			V_{DD}>2.7V	0.75 × V_{DD}	—	—	
V_{IL}	P	Input low voltage	All digital inputs	V_{DD}>4.5V	—	—	0.30 × V_{DD}	V
	C			V_{DD}>2.7V	—	—	0.35 × V_{DD}	
V_{hys}	C	Input hysteresis	All digital inputs	—	0.06 × V_{DD}	—	—	mV
$\lvert I_{In}\rvert$	P	Input leakage current	All input only pins (per pin)	V_{IN} = V_{DD} or V_{SS}	—	0.1	1	µA
$\lvert I_{OZ}\rvert$	P	Hi-Z (off-state) leakage current	All input/output (per pin)	V_{IN} = V_{DD} or V_{SS}	—	0.1	1	µA
$\lvert I_{OZTOT}\rvert$	C	Total leakage combined for all inputs and Hi-Z pins	All input only and I/O	V_{IN} = V_{DD} or V_{SS}	—	—	2	µA
R_{PU}	P	Pullup resistors	All digital inputs, when enabled (all I/O pins other than PTA2 and PTA3)	—	30.0	—	50.0	kΩ
R_{PU}[3]	P	Pullup resistors	PTA2 and PTA3 pin	—	30.0	—	60.0	kΩ
I_{IC}	D	DC injection current[4, 5, 6]	Single pin limit	V_{IN} < V_{SS}, V_{IN} > V_{DD}	-0.2	—	2	mA
			Total MCU limit, includes sum of all stressed pins		-5	—	25	
C_{In}	C	Input capacitance, all pins		—	—	—	7	pF
V_{RAM}	C	RAM retention voltage		—	2.0	—	—	V

1. Typical values are measured at 25 °C. Characterized, not tested.
2. Only PTB4, PTB5 support ultra high current output.
3. The specified resistor value is the actual value internal to the device. The pullup value may appear higher when measured externally on the pin.
4. All functional non-supply pins, except for PTA2 and PTA3, are internally clamped to V_{SS} and V_{DD}.
5. Input must be current-limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the large one.
6. Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If the positive injection current (V_{In} > V_{DD}) is higher than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure that external V_{DD} load will shunt current higher than maximum injection current when the MCU is not consuming power, such as no system clock is present, or clock rate is very low (which would reduce overall power consumption).

Table 3. LVD and POR Specification

Symbol	C	Description		Min	Typ	Max	Unit
V_{POR}	D	POR re-arm voltage[1, 2]		1.5	1.75	2.0	V
V_{LVDH}	C	Falling low-voltage detect threshold - high range (LVDV = 1)[3]		4.2	4.3	4.4	V
V_{LVW1H}	C	Falling low-voltage warning threshold - high range	Level 1 falling (LVWV = 00)	4.3	4.4	4.5	V
V_{LVW2H}	C		Level 2 falling (LVWV = 01)	4.5	4.5	4.6	V
V_{LVW3H}	C		Level 3 falling (LVWV = 10)	4.6	4.6	4.7	V
V_{LVW4H}	C		Level 4 falling (LVWV = 11)	4.7	4.7	4.8	V
V_{HYSH}	C	High range low-voltage detect/warning hysteresis		—	100	—	mV
V_{LVDL}	C	Falling low-voltage detect threshold - low range (LVDV = 0)		2.56	2.61	2.66	V
V_{LVDW1L}	C	Falling low-voltage warning threshold - low range	Level 1 falling (LVWV = 00)	2.62	2.7	2.78	V
V_{LVDW2L}	C		Level 2 falling (LVWV = 01)	2.72	2.8	2.88	V
V_{LVDW3L}	C		Level 3 falling (LVWV = 10)	2.82	2.9	2.98	V
V_{LVDW4L}	C		Level 4 falling (LVWV = 11)	2.92	3.0	3.08	V
V_{HYSDL}	C	Low range low-voltage detect hysteresis		—	40	—	mV
V_{HYSWL}	C	Low range low-voltage warning hysteresis		—	80	—	mV
V_{BG}	P	Buffered bandgap output [4]		1.14	1.16	1.18	V

1. Maximum is highest voltage that POR is guaranteed.
2. POR ramp time must be longer than 20us/V to get a stable startup.
3. Rising thresholds are falling threshold + hysteresis.
4. Voltage factory trimmed at V_{DD} = 5.0 V, Temp = 125 °C

