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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	12
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	16-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	16-TSSOP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s08rn8w2mtgr">https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s08rn8w2mtgr</a>

- Peripherals
  - ACMP - one analog comparator with both positive and negative inputs; separately selectable interrupt on rising and falling comparator output; filtering
  - ADC - 12-channel, 12-bit resolution for 48-, 32-pin packages; 10-channel, 10-bit resolution for 20-pin package; 8-channel, 10-bit for 16-pin package; 2.5  $\mu$ s conversion time; data buffers with optional watermark; automatic compare function; internal bandgap reference channel; operation in stop mode; optional hardware trigger
  - CRC - programmable cyclic redundancy check module
  - FTM - two flex timer modulators modules including one 6-channel and one 2-channel ones; 16-bit counter; each channel can be configured for input capture, output compare, edge- or center-aligned PWM mode
  - IIC - One inter-integrated circuit module; up to 400 kbps; multi-master operation; programmable slave address; supporting broadcast mode and 10-bit addressing
  - MTIM - One modulo timer with 8-bit prescaler and overflow interrupt
  - RTC - 16-bit real time counter (RTC)
  - SCI - two serial communication interface (SCI/UART) modules optional 13-bit break; full duplex non-return to zero (NRZ); LIN extension support
  - SPI - one 8-bit serial peripheral interface (SPI) modules; full-duplex or single-wire bidirectional; master or slave mode
  - TSI - supporting up to 16 external electrodes; configurable software or hardware scan trigger; fully support freescale touch sensing software library; capability to wake MCU from stop3 mode
- Input/Output
  - Up to 35 GPIOs including one output-only pin
  - One 8-bit keyboard interrupt module (KBI)
  - Two true open-drain output pins
  - Four, ultra-high current sink pins supporting 20 mA source/sink current
- Package options
  - 48-pin LQFP
  - 32-pin LQFP
  - 20-pin TSSOP
  - 16-pin TSSOP

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# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to [freescale.com](http://freescale.com) and perform a part number search for the following device numbers: RN16 and RN8.

# 2 Part identification

## 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

## 2.2 Format

Part numbers for this device have the following format:

S 9 S08 RN AA F1 B CC

## 2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
S	Qualification status	<ul style="list-style-type: none"> <li>S = fully qualified, general market flow</li> </ul>
9	Memory	<ul style="list-style-type: none"> <li>9 = flash based</li> </ul>
S08	Core	<ul style="list-style-type: none"> <li>S08 = 8-bit CPU</li> </ul>
RN	Device family	<ul style="list-style-type: none"> <li>RN</li> </ul>
AA	Approximate flash size in KB	<ul style="list-style-type: none"> <li>16 = 16 KB</li> <li>8 = 8 KB</li> </ul>
F1	Fab and mask set identifier	<ul style="list-style-type: none"> <li>W2</li> </ul>
B	Temperature range (°C)	<ul style="list-style-type: none"> <li>M = -40 to 125</li> </ul>
CC	Package designator	<ul style="list-style-type: none"> <li>LF = 48-LQFP</li> </ul>

Symbol	Description	Min.	Max.	Unit
$V_{DD}$	Supply voltage	-0.3	5.8	V
$I_{DD}$	Maximum current into $V_{DD}$	—	120	mA
$V_{DIO}$	Digital input voltage (except RESET, EXTAL, XTAL, or true open drain pin PTA2 and PTA3)	-0.3	$V_{DD} + 0.3$	V
	Digital input voltage (true open drain pin PTA2 and PTA3)	-0.3	6	V
$V_{AIO}$	Analog <sup>1</sup> , RESET, EXTAL, and XTAL input voltage	-0.3	$V_{DD} + 0.3$	V
$I_D$	Instantaneous maximum current single pin limit (applies to all port pins)	-25	25	mA
$V_{DDA}$	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V

1. All digital I/O pins, except open-drain pin PTA2 and PTA3, are internally clamped to  $V_{SS}$  and  $V_{DD}$ . PTA2 and PTA3 is only clamped to  $V_{SS}$ .

## 5 General

### 5.1 Nonswitching electrical specifications

#### 5.1.1 DC characteristics

This section includes information about power supply requirements and I/O pin characteristics.

**Table 2. DC characteristics**

Symbol	C	Descriptions		Min	Typical <sup>1</sup>	Max	Unit
—	—	Operating voltage		2.7	—	5.5	V
$V_{OH}$	C	Output high voltage	All I/O pins, standard-drive strength	5 V, $I_{load} = -5$ mA	$V_{DD} - 0.8$	—	V
	C			3 V, $I_{load} = -2.5$ mA	$V_{DD} - 0.8$	—	V
	C	High current drive pins, high-drive strength <sup>2</sup>	5 V, $I_{load} = -20$ mA	$V_{DD} - 0.8$	—	V	
	C		3 V, $I_{load} = -10$ mA	$V_{DD} - 0.8$	—	V	
$I_{OHT}$	D	Output high current	Max total $I_{OH}$ for all ports	5 V	—	-100	mA
				3 V	—	-50	
$V_{OL}$	C	Output low voltage	All I/O pins, standard-drive strength	5 V, $I_{load} = 5$ mA	—	0.8	V
	C			3 V, $I_{load} = 2.5$ mA	—	0.8	V

Table continues on the next page...

**Table 2. DC characteristics (continued)**

Symbol	C	Descriptions			Min	Typical <sup>1</sup>	Max	Unit
	C		High current drive pins, high-drive strength <sup>2</sup>	5 V, $I_{load} = 20$ mA	—	—	0.8	V
	C			3 V, $I_{load} = 10$ mA	—	—	0.8	V
$I_{OLT}$	D	Output low current	Max total $I_{OL}$ for all ports	5 V	—	—	100	mA
				3 V	—	—	50	
$V_{IH}$	P	Input high voltage	All digital inputs	$V_{DD} > 4.5$ V	$0.70 \times V_{DD}$	—	—	V
	C			$V_{DD} > 2.7$ V	$0.75 \times V_{DD}$	—	—	
$V_{IL}$	P	Input low voltage	All digital inputs	$V_{DD} > 4.5$ V	—	—	$0.30 \times V_{DD}$	V
	C			$V_{DD} > 2.7$ V	—	—	$0.35 \times V_{DD}$	
$V_{hys}$	C	Input hysteresis	All digital inputs	—	$0.06 \times V_{DD}$	—	—	mV
$I_{in}$	P	Input leakage current	All input only pins (per pin)	$V_{IN} = V_{DD}$ or $V_{SS}$	—	0.1	1	$\mu$ A
$I_{OZ}$	P	Hi-Z (off-state) leakage current	All input/output (per pin)	$V_{IN} = V_{DD}$ or $V_{SS}$	—	0.1	1	$\mu$ A
$I_{OZTOT}$	C	Total leakage combined for all inputs and Hi-Z pins	All input only and I/O	$V_{IN} = V_{DD}$ or $V_{SS}$	—	—	2	$\mu$ A
$R_{PU}$	P	Pullup resistors	All digital inputs, when enabled (all I/O pins other than PTA2 and PTA3)	—	30.0	—	50.0	k $\Omega$
$R_{PU}^3$	P	Pullup resistors	PTA2 and PTA3 pin	—	30.0	—	60.0	k $\Omega$
$I_{IC}$	D	DC injection current <sup>4, 5, 6</sup>	Single pin limit	$V_{IN} < V_{SS}$ , $V_{IN} > V_{DD}$	-0.2	—	2	mA
			Total MCU limit, includes sum of all stressed pins		-5	—	25	
$C_{in}$	C	Input capacitance, all pins			—	—	7	pF
$V_{RAM}$	C	RAM retention voltage			—	2.0	—	V

