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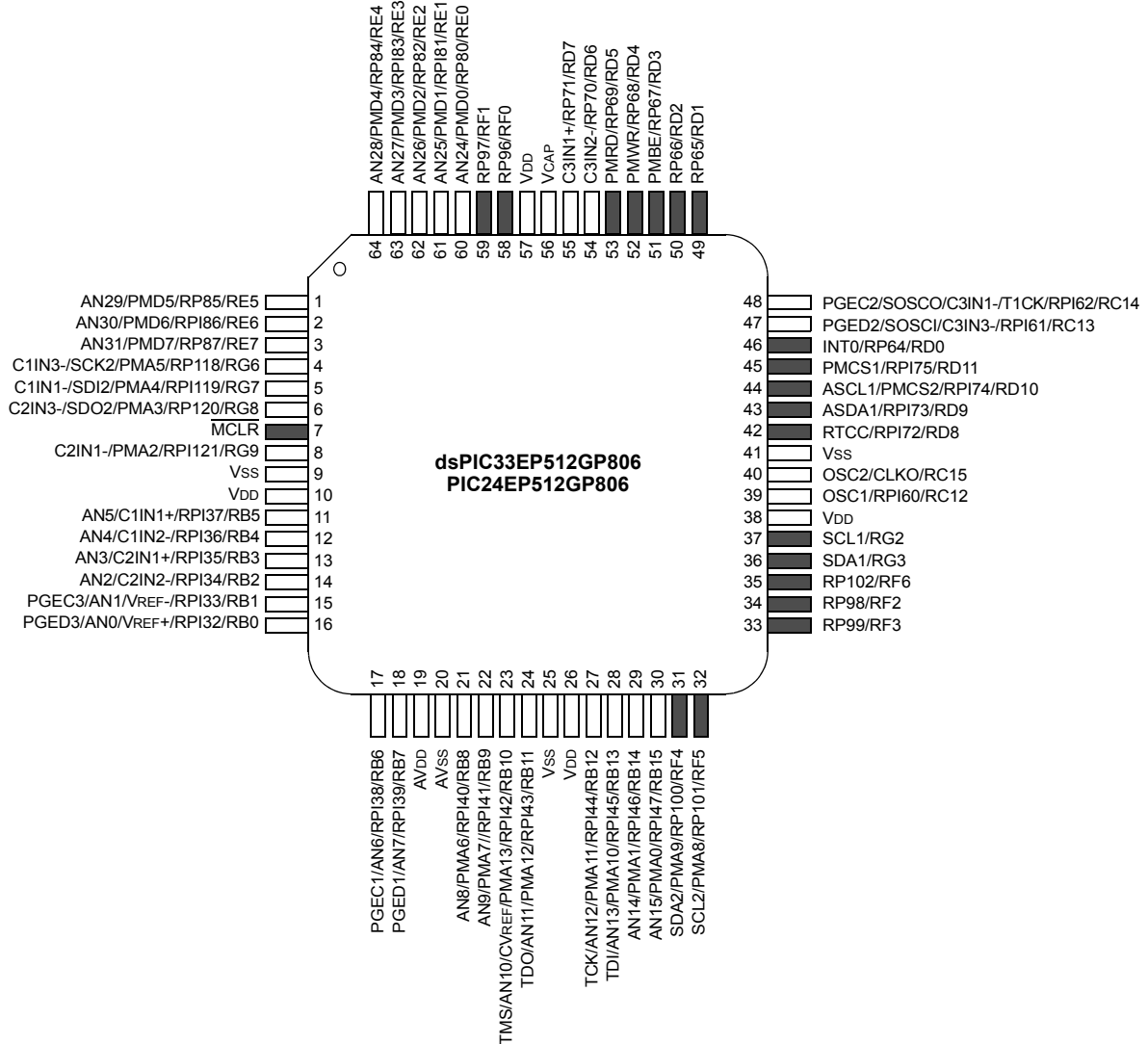
Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, QEI, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	122
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	12K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 32x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256mu814-e-pl

Pin Diagrams (Continued)

64-Pin TQFP

■ = Pins are up to 5V tolerant



- Note 1:** The RPN/RPIN pins can be used by any remappable peripheral with some limitation. See **Section 11.4 “Peripheral Pin Select”** for available peripherals and for information on limitations.
- 2:** Every I/O port pin (RAX-RGX) can be used as change notification (CNAX-CNGX). See **Section 11.0 “I/O Ports”** for more information.
- 3:** The availability of I²C™ interfaces varies by device. Selection (SDAx/SCLx or ASDAx/ASCLx) is made using the device Configuration bits, ALTI2C1 and ALTI2C2 (FPOR<5:4>). See **Section 29.0 “Special Features”** for more information.

