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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	53
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep512mc806-i-mr

TABLE 4-9: TIMER1 THROUGH TIMER9 REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TMR1	0100	Timer1 Register																xxxx
PR1	0102	Period Register 1																FFFF
T1CON	0104	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	TSYNC	TCS	—	—	0000
TMR2	0106	Timer2 Register																xxxx
TMR3HLD	0108	Timer3 Holding Register (for 32-bit timer operations only)																xxxx
TMR3	010A	Timer3 Register																xxxx
PR2	010C	Period Register 2																FFFF
PR3	010E	Period Register 3																FFFF
T2CON	0110	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T3CON	0112	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000
TMR4	0114	Timer4 Register																xxxx
TMR5HLD	0116	Timer5 Holding Register (for 32-bit operations only)																xxxx
TMR5	0118	Timer5 Register																xxxx
PR4	011A	Period Register 4																FFFF
PR5	011C	Period Register 5																FFFF
T4CON	011E	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T5CON	0120	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000
TMR6	0122	Timer6 Register																xxxx
TMR7HLD	0124	Timer7 Holding Register (for 32-bit operations only)																xxxx
TMR7	0126	Timer7 Register																xxxx
PR6	0128	Period Register 6																FFFF
PR7	012A	Period Register 7																FFFF
T6CON	012C	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T7CON	012E	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000
TMR8	0130	Timer8 Register																xxxx
TMR9HLD	0132	Timer9 Holding Register (for 32-bit operations only)																xxxx
TMR9	0134	Timer9 Register																xxxx
PR8	0136	Period Register 8																FFFF
PR9	0138	Period Register 9																FFFF
T8CON	013A	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T9CON	013C	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-33: ECAN2 REGISTER MAP WHEN WIN (C2CTRL<0>) = 1

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
—	0500-051E	See Table 4-31																—
C2BUFPNT1	0520	F3BP<3:0>				F2BP<3:0>				F1BP<3:0>				F0BP<3:0>				0000
C2BUFPNT2	0522	F7BP<3:0>				F6BP<3:0>				F5BP<3:0>				F4BP<3:0>				0000
C2BUFPNT3	0524	F11BP<3:0>				F10BP<3:0>				F9BP<3:0>				F8BP<3:0>				0000
C2BUFPNT4	0526	F15BP<3:0>				F14BP<3:0>				F13BP<3:0>				F12BP<3:0>				0000
C2RXM0SID	0530	SID<10:3>								SID<2:0>		—	MIDE	—	EID<17:16>			xxxx
C2RXM0EID	0532	EID<15:8>								EID<7:0>								xxxx
C2RXM1SID	0534	SID<10:3>								SID<2:0>		—	MIDE	—	EID<17:16>			xxxx
C2RXM1EID	0536	EID<15:8>								EID<7:0>								xxxx
C2RXM2SID	0538	SID<10:3>								SID<2:0>		—	MIDE	—	EID<17:16>			xxxx
C2RXM2EID	053A	EID<15:8>								EID<7:0>								xxxx
C2RXF0SID	0540	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF0EID	0542	EID<15:8>								EID<7:0>								xxxx
C2RXF1SID	0544	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF1EID	0546	EID<15:8>								EID<7:0>								xxxx
C2RXF2SID	0548	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF2EID	054A	EID<15:8>								EID<7:0>								xxxx
C2RXF3SID	054C	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF3EID	054E	EID<15:8>								EID<7:0>								xxxx
C2RXF4SID	0550	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF4EID	0552	EID<15:8>								EID<7:0>								xxxx
C2RXF5SID	0554	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF5EID	0556	EID<15:8>								EID<7:0>								xxxx
C2RXF6SID	0558	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF6EID	055A	EID<15:8>								EID<7:0>								xxxx
C2RXF7SID	055C	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF7EID	055E	EID<15:8>								EID<7:0>								xxxx
C2RXF8SID	0560	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF8EID	0562	EID<15:8>								EID<7:0>								xxxx
C2RXF9SID	0564	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF9EID	0566	EID<15:8>								EID<7:0>								xxxx
C2RXF10SID	0568	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx
C2RXF10EID	056A	EID<15:8>								EID<7:0>								xxxx
C2RXF11SID	056C	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>			xxxx

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

5.4 Flash Program Memory Resources

Many useful resources related to Flash program memory are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

<p>Note: In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310</p>

5.4.1 KEY RESOURCES

- **Section 5. “Flash Programming”** (DS70609) in the *“dsPIC33E/PIC24E Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *“dsPIC33E/PIC24E Family Reference Manual”* Sections
- Development Tools

5.5 Control Registers

Four SFRs are used to read and write the program Flash memory: NVMCON, NVMKEY, NVMADRU and NVMADR.

