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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	53
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24ep512gp806-i-pt

TABLE 4-10: INPUT CAPTURE 1 THROUGH INPUT CAPTURE 16 REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
IC1CON1	0140	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC1CON2	0142	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC1BUF	0144	Input Capture 1 Buffer Register																	xxxx
IC1TMR	0146	Input Capture 1 Timer																	0000
IC2CON1	0148	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC2CON2	014A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC2BUF	014C	Input Capture 2 Buffer Register																	xxxx
IC2TMR	014E	Input Capture 2 Timer																	0000
IC3CON1	0150	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC3CON2	0152	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC3BUF	0154	Input Capture 3 Buffer Register																	xxxx
IC3TMR	0156	Input Capture 3 Timer																	0000
IC4CON1	0158	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC4CON2	015A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC4BUF	015C	Input Capture 4 Buffer Register																	xxxx
IC4TMR	015E	Input Capture 4 Timer																	0000
IC5CON1	0160	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC5CON2	0162	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC5BUF	0164	Input Capture 5 Buffer Register																	xxxx
IC5TMR	0166	Input Capture 5 Timer																	0000
IC6CON1	0168	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC6CON2	016A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC6BUF	016C	Input Capture 6 Buffer Register																	xxxx
IC6TMR	016E	Input Capture 6 Timer																	0000
IC7CON1	0170	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC7CON2	0172	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC7BUF	0174	Input Capture 7 Buffer Register																	xxxx
IC7TMR	0176	Input Capture 7 Timer																	0000
IC8CON1	0178	—	—	ICSIDL	ICTSEL<2:0>			—	—	—	ICI<1:0>		ICOV	ICBNE	ICM<2:0>			0000	
IC8CON2	017A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL<4:0>					000D	
IC8BUF	017C	Input Capture 8 Buffer Register																	xxxx
IC8TMR	017E	Input Capture 8 Timer																	0000

5.0 FLASH PROGRAM MEMORY

Note 1: This data sheet summarizes the features of the dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 5. “Flash Programming”** (DS70609) of the “dsPIC33E/PIC24E Family Reference Manual”, which is available from the Microchip web site (www.microchip.com).

- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices contain internal Flash program memory for storing and executing application code. The memory is readable, writable and erasable during normal operation over the entire VDD range.

Flash memory can be programmed in two ways:

- In-Circuit Serial Programming™ (ICSP™) programming capability
- Run-Time Self-Programming (RTSP)

ICSP allows a dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 device to be serially programmed while in the end application circuit. This is done with two lines for programming clock and programming data (one of the alternate programming

pin pairs: PGECx/PGEDx), and three other lines for power (VDD), ground (VSS) and Master Clear ($\overline{\text{MCLR}}$). This allows customers to manufacture boards with unprogrammed devices and then program the device just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

RTSP is accomplished using TBLRD (table read) and TBLWT (table write) instructions. With RTSP, the user application can write program memory data either in blocks or ‘rows’ of 128 instructions (384 bytes) at a time or a single program memory word, and erase program memory in blocks or ‘pages’ of 1024 instructions (3072 bytes) at a time.

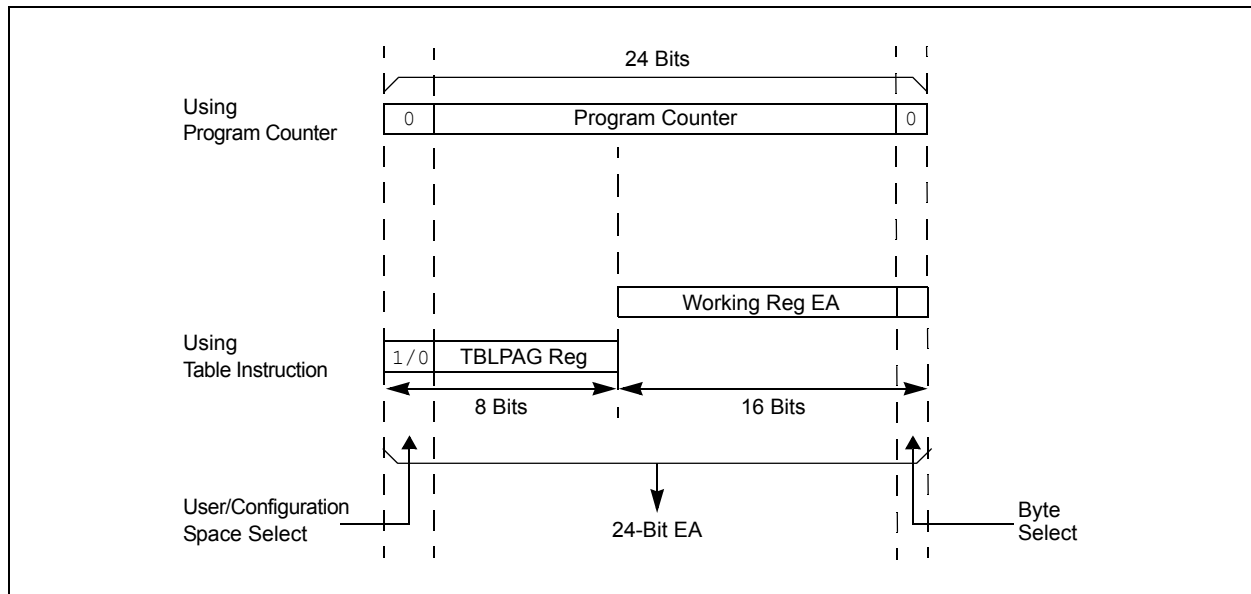
5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the table read and table write instructions. These allow direct read and write access to the program memory space from the data memory while the device is in normal operating mode. The 24-bit target address in the program memory is formed using bits<7:0> of the TBLPAG register and the Effective Address (EA) from a W register, specified in the table instruction, as shown in Figure 5-1.

