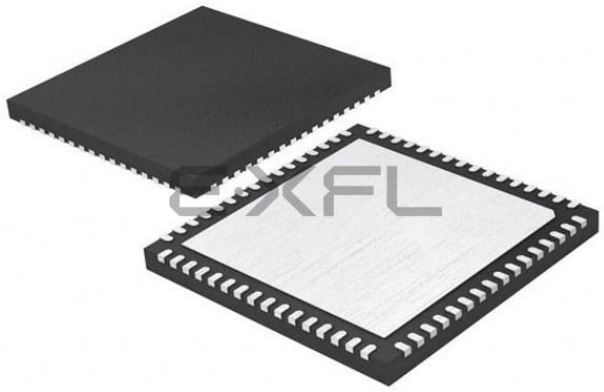
Microchip Technology - DSPIC33EP512MC806T-I/MR Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	CANbus, I²C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	53
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep512mc806t-i-mr

3.0 CPU

Note 1: This data sheet summarizes the features of the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 2. "CPU"** (DS70359) in the "*dsPIC33E/PIC24E Family Reference Manual*", which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for digital signal processing. The CPU has a 24-bit instruction word, with a variable length opcode field. The Program Counter (PC) is 24 bits wide and addresses up to 4M x 24 bits of user program memory space.

An instruction prefetch mechanism helps maintain throughput and provides predictable execution. Most instructions execute in a single-cycle effective execution rate, with the exception of instructions that change the program flow, the double-word move (`MOV.D`) instruction, PSV accesses and the table instructions. Overhead free program loop constructs are supported using the `DO` and `REPEAT` instructions, both of which are interruptible at any point.

3.1 Registers

Devices have sixteen 16-bit working registers in the programmer's model. Each of the working registers can act as a Data, Address or Address Offset register. The 16th working register (W15) operates as a Software Stack Pointer for interrupts and calls. The working registers, W0 through W3, and selected bits from the STATUS register, have shadow registers for fast context saves and restores using a single `POP.S` or `PUSH.S` instruction.

3.2 Instruction Set

The dsPIC33EPXXXMU806/810/814 instruction set has two classes of instructions: the MCU class of instructions and the DSP class of instructions. The PIC24EPXXX(GP/GU)810/814 instruction set has the MCU class of instructions and does not support DSP instructions. These two instruction classes are seamlessly integrated into the architecture and execute from a single execution unit. The instruction set includes many addressing modes and was designed for optimum C compiler efficiency.

3.3 Data Space Addressing

The Base Data Space can be addressed as 32K words or 64 Kbytes and is split into two blocks, referred to as X and Y data memory. Each memory block has its own independent Address Generation Unit (AGU). The MCU class of instructions operate solely through the X memory AGU, which accesses the entire memory map as one linear data space. On dsPIC33EPXXX(GP/MC/MU)806/810/814 devices, certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y data space boundary is device-specific.

The upper 32 Kbytes of the data space memory map can optionally be mapped into Program Space at any 16K program word boundary. The program-to-data space mapping feature, known as Program Space Visibility (PSV), lets any instruction access Program Space as if it were data space. Moreover, the Base Data Space address is used in conjunction with a read or write page register (DSRPAG or DSWPAG) to form an Extended Data Space (EDS) address. The EDS can be addressed as 8M words or 16 Mbytes. Refer to **Section 3. "Data Memory"** (DS70595) and **Section 4. "Program Memory"** (DS70613) in the *"dsPIC33E/PIC24E Family Reference Manual"* for more details on EDS, PSV and table accesses.

On dsPIC33EPXXX(GP/MC/MU)806/810/814 devices, overhead-free circular buffers (Modulo Addressing) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. The X AGU circular addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data reordering for radix-2 FFT algorithms. PIC24EPXXX(GP/GU)810/814 devices do not support Modulo and Bit-Reversed Addressing.

3.4 Addressing Modes

The CPU supports these addressing modes:

- Inherent (no operand)
- Relative
- Literal
- Memory Direct
- Register Direct
- Register Indirect

Each instruction is associated with a predefined addressing mode group, depending upon its functional requirements. As many as six addressing modes are supported for each instruction.