The NVMCON register (Register 5-1) controls which blocks are to be erased, which memory type is to be programmed and the start of the programming cycle.

NVMKEY (Register 5-4) is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register.

There are two NVM Address registers: NVMADRU and NVMADR. These two registers, when concatenated, form the 24-bit Effective Address (EA) of the selected row or word for programming operations, or the selected page for erase operations.

The NVMADRU register is used to hold the upper 8 bits of the EA, while the NVMADR register is used to hold the lower 16 bits of the EA.

REGISTER 8-14: DMAPPS: DMA PING-PONG STATUS REGISTER

U-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
—	PPST14	PPST13	PPST12	PPST11	PPST10	PPST9	PPST8
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
PPST7	PPST6	PPST5	PPST4	PPST3	PPST2	PPST1	PPST0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **Unimplemented:** Read as '0'
- bit 14 **PPST14:** Channel 14 Ping-Pong Mode Status Flag bit
 1 = DMASTB14 register selected
 0 = DMASTA14 register selected
- bit 13 **PPST13:** Channel 13 Ping-Pong Mode Status Flag bit
 1 = DMASTB13 register selected
 0 = DMASTA13 register selected
- bit 12 **PPST12:** Channel 12 Ping-Pong Mode Status Flag bit
 1 = DMASTB12 register selected
 0 = DMASTA12 register selected
- bit 11 **PPST11:** Channel 11 Ping-Pong Mode Status Flag bit
 1 = DMASTB11 register selected
 0 = DMASTA11 register selected
- bit 10 **PPST10:** Channel 10 Ping-Pong Mode Status Flag bit
 1 = DMASTB10 register selected
 0 = DMASTA10 register selected
- bit 9 **PPST9:** Channel 9 Ping-Pong Mode Status Flag bit
 1 = DMASTB9 register selected
 0 = DMASTA9 register selected
- bit 8 **PPST8:** Channel 8 Ping-Pong Mode Status Flag bit
 1 = DMASTB8 register selected
 0 = DMASTA8 register selected
- bit 7 **PPST7:** Channel 7 Ping-Pong Mode Status Flag bit
 1 = DMASTB7 register selected
 0 = DMASTA7 register selected
- bit 6 **PPST6:** Channel 6 Ping-Pong Mode Status Flag bit
 1 = DMASTB6 register selected
 0 = DMASTA6 register selected
- bit 5 **PPST5:** Channel 5 Ping-Pong Mode Status Flag bit
 1 = DMASTB5 register selected
 0 = DMASTA5 register selected
- bit 4 **PPST4:** Channel 4 Ping-Pong Mode Status Flag bit
 1 = DMASTB4 register selected
 0 = DMASTA4 register selected
- bit 3 **PPST3:** Channel 3 Ping-Pong Mode Status Flag bit
 1 = DMASTB3 register selected
 0 = DMASTA3 register selected

11.5 I/O Helpful Tips

1. In some cases, certain pins, as defined in Table 32-9 in **Section 32.0 “Electrical Characteristics”** under “Injection Current”, have internal protection diodes to VDD and VSS; the term “Injection Current” is also referred to as “Clamp Current”. On designated pins, with sufficient external current-limiting precautions by the user, I/O pin input voltages are allowed to be greater or less than the data sheet absolute maximum ratings with respect to the VSS and VDD supplies. Note that when the user application forward biases either of the high or low side internal input clamp diodes, that the resulting current being injected into the device that is clamped internally by the VDD and VSS power rails, may affect the ADC accuracy by four to six counts.
2. I/O pins that are shared with any analog input pin, (i.e., ANx, see Table 1-1 in **Section 1.0 “Device Overview”**), are always analog pins by default after any Reset. Consequently, configuring a pin as an analog input pin, automatically disables the digital input pin buffer and any attempt to read the digital input level by reading PORTx or LATx will always return a ‘0’, regardless of the digital logic level on the pin. To use a pin as a digital I/O pin on a shared analog pin (see Table 1-1 in **Section 1.0 “Device Overview”**), the user application needs to configure the Analog Pin Configuration registers in the I/O ports module (i.e., ANSELx) by setting the appropriate bit that corresponds to that I/O port pin to a ‘0’.