The TBLRDL and the TBLWTL instructions are used to read or write to bits<15:0> of program memory. TBLRDL and TBLWTL can access program memory in both Word and Byte modes.

The TBLRDH and TBLWTH instructions are used to read or write to bits<23:16> of program memory. TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS



10.5 Power-Saving Resources

Many useful resources related to Power-Saving features are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

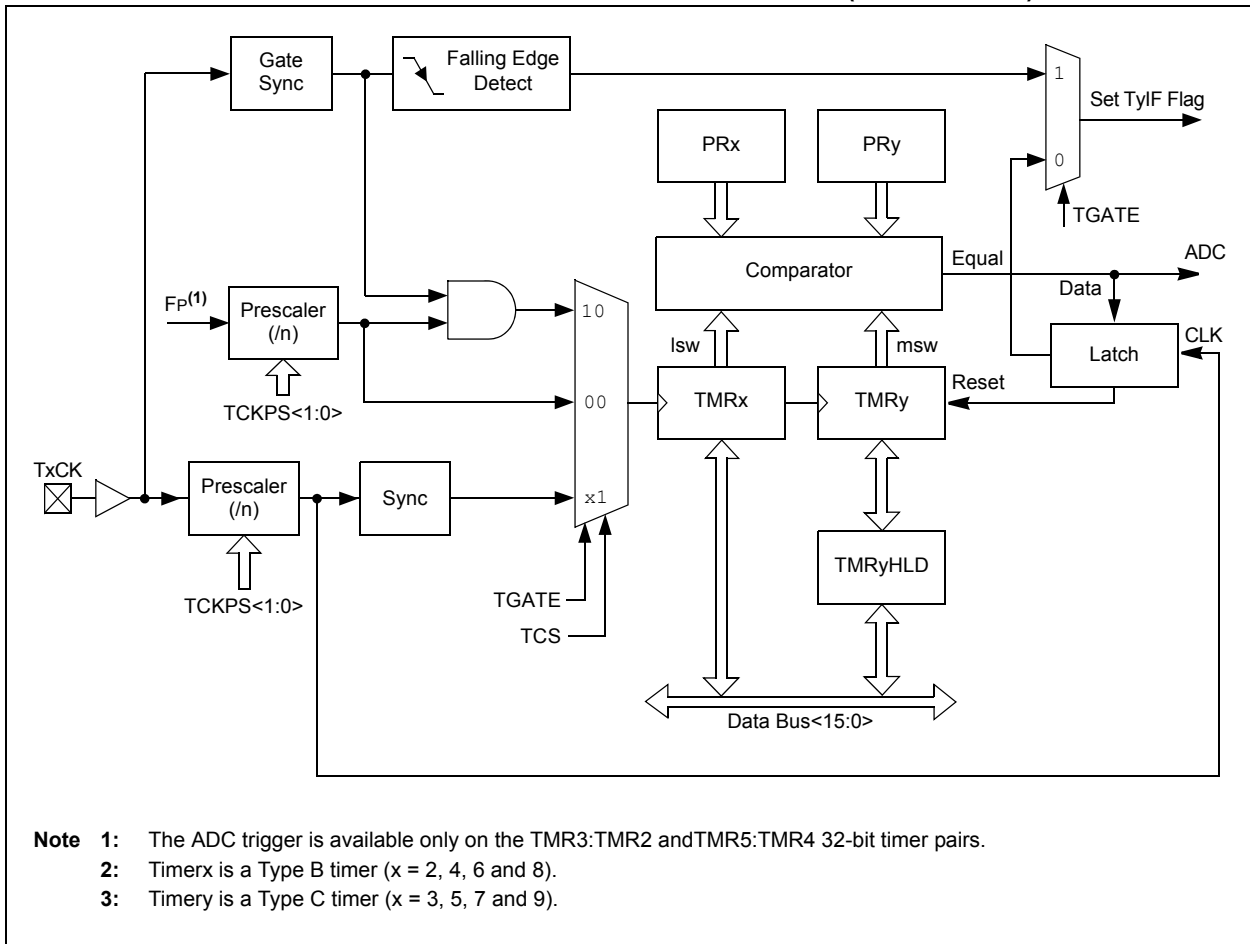
Note: In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310
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10.5.1 KEY RESOURCES