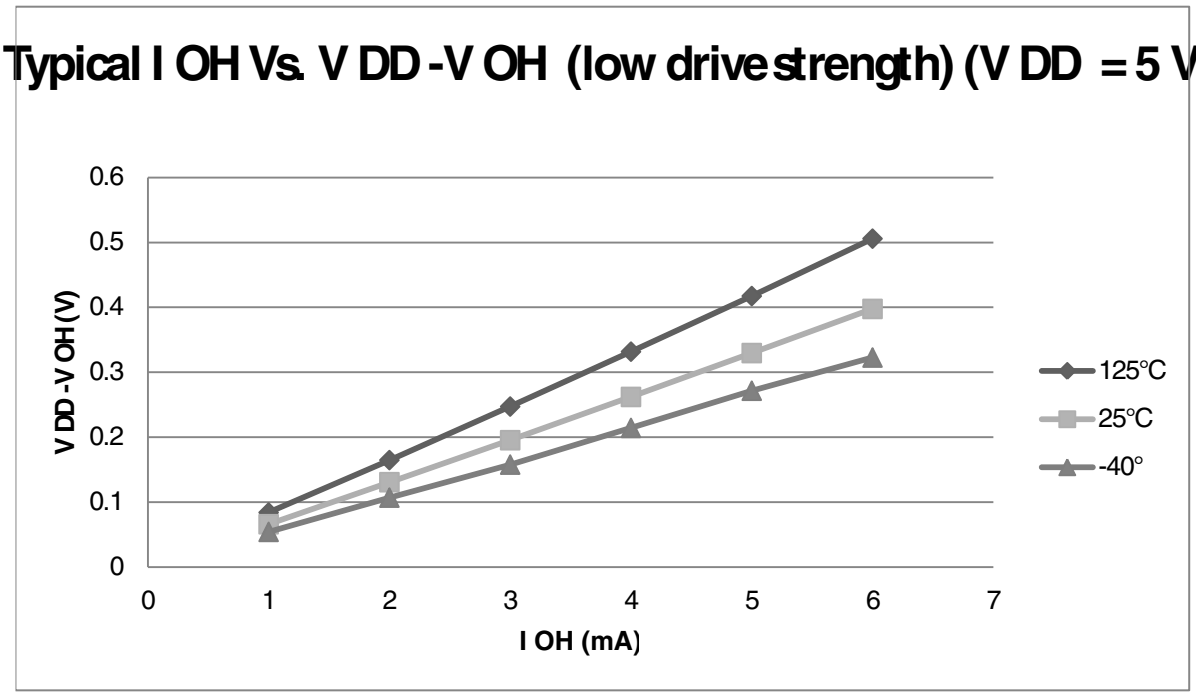


Figure 1. Typical I_{OH} Vs. V_{DD}-V_{OH} (standard drive strength) (V_{DD} = 5 V)

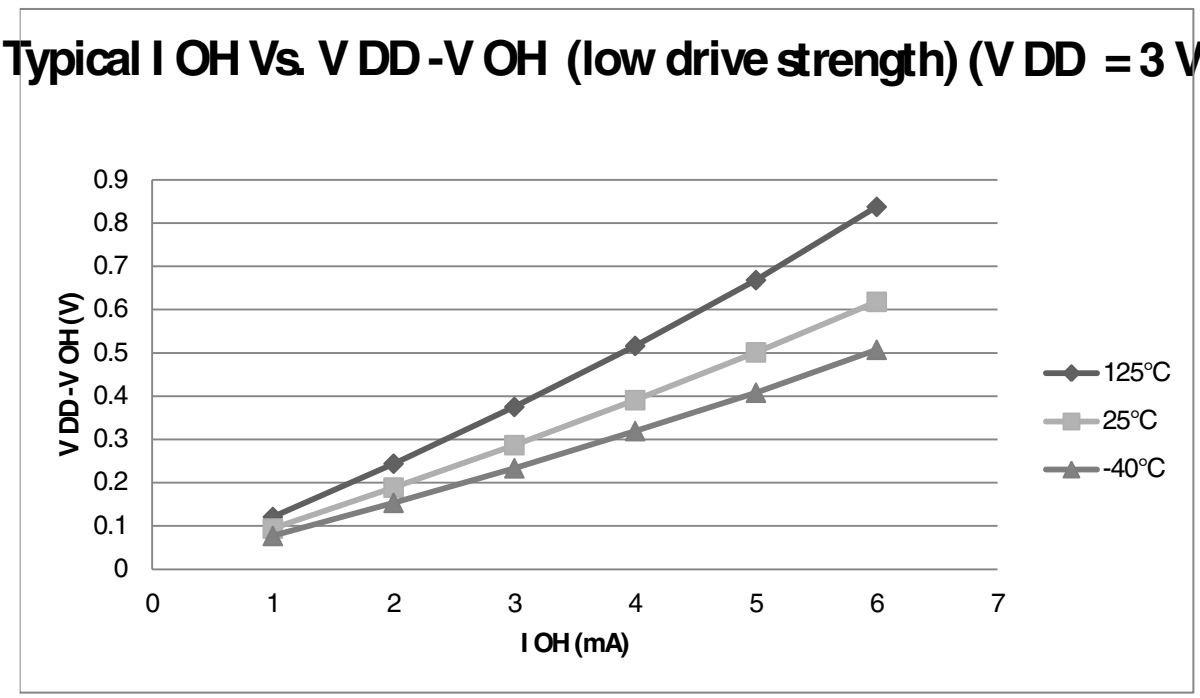


Figure 2. Typical I_{OH} Vs. V_{DD}-V_{OH} (standard drive strength) (V_{DD} = 3 V)