FIGURE 2-7: INTERLEAVED PFC

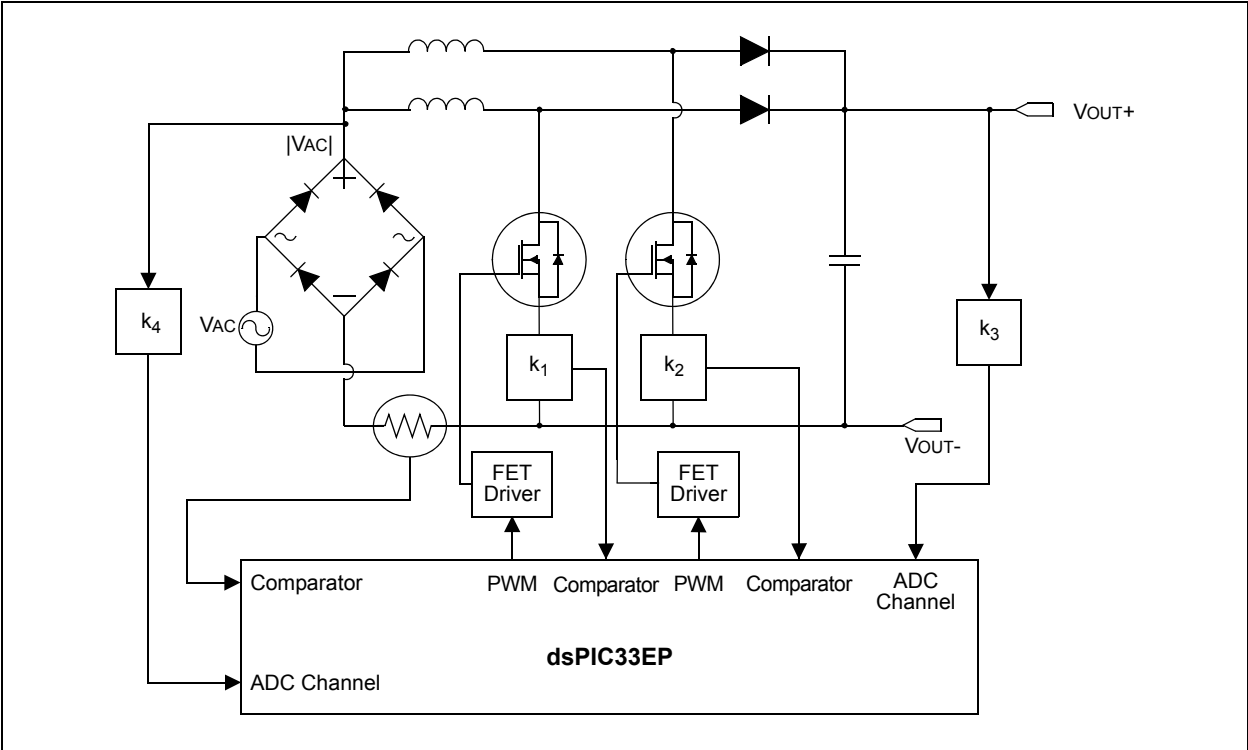
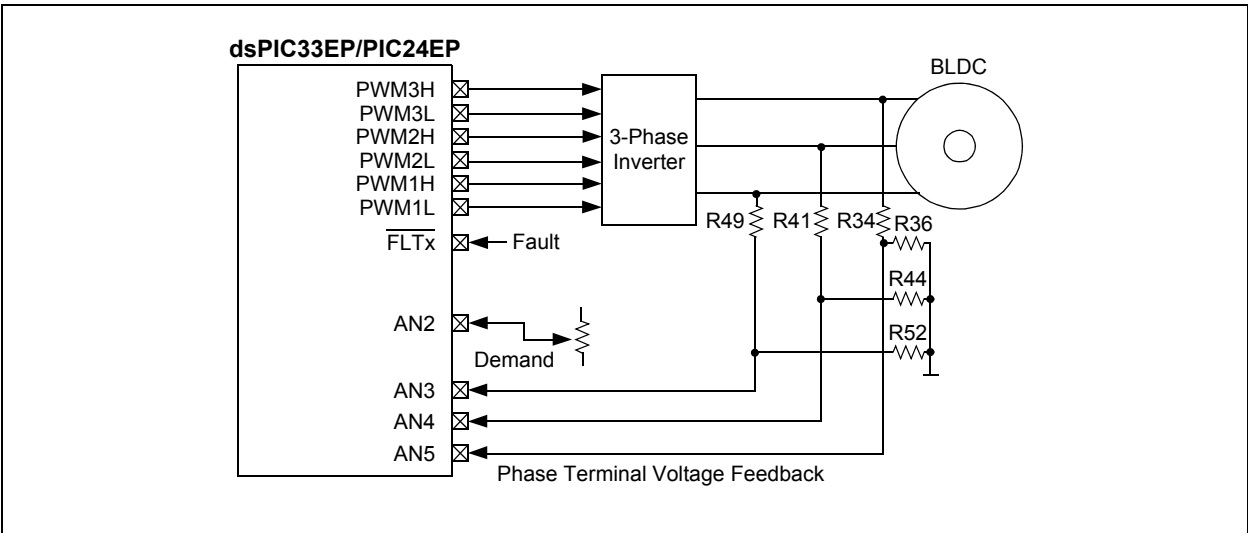