3.7 CPU Control Registers

REGISTER 3-1: SR: CPU STATUS REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/C-0	R/C-0	R -0	R/W-0
OA(1)	OB(1)	SA(1,4)	SB(1,4)	OAB(1)	SAB(1)	DA(1)	DC
bit 15							bit 8

R/W-0(2,3)	R/W-0(2,3)	R/W-0(2,3)	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL<2:0>			RA	N	OV	Z	C
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	W = Writable bit	C = Clearable bit	
-n = Value at POR	'1'= Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **OA:** Accumulator A Overflow Status bit(1)
1 = Accumulator A has overflowed
0 = Accumulator A has not overflowed

bit 14 **OB:** Accumulator B Overflow Status bit(1)
1 = Accumulator B has overflowed
0 = Accumulator B has not overflowed

bit 13 **SA:** Accumulator A Saturation 'Sticky' Status bit(1,4)
1 = Accumulator A is saturated or has been saturated at some time
0 = Accumulator A is not saturated

bit 12 **SB:** Accumulator B Saturation 'Sticky' Status bit(1,4)
1 = Accumulator B is saturated or has been saturated at some time
0 = Accumulator B is not saturated

bit 11 **OAB:** OA || OB Combined Accumulator Overflow Status bit(1)
1 = Accumulators A or B have overflowed
0 = Neither Accumulators A or B have overflowed

bit 10 **SAB:** SA || SB Combined Accumulator 'Sticky' Status bit(1)
1 = Accumulators A or B are saturated or have been saturated at some time
0 = Neither Accumulator A or B are saturated

bit 9 **DA:** DO Loop Active bit(1)
1 = DO loop in progress
0 = DO loop not in progress

bit 8 **DC:** MCU ALU Half Carry/$\overline{\text{Borrow}}$ bit
1 = A carry-out from the 4th low order bit (for byte-sized data) or 8th low order bit (for word-sized data) of the result occurred
0 = No carry-out from the 4th low order bit (for byte-sized data) or 8th low order bit (for word-sized data) of the result occurred

Note 1: This bit is available on dsPIC33EPXXX(GP/MC/MU)806/810/814 devices only.

2: The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL, if IPL<3> = 1.

3: The IPL<2:0> bits are read-only when NSTDIS = 1 (INTCON1<15>).

4: A data write to the SR register can modify the SA and SB bits by either a data write to SA and SB or by clearing the SAB bit. To avoid a possible SA or SB bit write race condition, the SA and SB bits should not be modified using bit operations.

REGISTER 10-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IC8MD	IC7MD	IC6MD	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OC8MD	OC7MD	OC6MD	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **IC8MD:** Input Capture 8 Module Disable bit
1 = Input Capture 8 module is disabled
0 = Input Capture 8 module is enabled

bit 14 **IC7MD:** Input Capture 2 Module Disable bit
1 = Input Capture 7 module is disabled
0 = Input Capture 7 module is enabled

bit 13 **IC6MD:** Input Capture 6 Module Disable bit
1 = Input Capture 6 module is disabled
0 = Input Capture 6 module is enabled

bit 12 **IC5MD:** Input Capture 5 Module Disable bit
1 = Input Capture 5 module is disabled
0 = Input Capture 5 module is enabled

bit 11 **IC4MD:** Input Capture 4 Module Disable bit
1 = Input Capture 4 module is disabled
0 = Input Capture 4 module is enabled

bit 10 **IC3MD:** Input Capture 3 Module Disable bit
1 = Input Capture 3 module is disabled
0 = Input Capture 3 module is enabled

bit 9 **IC2MD:** Input Capture 2 Module Disable bit
1 = Input Capture 2 module is disabled
0 = Input Capture 2 module is enabled

bit 8 **IC1MD:** Input Capture 1 Module Disable bit
1 = Input Capture 1 module is disabled
0 = Input Capture 1 module is enabled

bit 7 **OC8MD:** Output Compare 8 Module Disable bit
1 = Output Compare 8 module is disabled
0 = Output Compare 8 module is enabled

bit 6 **OC7MD:** Output Compare 7 Module Disable bit
1 = Output Compare 7 module is disabled
0 = Output Compare 7 module is enabled

bit 5 **OC6MD:** Output Compare 6 Module Disable bit
1 = Output Compare 6 module is disabled
0 = Output Compare 6 module is enabled

bit 4 **OC5MD:** Output Compare 5 Module Disable bit
1 = Output Compare 5 module is disabled
0 = Output Compare 5 module is enabled