1. Typical values are measured at 25 °C. Characterized, not tested.
2. Only PTB4, PTB5 support ultra high current output.
3. The specified resistor value is the actual value internal to the device. The pullup value may appear higher when measured externally on the pin.
4. All functional non-supply pins, except for PTA2 and PTA3, are internally clamped to  $V_{SS}$  and  $V_{DD}$ .
5. Input must be current-limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the large one.
6. Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If the positive injection current ( $V_{in} > V_{DD}$ ) is higher than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure that external  $V_{DD}$  load will shunt current higher than maximum injection current when the MCU is not consuming power, such as no system clock is present, or clock rate is very low (which would reduce overall power consumption).

### Typical $I_{OH}$ Vs. $V_{DD}-V_{OH}$ (high drive strength) ( $V_{DD} = 5\text{ V}$ )

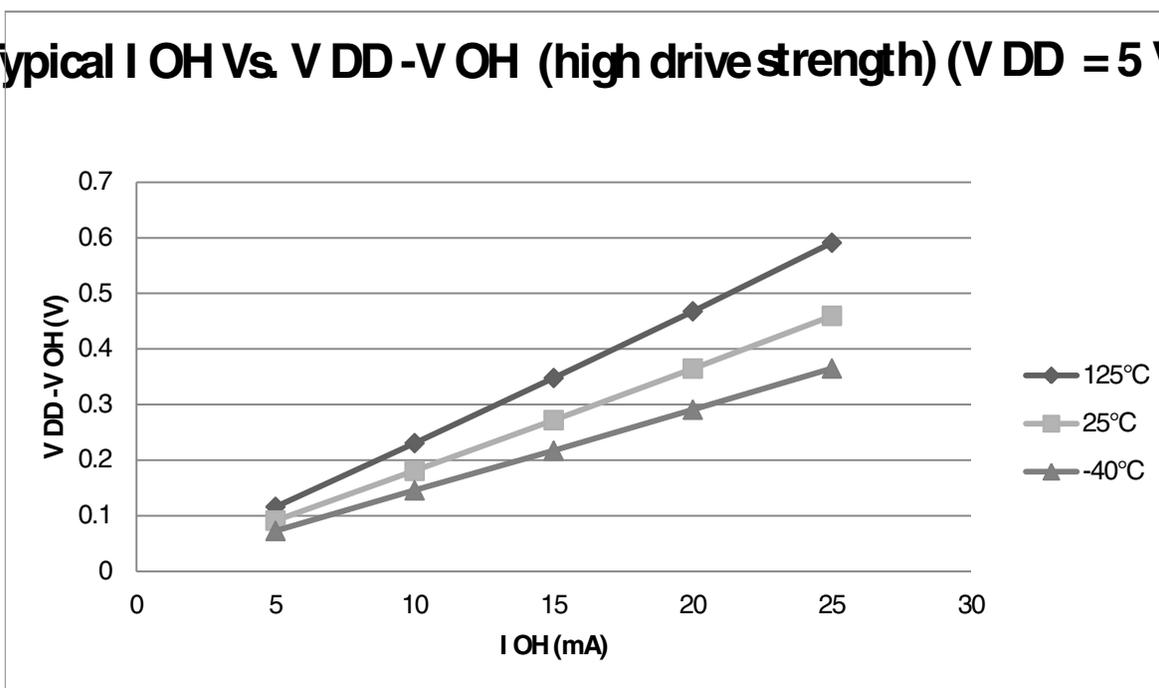


Figure 3. Typical  $I_{OH}$  Vs.  $V_{DD}-V_{OH}$  (high drive strength) ( $V_{DD} = 5\text{ V}$ )