- **Section 9. “Watchdog Timer and Power-Saving Modes”** (DS70615) in the *“dsPIC33E/PIC24E Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *“dsPIC33E/PIC24E Family Reference Manual”* Sections
- Development Tools

10.6 Special Function Registers

Seven registers, PMD1: Peripheral Module Disable Control Register 1 through PMD7: Peripheral Module Disable Control Register 7, are provided for peripheral module control.

FIGURE 13-3: TYPE B/TIME C TIMER PAIR BLOCK DIAGRAM (32-BIT TIMER)

13.1 Timer Resources

Many useful resources related to timers are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser:
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310>

13.1.1 KEY RESOURCES

- **Section 11. “Timers”** (DS70362) in the “dsPIC33E/PIC24E Family Reference Manual”
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related “dsPIC33E/PIC24E Family Reference Manual” Sections
- Development Tools

17.1 QEI Resources

Many useful resources related to QEI are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310
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17.1.1 KEY RESOURCES

- **Section 15. “Quadrature Encoder Interface (QEI)”** (DS70601) in the *“dsPIC33E/PIC24E Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *“dsPIC33E/PIC24E Family Reference Manual”* Sections
- Development Tools

REGISTER 17-1: QEIXCON: QEIX CONTROL REGISTER (CONTINUED)

bit 6-4	INTDIV<2:0> : Timer Input Clock Prescale Select bits (interval timer, main timer (position counter), velocity counter and index counter internal clock divider select) ⁽³⁾ 111 = 1:128 prescale value 110 = 1:64 prescale value 101 = 1:32 prescale value 100 = 1:16 prescale value 011 = 1:8 prescale value 010 = 1:4 prescale value 001 = 1:2 prescale value 000 = 1:1 prescale value
bit 3	CNTPOL : Position and Index Counter/Timer Direction Select bit 1 = Counter direction is negative unless modified by external up/down signal 0 = Counter direction is positive unless modified by external up/down signal
bit 2	GATEN : External Count Gate Enable bit 1 = External gate signal controls position counter operation 0 = External gate signal does not affect position counter/timer operation
bit 1-0	CCM<1:0> : Counter Control Mode Selection bits 11 = Internal Timer mode with optional external count is selected 10 = External clock count with optional external count is selected 01 = External clock count with external up/down direction is selected 00 = Quadrature Encoder Interface (x4 mode) Count mode is selected

- Note 1:** When CCM = 10 or CCM = 11, all of the QEI counters operate as timers and the PIMOD<2:0> bits are ignored.
- 2:** When CCM = 00, and QEA and QEB values match Index Match Value (IMV), the POSCNTH and POSCNTL registers are reset.
- 3:** The selected clock rate should be at least twice the expected maximum quadrature count rate.

18.1 SPI Helpful Tips

1. In Frame mode, if there is a possibility that the master may not be initialized before the slave:
 - a) If FRMPOL (SPIxCON2<13>) = 1, use a pull-down resistor on SSx.
 - b) If FRMPOL = 0, use a pull-up resistor on SSx.

Note: This insures that the first frame transmission after initialization is not shifted or corrupted.

2. In Non-Framed 3-Wire mode, (i.e., not using SSx from a master):
 - a) If CKP (SPIxCON1<6>) = 1, always place a pull-up resistor on SSx.
 - b) If CKP = 0, always place a pull-down resistor on SSx.

Note: This will insure that during power-up and initialization, the master/slave will not lose synchronization due to an errant SCKx transition that would cause the slave to accumulate data shift errors, for both transmit and receive, appearing as corrupted data.

