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### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	51
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	12K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256mu806t-i-pt">https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256mu806t-i-pt</a>

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## 2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS AND MICROCONTROLLERS

**Note 1:** This data sheet summarizes the features of the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the “dsPIC33E/PIC24E Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com))

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

### 2.1 Basic Connection Requirements

Getting started with the 16-bit DSCs and microcontrollers requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names, which must always be connected:

- All VDD and VSS pins (see **Section 2.2 “Decoupling Capacitors”**)
- All AVDD and AVSS pins (regardless if ADC module is not used) (see **Section 2.2 “Decoupling Capacitors”**)
- VCAP (see **Section 2.3 “CPU Logic Filter Capacitor Connection (VCAP)”**)
- MCLR pin (see **Section 2.4 “Master Clear (MCLR) Pin”**)
- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes (see **Section 2.5 “ICSP Pins”**)
- OSC1 and OSC2 pins when external oscillator source is used (see **Section 2.6 “External Oscillator Pins”**)

Additionally, the following pins may be required:

- VUSB3V3 pin is used when utilizing the USB module. If the USB module is not used, VUSB3V3 must be connected to VDD.
- VREF+/VREF- pin is used when external voltage reference for ADC module is implemented

**Note:** The AVDD and AVSS pins must be connected independent of the ADC voltage reference source. The voltage difference between AVDD and VDD cannot exceed 300 mV at any time during operation or start-up.

### 2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, VUSB3V3, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

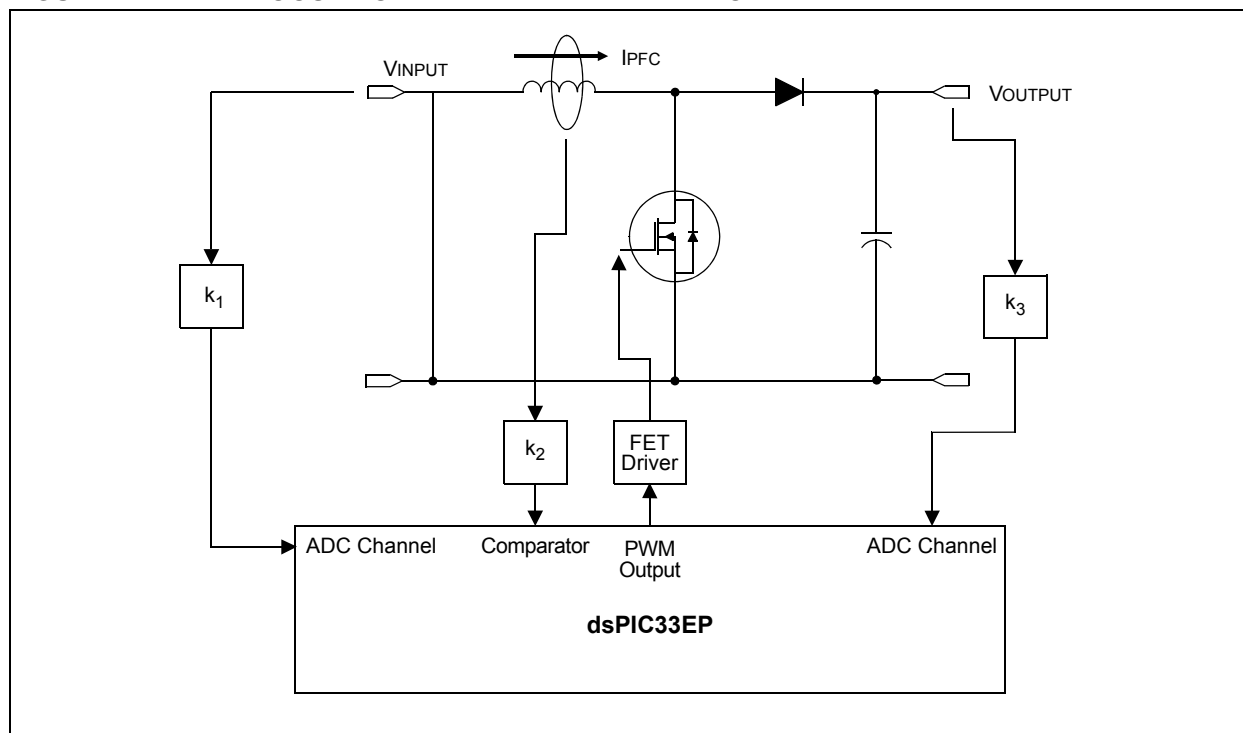
- **Value and type of capacitor:** Recommendation of 0.1  $\mu$ F (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended to use ceramic capacitors.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is within one-quarter inch (6 mm) in length.
- **Handling high frequency noise:** If the board is experiencing high frequency noise, above tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01  $\mu$ F to 0.001  $\mu$ F. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1  $\mu$ F in parallel with 0.001  $\mu$ F.
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB track inductance.

## 2.9 Application Examples

- Induction heating
- Uninterruptable Power Supplies (UPS)
- DC/AC inverters
- Compressor motor control
- Washing machine 3-phase motor control
- BLDC motor control
- Automotive HVAC, cooling fans, fuel pumps
- Stepper motor control
- Audio and fluid sensor monitoring
- Camera lens focus and stability control
- Speech (playback, hands-free kits, answering machines, VoIP)
- Consumer audio
- Industrial and building control (security systems and access control)
- Barcode reading
- Networking: LAN switches, gateways
- Data storage device management
- Smart cards and smart card readers

Examples of typical application connections are shown in Figure 2-4 through Figure 2-8.