### Typical $I_{OH}$ Vs. $V_{DD}-V_{OH}$ (high drive strength) ( $V_{DD} = 3\text{ V}$ )

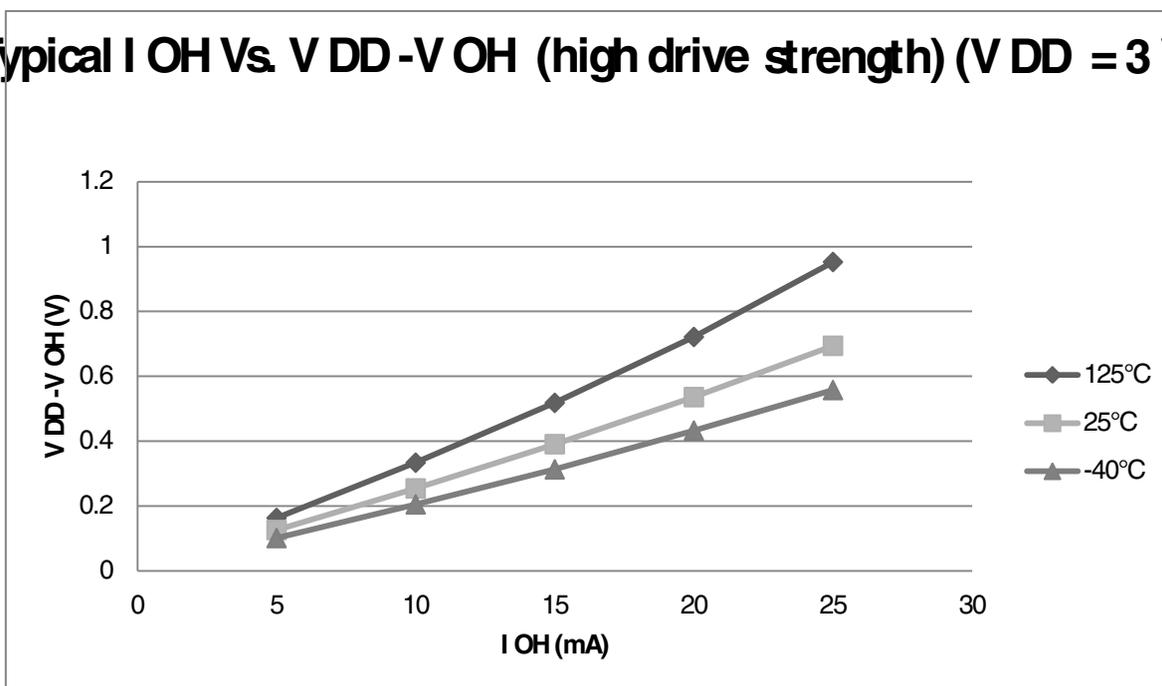


Figure 4. Typical  $I_{OH}$  Vs.  $V_{DD}-V_{OH}$  (high drive strength) ( $V_{DD} = 3\text{ V}$ )

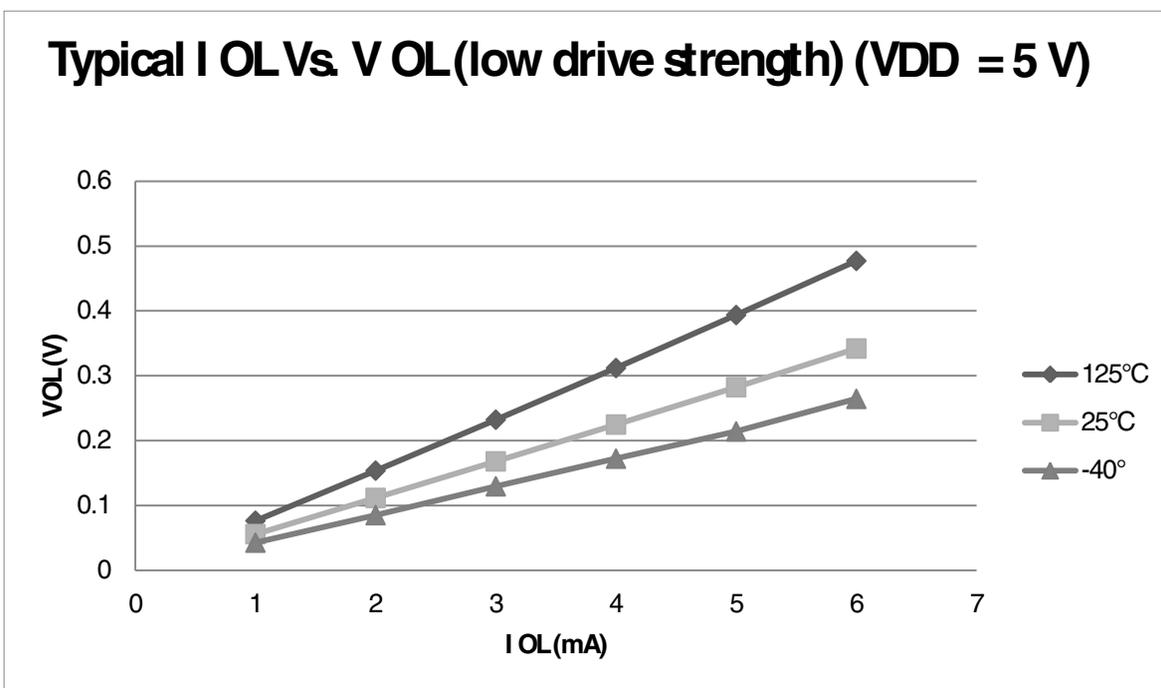


Figure 5. Typical  $I_{OL}$  Vs.  $V_{OL}$  (standard drive strength) ( $V_{DD} = 5\text{ V}$ )

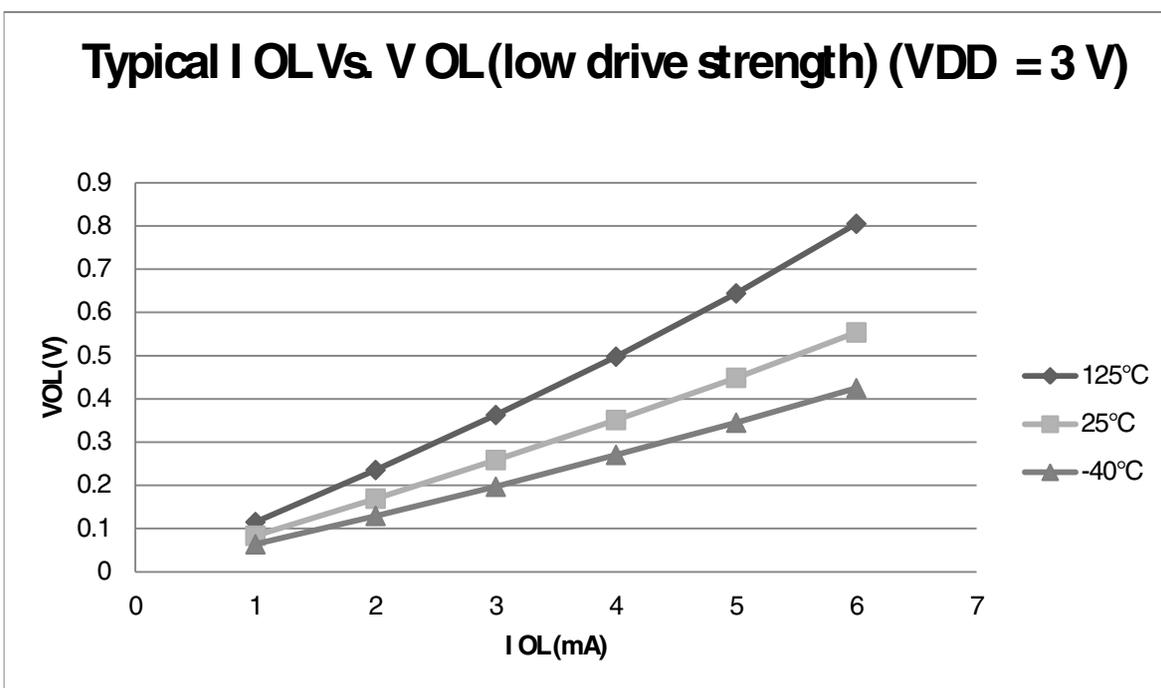


Figure 6. Typical  $I_{OL}$  Vs.  $V_{OL}$  (standard drive strength) ( $V_{DD} = 3\text{ V}$ )