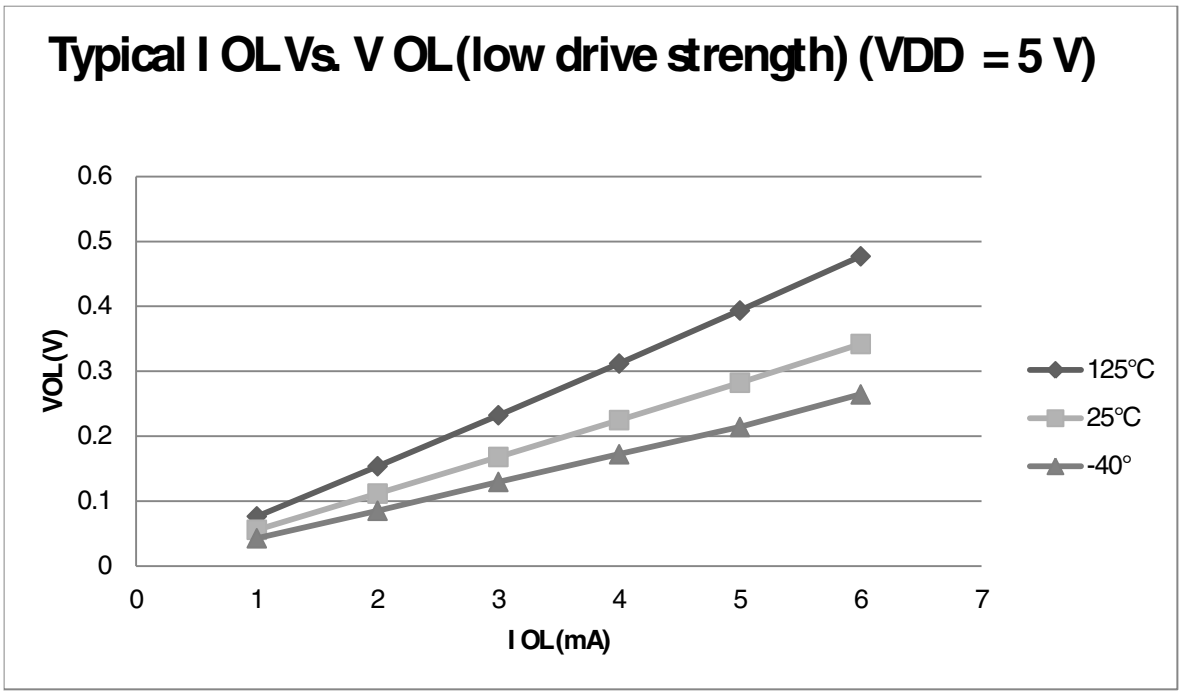


Figure 5. Typical I_{OL} Vs. V_{OL} (standard drive strength) (V_{DD} = 5 V)

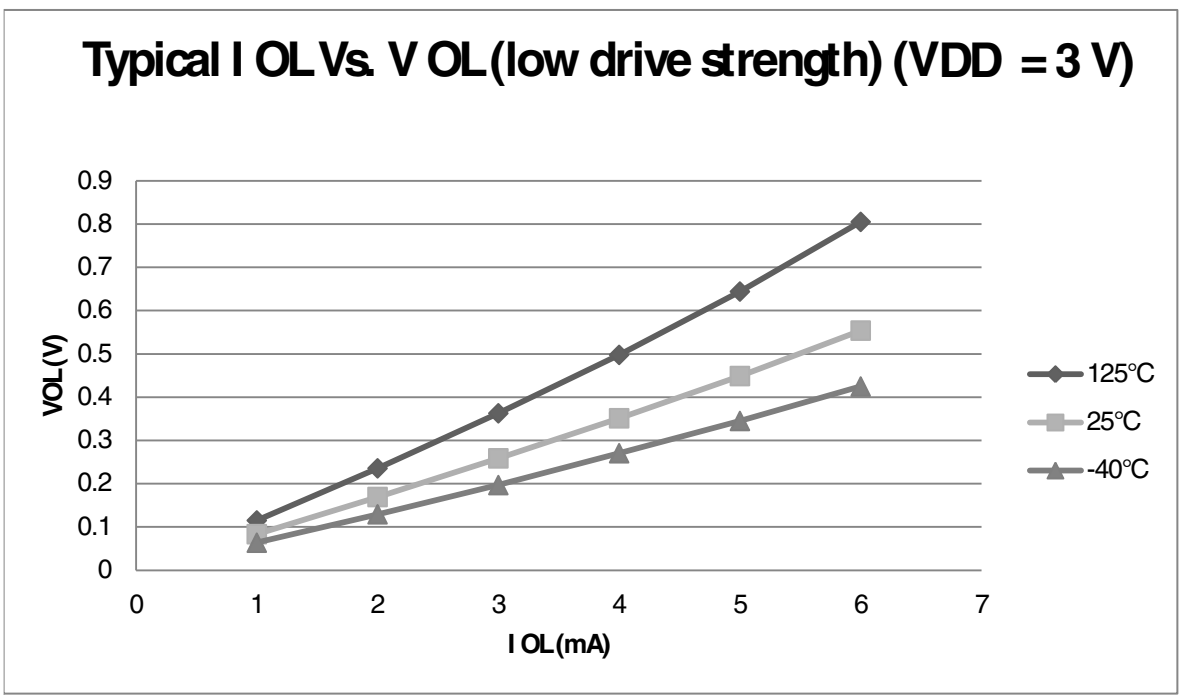


Figure 6. Typical I_{OL} Vs. V_{OL} (standard drive strength) (V_{DD} = 3 V)