Note: Although it is not possible to use a digital input pin when its analog function is enabled, it is possible to use the digital I/O output function, TRISx = 0x0, while the analog function is also enabled. However, this is not recommended, particularly if the analog input is connected to an external analog voltage source, which would create signal contention between the analog signal and the output pin driver.

3. Most I/O pins have multiple functions. Referring to the device pin diagrams in the data sheet, the priorities of the functions allocated to any pins are indicated by reading the pin name from left to right. The left most function name takes precedence over any function to its right in the naming convention. For example: AN16/T2CK/T7CK/RC1; this indicates that AN16 is the highest priority in this example and will supersede all other functions to its right in the list. Those other functions to its right, even if enabled, would not work as long as any other function to its left was enabled. This rule applies to all of the functions listed for a given pin. Dedicated peripheral functions are always higher priority than remappable functions. I/O pins are always the lowest priority.

4. Each pin has an internal weak pull-up resistor and pull-down resistor that can be configured using the CNPUx and CNPDx registers, respectively. These resistors eliminate the need for external resistors in certain applications. The internal pull-up is up to $\sim(VDD-0.8)$, not VDD. This value is still above the minimum V_{IH} of CMOS and TTL devices.
5. When driving LEDs directly, the I/O pin can source or sink more current than what is specified in the V_{OH}/I_{OH} and V_{OL}/I_{OL} DC characteristic specification. The respective I_{OH} and I_{OL} current rating only applies to maintaining the corresponding output at or above the V_{OH} and at or below the V_{OL} levels. However, for LEDs, unlike digital inputs of an externally connected device, they are not governed by the same minimum V_{IH}/V_{IL} levels. An I/O pin output can safely sink or source any current less than that listed in the absolute maximum rating section of the data sheet. For example:

$$V_{OH} = 2.4V @ I_{OH} = -8 \text{ mA and } V_{DD} = 3.3V$$

The maximum output current sourced by any 8 mA I/O pin = 12 mA.

LED source current < 12 mA is technically permitted. Refer to the V_{OH}/I_{OH} graphs in **Section 32.0 “Electrical Characteristics”** for additional information.

6. The Peripheral Pin Select (PPS) pin mapping rules are as follows:
 - a) Only one “output” function can be active on a given pin at any time regardless if it is a dedicated or remappable function (one pin, one output).
 - b) It is possible to assign a “remappable output” function to multiple pins and externally short or tie them together for increased current drive.
 - c) If any “dedicated output” function is enabled on a pin, it will take precedence over any remappable “output” function.
 - d) If any “dedicated digital” (input or output) function is enabled on a pin, any number of “input” remappable functions can be mapped to the same pin.
 - e) If any “dedicated analog” function(s) are enabled on a given pin, “digital input(s)” of any kind will all be disabled, although a single “digital output”, at the user’s cautionary discretion, can be enabled and active as long as there is no signal contention with an external analog input signal. For example, it is possible for the ADC to convert the digital output logic level, or to toggle a digital output on a comparator or ADC input, provided there is no external analog input, such as for a built-in self test.
 - f) Any number of “input” remappable functions can be mapped to the same pin(s) at the same time, including any pin with a single output from either a dedicated or remappable “output”.

REGISTER 11-2: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	INT3R<6:0>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	INT2R<6:0>						
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'bit 14-8 **INT3R<6:0>:** Assign External Interrupt 3 (INT3) to the Corresponding RPn/RPIn Pin bits
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.
.
.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'bit 6-0 **INT2R<6:0>:** Assign External Interrupt 2 (INT2) to the Corresponding RPn/RPIn Pin bits
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.
.
.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

**REGISTER 11-16: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15
(dsPIC33EPXXXMU806/810/814 DEVICES ONLY)**

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	HOME1R<6:0> ⁽¹⁾						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	INDX1R<6:0> ⁽¹⁾						
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'bit 14-8 **HOME1R<6:0>:** Assign QE1 HOME1 (HOME1) to the Corresponding RPn/RPIn Pin bits⁽¹⁾
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'bit 6-0 **INDX1R<6:0>:** Assign QE1 INDEX1 (INDX1) to the Corresponding RPn/RPIn Pin bits⁽¹⁾
(see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127

.

.

.

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

Note 1: These bits are available on dsPIC33EPXXX(MC/MU)806/810/814 devices only.