## 5.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

**Table 4. Supply current characteristics**

Num	C	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max	Unit	Temp
1	C	Run supply current FEI mode, all modules on; run from flash	R <sub>I</sub> DD	20 MHz	5	7.60	—	mA	-40 to 125 °C
	C			10 MHz		4.65	—		
	C			1 MHz		1.90	—		
	C			20 MHz	3	7.05	—		
	C			10 MHz		4.40	—		
	C			1 MHz		1.85	—		
2	C	Run supply current FEI mode, all modules off & gated; run from flash	R <sub>I</sub> DD	20 MHz	5	5.88	—	mA	-40 to 125 °C
	C			10 MHz		3.70	—		
	C			1 MHz		1.85	—		
	C			20 MHz	3	5.35	—		
	C			10 MHz		3.42	—		
	C			1 MHz		1.80	—		
3	P	Run supply current FBE mode, all modules on; run from RAM	R <sub>I</sub> DD	20 MHz	5	10.9	14.0	mA	-40 to 125 °C
	C			10 MHz		6.10	—		
	C			1 MHz		1.69	—		
	C			20 MHz	3	8.18	—		
	C			10 MHz		5.14	—		
	C			1 MHz		1.44	—		
4	P	Run supply current FBE mode, all modules off & gated; run from RAM	R <sub>I</sub> DD	20 MHz	5	8.50	13.0	mA	-40 to 125 °C
	C			10 MHz		5.07	—		
	C			1 MHz		1.59	—		
	C			20 MHz	3	6.11	—		
	C			10 MHz		4.10	—		
	C			1 MHz		1.34	—		
5	C	Wait mode current FEI mode, all modules on	W <sub>I</sub> DD	20 MHz	5	5.95	—	mA	-40 to 125 °C
	C			10 MHz		3.50	—		
	C			1 MHz		1.24	—		
	C			20 MHz	3	5.45	—		
	C			10 MHz		3.25	—		
	C			1 MHz		1.20	—		
6	C	Stop3 mode supply current no clocks active (except 1kHz LPO clock) <sup>2,3</sup>	S3 <sub>I</sub> DD	—	5	4.6	—	μA	-40 to 125 °C
	C			—	3	4.5	—		-40 to 125 °C
7	C	ADC adder to stop3	—	—	5	40	—	μA	-40 to 125 °C

Table continues on the next page...

**Table 4. Supply current characteristics (continued)**

Num	C	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max	Unit	Temp
	C	ADLPC = 1 ADLSMP = 1 ADCO = 1 MODE = 10B ADICLK = 11B			3	39	—		
8	C	TSI adder to stop3 <sup>4</sup>	—	—	5	121	—	μA	-40 to 125 °C
	C	PS = 010B NSCN = 0x0F EXTCHRG = 0 REFCHRG = 0 DVOLT = 01B			3	120	—		
9	C	LVD adder to stop3 <sup>5</sup>	—	—	5	128	—	μA	-40 to 125 °C
	C				3	124	—		

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. RTC adder cause <1 μA I<sub>DD</sub> increase typically, RTC clock source is 1kHz LPO clock.
3. ACMP adder cause <10 μA I<sub>DD</sub> increase typically.
4. The current varies with TSI configuration and capacity of touch electrode. Please refer to [TSI electrical specifications](#).
5. LVD is periodically woken up from stop3 by 5% duty cycle. The period is equal to or less than 2 ms.

### 5.1.3 EMC performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as [AN2321](#), [AN1050](#), [AN1263](#), [AN2764](#), and [AN1259](#) for advice and guidance specifically targeted at optimizing EMC performance.

## 5.2 Switching specifications

### 5.2.1 Control timing

**Table 5. Control timing**

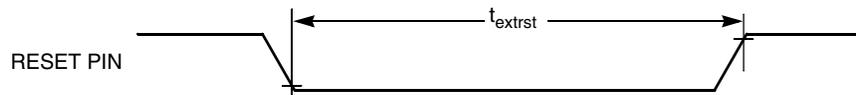
Num	C	Rating	Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	P	Bus frequency ( $t_{cyc} = 1/f_{Bus}$ )	f <sub>Bus</sub>	DC	—	20	MHz
2	P	Internal low power oscillator frequency	f <sub>LPO</sub>	0.67	1.0	1.25	KHz

Table continues on the next page...

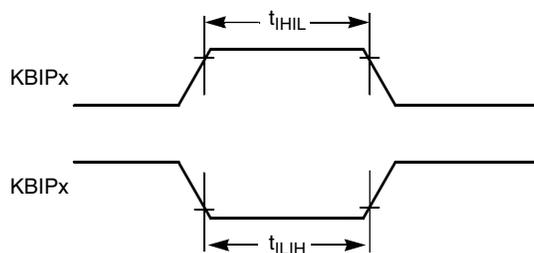
**Table 5. Control timing (continued)**

Num	C	Rating	Symbol	Min	Typical <sup>1</sup>	Max	Unit
3	D	External reset pulse width <sup>2</sup>	$t_{extrst}$	$1.5 \times t_{Self\_reset}$	—	—	ns
4	D	Reset low drive	$t_{rstdrv}$	$34 \times t_{cyc}$	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	$t_{MSSU}$	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup>	$t_{MSH}$	100	—	—	ns
7	D	Keyboard interrupt pulse width	Asynchronous path <sup>2</sup>	$t_{LIH}$	100	—	ns
	D		Synchronous path	$t_{IHIL}$	$1.5 \times t_{cyc}$	—	ns
8	C	Port rise and fall time - standard drive strength (load = 50 pF) <sup>4</sup>	—	$t_{Rise}$	—	10.2	ns
	C		—	$t_{Fall}$	—	9.5	ns
	C	Port rise and fall time - high drive strength (load = 50 pF) <sup>4</sup>	—	$t_{Rise}$	—	5.4	ns
	C		—	$t_{Fall}$	—	4.6	ns

1. Typical values are based on characterization data at  $V_{DD} = 5.0\text{ V}$ ,  $25\text{ }^\circ\text{C}$  unless otherwise stated.
2. This is the shortest pulse that is guaranteed to be recognized as a reset pin request.
3. To enter BDM mode following a POR, BKGD/MS must be held low during the powerup and for a hold time of  $t_{MSH}$  after  $V_{DD}$  rises above  $V_{LVD}$ .
4. Timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  levels. Temperature range  $-40\text{ }^\circ\text{C}$  to  $125\text{ }^\circ\text{C}$ .