3. FRMEN (SPIxCON2<15>) = 1 and SSEN (SPIxCON1<7>) = 1 are exclusive and invalid. In Frame mode, SCKx is continuous and the Frame Sync pulse is active on the SSx pin, which indicates the start of a data frame.

Note: Not all third-party devices support Frame mode timing. Refer to the SPIx electrical characteristics for details.

4. In Master mode only, set the SMP bit (SPIxCON1<9>) to a '1' for the fastest SPI data rate possible. The SMP bit can only be set at the same time or after the MSTEN bit (SPIxCON1<5>) is set.

To avoid invalid slave read data to the master, the user's master software must ensure enough time for slave software to fill its write buffer before the user application initiates a master write/read cycle. It is always advisable to preload the SPIxBUF Transmit register in advance of the next master transaction cycle. SPIxBUF is transferred to the SPIx Shift register and is empty once the data transmission begins.

18.2 SPI Resources

Many useful resources related to SPI are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser:
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554301>

18.2.1 KEY RESOURCES

- **Section 18. "Serial Peripheral Interface (SPI)"** (DS70569) in the "*dsPIC33E/PIC24E Family Reference Manual*"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related "*dsPIC33E/PIC24E Family Reference Manual*" Sections
- Development Tools

REGISTER 21-5: CxFIFO: ECANx FIFO STATUS REGISTER

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FBP<5:0>					
bit 15							bit 8

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FNRB<5:0>					
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **FBP<5:0>:** FIFO Buffer Pointer bits

011111 = RB31 buffer

011110 = RB30 buffer

•

•

•

000001 = TRB1 buffer

000000 = TRB0 buffer

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **FNRB<5:0>:** FIFO Next Read Buffer Pointer bits

011111 = RB31 buffer

011110 = RB30 buffer

•

•

•

000001 = TRB1 buffer

000000 = TRB0 buffer

22.3 USB OTG Resources

Many useful resources related to USB OTG are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310
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22.3.1 KEY RESOURCES

- **Section 11. “USB On-The-Go (OTG)”** (DS70571) in the “*dsPIC33E/PIC24E Family Reference Manual*”
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related “*dsPIC33E/PIC24E Family Reference Manual*” Sections
- Development Tools

REGISTER 24-3: DCICON3: DCI CONTROL REGISTER 3

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
r	r	r	r	BCG<11:8>			
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BCG<7:0>							
bit 7				bit 0			

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Reserved:** Read as '0'bit 11-0 **BCG<11:0>:** DCI Clock Generator Control bits