**FIGURE 2-4: BOOST CONVERTER IMPLEMENTATION**



**TABLE 4-16: PWM GENERATOR 4 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
PWMCON4	0C80	FLTSTAT	CLSTAT	TRGSTAT	FLTIEEN	CLIEEN	TRGIEEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000	
IOCON4	0C82	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000	
FCLCON4	0C84	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000	
PDC4	0C86	PDC4<15:0>																0000	
PHASE4	0C88	PHASE4<15:0>																0000	
DTR4	0C8A	—	—	DTR4<13:0>														0000	
ALTDTR4	0C8C	—	—	ALTDTR4<13:0>														0000	
SDC4	0C8E	SDC4<15:0>																0000	
SPHASE4	0C90	SPHASE4<15:0>																0000	
TRIG4	0C92	TRGCMP<15:0>																0000	
TRGCON4	0C94	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>							0000
PWMCAP4	0C98	PWMCAP4<15:0>																0000	
LEBCON4	0C9A	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000	
LEBDLY4	0C9C	—	—	—	—	LEB<11:0>												0000	
AUXCON4	0C9E	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000	

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-17: PWM GENERATOR 5 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)810/814 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets		
PWMCON5	0CA0	FLTSTAT	CLSTAT	TRGSTAT	FLTIEEN	CLIEEN	TRGIEEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000		
IOCON5	0CA2	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000		
FCLCON5	0CA4	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000		
PDC5	0CA6	PDC5<15:0>																0000		
PHASE5	0CA8	PHASE5<15:0>																0000		
DTR5	0CAA	—	—	DTR5<13:0>														0000		
ALTDTR5	0CAC	—	—	ALTDTR5<13:0>														0000		
SDC5	0CAE	SDC5<15:0>																0000		
SPHASE5	0CB0	SPHASE5<15:0>																0000		
TRIG5	0CB2	TRGCMP<15:0>																0000		
TRGCON5	0CB4	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>							0000	
PWMCAP5	0CB8	PWM Capture<15:0>																0000		
LEBCON5	0CBA	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000		
LEBDLY5	0CBC	—	—	—	—	LEB<11:0>														0000
AUXCON5	0CBE	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000		

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-37: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33EPXXXMU810/814 AND PIC24EPXXXGU810/814 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	0680	—	—	RP65R<5:0>					—	—	RP64R<5:0>							0000
RPOR1	0682	—	—	RP67R<5:0>					—	—	RP66R<5:0>							0000
RPOR2	0684	—	—	RP69R<5:0>					—	—	RP68R<5:0>							0000
RPOR3	0686	—	—	RP71R<5:0>					—	—	RP70R<5:0>							0000
RPOR4	0688	—	—	RP80R<5:0>					—	—	RP79R<5:0>							0000
RPOR5	068A	—	—	RP84R<5:0>					—	—	RP82R<5:0>							0000
RPOR6	068C	—	—	RP87R<5:0>					—	—	RP85R<5:0>							0000
RPOR7	068E	—	—	RP97R<5:0>					—	—	RP96R<5:0>							0000
RPOR8	0690	—	—	RP99R<5:0>					—	—	RP98R<5:0>							0000
RPOR9	0692	—	—	RP101R<5:0>					—	—	RP100R<5:0>							0000
RPOR11	0696	—	—	RP108R<5:0>					—	—	RP104R<5:0>							0000
RPOR12	0698	—	—	RP112R<5:0>					—	—	RP109R<5:0>							0000
RPOR13	069A	—	—	RP118R<5:0>					—	—	RP113R<5:0>							0000
RPOR14	069C	—	—	RP125R<5:0>					—	—	RP120R<5:0>							0000
RPOR15	069E	—	—	RP127R<5:0>					—	—	RP126R<5:0>							0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-75: FUNDAMENTAL ADDRESSING MODES SUPPORTED

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn forms the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn forms the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

#### 4.5.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions (dsPIC33EPXXXMU806/810/814 and PIC24EPXXXGU810/814) and the DSP accumulator class of instructions (dsPIC33EPXXXMU806/810/814 only) provide a greater degree of addressing flexibility than other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

**Note:** For the `MOV` instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (Register Offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-modified
- Register Indirect Pre-modified
- Register Indirect with Register Offset (Indexed)
- Register Indirect with Literal Offset
- 8-Bit Literal
- 16-Bit Literal

**Note:** Not all instructions support all the addressing modes given above. Individual instructions may support different subsets of these addressing modes.

#### 4.5.4 MAC INSTRUCTIONS (dsPIC33EPXXXMU806/810/814 DEVICES ONLY)

The dual source operand DSP instructions (`CLR`, `ED`, `EDAC`, `MAC`, `MPY`, `MPY.N`, `MOVSAC` and `MSC`), also referred to as `MAC` instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the Data Pointers through register indirect tables.

The two-source operand prefetch registers must be members of the set {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The Effective Addresses generated (before and after modification) must, therefore, be valid addresses within X data space for W8 and W9 and Y data space for W10 and W11.

**Note:** Register Indirect with Register Offset Addressing mode is available only for W9 (in X space) and W11 (in Y space).