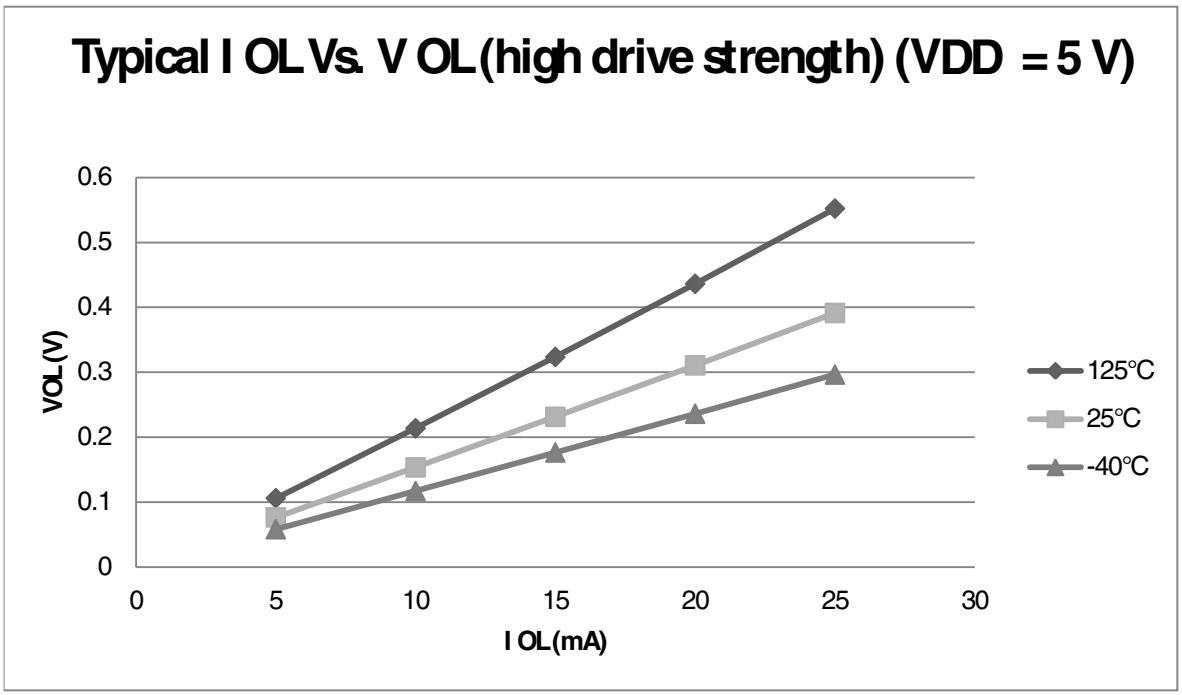


Figure 7. Typical I_{OL} Vs. V_{OL} (high drive strength) (V_{DD} = 5 V)

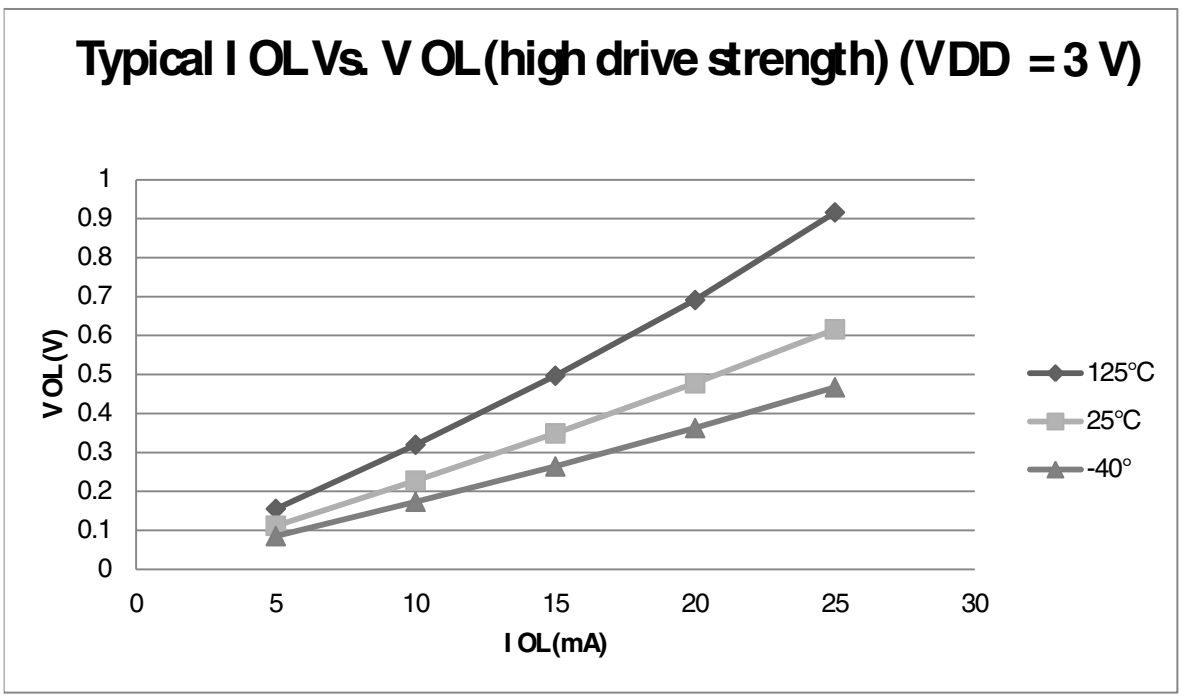


Figure 8. Typical I_{OL} Vs. V_{OL} (high drive strength) (V_{DD} = 3 V)