REGISTER 21-7: CxINTE: ECANx INTERRUPT ENABLE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
IVRIE	WAKIE	ERRIE	—	FIFOIE	RBOVIE	RBIE	TBIE
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-8 **Unimplemented:** Read as '0'
- bit 7 **IVRIE:** Invalid Message Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 6 **WAKIE:** Bus Wake-up Activity Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 5 **ERRIE:** Error Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **FIFOIE:** FIFO Almost Full Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 2 **RBOVIE:** RX Buffer Overflow Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 1 **RBIE:** RX Buffer Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled
- bit 0 **TBIE:** TX Buffer Interrupt Enable bit
 1 = Interrupt request is enabled
 0 = Interrupt request is not enabled

REGISTER 21-26: CxTRmnCON: ECANx TX/RX BUFFER m CONTROL REGISTER
(m = 0, 2, 4, 6; n = 1, 3, 5, 7)

R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
TXENn	TXABTn	TXLARBn	TXERRn	TXREQn	RTRENn	TXnPRI<1:0>	
bit 15							bit 8

R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
TXENm	TXABTm ⁽¹⁾	TXLARBm ⁽¹⁾	TXERRm ⁽¹⁾	TXREQm	RTRENm	TXmPRI<1:0>	
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-8 See definition for bits 7-0, controls Buffer n
- bit 7 **TXENm**: TX/RX Buffer Selection bit
1 = Buffer TRBn is a transmit buffer
0 = Buffer TRBn is a receive buffer
- bit 6 **TXABTm**: Message Aborted bit⁽¹⁾
1 = Message was aborted
0 = Message completed transmission successfully
- bit 5 **TXLARBm**: Message Lost Arbitration bit⁽¹⁾
1 = Message lost arbitration while being sent
0 = Message did not lose arbitration while being sent
- bit 4 **TXERRm**: Error Detected During Transmission bit⁽¹⁾
1 = A bus error occurred while the message was being sent
0 = A bus error did not occur while the message was being sent
- bit 3 **TXREQm**: Message Send Request bit
1 = Requests that a message be sent; the bit automatically clears when the message is successfully sent
0 = Clearing the bit to '0' while set requests a message abort
- bit 2 **RTRENm**: Auto-Remote Transmit Enable bit
1 = When a remote transmit is received, TXREQm will be set
0 = When a remote transmit is received, TXREQm will be unaffected
- bit 1-0 **TXmPRI<1:0>**: Message Transmission Priority bits
11 = Highest message priority
10 = High intermediate message priority
01 = Low intermediate message priority
00 = Lowest message priority

Note 1: This bit is cleared when TXREQm is set.

Note: The buffers, SID, EID, DLC, Data Field and Receive Status registers are located in DMA RAM.

REGISTER 22-13: UxOTGIE: USB OTG INTERRUPT ENABLE REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
IDIE	T1MSECIE	LSTATEIE	ACTVIE	SESVDIE	SESENDIE	—	VBUSVDIE
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'bit 7 **IDIE:** ID Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 6 **T1MSECIE:** 1 Millisecond Timer Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 5 **LSTATEIE:** Line State Stable Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 4 **ACTVIE:** Bus Activity Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 3 **SESVDIE:** Session Valid Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 2 **SESENDIE:** B-Device Session End Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

bit 1 **Unimplemented:** Read as '0'bit 0 **VBUSVDIE:** A-Device Vbus Valid Interrupt Enable bit

1 = Interrupt is enabled

0 = Interrupt is disabled

REGISTER 22-21: UxEIE: USB ERROR INTERRUPT ENABLE REGISTER (HOST MODE)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BTSEE	BUSACCEE	DMAEE	BTOEE	DFN8EE	CRC16EE	EOFEE	PIDEE
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-8 **Unimplemented:** Read as '0'
- bit 7 **BTSEE:** Bit Stuff Error Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 6 **BUSACCEE:** Bus Access Error Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 5 **DMAEE:** DMA Error Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 4 **BTOEE:** Bus Turnaround Time-out Error Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 3 **DFN8EE:** Data Field Size Error Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 2 **CRC16EE:** CRC16 Failure Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 1 **EOFEE:** End-of-Frame Error interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled
- bit 0 **PIDEE:** PID Check Failure Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

NOTES:

REGISTER 28-2: PMMODE: PARALLEL MASTER PORT MODE REGISTER

R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUSY	IRQM<1:0>		INCM<1:0>		MODE16	MODE<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAITB<1:0> ^(1,2,3)		WAITM<3:0>				WAITE<1:0> ^(1,2,3)	
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at Reset

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **BUSY:** Busy bit (Master mode only)