In summary, the following addressing modes are supported by the `MAC` class of instructions:

- Register Indirect
- Register Indirect Post-Modified by 2
- Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

#### 4.5.5 OTHER INSTRUCTIONS

Besides the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, `BRA` (branch) instructions use 16-bit signed literals to specify the branch destination directly, whereas the `DISI` instruction uses a 14-bit unsigned literal field. In some instructions, such as `ULNK`, the source of an operand or result is implied by the opcode itself. Certain operations, such as `NOP`, do not have any operands.

#### 4.6.3 MODULO ADDRESSING APPLICABILITY

Modulo Addressing can be applied to the Effective Address (EA) calculation associated with any W register. Address boundaries check for addresses equal to:

- The upper boundary addresses for incrementing buffers
- The lower boundary addresses for decrementing buffers

It is important to realize that the address boundaries check for addresses less than or greater than the upper (for incrementing buffers) and lower (for decrementing buffers) boundary addresses (not just equal to). Address changes can, therefore, jump beyond boundaries and still be adjusted correctly.

**Note:** The modulo corrected Effective Address is written back to the register only when Pre-Modify or Post-Modify Addressing mode is used to compute the Effective Address. When an address offset (such as  $[W7 + W2]$ ) is used, Modulo Addressing correction is performed but the contents of the register remain unchanged.

#### 4.7 Bit-Reversed Addressing (dsPIC33EPXXXMU806/810/814 Devices Only)

Bit-Reversed Addressing mode is intended to simplify data reordering for radix-2 FFT algorithms. It is supported by the X AGU for data writes only.

The modifier, which can be a constant value or register contents, is regarded as having its bit order reversed. The address source and destination are kept in normal order. Thus, the only operand requiring reversal is the modifier.

##### 4.7.1 BIT-REVERSED ADDRESSING IMPLEMENTATION

Bit-Reversed Addressing mode is enabled in any of these situations:

- BWMx bits (W register selection) in the MODCON register are any value other than '1111' (the stack cannot be accessed using Bit-Reversed Addressing)
- The BREN bit is set in the XBREV register
- The addressing mode used is Register Indirect with Pre-Increment or Post-Increment

If the length of a bit-reversed buffer is  $M = 2^N$  bytes, the last 'N' bits of the data buffer start address must be zeros.

$XB<14:0>$  is the Bit-Reversed Address modifier, or 'pivot point,' which is typically a constant. In the case of an FFT computation, its value is equal to half of the FFT data buffer size.

**Note:** All bit-reversed EA calculations assume word-sized data (LSb of every EA is always clear). The XB value is scaled accordingly to generate compatible (byte) addresses.

When enabled, Bit-Reversed Addressing is executed only for Register Indirect with Pre-Increment or Post-Increment Addressing and word-sized data writes. It does not function for any other addressing mode or for byte-sized data and normal addresses are generated instead. When Bit-Reversed Addressing is active, the W Address Pointer is always added to the address modifier (XB) and the offset associated with the Register Indirect Addressing mode is ignored. In addition, as word-sized data is a requirement, the LSb of the EA is ignored (and always clear).

**Note:** Modulo Addressing and Bit-Reversed Addressing can be enabled simultaneously using the same W register, but Bit-Reversed Addressing operation will always take precedence for data writes when enabled.

If Bit-Reversed Addressing has already been enabled by setting the BREN ( $XBREV<15>$ ) bit, a write to the XBREV register should not be immediately followed by an indirect read operation using the W register that has been designated as the Bit-Reversed Pointer.



**REGISTER 8-3: DMAxSTAH: DMA CHANNEL x START ADDRESS REGISTER A (HIGH)**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STA<23:16>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'bit 7-0 **STA<23:16>:** Primary Start Address bits (source or destination)**REGISTER 8-4: DMAxSTAL: DMA CHANNEL x START ADDRESS REGISTER A (LOW)**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STA<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STA<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **STA<15:0>:** Primary Start Address bits (source or destination)

**REGISTER 8-14: DMAPPS: DMA PING-PONG STATUS REGISTER**

U-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
—	PPST14	PPST13	PPST12	PPST11	PPST10	PPST9	PPST8
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
PPST7	PPST6	PPST5	PPST4	PPST3	PPST2	PPST1	PPST0
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **PPST14:** Channel 14 Ping-Pong Mode Status Flag bit  
              1 = DMASTB14 register selected  
              0 = DMASTA14 register selected
- bit 13      **PPST13:** Channel 13 Ping-Pong Mode Status Flag bit  
              1 = DMASTB13 register selected  
              0 = DMASTA13 register selected
- bit 12      **PPST12:** Channel 12 Ping-Pong Mode Status Flag bit  
              1 = DMASTB12 register selected  
              0 = DMASTA12 register selected
- bit 11      **PPST11:** Channel 11 Ping-Pong Mode Status Flag bit  
              1 = DMASTB11 register selected  
              0 = DMASTA11 register selected
- bit 10      **PPST10:** Channel 10 Ping-Pong Mode Status Flag bit  
              1 = DMASTB10 register selected  
              0 = DMASTA10 register selected
- bit 9        **PPST9:** Channel 9 Ping-Pong Mode Status Flag bit  
              1 = DMASTB9 register selected  
              0 = DMASTA9 register selected
- bit 8        **PPST8:** Channel 8 Ping-Pong Mode Status Flag bit  
              1 = DMASTB8 register selected  
              0 = DMASTA8 register selected
- bit 7        **PPST7:** Channel 7 Ping-Pong Mode Status Flag bit  
              1 = DMASTB7 register selected  
              0 = DMASTA7 register selected
- bit 6        **PPST6:** Channel 6 Ping-Pong Mode Status Flag bit  
              1 = DMASTB6 register selected  
              0 = DMASTA6 register selected
- bit 5        **PPST5:** Channel 5 Ping-Pong Mode Status Flag bit  
              1 = DMASTB5 register selected  
              0 = DMASTA5 register selected
- bit 4        **PPST4:** Channel 4 Ping-Pong Mode Status Flag bit  
              1 = DMASTB4 register selected  
              0 = DMASTA4 register selected
- bit 3        **PPST3:** Channel 3 Ping-Pong Mode Status Flag bit  
              1 = DMASTB3 register selected  
              0 = DMASTA3 register selected