REGISTER 10-7: PMD7: PERIPHERAL MODULE DISABLE CONTROL REGISTER 7 (CONTINUED)

bit 4 **DMA0MD:** DMA0 Module Disable bit
1 = DMA0 module is disabled
0 = DMA0 module is enabled

DMA1MD: DMA1 Module Disable bit
1 = DMA1 module is disabled
0 = DMA1 module is enabled

DMA2MD: DMA2 Module Disable bit
1 = DMA2 module is disabled
0 = DMA2 module is enabled

DMA3MD: DMA3 Module Disable bit
1 = DMA3 module is disabled
0 = DMA3 module is enabled

bit 3-0 **Unimplemented:** Read as '0'

REGISTER 11-29: RPINR29: PERIPHERAL PIN SELECT INPUT REGISTER 29

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	SCK3R<6:0>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	SDI3R<6:0>						
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-8 **SCK3R<6:0>:** Assign SPI3 Clock Input (SCK3) to the Corresponding RPn/RPIn Pin bits (see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127
.
.
.
0000001 = Input tied to CMP1
0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **SDI3R<6:0>:** Assign SPI3 Data Input (SDI3) to the Corresponding RPn/RPIn Pin bits (see Table 11-2 for input pin selection numbers)

1111111 = Input tied to RP127
.
.
.
0000001 = Input tied to CMP1
0000000 = Input tied to Vss

REGISTER 11-45: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP67R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP66R<5:0>					
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP67R<5:0>:** Peripheral Output Function is Assigned to RP67 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP66R<5:0>:** Peripheral Output Function is Assigned to RP66 Output Pin bits (see Table 11-3 for peripheral function numbers)

REGISTER 11-46: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP69R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP68R<5:0>					
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP69R<5:0>:** Peripheral Output Function is Assigned to RP69 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP68R<5:0>:** Peripheral Output Function is Assigned to RP68 Output Pin bits (see Table 11-3 for peripheral function numbers)

NOTES:

14.2 Input Capture Control Registers

REGISTER 14-1: ICxCON1: INPUT CAPTURE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
—	—	ICSIDL	ICTSEL<2:0>			—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/HC/HS-0	R/HC/HS-0	R/W-0	R/W-0	R/W-0
—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>		
bit 7							bit 0

Legend:			
R = Readable bit	HC = Hardware Clearable bit	HS = Hardware Settable bit	'0' = Bit is cleared
-n = Value at POR	W = Writable bit	U = Unimplemented bit, read as '0'	

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **ICSIDL:** Input Capture Stop in Idle Control bit
- 1 = Input capture will Halt in CPU Idle mode
- 0 = Input capture will continue to operate in CPU Idle mode

bit 12-10 **ICTSEL<12:10>:** Input Capture Timer Select bits
- 111 = Peripheral clock (FP) is the clock source of the ICx
- 110 = Reserved
- 101 = Reserved
- 100 = Clock source of T1CLK is the clock source of the ICx (only the synchronous clock is supported)
- 011 = Clock source of T5CLK is the clock source of the ICx
- 010 = Clock source of T4CLK is the clock source of the ICx
- 001 = Clock source of T2CLK is the clock source of the ICx
- 000 = Clock source of T3CLK is the clock source of the ICx

bit 9-7 **Unimplemented:** Read as '0'

bit 6-5 **ICI<1:0>:** Number of Captures per Interrupt Select bits (this field is not used if ICM<2:0> = 001 or 111)
- 11 = Interrupt on every fourth capture event
- 10 = Interrupt on every third capture event
- 01 = Interrupt on every second capture event
- 00 = Interrupt on every capture event

bit 4 **ICOV:** Input Capture Overflow Status Flag bit (read-only)
- 1 = Input capture buffer overflow occurred
- 0 = No input capture buffer overflow occurred

bit 3 **ICBNE:** Input Capture Buffer Not Empty Status bit (read-only)
- 1 = Input capture buffer is not empty, at least one more capture value can be read
- 0 = Input capture buffer is empty

bit 2-0 **ICM<2:0>:** Input Capture Mode Select bits
- 111 = Input capture functions as interrupt pin only in CPU Sleep and Idle modes (rising edge detect only, all other control bits are not applicable)
- 110 = Unused (module disabled)
- 101 = Capture mode, every 16th rising edge (Prescaler Capture mode)
- 100 = Capture mode, every 4th rising edge (Prescaler Capture mode)
- 011 = Capture mode, every rising edge (Simple Capture mode)
- 010 = Capture mode, every falling edge (Simple Capture mode)
- 001 = Capture mode, every edge rising and falling (Edge Detect mode (ICI<1:0>) is not used in this mode)
- 000 = Input capture module is turned off