FIGURE 2-8: BEMF VOLTAGE MEASURED USING THE ADC MODULE



REGISTER 3-2: CORCON: CORE CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0
VAR	—	US<1:0> ⁽¹⁾		EDT ^(1,2)	DL<2:0> ⁽¹⁾		
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R-0	R/W-0	R/W-0
SATA ⁽¹⁾	SATB ⁽¹⁾	SATDW ⁽¹⁾	ACCSAT ⁽¹⁾	IPL3 ⁽³⁾	SFA	RND ⁽¹⁾	IF ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **VAR:** Variable Exception Processing Latency Control bit
 1 = Variable exception processing is enabled
 0 = Fixed exception processing is enabled
- bit 14 **Unimplemented:** Read as '0'
- bit 13-12 **US<1:0>:** DSP Multiply Unsigned/Signed Control bits⁽¹⁾
 11 = Reserved
 10 = DSP engine multiplies are mixed-sign
 01 = DSP engine multiplies are unsigned
 00 = DSP engine multiplies are signed
- bit 11 **EDT:** Early DO Loop Termination Control bit^(1,2)
 1 = Terminates executing DO loop at end of current loop iteration
 0 = No effect
- bit 10-8 **DL<2:0>:** DO Loop Nesting Level Status bits⁽¹⁾
 111 = 7 DO loops are active
 •
 •
 •
 001 = 1 DO loop is active
 000 = 0 DO loops are active
- bit 7 **SATA:** ACCA Saturation Enable bit⁽¹⁾
 1 = Accumulator A saturation is enabled
 0 = Accumulator A saturation is disabled
- bit 6 **SATB:** ACCB Saturation Enable bit⁽¹⁾
 1 = Accumulator B saturation is enabled
 0 = Accumulator B saturation is disabled
- bit 5 **SATDW:** Data Space Write from DSP Engine Saturation Enable bit⁽¹⁾
 1 = Data space write saturation is enabled
 0 = Data space write saturation is disabled
- bit 4 **ACCSAT:** Accumulator Saturation Mode Select bit⁽¹⁾
 1 = 9.31 saturation (super saturation)
 0 = 1.31 saturation (normal saturation)
- bit 3 **IPL3:** CPU Interrupt Priority Level Status bit 3⁽³⁾
 1 = CPU Interrupt Priority Level is greater than 7
 0 = CPU Interrupt Priority Level is 7 or less

Note 1: This bit is available on dsPIC33EPXXX(GP/MC/MU)806/810/814 devices only.

2: This bit is always read as '0'.

3: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

4.6 Modulo Addressing (dsPIC33EPXXXMU806/810/814 Devices Only)

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either data or Program Space (since the Data Pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into Program Space) and Y data spaces. Modulo Addressing can operate on any W Register Pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing since these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction as there are certain restrictions on the buffer start address (for incrementing buffers), or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

4.6.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT and YMODEND (see Table 4-1).