**REGISTER 9-5: ACLKCON3: AUXILIARY CLOCK CONTROL REGISTER 3<sup>(1,2)</sup>**

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
ENAPLL	—	SELACLK	AOSCMD<1:0>	ASRCSEL	FRCSEL	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
APLLPOST<2:0>			—	—	APLLPRE<2:0>		
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15            **ENAPLL:** Enable Auxiliary PLL (APLL) and Select APLL as USB Clock Source bit  
                   1 = APLL is enabled, the USB clock source is the APLL output  
                   0 = APLL is disabled, the USB clock source is the input clock to the APLL
- bit 14            **Unimplemented:** Read as '0'
- bit 13            **SELACLK:** Select Auxiliary Clock Source for Auxiliary Clock Divider bit  
                   1 = Auxiliary PLL or oscillator provides the source clock for auxiliary clock divider  
                   0 = Primary PLL provides the source clock for auxiliary clock divider
- bit 12-11        **AOSCMD<1:0>:** Auxiliary Oscillator Mode bits  
                   11 = EC (External Clock) Oscillator mode select  
                   10 = XT (Crystal) Oscillator mode select  
                   01 = HS (High-Speed) Oscillator mode select  
                   00 = Auxiliary Oscillator disabled (default)
- bit 10            **ASRCSEL:** Select Reference Clock Source for APLL bit  
                   1 = Primary Oscillator is the clock source for APLL  
                   0 = Auxiliary Oscillator is the clock source for APLL
- bit 9             **FRCSEL:** Select FRC as Reference Clock Source for APLL bit  
                   1 = FRC is the clock source for APLL  
                   0 = Auxiliary Oscillator or Primary Oscillator is the clock source for APLL (determined by ASRCSEL bit)
- bit 8             **Unimplemented:** Read as '0'
- bit 7-5          **APLLPOST<2:0>:** Select PLL VCO Output Divider bits  
                   111 = Divided by 1  
                   110 = Divided by 2  
                   101 = Divided by 4  
                   100 = Divided by 8  
                   011 = Divided by 16  
                   010 = Divided by 32  
                   001 = Divided by 64  
                   000 = Divided by 256 (default)
- bit 4-3          **Unimplemented:** Read as '0'
- bit 2-0          **APLLPRE<2:0>:** PLL Phase Detector Input Divider bits  
                   111 = Divided by 12  
                   110 = Divided by 10  
                   101 = Divided by 6  
                   100 = Divided by 5  
                   011 = Divided by 4  
                   010 = Divided by 3  
                   001 = Divided by 2  
                   000 = Divided by 1 (default)

**Note 1:** This register resets only on a Power-on Reset (POR).

**2:** This register is only available on dsPIC33EPXXXMU8XX and PIC24EPXXXGU8XX devices.

**REGISTER 11-18: RPINR17: PERIPHERAL PIN SELECT INPUT REGISTER 17**  
**(dsPIC33EPXXXMU806/810/814 DEVICES ONLY)**

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	HOME2R<6:0> <sup>(1)</sup>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	INDX2R<6:0> <sup>(1)</sup>						
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-8 **HOME2R<6:0>:** Assign QEI2 HOME2 (HOME2) to the Corresponding RPN/RPIN Pin bits<sup>(1)</sup>  
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **INDX2R<6:0>:** Assign QEI2 INDEX2 (INDEX2) to the Corresponding RPN/RPIN Pin bits<sup>(1)</sup>  
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

**Note 1:** These bits are available on dsPIC33EPXXX(MC/MU)806/810/814 devices only.

**REGISTER 11-45: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1**

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP67R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP66R<5:0>					
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'bit 13-8 **RP67R<5:0>**: Peripheral Output Function is Assigned to RP67 Output Pin bits  
(see Table 11-3 for peripheral function numbers)bit 7-6 **Unimplemented:** Read as '0'bit 5-0 **RP66R<5:0>**: Peripheral Output Function is Assigned to RP66 Output Pin bits  
(see Table 11-3 for peripheral function numbers)**REGISTER 11-46: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2**

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP69R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP68R<5:0>					
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'bit 13-8 **RP69R<5:0>**: Peripheral Output Function is Assigned to RP69 Output Pin bits  
(see Table 11-3 for peripheral function numbers)bit 7-6 **Unimplemented:** Read as '0'bit 5-0 **RP68R<5:0>**: Peripheral Output Function is Assigned to RP68 Output Pin bits  
(see Table 11-3 for peripheral function numbers)

FIGURE 13-1: TYPE B TIMERx BLOCK DIAGRAM (x = 2, 4, 6 AND 8)