**Figure 9. Reset timing**



**Figure 10. KBIPx timing**

## 5.2.2 Debug trace timing specifications

**Table 6. Debug trace operating behaviors**

Symbol	Description	Min.	Max.	Unit
$t_{cyc}$	Clock period	Frequency dependent		MHz
$t_{wl}$	Low pulse width	2	—	ns

Table continues on the next page...

**Table 8. Thermal characteristics (continued)**

Rating	Symbol	Value	Unit
48-pin LQFP	$\theta_{JA}$	58	°C/W
32-pin LQFP	$\theta_{JA}$	59	°C/W
20-pin TSSOP	$\theta_{JA}$	76	°C/W
16-pin TSSOP	$\theta_{JA}$	87	°C/W

The average chip-junction temperature ( $T_J$ ) in °C can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA})$$

Where:

$T_A$  = Ambient temperature, °C

$\theta_{JA}$  = Package thermal resistance, junction-to-ambient, °C/W

$$P_D = P_{int} + P_{I/O}$$

$P_{int} = I_{DD} \times V_{DD}$ , Watts - chip internal power

$P_{I/O}$  = Power dissipation on input and output pins - user determined

For most applications,  $P_{I/O} \ll P_{int}$  and can be neglected. An approximate relationship between  $P_D$  and  $T_J$  (if  $P_{I/O}$  is neglected) is:

$$P_D = K \div (T_J + 273 \text{ °C})$$

Solving the equations above for K gives:

$$K = P_D \times (T_A + 273 \text{ °C}) + \theta_{JA} \times (P_D)^2$$

where K is a constant pertaining to the particular part. K can be determined by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  can be obtained by solving the above equations iteratively for any value of  $T_A$ .

## 6 Peripheral operating requirements and behaviors

## 6.1 External oscillator (XOSC) and ICS characteristics

**Table 9. XOSC and ICS specifications (temperature range = -40 to 125 °C ambient)**

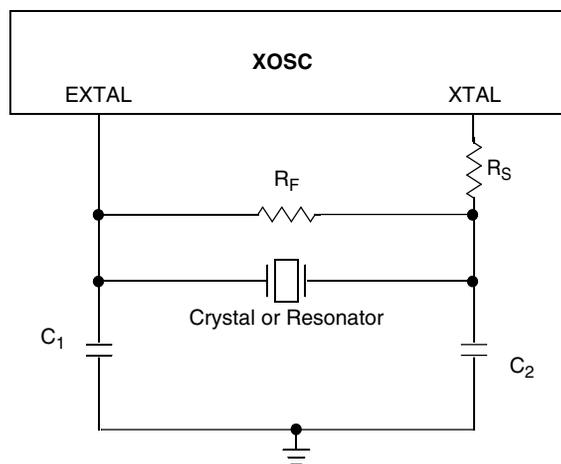
Num	C	Characteristic		Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	C	Oscillator crystal or resonator	Low range (RANGE = 0)	$f_{lo}$	32	—	40	kHz
	C		High range (RANGE = 1) FEE or FBE mode <sup>2</sup>	$f_{hi}$	4	—	20	MHz
	C		High range (RANGE = 1), high gain (HGO = 1), FBELP mode	$f_{hi}$	4	—	20	MHz
	C		High range (RANGE = 1), low power (HGO = 0), FBELP mode	$f_{hi}$	4	—	20	MHz
2	D	Load capacitors		C1, C2	See Note <sup>3</sup>			
3	D	Feedback resistor	Low Frequency, Low-Power Mode <sup>4</sup>	$R_F$	—	—	—	MΩ
			Low Frequency, High-Gain Mode		—	10	—	MΩ
			High Frequency, Low-Power Mode		—	1	—	MΩ
			High Frequency, High-Gain Mode		—	1	—	MΩ
4	D	Series resistor - Low Frequency	Low-Power Mode <sup>4</sup>	$R_S$	—	—	—	kΩ
			High-Gain Mode		—	200	—	kΩ
5	D	Series resistor - High Frequency	Low-Power Mode <sup>4</sup>	$R_S$	—	—	—	kΩ
	D	Series resistor - High Frequency, High-Gain Mode	4 MHz		—	0	—	kΩ
	D		8 MHz		—	0	—	kΩ
	D		16 MHz		—	0	—	kΩ
6	C	Crystal start-up time Low range = 39.0625 kHz crystal; High range = 20 MHz crystal <sup>5, 6</sup>	Low range, low power	$t_{CSTL}$	—	1000	—	ms
	C		Low range, high power		—	800	—	ms
	C		High range, low power	$t_{CSTH}$	—	3	—	ms
	C		High range, high power		—	1.5	—	ms
7	T	Internal reference start-up time		$t_{IRST}$	—	20	50	μs
8	D	Square wave input clock frequency	FEE or FBE mode <sup>2</sup>	$f_{extal}$	0.03125	—	5	MHz
	D		FBELP mode		0	—	20	MHz
9	P	Average internal reference frequency - trimmed		$f_{int\_t}$	—	39.0625	—	kHz
10	P	DCO output frequency range - trimmed		$f_{dco\_t}$	16	—	20	MHz
11	P	Total deviation of DCO output from trimmed frequency <sup>5</sup>	Over full voltage range and temperature range of -40 to 125 °C	$\Delta f_{dco\_t}$	—	—	±2.0	
	C		Over full voltage range and temperature range of -40 to 105 °C		—	—	±1.5	% $f_{dco}$

Table continues on the next page...

**Table 9. XOSC and ICS specifications (temperature range = -40 to 125 °C ambient)  
(continued)**

Num	C	Characteristic	Symbol	Min	Typical <sup>1</sup>	Max	Unit
	C	Over fixed voltage and temperature range of 0 to 70 °C				±1.0	
12	C	FLL acquisition time <sup>5, 7</sup>	$t_{Acquire}$	—	—	2	ms
13	C	Long term jitter of DCO output clock (averaged over 2 ms interval) <sup>8</sup>	$C_{Jitter}$	—	0.02	0.2	% $f_{dco}$

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. When ICS is configured for FEE or FBE mode, input clock source must be divisible using RDIV to within the range of 31.25 kHz to 39.0625 kHz.
3. See crystal or resonator manufacturer's recommendation.
4. Load capacitors ( $C_1, C_2$ ), feedback resistor ( $R_F$ ) and series resistor ( $R_S$ ) are incorporated internally when RANGE = HGO = 0.
5. This parameter is characterized and not tested on each device.
6. Proper PC board layout procedures must be followed to achieve specifications.
7. This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
8. Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum  $f_{Bus}$ . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via  $V_{DD}$  and  $V_{SS}$  and variation in crystal oscillator frequency increase the  $C_{Jitter}$  percentage for a given interval.