Note: Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

4.6.2 W ADDRESS REGISTER SELECTION

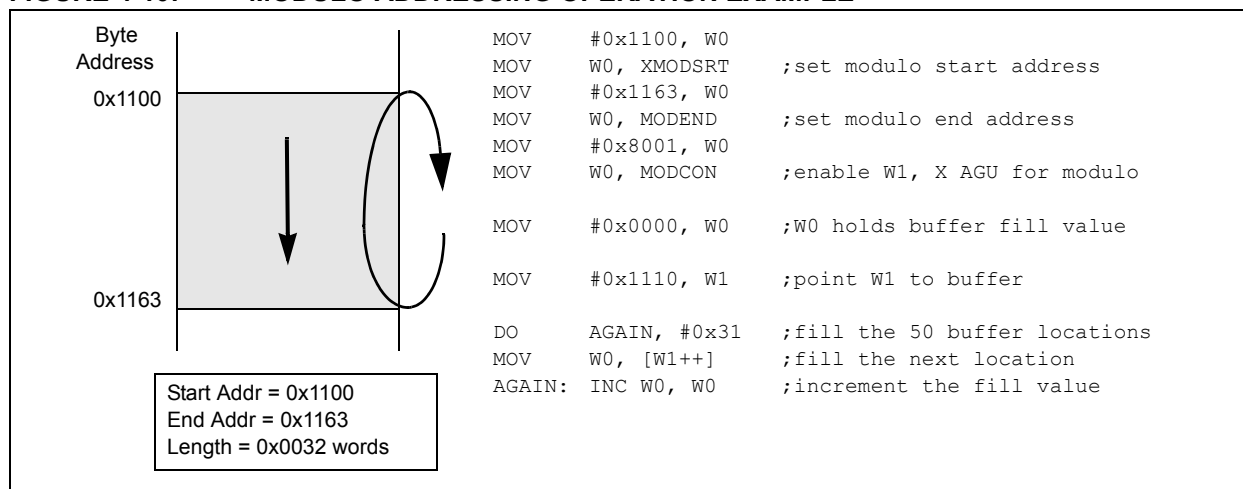
The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 1111, X RAGU and X WAGU Modulo Addressing is disabled.
- If YWM = 1111, Y AGU Modulo Addressing is disabled.

The X Address Space Pointer W register (XWM), to which Modulo Addressing is to be applied, is stored in MODCON<3:0> (see Table 4-1). Modulo Addressing is enabled for X data space when XWM is set to any value other than '1111' and the XMODEN bit is set at MODCON<15>.

The Y Address Space Pointer W register (YWM) to which Modulo Addressing is to be applied is stored in MODCON<7:4>. Modulo Addressing is enabled for Y data space when YWM is set to any value other than '1111' and the YMODEN bit is set at MODCON<14>.

FIGURE 4-10: MODULO ADDRESSING OPERATION EXAMPLE



REGISTER 8-12: DMARQC: DMA REQUEST COLLISION STATUS REGISTER (CONTINUED)

- bit 2 **RQCOL2:** Channel 2 Transfer Request Collision Flag bit
1 = User FORCE and interrupt-based request collision detected
0 = No request collision detected
- bit 1 **RQCOL1:** Channel 1 Transfer Request Collision Flag bit
1 = User FORCE and interrupt-based request collision detected
0 = No request collision detected
- bit 0 **RQCOL0:** Channel 0 Transfer Request Collision Flag bit
1 = User FORCE and interrupt-based request collision detected
0 = No request collision detected

bit 1 **I2C2MD:** I2C2 Module Disable bit
 1 = I2C2 module is disabled
 0 = I2C2 module is enabled

bit 0 **AD2MD:** ADC2 Module Disable bit
 1 = ADC2 module is disabled
 0 = ADC2 module is enabled

Note 1: This bit is available in dsPIC33EPXXX(MC/MU)806/810/814 devices only.

TABLE 11-3: OUTPUT SELECTION FOR REMAPPABLE PINS (RPn) (CONTINUED)

Function	RPnR<5:0>	Output Name
U4TX	011101	RPn tied to UART4 Transmit
U4RTS	011110	RPn tied to UART4 Ready-to-Send
SDO3	011111	RPn tied to SPI3 Data Output
SCK3	100000	RPn tied to SPI3 Clock Output
SS3	100001	RPn tied to SPI3 Slave Select
SDO4	100010	RPn tied to SPI4 Data Output
SCK4	100011	RPn tied to SPI4 Clock Output
SS4	100100	RPn tied to SPI4 Slave Select
OC9	100101	RPn tied to Output Compare 9 Output
OC10	100110	RPn tied to Output Compare 10 Output
OC11	100111	RPn tied to Output Compare 11 Output
OC12	101000	RPn tied to Output Compare 12 Output
OC13	101001	RPn tied to Output Compare 13 Output
OC14	101010	RPn tied to Output Compare 14 Output
OC15	101011	RPn tied to Output Compare 15 Output
OC16	101100	RPn tied to Output Compare 16 Output
SYNCO1 ⁽¹⁾	101101	RPn tied to PWM Primary Time Base Sync Output
SYNCO2 ⁽¹⁾	101110	RPn tied to PWM Secondary Time Base Sync Output
QE1CCMP ⁽¹⁾	101111	RPn tied to QE1 1 Counter Comparator Output
QE2CCMP ⁽¹⁾	110000	RPn tied to QE1 2 Counter Comparator Output
REFCLK	110001	RPn tied to Reference Clock Output

Note 1: This function is available in dsPIC33EPXXX(MC/MU)806/810/814 devices only.