5.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

Table 4. Supply current characteristics

Num	C	Parameter	Symbol	Bus Freq	V_{DD} (V)	Typical[1]	Max	Unit	Temp
1	C	Run supply current FEI mode, all modules on; run from flash	RI_{DD}	20 MHz	5	7.60	—	mA	-40 to 125 °C
	C			10 MHz		4.65	—		
				1 MHz		1.90	—		
	C			20 MHz	3	7.05	—		
	C			10 MHz		4.40	—		
				1 MHz		1.85	—		
2	C	Run supply current FEI mode, all modules off & gated; run from flash	RI_{DD}	20 MHz	5	5.88	—	mA	-40 to 125 °C
	C			10 MHz		3.70	—		
				1 MHz		1.85	—		
	C			20 MHz	3	5.35	—		
	C			10 MHz		3.42	—		
				1 MHz		1.80	—		
3	P	Run supply current FBE mode, all modules on; run from RAM	RI_{DD}	20 MHz	5	10.9	14.0	mA	-40 to 125 °C
	C			10 MHz		6.10	—		
				1 MHz		1.69	—		
	C			20 MHz	3	8.18	—		
				10 MHz		5.14	—		
				1 MHz		1.44	—		
4	P	Run supply current FBE mode, all modules off & gated; run from RAM	RI_{DD}	20 MHz	5	8.50	13.0	mA	-40 to 125 °C
	C			10 MHz		5.07	—		
				1 MHz		1.59	—		
	C			20 MHz	3	6.11	—		
				10 MHz		4.10	—		
				1 MHz		1.34	—		
5	C	Wait mode current FEI mode, all modules on	WI_{DD}	20 MHz	5	5.95	—	mA	-40 to 125 °C
				10 MHz		3.50	—		
				1 MHz		1.24	—		
	C			20 MHz	3	5.45	—		
				10 MHz		3.25	—		
				1 MHz		1.20	—		
6	C	Stop3 mode supply current no clocks active (except 1kHz LPO clock)[2, 3]	$S3I_{DD}$	—	5	4.6	—	µA	-40 to 125 °C
	C			—	3	4.5	—		-40 to 125 °C
7	C	ADC adder to stop3	—	—	5	40	—	µA	-40 to 125 °C

Table continues on the next page...

Table 4. Supply current characteristics (continued)

Num	C	Parameter	Symbol	Bus Freq	V_{DD} (V)	Typical[1]	Max	Unit	Temp
	C	ADLPC = 1 ADLSMP = 1 ADCO = 1 MODE = 10B ADICLK = 11B			3	39	—		
8	C	TSI adder to stop3[4]	—	—	5	121	—	µA	-40 to 125 °C
	C	PS = 010B NSCN = 0x0F EXTCHRG = 0 REFCHRG = 0 DVOLT = 01B			3	120	—		
9	C	LVD adder to stop3[5]	—	—	5	128	—	µA	-40 to 125 °C
	C				3	124	—		

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. RTC adder cause <1 µA I_{DD} increase typically, RTC clock source is 1kHz LPO clock.
3. ACMP adder cause <10 µA I_{DD} increase typically.
4. The current varies with TSI configuration and capacity of touch electrode. Please refer toTSI electrical specifications.
5. LVD is periodically woken up from stop3 by 5% duty cycle. The period is equal to or less than 2 ms.

5.1.3 EMC performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

5.2 Switching specifications

5.2.1 Control timing

Table 5. Control timing

Num	C	Rating	Symbol	Min	Typical[1]	Max	Unit
1	P	Bus frequency (t_{cyc} = 1/f_{Bus})	f_{Bus}	DC	—	20	MHz
2	P	Internal low power oscillator frequency	f_{LPO}	0.67	1.0	1.25	KHz

Table continues on the next page...

Table 5. Control timing (continued)

Num	C	Rating		Symbol	Min	Typical[1]	Max	Unit
3	D	External reset pulse width[2]		t_{extrst}	1.5 × t_{Self_reset}	—	—	ns
4	D	Reset low drive		t_{rstdrv}	34 × t_{cyc}	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes		t_{MSSU}	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes[3]		t_{MSH}	100	—	—	ns
7	D	Keyboard interrupt pulse width	Asynchronous path[2]	t_{ILIH}	100	—	—	ns
	D		Synchronous path	t_{IHIL}	1.5 × t_{cyc}	—	—	ns
8	C	Port rise and fall time - standard drive strength (load = 50 pF)[4]	—	t_{Rise}	—	10.2	—	ns
	C			t_{Fall}	—	9.5	—	ns
	C	Port rise and fall time - high drive strength (load = 50 pF)[4]	—	t_{Rise}	—	5.4	—	ns
	C			t_{Fall}	—	4.6	—	ns

1. Typical values are based on characterization data at V_{DD} = 5.0 V, 25 °C unless otherwise stated.
2. This is the shortest pulse that is guaranteed to be recognized as a reset pin request.
3. To enter BDM mode following a POR, BKGD/MS must be held low during the powerup and for a hold time of t_{MSH} after V_{DD} rises above V_{LVD}.
4. Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range -40 °C to 125 °C.

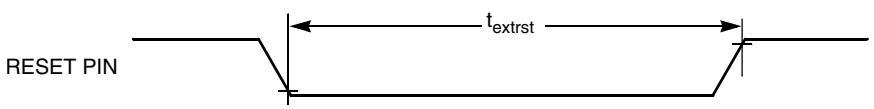


Figure 9. Reset timing

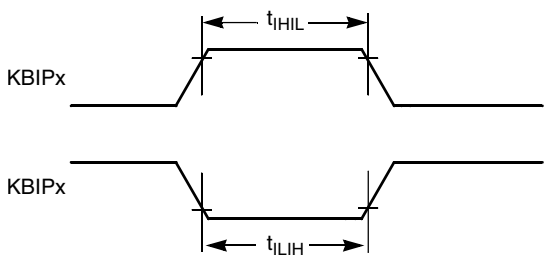


Figure 10. KBIPx timing

5.2.2 Debug trace timing specifications

Table 6. Debug trace operating behaviors

Symbol	Description	Min.	Max.	Unit
t_{cyc}	Clock period	Frequency dependent		MHz
t_{wl}	Low pulse width	2	—	ns

Table continues on the next page...