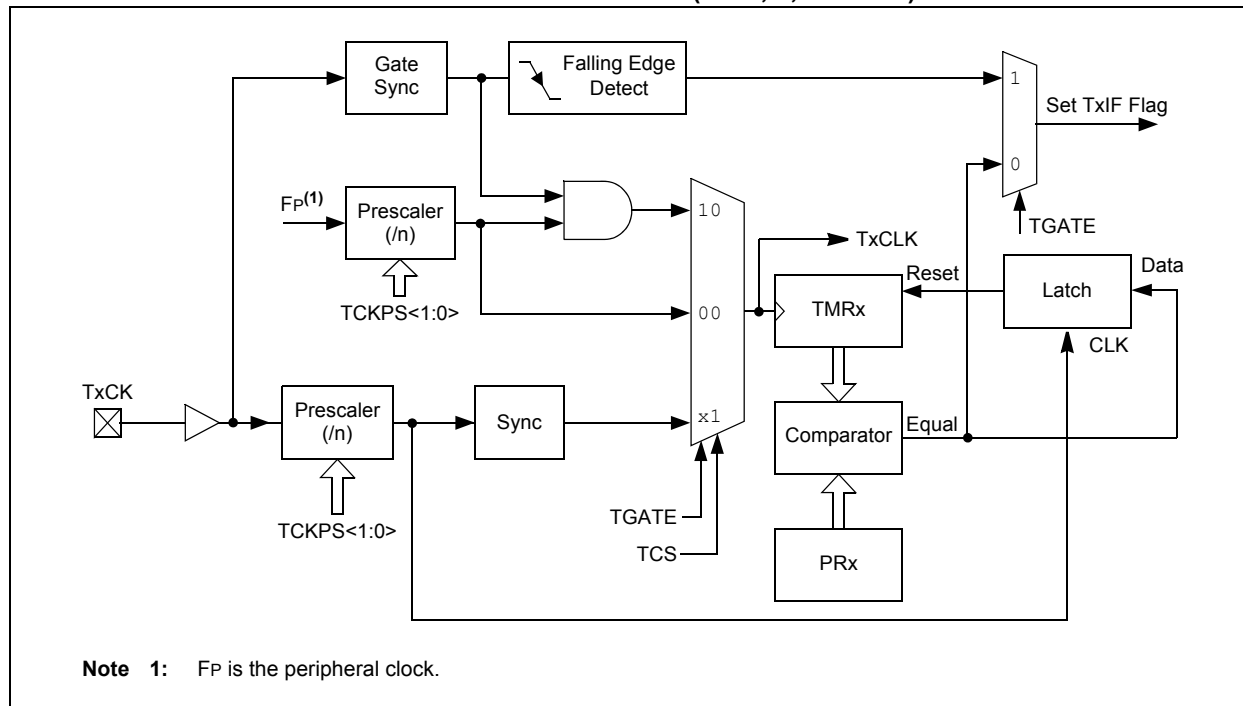
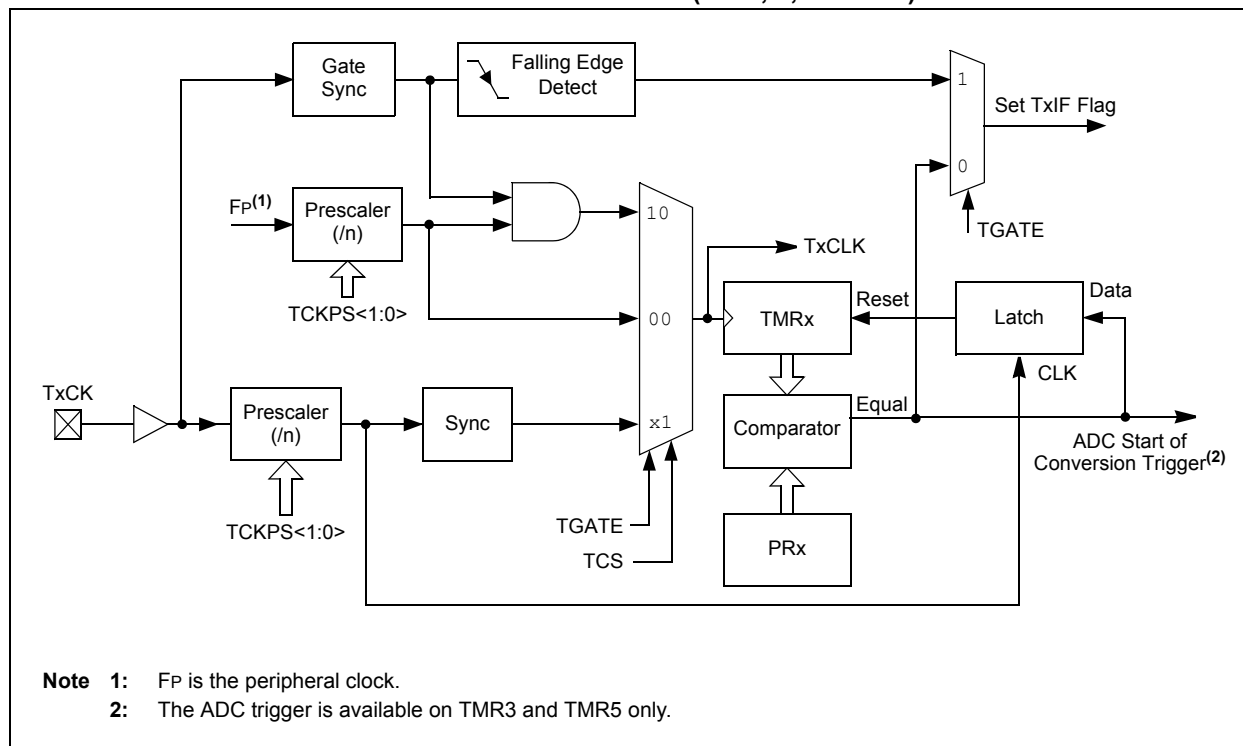