FIGURE 25-2: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM

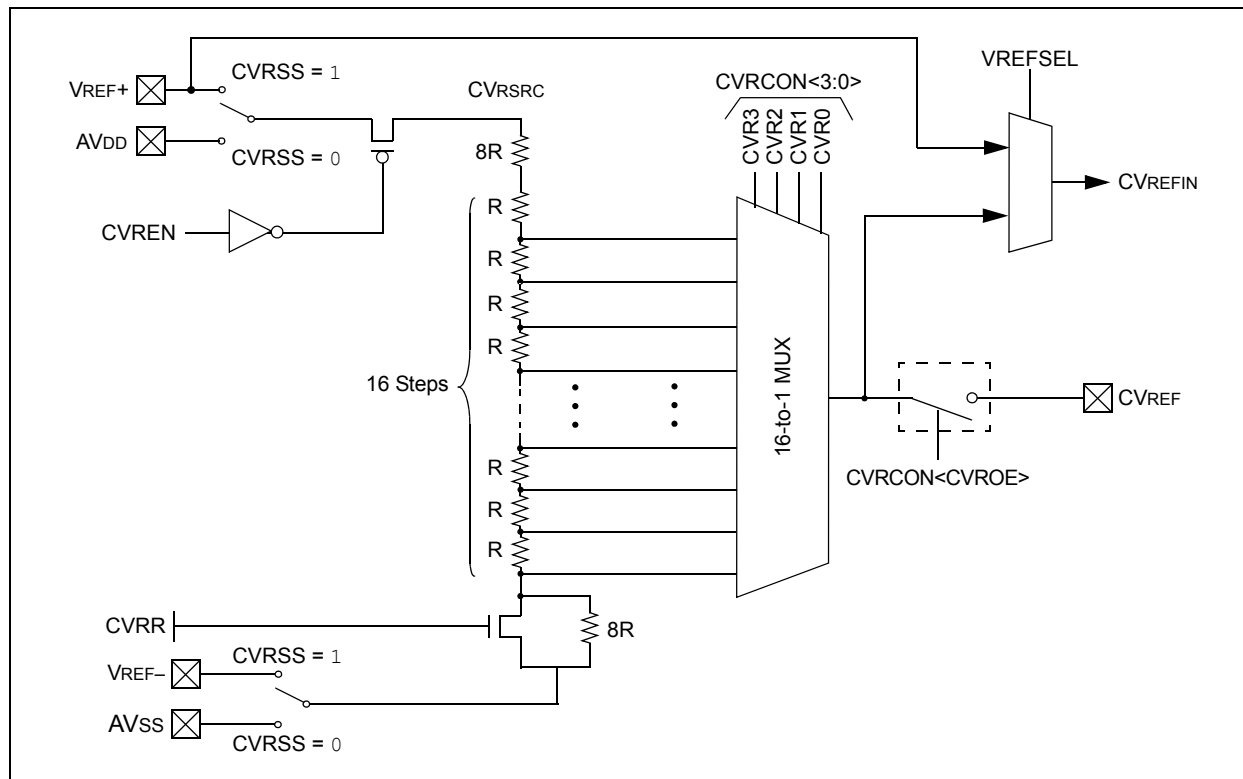
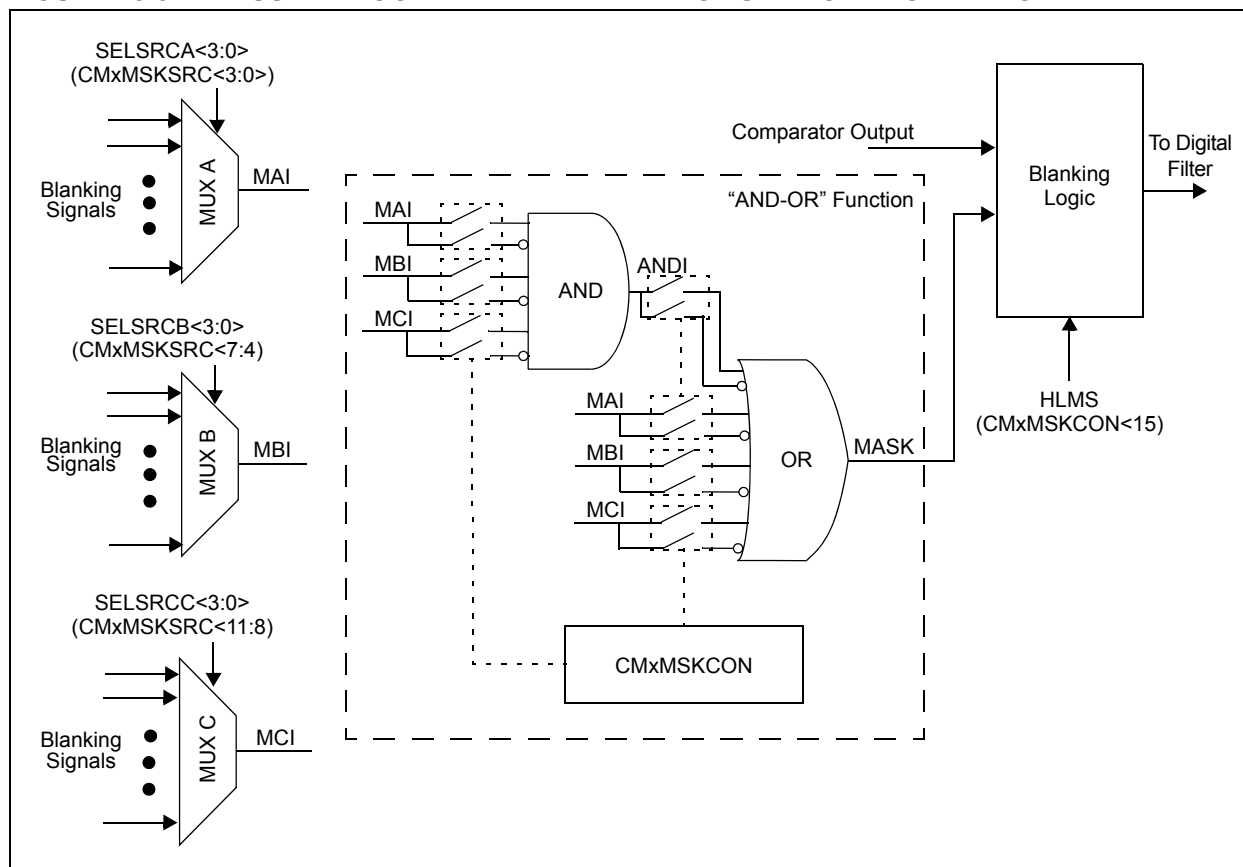