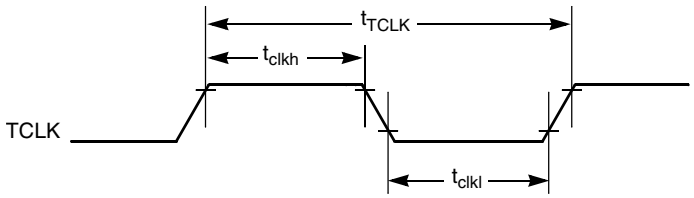


Figure 13. Timer external clock

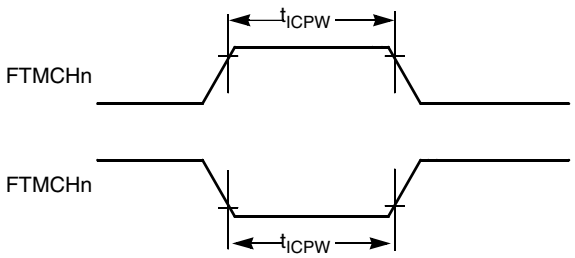


Figure 14. Timer input capture pulse

5.3 Thermal specifications

5.3.1 Thermal characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 8. Thermal characteristics

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T_A	T_L to T_H -40 to 125	°C
Junction temperature range	T_J	-40 to 135	°C
Thermal resistance single-layer board			
48-pin LQFP	θ_{JA}	82	°C/W
32-pin LQFP	θ_{JA}	88	°C/W
20-pin TSSOP	θ_{JA}	116	°C/W
16-pin TSSOP	θ_{JA}	130	°C/W
Thermal resistance four-layer board			

Table continues on the next page...

Table 8. Thermal characteristics (continued)

Rating	Symbol	Value	Unit
48-pin LQFP	θ_{JA}	58	°C/W
32-pin LQFP	θ_{JA}	59	°C/W
20-pin TSSOP	θ_{JA}	76	°C/W
16-pin TSSOP	θ_{JA}	87	°C/W

The average chip-junction temperature (T_J) in °C can be obtained from:

$T_J = T_A + (P_D \times \theta_{JA})$

Where:

T_A = Ambient temperature, °C

θ_{JA} = Package thermal resistance, junction-to-ambient, °C/W

$P_D = P_{int} + P_{I/O}$

$P_{int} = I_{DD} \times V_{DD}$, Watts - chip internal power

$P_{I/O}$ = Power dissipation on input and output pins - user determined

For most applications, $P_{I/O} << P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$P_D = K \div (T_J + 273\ °C)$

Solving the equations above for K gives:

$K = P_D \times (T_A + 273\ °C) + \theta_{JA} \times (P_D)^2$

where K is a constant pertaining to the particular part. K can be determined by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving the above equations iteratively for any value of T_A.

6 Peripheral operating requirements and behaviors

Table 9. XOSC and ICS specifications (temperature range = -40 to 125 °C ambient) (continued)

Num	C	Characteristic	Symbol	Min	Typical[1]	Max	Unit
	C	Over fixed voltage and temperature range of 0 to 70 °C				±1.0	
12	C	FLL acquisition time[5, 7]	$t_{Acquire}$	—	—	2	ms
13	C	Long term jitter of DCO output clock (averaged over 2 ms interval)[8]	C_{Jitter}	—	0.02	0.2	$\%f_{dco}$

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. When ICS is configured for FEE or FBE mode, input clock source must be divisible using RDIV to within the range of 31.25 kHz to 39.0625 kHz.
3. See crystal or resonator manufacturer's recommendation.
4. Load capacitors (C_1,C_2), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE = HGO = 0.
5. This parameter is characterized and not tested on each device.
6. Proper PC board layout procedures must be followed to achieve specifications.
7. This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
8. Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{Bus}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