1 = Port is busy

0 = Port is not busy

bit 14-13 **IRQM<1:0>:** Interrupt Request Mode bits

11 = Interrupt is generated when Read Buffer 3 is read or Write Buffer 3 is written (Buffered PSP mode), or on a read/write operation when PMA<1:0> = 11 (Addressable PSP mode only)

10 = Reserved

01 = Interrupt is generated at the end of the read/write cycle

00 = No Interrupt is generated

bit 12-11 **INCM<1:0>:** Increment Mode bits

11 = PSP read and write buffers auto-increment (Legacy PSP mode only)

10 = Decrements ADDR by 1 every read/write cycle

01 = Increments ADDR by 1 every read/write cycle

00 = No increment or decrement of address

bit 10 **MODE16:** Parallel Master Port Mode 8/16-Bit Mode bit

1 = 16-bit mode: data register is 16 bits, a read/write to the data register invokes two 8-bit transfers

0 = 8-bit mode: data register is 8 bits, a read/write to the data register invokes one 8-bit transfer

bit 9-8 **MODE<1:0>:** Parallel Master Port Mode Select bits

11 = Master Mode 1 (PMCSx, PMRD/PMWR, PMENB, PMBE, PMA<x:0> and PMD<7:0>)

10 = Master Mode 2 (PMCSx, PMRD, PMWR, PMBE, PMA<x:0> and PMD<7:0>)

01 = Enhanced PSP, controls signals (PMRD, PMWR, PMCSx, PMD<7:0> and PMA<1:0>)

00 = Legacy Parallel Slave Port, controls signals (PMRD, PMWR, PMCSx and PMD<7:0>)

bit 7-6 **WAITB<1:0>:** Data Setup to Read/Write/Address Phase Wait State Configuration bits^(1,2,3)

11 = Data wait of 4 TP (demultiplexed/multiplexed); address phase of 4 TP (multiplexed)

10 = Data wait of 3 TP (demultiplexed/multiplexed); address phase of 3 TP (multiplexed)

01 = Data wait of 2 TP (demultiplexed/multiplexed); address phase of 2 TP (multiplexed)

00 = Data wait of 1 TP (demultiplexed/multiplexed); address phase of 1 TP (multiplexed)

bit 5-2 **WAITM<3:0>:** Read to Byte Enable Strobe Wait State Configuration bits

1111 = Wait of additional 15 TP

•

•

•

0001 = Wait of additional 1 TP

0000 = No additional Wait cycles (operation forced into one TP)

Note 1: The applied Wait state depends on whether data and address are multiplexed or demultiplexed. See **Section 28.4.1.8. "Wait States"** in **Section 28. "Parallel Master Port (PMP)"** (DS70576) in the *"dsPIC33E/PIC24E Family Reference Manual"* for more information.

2: WAITB<1:0> and WAITE<1:0> bits are ignored whenever WAITM<3:0> = 0000.

3: TP = 1/FP.

29.4 Watchdog Timer (WDT)

For dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices, the WDT is driven by the LPRC Oscillator. When the WDT is enabled, the clock source is also enabled.

29.4.1 PRESCALER/POSTSCALER

The nominal WDT clock source from LPRC is 32 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the WDTPRE Configuration bit. With a 32 kHz input, the prescaler yields a nominal WDT Time-out (T_{WDT}) period of 1 ms in 5-bit mode or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPOST<3:0> Configuration bits (FWDT<3:0>), which allow the selection of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods ranging from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSC bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

Note: The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

29.4.2 SLEEP AND IDLE MODES

If the WDT is enabled, it continues to run during Sleep or Idle modes. When the WDT time-out occurs, the device wakes the device and code execution continues from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bits (RCON<3,2>) need to be cleared in software after the device wakes up.

29.4.3 ENABLING WDT

The WDT is enabled or disabled by the FWDTEN Configuration bit in the FWDT Configuration register. When the FWDTEN Configuration bit is set, the WDT is always enabled.

The WDT can be optionally controlled in software when the FWDTEN Configuration bit has been programmed to '0'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user application to enable the WDT for critical code segments and disable the WDT during non-critical segments for maximum power savings.

Note: If the WINDIS bit (FWDT<6>) is cleared, the CLRWDT instruction should be executed by the application software only during the last 1/4 of the WDT period. This CLRWDT instruction window can be determined by using a timer. If a CLRWDT instruction is executed before this window, a WDT Reset occurs.