REGISTER 16-21: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IFLTMOD	CLSRC<4:0>(2,3)					CLPOL(1)	CLMOD
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLTSRC<4:0>(2,3)					FLTPOL(1)	FLTMOD<1:0>	
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **IFLTMOD:** Independent Fault Mode Enable bit
- 1 = Independent Fault mode: Current-limit input maps FLTDAT<1> to PWMxH output and Fault input maps FLTDAT<0> to PWMxL output; the CLDAT<1:0> bits are not used for override functions
- 0 = Normal Fault mode: Current-Limit mode maps CLDAT<1:0> bits to the PWMxH and PWMxL outputs; the PWM Fault mode maps FLTDAT<1:0> to the PWMxH and PWMxL outputs.

bit 14-10 **CLSRC<4:0>:** Current-Limit Control Signal Source Select for PWM Generator # bits(2,3)
- 11111 = Reserved
- •
- •
- •
- 01001 = Reserved
- 01010 = Comparator 3
- 01001 = Comparator 2
- 01000 = Comparator 1
- 00111 = Reserved
- 00110 = Fault 7
- 00101 = Fault 6
- 00100 = Fault 5
- 00011 = Fault 4
- 00010 = Fault 3
- 00001 = Fault 2
- 00000 = Fault 1

bit 9 **CLPOL:** Current-Limit Polarity bit for PWM Generator #(1)
- 1 = The selected current-limit source is active-low
- 0 = The selected current-limit source is active-high

bit 8 **CLMOD:** Current-Limit Mode Enable bit for PWM Generator #
- 1 = Current-Limit mode is enabled
- 0 = Current-Limit mode is disabled

Note 1: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

2: When Independent Fault mode is enabled (IFLTMOD = 1) and Fault 1 is used for Fault mode (FLTSRC<4:0> = 01000), the Current-Limit Control Source Select bits (CLSRC<4:0>) should be set to an unused current-limit source to prevent the current-limit source from disabling both the PWMxH and PWMxL outputs.

3: When Independent Fault mode is enabled (IFLTMOD = 1) and Fault 1 is used for Current-Limit mode (CLSRC<4:0> = 01000), the Fault Control Source Select bits (FLTSRC<4:0>) should be set to an unused Fault source to prevent Fault 1 from disabling both the PWMxL and PWMxH outputs.

17.0 QUADRATURE ENCODER INTERFACE (QEI) MODULE (dsPIC33EPXXX(MC/MU)8XX DEVICES ONLY)

Note 1: This data sheet summarizes the features of the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 15. "Quadrature Encoder Interface (QEI)"** (DS70601) of the "*dsPIC33E/PIC24E Family Reference Manual*", which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

This chapter describes the Quadrature Encoder Interface (QEI) module and associated operational modes. The QEI module provides the interface to incremental encoders for obtaining mechanical position data.

The operational features of the QEI module include:

- 32-Bit Position Counter
- 32-Bit Index Pulse Counter
- 32-Bit Interval Timer
- 16-Bit Velocity Counter
- 32-Bit Position Initialization/Capture/Compare High Register
- 32-Bit Position Compare Low Register
- x4 Quadrature Count mode
- External Up/Down Count mode
- External Gated Count mode
- External Gated Timer mode
- Internal Timer mode

Figure 17-1 illustrates the QEI block diagram.

Note: An 'x' used in the names of pins, control/status bits and registers denotes a particular Quadrature Encoder Interface (QEI) module number (x = 1 or 2).