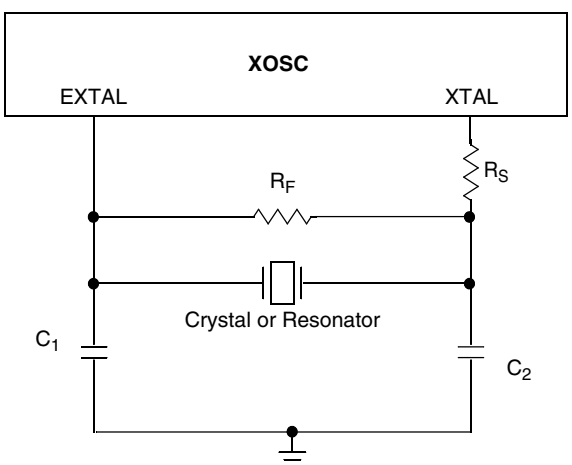


Figure 15. Typical crystal or resonator circuit

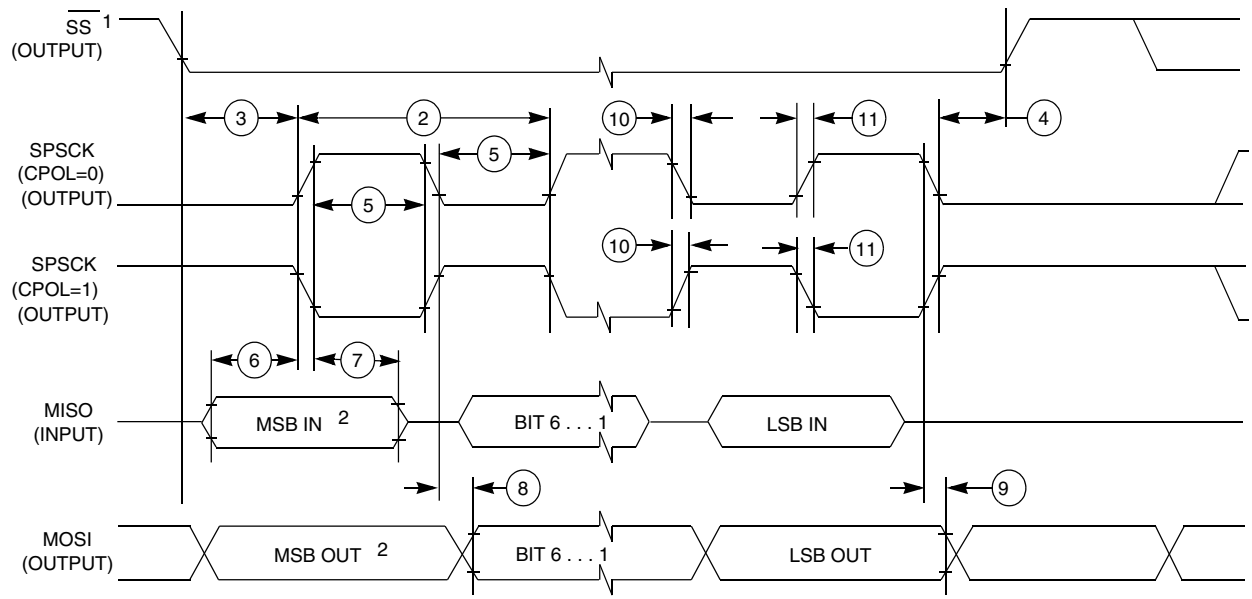
Table 12. 12-bit ADC Characteristics (V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA}) (continued)

Characteristic	Conditions	C	Symb	Min	Typ[1]	Max	Unit
	Low power (ADLPC = 1)			1.25	2	3.3	
Conversion time (including sample time)	Short sample (ADLSMP = 0)	T	t_{ADC}	—	20	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	40	—	
Sample time	Short sample (ADLSMP = 0)	T	t_{ADS}	—	3.5	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	23.5	—	
Total unadjusted Error[2]	12-bit mode	T	E_{TUE}	—	±5.0	—	LSB[3]
	10-bit mode	P		—	±1.5	±2.0	
	8-bit mode	P[4]		—	±0.7	±1.0	
Differential Non-Linearity	12-bit mode	T	DNL	—	±1.0	—	LSB[3]
	10-bit mode[5]	P		—	±0.25	±0.5	
	8-bit mode[5]	P[4]		—	±0.15	±0.25	
Integral Non-Linearity	12-bit mode	T	INL	—	±1.0	—	LSB[3]
	10-bit mode	T		—	±0.3	±0.5	
	8-bit mode	T		—	±0.15	±0.25	
Zero-scale error[6]	12-bit mode	C	E_{ZS}	—	±2.0	—	LSB[3]
	10-bit mode	P		—	±0.25	±1.0	
	8-bit mode	P[4]		—	±0.65	±1.0	
Full-scale error[7]	12-bit mode	T	E_{FS}	—	±2.5	—	LSB[3]
	10-bit mode	T		—	±0.5	±1.0	
	8-bit mode	T		—	±0.5	±1.0	
Quantization error	≤12 bit modes	D	E_Q	—	—	±0.5	LSB[3]
Input leakage error[8]	all modes	D	E_{IL}	I_{In} * R_{AS}			mV
Temp sensor slope	-40°C– 25°C	D	m	—	3.266	—	mV/°C
	25°C– 125°C			—	3.638	—	
Temp sensor voltage	25°C	D	V_{TEMP25}	—	1.396	—	V

1. Typical values assume V_{DDA} = 5.0 V, Temp = 25°C, f_{ADCK}=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. Includes quantization.
3. 1 LSB = (V_{REFH} - V_{REFL})/2^N
4. 10-bit mode only for package LQFP48/32, TSSOP20/16. Those parameters are only achieved by the design characterization.
5. Monotonicity and no-missing-codes guaranteed in 10-bit and 8-bit modes
6. V_{ADIN} = V_{SSA}
7. V_{ADIN} = V_{DDA}
8. I_{In} = leakage current (refer to DC characteristics)