The WDT flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

FIGURE 29-2: WDT BLOCK DIAGRAM

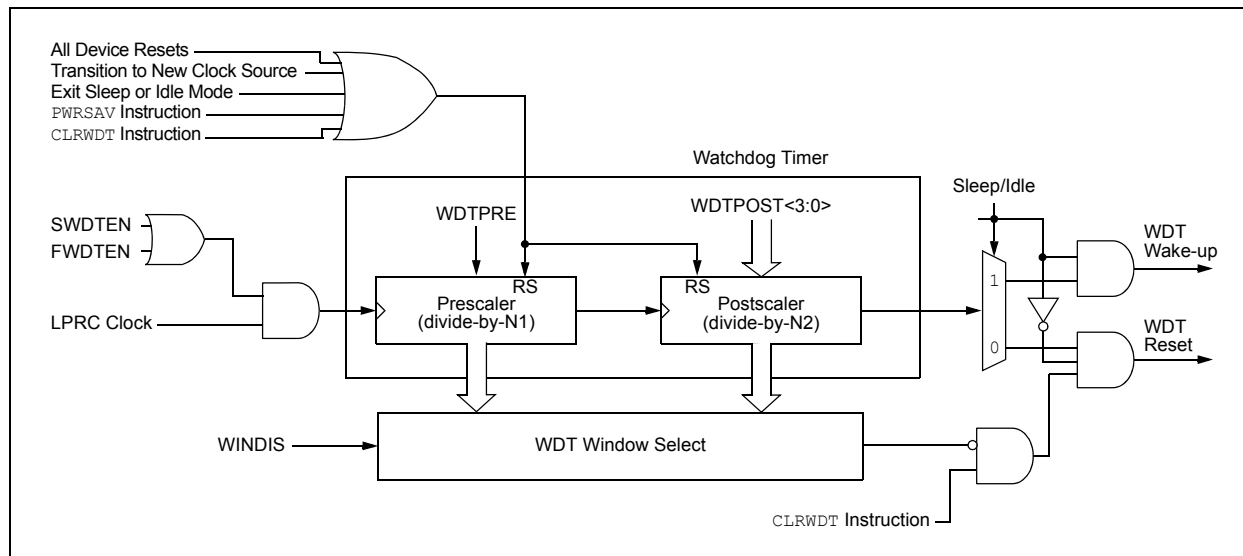


TABLE 30-1: SYMBOLS USED IN OPCODE DESCRIPTIONS (CONTINUED)

Field	Description
Wm*Wm	Multiplicand and Multiplier working register pair for Square instructions $\in \{W4 * W4, W5 * W5, W6 * W6, W7 * W7\}$
Wm*Wn	Multiplicand and Multiplier working register pair for DSP instructions $\in \{W4 * W5, W4 * W6, W4 * W7, W5 * W6, W5 * W7, W6 * W7\}$
Wn	One of 16 working registers $\in \{W0...W15\}$
Wnd	One of 16 destination working registers $\in \{W0...W15\}$
Wns	One of 16 source working registers $\in \{W0...W15\}$
WREG	W0 (working register used in file register instructions)
Ws	Source W register $\in \{Ws, [Ws], [Ws++] , [Ws--], [++Ws], [--Ws] \}$
Wso	Source W register $\in \{Wns, [Wns], [Wns++] , [Wns--], [++Wns], [--Wns], [Wns+Wb] \}$
Wx	X Data Space Prefetch Address register for DSP instructions $\in \{[W8] + = 6, [W8] + = 4, [W8] + = 2, [W8], [W8] - = 6, [W8] - = 4, [W8] - = 2, [W9] + = 6, [W9] + = 4, [W9] + = 2, [W9], [W9] - = 6, [W9] - = 4, [W9] - = 2, [W9 + W12], \text{none}\}$
Wxd	X Data Space Prefetch Destination register for DSP instructions $\in \{W4...W7\}$
Wy	Y Data Space Prefetch Address register for DSP instructions $\in \{[W10] + = 6, [W10] + = 4, [W10] + = 2, [W10], [W10] - = 6, [W10] - = 4, [W10] - = 2, [W11] + = 6, [W11] + = 4, [W11] + = 2, [W11], [W11] - = 6, [W11] - = 4, [W11] - = 2, [W11 + W12], \text{none}\}$
Wyd	Y Data Space Prefetch Destination register for DSP instructions $\in \{W4...W7\}$