REGISTER 11-12: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	OCFBR<6:0>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	OCFAR<6:0>						
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'bit 14-8 **OCFBR<6:0>:** Assign Output Compare Fault B (OCFB) to the Corresponding RPn/RPIn Pin bits (see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'bit 6-0 **OCFAR<6:0>:** Assign Output Compare Fault A (OCFA) to the Corresponding RPn/RPIn Pin bits (see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

REGISTER 11-36: RPINR36: PERIPHERAL PIN SELECT INPUT REGISTER 36

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	IC16R<6:0>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	IC15R<6:0>						
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-8 **IC16R<6:0>:** Assign Input Capture 16 (IC16) to the Corresponding RPn/RPIn Pin bits
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **IC15R<6:0>:** Assign Input Capture 15 (IC15) to the Corresponding RPn/RPIn Pin bits
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

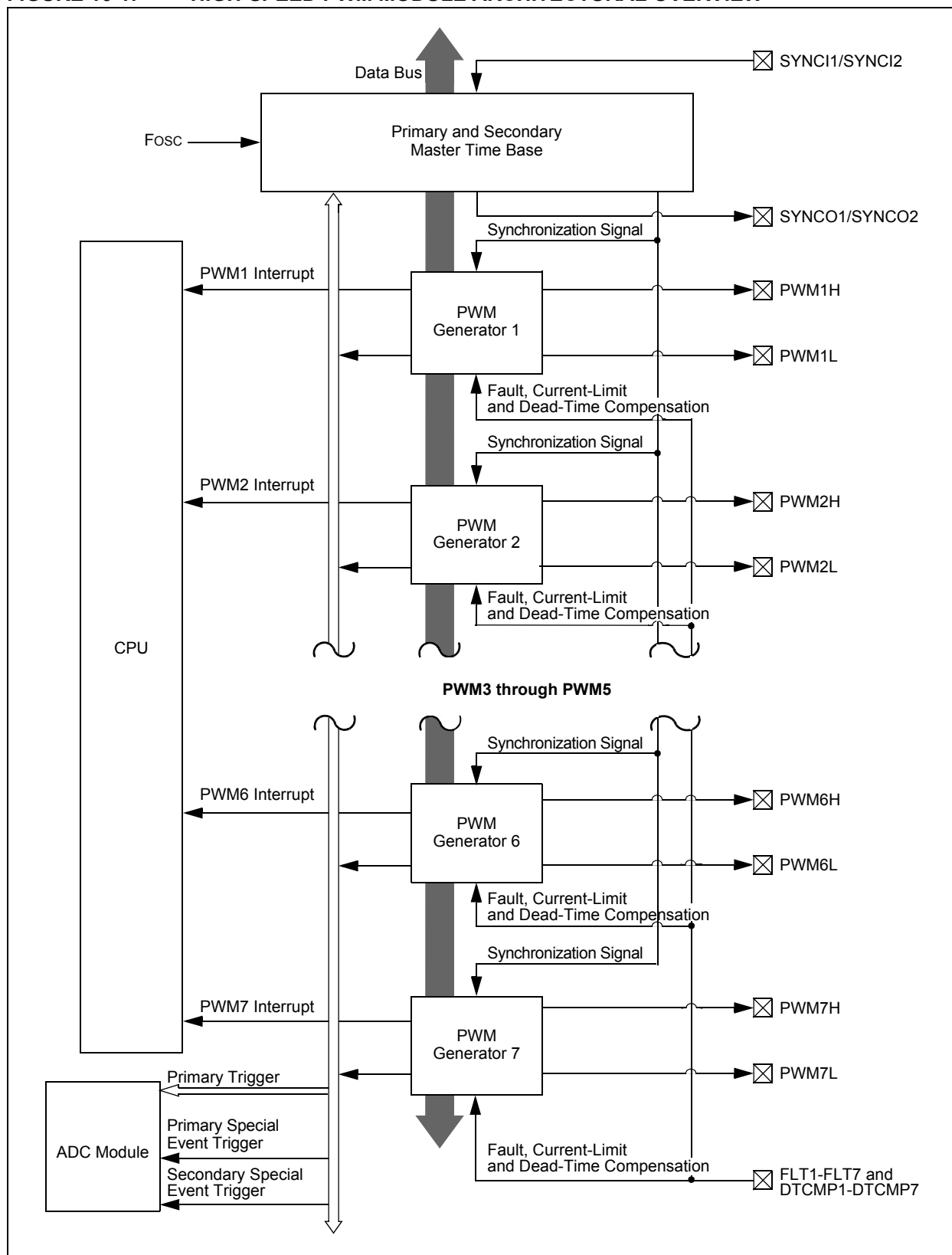
.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

FIGURE 16-1: HIGH-SPEED PWM MODULE ARCHITECTURAL OVERVIEW

REGISTER 16-23: LEBDLYx: LEADING-EDGE BLANKING DELAY REGISTER x

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	LEB<11:8>			
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
LEB<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'

bit 11-0 **LEB<11:0>:** Leading-Edge Blanking Delay for Current-Limit and Fault Inputs bits

NOTES:

REGISTER 20-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 4	URXINV: Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	BRGH: High Baud Rate Enable bit 1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode) 0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)
bit 2-1	PDSEL<1:0>: Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	STSEL: Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** Refer to **Section 17. “UART”** (DS70582) in the “*dsPIC33E/PIC24E Family Reference Manual*” for information on enabling the UARTx module for receive or transmit operation.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).