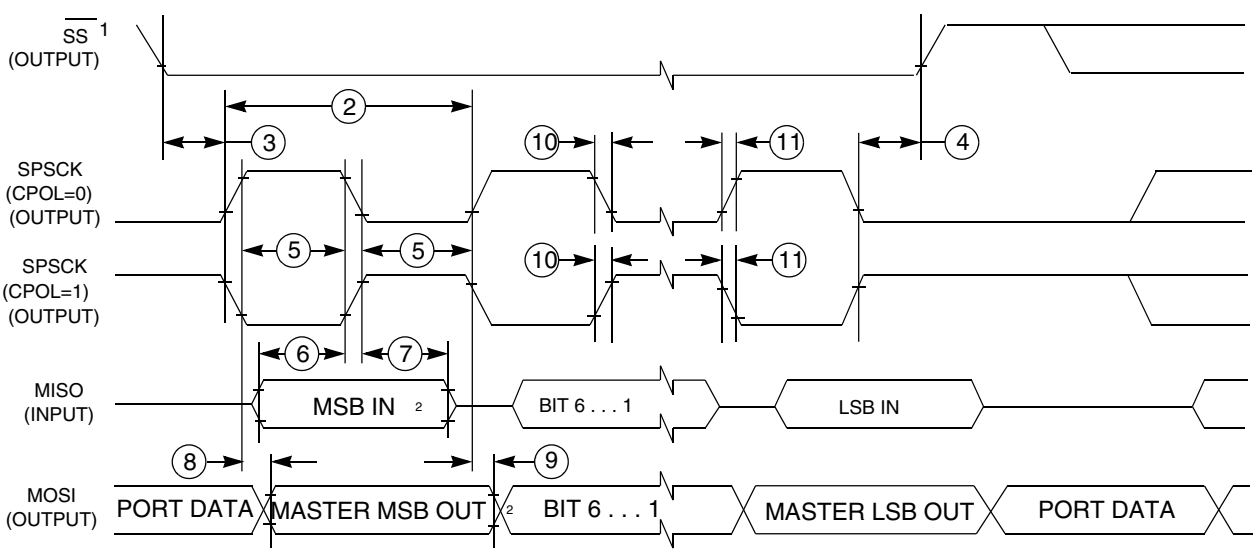
Table 14. SPI master mode timing (continued)

Num.	Symbol	Description	Min.	Max.	Unit	Comment
	t_{FI}	Fall time input				
11	t_{RO}	Rise time output	—	25	ns	—
	t_{FO}	Fall time output				



1. If configured as an output.
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 17. SPI master mode timing (CPHA=0)



1.If configured as output
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 18. SPI master mode timing (CPHA=1)

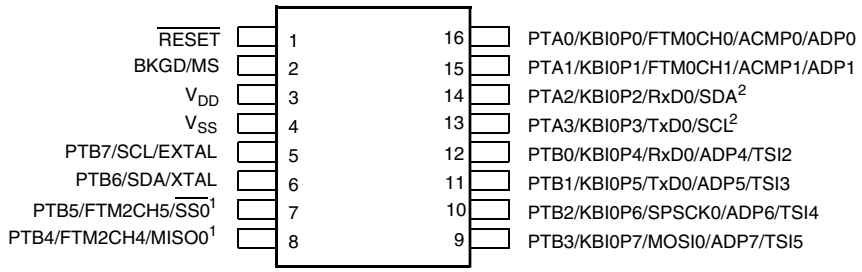
Table 17. Pin availability by package pin-count (continued)

Pin Number				Lowest Priority <-- --> Highest				
48-LQFP	32-LQFP	20-TSSOP	16-TSSOP	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
19	—	—	—	PTD6	—	—	—	—
20	—	—	—	PTD5	—	—	—	—
21	13	11	—	PTC1	—	FTM2CH1	ADP9	TSI7
22	14	12	—	PTC0	—	FTM2CH0	ADP8	TSI6
23	15	13	9	PTB3	KBI0P7	MOSI0	ADP7	TSI5
24	16	14	10	PTB2	KBI0P6	SPSCK0	ADP6	TSI4
25	17	15	11	PTB1	KBI0P5	TXD0	ADP5	TSI3
26	18	16	12	PTB0	KBI0P4	RXD0	ADP4	TSI2
27	19	—	—	PTA7	—	FTM2FAULT2	ADP3	TSI1
28	20	—	—	PTA6	—	FTM2FAULT1	ADP2	TSI0
29	—	—	—	NC				
30	—	—	—	—	—	—	—	Vss
31	—	—	—	—	—	—	—	V_{DD}
32	—	—	—	PTD4	—	—	—	—
33	21	—	—	PTD3	—	—	—	TSI15
34	22	—	—	PTD2	—	—	—	TSI14
35	23	17	13	PTA3[2]	KBI0P3	TXD0	SCL	—
36	24	18	14	PTA2[2]	KBI0P2	RXD0	SDA	—
37	25	19	15	PTA1	KBI0P1	FTM0CH1	ACMP1	ADP1
38	26	20	16	PTA0	KBI0P0	FTM0CH0	ACMP0	ADP0
39	27	—	—	PTC7	—	TxD1	—	TSI13
40	28	—	—	PTC6	—	RxD1	—	TSI12
41	—	—	—	NC				
42	—	—	—	PTE2	—	MISO0	—	—
43	—	—	—	PTE1	—	MOSI0	—	—
44	—	—	—	PTE0	—	SPSCK0	—	—
45	29	—	—	PTC5	—	FTM0CH1	—	TSI11
46	30	—	—	PTC4	—	FTM0CH0	—	TSI10
47	31	1	1	—	—	—	—	$\overline{\text{RESET}}$
48	32	2	2	—	—	—	BKGD	MS

1. This is a high current drive pin when operated as output.
2. This is a true open-drain pin when operated as output.

Note

When an alternative function is first enabled, it is possible to get a spurious edge to the module. User software must clear any associated flags before interrupts are enabled. The table above illustrates the priority if multiple modules are enabled. The



1. High source/sink current pins
2. True open drain pins

Figure 24. S9S08RN16 16-pin TSSOP package

9 Revision history

The following table provides a revision history for this document.

Table 18. Revision history

Rev. No.	Date	Substantial Changes
1	02/2014	Initial Release

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Document Number S9S08RN16DS
Revision 1, 02/2014