FIGURE 25-3: USER-PROGRAMMABLE BLANKING FUNCTION BLOCK DIAGRAM



REGISTER 28-1: PMCON: PARALLEL MASTER PORT CONTROL REGISTER (CONTINUED)

bit 3	CS1P: Chip Select 0 Polarity bit ⁽¹⁾ 1 = Active-high (<u>PMCS1/PMCS</u>) ⁽²⁾ 0 = Active-low (<u>PMCS1/PMCS</u>)
bit 2	BEP: Byte Enable Polarity bit 1 = Byte enable active-high (<u>PMBE</u>) 0 = Byte enable active-low (<u>PMBE</u>)
bit 1	WRSP: Write Strobe Polarity bit <u>For Slave Modes and Master Mode 2 (PMMODE<9:8> = 00, 01, 10):</u> 1 = Write strobe is active-high (<u>PMWR</u>) 0 = Write strobe is active-low (<u>PMWR</u>) <u>For Master Mode 1 (PMMODE<9:8> = 11):</u> 1 = Enables strobe active-high (<u>PMENB</u>) 0 = Enables strobe active-low (<u>PMENB</u>)
bit 0	RDSP: Read Strobe Polarity bit <u>For Slave Modes and Master Mode 2 (PMMODE<9:8> = 00, 01, 10):</u> 1 = Read strobe is active-high (<u>PMRD</u>) 0 = Read strobe is active-low (<u>PMRD</u>) <u>For Master Mode 1 (PMMODE<9:8> = 11):</u> 1 = Enables strobe active-high (<u>PMRD/PMWR</u>) 0 = Enables strobe active-low (<u>PMRD/PMWR</u>)

Note 1: These bits have no effect when their corresponding pins are used as address lines.

2: PMCS1 applies to Master mode and PMCS applies to Slave mode.

**REGISTER 28-3: PMADDR: PARALLEL MASTER PORT ADDRESS REGISTER
(MASTER MODES ONLY)⁽¹⁾**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CS2	CS1	ADDR<13:8>					
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADDR<7:0>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at Reset

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **CS2:** Chip Select 2 bit
 If PMCON<7:6> = 10 or 01:
 1 = Chip Select 2 is active
 0 = Chip Select 2 is inactive
 If PMCON<7:6> = 11 or 00:
 Bit functions as ADDR<15>.

bit 14 **CS1:** Chip Select 1 bit
 If PMCON<7:6> = 10:
 1 = Chip Select 1 is active
 0 = Chip Select 1 is inactive
 If PMCON<7:6> = 11 or 0x:
 Bit functions as ADDR<14>.

bit 13-0 **ADDR<13:0>:** Destination Address bits

Note 1: In Enhanced Slave mode, PMADDR functions as PMDOUT1, one of the two Data Buffer registers.

29.5 JTAG Interface

dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices implement a JTAG interface, which supports boundary scan device testing. Detailed information on this interface is provided in future revisions of the document.

Note: Refer to **Section 24. “Programming and Diagnostics”** (DS70608) of the *“dsPIC33E/PIC24E Family Reference Manual”* for further information on usage, configuration and operation of the JTAG interface.

29.6 In-Circuit Serial Programming

The dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices can be serially programmed while in the end application circuit. This is done with two lines for clock and data, and three other lines for power, ground and the programming sequence. Serial programming allows customers to manufacture boards with unprogrammed devices and then program the digital signal controller just before shipping the product. Serial programming also allows the most recent firmware or a custom firmware to be programmed. Refer to the *“dsPIC33E/PIC24E Flash Programming Specification”* (DS70619) for details about In-Circuit Serial Programming (ICSP).

Any of the three pairs of programming clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

29.7 In-Circuit Debugger

When MPLAB® ICD 3 or REAL ICE™ is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pin functions.