21.2 Modes of Operation

The ECANx module can operate in one of several operation modes selected by the user. These modes include:

- Initialization mode
- Disable mode
- Normal Operation mode
- Listen Only mode
- Listen All Messages mode
- Loopback mode

Modes are requested by setting the REQOP<2:0> bits (CxCTRL1<10:8>). Entry into a mode is Acknowledged by monitoring the OPMODE<2:0> bits (CxCTRL1<7:5>). The module does not change the mode and the OPMODE bits until a change in mode is acceptable, generally during bus Idle time, which is defined as at least 11 consecutive recessive bits.

21.3 ECAN Resources

Many useful resources related to ECAN are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser:
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310>

21.3.1 KEY RESOURCES

- **Section 21. “Enhanced Controller Area Network (ECAN™)”** (DS70353) in the *“dsPIC33E/PIC24E Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *“dsPIC33E/PIC24E Family Reference Manual”* Sections
- Development Tools

REGISTER 21-6: CxINTF: ECANx INTERRUPT FLAG REGISTER

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	TXBO	TXBP	RXBP	TXWAR	RXWAR	EWARN
bit 15							
							bit 8

R/C-0	R/C-0	R/C-0	U-0	R/C-0	R/C-0	R/C-0	R/C-0
IVRIF	WAKIF	ERRIF	—	FIFOIF	RBOVIF	RBIF	TBIF
bit 7							
							bit 0

Legend:	C = Writable bit, but only '0' can be written to clear the bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **TXBO:** Transmitter in Error State Bus Off bit
1 = Transmitter is in Bus Off state
0 = Transmitter is not in Bus Off state
- bit 12 **TXBP:** Transmitter in Error State Bus Passive bit
1 = Transmitter is in Bus Passive state
0 = Transmitter is not in Bus Passive state
- bit 11 **RXBP:** Receiver in Error State Bus Passive bit
1 = Receiver is in Bus Passive state
0 = Receiver is not in Bus Passive state
- bit 10 **TXWAR:** Transmitter in Error State Warning bit
1 = Transmitter is in Error Warning state
0 = Transmitter is not in Error Warning state
- bit 9 **RXWAR:** Receiver in Error State Warning bit
1 = Receiver is in Error Warning state
0 = Receiver is not in Error Warning state
- bit 8 **EWARN:** Transmitter or Receiver in Error State Warning bit
1 = Transmitter or Receiver is in Error State Warning state
0 = Transmitter or Receiver is not in Error State Warning state
- bit 7 **IVRIF:** Invalid Message Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 6 **WAKIF:** Bus Wake-up Activity Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 5 **ERRIF:** Error Interrupt Flag bit (multiple sources in CxINTF<13:8> register)
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **FIFOIF:** FIFO Almost Full Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 2 **RBOVIF:** RX Buffer Overflow Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 1 **RBIF:** RX Buffer Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred
- bit 0 **TBIF:** TX Buffer Interrupt Flag bit
1 = Interrupt Request has occurred
0 = Interrupt Request has not occurred

REGISTER 22-12: UxOTGIR: USB OTG INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	U-0	R/K-0, HS
IDIF	T1MSECIF	LSTATEIF	ACTVIF	SESVDF	SESENDIF	—	VBUSVDIF
bit 7				bit 0			

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **IDIF:** ID State Change Indicator bit

- 1 = Change in ID state is detected
- 0 = No ID state change

bit 6 **T1MSECIF:** 1 Millisecond Timer bit

- 1 = The 1 millisecond timer has expired
- 0 = The 1 millisecond timer has not expired

bit 5 **LSTATEIF:** Line State Stable Indicator bit

- 1 = USB line state (as defined by the SE0 and JSTATE bits) has been stable for 1 ms, but different from last time
- 0 = USB line state has not been stable for 1 ms

bit 4 **ACTVIF:** Bus Activity Indicator bit

- 1 = Activity on the D+/D- lines or VBUS is detected
- 0 = No activity on the D+/D- lines or VBUS is detected

bit 3 **SESVDF:** Session Valid Change Indicator bit

- 1 = VBUS has crossed VA_SESS_VLD (as defined in the USB OTG Specification)⁽¹⁾
- 0 = VBUS has not crossed VA_SESS_VLD

bit 2 **SESENDIF:** B-Device VBUS Change Indicator bit

- 1 = VBUS change on B-device is detected; VBUS has crossed VB_SESS_END (as defined in the USB OTG Specification)⁽¹⁾
- 0 = VBUS has not crossed VA_SESS_END

bit 1 **Unimplemented:** Read as '0'

bit 0 **VBUSVDIF:** A-Device VBUS Change Indicator bit

- 1 = VBUS change on A-device is detected; VBUS has crossed VA_VBUS_VLD (as defined in the USB OTG Specification)⁽¹⁾
- 0 = No VBUS change on A-device is detected

Note 1: VBUS threshold crossings may be either rising or falling.