FIGURE 13-2: TYPE C TIMERx BLOCK DIAGRAM (x = 3, 5, 7 AND 9)



**REGISTER 16-6: STCON2: PWM SECONDARY CLOCK DIVIDER SELECT REGISTER 2**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	PCLKDIV<2:0> <sup>(1)</sup>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3 **Unimplemented:** Read as '0'bit 2-0 **PCLKDIV<2:0>:** PWM Input Clock Prescaler (Divider) Select bits<sup>(1)</sup>

111 = Reserved

110 = Divide-by-64

101 = Divide-by-32

100 = Divide-by-16

011 = Divide-by-8

010 = Divide-by-4

001 = Divide-by-2

000 = Divide-by-1, maximum PWM timing resolution (power-on default)

**Note 1:** These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

**REGISTER 16-7: STPER: SECONDARY MASTER TIME BASE PERIOD REGISTER<sup>(1)</sup>**

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
STPER<15:8>							
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
STPER<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **STPER<15:0>:** Secondary Master Time Base (PMTMR) Period Value bits

## 23.2 ADC Helpful Tips

1. The SMPLx control bits in the ADxCON2 registers:
  - a) Determine when the ADC interrupt flag is set and an interrupt is generated, if enabled.
  - b) When the CSCNA bit in the ADxCON2 register is set to '1', this determines when the ADC analog scan channel list, defined in the AD1CSSL/AD1CSSH registers, starts over from the beginning.
  - c) When the DMA peripheral is not used (ADDMAEN = 0), this determines when the ADC Result Buffer Pointer to ADC1BUF0-ADC1BUFF gets reset back to the beginning at ADC1BUF0.
  - d) When the DMA peripheral is used (ADDMAEN = 1), this determines when the DMA Address Pointer is incremented after a sample/conversion operation. ADC1BUF0 is the only ADC buffer used in this mode. The ADC Result Buffer Pointer to ADC1BUF0-ADC1BUFF gets reset back to the beginning at ADC1BUF0. The DMA address is incremented after completion of every 32nd sample/conversion operation. Conversion results are stored in the ADC1BUF0 register for transfer to RAM using DMA.
2. When the DMA module is disabled (ADDMAEN = 0), the ADC has 16 result buffers. ADC conversion results are stored sequentially in ADC1BUF0-ADC1BUFF, regardless of which analog inputs are being used subject to the SMPLx bits and the condition described in 1c) above. There is no relationship between the ANx input being measured and which ADC buffer (ADC1BUF0-ADC1BUFF) that the conversion results will be placed in.
3. When the DMA module is disabled (ADDMAEN = 1), the ADC module has only 1 ADC result buffer (i.e., ADC1BUF0) per ADC peripheral and the ADC conversion result must be read, either by the CPU or DMA controller, before the next ADC conversion is complete to avoid overwriting the previous value.
4. The DONE bit (ADxCON1<0>) is only cleared at the start of each conversion and is set at the completion of the conversion, but remains set indefinitely, even through the next sample phase until the next conversion begins. If application code is monitoring the DONE bit in any kind of software loop, the user must consider this behavior because the CPU code execution is faster than the ADC. As a result, in Manual Sample mode, particularly where the user's code is setting the SAMP bit (ADxCON1<1>), the DONE bit should also be cleared by the user application just before setting the SAMP bit.

## 23.3 ADC Resources

Many useful resources related to Analog-to-Digital conversion are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310>

### 23.3.1 KEY RESOURCES

- **Section 16. “Analog-to-Digital Converter (ADC)”** (DS70621) in the *“dsPIC33E/PIC24E Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *“dsPIC33E/PIC24E Family Reference Manual”* Sections
- Development Tools



**REGISTER 23-2: AD1CON2: ADC1 CONTROL REGISTER 2 (CONTINUED)**

- bit 1      **BUFM:** Buffer Fill Mode Select bit
- 1 = Starts filling the first half of the buffer on the first interrupt and the second half of the buffer on the next interrupt
  - 0 = Always starts filling the buffer from the Start address.
- bit 0      **ALTS:** Alternate Input Sample Mode Select bit
- 1 = Uses channel input selects for Sample A on the first sample and Sample B on the next sample
  - 0 = Always uses channel input selects for Sample A

**REGISTER 24-4: DCISTAT: DCI STATUS REGISTER**

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
r	r	r	r	SLOT<3:0>			
bit 15				bit 8			

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
r	r	r	r	ROV	RFUL	TUNF	TMPTY
bit 7				bit 0			