19.1 I²C Resources

Many useful resources related to I²C are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310

19.1.1 KEY RESOURCES

- **Section 19. "Inter-Integrated Circuit™ (I²C™)"** (DS70330) in the *"dsPIC33E/PIC24E Family Reference Manual"*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *"dsPIC33E/PIC24E Family Reference Manual"* Sections
- Development Tools

REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

bit 3 **S:** Start bit

1 = Indicates that a Start (or Repeated Start) bit has been detected last
0 = Start bit was not detected last
Hardware is set or clear when a Start, Repeated Start or Stop is detected.

bit 2 **R_W:** Read/Write Information bit (when operating as I^2C slave)

1 = Read – indicates data transfer is output from a slave
0 = Write – indicates data transfer is input to a slave
Hardware is set or clear after reception of an I^2C device address byte.

bit 1 **RBF:** Receive Buffer Full Status bit

1 = Receive is complete, I2CxRCV is full
0 = Receive is not complete, I2CxRCV is empty
Hardware is set when I2CxRCV is written with a received byte. Hardware is clear when software reads I2CxRCV.

bit 0 **TBF:** Transmit Buffer Full Status bit

1 = Transmit is in progress, I2CxTRN is full
0 = Transmit is complete, I2CxTRN is empty
Hardware is set when software writes to I2CxTRN. Hardware is clear at completion of a data transmission.

REGISTER 19-3: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	AMSK9	AMSK8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AMSK7	AMSK6	AMSK5	AMSK4	AMSK3	AMSK2	AMSK1	AMSK0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-10 **Unimplemented:** Read as '0'

bit 9-0 **AMSKx:** Mask for Address bit x Select bit

For 10-Bit Address:

1 = Enables masking for bit Ax of incoming message address; bit match is not required in this position

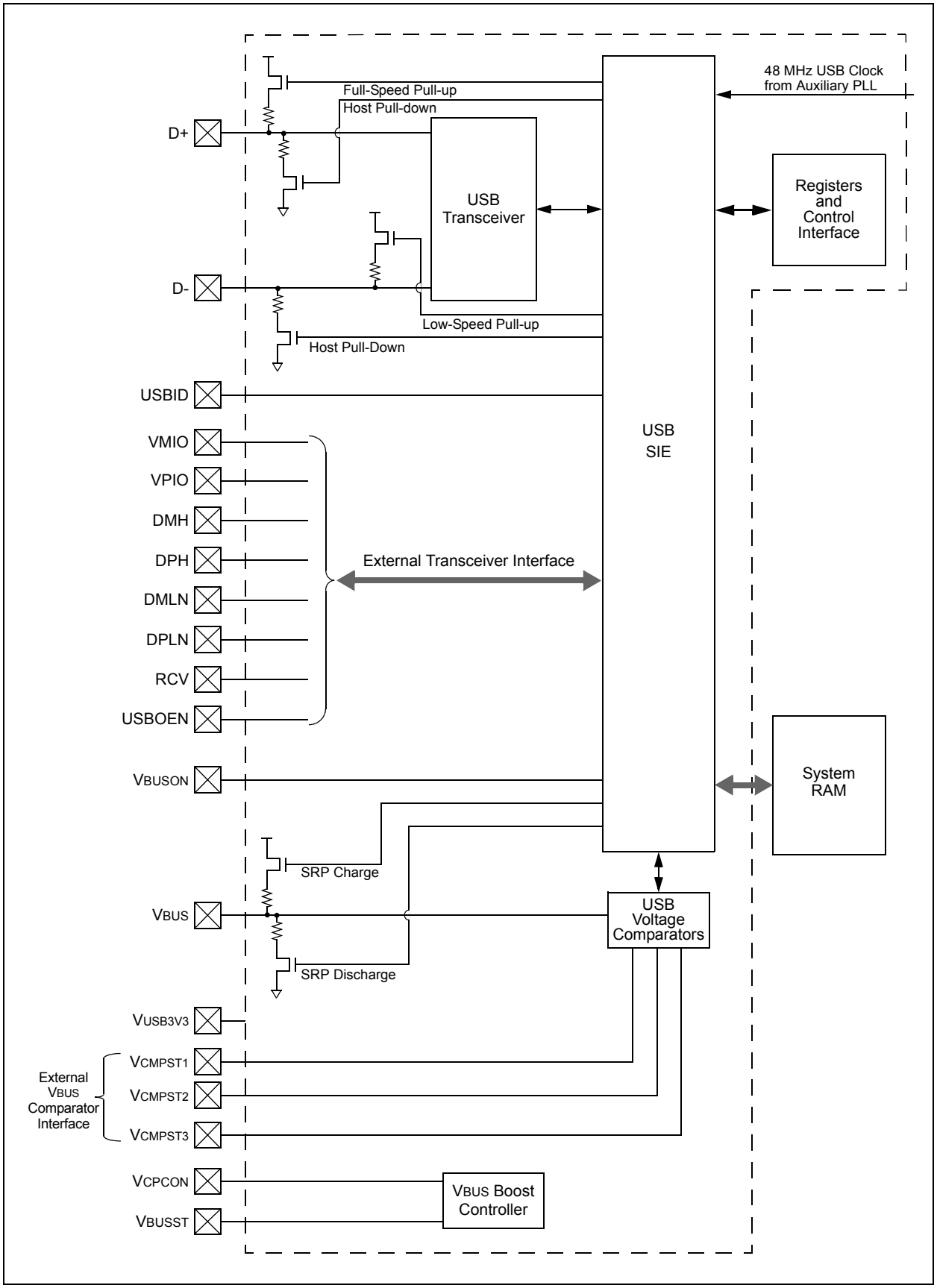
0 = Disables masking for bit Ax; bit match is required in this position