31.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers and dsPIC® digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
 - MPLAB® IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB C Compiler for Various Device Families
 - HI-TECH C® for Various Device Families
 - MPASM™ Assembler
 - MPLINK™ Object Linker/
MPLIB™ Object Librarian
 - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers
 - MPLAB ICD 3
 - PICKit™ 3 Debug Express
- Device Programmers
 - PICKit™ 2 Programmer
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits

31.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows® operating system-based application that contains:

- A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - In-Circuit Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- Debug using:
 - Source files (C or assembly)
 - Mixed C and assembly
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

FIGURE 32-26: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING CHARACTERISTICS

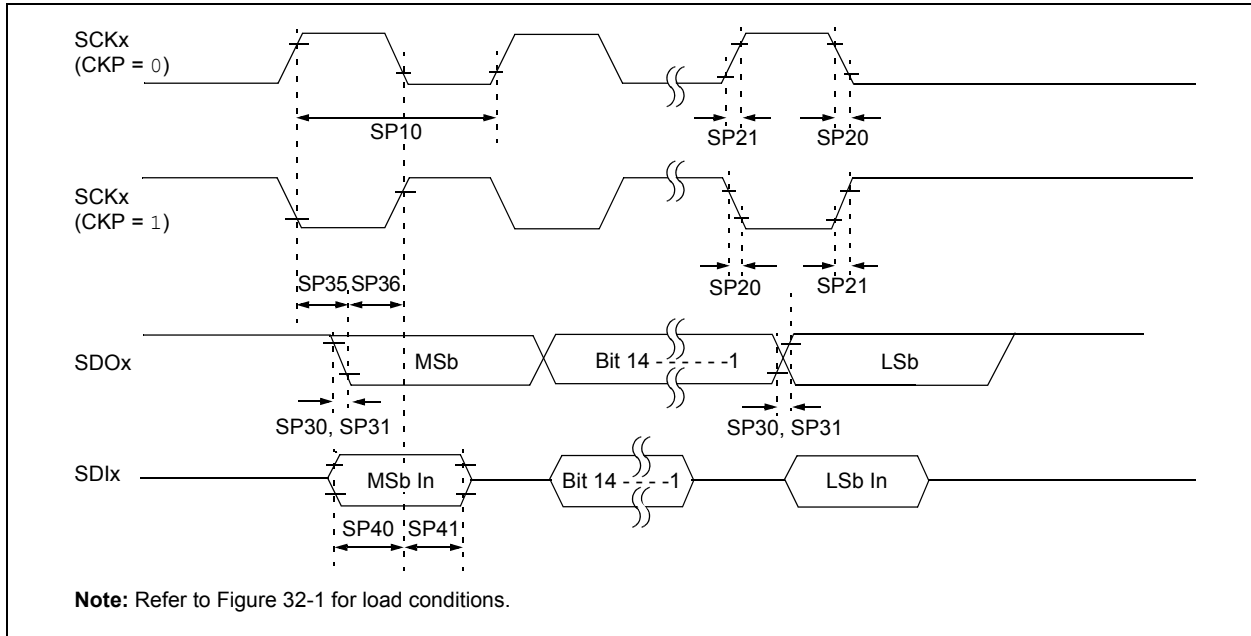


TABLE 32-44: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP10	TscP	Maximum SCKx Frequency	—	—	10	MHz	-40°C to +125°C and see Note 3
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP21	TscR	SCKx Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdoV2sch, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	
SP40	TdiV2sch, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

Note 2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

Note 3: The minimum clock period for SCKx is 100 ns. The clock generated in Master mode must not violate this specification.

Note 4: Assumes 50 pF load on all SPIx pins.

TABLE 32-48: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP70	TscP	Maximum SCKx Input Frequency	—	—	11	MHz	See Note 3
SP72	TscF	SCKx Input Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	\overline{SSx} ↓ to SCKx ↑ or SCKx ↓ Input	120	—	—	ns	
SP51	TssH2doZ	\overline{SSx} ↑ to SDOx Output, High-Impedance	10	—	50	ns	See Note 4
SP52	Tsch2ssH, TscL2ssH	\overline{SSx} ↑ after SCKx Edge	1.5 TCY + 40	—	—	ns	See Note 4

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 91 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

TABLE A-3: MAJOR SECTION UPDATES (CONTINUED)