<b>Legend:</b>	r = Reserved bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	'0' = Bit is cleared
-n = Value at POR	'1' = Bit is set	x = Bit is unknown

bit 15-12 **Reserved:** Read as '0'

bit 11-8 **SLOT<3:0>:** DCI Slot Status bits

1111 = Slot 15 is currently active

•  
•  
•

0010 = Slot 2 is currently active

0001 = Slot 1 is currently active

0000 = Slot 0 is currently active

bit 7-4 **Reserved:** Read as '0'

bit 3 **ROV:** Receive Overflow Status bit

1 = A receive overflow has occurred for at least one Receive register

0 = A receive overflow has not occurred

bit 2 **RFUL:** Receive Buffer Full Status bit

1 = New data is available in the Receive registers

0 = The Receive registers have old data

bit 1 **TUNF:** Transmit Buffer Underflow Status bit

1 = A transmit underflow has occurred for at least one Transmit register

0 = A transmit underflow has not occurred

bit 0 **TMPTY:** Transmit Buffer Empty Status bit

1 = The Transmit registers are empty

0 = The Transmit registers are not empty

**NOTES:**

FIGURE 25-2: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM

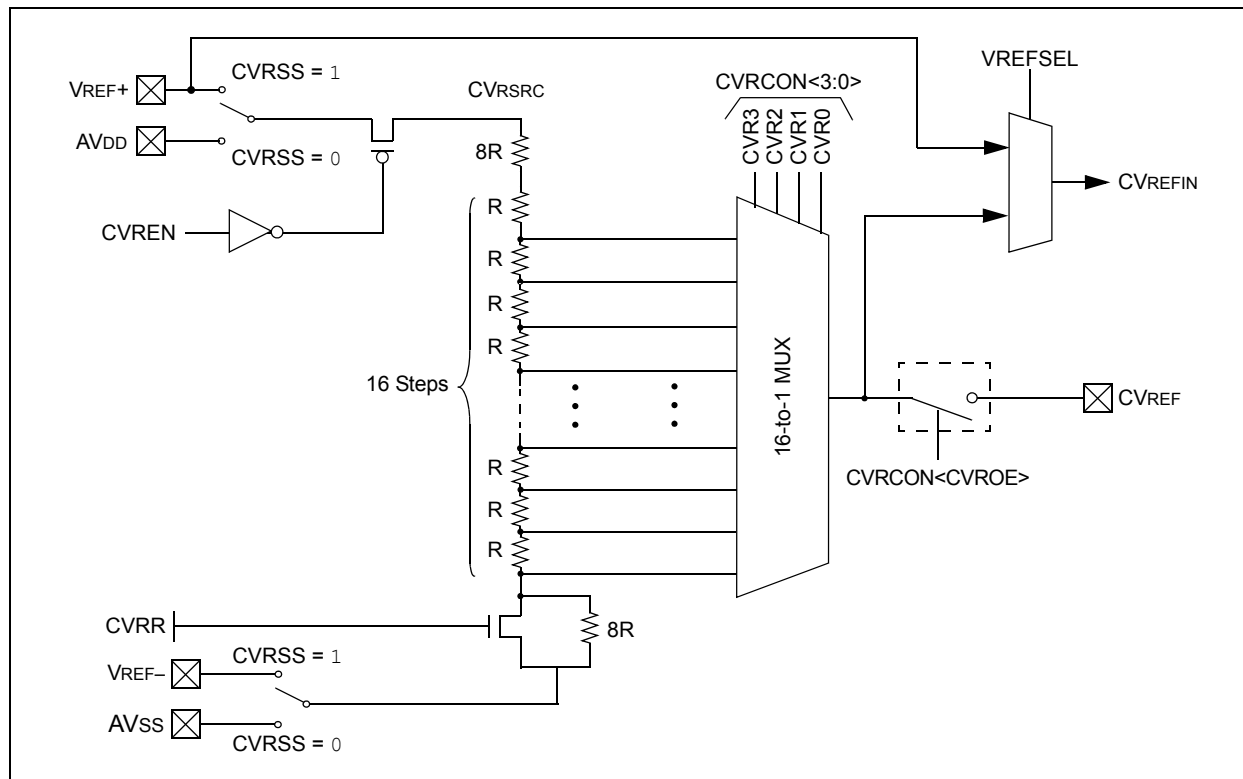
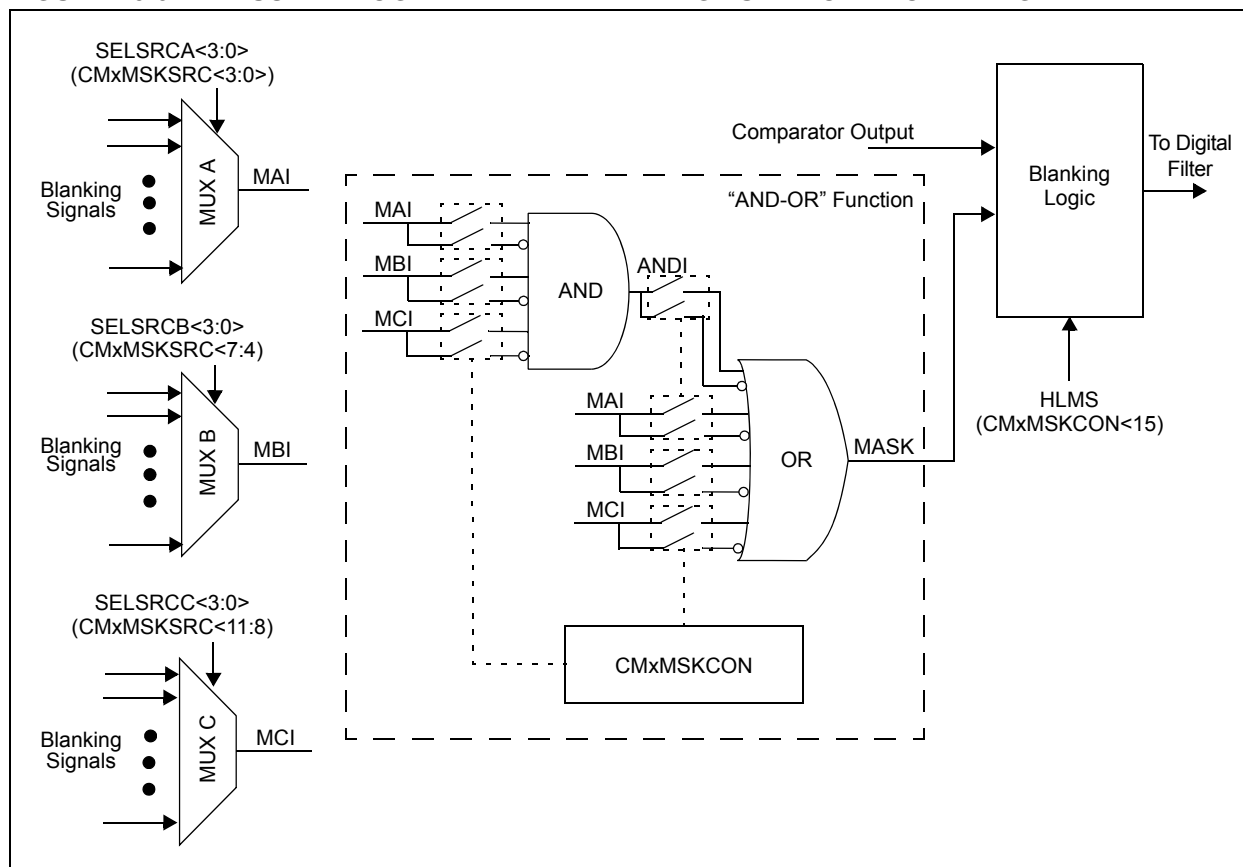