For 7-Bit Address (I2CxMSK<6:0> only):

1 = Enables masking for bit Ax + 1 of incoming message address; bit match is not required in this position

0 = Disable masking for bit Ax + 1; bit match is required in this position

FIGURE 22-1: USB INTERFACE DIAGRAM



REGISTER 24-4: DCISTAT: DCI STATUS REGISTER

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
r	r	r	r	SLOT<3:0>			
bit 15							bit 8

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
r	r	r	r	ROV	RFUL	TUNF	TMPTY
bit 7							bit 0

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Reserved:** Read as '0'

bit 11-8 **SLOT<3:0>:** DCI Slot Status bits
1111 = Slot 15 is currently active
•
•
•
0010 = Slot 2 is currently active
0001 = Slot 1 is currently active
0000 = Slot 0 is currently active

bit 7-4 **Reserved:** Read as '0'

bit 3 **ROV:** Receive Overflow Status bit
1 = A receive overflow has occurred for at least one Receive register
0 = A receive overflow has not occurred

bit 2 **RFUL:** Receive Buffer Full Status bit
1 = New data is available in the Receive registers
0 = The Receive registers have old data

bit 1 **TUNF:** Transmit Buffer Underflow Status bit
1 = A transmit underflow has occurred for at least one Transmit register
0 = A transmit underflow has not occurred

bit 0 **TMPTY:** Transmit Buffer Empty Status bit
1 = The Transmit registers are empty
0 = The Transmit registers are not empty

REGISTER 25-3: CMxMSKSRC: COMPARATOR x MASK SOURCE SELECT CONTROL REGISTER (CONTINUED)

bit 3-0 **SELSRCA<3:0>:** Mask A Input Select bits

1111 = FLT4
1110 = FLT2
1101 = PWM7H
1100 = PWM7L
1011 = PWM6H
1010 = PWM6L
1001 = PWM5H
1000 = PWM5L
0111 = PWM4H
0110 = PWM4L
0101 = PWM3H
0100 = PWM3L
0011 = PWM2H
0010 = PWM2L
0001 = PWM1H
0000 = PWM1L

REGISTER 28-4: PMAEN: PARALLEL MASTER PORT ADDRESS ENABLE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTEN15	PTEN14	PTEN13	PTEN12	PTEN11	PTEN10	PTEN9	PTEN8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTEN7	PTEN6	PTEN5	PTEN4	PTEN3	PTEN2	PTEN1	PTEN0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at Reset	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **PTEN15:** PMCS2 Strobe Enable bit
1 = PMA15 functions as either PMA<15> or PMCS2
0 = PMA15 functions as port I/O

bit 14 **PTEN14:** PMCS1 Strobe Enable bit
1 = PMA14 functions as either PMA<14> or PMCS1
0 = PMA14 functions as port I/O

bit 13-2 **PTEN<13:2>:** PMP Address Port Enable bits
1 = PMA<13:2> function as PMP address lines
0 = PMA<13:2> function as port I/O

bit 1-0 **PTEN<1:0>:** PMALH/PMALL Strobe Enable bits
1 = PMA1 and PMA0 function as either PMA<1:0> or PMALH and PMALL
0 = PMA1 and PMA0 function as port I/O

REGISTER 28-6: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL	PMPTTL
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-2 **Unimplemented:** Read as '0'

bit 1 Not used by the PMP module.

bit 0 **PMPTTL:** PMP Module TTL Input Buffer Select bit
1 = PMP module uses TTL input buffers
0 = PMP module uses Schmitt Trigger input buffers