**Figure 15. Typical crystal or resonator circuit**

## 6.2 NVM specifications

This section provides details about program/erase times and program/erase endurance for the flash and EEPROM memories.

**Table 10. Flash characteristics**

C	Characteristic	Symbol	Min <sup>1</sup>	Typical <sup>2</sup>	Max <sup>3</sup>	Unit <sup>4</sup>
D	Supply voltage for program/erase -40 °C to 125 °C	$V_{\text{prog/erase}}$	2.7	—	5.5	V
D	Supply voltage for read operation	$V_{\text{Read}}$	2.7	—	5.5	V
D	NVM Bus frequency	$f_{\text{NVMBUS}}$	1	—	25	MHz
D	NVM Operating frequency	$f_{\text{NVMOP}}$	0.8	1	1.05	MHz
D	Erase Verify All Blocks	$t_{\text{VFYALL}}$	—	—	17338	$t_{\text{cyc}}$
D	Erase Verify Flash Block	$t_{\text{RD1BLK}}$	—	—	16913	$t_{\text{cyc}}$
D	Erase Verify EEPROM Block	$t_{\text{RD1BLK}}$	—	—	810	$t_{\text{cyc}}$
D	Erase Verify Flash Section	$t_{\text{RD1SEC}}$	—	—	484	$t_{\text{cyc}}$
D	Erase Verify EEPROM Section	$t_{\text{DRD1SEC}}$	—	—	555	$t_{\text{cyc}}$
D	Read Once	$t_{\text{RDONCE}}$	—	—	450	$t_{\text{cyc}}$
D	Program Flash (2 word)	$t_{\text{PGM2}}$	0.12	0.12	0.29	ms
D	Program Flash (4 word)	$t_{\text{PGM4}}$	0.20	0.21	0.46	ms
D	Program Once	$t_{\text{PGMONCE}}$	0.20	0.21	0.21	ms
D	Program EEPROM (1 Byte)	$t_{\text{DPGM1}}$	0.10	0.10	0.27	ms
D	Program EEPROM (2 Byte)	$t_{\text{DPGM2}}$	0.17	0.18	0.43	ms
D	Program EEPROM (3 Byte)	$t_{\text{DPGM3}}$	0.25	0.26	0.60	ms
D	Program EEPROM (4 Byte)	$t_{\text{DPGM4}}$	0.32	0.33	0.77	ms
D	Erase All Blocks	$t_{\text{ERSALL}}$	96.01	100.78	101.49	ms
D	Erase Flash Block	$t_{\text{ERSBLK}}$	95.98	100.75	101.44	ms
D	Erase Flash Sector	$t_{\text{ERSPG}}$	19.10	20.05	20.08	ms
D	Erase EEPROM Sector	$t_{\text{DERSPG}}$	4.81	5.05	20.57	ms
D	Unsecure Flash	$t_{\text{UNSECU}}$	96.01	100.78	101.48	ms
D	Verify Backdoor Access Key	$t_{\text{VFYKEY}}$	—	—	464	$t_{\text{cyc}}$
D	Set User Margin Level	$t_{\text{MLOADU}}$	—	—	407	$t_{\text{cyc}}$
C	FLASH Program/erase endurance $T_L$ to $T_H = -40$ °C to 125 °C	$n_{\text{FLPE}}$	10 k	100 k	—	Cycles
C	EEPROM Program/erase endurance $T_L$ to $T_H = -40$ °C to 125 °C	$n_{\text{FLPE}}$	50 k	500 k	—	Cycles
C	Data retention at an average junction temperature of $T_{\text{Javg}} = 85$ °C after up to 10,000 program/erase cycles	$t_{\text{D-ret}}$	15	100	—	years

1. Minimum times are based on maximum  $f_{\text{NVMOP}}$  and maximum  $f_{\text{NVMBUS}}$
2. Typical times are based on typical  $f_{\text{NVMOP}}$  and maximum  $f_{\text{NVMBUS}}$
3. Maximum times are based on typical  $f_{\text{NVMOP}}$  and typical  $f_{\text{NVMBUS}}$  plus aging
4.  $t_{\text{cyc}} = 1 / f_{\text{NVMBUS}}$

## 6.3.2 Analog comparator (ACMP) electricals

**Table 13. Comparator electrical specifications**

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	$V_{DDA}$	2.7	—	5.5	V
T	Supply current (Operation mode)	$I_{DDA}$	—	10	20	$\mu$ A
D	Analog input voltage	$V_{AIN}$	$V_{SS} - 0.3$	—	$V_{DDA}$	V
P	Analog input offset voltage	$V_{AIO}$	—	—	40	mV
C	Analog comparator hysteresis (HYST=0)	$V_H$	—	15	20	mV
C	Analog comparator hysteresis (HYST=1)	$V_H$	—	20	30	mV
T	Supply current (Off mode)	$I_{DDAOFF}$	—	60	—	nA
C	Propagation Delay	$t_D$	—	0.4	1	$\mu$ s

## 6.4 Communication interfaces

### 6.4.1 SPI switching specifications

The serial peripheral interface (SPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic SPI timing modes. Refer to the SPI chapter of the chip's reference manual for information about the modified transfer formats used for communicating with slower peripheral devices. All timing is shown with respect to 20%  $V_{DD}$  and 70%  $V_{DD}$ , unless noted, and 100 pF load on all SPI pins. All timing assumes slew rate control is disabled and high drive strength is enabled for SPI output pins.

**Table 14. SPI master mode timing**

Num.	Symbol	Description	Min.	Max.	Unit	Comment
1	$f_{op}$	Frequency of operation	$f_{Bus}/2048$	$f_{Bus}/2$	Hz	$f_{Bus}$ is the bus clock
2	$t_{SPSCK}$	SPSCK period	$2 \times t_{Bus}$	$2048 \times t_{Bus}$	ns	$t_{Bus} = 1/f_{Bus}$
3	$t_{Lead}$	Enable lead time	1/2	—	$t_{SPSCK}$	—
4	$t_{Lag}$	Enable lag time	1/2	—	$t_{SPSCK}$	—
5	$t_{WSPSCK}$	Clock (SPSCK) high or low time	$t_{Bus} - 30$	$1024 \times t_{Bus}$	ns	—
6	$t_{SU}$	Data setup time (inputs)	15	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	0	—	ns	—
8	$t_v$	Data valid (after SPSCK edge)	—	25	ns	—
9	$t_{HO}$	Data hold time (outputs)	0	—	ns	—
10	$t_{RI}$	Rise time input	—	$t_{Bus} - 25$	ns	—

Table continues on the next page...