25.2 Comparator Control Registers

REGISTER 25-1: CMSTAT: COMPARATOR STATUS REGISTER

R/W-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
CMSIDL	—	—	—	—	C3EVT	C2EVT	C1EVT
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
—	—	—	—	—	C3OUT	C2OUT	C1OUT
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

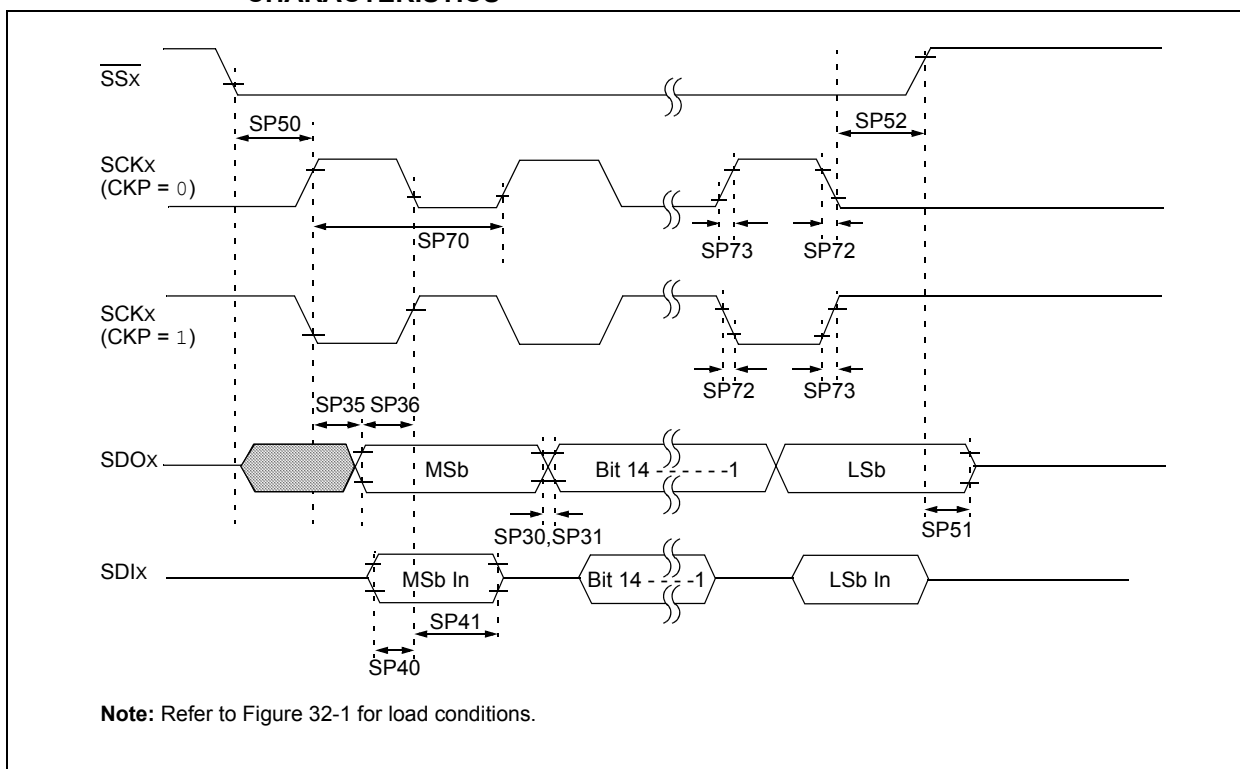
- bit 15 **CMSIDL:** Comparator Stop in Idle Mode bit
 1 = Discontinues operation of all comparators when device enters Idle mode
 0 = Continues operation of all comparators in Idle mode
- bit 14-11 **Unimplemented:** Read as '0'
- bit 10 **C3EVT:** Comparator 3 Event Status bit
 1 = Comparator event occurred
 0 = Comparator event did not occur
- bit 9 **C2EVT:** Comparator 2 Event Status bit
 1 = Comparator event occurred
 0 = Comparator event did not occur
- bit 8 **C1EVT:** Comparator 1 Event Status bit
 1 = Comparator event occurred
 0 = Comparator event did not occur
- bit 7-3 **Unimplemented:** Read as '0'
- bit 2 **C3OUT:** Comparator 3 Output Status bit
When CPOL = 0:
 1 = $V_{IN+} > V_{IN-}$
 0 = $V_{IN+} < V_{IN-}$
When CPOL = 1:
 1 = $V_{IN+} < V_{IN-}$
 0 = $V_{IN+} > V_{IN-}$
- bit 1 **C2OUT:** Comparator 2 Output Status bit
When CPOL = 0:
 1 = $V_{IN+} > V_{IN-}$
 0 = $V_{IN+} < V_{IN-}$
When CPOL = 1:
 1 = $V_{IN+} < V_{IN-}$
 0 = $V_{IN+} > V_{IN-}$
- bit 0 **C1OUT:** Comparator 1 Output Status bit
When CPOL = 0:
 1 = $V_{IN+} > V_{IN-}$
 0 = $V_{IN+} < V_{IN-}$
When CPOL = 1:
 1 = $V_{IN+} < V_{IN-}$
 0 = $V_{IN+} > V_{IN-}$