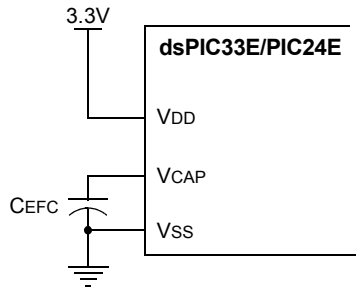
29.2 On-Chip Voltage Regulator

All of the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices power their core digital logic at a nominal 1.8V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. A low-ESR (less than 1 Ohms) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (Figure 29-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 32-13 located in **Section 32.0 "Electrical Characteristics"**.

Note:	It is important for the low-ESR capacitor to be placed as close as possible to the VCAP pin.

FIGURE 29-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR(1,2,3)



Note 1: These are typical operating voltages. Refer to Table 32-13 located in **Section 32.1 "DC Characteristics"** for the full operating ranges of VDD and VCAP.

2: It is important for the low-ESR capacitor to be placed as close as possible to the VCAP pin.

3: Typical VCAP pin voltage is 1.8V when VDD ≥ VDDMIN.

29.3 Brown-out Reset (BOR)

The Brown-out Reset module is based on an internal voltage reference circuit that monitors the regulated supply voltage, VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines, or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse, which resets the device. The BOR selects the clock source based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is '1'.

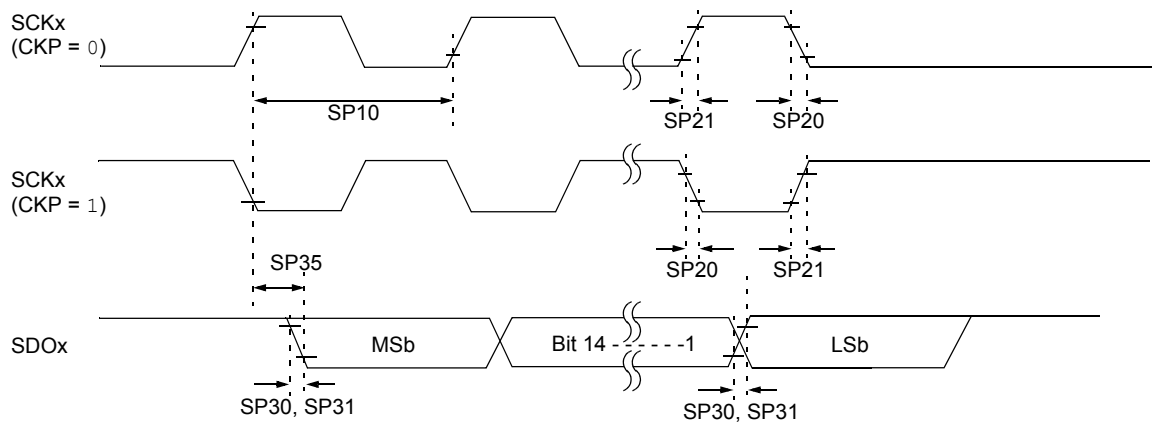
Concurrently, the Power-up Timer (PWRT) Time-out (TPWRT) is applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, then a nominal delay of TFSCM is applied. The total delay in this case is TFSCM. Refer to Parameter SY35 in Table 32-22 of **Section 32.0 "Electrical Characteristics"** for specific TFSCM values.

The BOR Status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit, continues to operate while in Sleep or Idle modes and resets the device should VDD fall below the BOR threshold voltage.

TABLE 32-41: SPI2 MAXIMUM DATA/CLOCK RATE SUMMARY

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Maximum Data Rate	**Master Transmit Only (Half-Duplex)**	**Master Transmit/Receive (Full-Duplex)**	**Slave Transmit/Receive (Full-Duplex)**	**CKE**	**CKP**	**SMP**
15 MHz	Table 32-42	—	—	0,1	0,1	0,1
10 MHz	—	Table 32-43	—	1	0,1	1
10 MHz	—	Table 32-44	—	0	0,1	1
15 MHz	—	—	Table 32-45	1	0	0
11 MHz	—	—	Table 32-46	1	1	0
15 MHz	—	—	Table 32-47	0	1	0
11 MHz	—	—	Table 32-48	0	0	0

FIGURE 32-23: SPI2 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS



Note: Refer to Figure 32-1 for load conditions.