Section Name	Update Description
Section 25.0 “Comparator Module”	Updated the Comparator I/O Operating Modes diagram (see Figure 25-1). Added Note 2 to the Comparator Voltage Reference Control Register (see Register 25-6).
Section 29.0 “Special Features”	Added Note 3 to the Connections for the On-chip Voltage Regulator (see Figure 29-1).
Section 32.0 “Electrical Characteristics”	Removed the Voltage on VCAP with respect to VSS from the Absolute Maximum Ratings ⁽¹⁾ . Removed Note 3 and parameter DC18 from the DC Temperature and Voltage Specifications (see Table 32-4). Updated the notes in the DC Characteristics: Operating Current (IDD) (see Table 32-5). Updated the notes in the DC Characteristics: Idle Current (IDLE) (see Table 32-6). Updated the Typical and Maximum values for parameter DC60c and the notes in the DC Characteristics: Power-down Current (IPD) (see Table 32-7). Updated the notes in the DC Characteristics: Doze Current (IDOZE) (see Table 32-8). Updated the conditions for parameters DI60a and DI60b (see Table 32-9). Updated the conditions for parameter BO10 in the BOR Electrical Characteristics (see Table 32-10). Added Note 1 to the Internal Voltage Regulator Specifications (see Table 32-13). Updated the Minimum and Maximum values for parameter OS53 in the PLL Clock Timing Specifications (see Table 32-17). Updated the Minimum and Maximum values for parameter F21b in the Internal LPRC Accuracy specifications (see Table 32-20). Added Note 2 to the ADC Module Specifications (see Table 32-54).

Revision F (February 2012)

This revision includes typographical and formatting changes throughout the data sheet text.

Throughout the document, references to the package formerly known as XBGA where changed to TFBGA.

In addition, where applicable, new sections were added to each peripheral chapter that provide information and links to related resources, as well as helpful tips. For examples, see **Section 18.1 “SPI Helpful Tips”** and **Section 18.2 “SPI Resources”**. The major changes are referenced by their respective section in Table A-4.

TABLE A-4: MAJOR SECTION UPDATES

Section Name	Update Description
“16-Bit Microcontrollers and Digital Signal Controllers with High-Speed PWM, USB and Advanced Analog”	<p>The content on the first page of this section was extensively reworked to provide the reader with the key features and functionality of this device family in an “at-a-glance” format.</p> <p>The following devices were added to the Controller Families table (see Table 1 and the “Pin Diagrams” section):</p> <ul style="list-style-type: none"> • dsPIC33EP512MC806 • dsPIC33EP512GP806 • PIC24EP512GP806
Section 2.0 “Guidelines for Getting Started with 16-Bit Digital Signal Controllers and Microcontrollers”	Added Section 2.9 “Application Examples”
Section 3.0 “CPU”	Updated the Status Register information in the Programmer’s Model (see Figure 3-2).
Section 4.0 “Memory Organization”	<p>Added Interrupt Controller Register Maps (see Table 4-6 and Table 4-7).</p> <p>Added Peripheral Pin Select Output Register Map (see Table 4-39).</p> <p>Added PMD Register Maps (see Table 4-50 and Table 4-51).</p> <p>Added PORTF Register Map (see Table 4-64).</p> <p>Added PORTG Register Map (see Table 4-67).</p> <p>Updated the second note in Section 4.7 “Bit-Reversed Addressing (dsPIC33EPXXXMU806/810/814 Devices Only)”.</p>
Section 11.0 “I/O Ports”	Added RPOR10: Peripheral Pin Select Output Register 10 (see Register 11-54).
Section 14.0 “Input Capture”	Updated the Input Capture Module Block Diagram (see Figure 14-1).
Section 15.0 “Output Compare”	Updated the Output Compare Module Block Diagram (see Figure 15-1).
Section 25.0 “Comparator Module”	<p>Updated the User-programmable Blanking Function Block Diagram (see Figure 25-3).</p> <p>Updated the bit definitions in the Comparator Mask Gating Control Register (see Register 25-4).</p>
Section 29.0 “Special Features”	Added Note 3 to the Configuration Bits Description (see Table 29-2).
Section 32.0 “Electrical Characteristics”	<p>Updated the I/O pin Absolute Maximum Ratings.</p> <p>Updated Note 1 in the DC Characteristics: Operating Current (see Table 32-5).</p> <p>Updated Note 1 in the DC Characteristics: Idle Current (see Table 32-6).</p> <p>Updated Note 1 in the DC Characteristics: Power-down Current (see Table 32-7).</p> <p>Updated Note 1 in the DC Characteristics: Doze Current (see Table 32-8).</p> <p>Removed parameters DO16 and DO26, added parameter DO26a, updated parameters DO10 and DO20, and added Note 1 in the DC Characteristics: I/O Pin Output Specifications (see Table 32-10).</p>