**REGISTER 25-3: CMxMSKSRCA: COMPARATOR x MASK SOURCE SELECT
CONTROL REGISTER (CONTINUED)**

bit 3-0 **SELSRCA<3:0>**: Mask A Input Select bits

1111 = FLT4
1110 = FLT2
1101 = PWM7H
1100 = PWM7L
1011 = PWM6H
1010 = PWM6L
1001 = PWM5H
1000 = PWM5L
0111 = PWM4H
0110 = PWM4L
0101 = PWM3H
0100 = PWM3L
0011 = PWM2H
0010 = PWM2L
0001 = PWM1H
0000 = PWM1L

FIGURE 32-29: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING CHARACTERISTICS



Revision C (May 2011)

This revision includes minor typographical and formatting changes throughout the data sheet text.

These global changes were implemented:

- All instances of VDDCORE have been removed.
- References to remappable pins have been updated to clarify output-only pins (RPn) versus input/output pins (RPIIn).
- The minimum VDD value was changed from 2.7V to 3.0V to adhere to the current BOR specification.

The major changes are referenced by their respective section in Table A-2.

TABLE A-2: MAJOR SECTION UPDATES

Section Name	Update Description
High-Performance, 16-bit Digital Signal Controllers and Microcontrollers	Removed the shading for D+/RG2 and D-/RG3 pin designations in all pin diagrams, as these pins are not 5V tolerant. References to remappable pins have been updated to clarify input/output pins (RPn) and input-only pins (RPIIn).
Section 2.0 “Guidelines for Getting Started with 16-bit Digital Signal Controllers and Microcontrollers”	Add information on the VUSB pin in Section 2.1 “Basic Connection Requirements” . Updated the title of Section 2.3 to Section 2.3 “CPU Logic Filter Capacitor Connection (VCAP)” and modified the first paragraph.
Section 3.0 “CPU”	Added Note 2 to the Programmer’s Model Register Descriptions (see Table 3-1).
Section 4.0 “Memory Organization”	Added the CANCKS bit (CxCTRL1<11>) to the ECAN1 and ECAN 2 Register Maps (see Table 4-26 and Table 4-29). Added the SBOREN bit (RCON<13>) to the System Control Register Map (see Table 4-43). Added Note 1 to the PORTG Register maps (see Table 4-60 and Table 4-61). Updated the Page Description for DSRPAG = 0x1FF and DSRPAG = 0x200 in Table 4-66. Updated the second paragraph of Section 4.2.9 “EDS Arbitration and Bus Master Priority” . Updated the last note box in Section 4.2.10 “Software Stack” .
Section 5.0 “Flash Program Memory”	Updated the equation formatting in Section 5.3 “Programming Operations” . Added the Non-Volatile Memory Upper Address (NVMADRU) and Non-Volatile Memory Address (NVMADR) registers (see Register 5-2 and Register 5-3).
Section 6.0 “Resets”	Added Security Reset to the Reset System Block Diagram (see Figure 6-1). Added the SBOREN bit (RCON<13>) and Notes 3 and 4 to the Reset Control register (see Register 6-1).
Section 11.0 “I/O Ports”	References to remappable pins have been updated to clarify input/output pins (RPn) and input-only pins (RPIIn). Added the new column, Input/Output, to Input Pin Selection for Selectable Input Sources (see Table 11-2).
Section 17.0 “Quadrature Encoder Interface (QEI) Module (dsPIC33EPXXMU806/810/814 Devices Only)”	Updated the definition for the INTHLD<31:0> bits (see Register 17-19 and Register 17-20).