Any of the three pairs of debugging clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, VSS and the PGECx/PGEDx pin pair. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

29.8 Code Protection and CodeGuard™ Security

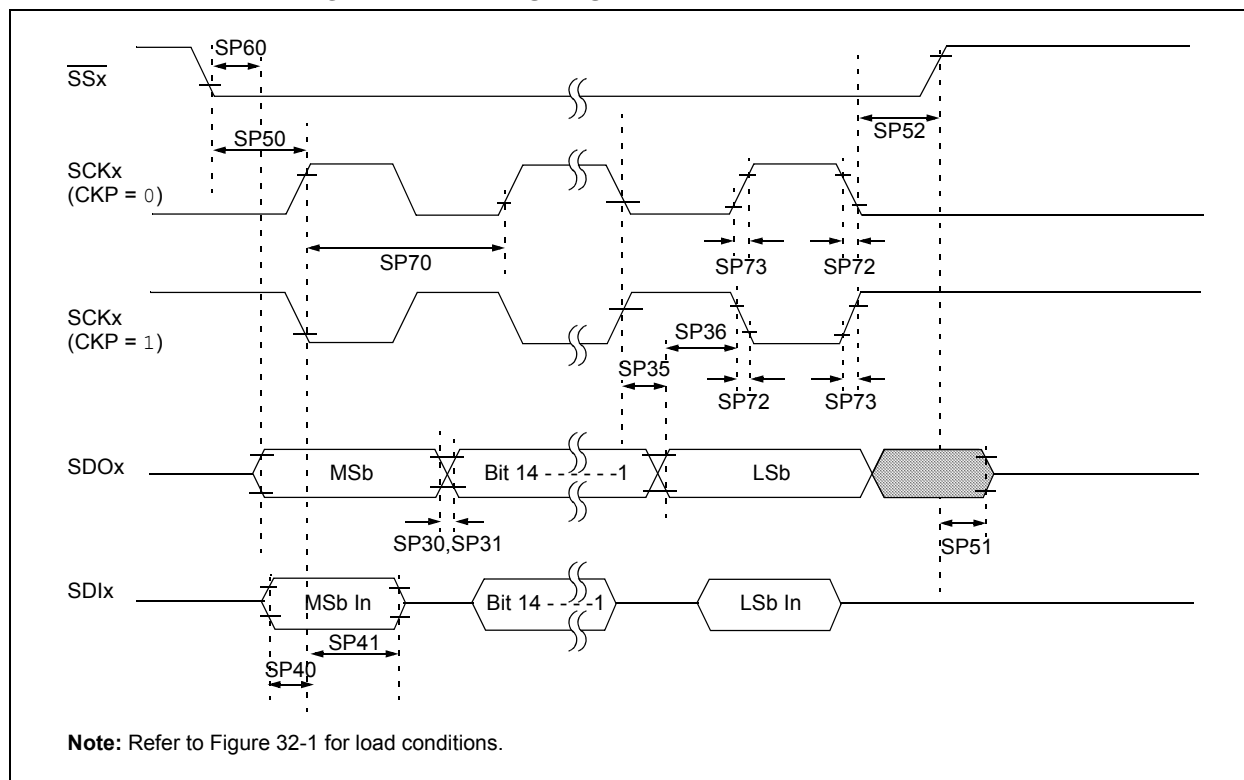
The dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices offer basic implementation of CodeGuard Security that supports only General Segment (GS) security. This feature helps protect individual Intellectual Property in collaborative system designs.

When coupled with software encryption libraries, CodeGuard Security can be used to securely update Flash even when multiple IPs reside on the single chip. The code protection features vary depending on the actual dsPIC33E implemented. The following sections provide an overview of these features.

The dsPIC33EPXXX(GP/MC/MU)806/810/814 and PIC24EPXXX(GP/GU)810/814 devices do not support Boot Segment (BS), Secure Segment (SS) and RAM protection.

Note: Refer to **Section 23. “CodeGuard™ Security”** (DS70634) of the *“dsPIC33E/PIC24E Family Reference Manual”* for further information on usage, configuration and operation of CodeGuard Security.

FIGURE 32-20: SPI1, SPI3 AND SPI4 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS



**TABLE 32-40: SPI1, SPI3 AND SPI4 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0)
TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP70	TscP	Maximum SCKx Input Frequency	—	—	11	MHz	See Note 3
SP72	TscF	SCKx Input Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{SSx} \downarrow$ to SCKx $\uparrow$ or SCKx $\downarrow$ Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{SSx} \uparrow$ to SDOx Output High-Impedance	10	—	50	ns	See Note 4
SP52	Tsch2ssH, TscL2ssH	$\overline{SSx} \uparrow$ after SCKx Edge	1.5 TCY + 40	—	—	ns	See Note 4

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 91 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

FIGURE 32-29: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING CHARACTERISTICS