FIGURE 25-3: USER-PROGRAMMABLE BLANKING FUNCTION BLOCK DIAGRAM



## Revision D (August 2011)

This revision includes minor typographical and formatting changes throughout the data sheet text.

The Data Converter Interface (DCI) module is available on all dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices. References throughout the document have been updated accordingly.

The following pin name changes were implemented throughout the document:

- C1INA renamed to C1IN1+
- C1INB renamed to C1IN2-
- C1INC renamed to C1IN1-
- C1IND renamed to C1IN3-
- C2INA renamed to C2IN1+
- C2INB renamed to C2IN2-
- C2INC renamed to C2IN1-
- C2IND renamed to C2IN3-
- C3INA renamed to C3IN1+
- C3INB renamed to C3IN2-
- C3INC renamed to C3IN1-
- C3IND renamed to C3IN3-

The other major changes are referenced by their respective section in Table A-3.

**TABLE A-3: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>Section 1.0 “Device Overview”</b>	Added <b>Section 1.1 “Referenced Sources”</b> .
<b>Section 2.0 “Guidelines for Getting Started with 16-bit Digital Signal Controllers and Microcontrollers”</b>	Updated the Note in <b>Section 2.1 “Basic Connection Requirements”</b> .
<b>Section 3.0 “CPU”</b>	Updated <b>Section 3.1 “Registers”</b> .
<b>Section 4.0 “Memory Organization”</b>	Updated <b>FIGURE 4-3: “Data Memory Map for dsPIC33EP512MU810/814 Devices with 52 KB RAM”</b> and <b>FIGURE 4-5: “Data Memory Map for dsPIC33EP256MU806/810/814 Devices with 28 KB RAM”</b> .  Updated the IFS3, IEC3, IPC14, and IPC15 SFRs in the Interrupt Controller Register Map (see Table 4-6).  Updated the SMPI bits for the AD1CON2 and AD2CON2 SFRs in the ADC1 and ADC2 Register Map (see Table 4-23).  Updated the All Resets values for the CLKDIV and PLLFBD SFRs and removed the SBOREN bit in the System Control Register Map (see Table 4-43).
<b>Section 6.0 “Resets”</b>	Removed the SBOREN bit and Notes 3 and 4 from the Reset Control Register (see Register 6-1).
<b>Section 8.0 “Direct Memory Access (DMA)”</b>	Removed Note 2 from the DMA Channel x IRQ Select Register (see Register 8-2).
<b>Section 9.0 “Oscillator Configuration”</b>	Updated the PLL Block Diagram (see Figure 9-2).  Updated the value at PORT and the default designations for the DOZE<2:0>, FRCDIV<2:0>, and PLLPOST<1:0> bits in the Clock Divisor Register and the PLLDIV<8:0> bits in the PLLFBD register (see Register 9-2 and Register 9-3).
<b>Section 23.0 “10-bit/12-bit Analog-to-Digital Converter (ADC)”</b>	Added Note 4 and updated the ADC Buffer names in the ADCx Module Block Diagram (see Figure 23-1).  Added Note 3 to the ADCx Control Register 1 (see Register 23-1).  Added the new ADC2 Control Register 2 (see Register 23-3).  Updated the SMPI<4:0> bit value definitions in the ADC1 Control Register 2 (see Register 23-2).