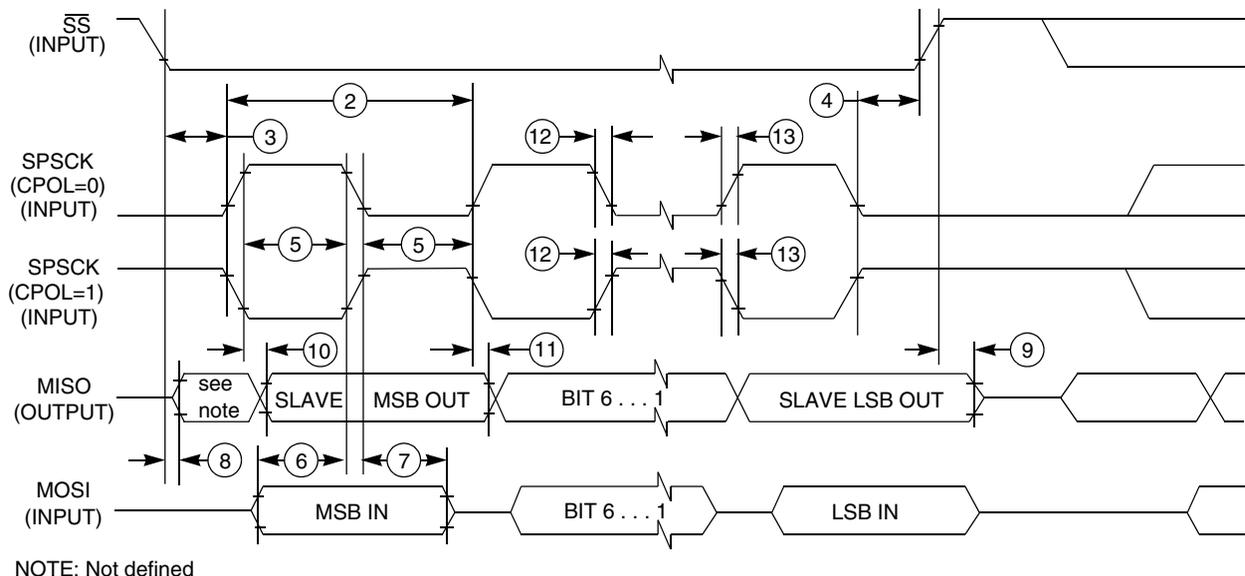


Figure 20. SPI slave mode timing (CPHA=1)

## 6.5 Human-machine interfaces (HMI)

### 6.5.1 TSI electrical specifications

Table 16. TSI electrical specifications

Symbol	Description	Min.	Type	Max	Unit
TSI_RUNF	Fixed power consumption in run mode	—	100	—	μA
TSI_RUNV	Variable power consumption in run mode (depends on oscillator's current selection)	1.0	—	128	μA
TSI_EN	Power consumption in enable mode	—	100	—	μA
TSI_DIS	Power consumption in disable mode	—	1.2	—	μA
TSI_TEN	TSI analog enable time	—	66	—	μs
TSI_CREF	TSI reference capacitor	—	1.0	—	pF
TSI_DVOLT	Voltage variation of VP & VM around nominal values	-10	—	10	%

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

**Table 17. Pin availability by package pin-count (continued)**

Pin Number				Lowest Priority <-- --> Highest				
48-LQFP	32-LQFP	20-TSSOP	16-TSSOP	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
19	—	—	—	PTD6	—	—	—	—
20	—	—	—	PTD5	—	—	—	—
21	13	11	—	PTC1	—	FTM2CH1	ADP9	TSI7
22	14	12	—	PTC0	—	FTM2CH0	ADP8	TSI6
23	15	13	9	PTB3	KBI0P7	MOSI0	ADP7	TSI5
24	16	14	10	PTB2	KBI0P6	SPSCK0	ADP6	TSI4
25	17	15	11	PTB1	KBI0P5	TXD0	ADP5	TSI3
26	18	16	12	PTB0	KBI0P4	RXD0	ADP4	TSI2
27	19	—	—	PTA7	—	FTM2FAULT2	ADP3	TSI1
28	20	—	—	PTA6	—	FTM2FAULT1	ADP2	TSI0
29	—	—	—	NC				
30	—	—	—	—	—	—	—	V <sub>SS</sub>
31	—	—	—	—	—	—	—	V <sub>DD</sub>
32	—	—	—	PTD4	—	—	—	—
33	21	—	—	PTD3	—	—	—	TSI15
34	22	—	—	PTD2	—	—	—	TSI14
35	23	17	13	PTA3 <sup>2</sup>	KBI0P3	TXD0	SCL	—
36	24	18	14	PTA2 <sup>2</sup>	KBI0P2	RXD0	SDA	—
37	25	19	15	PTA1	KBI0P1	FTM0CH1	ACMP1	ADP1
38	26	20	16	PTA0	KBI0P0	FTM0CH0	ACMP0	ADP0
39	27	—	—	PTC7	—	TxD1	—	TSI13
40	28	—	—	PTC6	—	RxD1	—	TSI12
41	—	—	—	NC				
42	—	—	—	PTE2	—	MISO0	—	—
43	—	—	—	PTE1	—	MOSI0	—	—
44	—	—	—	PTE0	—	SPSCK0	—	—
45	29	—	—	PTC5	—	FTM0CH1	—	TSI11
46	30	—	—	PTC4	—	FTM0CH0	—	TSI10
47	31	1	1	—	—	—	—	RESET
48	32	2	2	—	—	—	BKGD	MS

1. This is a high current drive pin when operated as output.
2. This is a true open-drain pin when operated as output.

### Note

When an alternative function is first enabled, it is possible to get a spurious edge to the module. User software must clear any associated flags before interrupts are enabled. The table above illustrates the priority if multiple modules are enabled. The

highest priority module will have control over the pin. Selecting a higher priority pin function with a lower priority function already enabled can cause spurious edges to the lower priority module. Disable all modules that share a pin before enabling another module.