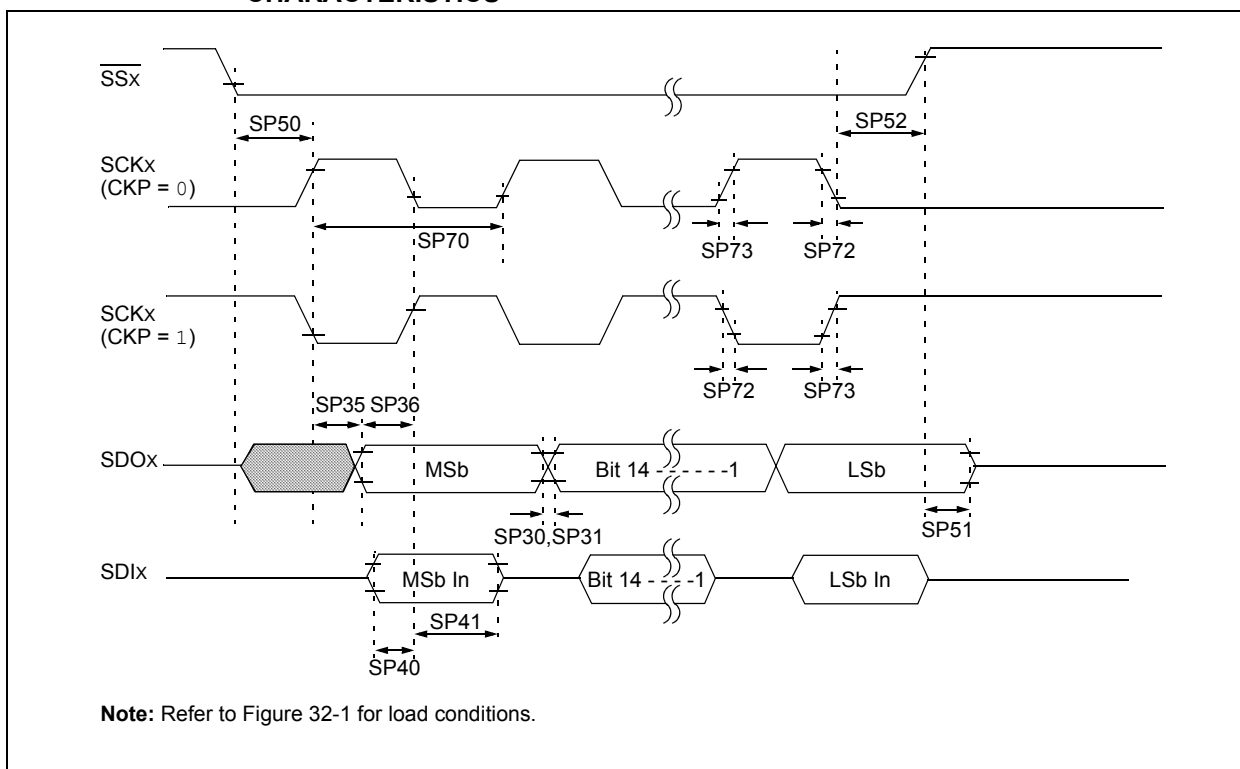


TABLE 32-57: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (see Note 4) (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param.	Symbol	Characteristic	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
Clock Parameters							
AD50	TAD	ADC Clock Period	117.6	—	—	ns	
AD51	tRC	ADC Internal RC Oscillator Period	—	250	—	ns	
Conversion Rate							
AD55	tCONV	Conversion Time	—	14 TAD	—	ns	
AD56	FCNV	Throughput Rate	—	—	500	Ksps	
AD57	TSAMP	Sample Time	3 TAD	—	—	—	
Timing Parameters							
AD60	tPCS	Conversion Start from Sample Trigger ⁽¹⁾	2 TAD	—	3 TAD	—	Auto-Convert Trigger not selected
AD61	tPSS	Sample Start from Setting Sample (SAMP) bit ⁽¹⁾	2 TAD	—	3 TAD	—	
AD62	tCSS	Conversion Completion to Sample Start (ASAM = 1) ⁽¹⁾	—	0.5 TAD	—	—	
AD63	tDPU	Time to Stabilize Analog Stage from ADC Off to ADC On ⁽¹⁾	—	—	20	μs	See Note 3

Note 1: Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.

2: These parameters are characterized but not tested in manufacturing.

3: The tDPU parameter is the time required for the ADC module to stabilize at the appropriate level when the module is turned on (ADON (ADxCON1<15>) = 1). During this time, the ADC result is indeterminate.

4: Device is functional at $V_{BORMIN} < V_{DD} < V_{DDMIN}$. Analog modules: ADC, Comparator and DAC will have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 32-11 for the minimum and maximum BOR values.

Revision G (October 2012)

This revision includes updates to the packaging diagrams in **Section 34.0 “Packaging Information”**. Preliminary has been removed and there are minor text edits throughout the document.

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