## 8.2 Device pin assignment

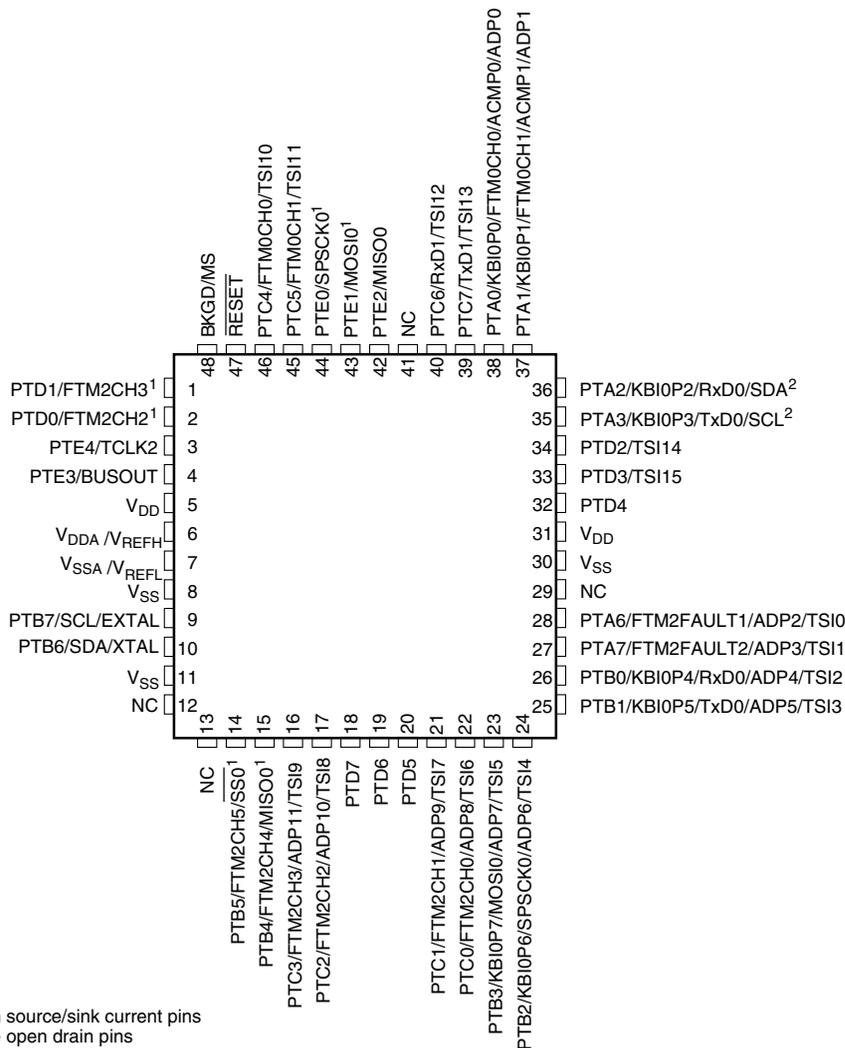
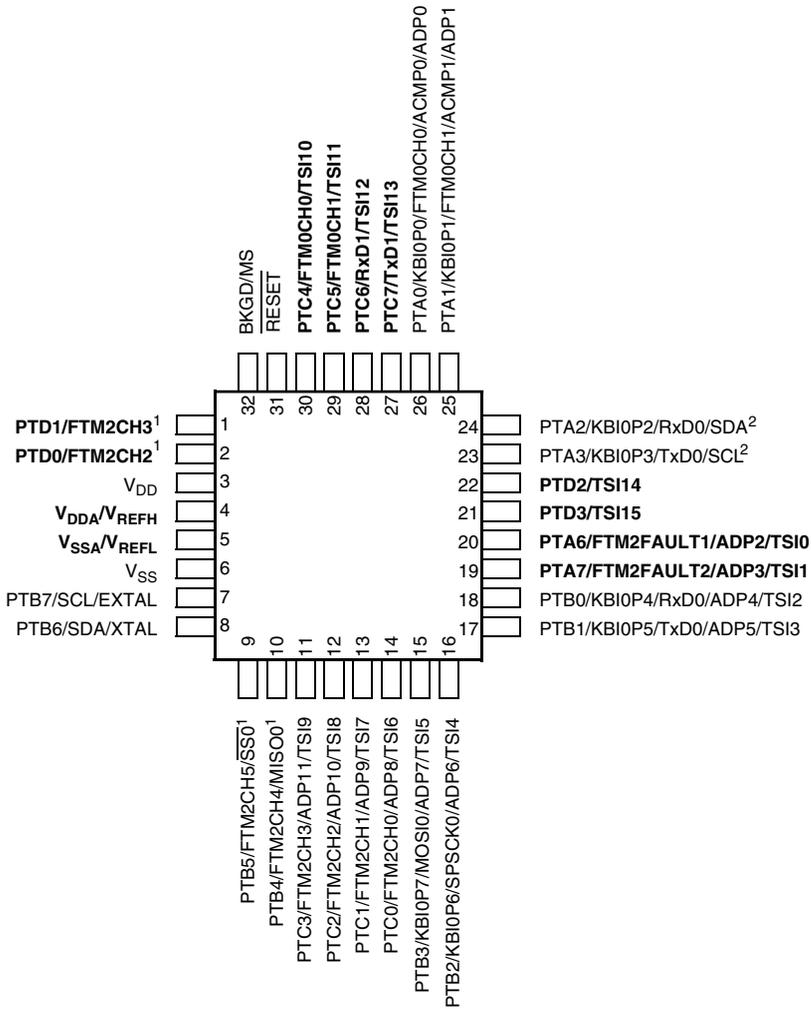


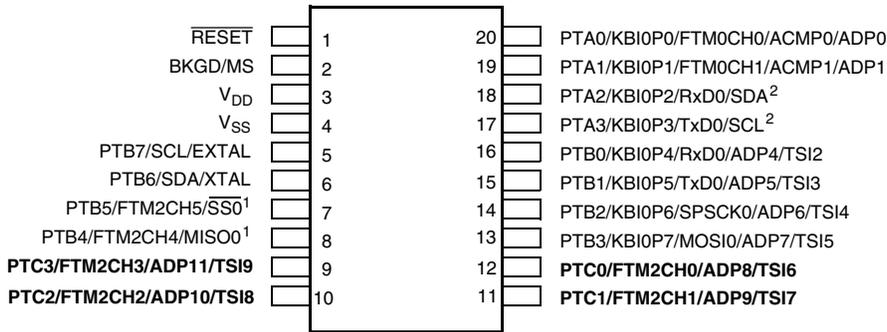
Figure 21. S9S08RN16 48-pin LQFP package



Pins in **bold** are not available on less pin-count packages.

- 1. High source/sink current pins
- 2. True open drain pins

**Figure 22. S9S08RN16 32-pin LQFP package**



Pins in **bold** are not available on less pin-count packages.

- 1. High source/sink current pins
- 2. True open drain pins

**Figure 23. S9S08RN16 20-pin TSSOP package**



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